

### **News from the ITS**

Run 2 ...

Run 3 ...



## ITS in Run 2 It is still the same detector

- Not much new from the offline point of view...
- Re-doing the alignment
- Some QA tasks need to be automatized
- Investigation of the possibilities to run the local SDD reconstruction on the HLT (manpower needed)

# ALICE

Outer Barrel

### **ITS IN RUN 3**

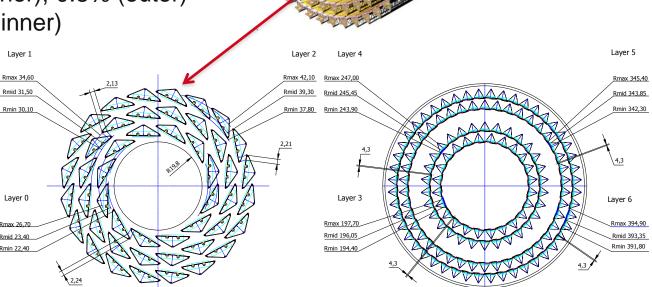
### This will be a completely different new detector

Beam pipe

- 7 layers of monolithic pixel sensors
- R of the innermost layer ~22 mm
- R of the outermost layer ~400 mm
- ~23k pixel sensors
- ~500k pixels per (inner) sensor

Material: 0.3% (inner), 0.8% (outer)

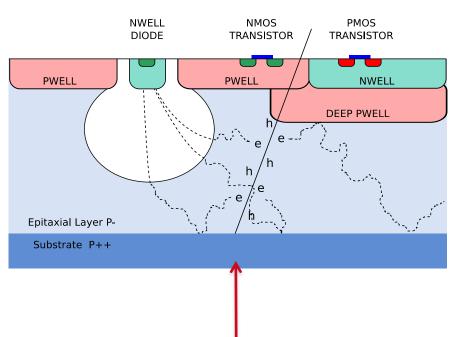
Precision ~4 μm (inner)



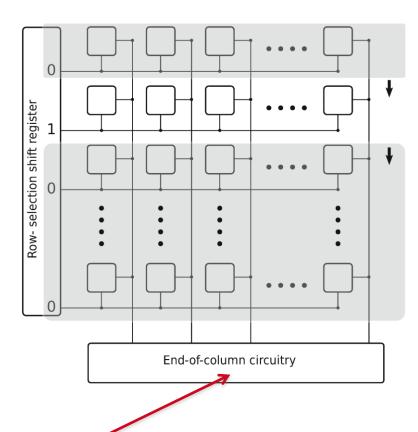
~1.5 m



### A readout «unit»: Pixel Chip

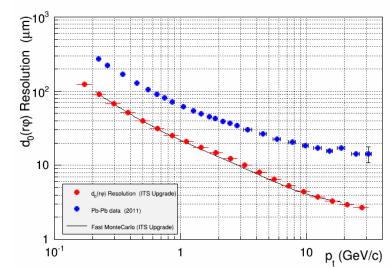


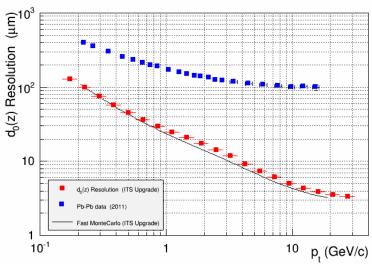
- Monolithic Active Pixel Sensors (MAPS):
   integrate both the sensor and the readout
- Read out sequentially column-by-column,
   with a total "integration time" ~20 30 μs



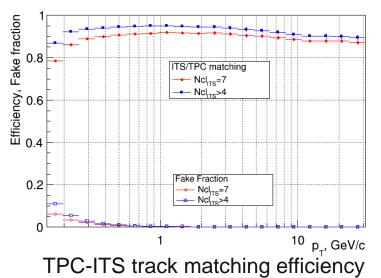
### Performance of the ITS in Run 3

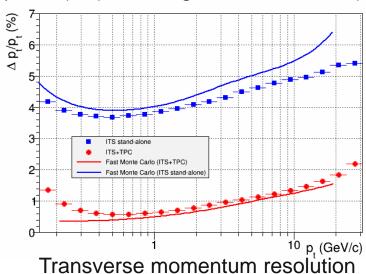
"In principal", evaluated with the current AliROOT (see ITSU TDR)





Impact parameter resolution in the bending plane (left) and longitudinal direction (right)







### ITS SOFTWARE REQUIREMENTS IN RUN 3

(A few points are common with other ALICE detectors?)

### Monte Carlo (always the slowest part !):

With the number of events x100 of the current, some "fast" MC is desperately needed

- ◆ Calibration: Dead/noisy pixels only (~10<sup>-5</sup> of the total number of pixels)
- Alignment: Down to ~4 μm, with an expected outer layer sagging up to ~100 μm
   Can the sagging be reliably modelled?

### Reconstruction:

- Amount of processing: a need for a migration on-line (cluster finder, PV finder, ...)
- Challenges with the TPC: a need for a powerful stand-alone ITS tracking
- 50 kHz rate + 30 μs readout: a need for a reliable pileup tagging (time stamps for the hits, an improved (separation <1 cm) multiple PV reconstruction)