FairRoot framework



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FairRoot : Timeline



Design



Building & Testing system



Testing and building system

- CMake
 - Creates Makefiles (and/or project files) for different platforms.
 - Test support.
 - Large user base assures support.
- CDash to handle data created with CMake
 - PHP framework
 - MySQL database
- Both tools are open source.

If someone experiments with new features in his local working copy and wants to test them (experimental build)

2. Configure, build and test on local machine



1. Update (optional)



3. Send results automatically

to central web page

5. Developer check results

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4. Dashboard prepares and display results

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neck results			

If new code enters the central code base (continuous build)



6. Dashboard prepares and display results

From time to time a full check on all supported platforms should be done (nightly build)

Central SVN repository





4. In case of problems Dashboard sends an E-mail to Developer and Administrator

- 2. Send results automatically
 - to central web page

5. In the morning Developers and Administrators check their mails and the dashboard. And the development cycle starts again

3. Dashboard prepares and display results

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From SVN to Git

- With SVN we can only do very fast tests in the pre-commit
- Moving to Git will help us to put more tests on the code before it is committed the Master branch





Time based simulation In FairRoot

How do events overlap?

- In Detectors:
 - Sensor elements are still blocked from previous hits
 - Electronic is still busy
 - Hits too close in time cannot be distinguished
- Special problem for CBM and PANDA:
 - Continuous beam with Poisson statistics (?) → many events with short time between them
 - No hardware trigger
 - Complex event reconstruction
 - → Necessary to simulate data stream as realistic as possible



Time based simulation: Implementation

- FairWriteoutBuffer is Special buffer to store detector data between different events
- You give the data you want to store an absolute time window this data is active in your detector and can influence later events.
- If the same detector element is hit a second time the data is modified.
- This is an abstract base class where you have to inherit from

Time based simulation: Reading back data

- FairRootManager has new reading algorithms, which make it possible to use the event wise implemented tasks to run on such data streams
- Different algorithms available to extract data:
 - All data up to a given time
 - All data in a time window
 - All data between time gaps of a certain size
- Other algorithms can be (easily) implemented

Time-based simulation in FAIRROOT was presented in details with code

https://indico.gsi.de/contributionDisplay.py?contribId=9&confId=1810

Fast Simulation

• The same application, just different configuration:

– Event generators just push the event into the stack, no transport is taking place

- -Detector response is presented as FairTasks (TTask)
- -The output has the same form as full simulation

Simulation-Reconstruction Chain



Klaus Götzen

Fast Simulation: Concept

Full Simulation



Fast Simulation





Particle Transport Digitization Calibration Reconstruction

Effective parametrization - acceptance cuts

- acceptance cuts
- resolution smearing

- PID info

Physics Analysis

Compared to Full Sim

Klaus Götzen

• Comparison to Full Sim are reasonable (channel: $\overline{p}p \rightarrow D_s D_{so}$)



(10 k Signal events; absolute numbers)

Next challenge is: Online vs. Offline or Online + Offline ?



FairRoot: Where we are now?

- ROOT event loop
- User code in Task hierarchy
- Task hierarchy runs sequentially in one process
- Tasks implement only algorithms (can be exchanged/replaced)



FairRoot: How to scale

- Computer have more and more cores.
 - Online clusters of CBM and Panda will have about 60.000 cores
 - One monolithic program only use one of this cores
 - How we can better use the computing power of the modern computers?
- C and C++ do not offer any support for concurrency!
- Embarrassingly parallel workload (Start as many FairRoot processes as cores are available)
 - $_{\circ}$ Memory needed for each process \rightarrow expensive
 - How this scheme should work for the Online cluster?

Design constrains

- Highly flexible:
 - ^o different data paths should be modeled.
- Adaptive:



- Sub-systems are continuously under development and improvement
- Should work for simulated and real data:
 - developing and debugging the algorithms
- It should support all possible hardware where the algorithms could run (CPU, GPU, FPGA)
- It has to scale to any size! With minimum or ideally no effort.

Multi-processing vs. Multi-threading

- Different processes are insulated from each other by the OS, an error in one process cannot bring down another process.
- Inter-process communication can be used across network

• Error in one thread can bring down all the threads in the process.

• Inter-thread communication is fast

The best would be to find the correct balance between reliability and performance

- Multi-process concept with message queues for data exchange
 - Each "Task" is a separate process, which can be also multithreaded, and the data exchange between the different tasks is done via messages.
 - Different topologies of tasks that can be adapted to the problem itself, and the hardware capabilities.

FairRoot: Where we are going ? (almost there!)

- Each Task is a process (can be Multi-threaded)
- Message Queues for data exchange
- Support multi-core and multi node



Before Re-inventing the Wheel

- What is available on the market and in the community?
 - A very promising package: ZeroMQ is available since 2011
- Do we intend to separate online and offline? NO
- Multithreaded concept or a message queue based one?
 - Message based systems allow us to decouple producers from consumers.
 - We can spread the work to be done over several processes and machines.
 - We can manage/upgrade/move around programs (processes) independently of each other.





- A messaging library, which allows you to design a complex communication system without much effort
- Abstraction on higher level than MPI (programming model is easier)
- Is suitable for loosely coupled and more general distributed systems
- Multiplatform, multi-language (+30)
- Small (20K lines of C++ code)
- Large and active open source community.
- Open source LGPL free software (large community)

Current Status

- The Framework delivers some components which can be connected to each other in order to construct a processing pipeline(s).
- All components share a common base called Device (ZeroMQ Class).
- Devices are grouped by three categories:
 - Source:
 - Data Sampler
 - Message-based Processor:
 - Sink, Splitter, Merger, Buffer, Proxy
 - **Content-based Processor:**
 - Processor



Integrating the existing software:



ROOT Files, Lmd Files, Remote event server, ...



FairRoot: Example 3

4 -Tracking stations with a dipole field

Simulation: 10k event: 300 Protons/ev

Digitization

Reconstruction: Hit/Cluster Finder

From digits to hits with ROOT:





RUN	CPU Time (s) (Wall time)	Memory (Mbyte)
10k Events, 300 Protons/event	100	263

From digits to hits with **ØMQ**:





Vs.





Throughput ~ 1000 ev/s Total Memory 263 Mb



Throughput ~ 2000 ev/s Total Memory 526 Mb



Throughput ~ 3300 ev/s

Total Memory 1052 Mb



Throughput ~ 3500 ev/s



Throughput ~ 2660 ev/s



Throughput Event/s

Before we continue:



14.7 s 75 Mb



Throughput ~ 4166 ev/s Total Memory 720 Mb

M. Al-Turany, ALICE offline week

Wall time: 24 s

19.25s 35.7 Mb



Throughput ~ 5190 ev/s Total Memory 692 Mb

M. Al-Turany, ALICE offline week

Wall time: 19.25 s



Throughput ~ 4780 ev/s Total Memory 342 Mb



Throughput ~ 7320 ev/s Total Memory 1245 Mb



Throughput ~ 7400 ev/s Total Memory 1355 Mb



2 x 2.4 Xeon Quad core Intel Xeon

Throughput ~ 6560 ev/s Total Memory 643 Mb

M. Al-Turany, ALICE offline week

Wall time: 30.5 s

Wall time: 23.74 s



Wall time: 36.4 s



Summary

- ZeroMQ communication layer is integrated into our offline framework (FairRoot).
- On the short term we will keep both options: ROOT based event loop and concurrent processes communicating with each other via ZeroMQ.
- On long term we are moving away from single event loop to distributed processes.

Next Step: Design and development of a dynamic deployment system (DDS)

- STORM is very attractive but no native support for C++ !
- We need to utilize any RMS (Resource Management system)
- Support different topologies and process dependencies
- Device (process) is a single entity of the system
 - Each device has its own watchdog process
 - Devices are defined by a set of props and rules,
 - All devices are statically inherited (should support) 3 interfaces:
 IDDSConfig, IDDSStatus, and IDDSLog



Thank you

Backup

ZeroMQ sockets provide efficient transport options

- Inter-thread
- Inter-process
- Inter-node
 - which is really just interprocess across nodes communication

ØMQ							
inter-	node	inter-process	inter-thread				
PGM	TCPMP	named pipe	in-memory				

PMG : Pragmatic General Multicast (a reliable multicast protocol) **Named Pipe**: Piece of random access memory (RAM) managed by the operating system and exposed to programs through a file descriptor and a named mount point in the file system. It behaves as a first in first out (FIFO) buffer

The built-in core ØMQ patterns are:

- Request-reply, which connects a set of clients to a set of services. (remote procedure call and task distribution pattern)
- **Publish-subscribe**, which connects a set of publishers to a set of subscribers. (data distribution pattern)
- **Pipeline**, which connects nodes in a fan-out / fan-in pattern that can have multiple steps, and loops. (Parallel task distribution and collection pattern)
- **Exclusive pair**, which connect two sockets exclusively







Entities



Entities

