

Technological prototype of the SiW ECAL

Vincent Boudry

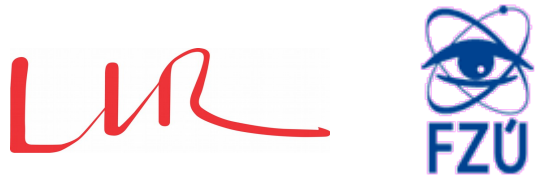
École polytechnique



***3rd AIDA annual meeting
Vienna
26/03/2014***



ECAL in AIDA



FE & Silicon sensors (51 kEuro+18 kEuro)



Mechanical aspects – Cooling (27 kEuro)



Ecal Front End Electronics (31 kEuro)



Formerly on SiTr & DAQ ... now gluing



Former EUDET partners

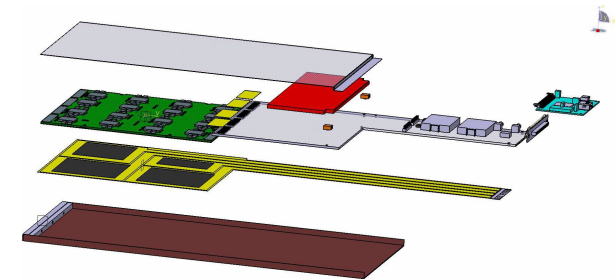
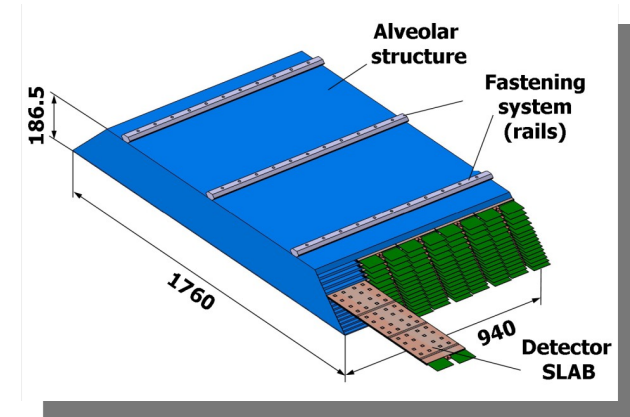
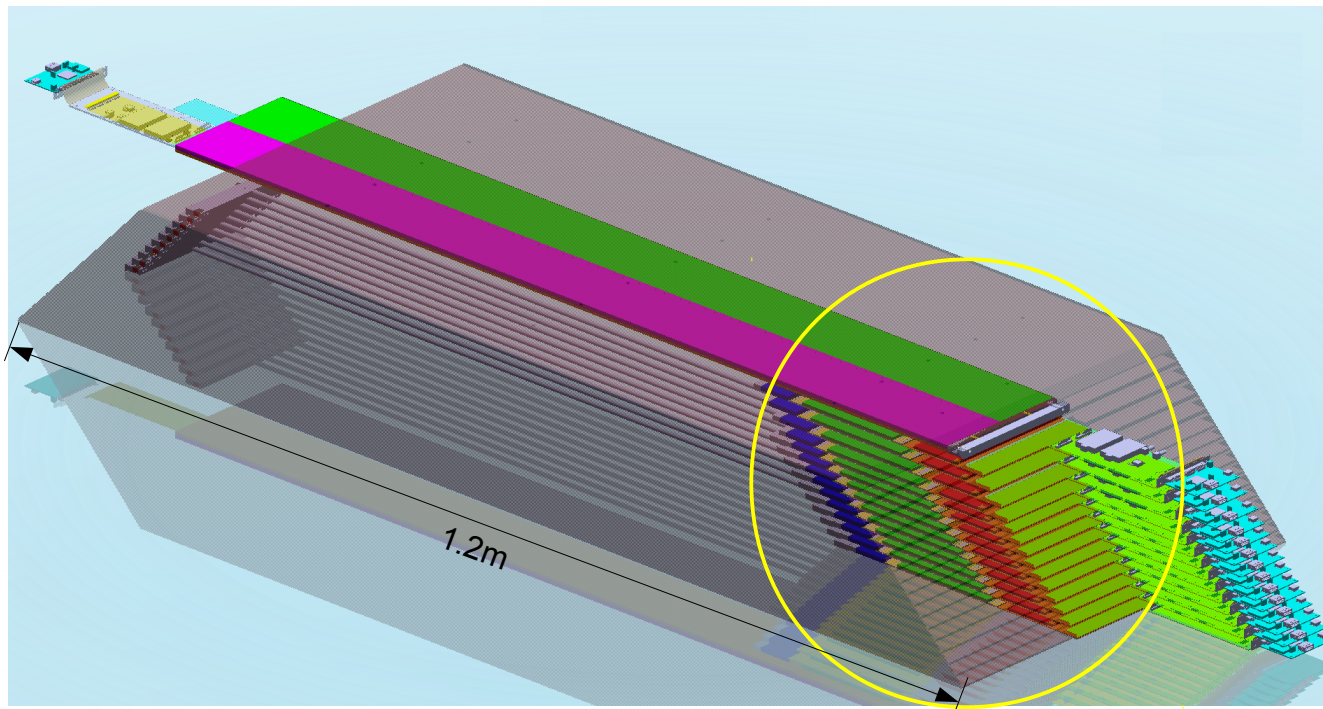
Project description: ECAL extension of the EUDET Module

Project task: Electromagnetic calorimeter of at least 18x18 cm² area

i.e. several short ASUs assembled in vertical direction

MS 46 to be delivered in month 36 → delay expected.

Technological prototype



Additional work not mentionned here:
ILD studies (optimisation, mechanical integration, performances, ...)

Acquisition

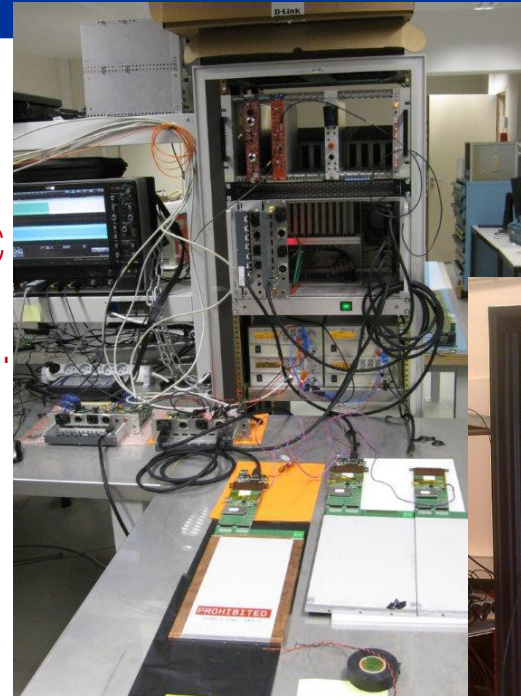
HW:

- (EUDET) LDA is substituted by GDCC
- bug fixes in DIF/LDA-GDCC firmware.
 - Lost packets rate $\ll 1\%$
- ready for larger production (\rightarrow fall)

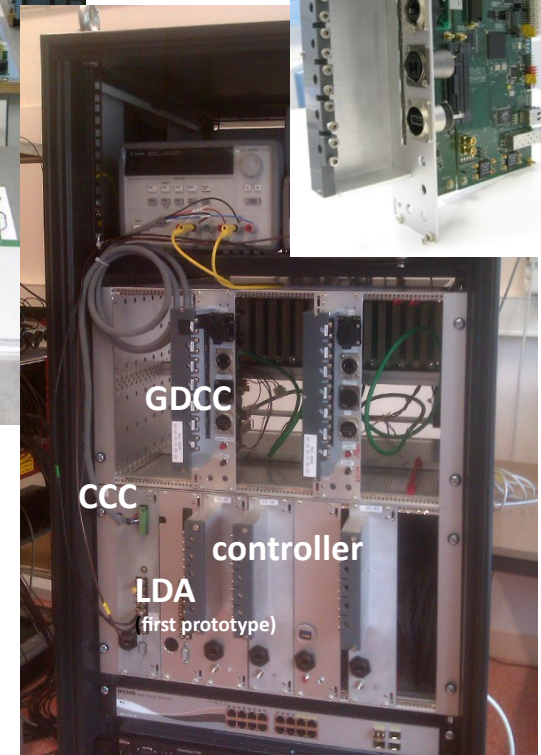
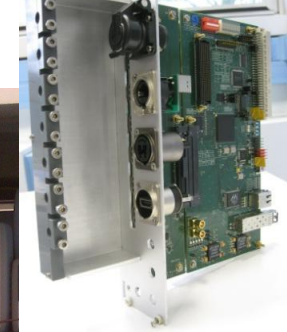
SW:

- new “distributed” DAQ software (CALICOES)
- quasi-online monitor GUI,
- SKIROC configuration GUI,
 - “automatic” channel masking

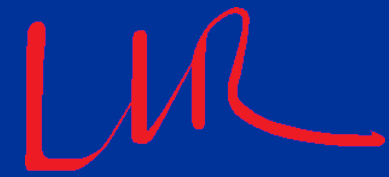
Fully stable \rightarrow started sharing



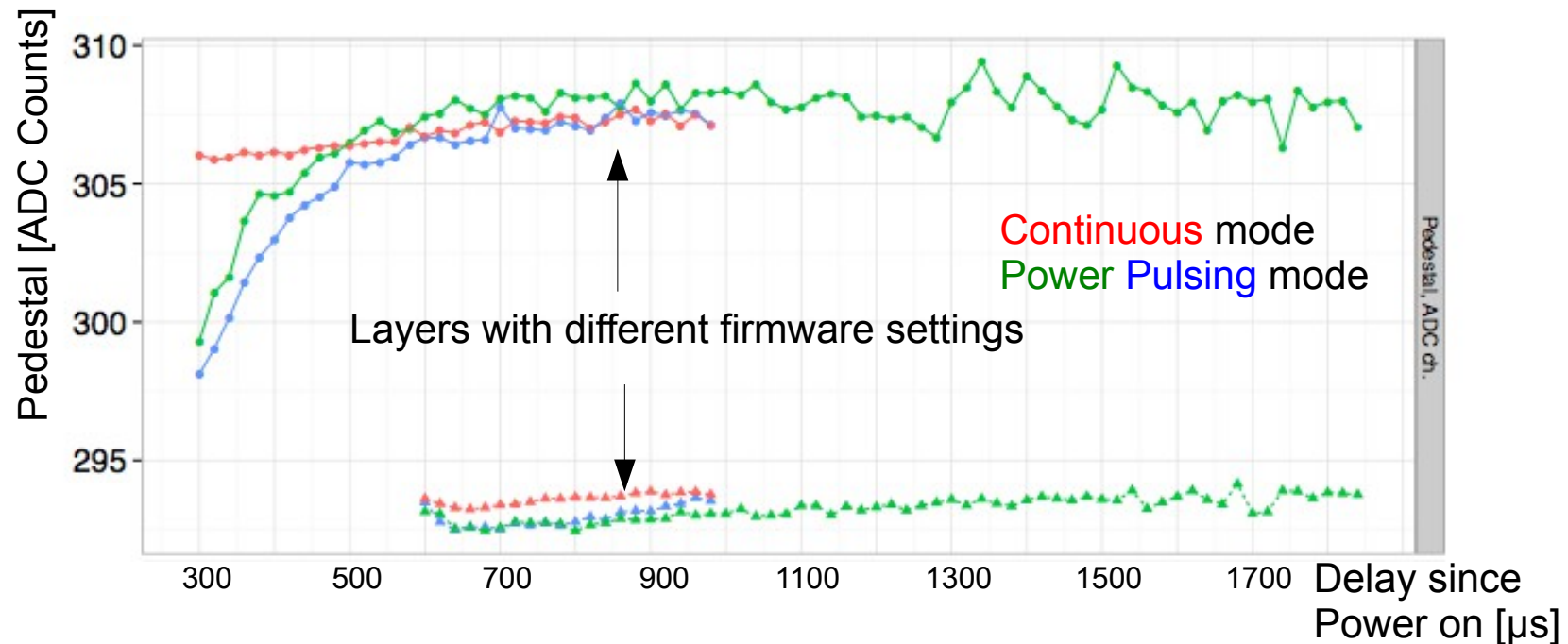
GDCC board



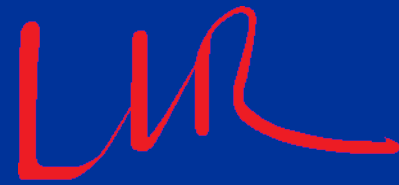
2013 TB activities:



- 2 beam tests in 2013 in DESY with 1–5 GeV electrons
 - ... debugging
- Power pulsing works, pedestal stabilizes during 600 μs , S/N is worse for first few msec. S/N improves for higher SKIROC gains
 - Performance paper submitted [JINST]



SKIROC configuration tool



Full control of 4 SKIROCs in one ASU. Plan to extend to many ASUs.

- (labview) → Currently in Ruby (→? Python) + GTK

The screenshot displays the SKIROC configuration tool interface. At the top, there are tabs for 'Choose chip', 'Show descriptions', and a file path: '/home/balagura/c/ecal/skiroc/config/example4skirocs.txt'. Below this, the interface is divided into several sections:

- EC (Event Controller) parameters:** A list of 18 parameters, each with a 4-bit selector (0-3) and a label like 'EC: ChipSat', 'EC: Dout1', etc.
- EN (Event Node) parameters:** A list of 12 parameters, each with a 4-bit selector and a label like 'ENADCRamp', 'ENBandgap', etc.
- GC (Gain Controller) parameters:** A list of 12 parameters, each with a 4-bit selector and a label like 'GC: ADC Ramp Slope', 'GC: Auto Gain', etc.
- PP (Pre-Processor) parameters:** A list of 12 parameters, each with a 4-bit selector and a label like 'PP: DAC4bit', 'PP: DelayTrigger', etc.
- Global parameters:** Four sliders for 'GC: Capacitor PA Comp' (value 7), 'GC: Capacitor PA Fdbck' (value 15), 'GC: Chip ID (8 bits)' (values 0, 1, 3, 2), and 'GC: DAC0: Trigger' (value 0).
- DA (DAC Adjustment) table:** A 6x8 grid of sliders for '4-bit DAC Threshold Adjustment'.
- PA (Pre-Amp) table:** A 6x8 grid of sliders for 'PreAmp, In_calib & I_leakage'.
- TM (Trigger Mask) table:** A 6x8 grid of sliders for 'Trigger Mask'.

Si Wafers studies : test benches

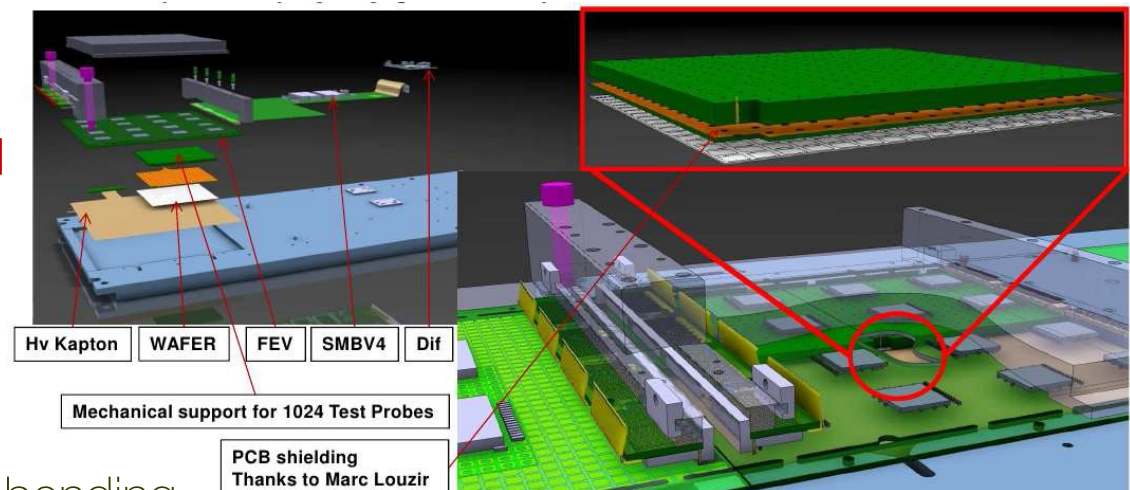
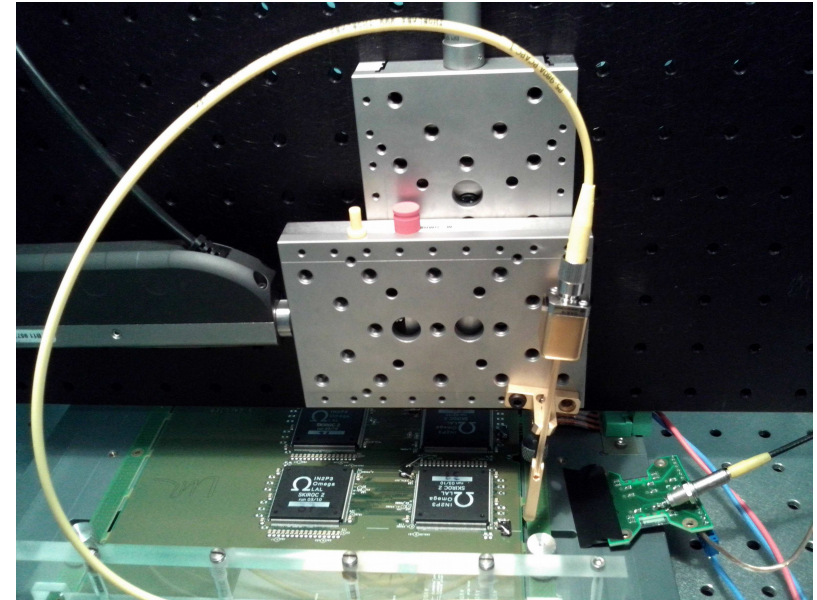


New laser TB \Rightarrow X-talks studies

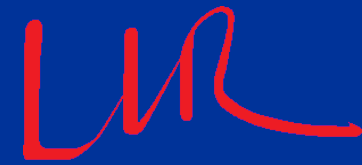
- Laser characteristics: = 1056 ± 5 nm, 200 kHz, < 1 nsec pulse generates
 - ~ 700 MIP signal. Intrinsic silicon absorption length at 300 K: ≈ 0.8 mm.
 - Reproduction of “square events”...

Hamamatsu Silicon sensors:
16x16 pixels of 5.5×5.5 mm², thickness 330 μ m.

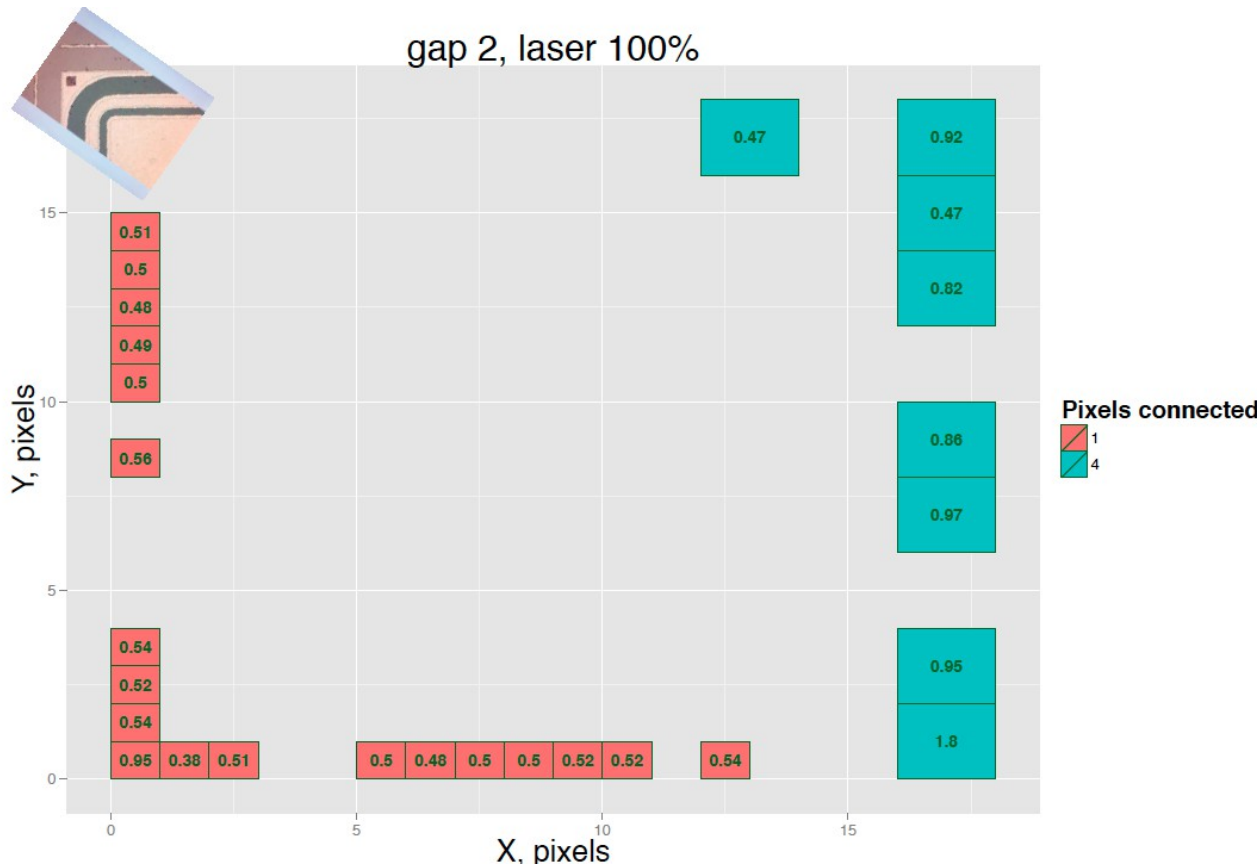
- In technological prototype Si pixels are glued to PCB with conductive epoxy.
- New mechanical setup was designed \Rightarrow sensors may be easily changed.
 - ≤ 1024 spring contacts of 5 mm length between pixels and PCB pads.
 - To be improved: high noises, PCB bending.



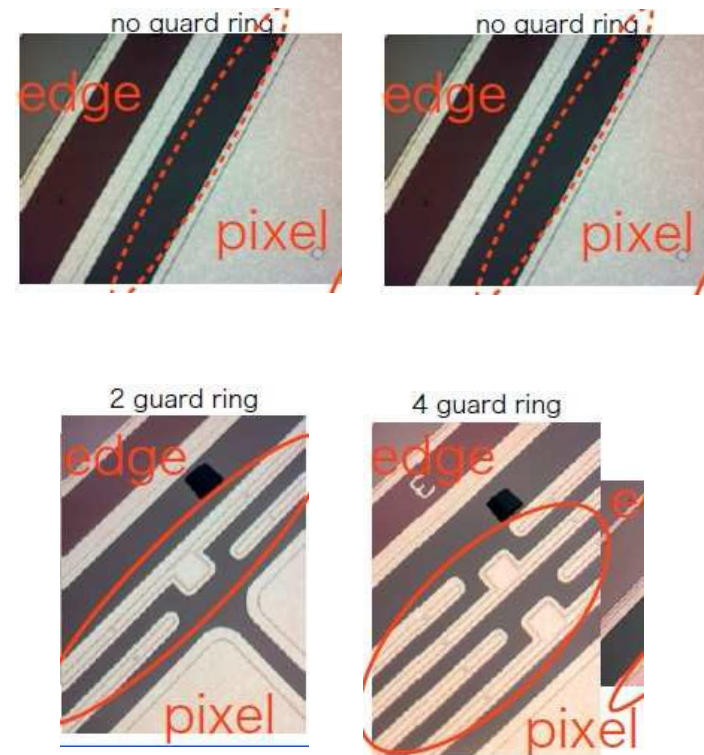
X-talks measurements



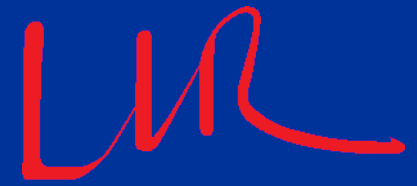
- Preliminary:
 - Not all springs installed and not all have contacts \Rightarrow ~50% operational.
- Clear signals in connected pixels.
 - A typical induced signal is ~ 0.4...0.5% per outer pixel side (x2 for corner, x2 in case of 4 connected pixels).



« baby wafers »
(Hamamatsu)



New PCB: FEV8 → 9 → 10



- 4 → 16 chips per ASU with BGA packaging.
- 10 FEV9 received
- good flatness <0.5 mm: OK to glue flat Si sensor.

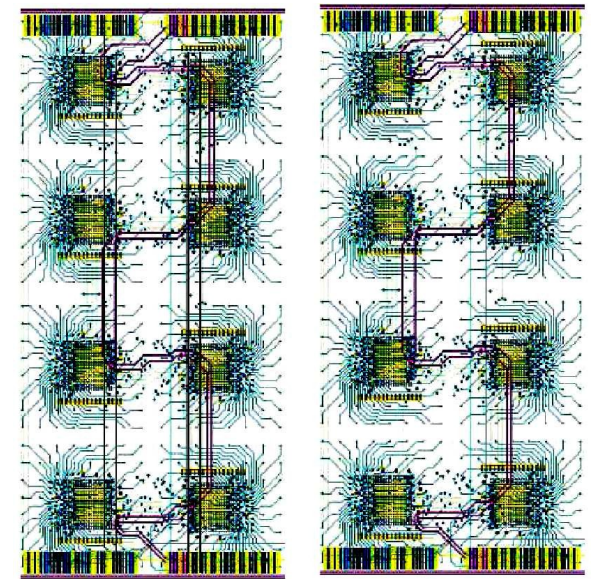
Many improvements:

- x4 channel density
- 2–3 times shorter signal traces
 - less input C and pick up noises
- power decoupling capacitors to reduce noises, corrected SKIROC “grounding”
- signal transmission (esp. clock) over long distances ~ 1.5m, two options in FEV9:
 - snake or straight lines (x2 interconnections),

FEV10 will have straight lines.; BGA thickness 1.6 → 1.2mm

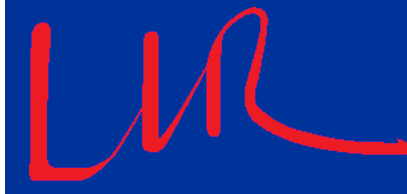
FEV9 with all components installed

(> 16 tested SKIROCs) ordered, expected this week



Straight and snake lines

Next steps



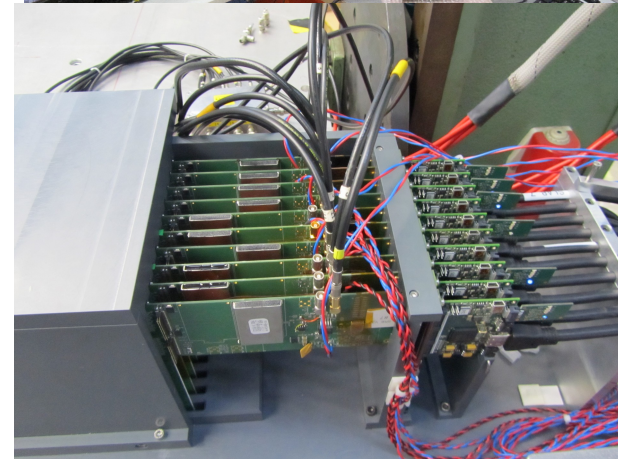
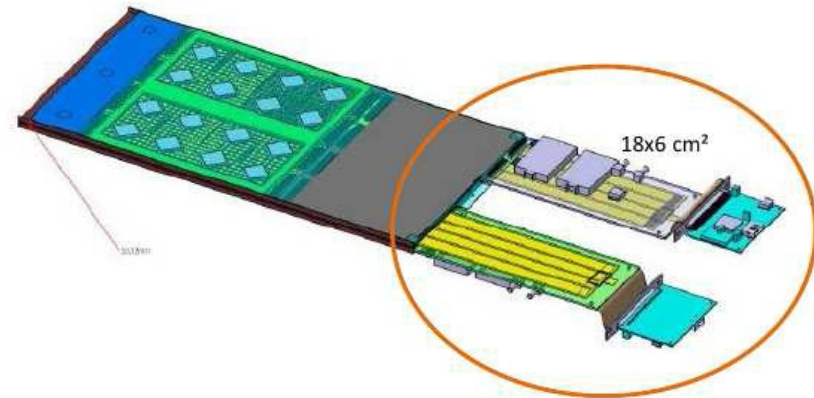
SMB4 design (between ASUs and DIF) has started: with power distribution for many ASUs and with special drivers for signal propagation along long lines.

- U-type short slab production
- Physics tests (cosmics, laser, PHIL?)
- Long slab production
- Goal: produce ≥ 1 long(6-7 ASUs) and short slabs to fill one tower in full scale mechanical prototype.
 - Possibly reuse existing 1/4 ASU short slabs.

With GEANT4 simulation, find their affordable fraction in the tower \Rightarrow "ECAL" of $18 \times 18 \text{ cm}^2$

Test at CERN in 2015.

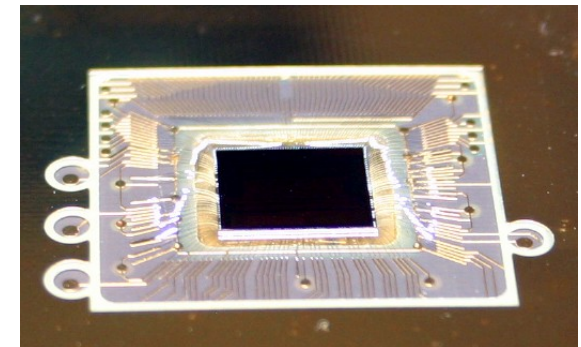
In parallel, look at boards integration in ILD.



Chip-On-Board PCB

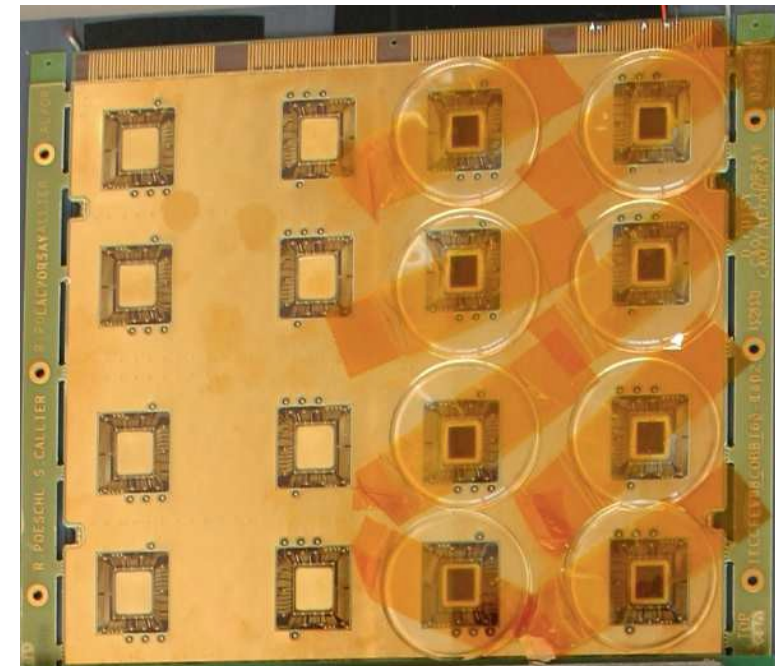


Only 1.2 mm thick,
8 naked die chips wire bonded

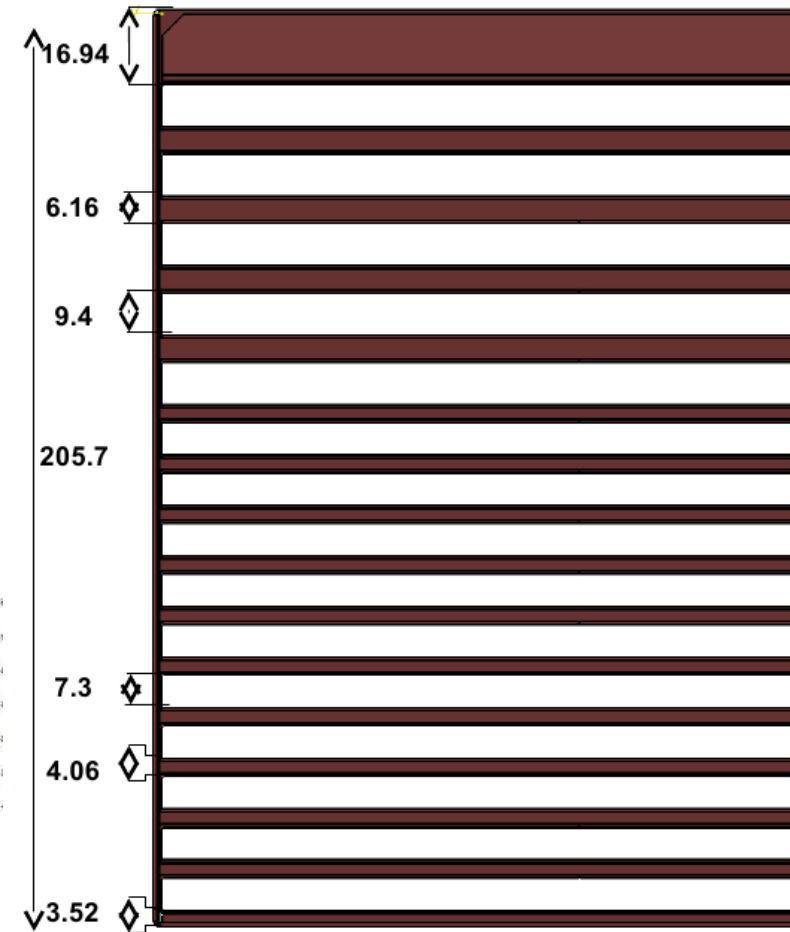
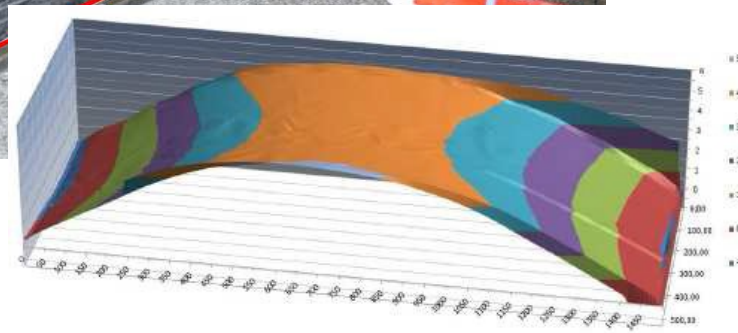
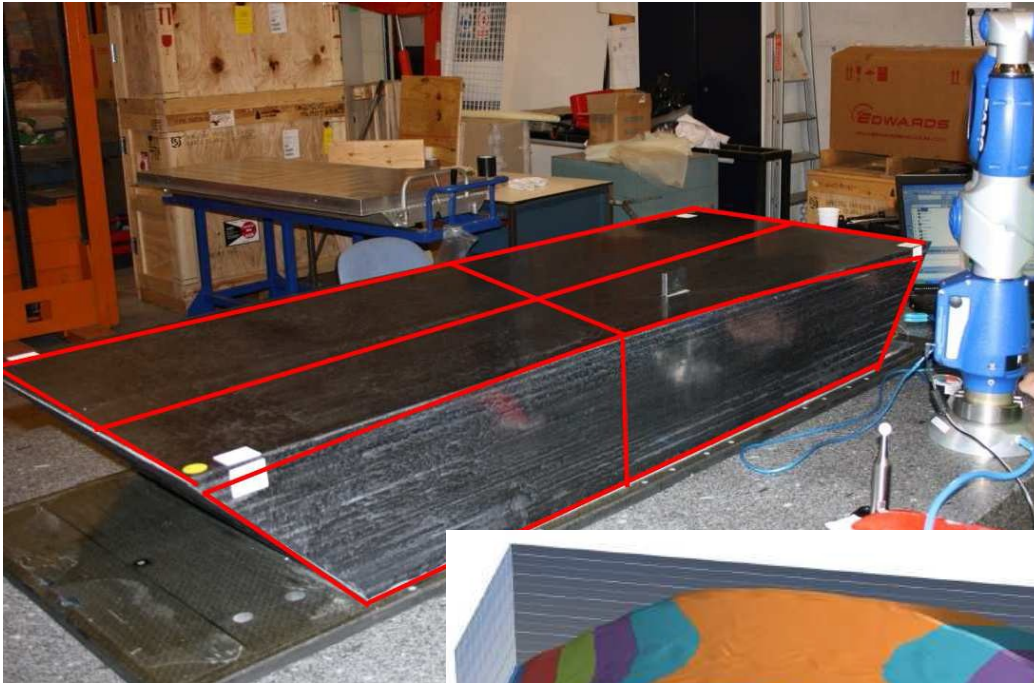


Status: two productions,

- ≥ 1.2 mm bending prevents gluing Si.
- Production under supervision of [SKKU@Suwon](#) (Mechanically) promising board from EOS (Incheon)
- Visit to SKKU to arrange FEV_COB production with SKKU
- Contact with two manufacturers (EOS and HSDGT)



Carbon-Fiber Tunsten structure



Prototype: 3/5 of one ILD module, ~ 600 kg.

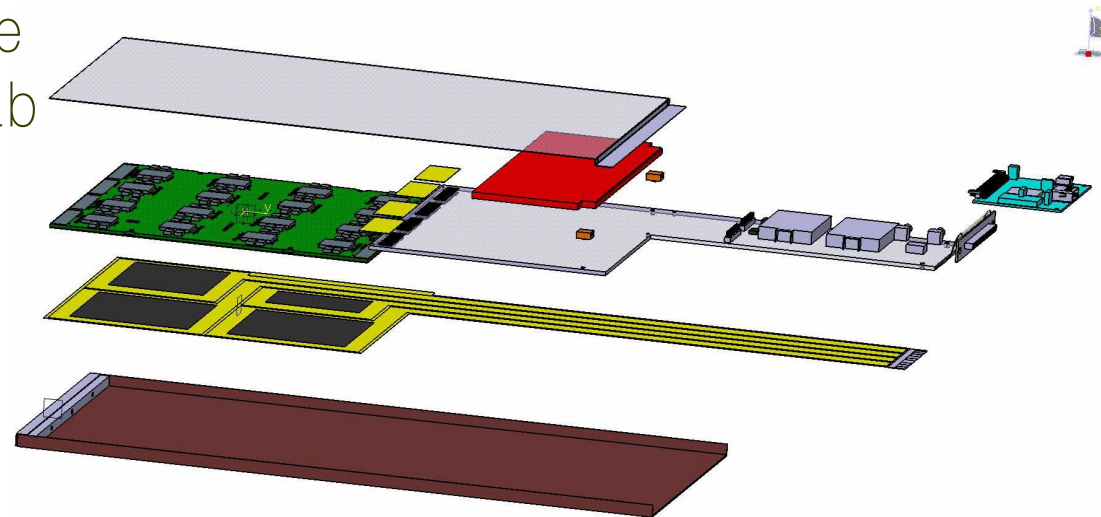
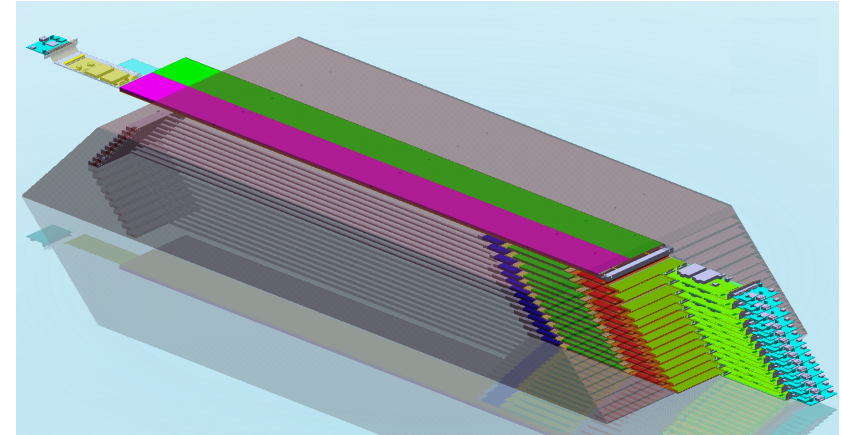
Separately built layers “cooked” together.

Simulated mechanically & thermally.

U- and H-shape slabs: plans

Fill alveolas with

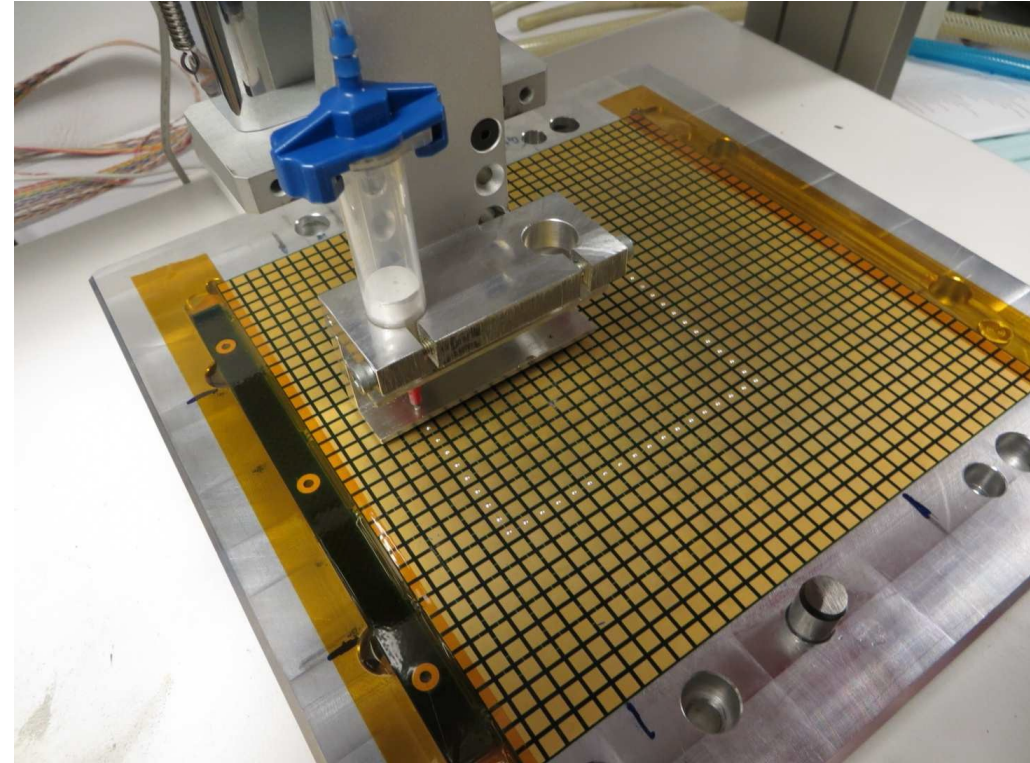
- 14 "U"-shape short slabs
- 1 "H"- or
1 "U"- shape
long slab without or with W.
- If without: possibility to glue
(and then detach) W to slab
from Si side and insert to
alveola.



9 sensors were glued by robot

Next steps:

- second robot for positioning and aligning
- glue 4 sensors on PCB with 100 μm gaps
 - \Rightarrow for summer...
- prepare technology for mass production



Assembly bench

Development of a set of specifications to assure proper assembly of four wafer ASUs

- Tolerances of PCB, H or U board
- Example : Mechanical stress on wafers during interconnections
 - First set end spring 2014

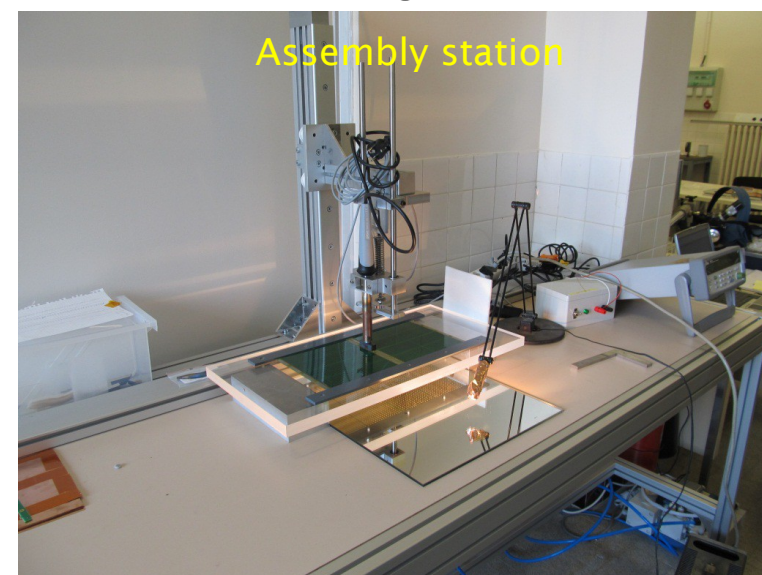


Interconnection station



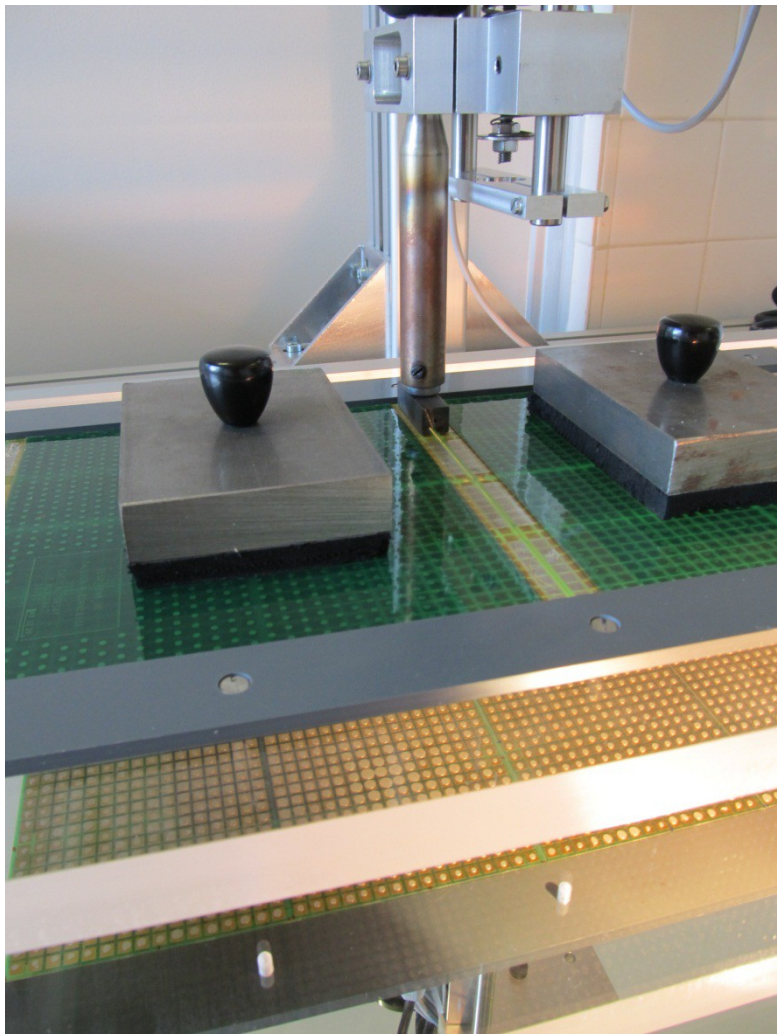
Revision/Scrutinisation of assembly tools

- Development and validation of assembly bench, “easy” reproducibility
- Combination of ASU positioning and interconnection
 - Continuous revision of process with aim to propose a procedure for LC Ecal in ~ 1 year (first version exists however)

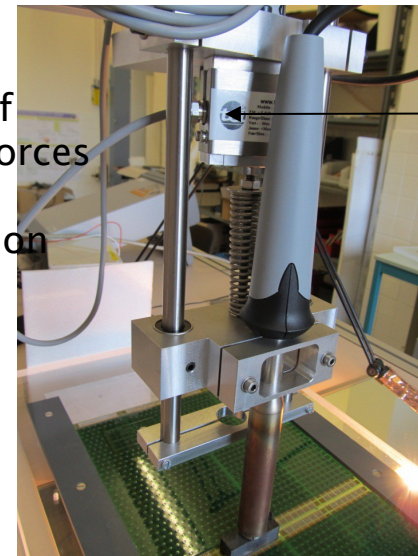


Assembly station

Assembly bench (details)

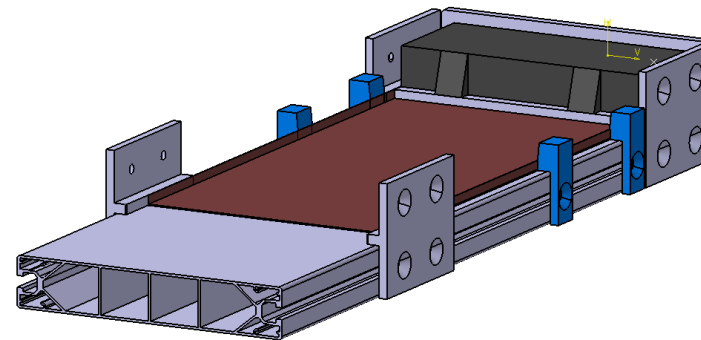
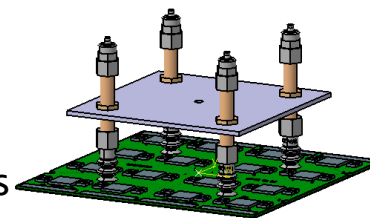


Monitoring of mechanical forces during interconnection



Pressure probe

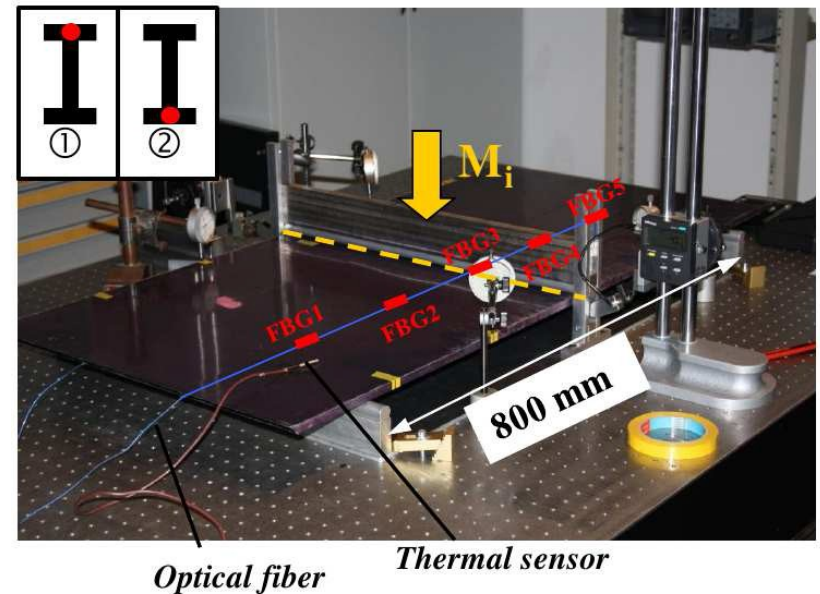
Proposal for an assembly tool for four wafer ASUs



Prototype with molded Bragg grating fibers

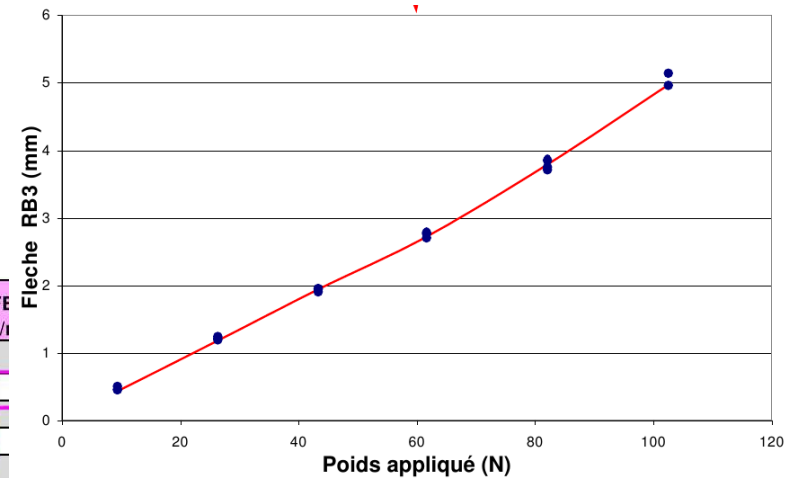
Detailed verification of simulated elongations under loads (by monitoring frequency shift of light reflected by fiber).

- Details on first measurements: <http://indico.cern.ch/event/274076/>, French IRFU Linear Collider Days, Nov'13.
- Done on single alveola
 - to be repeated on structure



Correlation with the experimental data (FBGs):

	Load (N)	ϵ_{yy} FBG1 ($\mu\text{m/m}$)		ϵ_{yy} FBG2 ($\mu\text{m/m}$)		ϵ_{yy} FBG3 ($\mu\text{m/m}$)		ϵ_{yy} FBG4 ($\mu\text{m/m}$)		ϵ_{yy} FE ($\mu\text{m/m}$)
		Exp.	Simu.	Exp.	Simu.	Exp.	Simu.	Exp.	Simu.	Exp.
M1	9,38	-2,52	14	-12,6	-12,2	-29,86	-36,8	-7,41	-8,1	4,91
M2	26,35	0,84	27,8	-32,77	-30,6	-92,9	-100,7	-24,72	-26,5	15,55
M3	43,32	10,92	41,1	-53,78	-49,1	-156,77	-165,6	-39,55	-44,9	26,2
M4	61,64	21,01	55,4	-78,16	-69	-235,57	-237	-59,33	-64,8	31,11
M5	82,08	33,61	71,5	-109,26	-91,4	-336,77	-319,6	-79,93	-87,1	44,21
M6	102,53	48,74	87,4	-145,4	-117,7	-468,66	-413,7	-115,37	-112,8	58,13

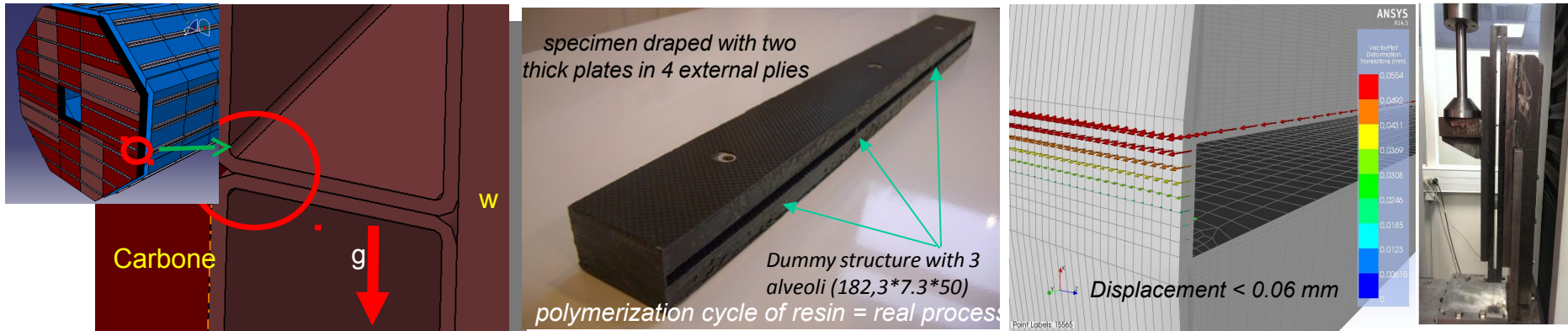


Vérification des paramètres du modèle en comparant la flèche FBG3 mesurée et simulée

Evolution of skin thickness

Correlation of FEA simulations / shearing tests of representative structure

Problem of bending stress of alveoli skins / evolution of external plies



Influence of modification of external ply thickness on the first main constraint of external and internal walls

If external plies thickness increases => **Impact on ECAL dead zone** => Optimization of deflection values

Displacements	~0.1 mm vs 0.5mm for fatigue shearing tests ...
Main constraints	< 159 Mpa both
Shearing constraint	11.5 Mpa vs 6 (1,8/wall) Mpa for shearing tests ...

From simulations to shearing tests
(ANSYS APDL / SAMCEF / ANSYS ACP)

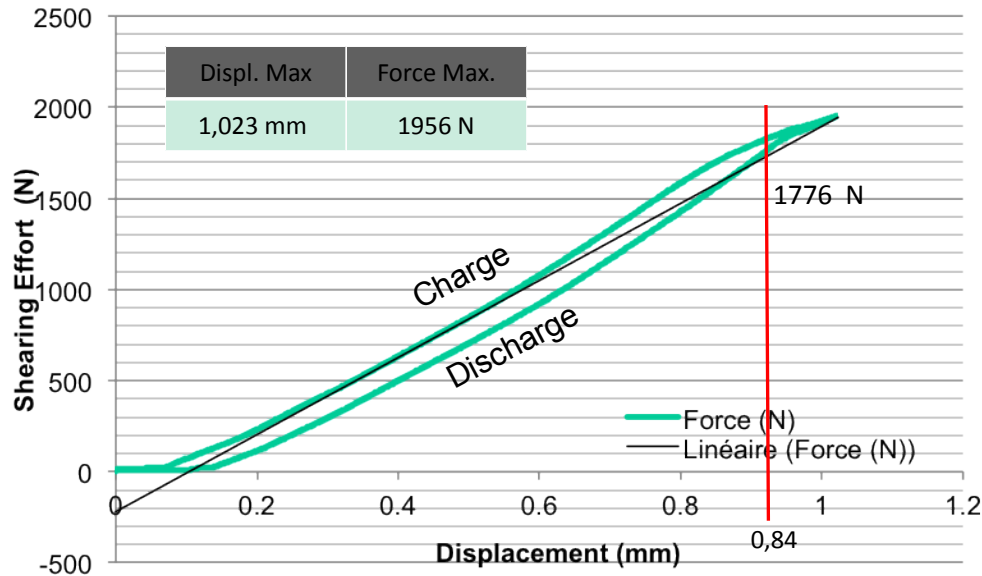
Tests & simulations to be performed

- Adapt FEA parameters to simulate the whole structure / shearing results
- Destructive test on a existing structure (*demonstrator -EUDET*) / **verification** of bonded structures
- Process: increase intercoat adhesion with structural adhesive film
- Process: obtaining reliable thicknesses of walls (*specific long moulds, tooling development*) / **Draping optimization**
- Reliability tests: good & uniform impregnation of parts, good compacting
- Resistance of End-Caps to earthquake
- “Mass” production conception (*ply book enhancement, tooling, process*)

ECAL End-Caps: shearing tests

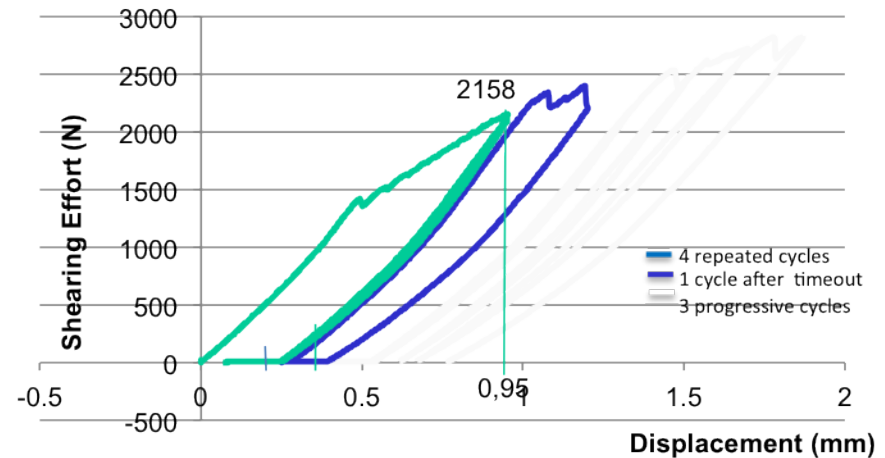


Monotonic shearing test

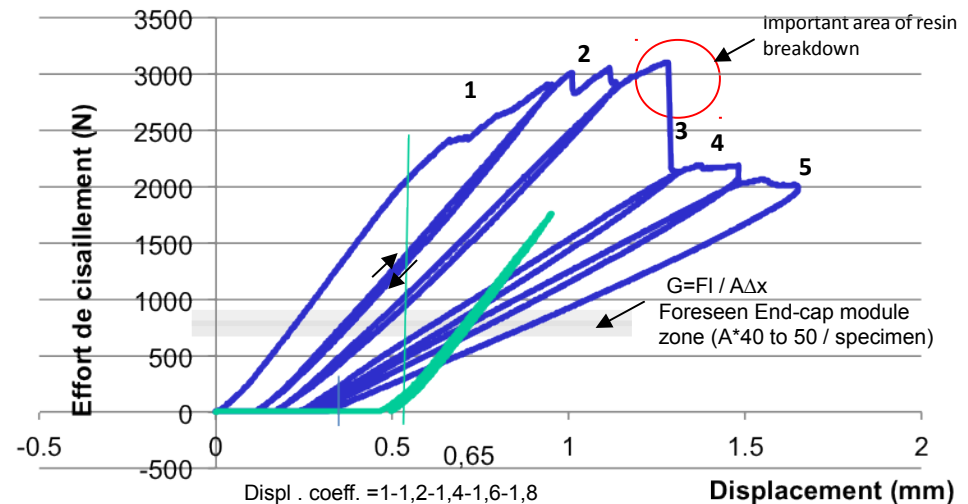


Destructive tests with charge & discharge cycles / hysteresis & weakening of the structures (resin) during repeated stresses

Fatigue + Progressive shearing cycles



Progressive shearing cycles



Reduction in stiffness
predictable during integration

(G# 85 MPa to 74 Mpa)

Stay < $\Delta x = 0.35$ mm (mechanical limiters) or

Increase No. of envelope folds (/ seism)

Max. admissible flexion value of slabs to be confirmed

To be continued in 2014

Structure of end caps

2.5 m alveoli layer molding

- **The end-cap layer test consisted of**
- **3 long alveoli** (representative of end-cap module longest layers)
- **Width of cell : 182,3 mm** like barrel's one (for electronic uniformity)
- **Thickness of cells : 7.3 mm - wall: 0.5 mm**
- **Length : 2.490 m**



long layer of 3 alveoli demolded nov.2013 with new system woven-resin (C202+ET445) .To be improved

Thick plates & fastening system

ANSYS Noncommercial use only

Optimization of fastening
~2,56 T

EUDET Carbon HR plate 13 mm with metallic inserts to Carbon HR Rails

Building on going of transport and handling tools for integration & tests

Ongoing developments

- Design of specific tools for long draping
- **Industrialisation study of process** / long alveoli layers (~ 540 cells up to 2,50m)
- Continuing the mounting of the handling tool of modules & design /quarters End-Cap
- Thick composite plate for double **low section rails: OK**
- Characterization, tests & optimization: **positioning / bending of modules**
- Towards construction of a long EC module ?

Conclusion

Much progress:

- acquisition: GDCC, firmware, low level SW (Calicoes) + other software tools
 - to be integrated with EUDAQ for common DAQ
- VFE: BGA solution ready to be tested, small defects form FEV, Power pulsing works, with only slightly higher noises
 - Fixed design for technological prototype: FEV10 (BGA)
 - Design new adaptor board SMB4 for long slab
- Wafers characterisation: test benches (flexible & laser), first measurement of capacitive guard ring cross talks
 - Physics tests: charge injection, cosmics, laser, possibly PHIL accelerator

Production of 14 short slabs and ≥ 1 long slab being prepared

- quality procedure being established;
- 9 sensors glued by LPNHE robot
 - Test gluing 4 sensors to PCB with 100 um gaps, positioning and alignment robot
 - Produce U-type short slabs with FEV10, test them, then produce ≥ 1 long slab (6-7 ASUs)
- First assembly chain running ~ july
 - **Equip with detectors one tower of full scale prototype and test at CERN beams (2015)**
 - \Rightarrow ~fall 2014
 - Possibly, test silicon sensors from other producers

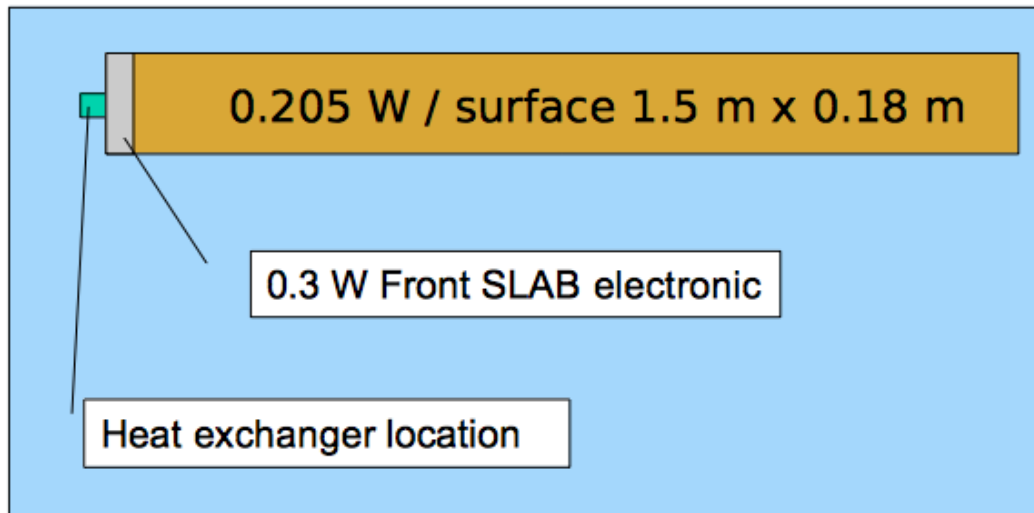
Cooling capacity

Power dissipation : Final goal with power pulsing 1/100 s

For 1/2 SLAB from barrel
Wafers consumption : 0.205 W
Front SLAB electronic : 0.3 W

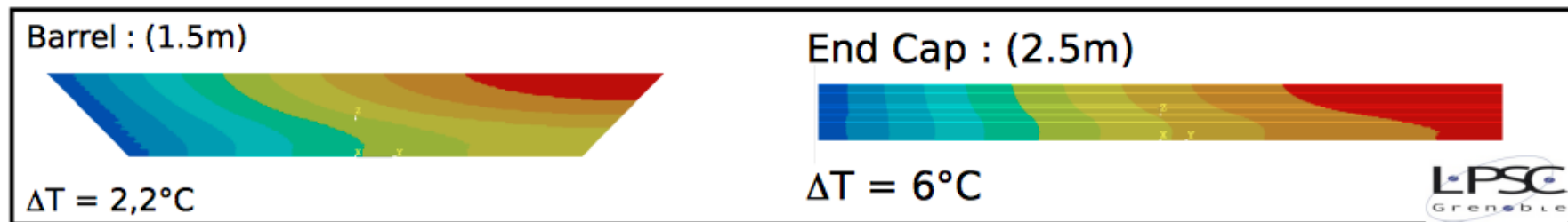


Ecal detector : 4.5 kW



Passive cooling : OK

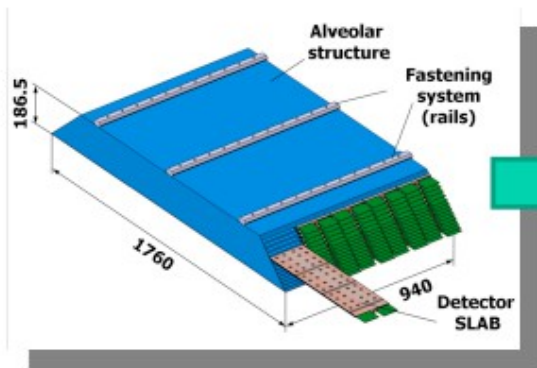
... support up to 10x bigger heat load (for details see backup)



		1/2 SLAB						
		Front electronic (W)	Wafer (W)	Total ECAL (W)	Temperature variation near the exchanger (°c) (Thermal contact resistance)	Temperature variation along the SLAB (°c)	Température at the end of the SLAB (°c) (water temp : 18°c)	Remark
		/ Electronic consumption						
Configuration 1	ECAL Goal	0.3	0.205	4500	0.5	2.2	20.7	Passive cooling : OK
Configuration 2	Front elec x 10	3	0.205	30 000	3.2	2.2	23.4	Front SLAB electronic close to the heat exchanger => low impact of the SLAB temperature
Configuration 3	Wafer x 10	3	2.05	45 000	5.1	24	47.1	Passive cooling may work
Configuration 4	Wafer x 100	3	20.5	205 000	24	250	292	Passive cooling will not work !! We need to work on active cooling in the SLAB

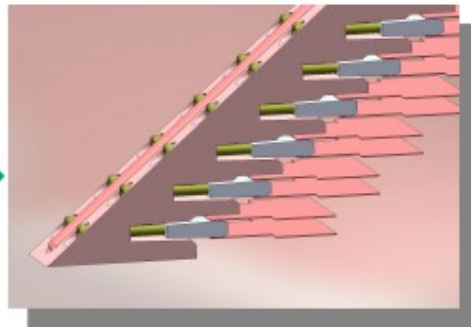
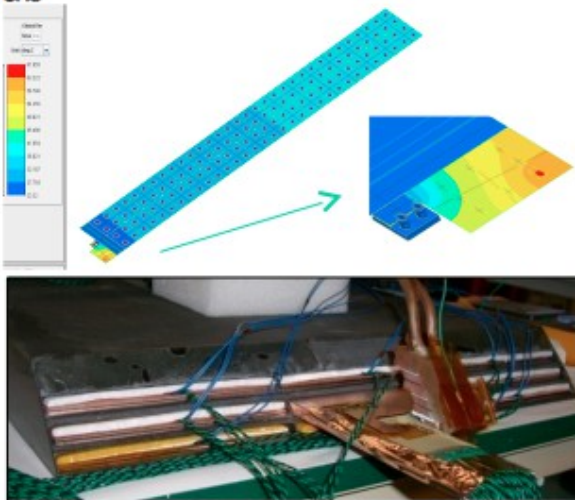


Study from the power source to the global cooling



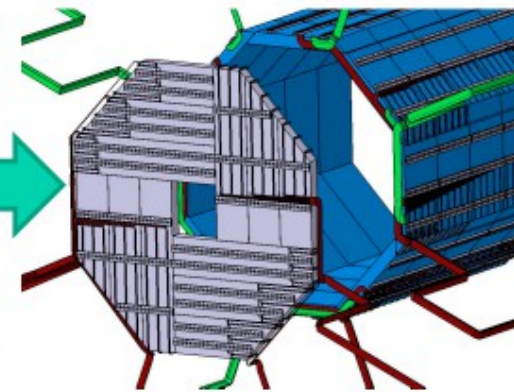
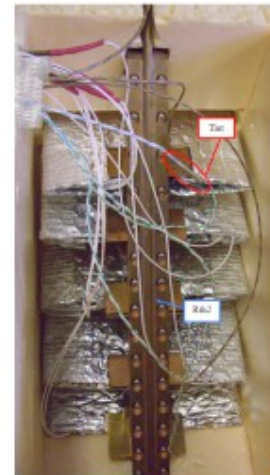
SLAB

Thermal simulation and test on Slab



Heat exchanger

Simulation and test on different type of heat exchanger s



Global cooling
True scale leak less loop

