

Numerical Model and Scaling Law of PIC Noise

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- 1 2.5D Space Charge Model
- 2 Noise in 2D PIC Calculations
- 3 Tracking of Noisy Beams

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Tracking with Space Charge Kicks

Basic idea of maps:

$$\begin{pmatrix} x_i \\ x'_i \\ y_i \\ y'_i \end{pmatrix} \rightarrow \begin{pmatrix} x_f \\ x'_f \\ y_f \\ y'_f \end{pmatrix} = \mathcal{M}(s_i, s_f) \begin{pmatrix} x_i \\ x'_i \\ y_i \\ y'_i \end{pmatrix}$$

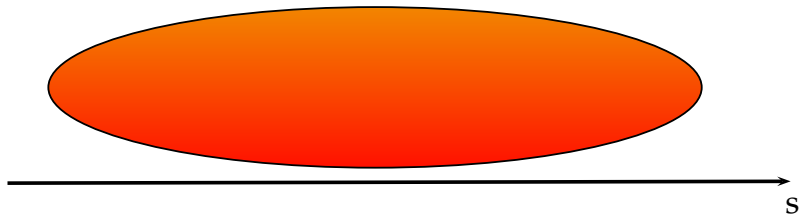
Space charge can be modeled by non-linear kicks:

$$\begin{pmatrix} x_i \\ x'_i \\ y_i \\ y'_i \end{pmatrix} \rightarrow \begin{pmatrix} x_f \\ x'_f \\ y_f \\ y'_f \end{pmatrix} = \begin{pmatrix} x_i \\ x'_i + \Delta s \frac{qE_{SC,x}(x,y,z)}{v_0 p_0} \\ y_i \\ y'_i + \Delta s \frac{qE_{SC,y}(x,y,z)}{v_0 p_0} \end{pmatrix}$$

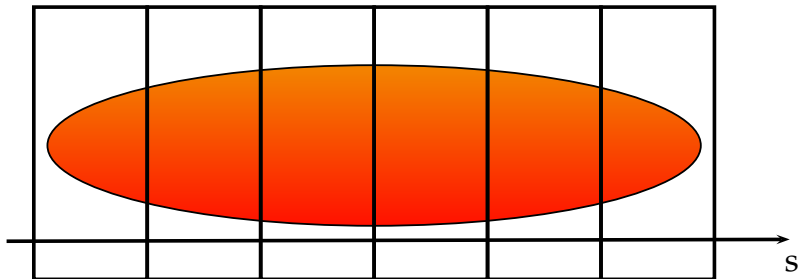
$\Rightarrow E_x(x, y, z)$ and $E_y(x, y, z)$ have to be calculated for every particle.

for example 10^{13} protons at the SIS100/FAIR

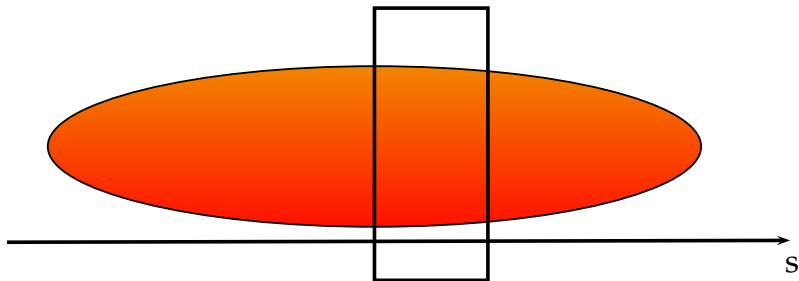
2.5D Space Charge Model



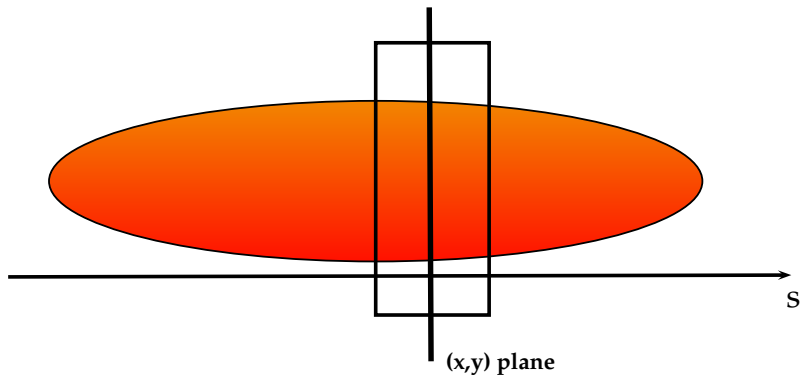
2.5D Space Charge Model



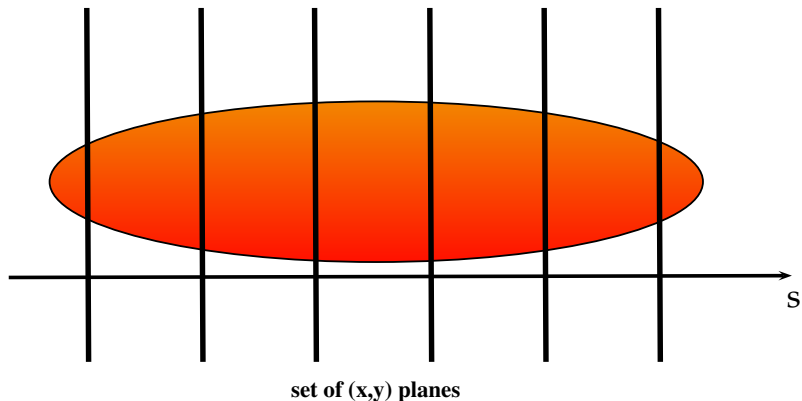
2.5D Space Charge Model



2.5D Space Charge Model



2.5D Space Charge Model



⇒ Solution on planes of $E_x(x, y)$ and $E_y(x, y)$ via 2D Poisson solver.

⇒ Interpolation inbetween planes to get $E_x(x, y, z)$ and $E_y(x, y, z)$.

2D Poisson Solver

Our 2-dimensional Problem:

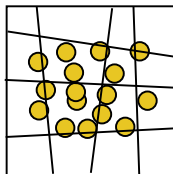
$$\nabla^2 \Phi = -\frac{\rho}{\epsilon_0}$$

Find proper approximations:

⇒ use M macro-particles



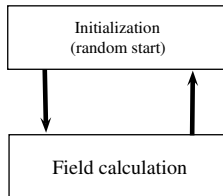
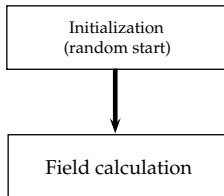
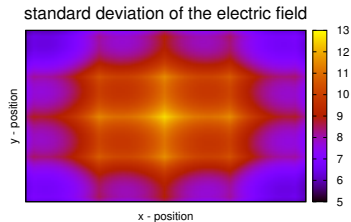
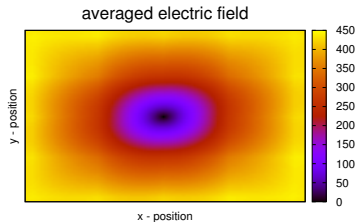
⇒ and N grid points



Choose a fixed number of grid points N and macro-particles M .

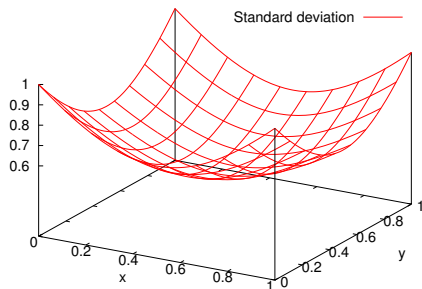
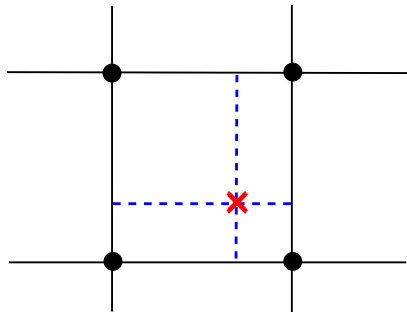
⇒ Can we reasonably decrease the error?

Sample output for a Gaussian beam profile



2D Poisson Solver - Bilinear Interpolation

What happens in-between those grid points?



$$f(x, y) = 1/4 \{ (1-x)(1-y)g_{00} + x(1-y)g_{10} + (1-x)y g_{01} + xy g_{11} \}$$

⇒ Error calculation

⇒ Periodic extension for the whole grid

Space charge field for a Gaussian beam profile:

$$E(r) = \frac{E_0}{r} \left(1 - e^{-\frac{r^2}{2\sigma_r^2}} \right) \quad (1)$$

with a standard deviation of:

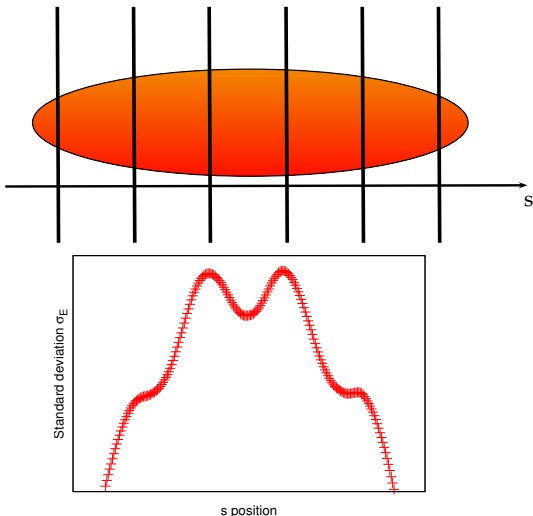
$$\delta E_{SC}(r) = \sigma_0 \xi(x, y) \sqrt{\frac{\sqrt{N_G}}{N_M}} e^{-\frac{r^2}{4\sigma_r^2}} \quad (2)$$

N_G ... Number of grid points

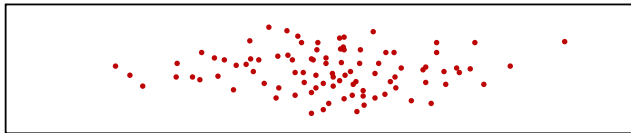
N_M ... Number of macro - particles

$\xi(x, y)$... Fourier extension of the grid

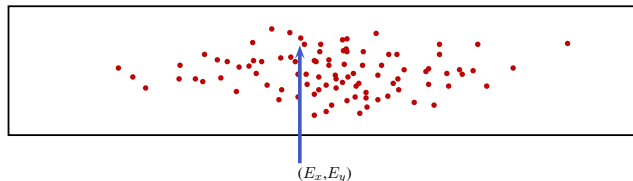
2D Poisson Solver - Longitudinal interpolation



Tracking of noisy beams



Tracking of noisy beams



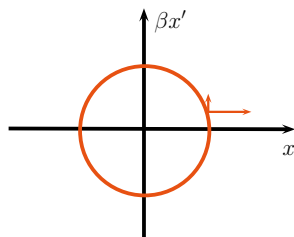
Spectral analysis of the electric field (E_x, E_y)

Flat spectrum \Rightarrow Random walk modelling possible!

Peaks in spectrum \Rightarrow Extended random walk modelling?

Random Walk Modelling

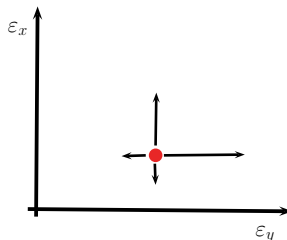
Phase Space Description



$$x \rightarrow x \pm dx$$

$$x' \rightarrow x' \pm dx'$$

Emittance Description



$$\varepsilon_x \rightarrow (1 + \Delta) \varepsilon_x$$

- Gives (in the regular case) an understanding of
- \Rightarrow the effect of noise on a single particle
 - \Rightarrow the effect of macroparticles and grid points
 - \Rightarrow the effect of the optics of a machine

Summary

⇒ Mathematical modeling of PIC noise in 2D

$$\delta E_{SC}(r) = \sigma_0 \xi(x, y) \sqrt{\frac{\sqrt{N_G}}{N_M}} e^{\frac{-r^2}{4\sigma_r}}$$

⇒ Extension for 2.5D bunched beams

⇒ Random walk modelling for regular cases

Outlook:

⇒ Studing the irregular cases in more detail

⇒ Benchmarking of codes



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Six-dimensional approach to the beam dynamics in HIDIF scenario'
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Eur. Phys. J. C 30, 279-290, 2003



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