CMS Tracker Upgrade: Requirements and Layout

Stefano Mersi On behalf of the CMS Collaboration 19 March 2014 RCES 2014

Pixel & strip replacement: aim at LS3

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Survive **JL.dt** = **3000 fb**⁻¹

Higher L1A rate \rightarrow > 500 kHz

Resolve **<µ>=140** → 200

Latency \rightarrow > 10 µs

Ensure experiment lifetime

Improve tracking at high pT

Improve tracking at low pT Reduce secondary interactions

Increase forward acceptance

Improve CMS trigger

New outer tracker & new pixel

Total tracker replace Pixel & strip replacement: aim Survive ∫L.dt = 3000 fb ⁻¹ Higher L1A rate → > 500 kHz	ment Mersi - RCES 2014 A
Resolve <µ>=140 → 200	Higher granularity
Latency → > 10 µs	Larger front-end buffers
Ensure experiment lifetime	Redundancy for Outer Tracker Possible extraction for Pixels
Improve tracking at high pT	Increase granularity
Improve tracking at low pT Reduce secondary interactions	Reduce material
Increase forward acceptance	Mostly through pixel layout
Improve CMS trigger	Provide tracking to Level-1 40 MHz output for L1

The challenge

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Material amount is limiting current tracker's performance: reduce material

LESS power/material

MORE power/material

New technologies

- DC-DC converters
- CO₂ cooling
- Low-power GBT
- Front-ends

Less layers

Higher granularity Bandwidth!

Outer Tracker

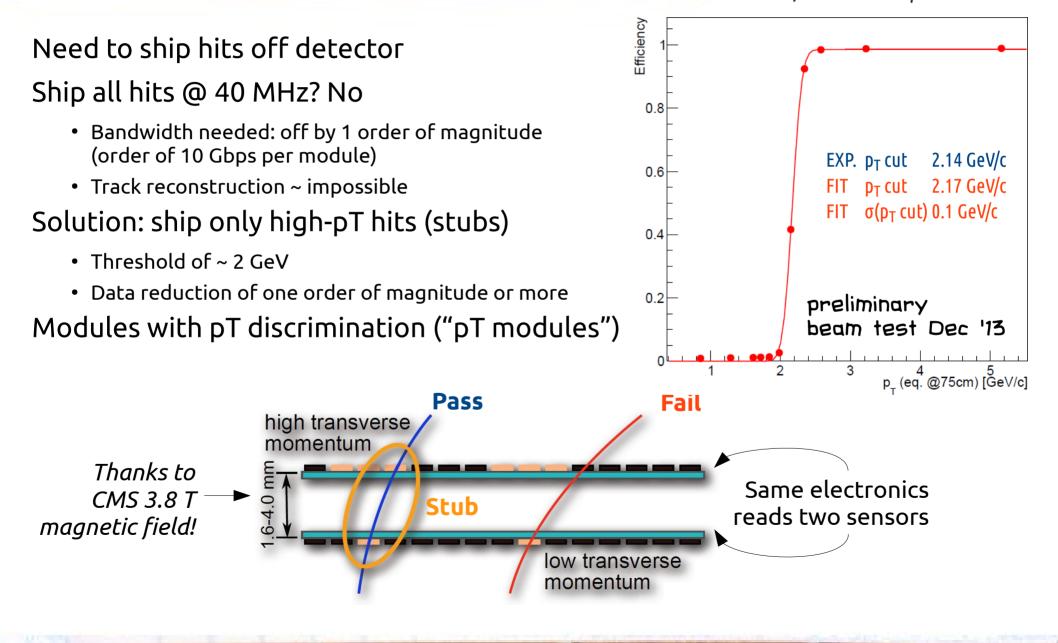
Challenging requirements:

- Trigger readout (40 MHz)
- Power (=material!)
- Track finding QL1

pT modules Providing "stubs" for tracking trigger

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Module design Concept: integration at the module level

Binary readout: CBC

provides hit-matching (already working prototype)

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CO_2 cooling

already used in Phase-1 mass-efficient cooling

Hybrid is the key element

nyunu nodule integration

Data link: Low-power GigaBit Transceiver

lpGBT currently under development integrated at module level

DC/DC converter

Functional Prototypes in handl

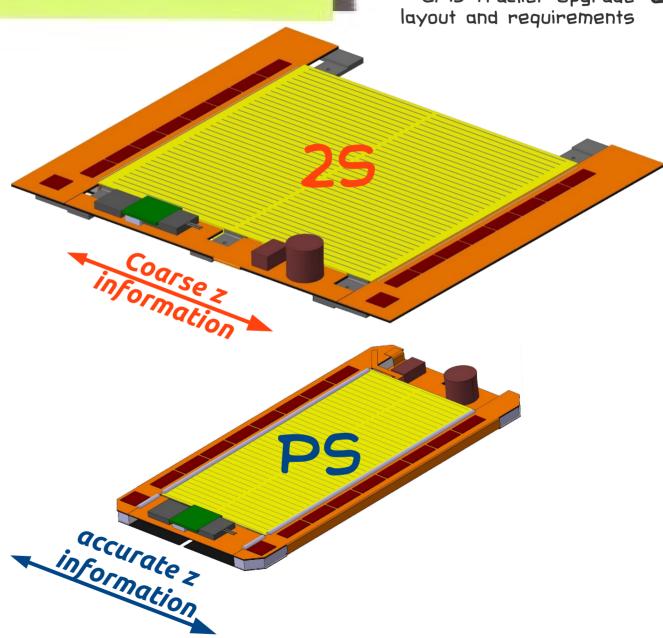
already used in Phase-1 10 V lines: lower current, lower material

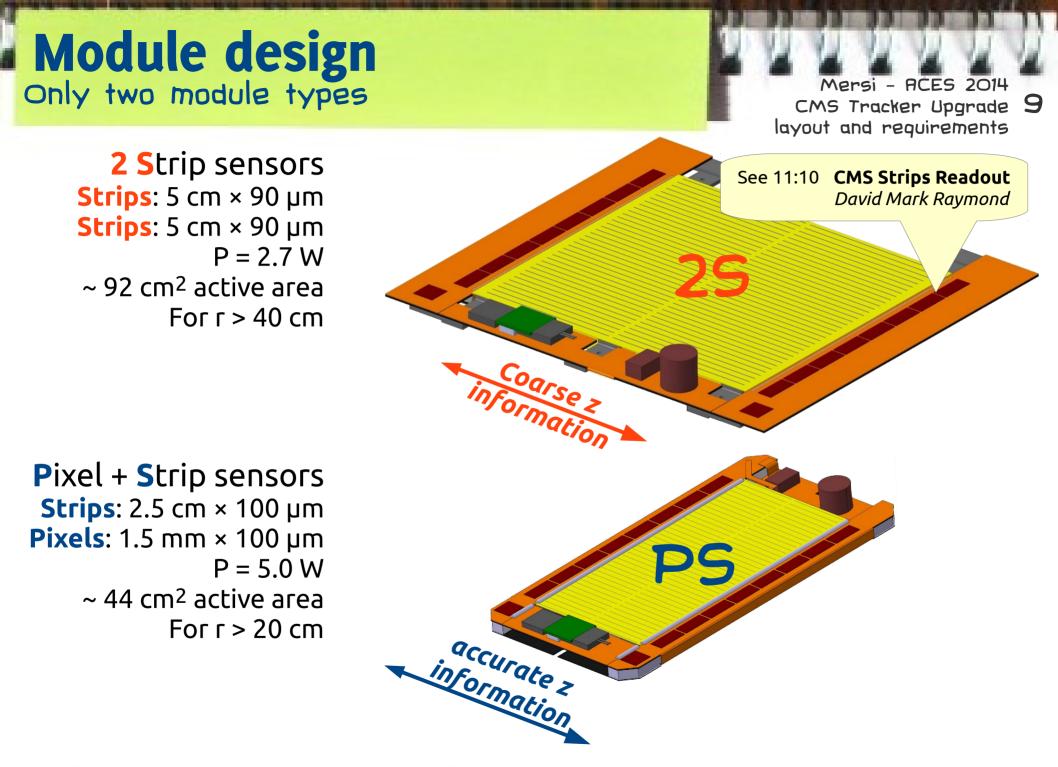
Only two module types

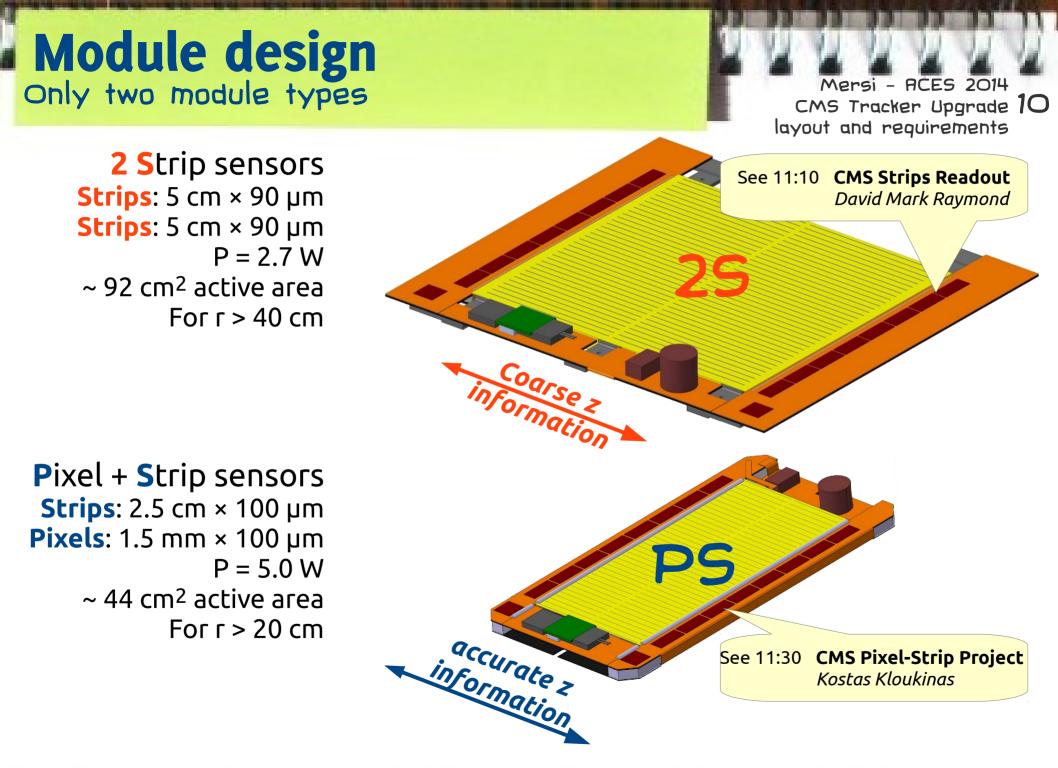
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2 Strip sensors Strips: 5 cm × 90 μm Strips: 5 cm × 90 μm P = 2.7 W ~ 92 cm² active area For r > 40 cm

Pixel + Strip sensors Strips: 2.5 cm × 100 μm **Pixels**: 1.5 mm × 100 μm P = 5.0 W ~ 44 cm² active area For r > 20 cm







Module design Concept: integration at the module level

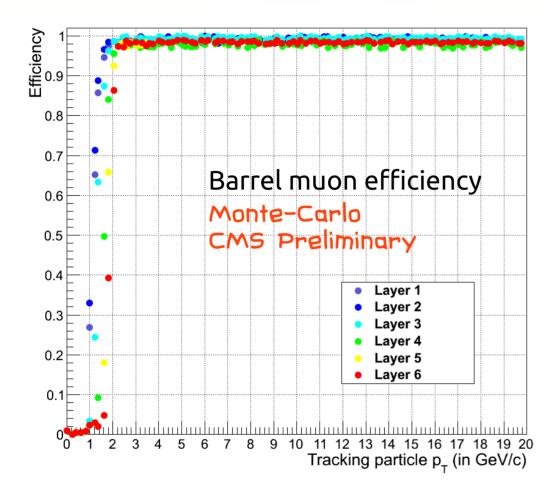
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- Two sensors per module
 - Mass-effective way of collecting two coordinates
 - Help for pattern recognition (also for HLT)
- Large bandwidth needed => one link per module
 - Contribution to power: moderate
 - System very simple and elegant (... light!)
 - Almost no electrical connectivity in the tracking volume
 - The module is a self-contained system

The chosen implementation brings many **more advantages than drawbacks**

Uniform cut Possible, with tuning

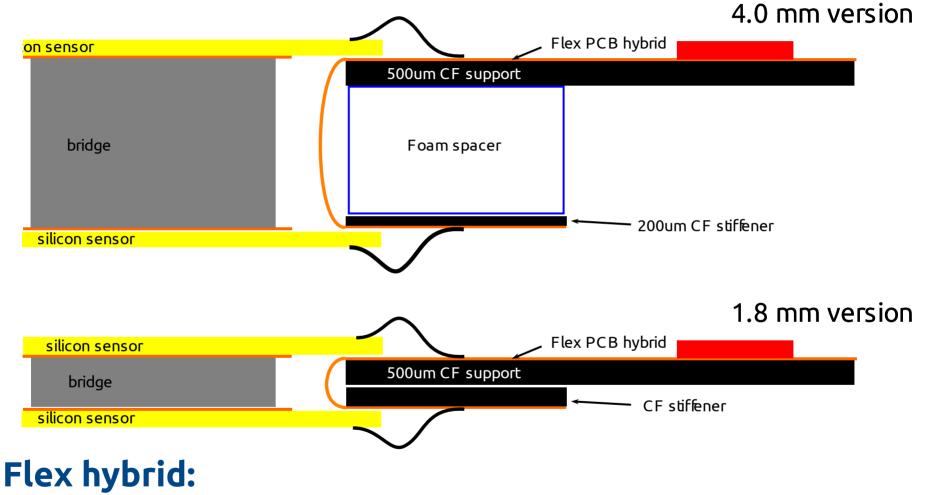
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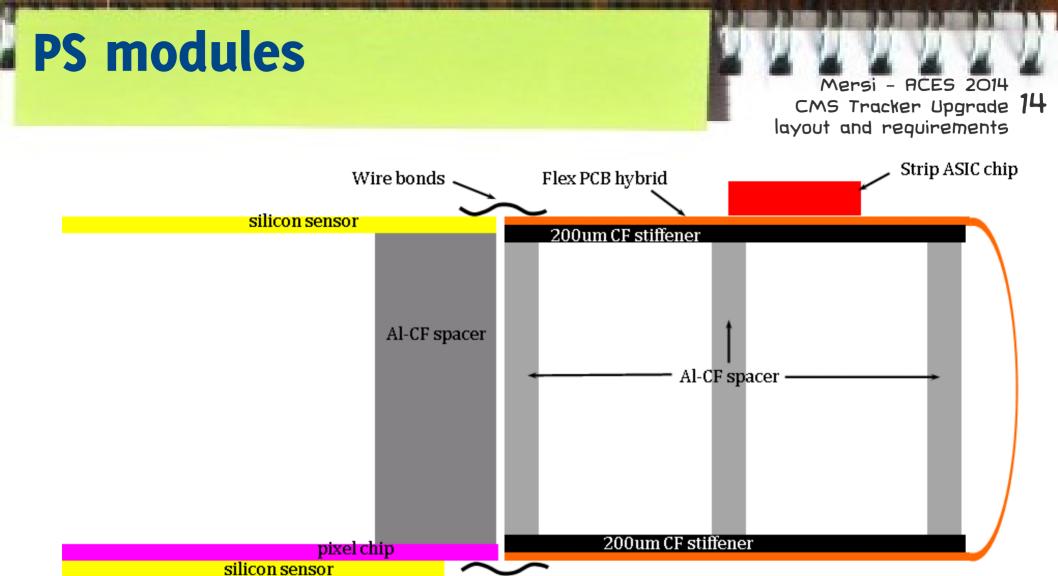
(@construction) (@front-ends) Need to tune **sensor spacings** and **hit matching windows** are required to maintain uniform p_T cut

2S modules

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- Technology leap
- Key element for 2-sensor design



Flex hybrid:

200um CF base plate

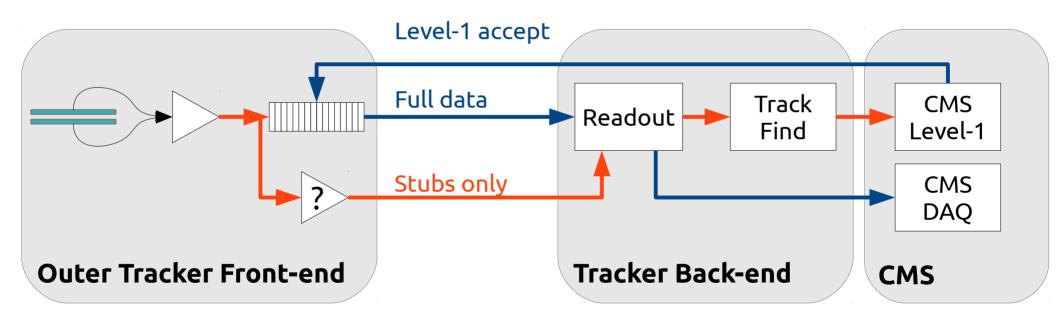
- Technology leap
- Key element for 2-sensor design

Providing tracks for trigger Readout architecture

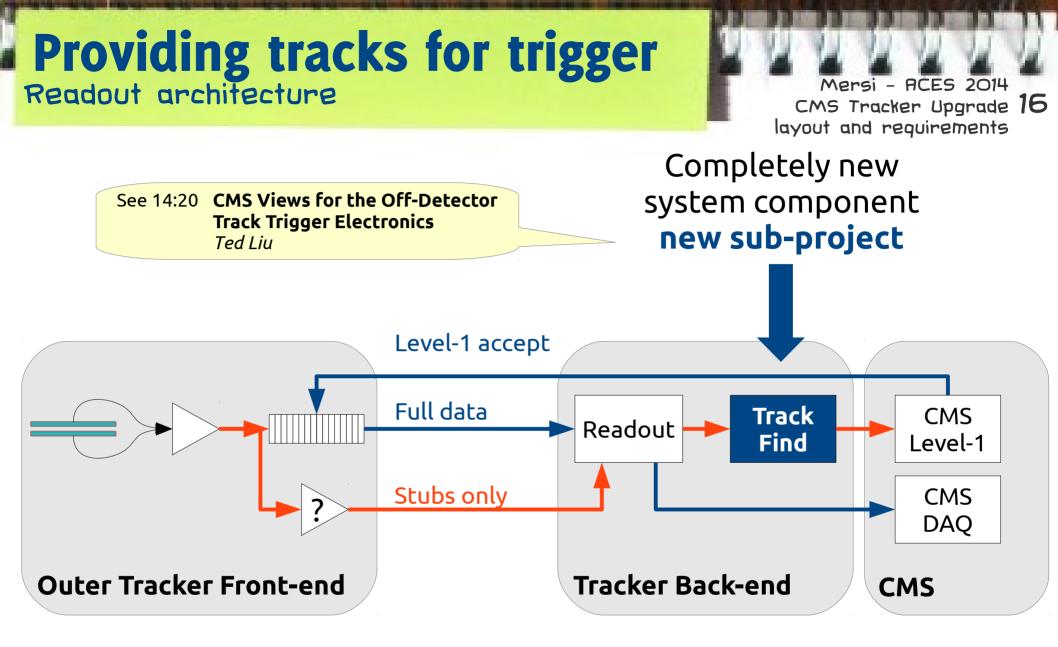
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Level-1 "stubs" are processed in the back-end

Form Level-1 tracks, pT above ~ 2 GeV, contributing to CMS Level-1 trigger



@ 40 MHz – Bunch crossing
@ ~ 500 kHz – CMS Level-1 trigger



@ 40 MHz – Bunch crossing
@ ~ 500 kHz – CMS Level-1 trigger

Pixel detector

Challenging requirements:

- Radiation hardness
- Readout bandwidth
- Power (=material!)
- Contribution to trigger ?

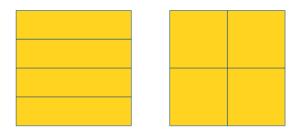
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Sensors: Φ up to 2×10¹⁶ neq cm⁻² @ r=5 cm

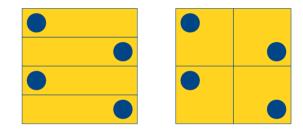
With current CMS pixel @600V CCE = 50% at 10¹⁶ neg cm⁻²

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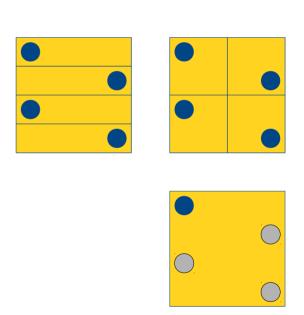
- Sensors: Φ up to 2×10¹⁶ neq cm⁻² @ r=5 cm
 - Thin planar
 - 3D
 - Resolution? Smaller pixels:
 - 100 × 25 µm²
 - 50 × 50 µm²



- Mersi ACES 2014 CMS Tracker Upgrade 20 layout and requirements
- Sensors: Φ up to 2×10¹⁶ neq cm⁻² @ r=5 cm
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 - 3D
 - Resolution? Smaller pixels:
 - 100 × 25 µm²
 - 50 × 50 µm²
- Front-end: up to 10 MGy
 - ROC Chip 65 nm CMOS
 - One chip, footprint compatible with both pixel geometries



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 - 3D
 - Resolution? Smaller pixels:
 - 100 × 25 µm²
 - 50 × 50 µm²
- Front-end: up to 10 MGy
 - ROC Chip 65 nm CMOS
 - One chip, footprint compatible with both pixel geometries
 - Same chip compatible also with 100x100 μm^2 pixels
 - Radiation hardness? Other electronics?



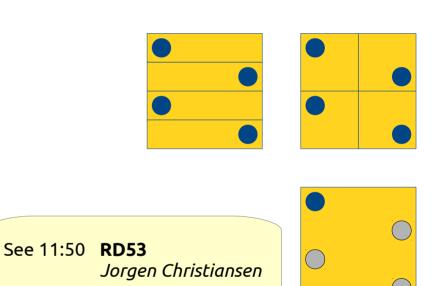
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- Sensors: Φ up to 2×10¹⁶ neq cm⁻² @ r=5 cm
 - Thin planar
 - 3D
 - Resolution? Smaller pixels:
 - 100 × 25 µm²
 - 50 × 50 µm²
- Front-end: up to 10 MGy
 - ROC Chip 65 nm CMOS
 - One chip, footprint compatible with both pixel geometries
 - Same chip compatible also with 200x200 μm^2 pixels
 - Radiation hardness? Other electronics?



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Pixels: readout bandwidth Huge increase w.r.t. present system

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HL-LHC Present system × 10 Rate → 200 MHz/cm² Rate \rightarrow 2 GHz/cm² L1 rate 500 kHz (1 MHz) x 5~10 – L1 rate 100 kHz x 50~100 Optical on-board readout not possible: – Rad-hardness – Material/space Electrical links to opto links Out of main Phase 1: ~1m x 400 MBps acceptance? Twp link Ooto Module Even more difficult to keep material budget under control

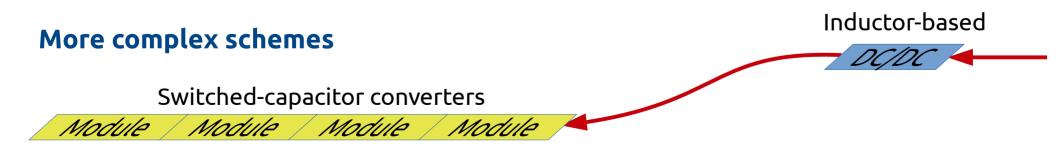
Pixel: power => material

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- Target: O(0.5) W/cm²
- Traditional inductor-based on-board DC/DC not possible:
 - Rad-hardness
 - Material/space
- Possible options:

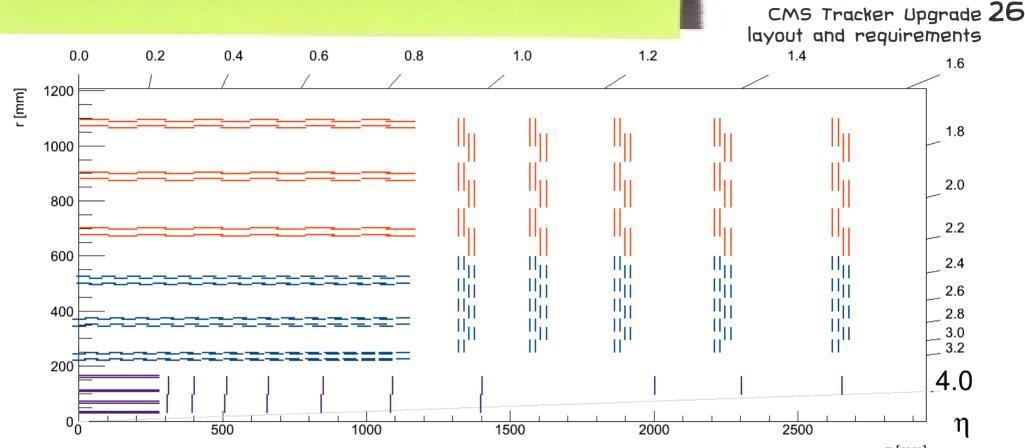
Serial powering





Layout and expected performance

Tracker Layout



Lower density **25 modules** outside (~8400 modules) **PS modules** middle z info in trigger θ info in trigger (~7100 modules)

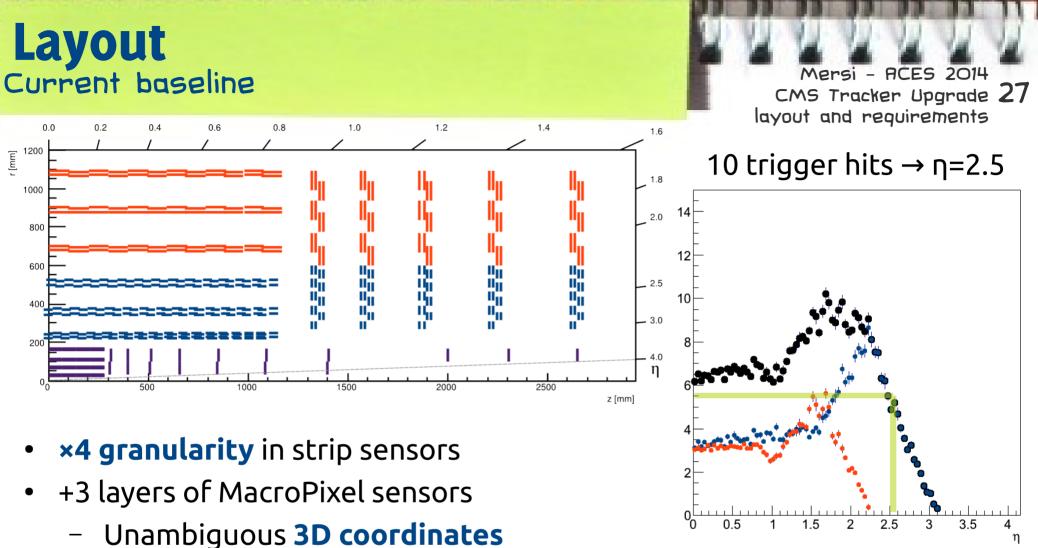
More detailed model

Pixel modules inside accurate impact parameter resolution & forward coverage **No detailed model**: using Phase-I detector layout w/ more disks in the forward

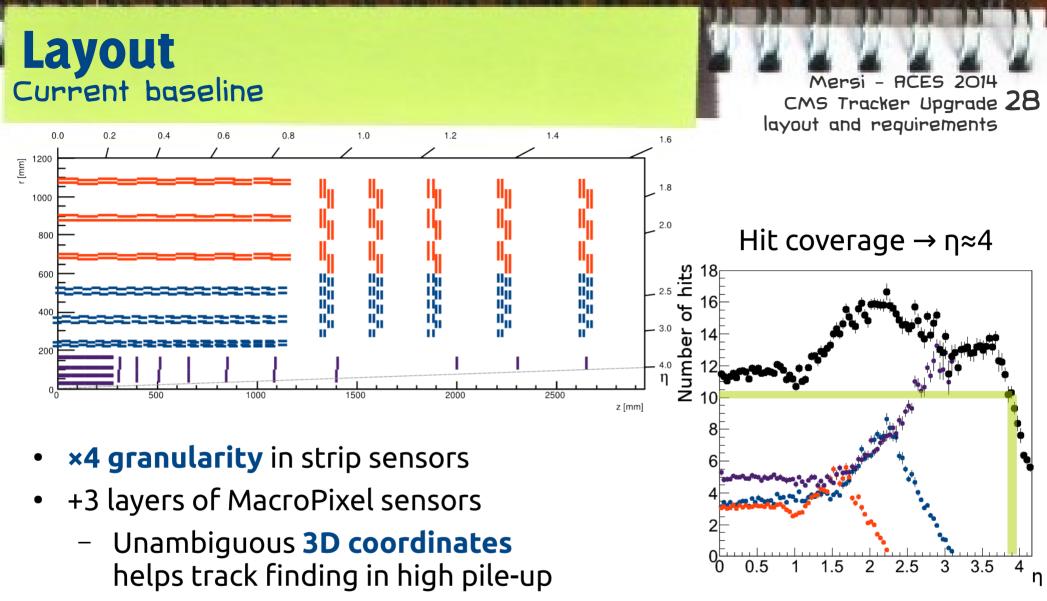
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- Unambiguous 3D coordinates helps track finding in high pile-up
- Up to **10 points** available for track-trigger up to $\eta=2.5$
 - Comparable to current tracker's coverage, but at L1



- Up to **10 points** available for track-trigger up to η=2.5
 - Comparable to current tracker's coverage, but at L1
- Hit coverage up to **η≈4** at L1A

Upgrade overview

Current

Upgrade

Outer	~200 m ²	Silicon	~220 m ²	Silicon
0	9.3 M	Strips	47.8 M	Strips
	0	MacroPixels	217 M	MacroPixels
	15'148	Modules	15'508	Modules
	100 kHz	readout rate	40 MHz	readout rate*
Pixel	~1 m²	Silicon	4.6 m ²	Silicon
	66 M	Pixels	O(1) G?	Pixels
	1440	Modules	??	??
	100 kHz	readout rate	>500 kHz readout rate	
			¥	

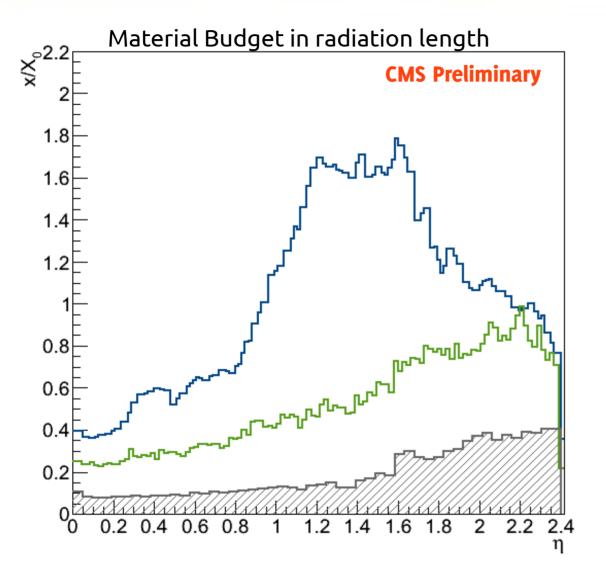
* only high-pt hits read-out

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Tracker material budget

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CMS Phase-1

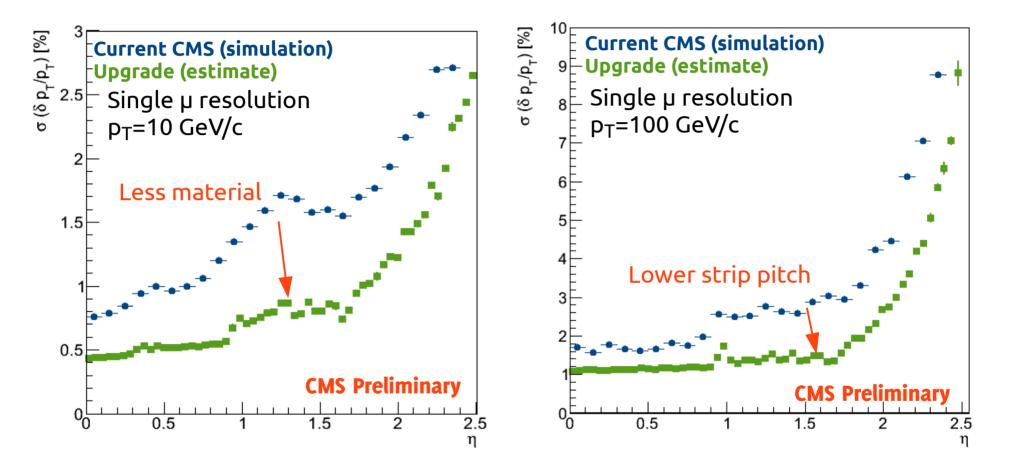
CMS Phase-2 estimate, if keeping ~ phase-1 pixels material



Phase-1 Pixel

Tracking resolution pT resolution of single muons

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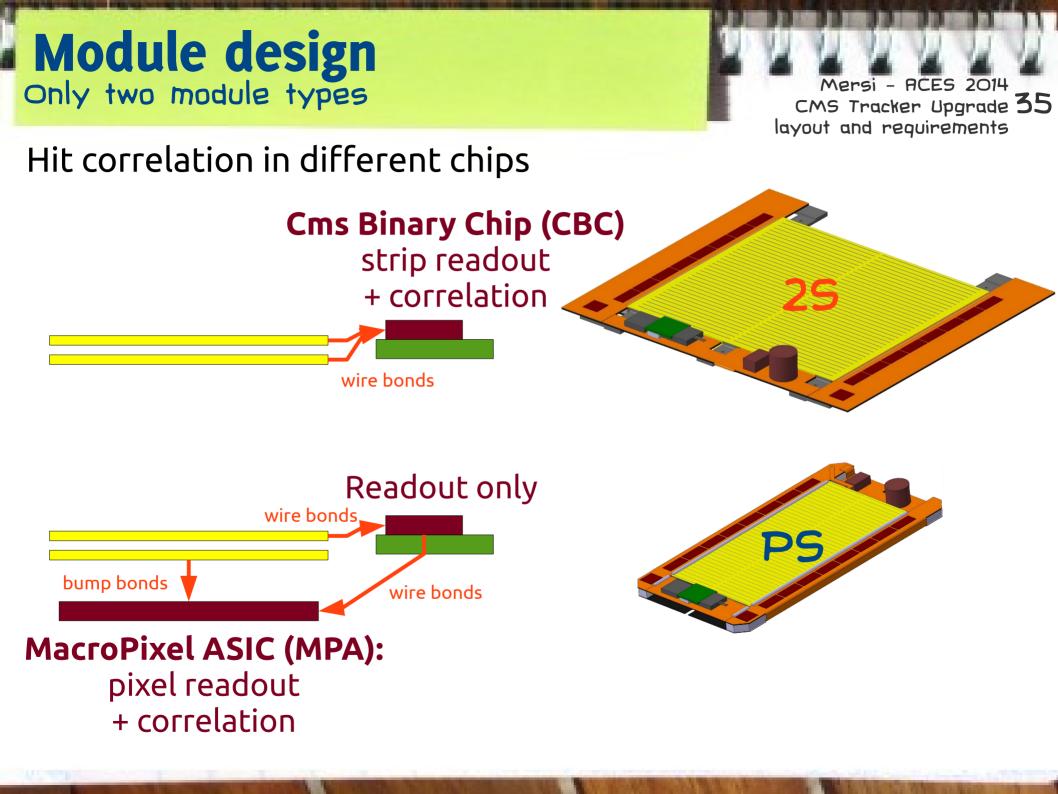
Clear improvement expected in the whole pT range

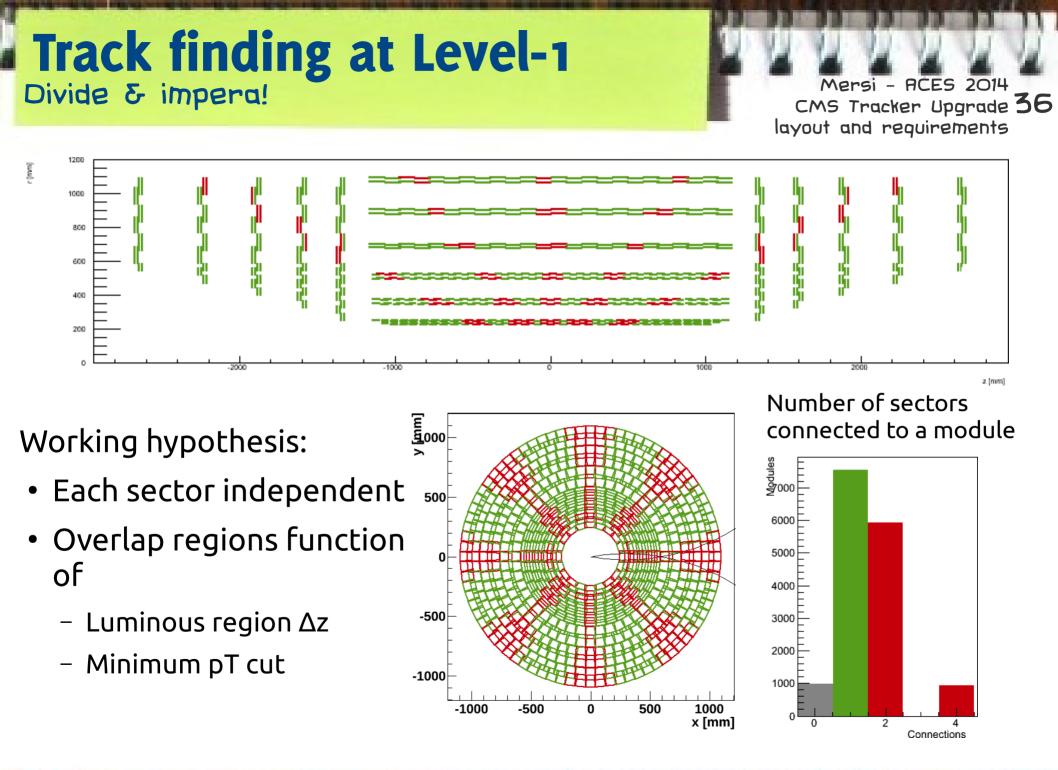
Track-trigger resolution Potential pT resolution using all stub info Mersi **RCES 2014** CMS Tracker Upgrade 32 lavout and requirements 10 σ (δ p_T/p_T) [%] 0.3_{I} z₀) [cm] pT potential resolution z0 potential resolution 9 **CMS** Preliminary **CMS Preliminary** [∞]0.25 0.2 6 5 0.15 4 % 1 mm 0 3 0.05 **CMS Preliminary** 0₀ 0.5 0.5 1.5 1.5 2 2.52 2.5 Challenge for L1-track finding: Single $\mu p_T = 2 \text{ GeV/c}$ Single µ p_T=10 GeV/c finding precise tracking information Single µ p_T=100 GeV/c See 14:20 CMS Views for the Off-Detector **Track Trigger Electronics**

Ted Liu

Thank you!

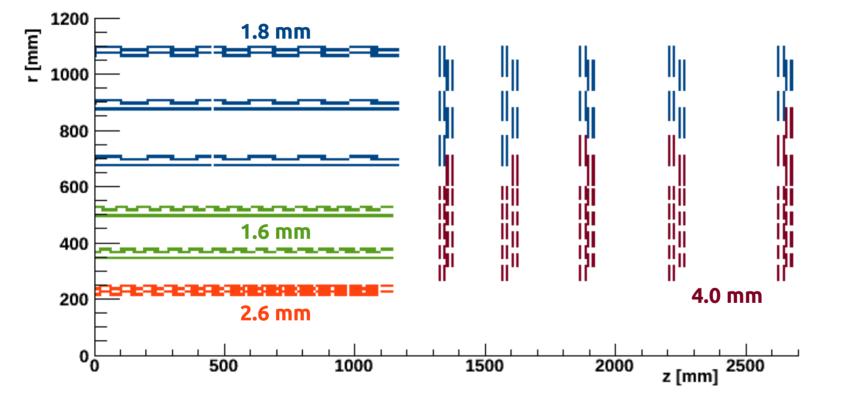
Total tracker replace Pixel & strip replacement: aim of	Mersi - ACES 2014 CMS Tracker Upgrade 34 layout and requirements
Survive JL.dt = 3000 fb-1	Radiation hardness Operating cold (-20°C)
Higher L1A rate → > 500 kHz	Bandwidth!
Resolve <µ>=140 → 200	Higher granularity
Latency → > 10 µs	Larger front-end buffers
Ensure experiment lifetime	Redundancy for Outer Tracker Possible extraction for Pixels
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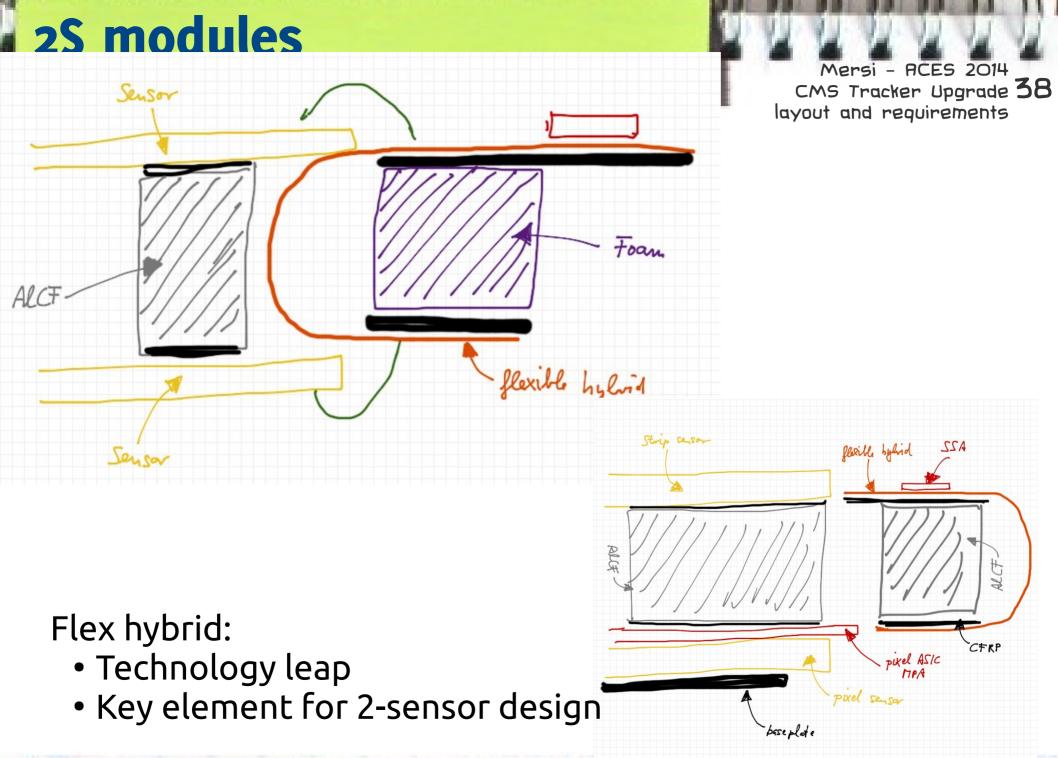




sensor spacing must be tuned along with search windows

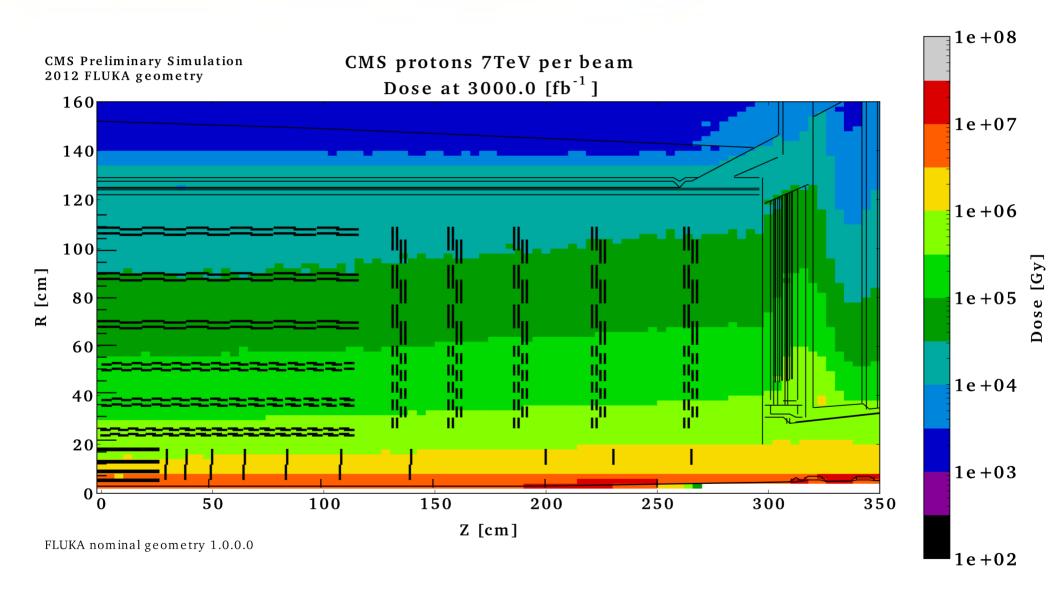
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Radiation map

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