

# Introduction to Transverse Beam Dynamics

## Lecture 4: Dispersion / Errors in fields and gradient / Chromaticity correction

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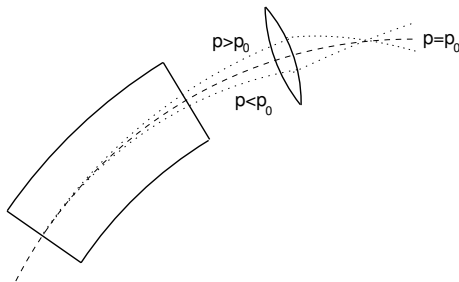
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## Re-Introducing the dispersion

So far we have studied monochromatic beams of particles, but this is slightly unrealistic: We always have some (small) momentum spread among all particles:  $\Delta p = p - p_0 \neq 0$ .

Consider three particles with  $p$  respectively: less than, greater than, and equal to  $p_0$ , traveling through a dipole. Remembering  $B\rho = \frac{p}{q}$ :



The system introduces a correlation of momentum with transverse position. This correlation is known as **dispersion** (an intrinsic property of the dipole magnets).

# Dispersion function and orbit

We need to study the motion for particles with  $\Delta p = p - p_0 \neq 0$  :

$$x''(s) + K(s)x(s) = \frac{1}{\rho} \frac{\Delta p}{p_0}$$

The general solution of this equation is:

$$x(s) = x_\beta(s) + x_D(s) \quad \left\{ \begin{array}{l} x_\beta''(s) + K(s)x_\beta(s) = 0 \\ D''(s) + K(s)D(s) = \frac{1}{\rho} \end{array} \right.$$

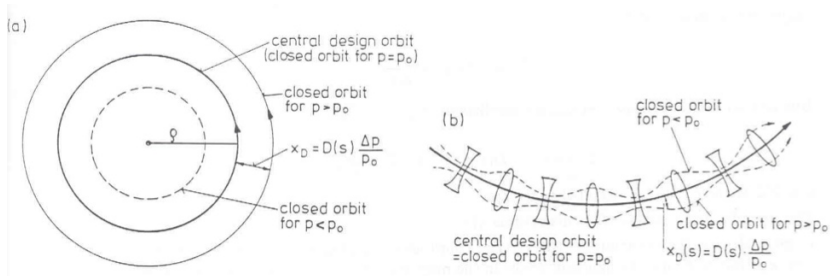
with  $x_D(s) = D(s) \frac{\Delta p}{p_0}$ .

## Remarks

- ▶  $D(s)$  is that special orbit that a particle would have for  $\Delta p/p = 1$
- ▶  $x_D(s)$  describes the deviation from the new **closed orbit** for an off-momentum particle with a certain  $\Delta p$
- ▶ the orbit of a generic particle is the sum of the well known  $x_\beta(s)$  and  $x_D(s)$

# Understanding the solution $x(s) = x_\beta(s) + x_D(s)$

with  $x_D(s) = D(s) \frac{\Delta p}{p_0}$ .



*Closed orbit for particles with momentum  $p \neq p_0$  in a weakly (a) and strongly (b) focusing circular accelerator.*

- ▶  $x_D(s) = D(s) \frac{\Delta p}{p_0}$  describes the deviation of the closed orbit for off-momentum particles with a fixed  $\Delta p$  from the reference orbit
- ▶  $x_\beta(s)$  describes the betatron oscillation around this dispersive closed orbit

## Dispersion and orbit propagation

Inside a magnet, the dispersion trajectory is solution of  $D''(s) + K(s)D(s) = \frac{1}{\rho}$  :

$$D(s) = S(s) \int_0^s \frac{1}{\rho(t)} C(t) dt - C(s) \int_0^s \frac{1}{\rho(t)} S(t) dt$$

Now the orbit:

$$x(s) = x_\beta(s) + x_D(s)$$

$$x(s) = C(s)x_0 + S(s)x'_0 + D(s)\frac{\Delta p}{p}$$

In matrix form

$$\begin{pmatrix} x \\ x' \end{pmatrix}_s = \begin{pmatrix} C & S \\ C' & S' \end{pmatrix} \begin{pmatrix} x \\ x' \end{pmatrix}_0 + \frac{\Delta p}{p} \begin{pmatrix} D \\ D' \end{pmatrix}_0$$

We can rewrite the solution in matrix form:

$$\begin{pmatrix} x \\ x' \\ \Delta p/p \end{pmatrix}_s = \begin{pmatrix} C & S & D \\ C' & S' & D' \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ x' \\ \Delta p/p \end{pmatrix}_0$$

Exercise: show that  $D(s)$  is a solution for the equation of motion, with the initial conditions  $D_0 = D'_0 = 0$ .

# Dispersion examples

Let's study, for different magnetic elements, the solution of:

$$D(s) = S(s) \int_0^s \frac{1}{\rho(t)} C(t) dt - C(s) \int_0^s \frac{1}{\rho(t)} S(t) dt$$

at the exit of the element: that is,  $D(s)$  with  $s = L_{\text{magnet}}$

► Drift space:

$$M_{\text{Drift}} = \begin{pmatrix} 1 & L \\ 0 & 1 \end{pmatrix}$$

$C(t) = 1$ ,  $S(t) = L$ ,  $\rho(t) = \infty \Rightarrow$  the integrals cancel

$$M_{\text{Drift}} = \begin{pmatrix} 1 & L & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

# Dispersion function: sector dipole

- Sector dipole:

$$K = \frac{1}{\rho^2}:$$

$$M_{\text{Dipole}} = \begin{pmatrix} \cos(\sqrt{K}L) & \frac{1}{\sqrt{K}} \sin(\sqrt{K}L) \\ -\sqrt{K} \sin(\sqrt{K}L) & \cos(\sqrt{K}L) \end{pmatrix} = \begin{pmatrix} \cos \frac{L}{\rho} & \rho \sin \frac{L}{\rho} \\ -\frac{1}{\rho} \sin \frac{L}{\rho} & \cos \frac{L}{\rho} \end{pmatrix}$$

which gives

$$D(s) = \rho \left( 1 - \cos \frac{L}{\rho} \right)$$

$$D'(s) = \sin \frac{L}{\rho}$$

therefore

$$M_{\text{Dipole}} = \begin{pmatrix} \cos \frac{L}{\rho} & \rho \sin \frac{L}{\rho} & \rho \left( 1 - \cos \frac{L}{\rho} \right) \\ -\frac{1}{\rho} \sin \frac{L}{\rho} & \cos \frac{L}{\rho} & \sin \frac{L}{\rho} \\ 0 & 0 & 1 \end{pmatrix}$$

# Dispersion function: quadrupole

- Focusing quadrupole,  $K > 0$ :

$$M_{\text{QF}} = \begin{pmatrix} \cos(\sqrt{K}L) & \frac{1}{\sqrt{K}} \sin(\sqrt{K}L) & 0 \\ -\sqrt{K} \sin(\sqrt{K}L) & \cos(\sqrt{K}L) & 0 \\ 0 & 0 & 1 \end{pmatrix};$$

- Defocusing quadrupole,  $K < 0$ :

$$M_{\text{QD}} = \begin{pmatrix} \cosh(\sqrt{|K|}L) & \frac{1}{\sqrt{|K|}} \sinh(\sqrt{|K|}L) & 0 \\ \sqrt{|K|} \sinh(\sqrt{|K|}L) & \cosh(\sqrt{|K|}L) & 0 \\ 0 & 0 & 1 \end{pmatrix}$$



# Dispersion propagation through the machine

- The equation:

$$D(s) = S(s) \int_0^s \frac{1}{\rho(t)} C(t) dt - C(s) \int_0^s \frac{1}{\rho(t)} S(t) dt$$

shows **the dispersion inside a magnet**, which does not depend on the dispersion that might have been generated by the upstreams magnets.

- At the exit of a magnet of length  $L_m$  the dispersion reaches the value  $D(L_m)$
- ...then it propagates from there on through the rest of the machine, just like any other particle:

$$\begin{pmatrix} \tilde{D} \\ \tilde{D}' \\ 1 \end{pmatrix}_s = \begin{pmatrix} C & S & D \\ C' & S' & D' \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \tilde{D} \\ \tilde{D}' \\ 1 \end{pmatrix}_0$$

(to avoid confusion,  $\tilde{D}$  and  $\tilde{D}'$ , are often called  $\eta$  and  $\eta'$ )

# Closed orbit for an off-momentum particle

In a periodic lattice, also the dispersion must be periodic.

That is, for  $\begin{pmatrix} \eta \\ \eta' \\ 1 \end{pmatrix}$  we want:

$$\begin{pmatrix} \eta \\ \eta' \\ 1 \end{pmatrix} = \begin{pmatrix} C & S & D \\ C' & S' & D' \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \eta \\ \eta' \\ 1 \end{pmatrix}$$

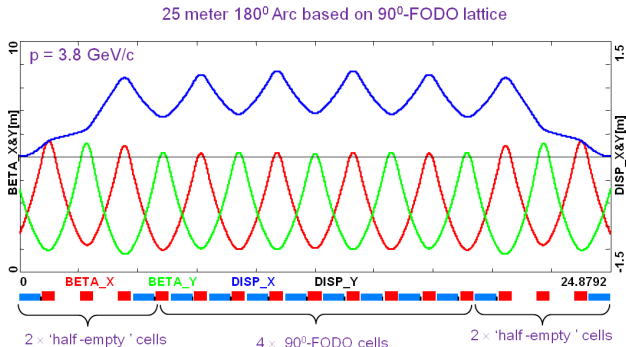
Let's rewrite this in  $2 \times 2$  form:

$$\begin{pmatrix} \eta \\ \eta' \end{pmatrix} = \begin{pmatrix} C & S \\ C' & S' \end{pmatrix} \begin{pmatrix} \eta \\ \eta' \end{pmatrix} + \begin{pmatrix} D \\ D' \end{pmatrix}$$
$$\begin{pmatrix} 1 - C & -S \\ -C' & 1 - S' \end{pmatrix} \begin{pmatrix} \eta \\ \eta' \end{pmatrix} = \begin{pmatrix} D \\ D' \end{pmatrix}$$

The solution is:

$$\begin{pmatrix} \eta \\ \eta' \end{pmatrix} = \frac{1}{(1 - C)(1 - S') - C'S} \begin{pmatrix} 1 - S' & S \\ C' & 1 - C \end{pmatrix} \begin{pmatrix} D \\ D' \end{pmatrix}$$

# Example of dispersion function in a FODO lattice



Aperture radius:  $r = 15 \text{ cm}$

12 × Dipoles:

15 × Quads:

field: 3.9 Tesla

gradient: 25 Tesla/m (3.8 Tesla at the pole)

length: 85 cm

length: 50 cm

Dispersion in a FODO cell:  $D^\pm = \frac{L\phi(1 \pm \frac{1}{2} \sin \frac{\mu}{2})}{4 \sin^2 \frac{\mu}{2}}$ . The dispersion has a maximum at the focusing quadrupoles.

# Example of dispersion function

In this example from the HERA storage ring (DESY) we see the twiss parameters and the dispersion near the interaction point. In the periodic region,

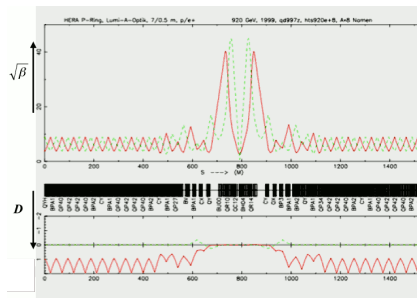
$$x_{\beta}(s) = 1 \dots 2 \text{ mm}$$

$$D(s) = 1 \dots 2 \text{ m}$$

$$\Delta p/p \approx 1 \cdot 10^{-3}$$

Remember:

$$x(s) = x_{\beta}(s) + D(s) \frac{\Delta p}{p}$$



Beware: the dispersion contributes to the beam size:

$$\sigma_x = \sqrt{\sigma_{x_{\beta}}^2 + \left(D \cdot \frac{\Delta p}{p}\right)^2} = \sqrt{\epsilon\beta + \left(D \cdot \frac{\Delta p}{p}\right)^2}$$

- ▶ We need to suppress the dispersion at the IP !
- ▶ We need a special insertion section: a *dispersion suppressor*

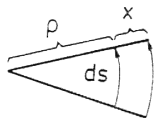
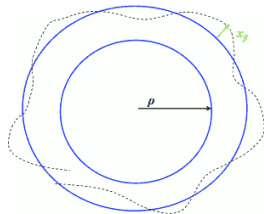
# The momentum compaction factor

The dispersion function relates the momentum error of a particle to the horizontal orbit coordinate

The general solution of the equation of motion is

$$x(s) = x_{\beta}(s) + D(s) \frac{\Delta p}{p}$$

The dispersion changes also the length of the off-energy orbit.



particle with offset  $x$  w.r.t. the design orbit:

$$ds' = ds \left( 1 + \frac{x}{\rho} \right) \quad \frac{ds'}{ds} = \frac{\rho + x}{\rho} \quad \rightarrow \quad ds' = \left( 1 + \frac{x}{\rho} \right) ds$$

The circumference change is  $\Delta C$ , that is  $C' = \oint \left( 1 + \frac{x}{\rho} \right) ds = C + \Delta C$

We define the “momentum compaction factor”,  $\alpha$ , such that:

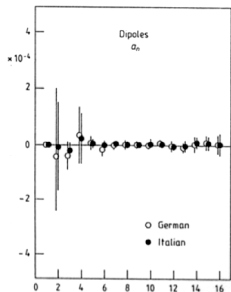
$$\frac{\Delta C}{C} = \alpha \frac{\Delta p}{p} \quad \rightarrow \text{a rough estimate is } \alpha = \frac{1}{Q_x^2}$$

# Magnetic imperfections

High order multipolar components and misalignments

Taylor expansion of the  $B$  field:

$$B_y(x) = \underbrace{B_{y0}}_{\text{dipole}} + \underbrace{\frac{\partial B_y}{\partial x}}_{\text{quad}} x + \frac{1}{2} \underbrace{\frac{\partial^2 B_y}{\partial x^2}}_{\text{sextupole}} x^2 + \frac{1}{3!} \underbrace{\frac{\partial^3 B_y}{\partial x^3}}_{\text{octupole}} x^3 + \dots \quad \text{divide by } B_{y0}$$



*There can be undesired multipolar components, due to small fabrication defects*

*Or also errors in the windings, in the gap  $h$ ,  
... remember:  $B = \frac{\mu_0 n I}{h}$*



**Moreover:** “feed-down” effect  $\Rightarrow$  a misalign magnet of order  $n$ , behaves like a magnet of order  $n + 1$  + a magnet of order  $n - 1$  overlapped

# Dipole magnet errors

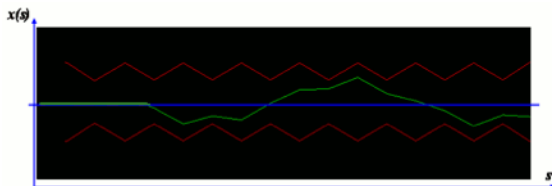
Let's imagine to have a magnet with  $B_x = B_0 + \Delta B$ . This will give an additional kick to each particle, and will distort the ideal design orbit

$$F_x = ev(B_0 + \Delta B); \quad \Delta x' = \Delta B ds / B\rho$$

A dipole error will cause a distortion of the closed orbit, that will „run around“ the storage ring, being observable everywhere. If the distortion is small enough, it will still lead to a closed orbit.

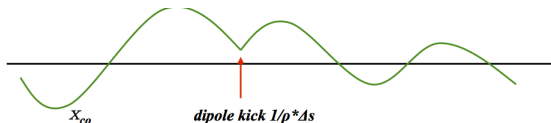
Example: 1 single dipole error

$$\begin{pmatrix} x \\ x' \end{pmatrix}_s = M_{\text{lattice}} \begin{pmatrix} 0 \\ \Delta x' \end{pmatrix}_0$$



In order to have bounded motion the tune  $Q$  must be non-integer,  $Q \neq 1$ . We see that even for particles with reference momentum  $p_0$  an integer  $Q$  value is forbidden, since small field errors are always present.

# Orbit distortion for a single dipole field error



We consider a single thin dipole field error at the location  $s = s_0$ , with a kick angle  $\Delta x'$ .

$$X_- = \begin{pmatrix} x_0 \\ x'_0 + \Delta x' \end{pmatrix}, \quad X_+ = \begin{pmatrix} x_0 \\ x'_0 \end{pmatrix}$$

are the phase space coordinates before and after the kick located at  $s_0$ . The closed-orbit condition becomes

$$M_{\text{Lattice}} \begin{pmatrix} x_0 \\ x'_0 \end{pmatrix} = \begin{pmatrix} x_0 \\ x'_0 + \Delta x' \end{pmatrix}$$

The resulting closed orbit at  $s_0$  is

$$x_0 = \frac{\beta_0 \Delta x'}{2 \sin \pi Q} \cos \pi Q; \quad x'_0 = \frac{\Delta x'}{2 \sin \pi Q} (\sin \pi Q - \alpha_0 \cos \pi Q)$$

where  $Q$  is the tune. The orbit at any other location  $s$  is

$$x(s) = \frac{\sqrt{\beta_s \beta_0}}{2 \sin \pi Q} \cos(\pi Q - |\mu_s - \mu_0|) \Delta x'$$

(see the references for a demonstration)



# Orbit distortion for distributed dipole field errors

One single dipole field error

$$x(s) = \frac{\sqrt{\beta(s)\beta(0)}}{2\sin\pi Q} \cos(\pi Q - |\mu(s) - \mu(0)|) \Delta x'$$

Distributed dipole field errors

$$x(s) = \frac{\sqrt{\beta(s)}}{2\sin\pi Q} \oint \sqrt{\beta(t)} \cos(\pi Q - |\mu(s) - \mu(t)|) \Delta x' dt$$

- ▶ orbit distortion is visible at any position  $s$  in the ring, even if the dipole error is located at one single point  $s_0$
- ▶ the  $\beta$  function describes the sensitivity of the beam to external fields
- ▶ the  $\beta$  function acts as amplification factor for the orbit amplitude at the given observation point
- ▶ there is a singularity at the denominator when  $Q$  integer  $\Rightarrow$  it's called resonance

# The resonances

Closed orbit distortion due to distributed dipole field errors:

$$x(s) = \frac{\sqrt{\beta(s)}}{2 \sin \pi Q} \oint \sqrt{\beta(t)} \cos(\pi Q - |\mu(s) - \mu(t)|) \Delta x' dt$$

Remember the definition of tune:

$$Q = \frac{\mu_L}{2\pi}$$

$\Rightarrow$  it is the phase advance for a revolution  $\mu_L$  in units of  $2\pi$ .

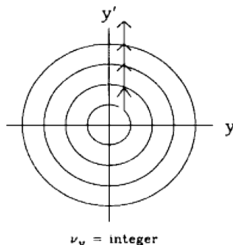
Extremely important:

- ▶ In case of imperfections the orbit becomes unstable for  $Q$  integer
- ▶ Integer tunes lead to a resonant increase of the closed orbit amplitude in presence of the smallest dipole field error!

# Tunes and resonances

The particles – oscillating under the influence of the external magnetic fields – can be excited in case of resonant tunes to infinite high amplitudes.

There is particle loss within a short number of turns.



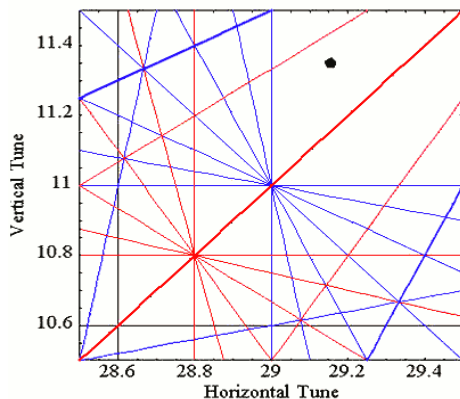
The cure:

1. **avoid** large magnet errors
2. **avoid forbidden tune values** in both planes

$$m \cdot Q_x + n \cdot Q_y \neq p$$

with  $m, n, p$  integer numbers

## Resonance diagram



A resonance diagram for the Diamond light source. The lines shown are the resonances and the black dot shows a suitable place where the machine could be operated.

# Quadrupole errors: tune shift

Orbit perturbation described by a thin lens quadrupole:

$$M_{\text{Perturbed}} = \underbrace{\begin{pmatrix} 1 & 0 \\ \Delta k ds & 1 \end{pmatrix}}_{\text{perturbation}} \underbrace{\begin{pmatrix} \cos \mu_0 + \alpha \sin \mu_0 & \beta \sin \mu_0 \\ -\gamma \sin \mu_0 & \cos \mu_0 - \alpha \sin \mu_0 \end{pmatrix}}_{\text{ideal ring}}$$

Let's see how the tunes changes: one-turn map

$$M_{\text{Perturbed}} = \begin{pmatrix} \cos \mu_0 + \alpha \sin \mu_0 & \beta \sin \mu_0 \\ \Delta k ds (\cos \mu_0 + \alpha \sin \mu_0) - \gamma \sin \mu_0 & \Delta k ds \beta \sin \mu_0 + \cos \mu_0 - \alpha \sin \mu_0 \end{pmatrix}$$

Remember the rule for computing the tune:

$$2 \cos \mu = \text{trace}(M) = 2 \cos \mu_0 + \Delta k ds \beta \sin \mu_0$$

## Quadrupole errors: tune shift (cont.)

We rewrite  $\cos \mu = \cos (\mu_0 + \Delta \mu)$

$$\cos (\mu_0 + \Delta \mu) = \cos \mu_0 + \frac{1}{2} \Delta k ds \beta \sin \mu_0$$

from which we can compute that

$$\Delta \mu = \frac{\Delta k ds \beta}{2} \quad \text{shift in the phase advance}$$

$$\Delta Q = \int_{s_0}^{s_0+L} \frac{\Delta k(s) \beta(s) ds}{4\pi} \quad \text{tune shift}$$

Important remarks:

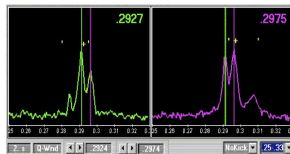
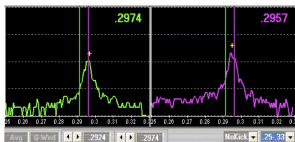
- ▶ the tune shift is proportional to the  $\beta$ -function at the quadrupole
  - ▶ field quality, power supply tolerances etc. are much tighter at places where  $\beta$  is large
- ▶  $\beta$  is a measurement of the sensitivity of the beam

# Quadrupole errors: tune shift example

Deliberate change of a quadrupole strength in a synchrotron:

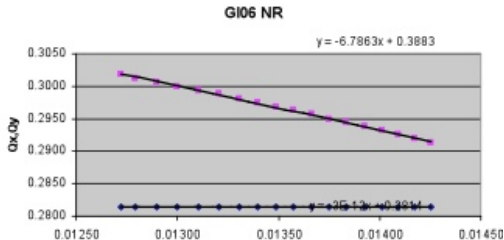
$$\Delta Q = \int_{s_0}^{s_0+L} \frac{\Delta K(s) \beta(s) ds}{4\pi} \approx \frac{\Delta K(s) L_{\text{quad}} \bar{\beta}}{4\pi}$$

⇒



*the tune is measured permanently*

*After changing the strength of a quad:  
we get a second peak*

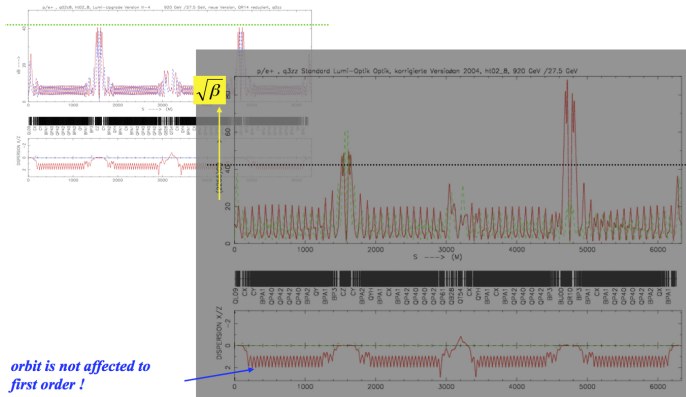


# Quadrupole errors: beta beat

A quadrupole error at  $s_0$  causes distortion of  $\beta$ -function at  $s$ :  $\Delta\beta(s)$  due to the errors of all quadrupoles:

$$\frac{\Delta\beta(s)}{\beta(s)} = \frac{1}{2 \sin 2\pi Q} \oint \beta(t) \Delta k(t) \cos(2\pi Q - 2(\mu(t) - \mu(s))) dt$$

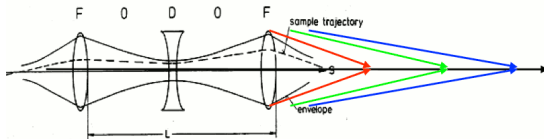
affects the element  $M_{12}$  of the  $M$  matrix.





## Quadrupole errors: chromaticity, $\xi$

Is an error (optical aberration) that happens in quadrupoles when  $\Delta p/p \neq 0$ :



The chromaticity  $\xi$  is the variation of tune  $\Delta Q$  with the relative momentum error:

$$\Delta Q = \xi \frac{\Delta p}{p_0} \Rightarrow \xi = \frac{\Delta Q}{\Delta p/p}$$

Remember the quadrupole strength:

$$k = \frac{g}{p/e} \quad \text{with } p = p_0 + \Delta p$$

then

$$k = \frac{eg}{p_0 + \Delta p} \approx \frac{e}{p_0} \left( 1 - \frac{\Delta p}{p_0} \right) g = k_0 + \Delta k$$

$$\Delta k = -\frac{\Delta p}{p_0} k_0$$

## Quadrupole errors: chromaticity (cont.)

$$\Delta k = -\frac{\Delta p}{p_0} k_0$$

⇒ Chromaticity acts like a quadrupole error and leads to a *tune spread*:

$$\Delta Q_{\text{one quad}} = -\frac{1}{4\pi} \frac{\Delta p}{p_0} k_0 \beta(s) ds \quad \Rightarrow \quad \Delta Q_{\text{all quads}} = -\frac{1}{4\pi} \frac{\Delta p}{p_0} \oint k(s) \beta(s) ds$$

Therefore the definition of chromaticity  $\xi$  is

$$\xi = -\frac{1}{4\pi} \oint_{\text{quads}} k(s) \beta(s) ds$$

The peculiarity of chromaticity is that it isn't due to external agents, it is generated by the lattice itself!

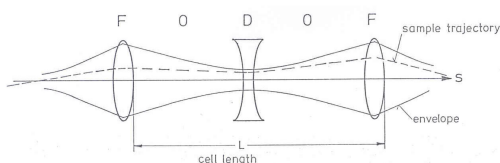
Remarks:

- ▶  $\xi$  is a number indicating the size of the tune spot in the working diagram
- ▶  $\xi$  is always created by the focusing strength  $k$  of **all** quadrupoles

In other words, because of chromaticity the tune is not a point, but it is pancake

## Example: Chromaticity of the FODO cell

Consider a ring composed by  $N_{\text{cell}}$  FODO cells like in figure, with two thin quads separated by length  $L/2$ ,

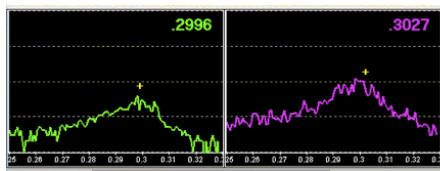


The natural chromaticity  $\xi_N$  for the  $N_{\text{cell}}$  cells is:

$$\begin{aligned}
 \xi_N &= -\frac{1}{4\pi} \oint \beta(s) k(s) ds \\
 &= -\frac{1}{4\pi} N_{\text{cell}} \int_{\text{cell}} \beta(s) \underbrace{k(s) d}_{\frac{1}{f}} \\
 &= -\frac{1}{4\pi} N_{\text{cell}} \left[ \beta^+ \left( \frac{1}{f_F} \right) - \beta^- \left( \frac{1}{f_D} \right) \right] \quad \left| \quad \begin{aligned}
 &= -\frac{1}{4\pi \sin \mu} N_{\text{cell}} \left[ \left( L + \frac{L^2}{4f_D} \right) \frac{1}{f_F} - \left( L - \frac{L^2}{4f_F} \right) \frac{1}{f_D} \right] \\
 &= -\frac{1}{4\pi \sin \mu} N_{\text{cell}} \left[ \frac{L}{f_F} - \frac{L}{f_D} + \frac{L^2}{2f_F f_D} \right] \\
 &\simeq -\frac{1}{8\pi \sin \mu} N_{\text{cell}} \frac{L^2}{f_F f_D}
 \end{aligned} \right.
 \end{aligned}$$

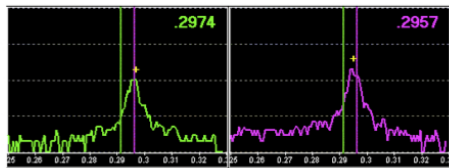
The chromaticity of the ring is  $N_{\text{cell}}$  times the chromaticity of each cell.

# Quadrupole errors: chromaticity



*Tune signal for a nearly  
uncompensated chromaticity  
(  $Q' \approx 20$  )*

*Ideal situation: chromaticity well corrected,  
(  $Q' \approx 1$  )*



# Tune shift correction

Errors in the quadrupole fields induce tune shift:

$$\Delta Q = \oint_{\text{quads}} \frac{\Delta k(s) \beta(s) ds}{4\pi}$$

Cure: we compensate the quad errors using other (correcting) quadrupoles

- ▶ If you use only one correcting quadrupole, with  $1/f = \Delta k_1 L$ 
  - ▶ it changes both  $Q_x$  and  $Q_y$ :

$$\Delta Q_x = \frac{\beta_{1x}}{4\pi f_1} \quad \text{and} \quad \Delta Q_y = -\frac{\beta_{1y}}{4\pi f_1}$$

- ▶ We need to use two independent correcting quadrupoles:

$$\begin{aligned} \Delta Q_x &= \frac{\beta_{1x}}{4\pi f_1} + \frac{\beta_{2x}}{4\pi f_2} \\ \Delta Q_y &= -\frac{\beta_{1y}}{4\pi f_1} - \frac{\beta_{2y}}{4\pi f_2} \end{aligned} \quad \begin{pmatrix} \Delta Q_x \\ \Delta Q_y \end{pmatrix} = \frac{1}{4\pi} \begin{pmatrix} \beta_{1x} & \beta_{2x} \\ \beta_{1y} & \beta_{2y} \end{pmatrix} \begin{pmatrix} 1/f_1 \\ 1/f_2 \end{pmatrix}$$

- ▶ Solve by inversion:

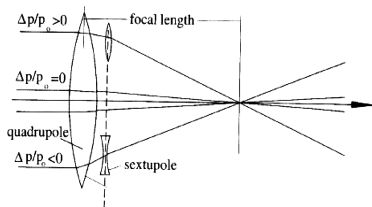
$$\begin{pmatrix} 1/f_1 \\ 1/f_2 \end{pmatrix} = \frac{4\pi}{\beta_{1x}\beta_{2y} - \beta_{2x}\beta_{1y}} \begin{pmatrix} \beta_{2y} & -\beta_{2x} \\ -\beta_{1y} & \beta_{1x} \end{pmatrix} \begin{pmatrix} \Delta Q_x \\ \Delta Q_y \end{pmatrix}$$

# Chromaticity correction

Remember what is chromaticity: the quadrupole focusing experienced by particles changes with energy

- ▶ it induces tune shift, which can cause beam lifetime reduction due to resonances

Cure: we need additional energy dependent focusing. This is given by sextupoles



- ▶ The sextupole magnetic field rises quadratically:

$$\begin{aligned} B_x &= \tilde{g}xy \\ B_y &= \frac{1}{2}\tilde{g}(x^2 - y^2) \end{aligned} \quad \Rightarrow \quad \frac{\partial B_x}{\partial y} = \frac{\partial B_y}{\partial x} = \tilde{g}x \quad \text{a "gradient"}$$

it provides a linearly increasing quadrupole gradient

## Chromaticity correction (cont.)

Now remember:

- ▶ Normalised quadrupole strength is

$$k = \frac{\tilde{g}}{p/e} [\text{m}^{-2}]$$

- ▶ Sextupoles are characterised by a normalised sextupole strength  $k_2$ , which carries a focusing quadrupolar component  $k_1$ :

$$k_2 = \frac{\tilde{g}}{p/e} [\text{m}^{-3}]; \quad \tilde{k}_1 = \frac{\tilde{g}x}{p/e} [\text{m}^{-2}]$$

Cure for chromaticity: we need sextupole magnets installed in the storage ring in order to increase the focusing strength for particles with larger energy

- ▶ A sextupole at a location with dispersion does the trick:  $x \rightarrow x + D \cdot \frac{\Delta p}{p}$

$$\tilde{k}_1 = \frac{\tilde{g} \left( x + D \frac{\Delta p}{p} \right)}{p/e} [\text{m}^{-2}]$$

- ▶ for  $x = 0$  it corresponds to an energy-dependent focal length

$$\frac{1}{f_{\text{sext}}} = \tilde{k}_1 L_{\text{sext}} = \underbrace{\frac{\tilde{g}}{p/e}}_{k_2} \overbrace{D \frac{\Delta p}{p}}^{\tilde{k}_1} \cdot L_{\text{sext}} = k_2 D \cdot \frac{\Delta p}{p} \cdot L_{\text{sext}}$$

Now the formula for the chromaticity rewrites:

$$\xi = \underbrace{-\frac{1}{4\pi} \oint k(s) \beta(s) ds}_{\text{chromaticity due to quadrupoles}} + \underbrace{\frac{1}{4\pi} \oint k_2(s) D \beta(s) ds}_{\text{chromaticity due to sextupoles}}$$



# Design rules for sextupole scheme

- ▶ Chromatic aberrations must be corrected in both planes  $\Rightarrow$  you need at least two sextupoles
- ▶ In each plane the sextupole fields contribute with different signs to the chromaticity  $\xi_x$  and  $\xi_y$ :

$$\xi_x = -\frac{1}{4\pi} \oint [k - S_F D_x + S_D D_x] \beta_x(s) ds$$

$$\xi_y = \frac{1}{4\pi} \oint [k - S_F D_x + S_D D_x] \beta_y(s) ds$$

- ▶ To minimise chromatic sextupoles strengths, sextupoles should be located near quadrupoles where  $\beta_x D_x$  and  $\beta_y D_x$  are maximum.
- ▶ Important remark: for offset orbits, the sextupoles introduce *geometric aberrations*. They can be reduced by adopting a  $-I$  transformation scheme:
  - ▶ put sextupoles in  $(2n+1)\pi$  phase advance apart in a periodic lattice to compensate the effect

# Summary

orbit for an off-momentum particle  $x(s) = x_\beta(s) + D(s) \frac{\Delta p}{p}$

dispersion trajectory  $D(s) = S(s) \int_0^s \frac{1}{\rho(t)} C(t) dt - C(s) \int_0^s \frac{1}{\rho(t)} S(t) dt$

equations of motion with dispersion 
$$\begin{pmatrix} x \\ x' \\ \Delta p/p \end{pmatrix}_s = \begin{pmatrix} C & S & D \\ C' & S' & D' \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ x' \\ \Delta p/p \end{pmatrix}_0$$

definition of momentum compaction  $\frac{\Delta C}{C} = \alpha \frac{\Delta p}{p}$

stability condition  $m \cdot Q_x + n \cdot Q_y \neq p$  with  $n, m, p$  integers

tune shift  $\Delta Q = \frac{1}{4\pi} \oint_{\text{quads}} \Delta k(s) \beta(s) ds$

beta beat 
$$\frac{\Delta \beta(s)}{\beta(s)} = \frac{1}{2 \sin 2\pi Q} \oint \beta(t) \Delta k(t) \cos(2\pi Q - 2(\mu(t) - \mu(s))) dt$$

chromaticity  $\xi = \frac{\Delta Q}{\Delta p/p} = -\frac{1}{4\pi} \oint_{\text{quads}} k(s) \beta(s) ds$

# References

Derivation of the equation of the orbit distortion for a dipole field errors:

1. Shyh-Yuan Lee: Accelerator Physics, World Scientific, 2004
2. The CERN Accelerator School (CAS) Proceedings