



# Drive Beam Quadrupoles

**Jim Clarke**, Norbert Collomb, Ben Shepherd, Graham  
Stokes

**STFC Daresbury Laboratory, UK**

Antonio Bartalesi, Michele Modena, and Mike Struik

**CERN, Geneva, Switzerland**

**4<sup>th</sup> October 2013**

# Current Work Programme

- **Objectives:**

- Design, assemble and test a tuneable permanent magnet quadrupole of sufficient strength and quality for the high energy end of the drive beam (2.4 GeV).
- Design, assemble and test a tuneable permanent magnet quadrupole of sufficient strength and quality for the low energy end of the drive beam (0.24 GeV).

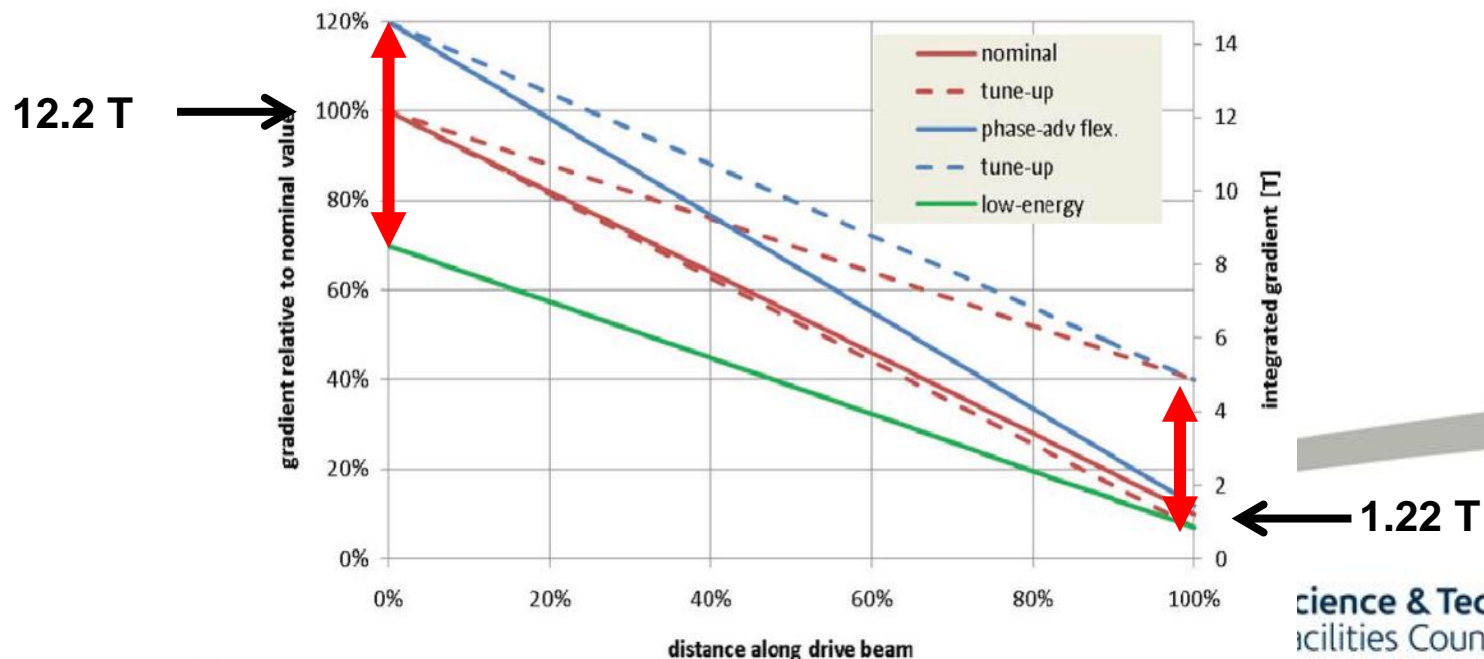
- **Deliverables:**

- A high strength (for a beam energy of 2.4 GeV), tuneable, permanent magnet quadrupole prototype (31/3/12)
- A report covering the design and test results of the high strength prototype (30/9/12)
- A low strength (for a beam energy of 0.24 GeV), tuneable, permanent magnet quadrupole prototype (30/9/13)
- A report covering the design and test results of the low strength prototype (31/3/14)
- Mass production assessment



# Quadrupole Tunability

- The **nominal** maximum integrated gradient is 12.2T and the minimum is 1.22T
- For operational flexibility each individual quadrupole must operate over a wide tuning range
  - 70% to 120% at high energy (2.4 GeV)
  - 7% to 40% at low energy (0.24 GeV)



# Quadrupole Specification

Parameter	High-energy side	Low-energy side
Number of magnets		41 400
Nominal maximum strength [T] (integrated gradient)	12.2	1.22
Stability		$5 \times 10^{-4}$
Integrated gradient quality		0.1%
Good field region [mm]		11
Bore radius [mm]		13
Available width [mm]		391
Available height [mm]		391
Available length [mm]		270



# Permanent Magnet Option

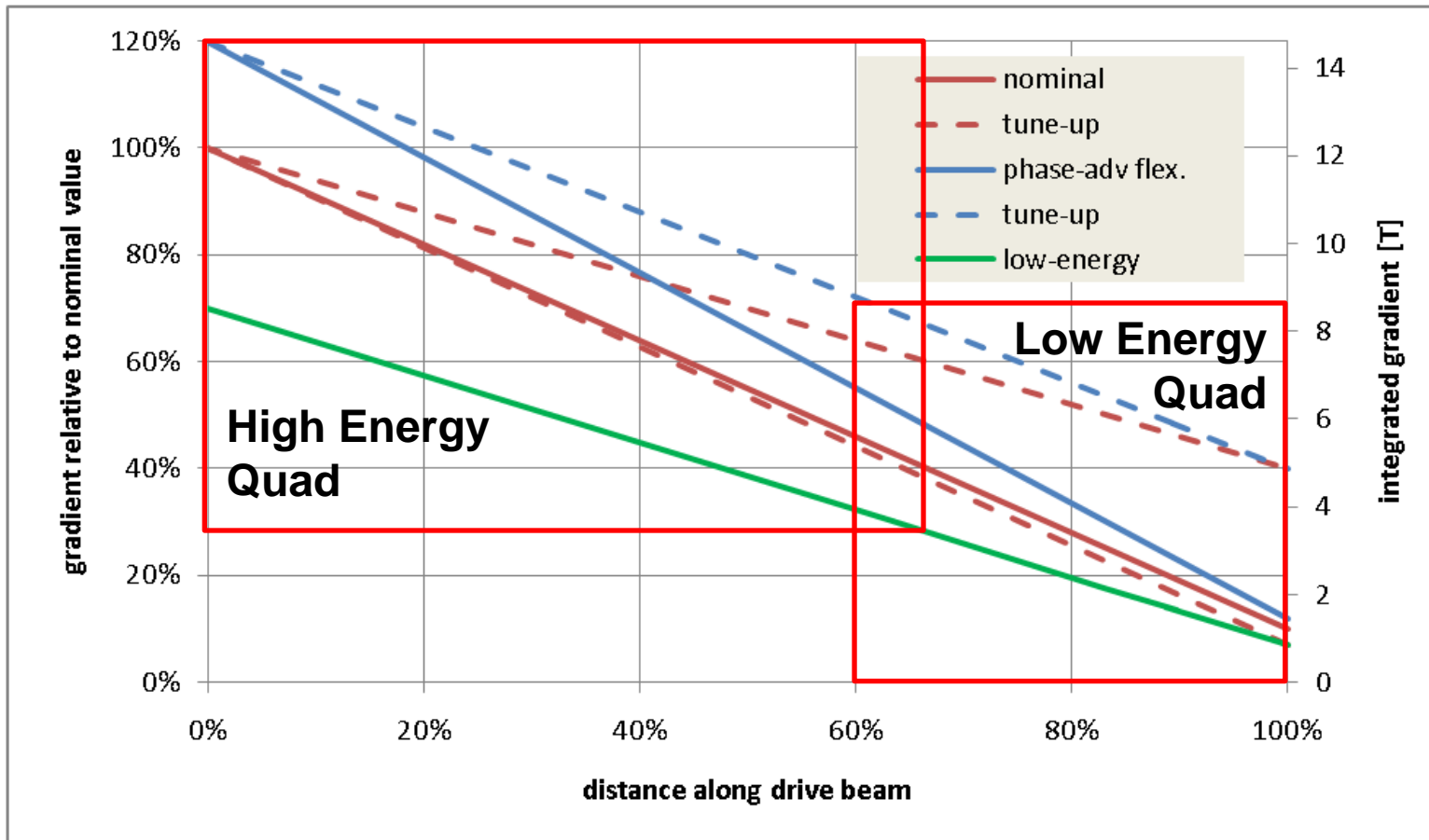
- The integrated magnet strength requirement is very challenging (given the space constraints) for a conventional electromagnet
- The nominal power consumption for the EM version will be **~13MW** in nominal mode and up to **~34 MW** in tune-up mode
- Total Power Load limit to air within the tunnel is only **150 W/m** (all components)
- A PM quad would potentially have many advantages
  - Vastly reduced electrical power
  - Very low operating costs
  - No cooling water needs
  - Very low power to air
- We have been investigating the PM option for the drive beam in detail

# Permanent Magnet Challenges

- There are many existing PM quadrupole examples
- The combination of high strength, large tunability, high field quality, and restricted volume meant that a new design was required
- Additional challenges for PM include possible **radiation damage**, field **variation with temperature**, PM strength **variation from block to block** (material and engineering tolerances)
- The complete tuning range (120% to 7%) could not be met by a single design
- We have broken the problem down into two magnet designs – **one high energy and one low energy**



# Quadrupole Types



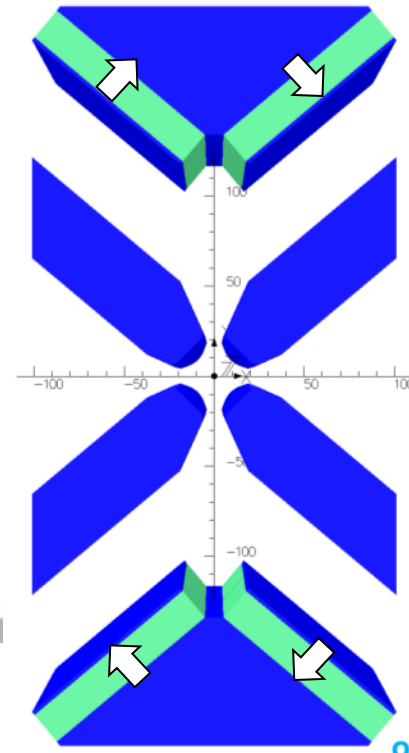
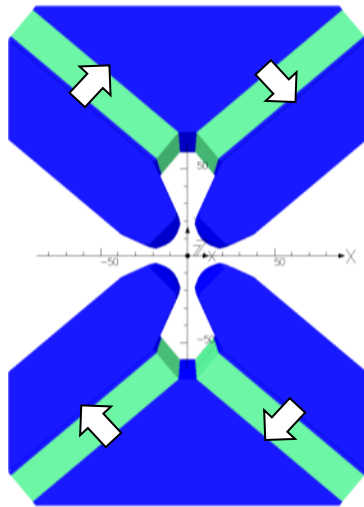
High energy quad – Gradient very high  
Low energy quad – Very large dynamic range



# High Energy Quad Design

- **NdFeB** magnets with  $B_r = 1.37$  T (VACODYM 764 TP)
- 4 permanent magnet blocks each 18 x 100 x 230 mm
- Mounted at optimum angle of  $40^\circ$
- **Max gradient = 60.4 T/m (stroke = 0 mm)**
- **Min gradient = 15.0 T/m (stroke = 64 mm)**
- Pole gap = 27.2 mm
- Field quality =  $\pm 0.1\%$  over 23 mm

Stroke = 0 mm



Stroke = 64 mm

Poles are permanently fixed in place.

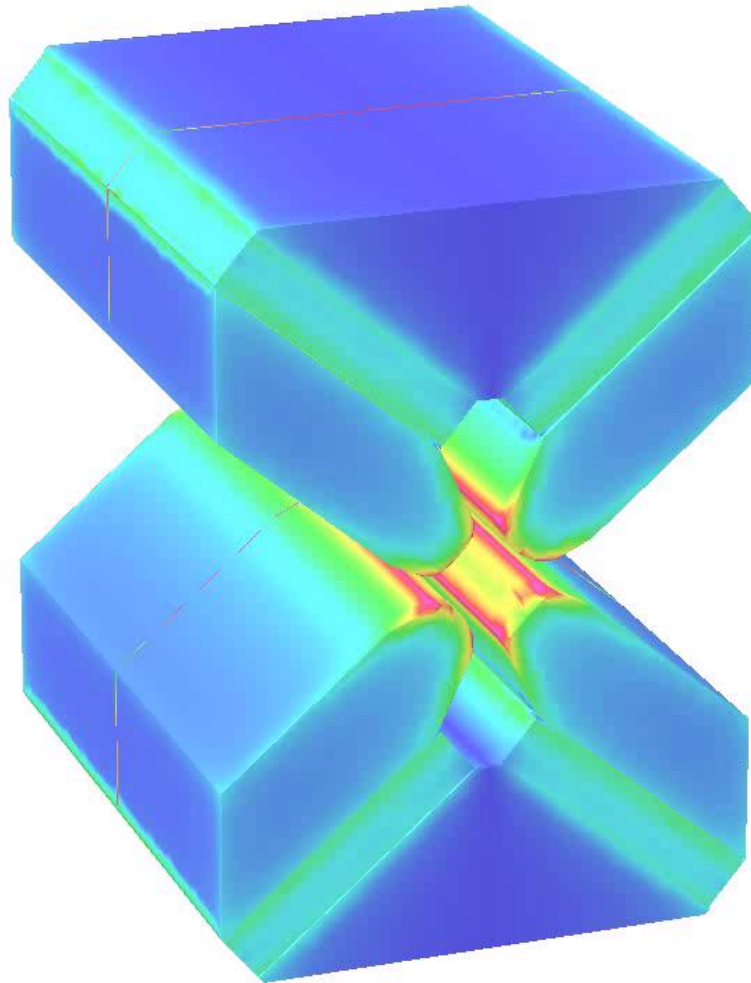
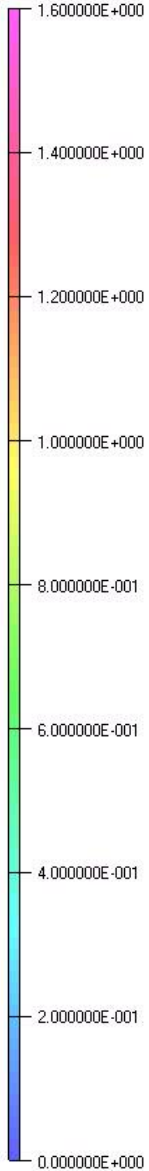


Science & Technology  
Facilities Council



**Gradient: 62.9 T/m**  
**Integrated gradient: 15.18 T**

Surface contours: MIN(BMOD,1.6)



**UNITS**

Length	mm
Magn Flux Density	T
Magnetic Field	A/m
Magn Scalar Pot	A
Current Density	A/mm <sup>2</sup>
Power	W
Force	N

**MODEL DATA**

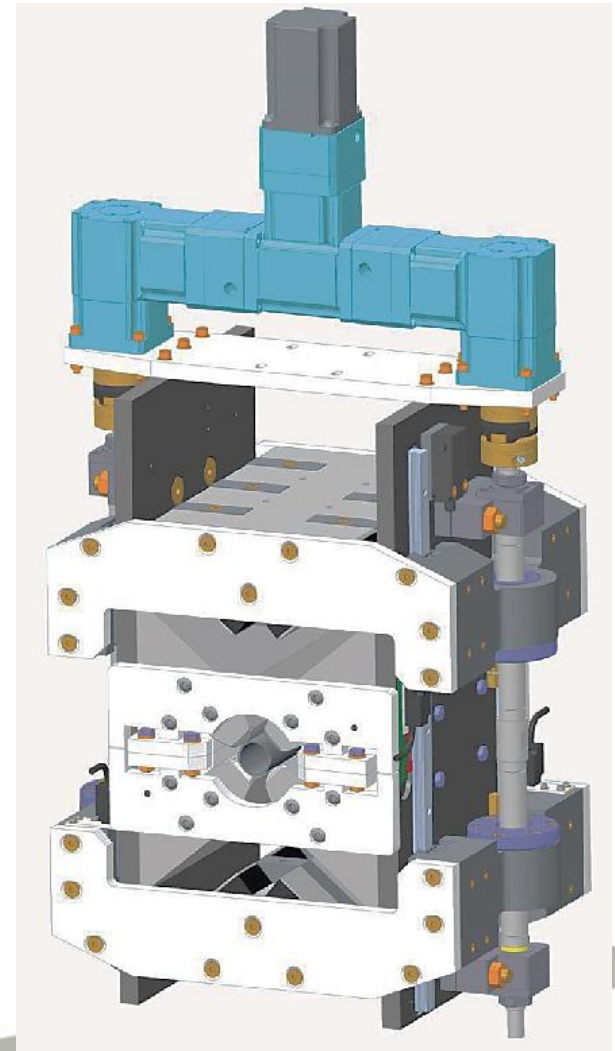
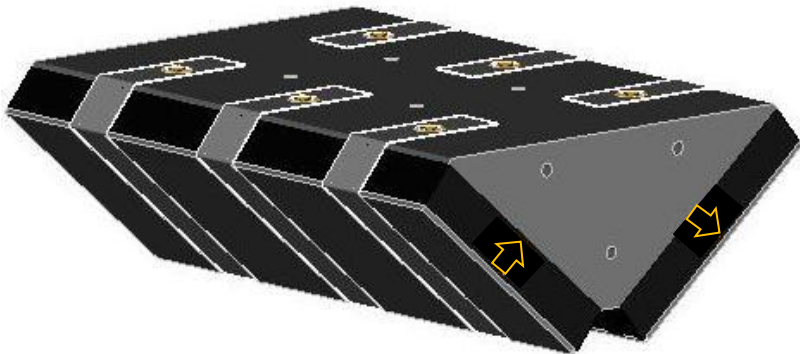
5-63-20-000.op3  
Magnetostatic (TOSCA )  
Nonlinear materials  
Simulation No 1 of 1  
125820 elements  
184466 nodes  
Nodally interpolated fields  
Activated in global coordinates  
Reflection in XY plane (Z field=0)  
Reflection in YZ plane (Y+Z fields=0)  
Reflection in ZX plane (Z+X fields=0)

**Field Point Local Coordinates**

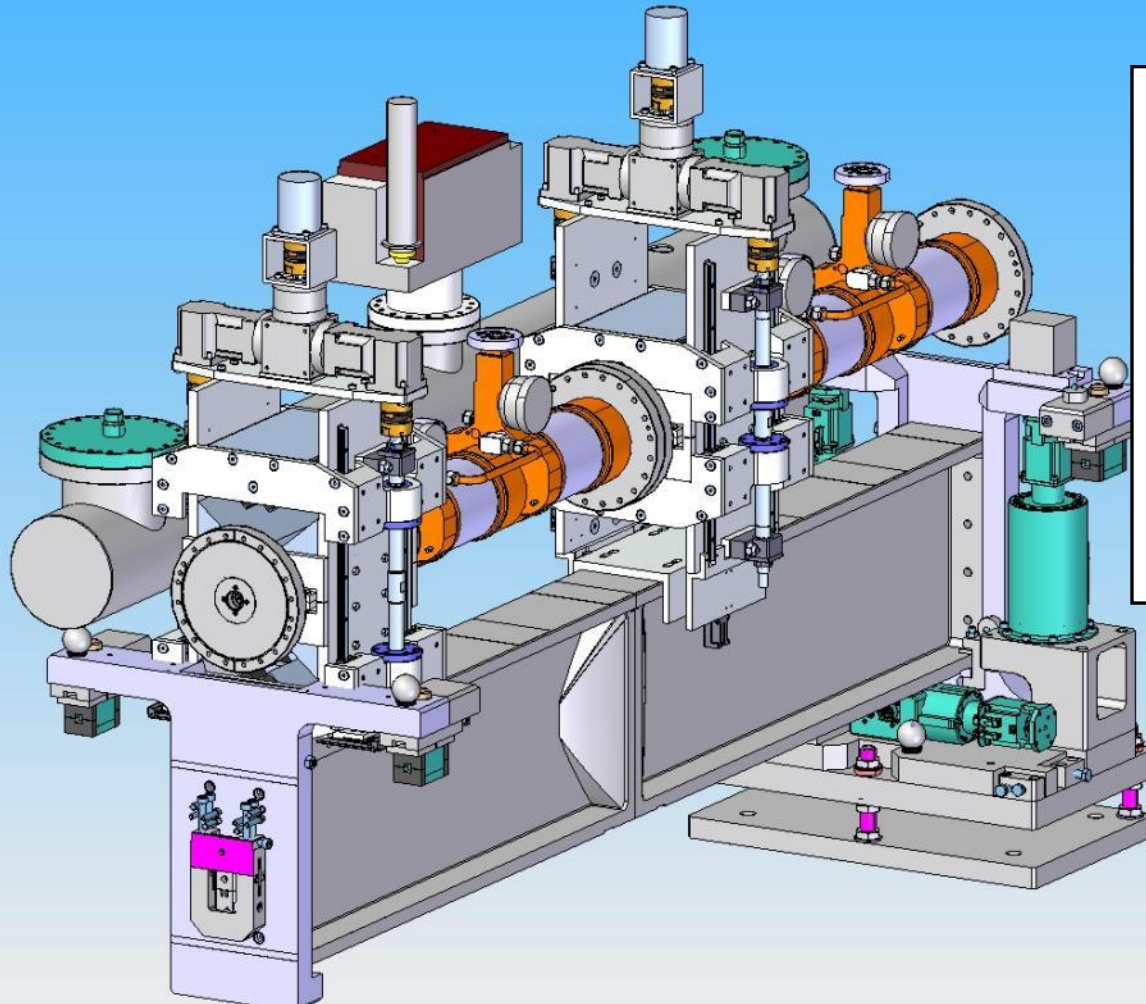
Local = Global

# Engineering of High Energy Quad

- Single axis motion with one motor and two ballscrews
- Two linear encoders to check position on both sides with  $1\mu\text{m}$  accuracy
- Maximum force is 16.4 kN per side, reduces by x10 when stroke = 64 mm
- PM blocks bonded to steel bridge piece and protective steel plate also bonded
- Steel straps added as extra security



# PM Quads in CLIC



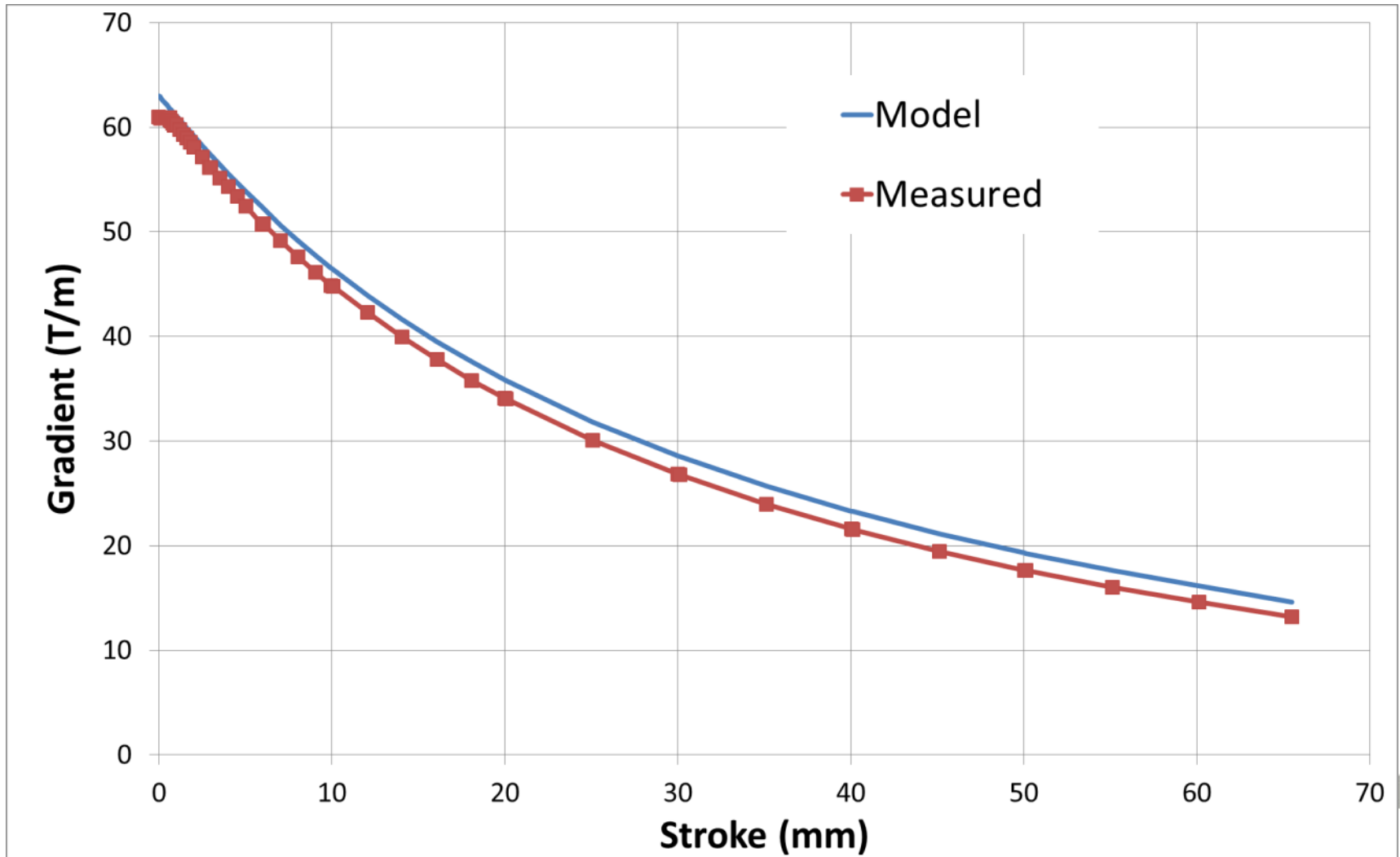
**Very tight space constraints**

Our designs were constrained by having to fit into predefined volume. We would benefit from relaxation in some areas if this is possible in the future.

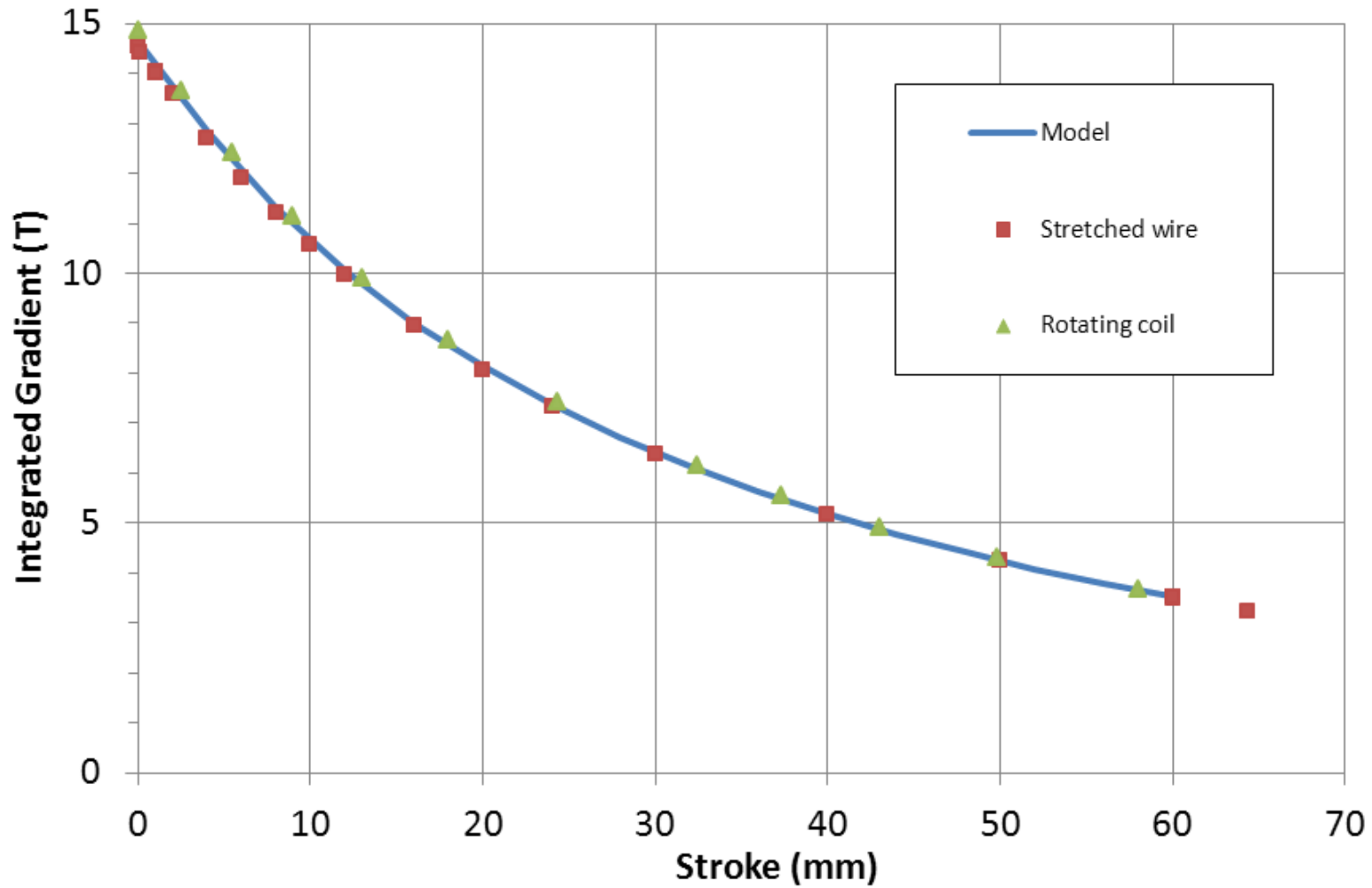
# Assembled Prototype



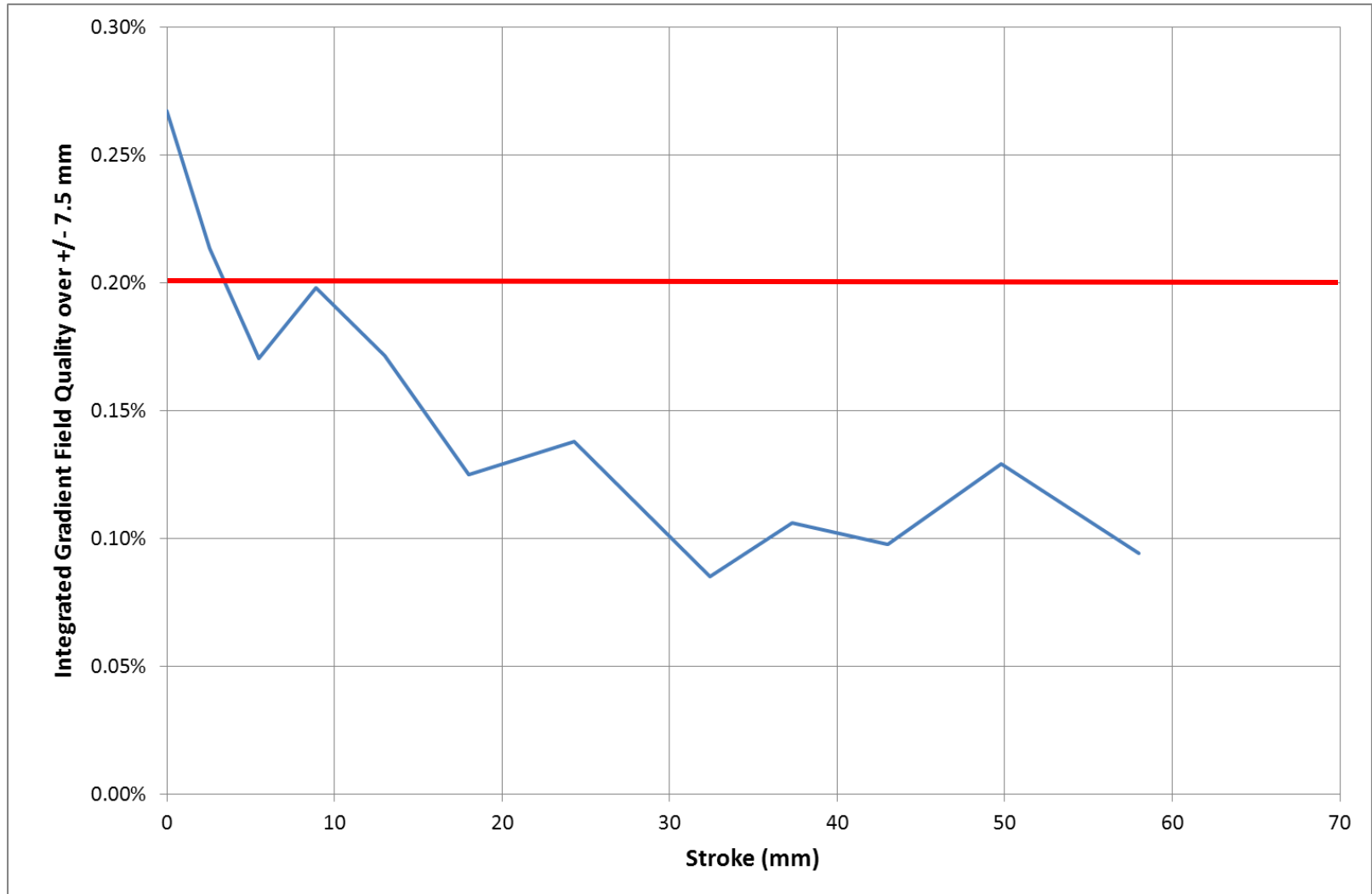
# Measured Gradient



# Measured Integrated Gradient

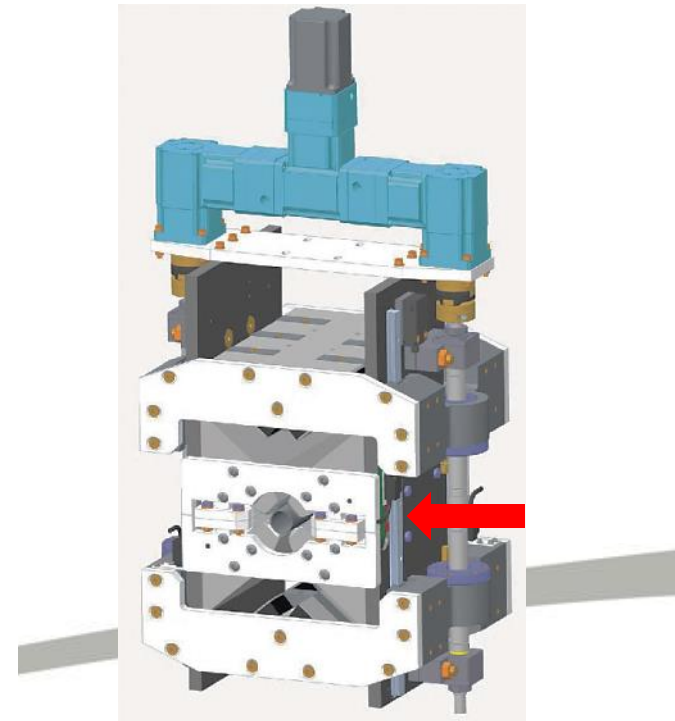
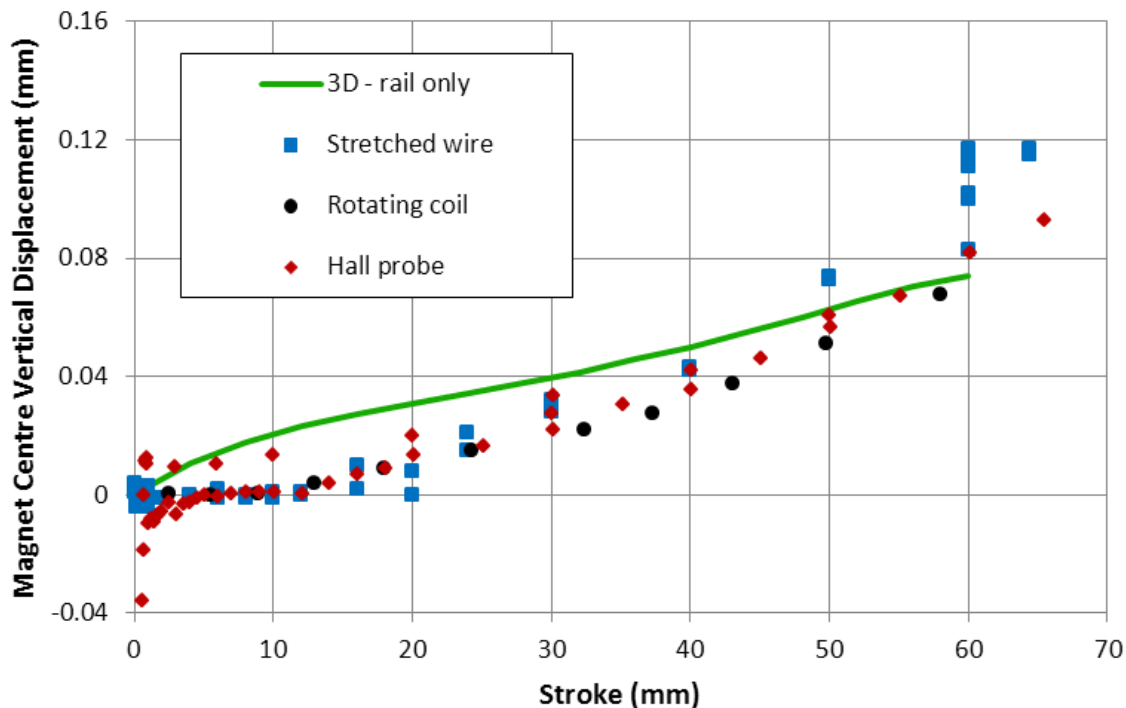


# Measured Field Quality



# Magnet Centre Movement

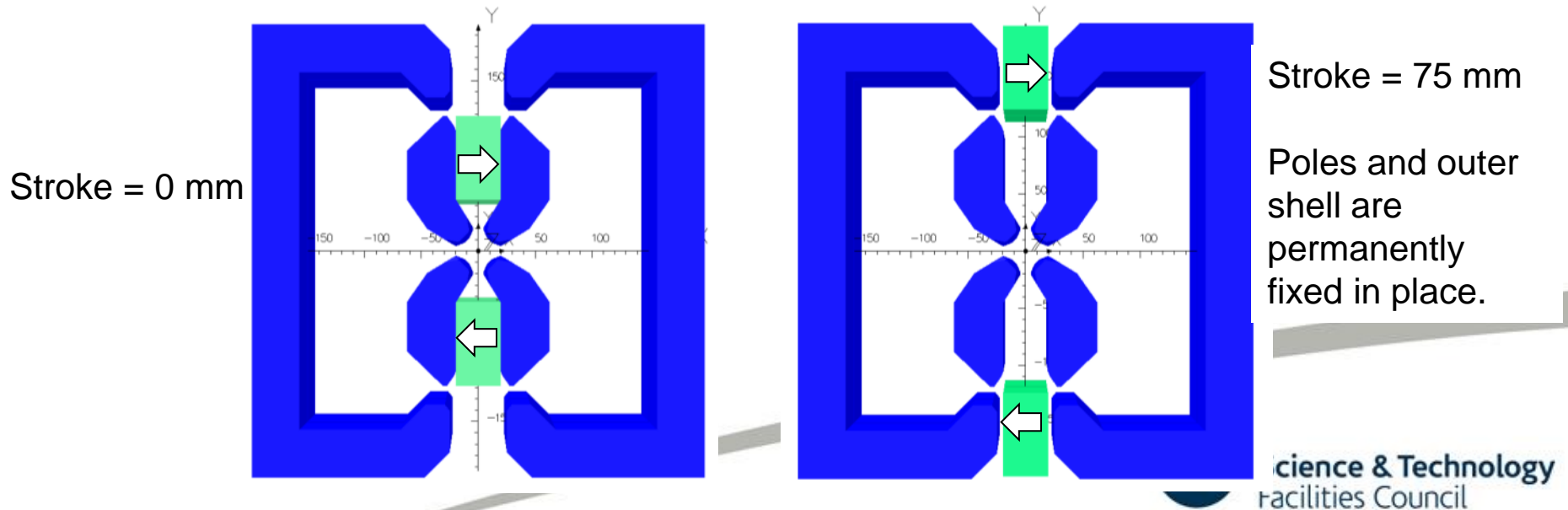
- The magnet centre moves upwards by  $\sim 100 \mu\text{m}$  as the permanent magnets are moved away
- 3D modelling suggests this is due to the rails being **ferromagnetic** ( $\mu_r \sim 100$ , measured) and **not mounted symmetrically** about the midplane – should be easy to fix
- Motor/gearbox assembly may also be a contributing factor





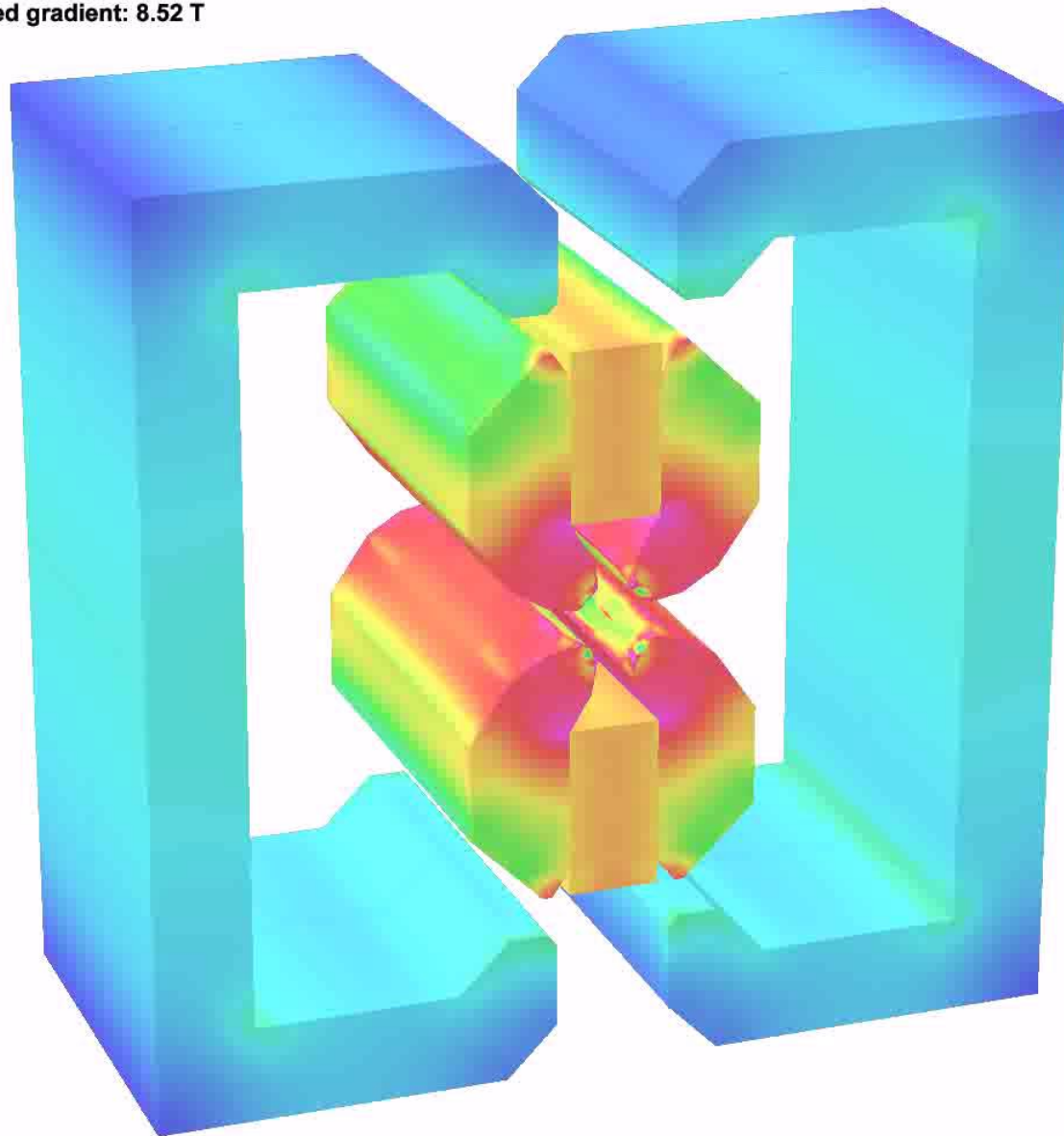
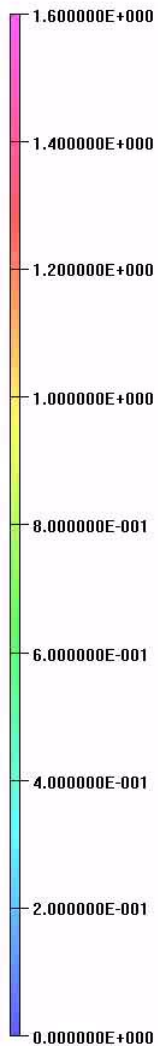
# Low Energy Quad Design

- Lower strength easier but requires **much larger tunability range (x10)**
- **Outer shell short circuits magnetic flux to reduce quad strength rapidly**
- **NdFeB** magnets with  $B_r = 1.37 \text{ T}$  (VACODYM 764 TP)
- 2 permanent magnet blocks are  $37.2 \times 70 \times 190 \text{ mm}$
- **Max gradient = 43.4 T/m (stroke = 0 mm)**
- **Min gradient = 3.5 T/m (stroke = 75 mm)**
- Pole gap = 27.6 mm
- Field quality =  $\pm 0.1\%$  over 23 mm



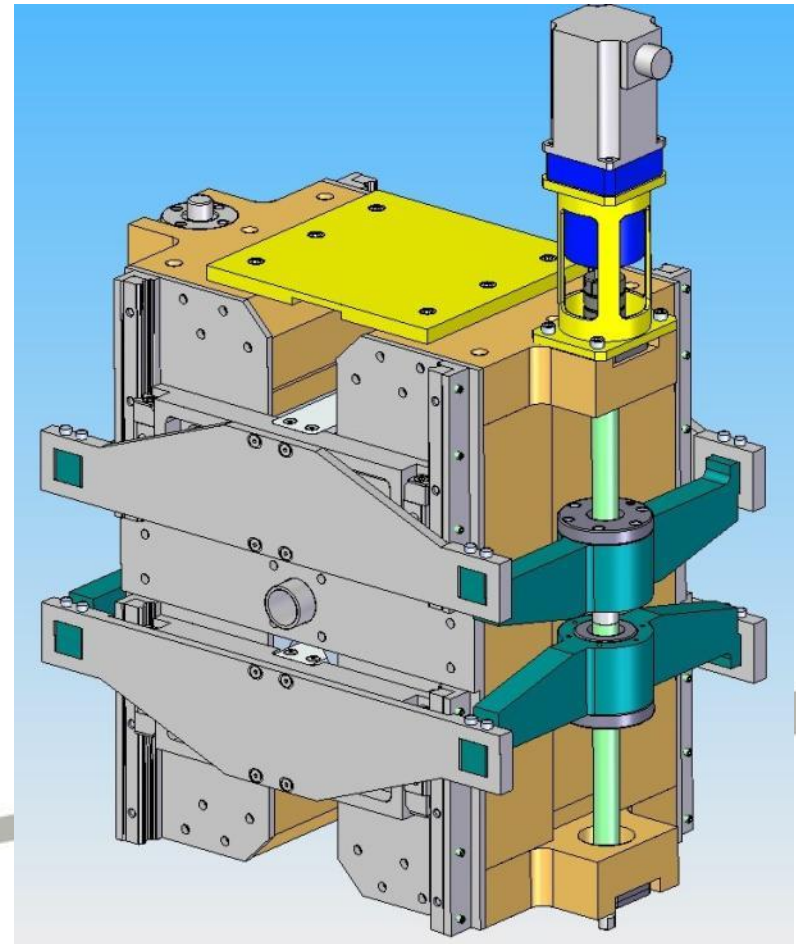
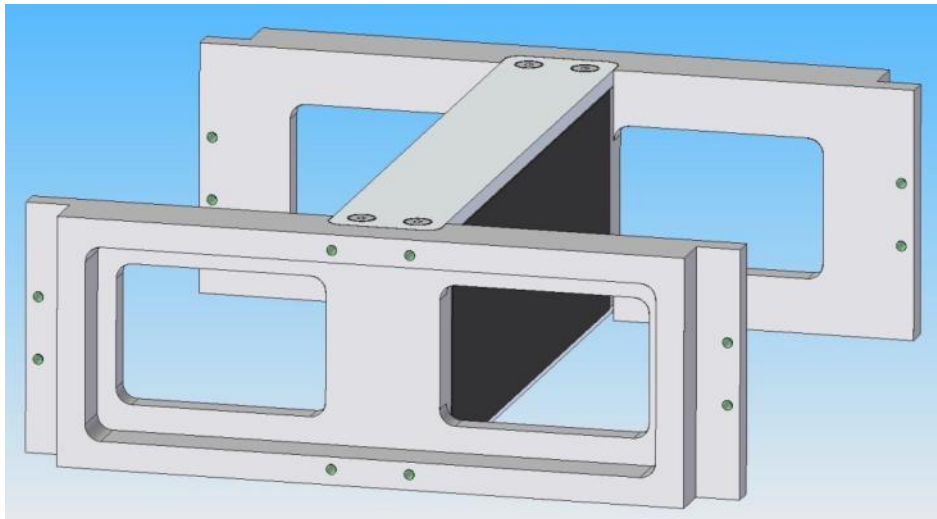
**Gradient: 41.68 T/m**  
**Integrated gradient: 8.52 T**

Surface contours: MIN(BMOD;1.6)

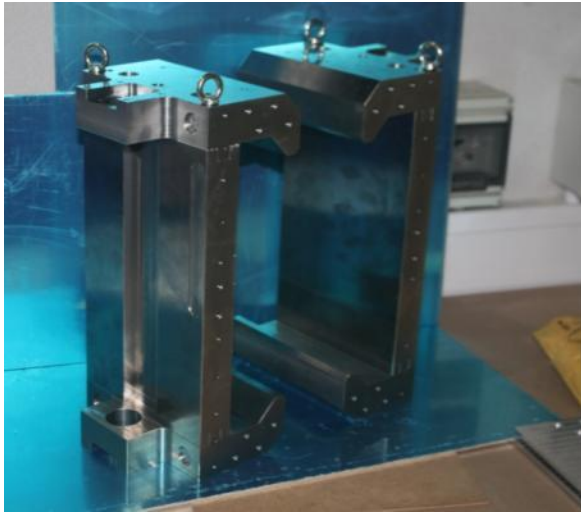


# Engineering of Low Energy Quad

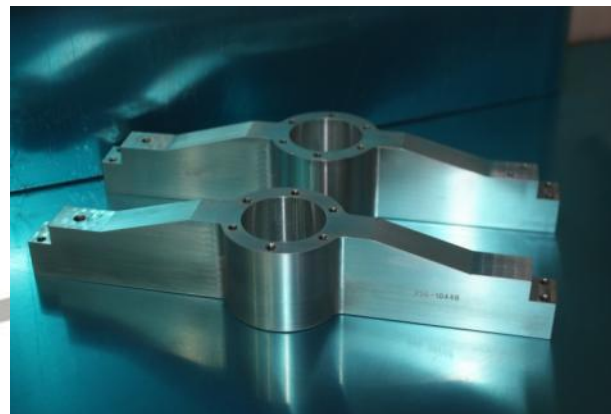
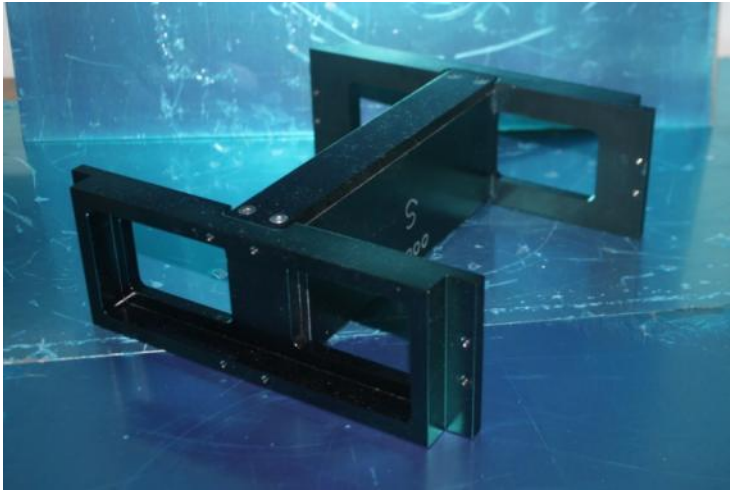
- Simplified single axis motion with one motor and one ballscrew
- Two linear encoders to check position on both sides with  $1\ \mu\text{m}$  accuracy
- Maximum force is only 0.7 kN per side
- PM blocks bonded within aluminium support frame



# Assembly Now Starting at Daresbury



Measurements at  
DL due to start in  
8 weeks



# Mass Production Assessment and Costings

- Face to face discussions have been held with the suppliers of the major components of the high energy quad
  - Permanent magnets
  - Motion system
  - Machined parts
  - Rails and ballscrews
- All suppliers have been extremely helpful and willing to spend time suggesting improvements, learning lessons from the prototype, to make mass production more practical and cost effective
- They will all provide cost estimates for high volume orders before end 2013
- No show stoppers identified that would prevent high volume production on realistic timescales

# Current Work Programme

- **Objectives:**

- Design, assemble and test a tuneable permanent magnet quadrupole of sufficient strength and quality for the high energy end of the drive beam (2.4 GeV).
- Design, assemble and test a tuneable permanent magnet quadrupole of sufficient strength and quality for the low energy end of the drive beam (0.24 GeV).

- **Deliverables:**

- A high strength (for a beam energy of 2.4 GeV), tuneable, permanent magnet quadrupole prototype (31/3/12)
- A report covering the design and test results of the high strength prototype (30/9/12)
- A low strength (for a beam energy of 0.24 GeV), tuneable, permanent magnet quadrupole prototype (30/9/13)
- A report covering the design and test results of the low strength prototype (31/3/14)
- (Mass production assessment)

All deliverables expected to be achieved



# Resources

- Contract 4/2011 to 3/2014

	CERN Contract	CERN Actual to Sept 13	STFC Contract	STFC Actual to Sept 13
Manpower	5.08 s-y	4.1 s-y	0.92 s-y	0.41 s-y
Material, travel, freight, etc	-	-	£59k	£78.2k

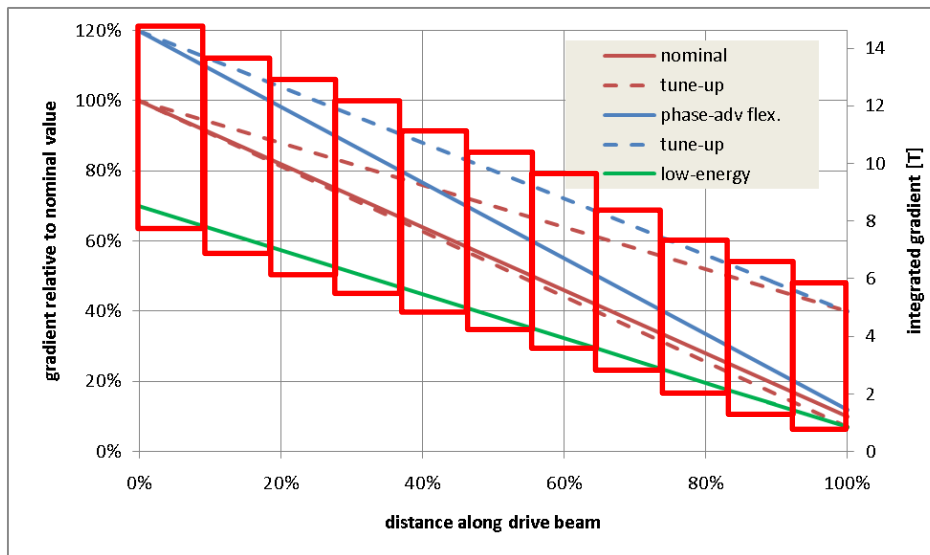
- High energy prototype cost £39.7k + VAT
- Low energy prototype cost £23.6k + VAT
- Jigs & Fixtures ~£9k



# Future Plan (1)

- **Proposed Programme:**

- Modify high strength quad prototype to improve field quality and reduce magnet centre motion to acceptable level.
- Modify low strength quad prototype to achieve specification (if required).
- Consider in detail possible magnet design refinements to tailor solutions better to each energy with the aim of reducing the tuning ranges required and so allowing simpler tuning mechanisms such as the use of low power coils or motion of only a fraction of the permanent magnet blocks





# Future Plan (2)

- **Proposed Programme:**

- Design and demonstrate, in one of the existing prototypes, a **passive temperature compensation scheme** to ensure the magnet strength is stable at the operating temperature
- Iterate the detailed mechanical and electrical designs to address features such as **fiducialisation and closed loop vs open loop motion control**.
- **Value engineer** the designs to ensure they provide the required performance at the optimal cost, including the need for mass production.
- Design and demonstrate, in one of the existing prototypes, the ability to provide **beam steering adjustment** to the level specified for the drive beam.



# Proposed Deliverables

- 2014-15
  - Field quality and magnet centre motion specification achieved for both prototypes
  - Iteration of designs and selection of number of quad types completed
- 2015-16
  - Temperature compensation demonstrated
  - Beam steering capability demonstrated
- 2016-17
  - Value engineered designs compatible with mass production completed



# Resources

- 2011 – 2014 Contract

	CERN	STFC
Manpower	5.08 s-y	0.92 s-y
Material, travel, freight, etc	-	£59k

- 2014 – 2017 Request

	CERN	STFC
Manpower	4.0 s-y	2.33 s-y
Material, travel, freight, etc	-	£68k

