



The path toward HEP High Performance Computing

(with a closer look at simulation)



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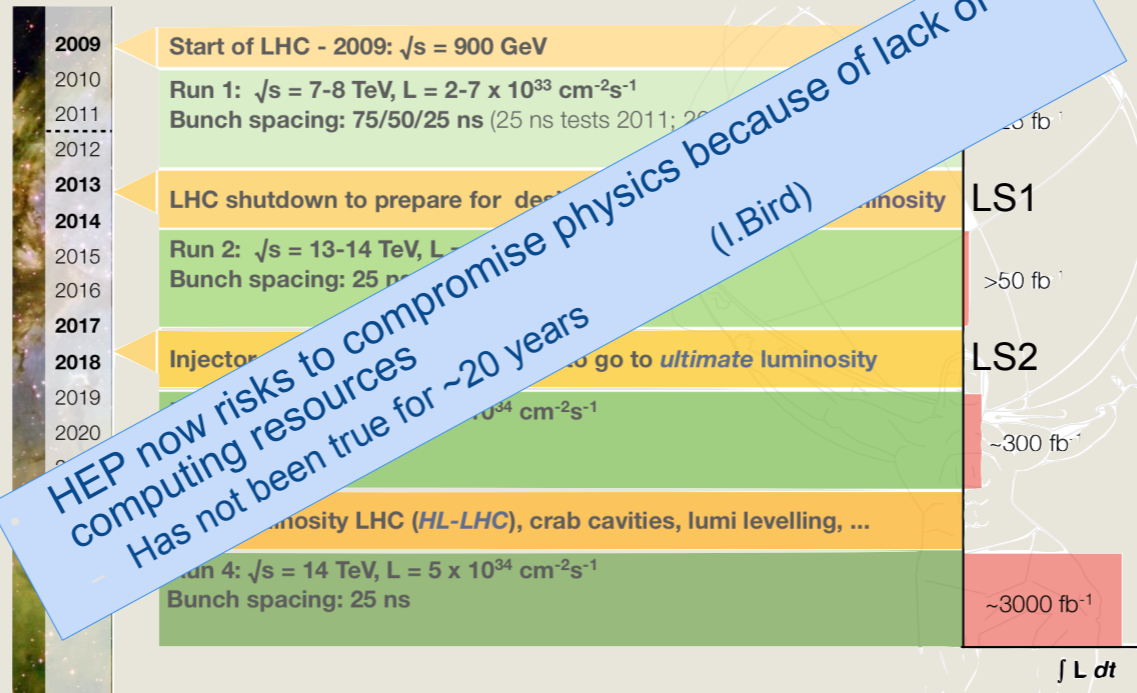
Acknowledgements

- M.Bandieramonte (Catania Univ.)
- L.Durhem (Intel)
- A.Nowak (CERN OpenLab)
- R.Seghal (BARC)





A luminous future for HEP...





The Eight dimensions

- The “dimensions of performance”

- Vectors
- Instruction Pipelining
- Instruction Level Parallelism (ILP)
- Hardware threading
- Clock frequency
- Multi-core
- Multi-socket
- Multi-node

Micro-parallelism: gain in throughput and in time-to-solution

Very little gain to be expected and no action to be taken

Gain in memory footprint and time-to-solution but not in throughput

Possibly running different jobs as we do now is the best solution

Expected limits on performance scaling				
	SIMD	ILP	HW	
THEORY		8	4	1.35
OPTIMISED		6	1.57	1.25
HEP		1	0.8	1.25

Expected limits on performance scaling (multiplied)				
	SIMD	ILP	HW	
THEORY		8	32	43.2
OPTIMISED		6	9.43	11.79
HEP		1	0.8	1

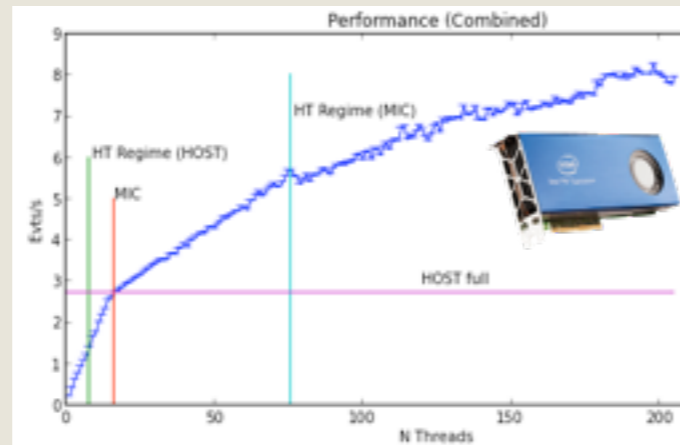
OpenLab@CHEP12





Geant4 Multi-threading

- Parallelism at level of event - for simple migration of experiments' "user" code
 - Part of next Geant4 10.0 production release (Dec 2013)



Preliminary, Courtesy of A.Dotti, SLAC

- Demonstrates

- Linear scaling of throughput with number of threads
- Large savings in memory: 40MB extra memory per thread
- Extension of parallelism to the track level
 - But deeper changes in "user" code





FNAL Geant GPU Prototype



- CERN-FNAL collaboration to
 - Develop and study the performance of various strategies and algorithms that will enable Geant4 to use multiple computational threads
- Kernel scheduling and CPU/GPU communication
 - The GPU Prototype as part of a full vectorized prototype for end-to-end test
 - A broker than can schedule the processing of tracks on the GPU with maximum flexibility
- Focus has been on NVidia hardware
- We have step up our collaboration with them with the idea to converge to a single code base





A fresh look at the Simulation

- More than a factor 10 increase expected in the simulation needs in the next few years!
- The most CPU-bound and time-consuming application in HEP with large room for speed-up
 - Largely experiment independent
 - Precision depends on (the inverse of the sqrt of) the number of events
- Grand strategy
 - Explore opportunities with no constraints from existing code
 - Expose the parallelism at all levels, from coarse granularity to micro-parallelism
 - Integrate slow and fast simulation to optimise both in the same framework
- Improvements (in geometry for instance) and techniques are expected to feed back into other HEP applications

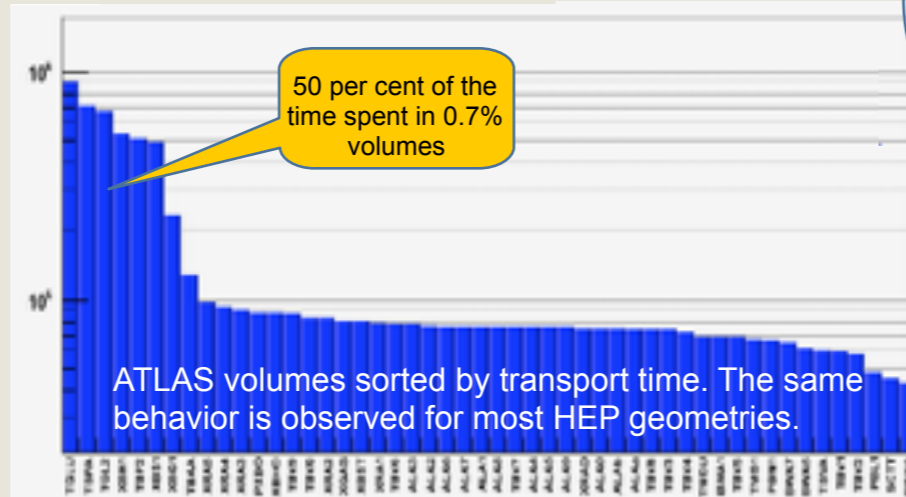
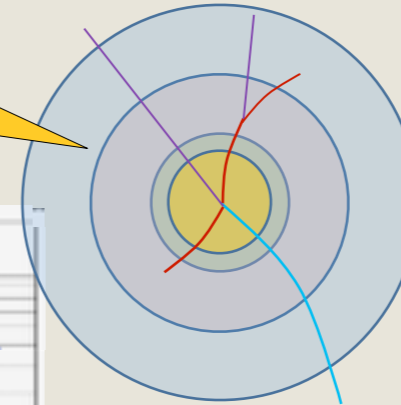




Classical HEP transport is mostly local !

- Event- or event track-level parallelism will better use resources but won't improve these points

- Geometry navigation (local)
- Material – X-section tables
- Particle type - physics processes



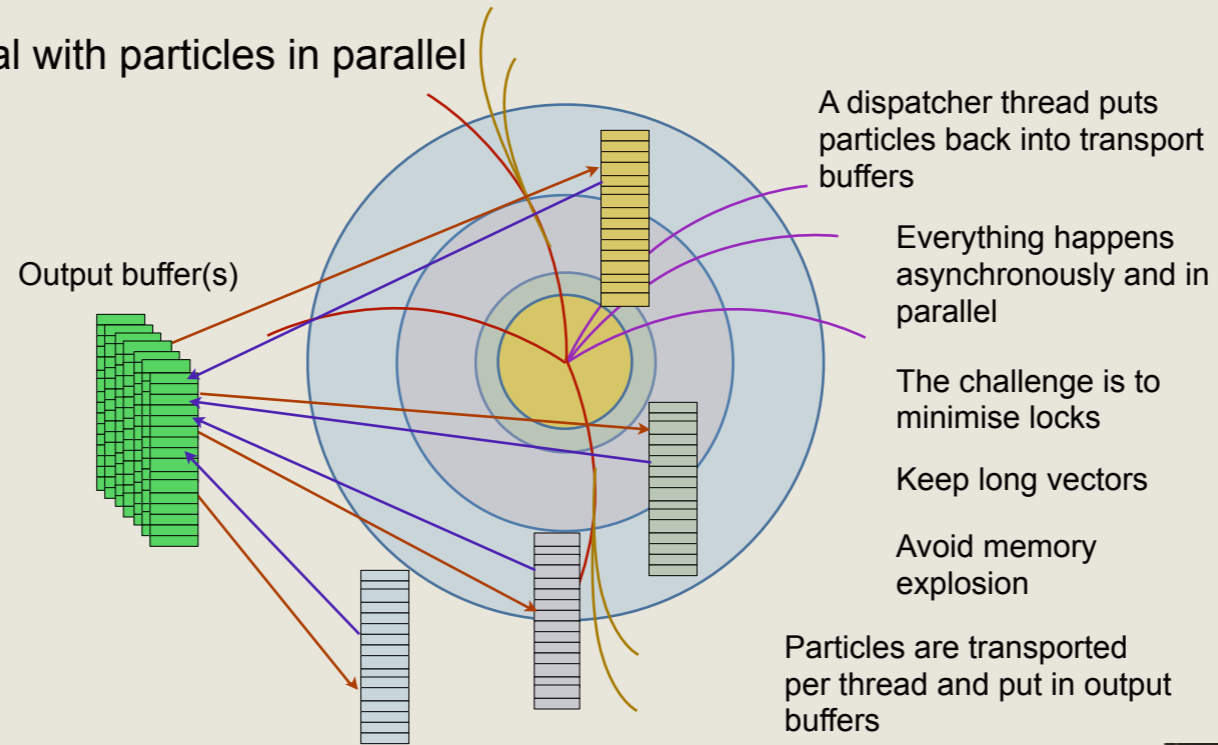
- Navigating very large data structures
- No locality
- OO abused: very deep instruction stack
- Cache misses

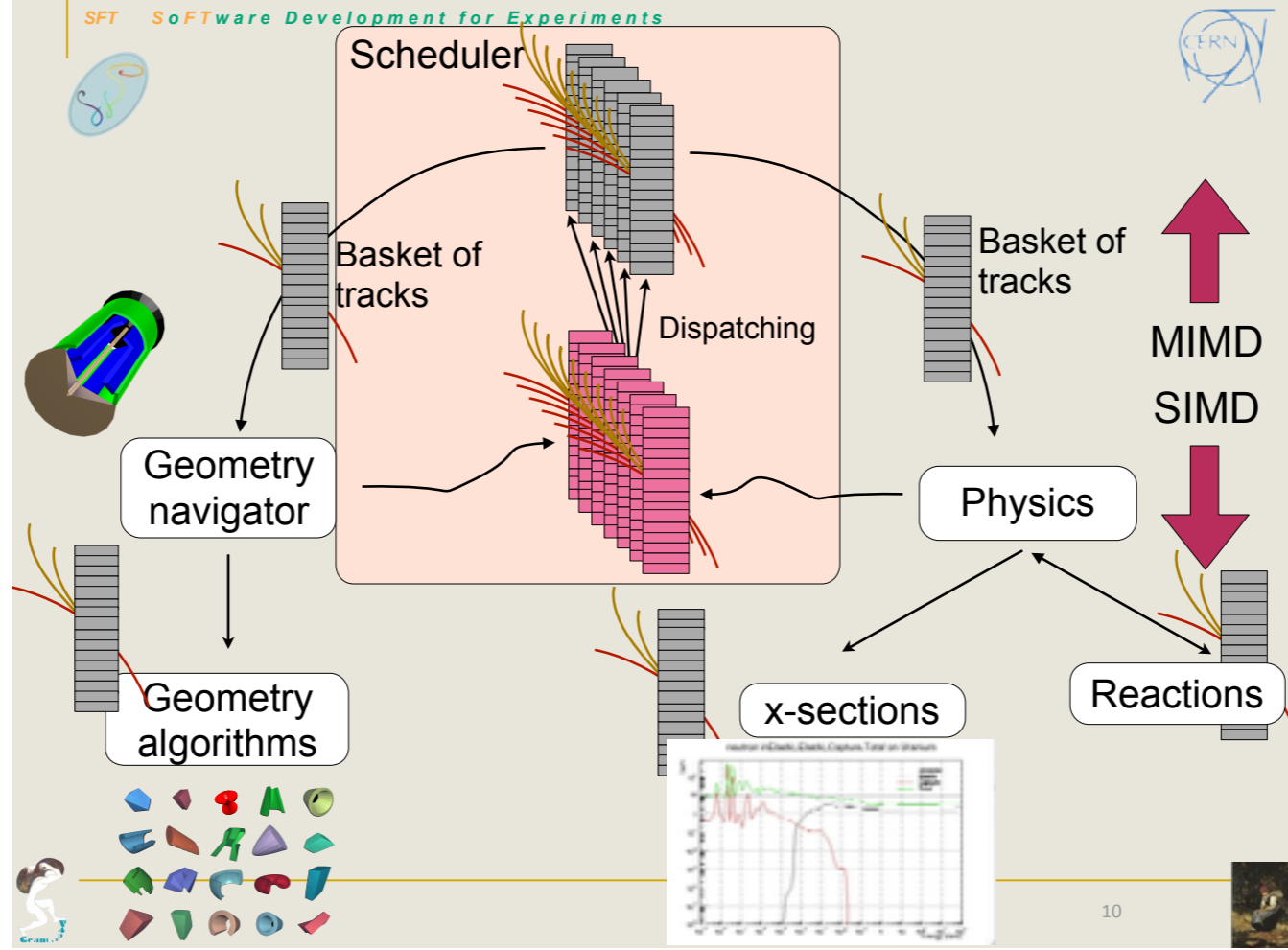




Introduce “basketised” transport

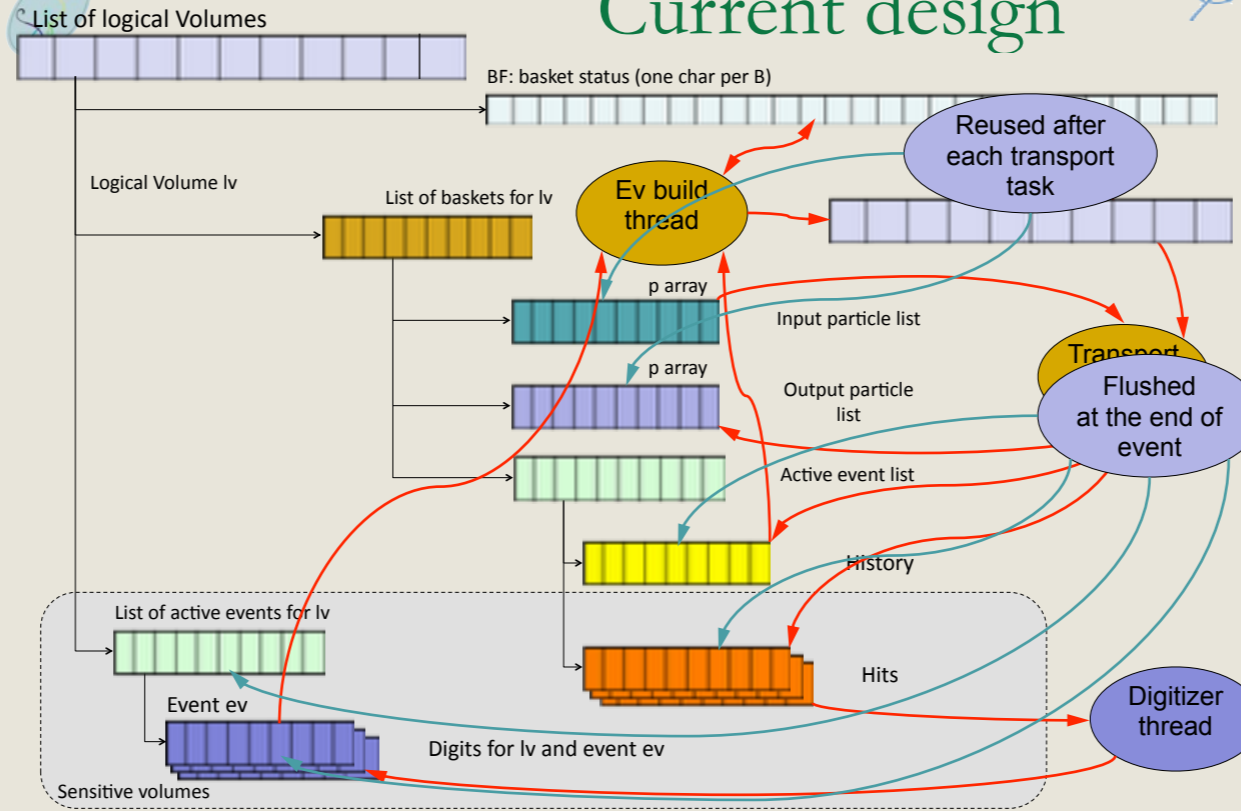
Deal with particles in parallel







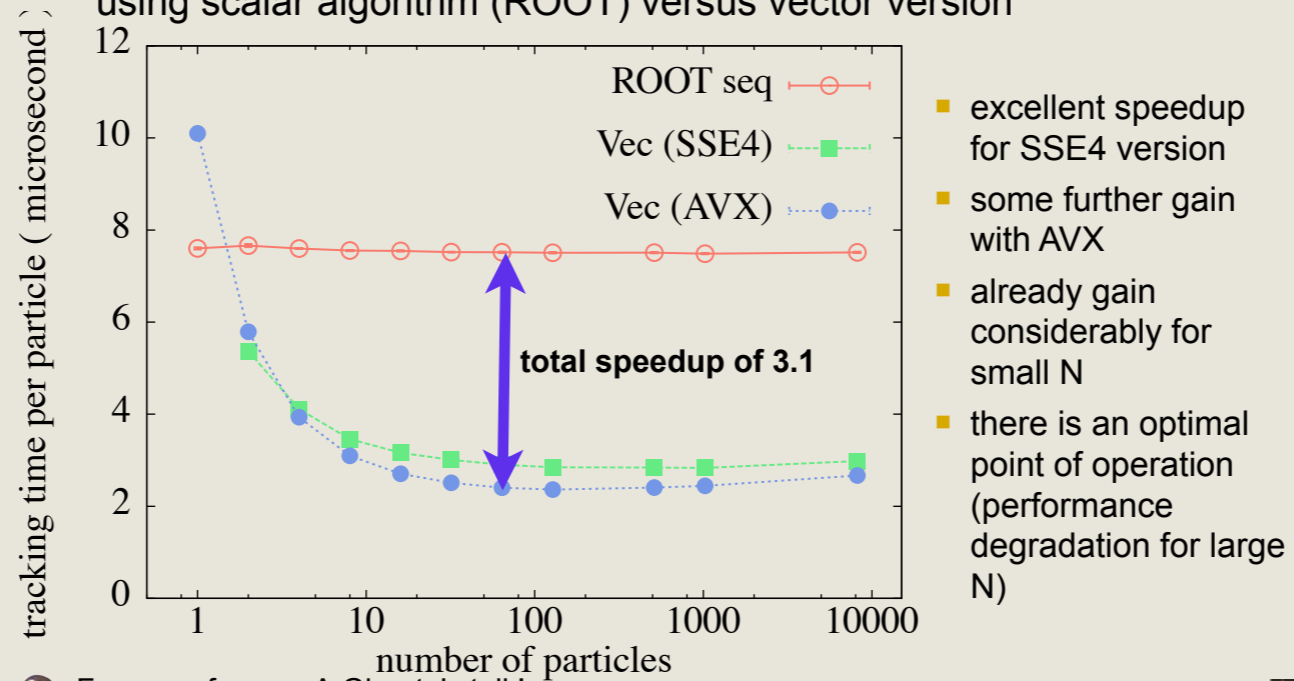
Current design





Gains from microparallelism & SIMD

- Time of processing/navigating N particles (P repetitions) using scalar algorithm (ROOT) versus vector version



For more fun see A.Gheata's talk!

<https://indico.cern.ch/contributionDisplay.py?contribId=453&confId=214784>

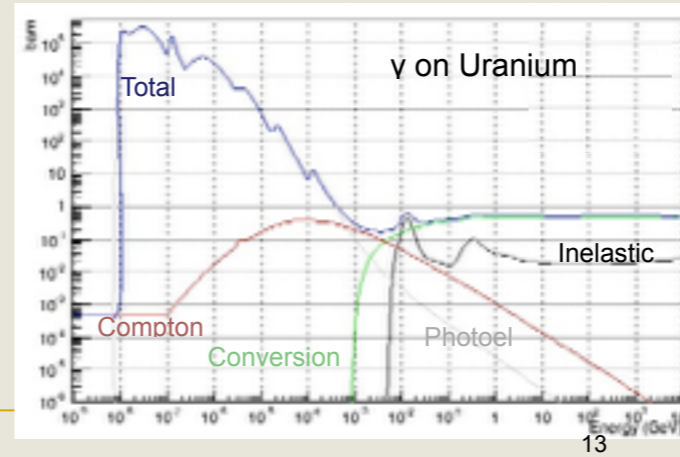
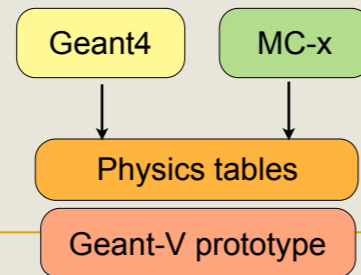




Physics



- A lightweight physics for realistic shower development
 - Select the major mechanisms
 - Bremsstrahlung, e+ annihilation, Compton, Decay, Delta ray, Elastic hadron, Inelastic hadron, Pair production, Photoelectric, Capture + dE/dx & MS
 - Tabulate all x-secs (100 bins -> 90MB)
 - Generate (10-50) final states (300kB per final state & element)
- It will not be good Geant4, but but it could be the seed of a fast simulation option
- Independent from the MonteCarlo that actually generates the tables





Where are we now?



- Scheduler
 - The new version, hopefully improved of the scheduler has been committed and we are testing it
- Geometry
 - The proof or principle that we can achieve large speedups (3-5+) is there (see A.Gheata's talk), however a lot of work lays ahead
- Navigator
 - "Percolating" vectors through the navigator is a difficult business. We have a simplified navigator that achieves that (S.Wenzel), but more work is needed here
- Physics
 - Can generate x-secs and final states and sample them, but there are still many points to be clarified with Geant4 experts

Scheduler
(A.Gheata, F.Carminati
+ R.Brun)



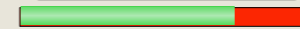
Geometry
(S.Wenzel, A.Gheata)



Navigator
(S.Wenzel, A.Gheata)



Physics
(F.Carminati,
J.Apostolakis + R.Brun)





Targets

- By the end of the year we will “glue” the different pieces together
 - And hopefully demonstrate the speedup potential of MT, locality and SIMD
- Measure the evolution of the memory footprint and the performance of the code at least in terms of hardware counters
- Absolute performance measurements will be harder
 - Difficult compare apples to apples
 - Probably we need to develop dedicated benchmarks
- Compare physics performance with full MC's
- For the moment we use Xeon architecture for the SIMD, but we intend to extend to GPU and to Xeon PHI
- We are working closely with Geant4 for the physics tables
- Once the prototyping phase over, we will have to sit down with the stakeholders and decide how to proceed from there





Summary



- HEP needs all the cycles it can obtain, nowadays this means using parallelism and SIMD
- Simulation is the ideal primary target for investigation for its relative experiment independence and its importance in the use of computing resources
- The Geant Vector project aims at demonstrating substantial speedup (3-5+) on modern architectures
- The work is done in close collaboration with the stakeholders and with Geant4

