



Functional description

Detailed view of the system
Status and features

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Castor Readiness Review - June 2006



Outline



- Detailed view of the architecture
 - Lifecycle of a GET and a PUT request
- Description and status of the components
 - Main daemons
 - Diskserver related
 - Central services
 - Tape related
- Tape migration and recall
 - Workflow details



Outline

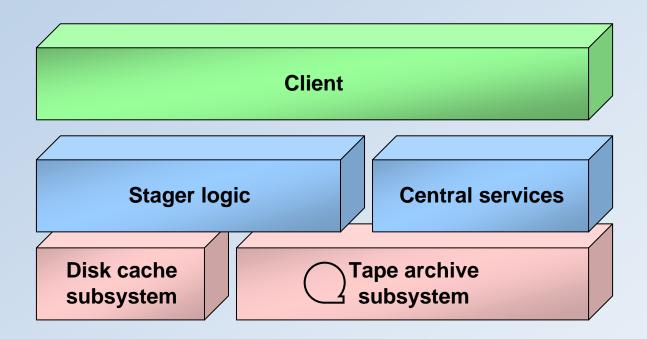


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Castor 2 Architecture



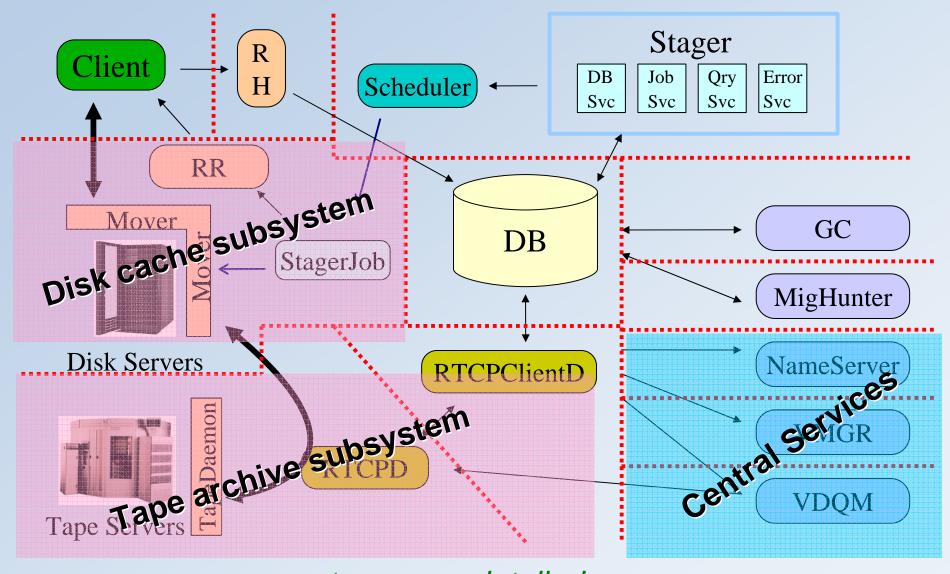


From the "simple" view ...



Castor 2 Architecture





... to a more detailed one



Lifecycle of a GET + recall



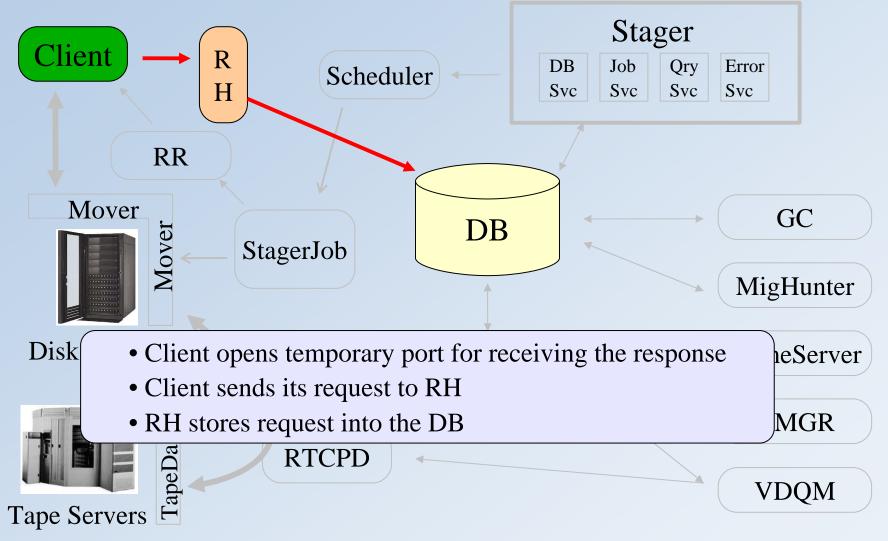
- Client connects to the RH
- 2. RH stores the request into the db
- 3. Stager polls the db and checks for file availability
- 4. If the file is not available, the recall process is activated
- 5. Once the file is available, stager asks the scheduler to schedule the access to the file
- 6. Client gets a callback and can initiate the transfer

The commandline is stager_get



stager_get (1)

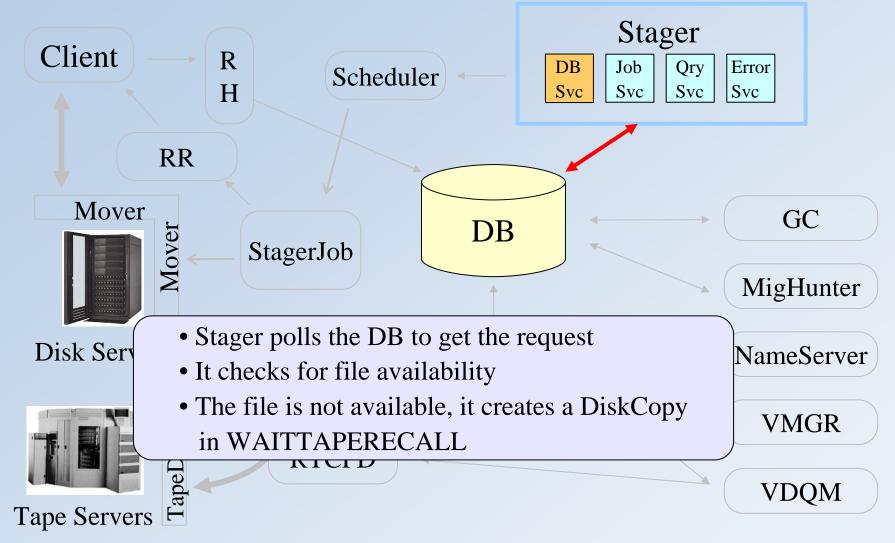






stager_get (2)





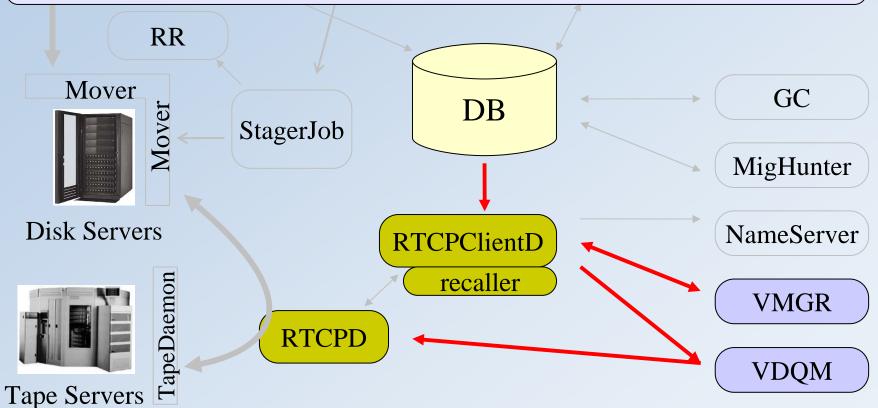


stager_get (3)



Stager

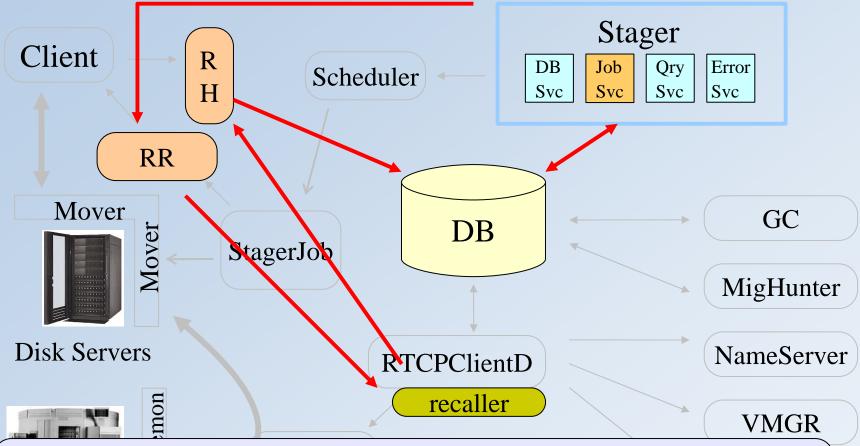
- rtcpClientd polls the DB to get diskCopies in WAITTAPERECALL
- It organizes the recall of the data but the target filesystem is not yet selected





stager_get (4)





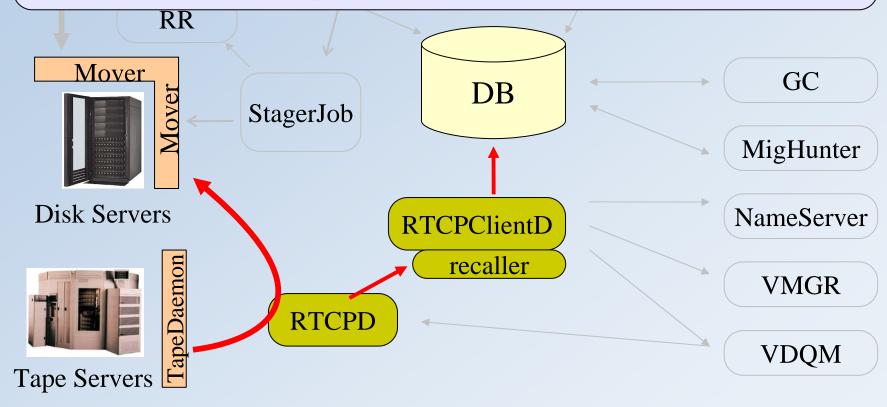
- recaller sends a request to the stager in order to know where to put the file
- the request goes through the usual way: Request Handler, DB, stager (job service), Request Replier



stager_get (5)



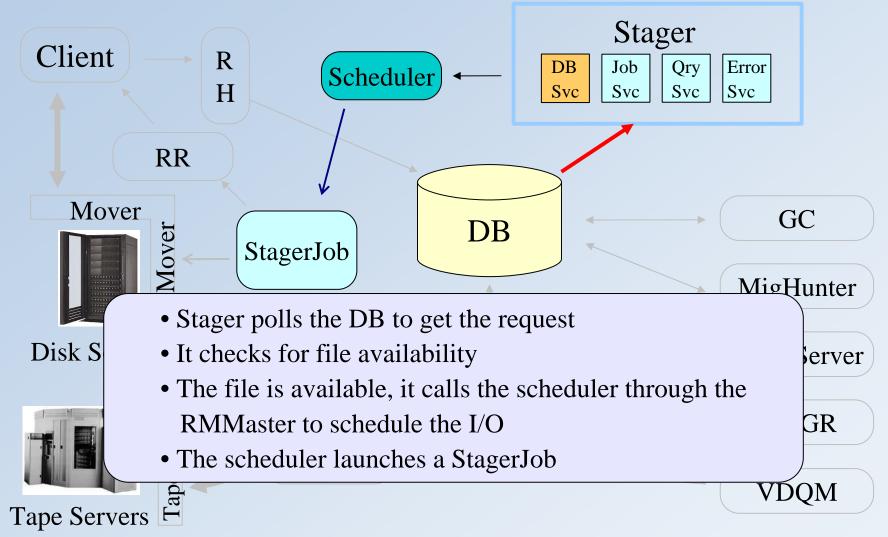
- rtcpd transfers the data from the tape to the selected filesystem
- the DB is updated with the new file size and position
- the original subrequest is set to RESTART status





stager_get (6)

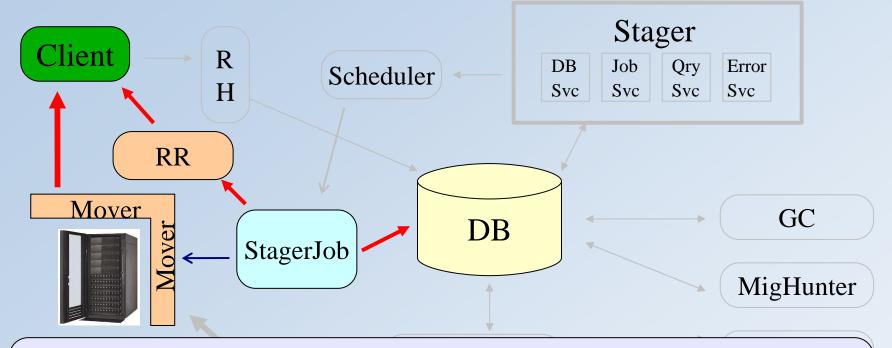






stager_get (7)





- the StagerJob launches the right mover corresponding to the client request (note that the scheduler takes available movers into account)
- it answers to the client, giving to it the machine and port where to contact the mover
- data is transfered
- DB is updated



Lifecycle of a PUT + migration



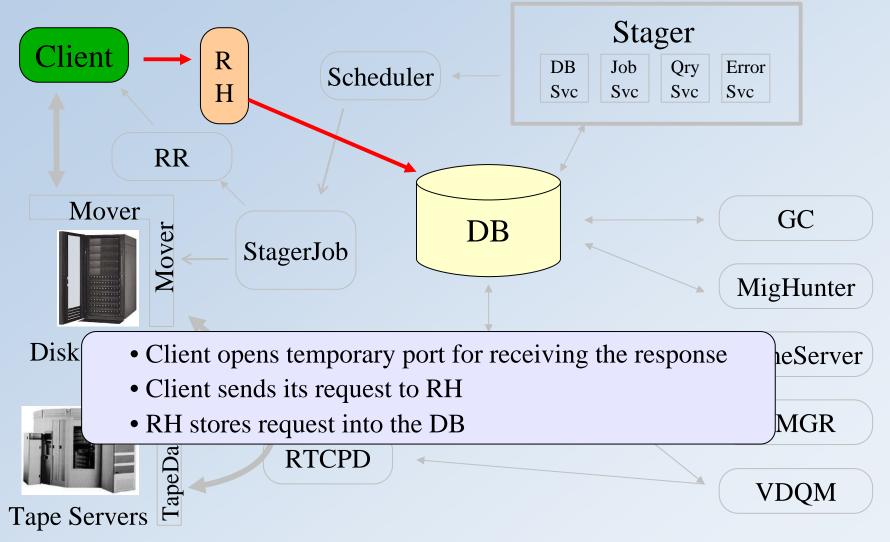
- 1. Client connects to the RH
- 2. RH stores the request into the db
- Stager polls the db and looks for a candidate filesystem for the transfer
- 4. Client gets a callback and can initiate the transfer
- After the transfer is completed, migration to tape is performed

The commandline is stager_put



stager_put (1)

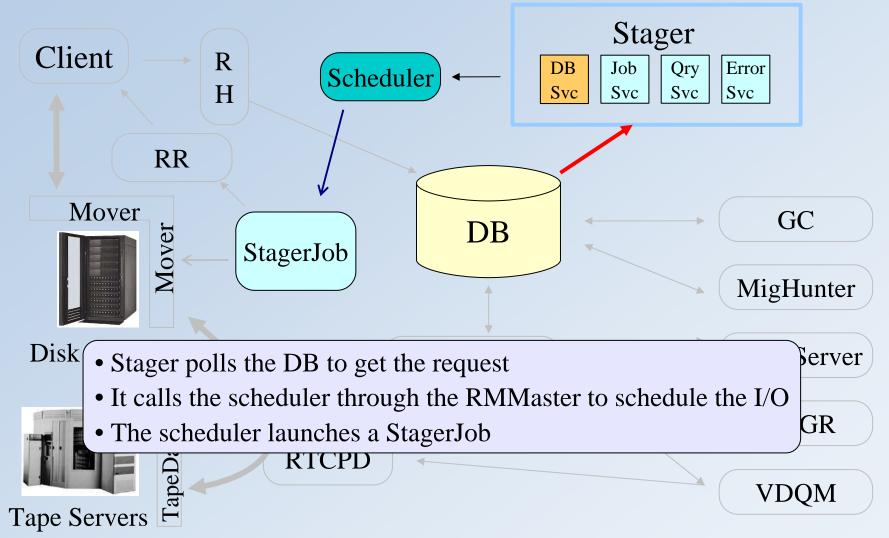






stager_put (2)

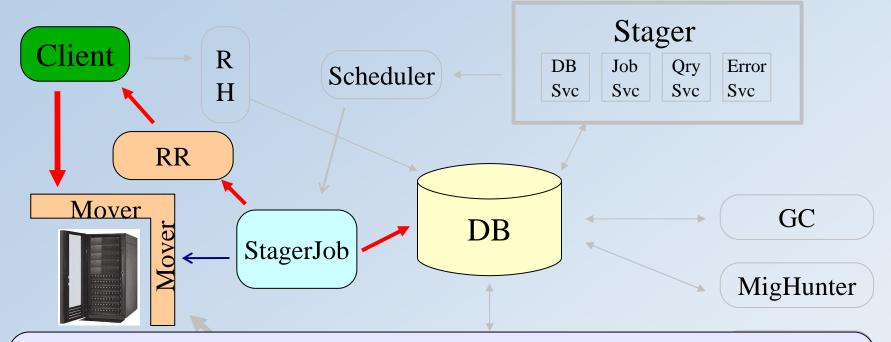






stager_put (3)



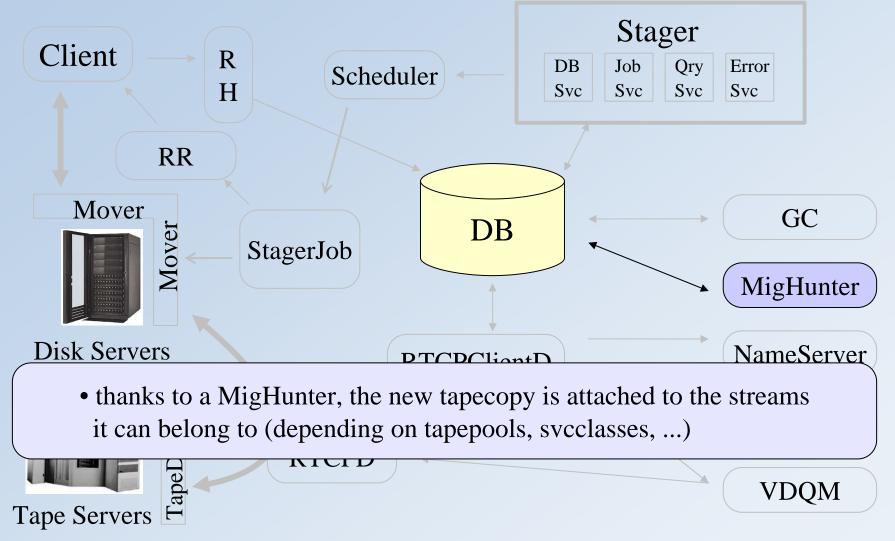


- the StagerJob launches the right mover corresponding to the client request (note that the scheduler takes available movers into account)
- it answers to the client, giving to it the machine and port where to contact the mover
- data is transferred
- DB is updated with the file size and the diskcopy is set in CANBEMIGR and one or many TapeCopies are created



stager_put (4)



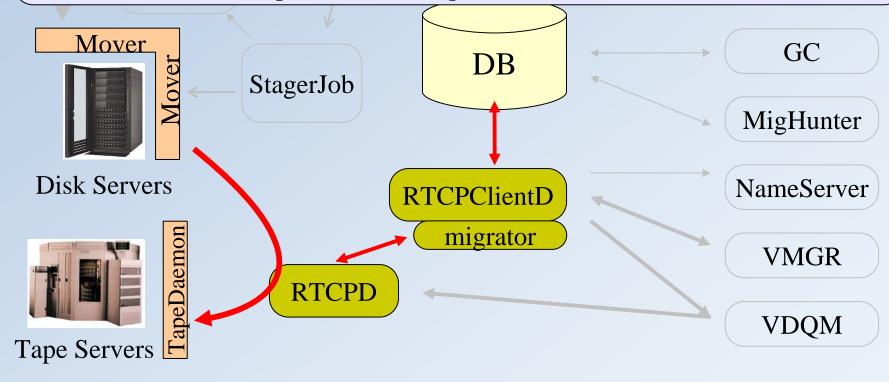




stager_put (5)



- rtcpclientd will launch a migrator
- this one asks the DB for the next migration candidate
- the DB takes the best candidate in the stream (based on filesystems availability)
- the file is written to tape and the DB updated





Outline

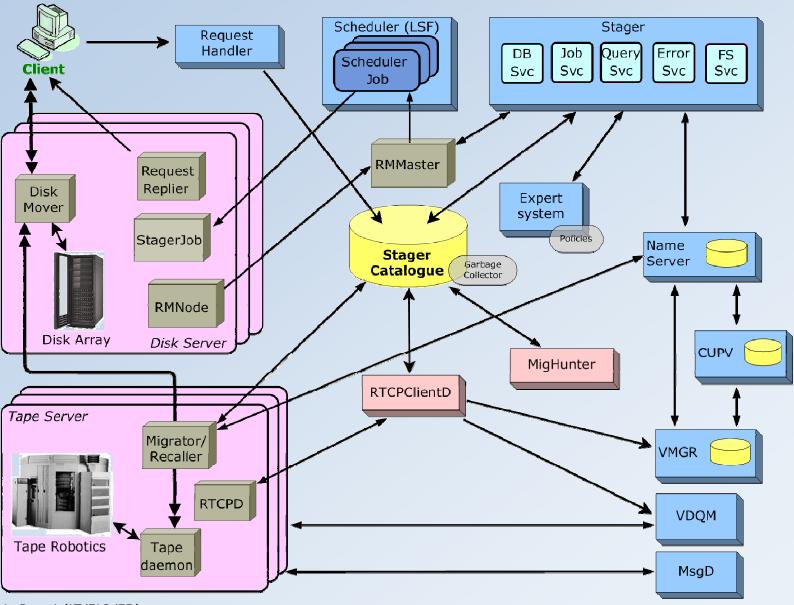


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Detailed picture of CASTOR







Status of all system components



- Request Handler
- Stager
- RMMaster & RMNode
- Distributed Logging Facility
- External plugins (LSF, expertd)
- gcDaemon
- Central services (NameServer, VDQM, VMGR, CUPV)
- Tape part (MigHunter, migrator/recaller, rtcopy, rtcpclientd)



Request Handler



Scope

Stores incoming requests into the DB

Features

- Very lightweight
- Allows for request throttling

- > Production, no changes since mid 2005
- Implementation
 - ➤ Fully C++
 - Usage of the internal DB API



Stager



Scope

Main daemon for requests processing

Features

- Stateless
- Multi-services implementation by thread pools
 - Allows for **independent** services execution, even on different nodes
 - Enhanced scalability

Maturity

- > Fairly stable, some bug fixes in the last months
- Development still going on to implement missing features
- Bugs and RFEs open on it (e.g. memory leak)

Implementation

- Main core in C, internal services in C or C++
- Usage of the internal DB API



RMMaster & RMNode



Scope

- Gather monitoring information from nodes
- Submit jobs to the scheduler

Features

- Not fully stateless
- RMMaster gathers data from RMNode
- RMNode runs on the diskservers and polls /proc data

Maturity

- > Fairly stable, not many bugfixes in the last months
- > But quite a number of major issues are open on it

Implementation

- > Fully C
- No usage of DB, internal protocol to communicate with stager



Distributed Logging Facility



Scope

Central DB-based logging system

Features

- A daemon accepts and stores any log entry from any Castor subsystem
- A PHP-based GUI allows for querying the log

Maturity

Fairly stable, development still going on to improve performances

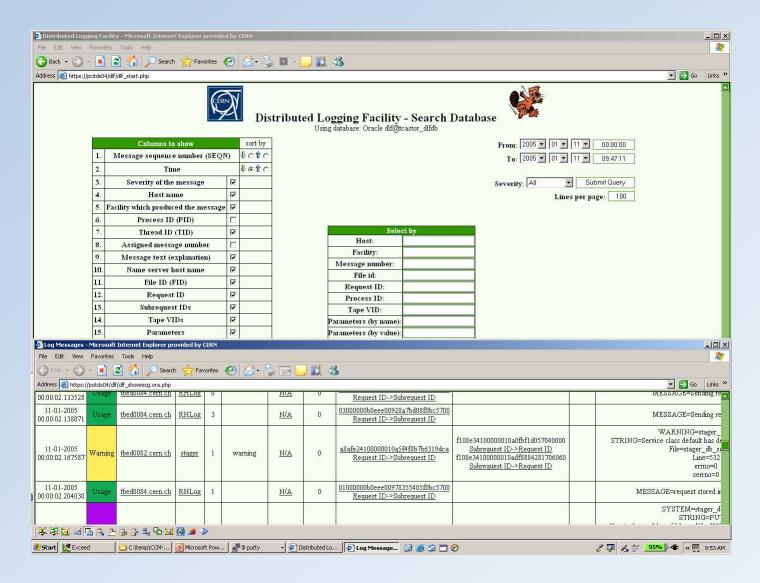
Implementation

Fully C, "legacy" DB API



DLF GUI







LSF plugin



Scope

Select best candidate resource (file system) among the set proposed by LSF

Features

Not entirely stateless due to lack of information flow in LSF API

Maturity

- > Stable, few changes in the last months
- Lack of optimization due to lack of functionality in the LSF API
 - Need for further development in conjunction with LSF people

Implementation

- > C
- Usage of the internal DB API



gcDaemon



Scope

Deletes files marked for garbage collection

Features

> Stateless daemon implemented as a stager client

Maturity

> Production, no changes since Dec 2004

Implementation

- > C++
- Usage of the client API and the internal API
 - proxy "remotized" implementation of the stager



NameServer



Scope

- Archive the filesystem-like information for the HSM files
- Associate tape related information

Features

> Stateless daemon, DB backend

Maturity

Production, last change has been a merge with DPM's NameServer in Jan 2006, otherwise no changes since 2004

Implementation

> Fully C



Expert daemon (expertd)



Scope

Externalize decisions based on policies

Features

- Framework for executing policy scripts
- Receives policy requests from other components (stager, MigHunter, TapeErrorHandler)
- Supported policy requests types are:
 - Filesystem weight
 - Replication
 - Migrator
 - Recaller



Filesystem policy



Scope

Provide an evaluation of each resource (filesystem) from gathered monitoring information

Features

- Single formula implementation
- Currently only global, to be converted soon to policy per service class

Maturity

Under development, the current implementation works in production but has demonstrated not to be stable enough under very heavy load (Tier0 Data Challenge)

Implementation

Rule in CLIPS logic engine, going to be converted to Perl



Volume and Drive Queue Mgr (VDQM)



Scope

Manage the tape queue and device status

Features

- Supports drive dedication (regexp)
- Supports request prioritization
- Allows for re-use of mounted tapes (useful for CASTOR1)

Maturity

- In production since 2000
- Scheduling algorithm melts down beyond ~4000 queued requests
- New implementation (VDQM 2) ready to be rolled out

Implementation

- > C
- C++ and DB API for the new VDQM 2



Volume Manager (VMGR)



Scope

Logical Volume Repository. Inventory of all tapes and their status

Features

- > Tape pools
 - Grouping of tapes for given activities
 - Counters for total and free space (calculated using compression rates)

- ➤ In production since 2000
- Implementation
 - > C
 - Oracle Pro-C



Castor User Privileges (Cupv)



Scope

Manages administrative authorization rights on other CASTOR modules (nameserver, VMGR)

Features

- Flat repository of privileges
- Supports regular expressions

- ➤ In production since 2000
- Implementation
 - > C
 - ➤ Oracle Pro-C



Tape mover (rtcpd)



Scope

Copy files between tape and disk

Features

- Highly multithreaded
 - Overlaid network and tape I/O
 - Large memory buffers allows for copying multiple files in parallel
- Supports a large number of legacy tape formats...

- ➤ In production since 2000
- Implementation
 - > C



MigHunter



Scope

Attach migration candidates to streams

Features

- Stateless
- Callout to expert system for executing migrator policies for finegrained control
- Can trigger on frequency or volume of data to be migrated

Maturity

- In production since 2006
- Some known problems with files that have been deleted from the name server but not cleared in the catalogue

Implementation

- > C
- Usage of internal DB API



Migrator/recaller



Scope

Controls the tape migration/recall

Features

Stateless, multithreaded

Maturity

- In production since 2006
- Some known problems with files that have been deleted from the name server but not cleared in the catalogue
- Known aging problem resulting in inconsistency in one auxiliary oracle table that is updated through triggers
 - Workaround for oracle problem
 - Operational procedure exists for repairing the streams

Implementation

- \triangleright C
- Usage of internal DB API



rtcpclientd



Scope

Master daemon controlling tape migration/recall

Features

- Not fully stateless due to VDQM
- Single threaded

Maturity

- ➤ In production since 2006
- Implementation
 - > C
 - Usage of internal DB API



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Tape Migration and Recall

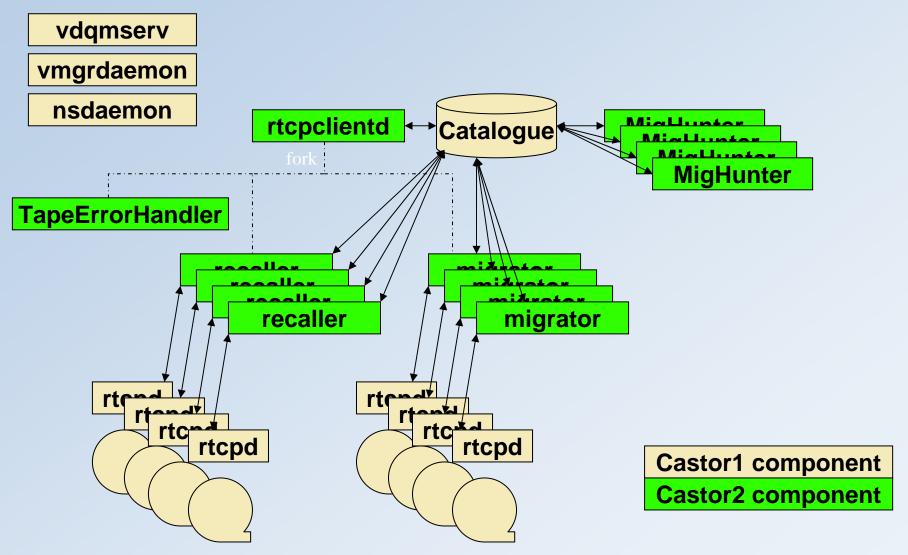


- "rtcpclientd" is the main component dealing with all interaction to the CASTOR tape archive
 - > For each running tape recall it forks a 'recaller' child process per tape
 - For each running tape migration it forks a 'migrator' child process per tape
- Migration streams are created and populated by the "MigHunter" component
- A TapeErrorHandler process is forked by the rtcpclientd daemon whenever a recaller or migrator child process exits with error status.
- Detailed description of the functioning and operation of tape migration and recall in CASTOR2 can be found at:
 - http://cern.ch/castor/docs/guides/admin/tapeMigrationAndRecall.pdf



Tape migration/recall components







Tape recall (1)



- Tape recalls are triggered when the stager receives a request for a CASTOR file for which there is no available disk resident copy
 - Stager calls the castor name server to retrieve the tape segment information (VID, fseq, blockid)
 - Stager inserts the corresponding rows in the Tape and Segment tables in the catalogue
- rtcpclientd regularly (every 30s) checks the catalogue for tapes to be recalled
 - > Submits the tape request to VDQM (tape queue)
 - When mover (rtcpd) starts it connects back to the rtcpclientd, which then forks a recaller process for servicing the tape recall



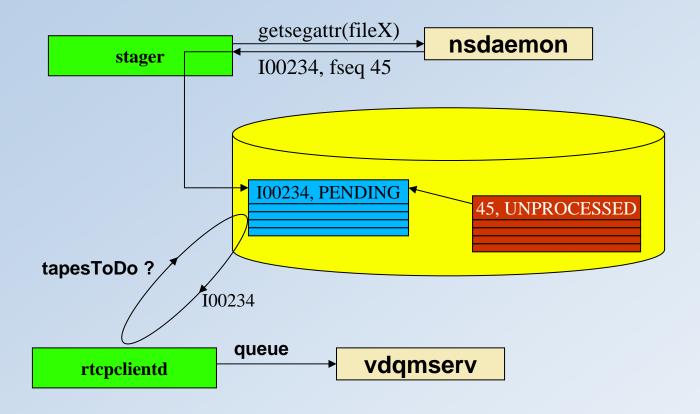
Tape recall (2)



- The recaller attempts to optimize the use of tape and disk resources
 - Tape files are sorted
 - Current in fseq order. Ongoing work to find more optimal sorting taking into account the serpentine track layout on media
 - Requests for new files on same tape are dynamically added to running request
 - Target file system is decided given the current load picture when the tape file is positioned

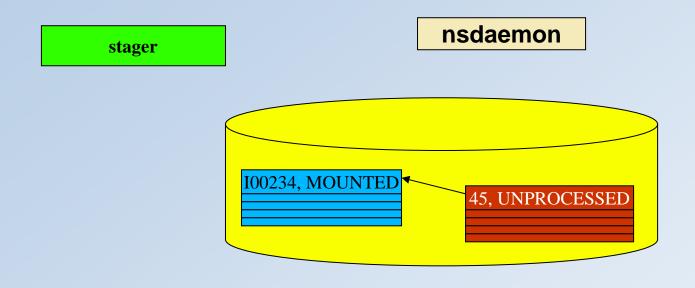


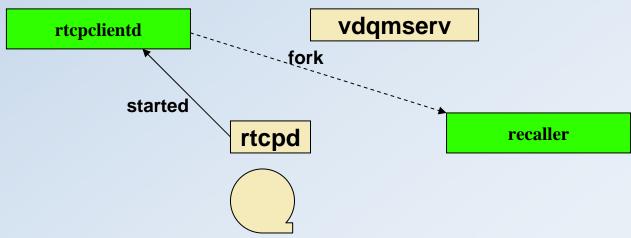






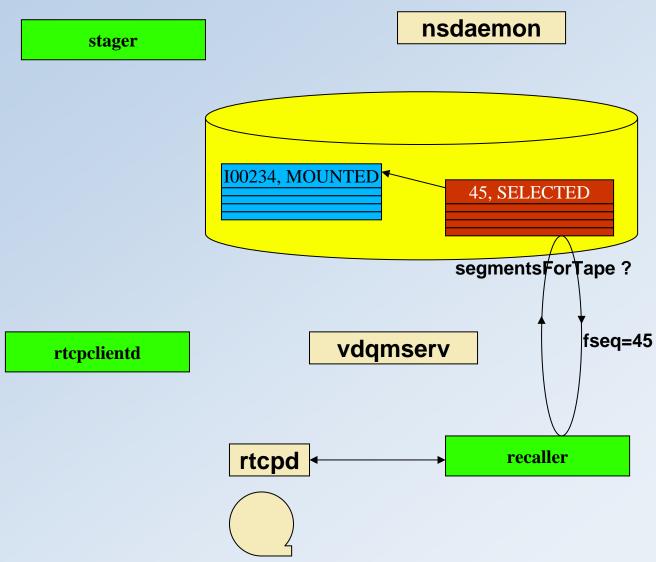






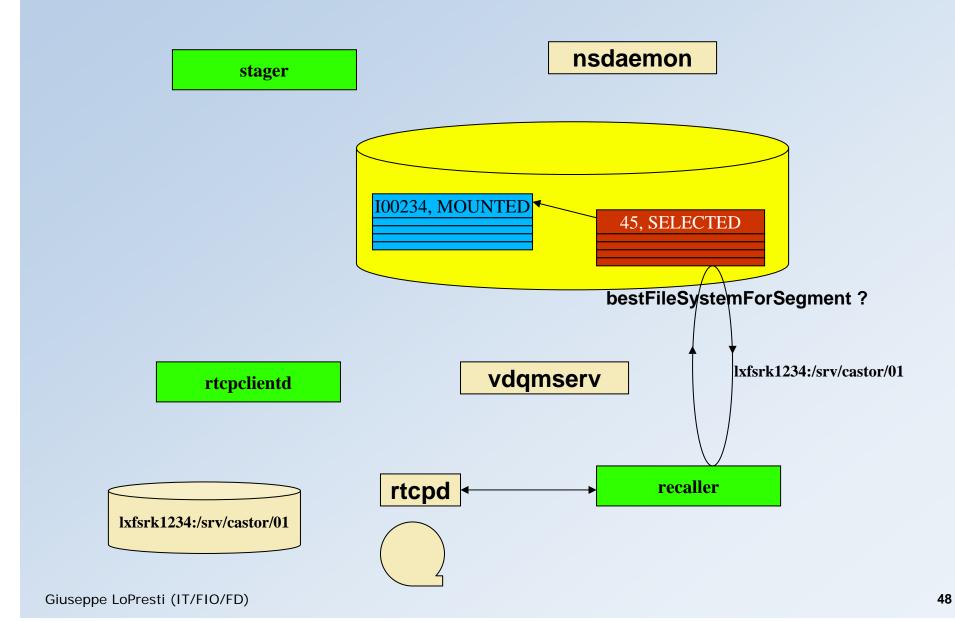














Tape migration



- Similar to tape recall but
 - Triggered by policy rather than waiting requests
- Migration candidates are attached to 'streams'
 - > A migration 'Stream' is a container of migration candidates
 - Each Stream is associated with 0 or 1 tapes:
 - 0 tape: stream not active (e.g. not yet picked up by rtcpclientd, or VMGR tape pool is full)
 - 1 tape: stream is running (tape write request is running) or waiting for tape mount
 - A Stream can survive many tapes (but only one at a time)
 - A TapeCopy can be linked to many Streams
 - When a TapeCopy is selected by one of the Streams, its status is atomically updated preventing it from being selected by another Stream
- The MigHunter process is responsible for attaching the migration candidates to the streams
 - Migrator policies can be used for fine-grained control over this process



Example policy





Comments, questions?

