

aCT and ARC CE

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- ARC Control Tower
 - Past, present and future
- ARC Compute Element
 - unique capability
 - matter of taste

aCT – ARC Control Tower

- Developed so that Nordugrid sites could integrate to Panda
 - pilot jobs required WN network – not allowed
 - Ah but...cvmfs,Frontier work! Selected IPs is allowed.
 - want known job with custom limits
 - WN pulls data from SE – no local SE on NG
 - must know inputs and pre-fetch
- aCT spoofs WN pilots
 - pulls job from Panda, sends heartbeats, final update

The payload

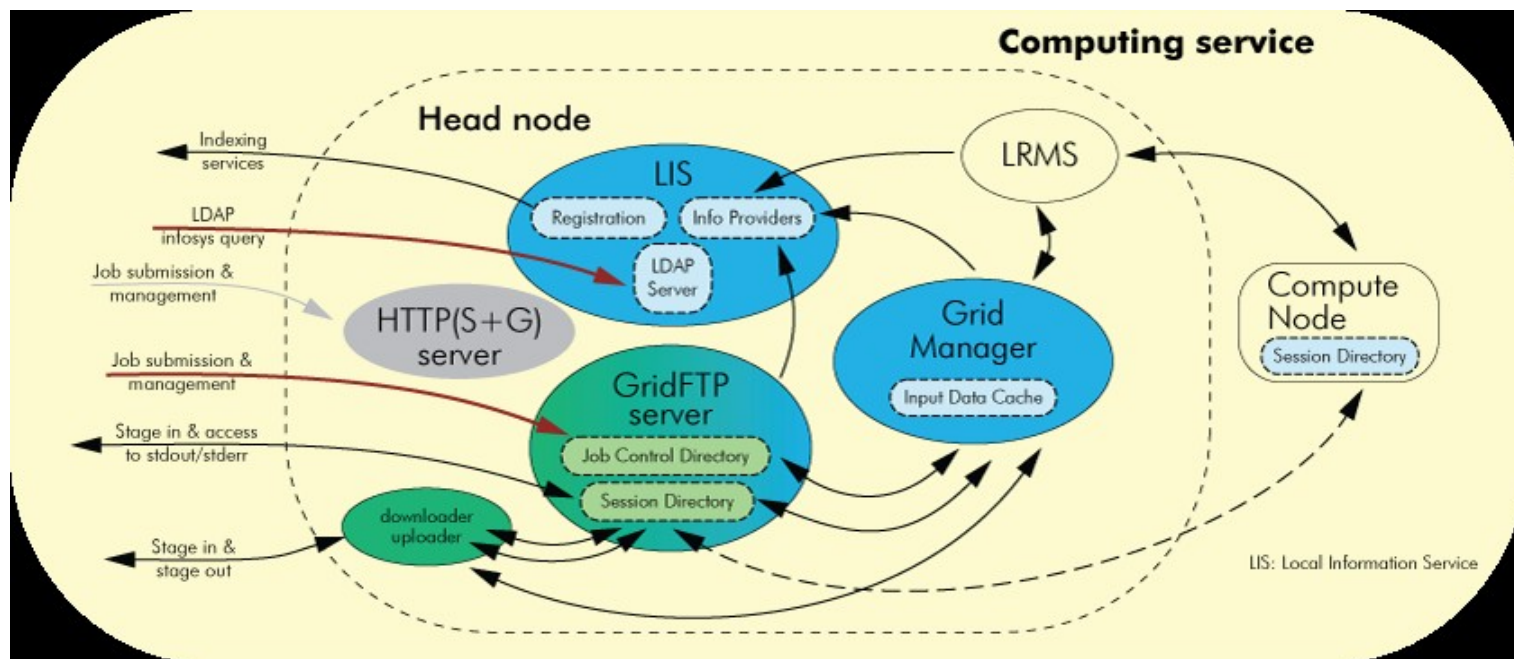
- In between preloaded pilot is submitted to ARC CE
 - input data known
 - resource limits, RSS+wall, known and set
- Lose late binding
 - do we care? Gain a lot.
 - instead must set BS priority for eg. merge job
 - modifying priorities possible(with dev) but maybe not necessary

Dynamic queues vs aCT

- Range of limits(mem,wall,cores) in Panda queues(static or chosen by JEDI)
 - send pilots to each queue with activated jobs
- Late binding messed up here too
 - cannot choose which pilot starts next
 - priorities between jobs in different queues NOT respected
- aCT sets priority per job
 - Panda chooses next job to run – better.

ARC Compute Element

- Fully functioned Grid Compute Element part of UMD
 - BDII, APEL, GOCDb, SAM, ...
 - ATLAS, CMS, LHCb, ALICE can use it
 - single users/small VOs have/will adapt...and benefit!
- Unique functionality
 - data input and output done outside batch job



Matter of taste

- Installation straightforward
 - SL, Debian, SUSE(builds ok)
 - single config file
 - major batch systems supported
 - PBS, SGE, Slurm, HTCondor, Loadleveler, LSF, Boinc
 - bash scripts for submit,stat,cancel
 - perl for infosys
- Operation
 - no scale limit observed yet: challenge to a T1?
 - RAL runs 3 ARC CEs but not due to scaling
 - 1 per Condor sched for RAM reasons & redundancy
 - debug is easier, e.g. log file per job

GridKa has 8 CreamCEs for
12k jobs
Try 1 ARC CE?

Use cases for ARC CE

- Traditional Computer centers/HPC
 - networkless WNs
 - job limits with no surprise workloads
- No local SE
 - data handling by CE, outside batch job
 - maybe suitable for Clouds – asynchronous data movement
- ssh backend to ARC CE
 - no service on site, just passwordless ssh
 - sshfs, batch commands via ssh – works well.
- Replace CREAM CE for pilot submission
 - ignore data handling – needs large shared FS, not common on WLCG sites
 - just use to submit pilots reading/writing to local SE
 - without pre-loaded jobs(works now), or with pre-loaded job(dev)

ARC CE to replace Cream CE

- Use to submit normal ATLAS pilot jobs
 - no data staging required(goes via SRM)
- Why do some need an alternative?
 - RW: “Cream CE is unreliable, difficult to configure/debug/upgrade, not scaling well, high RAM usage”
 - not alone: read lcg-rollout list
 - interfaced to aCT to receive preloaded pilots
 - with custom per job resource limits
 - increased entropy without multiple pilot streams
 - kill misbehaving jobs. Backfill MCORE.
 - passing resource limits to batch works
- Flexibility of choosing custom job limit
 - recall surprise RAM usage of pile MCORE – no manual action required
 - aCT served sites with higher BS queue limits, just received jobs with bigger limits

Conclusions

- aCT and ARC CE crucial for certain use-cases
 - HPC, strict CC, Boinc, no local SE, Cloud(?)
- Useful for ATLAS production
 - fine-grained & flexible job limits via aCT
 - aCT currently only supports ARC CE
 - no strong case/manpower to support preloaded pilots to Cream
 - no more empty pilots!
 - resource limit setting for dynamic queues
- personal recommendation rather than ATLAS