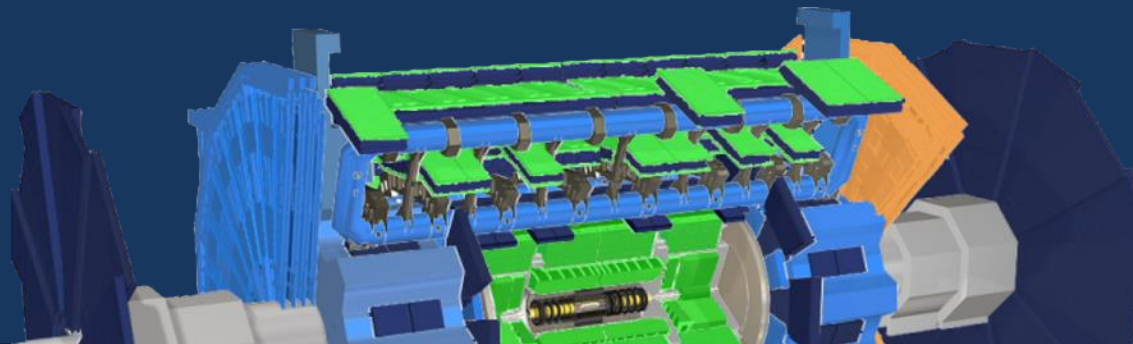




# ATLAS DCS Upgrade

**Theo Alexopoulos**  
NTU Athens



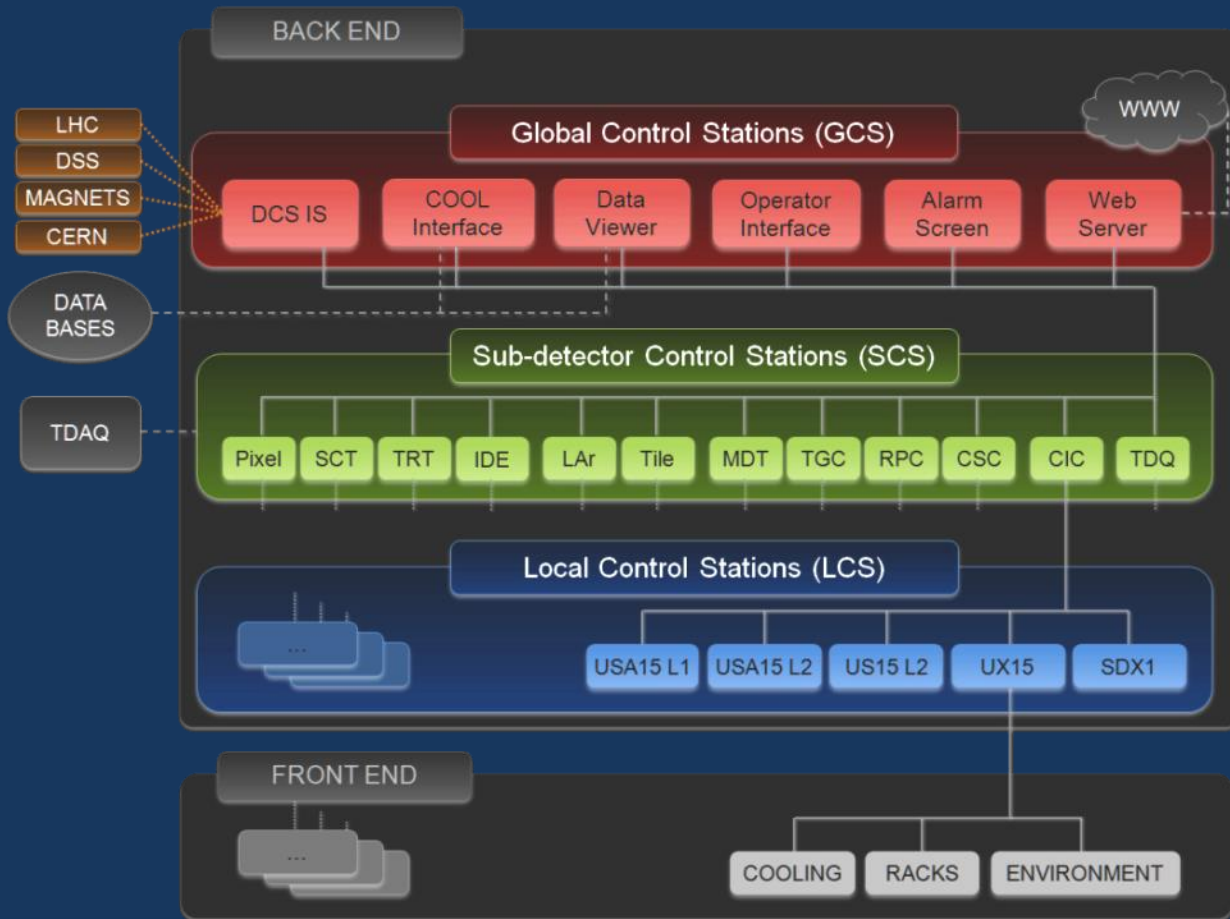
# DCS Architecture

- ▶ Facilitate management of implementation, operation and maintenance by using standard building blocks  
➔ **JointCOntrolsP**roject

- ▶ Controls hierarchy:

1. **Front-End (FE):** detector interface
2. **Local Back-End (BE):** FE connection, readout, processing
3. **Sub-detector BE:** grouping different technologies, standalone operation
4. **Global BE:** interfaces to operators, storage and external facilities

## Detector Control System



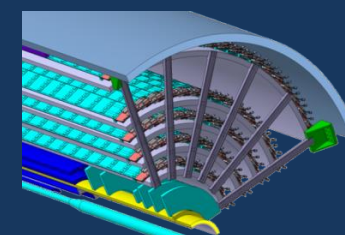
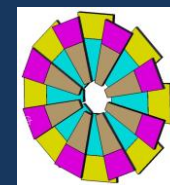
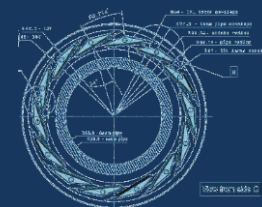
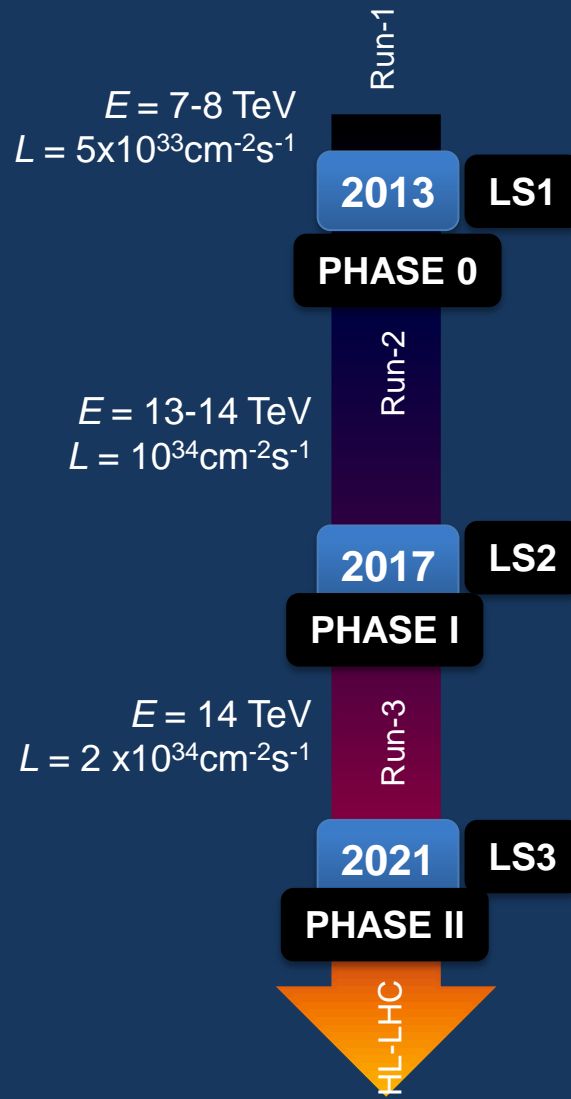
Layer architecture + FSM pays off during upgrade phases!

# Future Upgrades

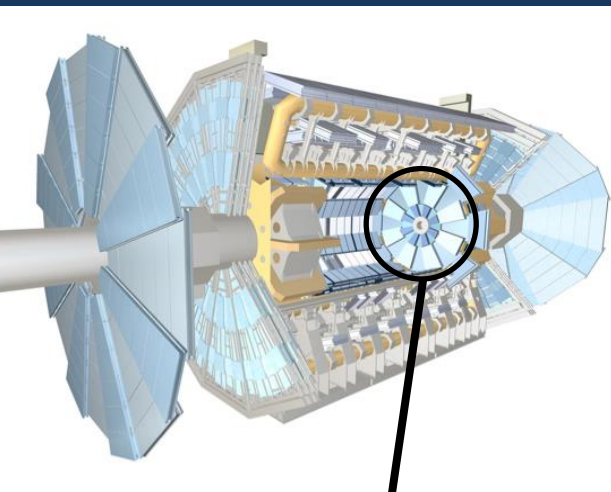
## Upgrade Constraints

- ▶ Higher luminosity ⇒ need to increase radiation tolerance for cavern equipment by factor  $\sim 10$
- ⇒ ELMB successor: **ELMB++**, still in designing stage
  - ⇒ Radiation hardness!
  - ⇒ Backwards compatibility
  - ⇒ Fix bugs, support new connectivity (Ethernet)
- ▶ Phase 0 (installed):
  - ▶ new Pixel Inner B-Layer (see Lukasz Z. talk on DCS cooling)
- ▶ Phase I (approved):
  - ▶ Fast Track Trigger (electronics)
  - ▶ LAr (trigger electronics)
  - ▶ TDAQ
  - ▶ **NSW (New Small Wheel)**
- ▶ Phase II (planning): Replace complete inner detector

## LHC Upgrade Schedule



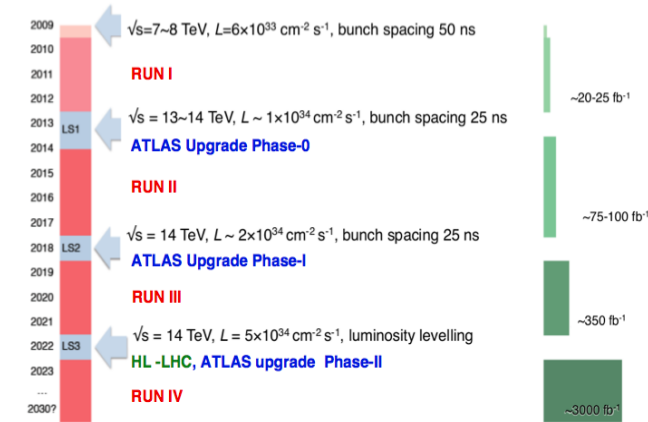
# Motivation ATLAS Small Wheel Upgrade 2017-18 (Phase I)



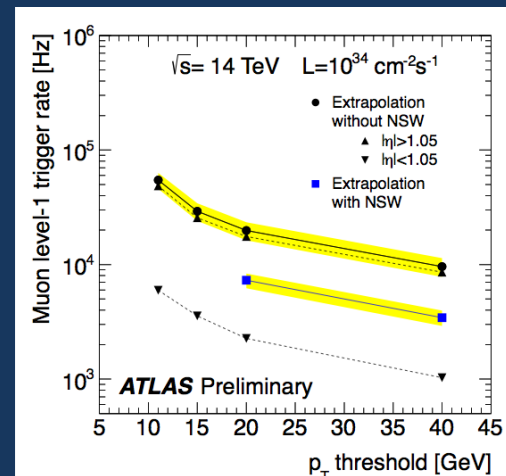
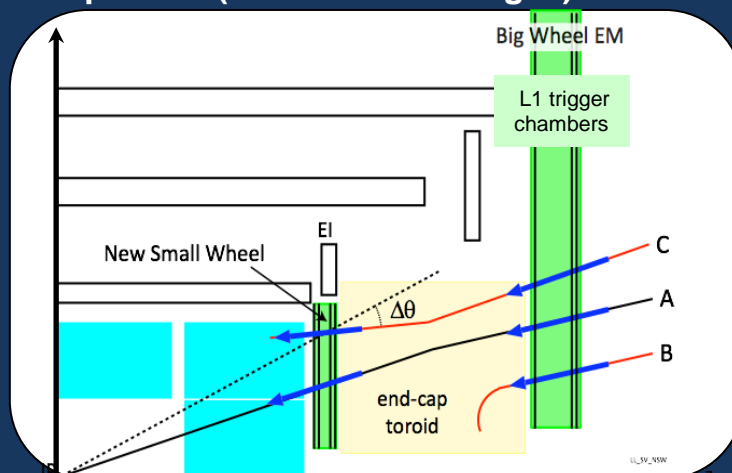
The innermost station of the muon endcap

Located between endcap calo and toroid

Pseudorapidity coverage:  
 $1.3 < |\eta| < 2.7$

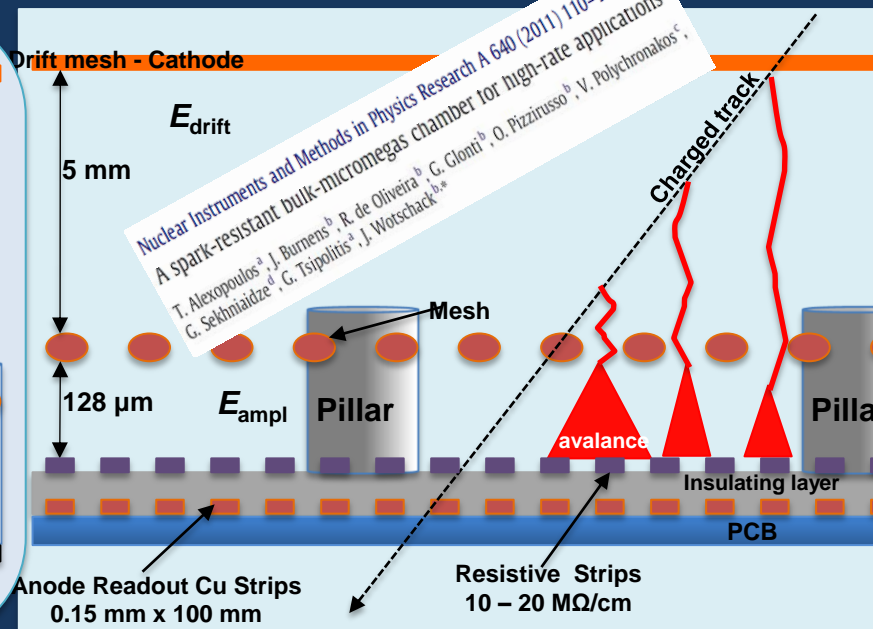
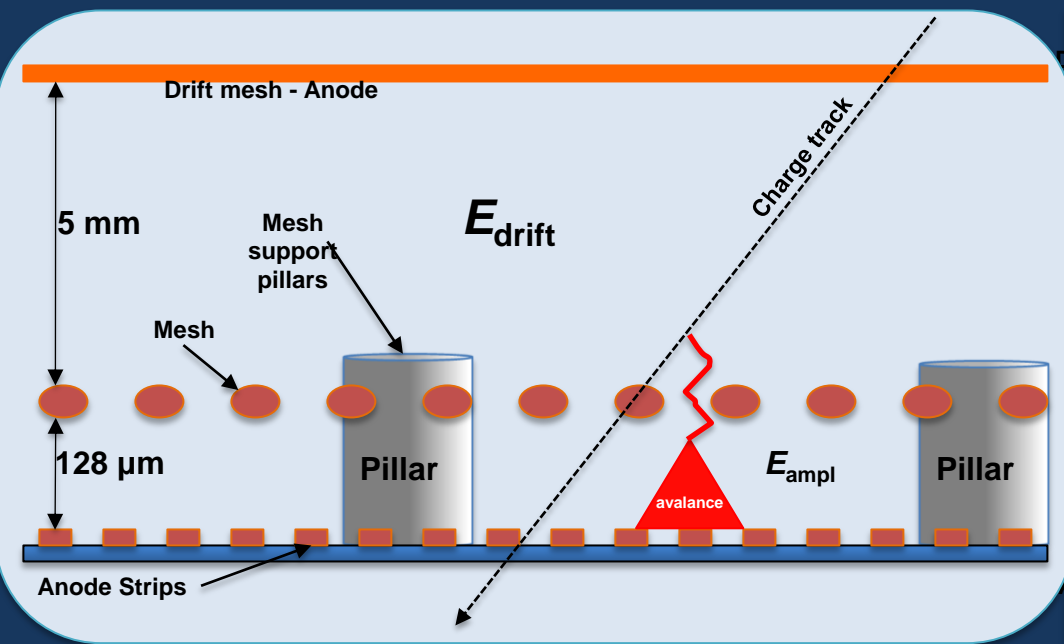


- The ATLAS upgrade is motivated primarily by the pile-up rate ( $\langle n \rangle = 55$  interactions per 25 ns bunch crossing) that are expected at  $L = 2 \times 10^{34} \text{ cm}^{-2} \text{ s}^{-1}$ . This will lead to an increased particle flux (rate) which the present detectors (MDT + CSC) cannot handle efficiently. Also, added trigger capability.
- Replacing the Small Wheels with a detector that can provide precise tracking and trigger segments will eliminate fake triggers without loss on physics acceptance. (sTGC + Micromegas)



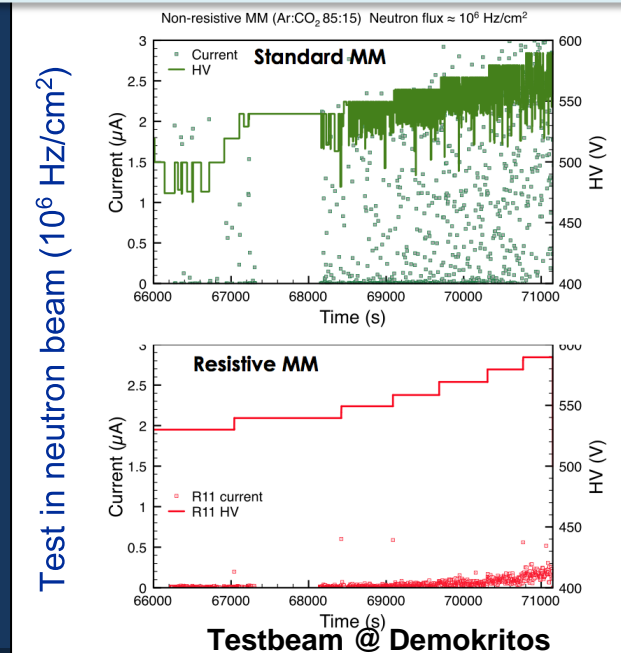


# Micromegas technology - Resistive Micromegas



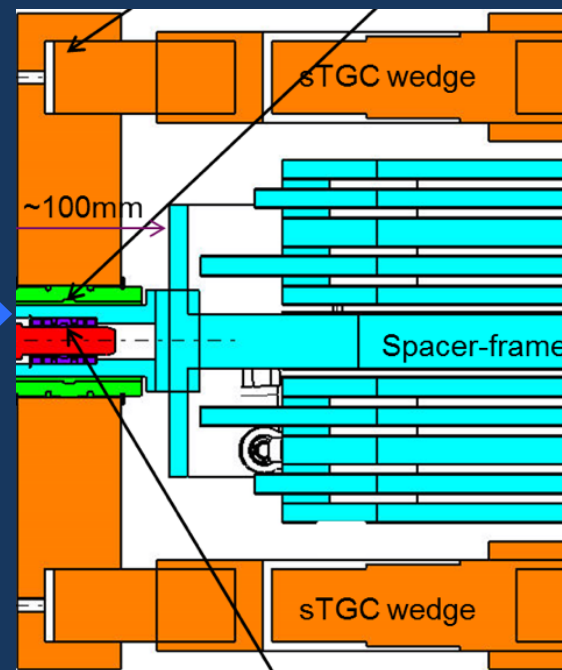
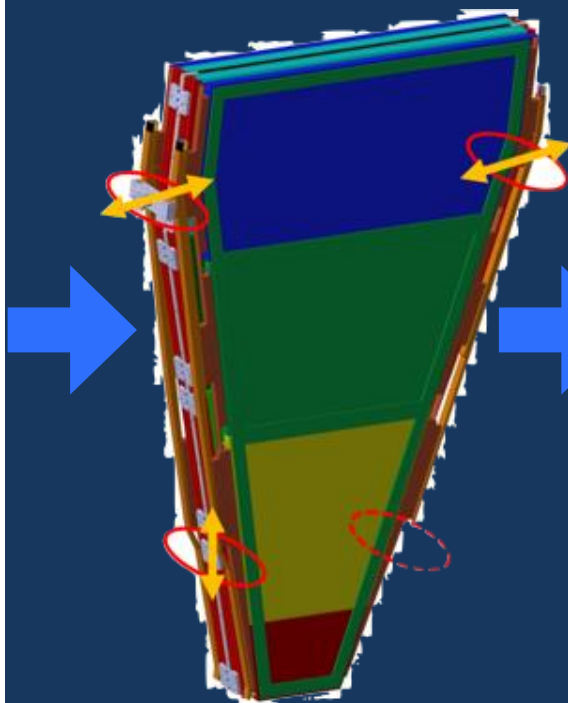
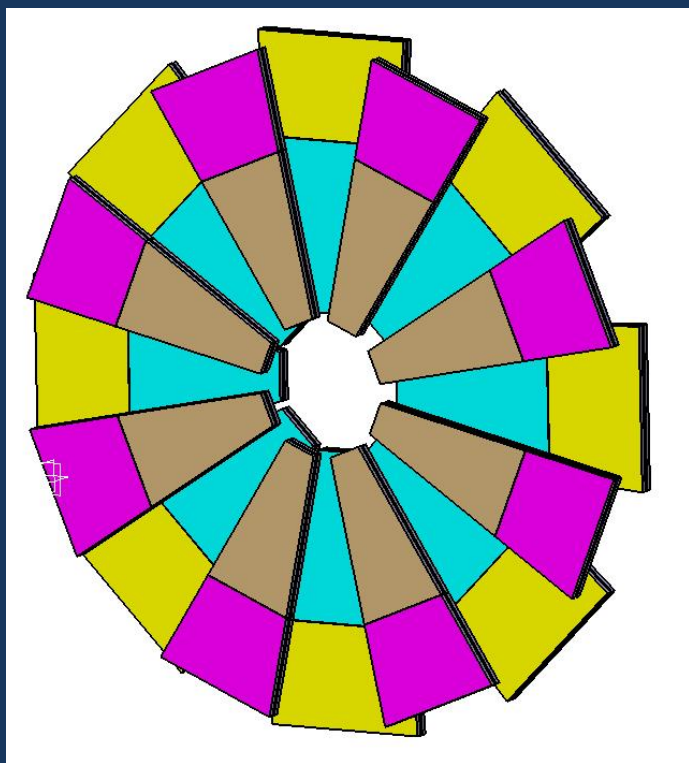
Nuclear Instruments and Methods in Physics Research A 640 (2011) 110-118  
 A spark-resistant bulk-micromegas chamber for high-rate applications  
 T. Alexopoulos<sup>a</sup>, J. Burnens<sup>b</sup>, R. de Oliveira<sup>b</sup>, G. Giomi<sup>b</sup>, O. Pizzirusso<sup>b</sup>, V. Polychronakos<sup>c</sup>,  
 G. Sekhniaidze<sup>d</sup>, G. Tsipolitis<sup>a</sup>, J. Wonschack<sup>b,\*,</sup>

- **Micromegas** (I. Giomataris et al., NIM A 376 (1996) 29) are parallel-plate chambers where the amplification takes place in a thin gap, separated from the conversion region by a fine metallic mesh
- The thin amplification gap (short drift times and fast absorption of the positive ions) makes it particularly suited for high-rate applications



# New Small Wheel (NSW) Layout

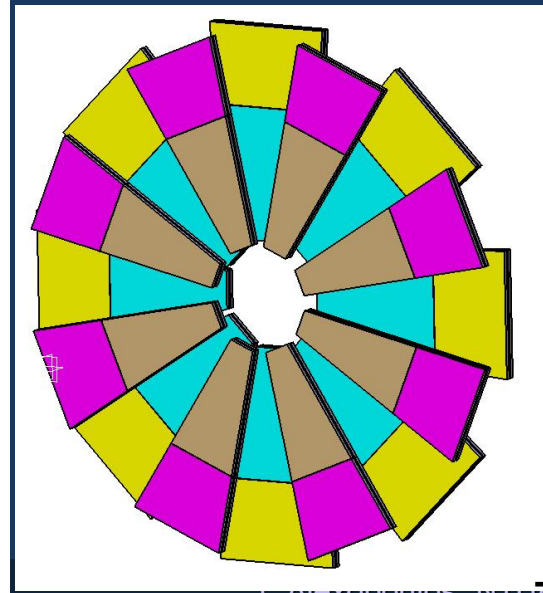
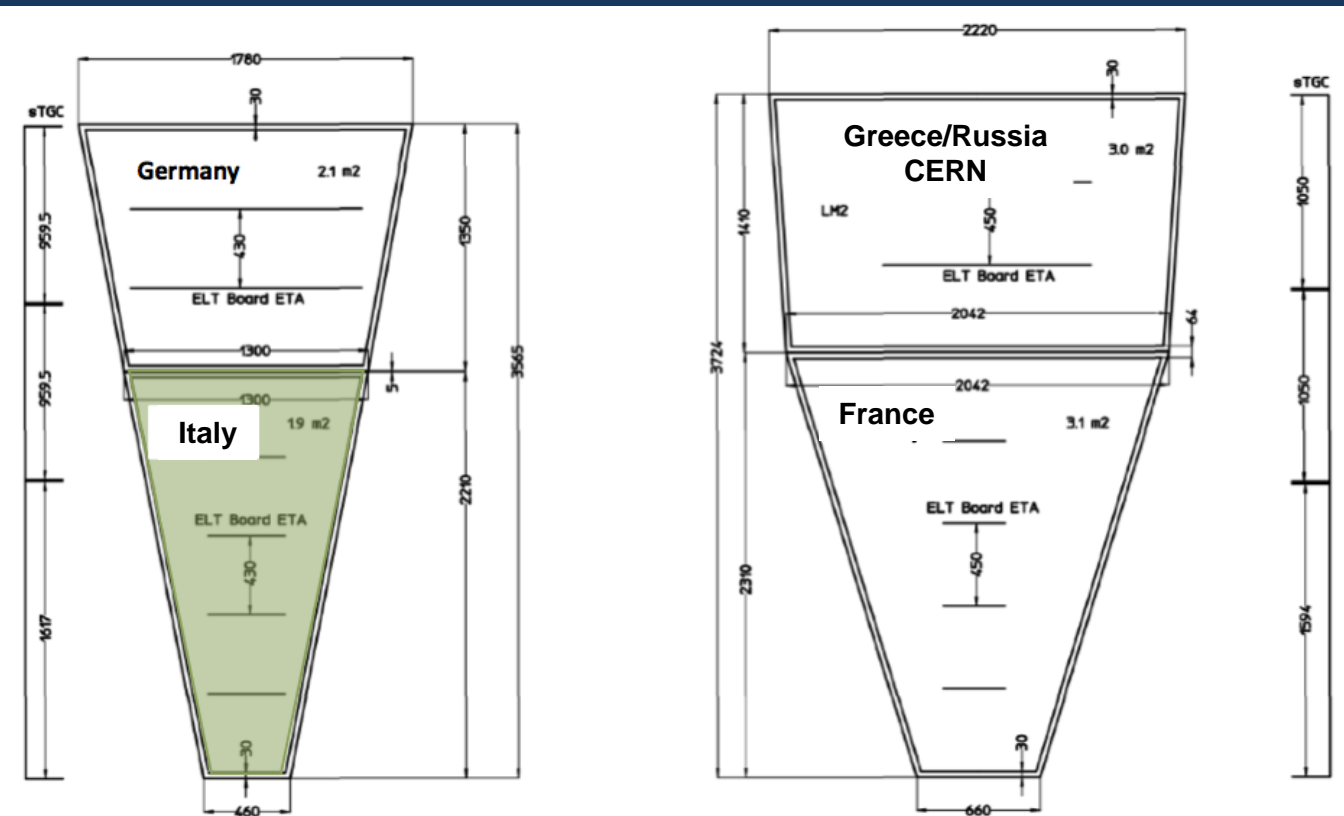
- Two technologies: Both Micromegas & sTGC detectors will provide tracking and trigger data
- 16 Sectors per Wheel (8 large, 8 small)
- 2 Multilayers per Sector
- 8 Micromegas Layers & 8 sTGC Layers per Multilayer



# Micromegas Construction

- Mechanics & Electronics** is a multi-national operation; **Mechanics:** institutes from 6 countries, **Electronics:** Institutes from 10 countries (USA, Italy, Romania, Netherlands, Italy, Israel, Greece, France, Chile, Taiwan) -- Total: 30 Institutions are involved
- 8 layers of Micromegas detectors will equip each large & small NSW sectors; for half of the layers, the strips will be under a stereo angle to measure the second coordinate.

Total Surface	1200 m <sup>2</sup>
Total number of MM Channels	2.1 M
Micromegas Strip Pitch	0.445 mm
Gas	Ar:CO <sub>2</sub> 93:7 atm pressure
Drift Gap	5 mm
Amplification Gap	128 μm
HV on Resistive Strips	550 V
Drift Field	600 V/cm
Resistive Strips	10-20 MΩhm/cm
Stereo Strips on 4/8 Layers	1.5°





# Full Micromegas Development Time-Plan

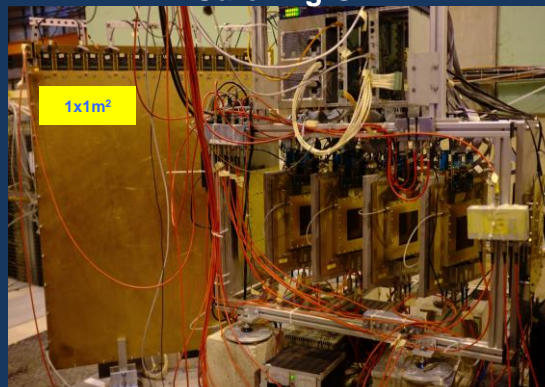
non-resistive MM, SPS/CERN,  
Demokritos-GR



2008

2009

resistive MM, SPS/CERN, Demokritos-GR,  
Garching-GE



2010

2011

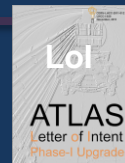
resistive MM, DESY II/DESY,  
LNF-IT, CEA-FR



2012

2013

developed new MM  
technology



approved by ATLAS

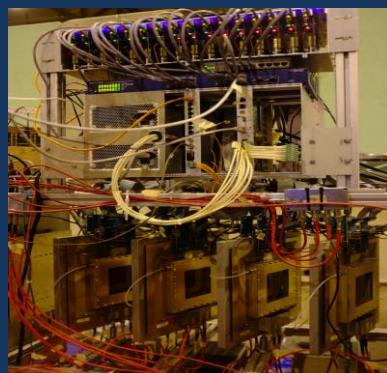


module-0 production  
& qualification



2014

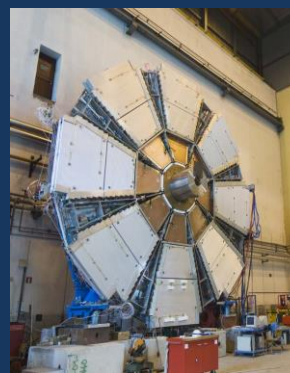
Full-production of  
chambers and electronics



2015

2016

Full commissioning  
on surface



2017

Full installation in cavern



2018

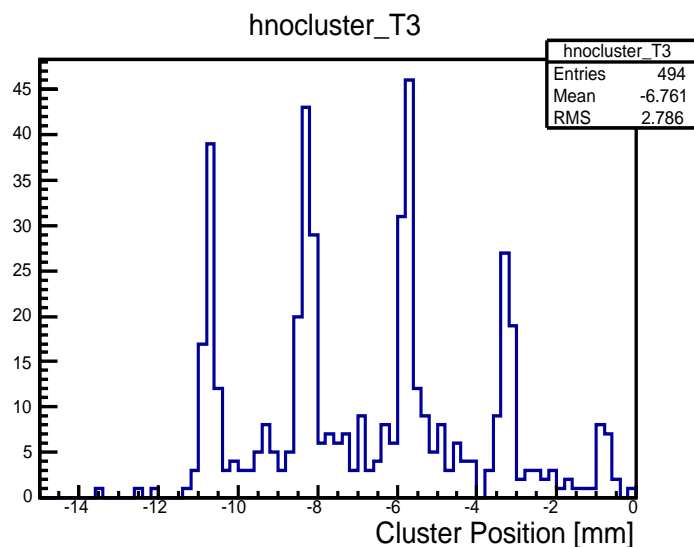
2019

Running...



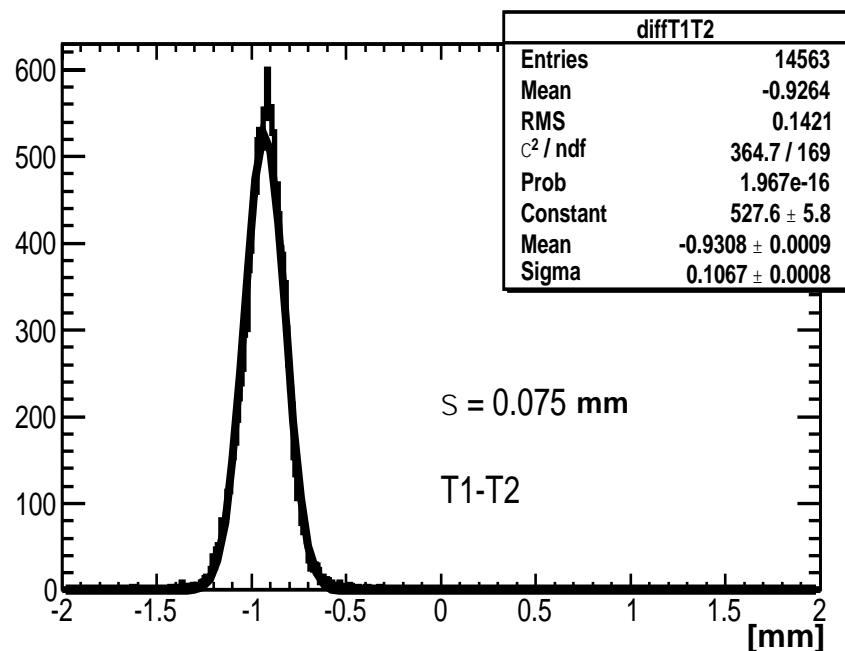
# Efficiency & Spatial Resolution for Normal Tracks

Distribution of local inefficiencies as measured from the missing hits on one chamber corresponding to a reconstructed track from the other chambers.



**Global inefficiencies of 2%** consistent with the partially dead area due to the presence of 300 $\mu$ m diameter pillars separated by 2.5 mm.

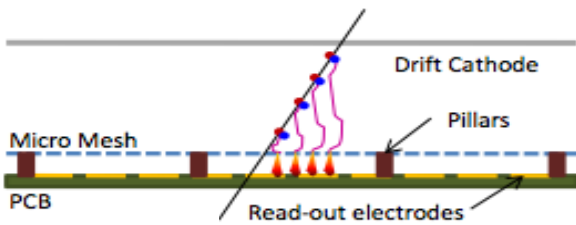
Spatial resolution for perpendicular tracks estimated by difference of cluster charge centroid measurements of pairs of MM chambers.



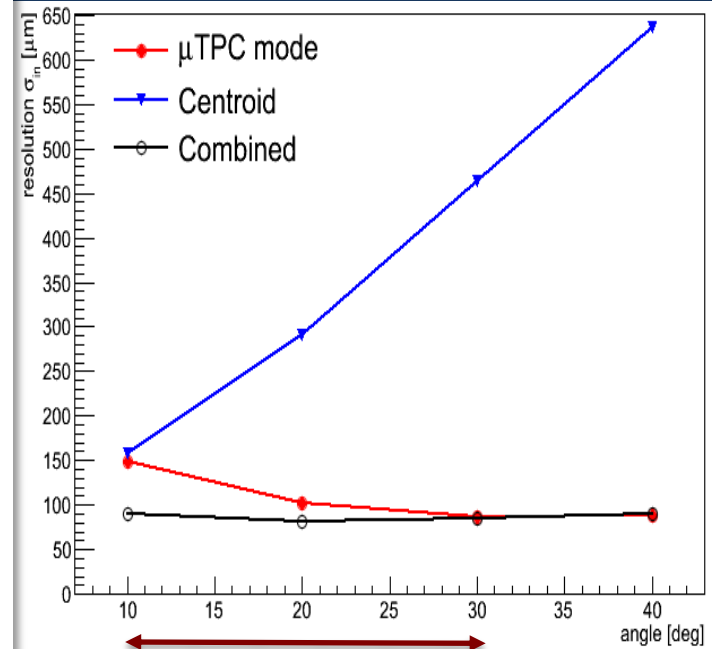
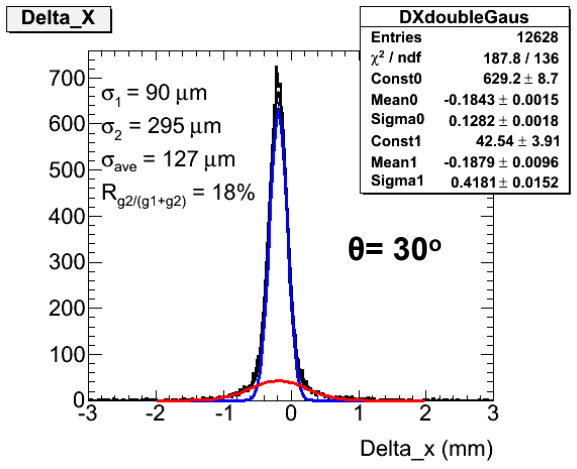
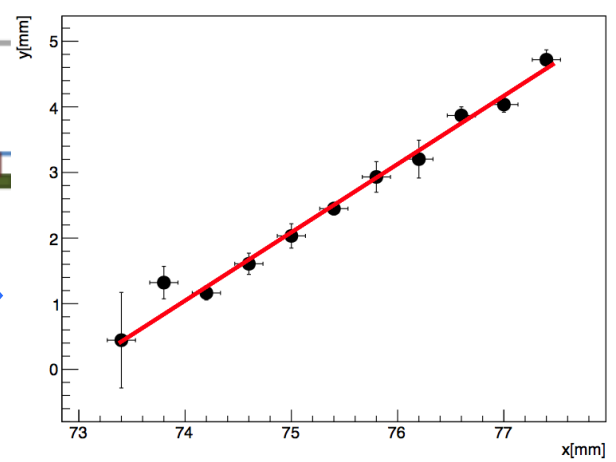
About **75  $\mu$ m** with an average cluster size of 3.2 strips (400 $\mu$ m pitch).  
Similar results obtained with a full track reconstruction method

# micro-TPC Mode for Incline Tracks

- Sub 100  $\mu\text{m}$  spatial resolution easy to achieve for perpendicular tracks
- For inclined tracks need to exploit time information to operate in micro-TPC mode



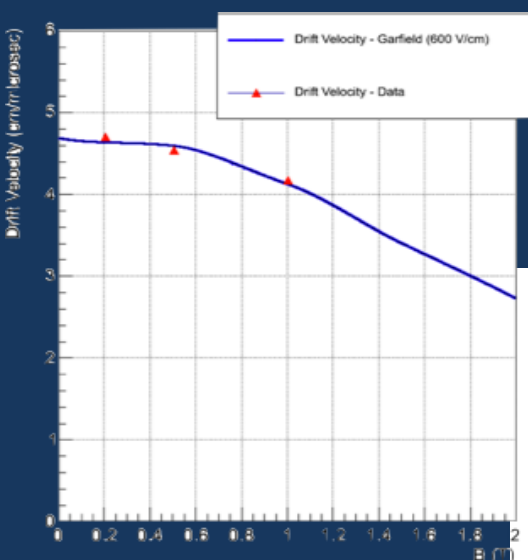
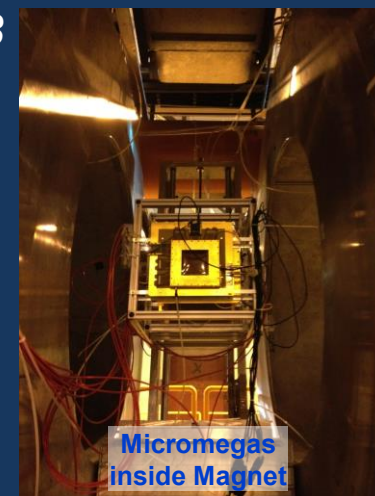
Single Segment Reconstruction in a Micromegas



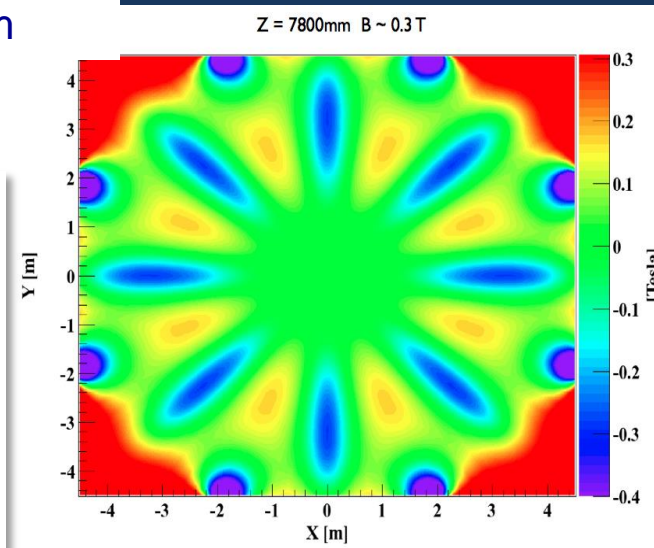
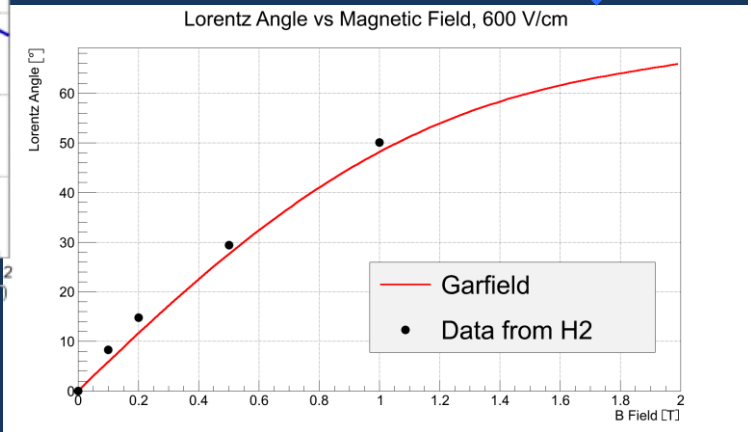
Muon angular range in NSW

# Micromegas Performance in $B$

- ATLAS New Small Wheels will be operated in a mixed directional  $B$  field up to 0.4 T.
- Micromegas chambers tested successfully in a magnetic field up to 1 T showing no performance degradation.
- Lorentz angle & drift velocity measurements are in agreement with simulation.



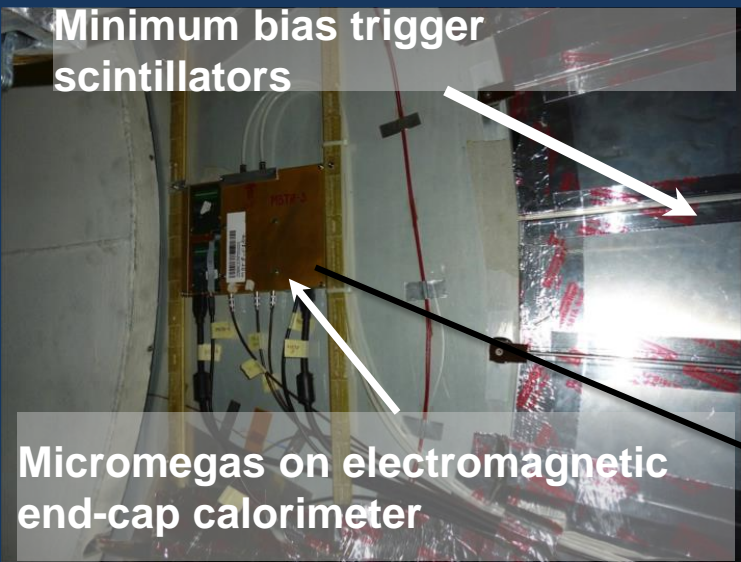
Lorentz angle from perpendicular tracks;  
 $E_{\text{drift}} = 600\text{V/cm}$



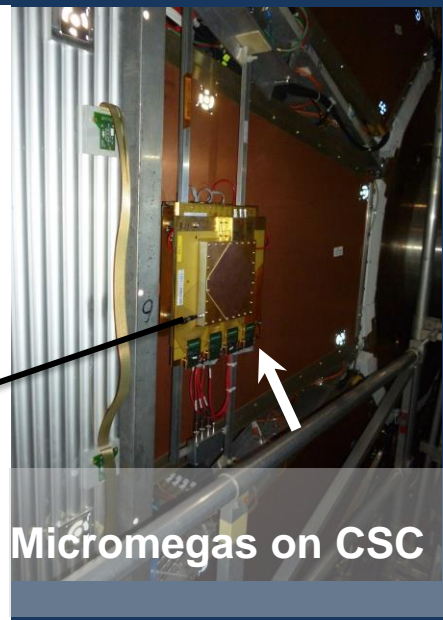
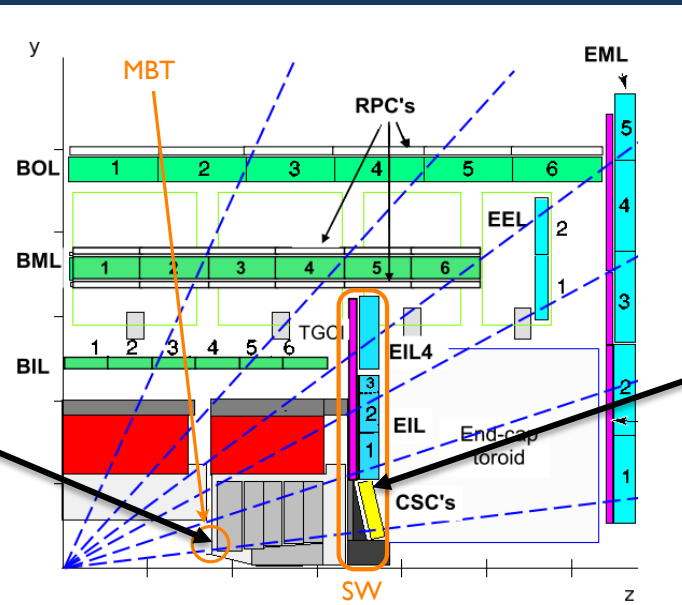
ATLAS End-Cap Toroid field

# Micromegas Performance in ATLAS

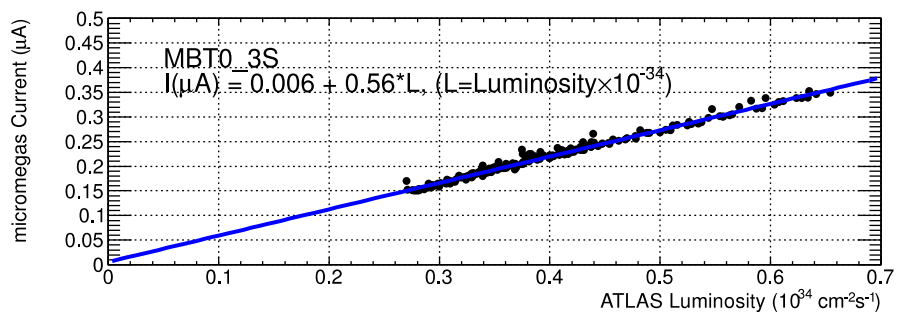
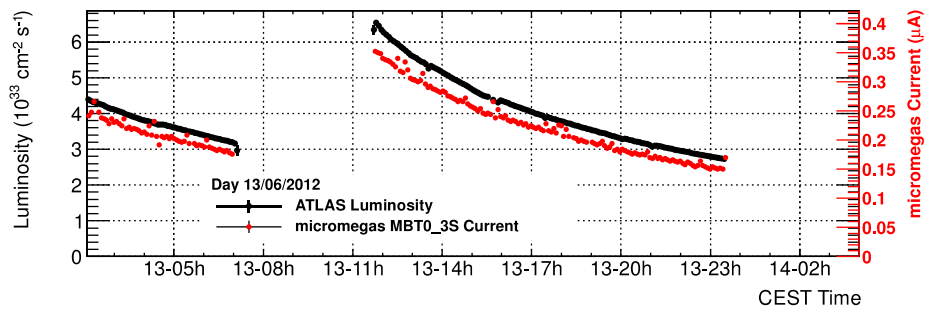
Minimum bias trigger scintillators



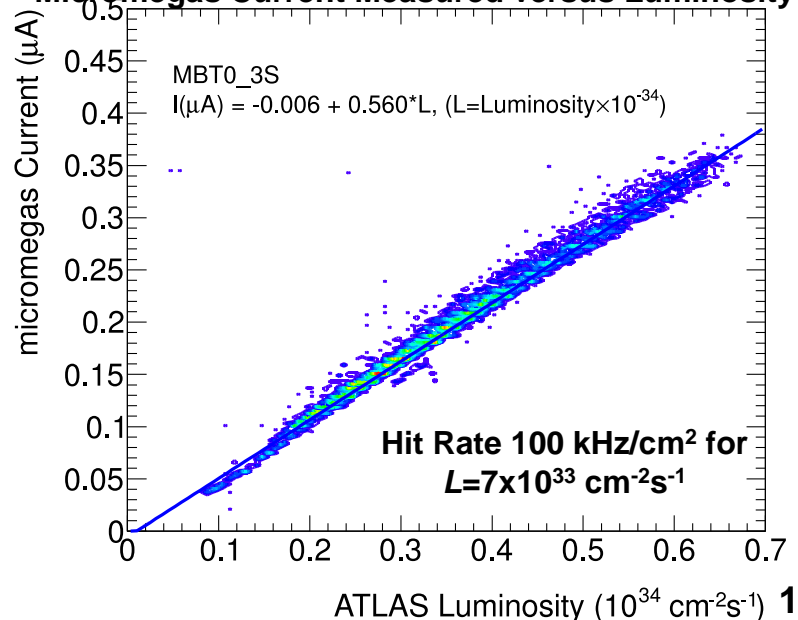
Micromegas on electromagnetic end-cap calorimeter



Micromegas on CSC



Micromegas Current Measured versus Luminosity

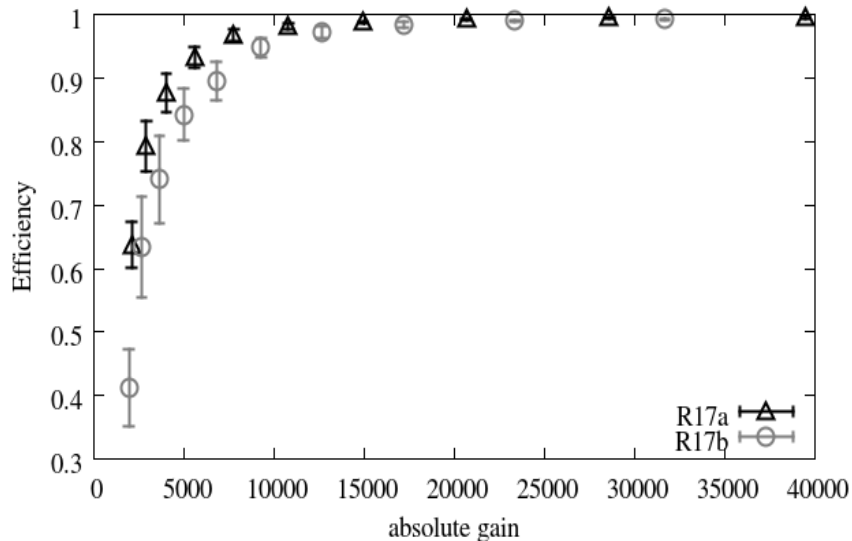




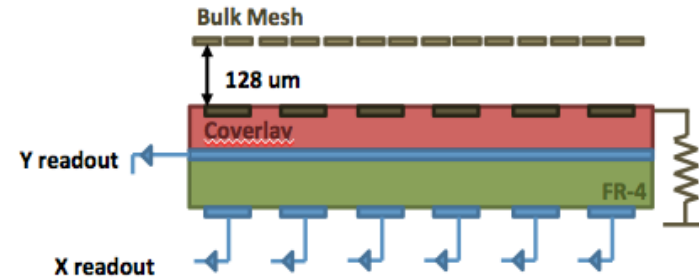
# Ageing Performance Studies

Extensive program of irradiations on small prototype (10x10 cm<sup>2</sup>) **performed** at C.E.A. Saclay, Orphee reactor,

Irradiation with	Charge Deposit (mC/cm <sup>2</sup> )	HL-LHC Equivalent	Results
X-Ray	225	5 HL-LHC years equivalent	No evidence of ageing
Neutron	0.5	10 years HL-LHC years equivalent	No evidence of ageing
Gamma	14.84	10 years HL-LHC years equivalent	No evidence of ageing
Alpha	2.4	5 x 10 <sup>8</sup> sparks equivalent	No evidence of ageing



**Both detectors reach efficiencies of about 99.5% for the highest values of the gain, proving that there is no visible degradation effect in these measurements**



**R17a detector is exposed to different radiation sources**

**R17b detector is kept unexposed.**

- Gain control measurements are performed before and after each exposure.
- After the ageing both detectors are taken to the SPS/CERN.
- The goal to accumulate an integrated operation charge equivalent to the one would be obtained at the HL-LHC for 10 years for each type of radiation.

Performance evaluated in terms of **efficiency** and **spatial**

# Components of NSW DCS

- *T, B, HV/LV, gas, alignment,*
- **ELMB++**
  
- **Monitor DC-DC converters**
- **Monitor Front End ASICs VMMx,  $V_{ref}$ , ...**
- **Monitor/Configuration companion ASIC on FrontEnd Boards**
- **Configuration/Status of VMMx**
- **Calibration VMMx**
  
- **propose to use the GBT-SCA ASIC**

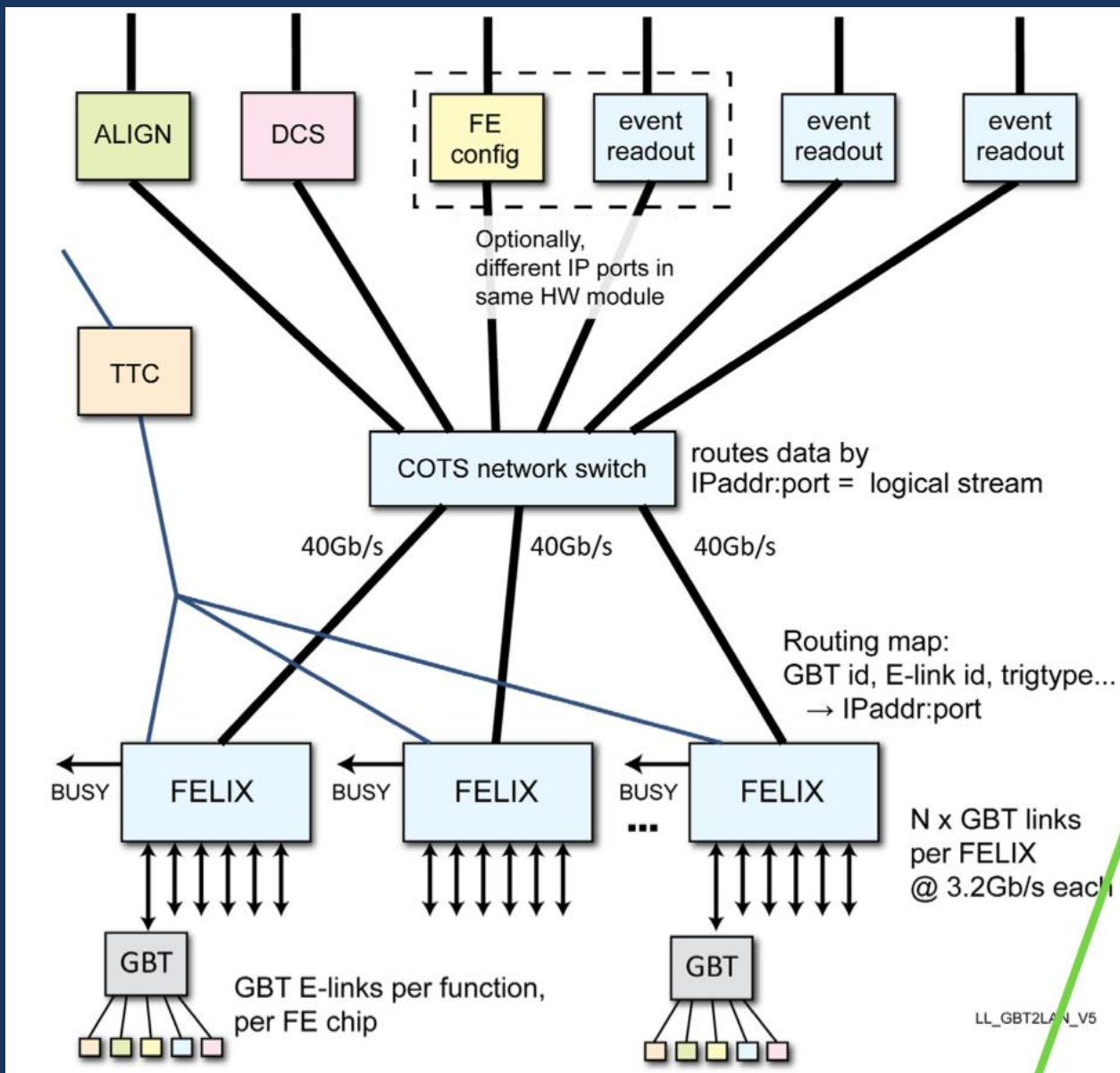
# New Small Wheel Proposed Readout

DCS: Detector Control System

TTC: Timing, Trigger and Control

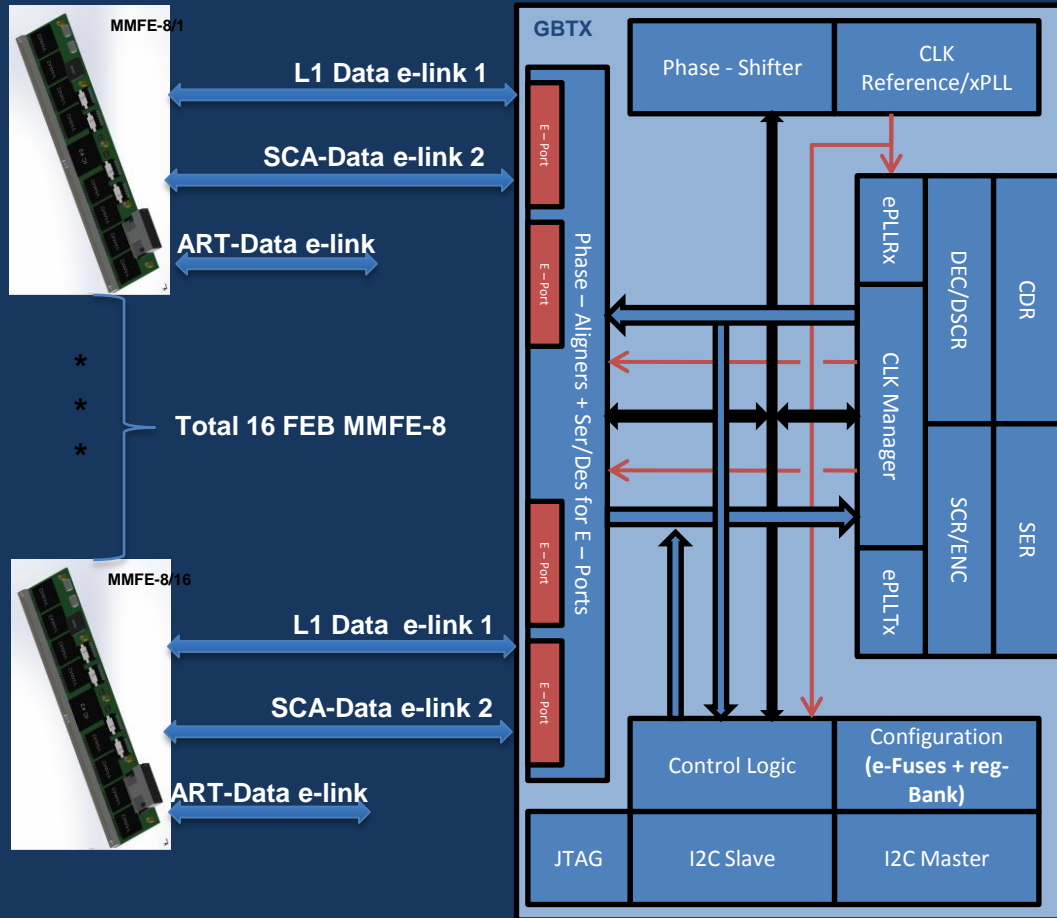
FELIX: Front End Link eXchange

GBT: Gigabit Transfer ASIC



# New Small Wheel DCS

## Front End Boards

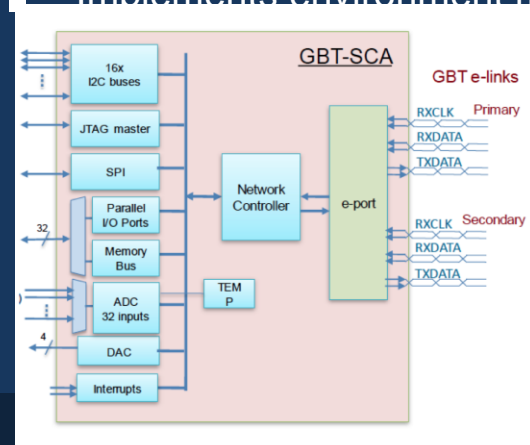




# GBT-Slow Control Adapter (SCA) ASIC

- Slow Control Adapter (GBT-SCA) ASIC suitable for the control and monitoring applications of the embedded front-end electronics
- Interfaces with the GBTX using a dedicated E-link port (Standard e-Ports in the 80 Mb/s can be used as well)
- Is intended for the slow control and monitoring of the embedded front end electronics and implements a point-to-multi point connection between one GBT optical link ASIC and several front end ASICs
- More than one GBT-SCA ASIC can be connected to a GBT ASIC thus increasing the control and monitoring capabilities in the system
- There are 16 I2C buses, 1 JTAG controller port, 4 8-bit wide parallel-ports, a memory bus controller and an ADC to monitor external analog signals

Implements environment monitoring functions: Temp sensing



## Specs:

- 16 I<sup>2</sup>C master controllers, @100kbts/s to 1 Mbits/s.
- 1 JTAG & 1 SPI master controller
- 32 multiplexed ADC channels, 12-bit dual slope, 1-occupied by the temp sensor
- 4 DAC channels
- 32 Digital I/O lines individually programmable

# Link Architecture

## Radiation tolerant chipset:

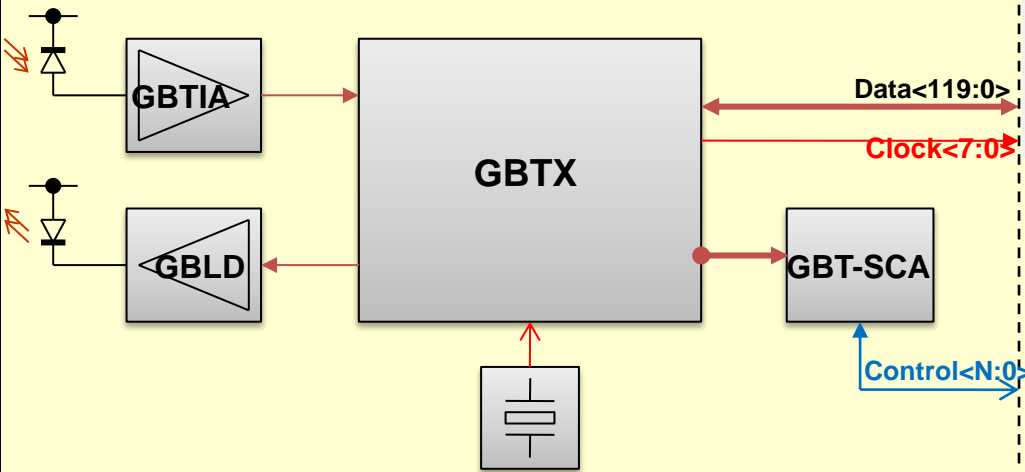
- ▶ GBTIA: Transimpedance optical receiver
- ▶ GBLD: Laser driver
- ▶ GBTX: Data and Timing Transceiver
- ▶ GBT-SCA: Slow control ASIC

## Supports:

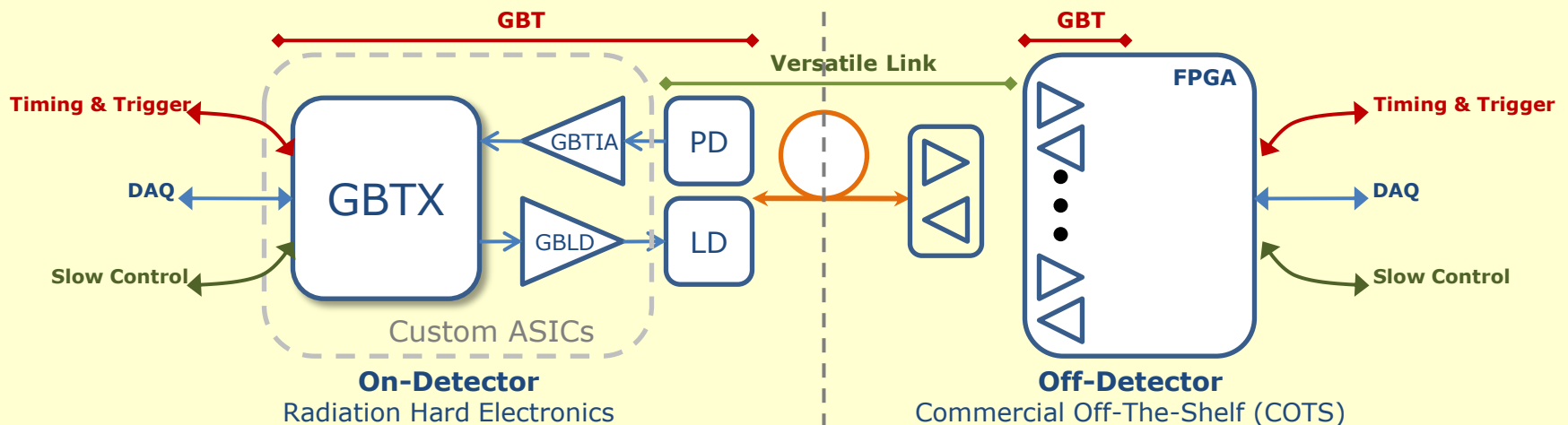
Bidirectional data transmission

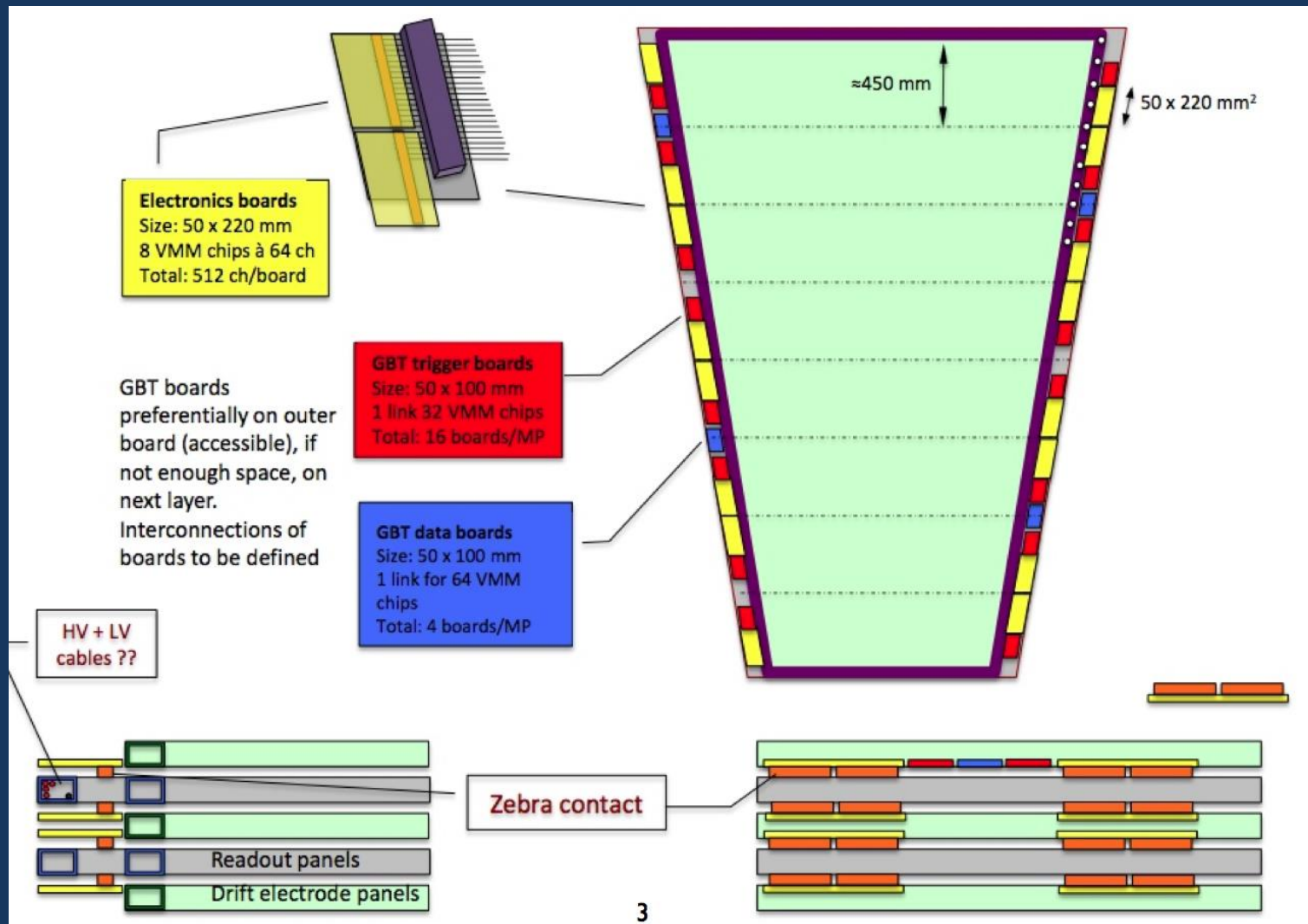
## Bandwidth:

Line rate: 4.8 Gb/s  
Effective: 3.36 Gb/s



## Frontend Electronics





**1GBT/plane serves 16 FEB/plane**  
**4GBT/MP x 2MP/sector x 32 sectors/MM = 256 GBT/MM Readout boards & 384 GBT/sTGC**  
**and 1024 GBT trigger boards**

# Summary

- ▶ Will continue using the highly distributed control system based on SCADA software WinCC OA
- ▶ A heavy & intense NSW upgrade program ahead of us!
- ▶ We are evaluating the optimal solution for NSW DCS

