Magnetic measurement systems for future high performance magnets

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Introduction

- Magnetic measurement services at CERN centralized in two work units as of 2007: PH-DT1-MM: experimental magnets
 AT-MEI-MM: accelerator magnets (resistive, superconducting ... everything BUT kickers)
- Accumulated equipment and knowledge from many groups and projects over 50 years
- Most instruments optimized for a specific magnet family (LHC, SPS, etc ..) adaptations possible but not always practical
- Large variety \rightarrow some duplication of functionality, costly maintenance, HW and SW platforms not always consistent (LabView, Visual Basic, C ...)
- Overall: an extensive array of instruments, devices and facilities that has served well its purpose for the existing machines

Present objectives

- <u>Qualify new/repaired magnets for existing machines and upgrades</u>
- <u>Refine</u> magnetic models for accelerator operation ("FIDEL")
- Extend capabilities and improve accuracy for LHC and future projects







Current status – instrumentation

	magnet parameters					quantity					performance	
		Field	dB/dt	I	Gap/Ø			axis		field	resolution	
System	Т	[T]	(T/s]	L _{MAX} [m]	[mm]	∫BdL	b _n a _n	magn	mech		time	length
						∫GdL					[s]	[mm]
15m shaft ("TRU")	W/C	0.01 - 10	0.007	15	40	✓	\checkmark				10	1150
Shafts for vertical cryostat ("bloc4")	W	0.05 - 10	0.007	3	50-70	✓	\checkmark	\checkmark			10	1000
은 Industry dipole moles ("DIMM")	W	0.01 - 0.05	steady-state	any (scan)	50	✓	✓			✓	steady-state	200-750
E Industry quad moles ("QIMM")	W	0.01 - 0.05	steady-state	any (scan)	45-70	 Image: A set of the set of the	\checkmark			\checkmark	steady-state	750
AC mole	W/C	10 ⁻⁵	steady-state	any (scan)	40-50		±	\checkmark	\checkmark	±	steady-state	100-200
Linac 2 bench	W	0.001-1	steady-state	0.2	20-30	~	~	\checkmark		 Image: A second s	steady-state	integral
Fluxmeter + digital integrator	W	n.a.	f(N _{TURNS} A _{COIL})	2	≥20	√	±				10 ⁻²	integral
Fluxmeter + digital integrator (SPS)	W	n.a.	2	8	≥20						10 ⁻²	integral
Fluxmeter + fast ADC	W	n.a.	f(N _{TURNS} A _{COIL})	2	≥ 20						10 ⁻⁵	integral
ё PS ("Huron") bench	W	n.a.	1	1.5	≥20	 Image: A second s		\checkmark		\checkmark	10 ⁻²	30-1000
Linac 2 bench	W	n.a.	300	0.2	20-70	 Image: A second s	√	\checkmark		√	n.a.	integral
Single Stretched Wire (FERMILAB)	W/C	0.01 - 10	steady-state	20	≥10	~	±	✓		~	steady-state	integral
Souble Stretched Wire	W/C	n.a.	f(L _{MAGNET})	20	≥10	✓					steady-state	integral
3-axis Hall probe scanner	W	30	steady-state	1.5	≥ 30	√	\checkmark				steady-state	2
B3-B5 Hall probe ring	С	10	0.007	any (scan)	40		\checkmark				10 ⁻³	2
Polarimeter (rotating Hall plate)	W	0.1	steady-state	any (scan)	50	±					steady-state	2

• <u>Typical accuracies</u>: B1 10⁻⁴, B2 10⁻³, harmonics (relative) 10⁻⁵, magnetic axis wr.t. external fiducials 0.2 mm

• Instruments often <u>customized</u> for internal use and external collaborations eg CNAO, ASG, CELLS/ALBA, Saclay

Main HW platform: VFC-based "Programmable Digital Integrator" PDI on VME bus







Current status - measurement coils



2.5 m curved fluxmeter array for CNAO dipoles

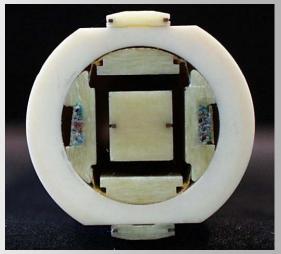


X-section of 20x20 multi-strand flat cable coil





Inset quadrupole-compensated coil for Linac4 PMQs



X-section of 15m long LHC ceramic coil shaft

- <u>Large stock (</u>~1000) of measurements coils and assemblies (20 mm≤∅≤70 mm, 2 mm≤L≤7 m)
- Specialized <u>coil manufacturing and calibration facility</u>: 2 mm to 2 m long, up to 4000 turns with mono-(machine wound) or multi-strand wire (manually wound), air or G10 core
- <u>Coil arrays, dipole and quadrupole-compensated assemblies</u> (bucking factor up to 6000 with matched sets) on ceramic or composite supports, straight or curved
- Specific expertise in design, micro-welding, precision machining, gluing and magnetic calibration



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Measurement parameters

- LHC (or any SC magnet): improve time resolution (0.1→5 Hz) and harmonic accuracy (0.1→0.02 units) for dynamic phenomena (snapback)
- **Fast-pulsed magnets:** improve time resolution for local/integral eddy current transients *(recently required for PS & CNAO)*
- Linac 4: measure magnetic axis in assembled DTL module (Ø20 1500 mm bore)
- LHC Upgrade: same accuracy of strength/harmonics/axis than existing triplets (??)



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Main issues

Higher B + higher dB/dt+ larger \emptyset = higher signal = better measurement, however ...

Harmonic/fixed coil systems

- Faster measurements and/or increased B, B, Ø ⇒ signals exceeding typical 10V range ⇒ use coils with reduced surface (turns), modulate rotation speed (better accuracy) and/or amplifier gain (more practical)
- Faster measurements \Rightarrow continuous rotation
- Existing PDI integrators cannot cope with high acquisition bandwidth
- Larger $\emptyset_{BORE} \Rightarrow \text{keep } \emptyset_{COIL} \gtrsim 2 \mathbb{A} \emptyset_{BORE}$ to minimize harmonic extrapolation errors \Rightarrow design & build new coil support shafts
- Larger Ø_{COIL} ⇒ massive ceramic shafts unsuitable ⇒ <u>new mechanical design necessary</u> (but: easier to machine, room to add optical targets for axis detection)
- Larger Ø_{COIL} ⇒ calibration in existing reference magnets may be not possible ⇒ <u>new reference magnets/calibration procedures/coil geometries</u>

General problems

- Eddy current magnetic forces scale as $\mathbf{B}\dot{\mathbf{B}} \Rightarrow$ effects on probe materials increased by $10^1 \sim 10^2$
- <u>High field reference magnets</u>: needed for sensor calibration, material and system characterization (NB: existing Metrolab NMR teslameter maxes at 14 T, primary reference needed)







Undergoing Activities

- Higher speed signal acquisition and integration → Fast Digital Integrator (FDI)
- Higher speed harmonic measurements → FAst MEasurement system (FAME)
- Obsolescent software → Flexible Framework for Magnetic Measurements (**FFMM**) (with UniSannio)
- Linac 4 → Existing Linac 2 bench being upgraded for permanent and fast-pulsed magnet (new mechanics, coils, integrators, power supplies, software)

Future Activities

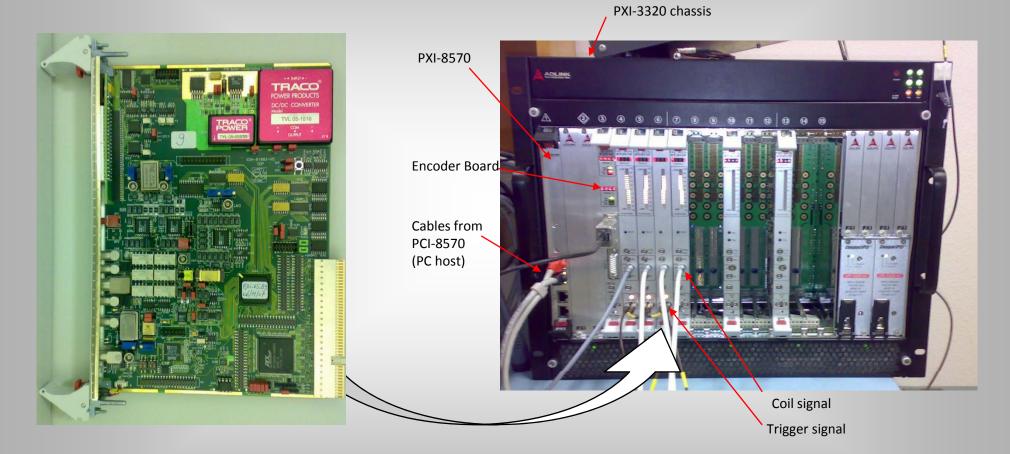
- Large diameter bores \rightarrow R&D for suitable coil shafts (geometry, materials, calibration etc..)
 - coil shaft for short models in vertical cryostat ("Bloc4" cold measurement system)
 - coil shaft for long cryoassemblies w/ anticryostat (SM18 test benches)
- General-purpose travelling probe family with <u>tangential harmonic coils</u> and <u>optical target</u> for axis detection ("supermole")
- R&D on components at high B/B: inclinometers, piezo motors, encoders etc ...
- Measurement and analysis techniques for strongly curved magnets





Fast Digital Integrator (FDI) – overview

- joint development since 2005 with Università del Sannio (Italy)
- PXI board integrating analog front-end, programmable amplifier, 18-bit ADC, DSP numerical processing
- software drivers for LabView + new in-house C++ class framework (FFMM)



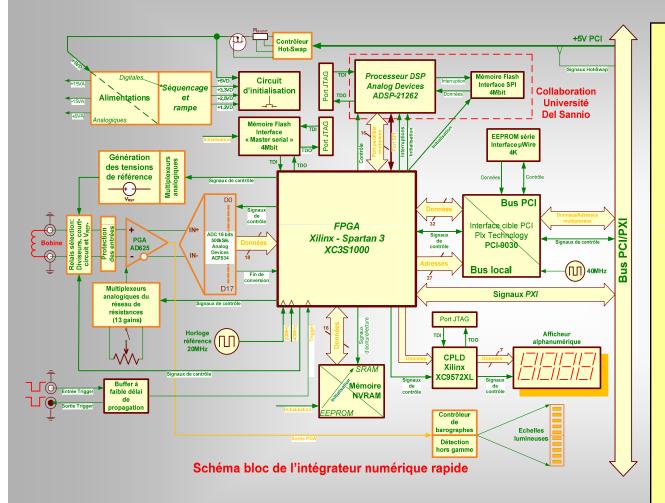
aim: increase bandwidth and accuracy for fast fixed- and rotating-coil magnetic measurements Set to replace existing base of VFC-based PDIs – workhorse of our future HW platform



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Fast Digital Integrator (FDI) - characteristics



- overvoltage-protected, low-pass filtered analog front-end
- fast-switchable programmable gain levels from 0.1 to 100
- auto-calibration of gain & offset with $V_{\text{reference}}$ generator
- 18-bit, 500 kHz ADC
- DSP allows multiple upgradeable integration/filtering/compression algorithms
- FPGA glues logically components
- industry-standard compact PCI interface
- real-time LED display of gain and signal level



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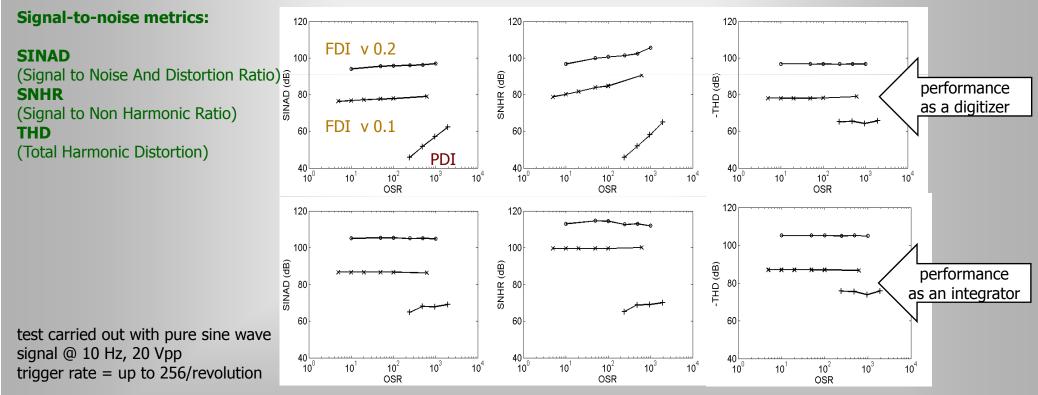




Fast Digital Integrator (FDI) - performance

Main advantages in switching from PDIs to FDIs:

- <u>Integrated board</u> (filter+ampli+ADC) → higher noise rejection, streamlined implementation, more cost-effective
- Bandwidth up to 250 kS/s (PDI: 1 kS/s)
- <u>Signal-to-noise</u> up to **110 dB** (PDI: 70 dB)
- Equivalent <u>resolution</u>: 0.5 nVs (PDI: 50 nVs)



OSR = oversampling ratio = ADC sampling rate/encoder trigger rate (typical value: 2000)



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Fast Digital Integrator (FDI) - outlook

- 12 prototype cards in use, 40 in production (NB long lead times for components)
- <u>firmware and drivers being updated</u> to exploit full HW capabilities (software programmable trigger generation, ADC mode, elimination of card-to-PCI bus bottleneck)
- Possible <u>future HW upgrades</u>: stand-alone version with USB interface, increased buffer memory, 18-bit DAC for flexible self-calibration and programmable function generation;



commercialization accord with METROLAB in progress \rightarrow lower volume/maintenance costs !



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FAME (FAst Measurement system) - overview

- Continuous, high-speed (8 Hz) harmonic measurement system for main LHC dipoles and quadrupoles
 → improvement of magnetic model for accelerator control (FIDEL)
- High-accuracy, high bandwidth integrated and local field quality during snapback transients
- Upgraded ceramic coil shaft with 6-turns coils, better mass balancing, robust connectors
- Compact Mobile Rotating Unit (MRU) simplifies installation and maintenance, might be adapted to other rotating coil systems (downside: longitudinal positioning requires Ti extension pieces)



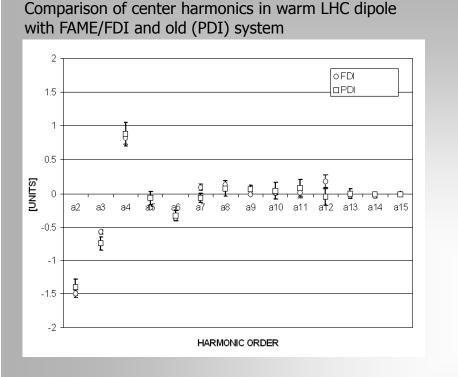


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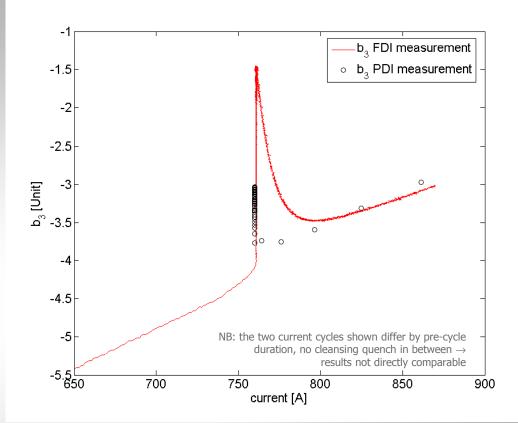


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FAME – first results and outlook



<u>Qualitative</u> comparison of center b3 snapback curves in LHC dipole with FAME/FDI and PDI system



- <u>Validation and characterization test</u> campaign being carried out with two prototype MRU + dipole shafts in SM18 (tests interrupted due to a cryogenic accident freezing the prototype shaft – now being repaired)
- Results coincide with older system within measurement uncertainty (< 0.1 unit)
- <u>Coming next</u>: spare dipole + quadrupole system; integration in new control/analysis software framework; new analysis algorithms to improve accuracy and bandwidth (harmonic reconstruction in rapidly changing field, progressive update during coil rotation)



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Timely input from our valued magnetic measurement clients !

Critical information:

- Ø cold bore: some R&D required + long lead times for coil shafts (and anticryostats)
- <u>twist pitch λ </u>: in long shafts, gap and coil length must be integer multiples of λ

Also important to know:

- Maximum <u>B and B</u>
- <u>Geometrical parameters</u>: good field region, magnet length, curvature radius for short dipoles, position of mechanical references/optical targets
- Desired <u>accuracy</u> for field strength, harmonics, direction and axis

... have you got a magnet to spare ?

high field/large aperture magnets to be kept stably as <u>references for calibration and cross-checks</u>, and as <u>test beds for materials and technologies</u>





