







Measurement of the luminosity at LHC

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On behalf of the ALICE, ATLAS, CMS and LHCb collaborations

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Luminosity

Fundamental relationships

Integrated luminosity

$$N = L_{int} \sigma$$
Number of events Process cross section

$$L_{int} = \int \mathcal{L} dt$$
Instantaneous luminosity

Luminosity from beam parameters

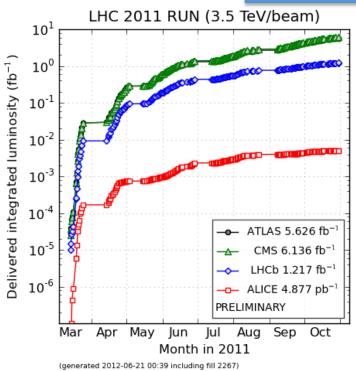
Bunch current product
$$\mathcal{L} \propto f_r n_b n_1 n_2 \int \int \int \rho_1(x,y,z,t) \rho_2(x,y,z,t) \, dx dy dz dt$$

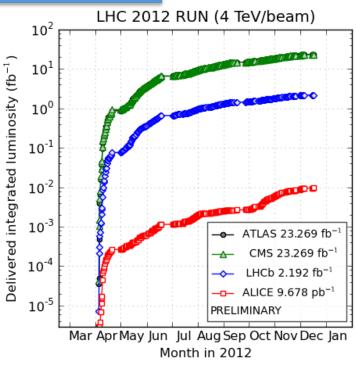
Number of bunches and revolution frequency

Spatial beam densities

LHC Run I – pp integrated luminosity

Only pp-luminosity shown here





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- So far LHC delivered
 - about 30 fb⁻¹ to ATLAS and CMS
 - about 3 fb⁻¹ to LHCb (low μ)
 - about 15 pb⁻¹ to ALICE (at very low μ)

 μ is approx. number of interactions per bunch crossing

Luminosity measurements

- 1. Direct bunch profile and intensity measurements
 - Van der Meer scan (VdM) ALICE, ATLAS, CMS, LHCb
 - Beam-Gas-Imaging (BGI) [LHCb]
- 2. Based on optical theorem ATLAS with ALFA, CMS with TOTEM
 - Forward scattering at very low angles
 - Cross-calibration of luminosity detectors
 - Challenging, program ongoing

Luminosity calibration basics

Mean number of inelastic interactions per BX

$$\mathcal{L} = \frac{R_{inel}}{\sigma_{inel}} = \frac{\mu n_b f_r}{\sigma_{inel}}$$

Inelastic cross section (not known precisely enough)

ε*μ = Mean number of interactions per

BX seen by detector

$$\sigma_{vis} n_b f_r$$

Cross section seen by detector

If beam densities factorize in x and y, i.e. $ho(x,y)=
ho_x(x)
ho_y(y)$,then

$$\mathcal{L} = f_r n_b \, n_1 n_2 \, \Omega_x(\rho_{x1},\rho_{x2}) \Omega_y(\rho_{y1},\rho_{y2}) \quad \text{\tiny (No crossing angle)}$$

where $\Omega_x = \int \rho_{x1}(x) \rho_{x2}(x) dx$ is the **beam overlap integral** in x.

- Measuring the beam overlap integral yields the absolute luminosity and thus σ_{vis}
- Beam overlap integral can be measured in VdM scans or with BGI (in case of BGI: crossing angle correction)

VdM scan basics

 The key idea of the VdM scan is to relate the overlap integral to the rate integral [12]:

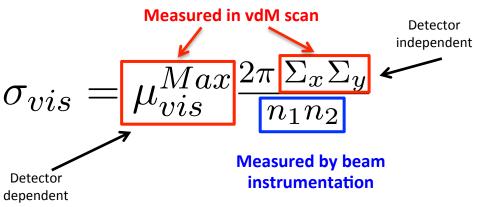
$$\Omega_x = rac{R_{ate} ext{ measured}}{\int R_x(\delta) d\delta}$$
 Beam separation

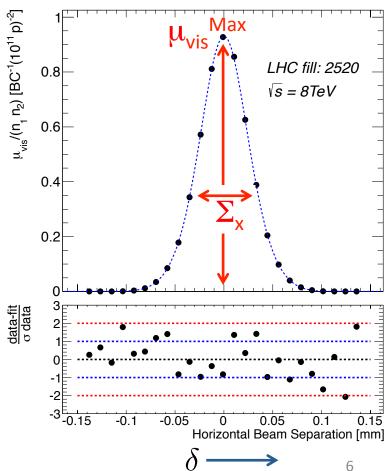
• Defining the convolved beam size Σ_x as

$$\Sigma_x = \frac{1}{\sqrt{2\pi}} \, \frac{1}{\Omega_x}$$

the luminosity becomes

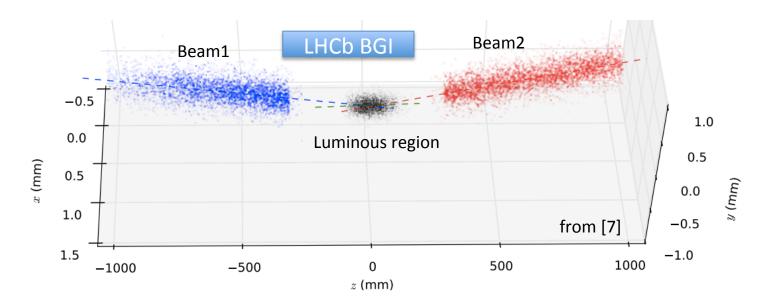
$$\mathcal{L} = \frac{n_b f_r n_1 n_2}{2\pi \sum_x \sum_y}$$





BGI basics

- Beam-Gas imaging (pioneered by LHCb) [1]
 - Reconstruct interaction vertices of protons with residual gas
 - Infer beam shape near interaction point (IP) and extrapolate to IP
- Combination of Beam-Gas and Beam-Beam vertices
 - Simultaneous fit to individual beam and luminous region shapes yields beam overlap integral and then luminosity
 - Beams do not need to be moved (hence no beam-beam corrections, etc.)
 - Overall calibration uncertainty dominated by vertex resolution
 - Several important systematic uncertainties are independent from VdM scan analysis



ALICE luminosity detectors [2]

V0 detector

- 32 scintillator tiles on each side of IP
 - Coincidence counters
- $-2.8 < \eta < 5.1$ and $-3.7 < \eta < -1.7$,

T0 detector

- 12 Cherenkov counters on each side of the IP
 - Coincidence counters
- $-4.6 < \eta < 4.9$ and $-3.3 < \eta < -3.0$

ZDC detector

- two calorimeters on opposite sides of the IP
- detect forward neutrons in p-Pb and Pb-Pb collisions
- $| \eta | > 8.8$

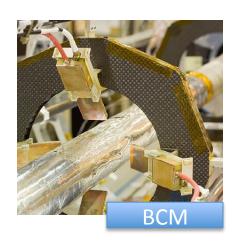


ATLAS luminosity detectors [3]

LUCID

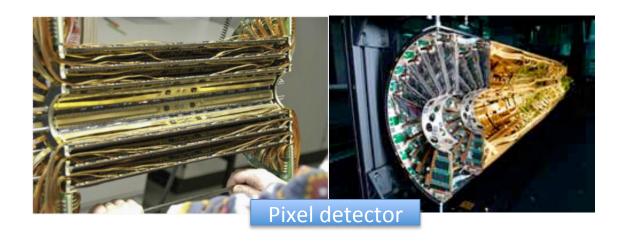
- Dedicated luminosity monitor (5.6 < $|\eta|$ < 6.0)
- Cherenkov tubes
- Zero-counting and hit-counting algorithms
- Beam Condition Monitor (BCM)
 - Designed as beam protection system
 - Diamond-based sensor ($|\eta| \sim 4.2$)
 - Zero-counting algorithms
- Silicon detectors
 - Track counting in Pixel and SCT
- Calorimeter currents (bunch-integrating)
 - TileCal PMT currents
 - LAr HV currents: ECC, FCal





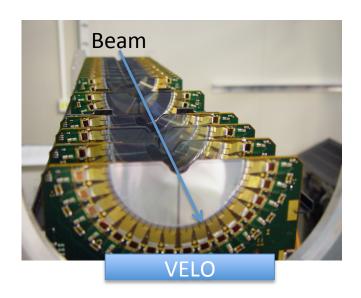
CMS luminosity detectors [4]

- Forward iron-quartz calorimeter (hit counting) for online measurements
- Silicon Pixel detector used offline
 - providing the most stable luminosity measurement
 - Luminosity through Pixel Clusters Counting (PCC)
 - Linear response till very high pileup



LHCb luminosity detectors [5]

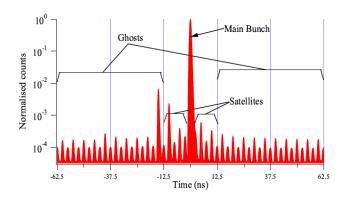
- Vertex/track monitoring with vertex locator (VELO)
 - VELO built around the IP and contained within vacuum
 - VELO approaches the beam if safe conditions
 - high precision in order to separate primary and secondary vertices
 - covers 1.6 < η < 4.9 and -3.3 < η < -1.6



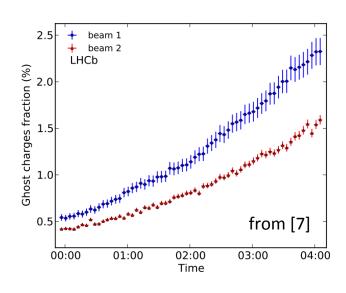
+ neon gas injection system for BGI (SMOG)

Bunch current measurements

- Currents are crucial input to VdM scan analysis
 - DC Beam Current Transformer (DCCT)
 - total circulating charges
 - Fast Beam Current Transformer (FBCT)
 - fraction of charge in each bunch
 - In 2010 uncertainty on bunch current product (10%) dominated luminosity uncertainty, due to major effort this uncertainty is well below 0.5% today [13]



- Corrections for ghost and satellite bunches
 - Fill dependent, but typically < 1%
 - Measured with various methods
 - Synchrotron radiation by LDM (for satellite bunches) [6]
 - BGI in LHCb VELO with SMOG (for ghost charge) [7]



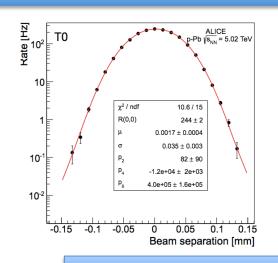
Luminosity uncertainties

 Only a selection of the most important systematic uncertainties is listed in the following

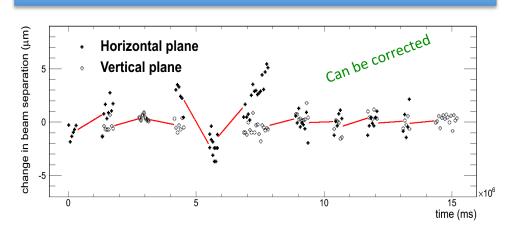
Calibration uncertainties	VdM scan	BGI		
	Scan curve model	Bunch shape model		
	Factorizability	(accounts for factorizability)		
	Beam-Beam effects	Vertexing resolution		
	Orbit drifts	Detector alignment & crossing angle		
	Reproducibility			
Calibration transfer uncertainties from low $\mathcal L$ calibration to high $\mathcal L$ physics	μ-dependence			
	Radiation effects			
Monitoring uncertainty	Long-term stability			

Uncertainties: calibration

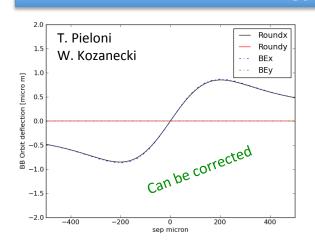
Choice of scan curve model



Orbit drifts



Beam-beam effects



Beam-beam deflection

 Orbit shift dependent on beam separation

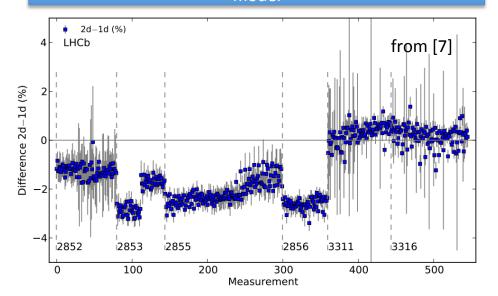
Dynamic β

 Beam sizes vary during VdM scan since beams exert focussing/ defocussing force on each other

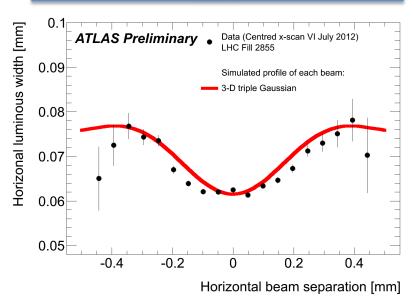
Uncertainties: non-factorizability

- Non-factorizability of beam densities could be tracked down as the source for significant inconsistencies in some VdM scans
 - Its effect on VdM scans is new territory and was first studied at LHC
- Two approaches to deal with the factorizability problem
 - Accelerator experts prepare good beams which have approx. factorizable densities
 - Experiments measure the non-factorizability and develop new methods to correct for it (based on BGI, luminous-region evolution during scan)

Difference between factorizable and non-factorizable model



Monitoring the luminous region during VdM scans



L_{int} : correlations between experiments

- Assessment difficult since uncertainty accounting and grouping varies among experiments
- Each uncertainty must be treated individually and often there are arguments for both view points (correlated vs uncorrelated)
- Preliminary (and not final!) statement
 - Calibrations done in different fills, mostly uncorrelated
 - If VdM calibrations done in the same fill, to some extend correlated

Snapshot of luminosity uncertainties

Parts of table reproduced from [11]

	ALICE	ATLAS	CMS	LHCb	
Running period	2013	2011	2012	2012	
Sqrt(s) [TeV]	5.02	7	8	8	size
Running mode	Pb-p	р-р	р-р	р-р	ual in
Reference	[8]	[9]	[10]	In the process of being made publicly available	almost equal in
Absolute calibration method	VdM	VdM	VdM	VdM + BGI *	spou
$\Delta \sigma_{\text{vis}} / \sigma_{\text{vis}}$ [%]	2.8	1.53	2.3	1.12	meth
μ-dependence [%]	1.0	0.50	<0.1	0.17	both
Long-term stability [%]		0.70	1.0	0.22	es of
Subtraction of luminosity backgrounds [%]		0.20	0.5	0.13	*uncertainties of both methods
Other luminosity-dependent effects [%]		0.25	0.5	-	*un
Total luminosity uncertainty [%]	3.0	1.8	2.6	1.2	

This snapshot represents a selection of the latest luminosity calibration results publicly available

Summary

- VdM scans are the one & only luminosity-calibration method (so far) for ALICE, ATLAS, CMS (and until recently for LHCb as well)
- BGI pioneered by LHCb is a new contender in the game and looks very promising
 - Several important systematic uncertainties are independent from the ones of a VdM scan
- Beam-Beam effects and orbit drifts are non-negligible and need to be taken into account
- Bunch density factorization crucial for luminosity calibration
 - New methods to monitor non-factorization and to correct for it
- Redundancy is key for monitoring long-term stability of detectors
- Integrated luminosity uncertainty for all experiments about 1-4 %
 - Depending on beam conditions, rate environment, instrumental capabilities, ..
 - Do not expect much improvements on these numbers ..

Future Challenges

- More difficult pile-up and radiation conditions at LHC will impose new challenges to detector hardware and data acquisition
 - Long-term stability of luminosity detectors will need to be closely monitored
- Preparation of good and factorizable beams for VdM scans by accelerator colleagues
- Successful VdM calibrations will rely on very close collaboration between LHC experiments, beam instrumentation experts and accelerator physicists

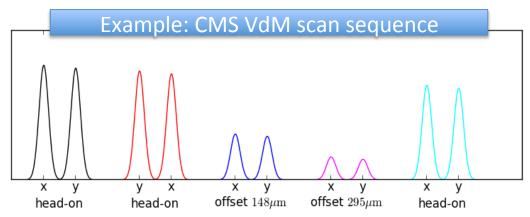
References

- [1] M. Ferro-Luzzi, Proposal for an absolute luminosity determination in colliding beam experiments using vertex detection of beam-gas interactions, Nucl. Instr. Meth. A 553 (2005) 388–399
- [2] The ALICE Collaboration, "The ALICE experiment at the CERN LHC," Journal of Instrumentation, vol. 3, no. 08, p. \$08002, 2008.
- [3] The ATLAS Collaboration, "The ATLAS Experiment at the CERN Large Hadron Collider," Journal of Instrumentation, vol. 3, no. 08, p. \$08003, 2008.
- [4] The CMS Collaboration, "The CMS experiment at the CERN LHC," Journal of Instrumentation, vol. 3, no. 08, p. \$08004, 2008.
- [5] The LHCb Collaboration, "The LHCb Detector at the LHC," Journal of Instrumentation, vol. 3, no. 08, p. \$08005, 2008.
- [6] A. Boccardi, et al., LHC Luminosity calibration using the Longitudinal Density Monitor, CERN-ATS-Note-2013-034 TECH, https://cds.cern.ch/record/1556087
- [7] C. Barschel, Precision Luminosity Measurement at LHCb with Beam-gas Imaging, CERN-THESIS-2013-301.
- [8] The ALICE Collaboration, Measurement of visible cross sections in proton-lead collisions at sqrt(s) = 5.02 TeV in van der Meer scans with the ALICE detector, arXiv:1405.1849, version 1
- [9] ATLAS Collaboration, Improved Luminosity Determination in pp Collisions at sqrt(s)=7 TeV Using the ATLAS Detector at the LHC, Eur. Phys. J. C73 (2013) 2518.
- [10] CMS Collaboration, CMS Luminosity Based on Pixel Cluster Counting Summer 2013 Update, CMS-PAS-LUM-13-001, 2013.
- [11] P. Grafstrom and W. Kozanecki, Luminosity Determination at Proton Colliders, submitted to Progress in Particle & Nuclear Physics
- [12] S. Van der Meer, "Calibration of the Effective Beam Height in the ISR," Tech. Rep. CERN-ISR-PO-68-31, CERN, Geneva, 1968.
- [13] Notes of the Bunch Current Normalization Working Group (BCNWG notes), http://lpc.web.cern.ch/lpc/bcnwg.htm

Backup

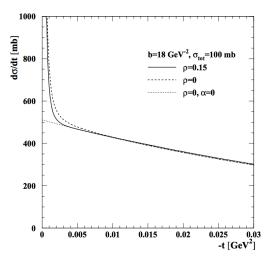
Typical VdM scan at LHC

- Horizontal and vertical beam separation
 - ~25 steps per scan plane, ~30 sec per separation step
- Dedicated machine setup for optimal conditions
 - Reduced number of bunches
 - Reduced bunch intensity
 - Larger β*
- Combined effort from all experiments and LHC experts to achieve maximum precision
- VdM scans are time-consuming and need to be carefully planned
 - Only two or three scan sessions per year



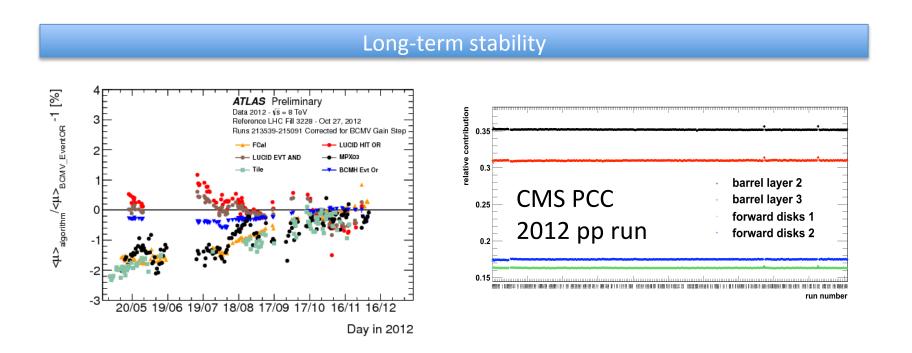
Optical theorem basics

- TOTEM for CMS and ALFA for ATLAS are able to perform absolute luminosity measurements
- Based on Optical theorem
 - Measurements of the total rate in combination with the t-dependence of the elastic cross section (TOTEM)
 - Measurements of elastic scattering rates in the Coulomb interference region(ALFA)



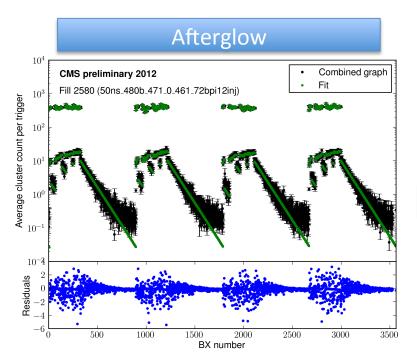
- Requires dedicated LHC fills with special magnet settings
- Roman pots far from the interaction points (about 200 m)
- Measurements at very low interaction rates
 - Cross-calibration of dedicated luminosity detectors
 - Extrapolation of calibration to typical physics conditions introduces big uncertainties
- Valuable cross check but at LHC not competitive to VdM scans for integrated luminosity measurements

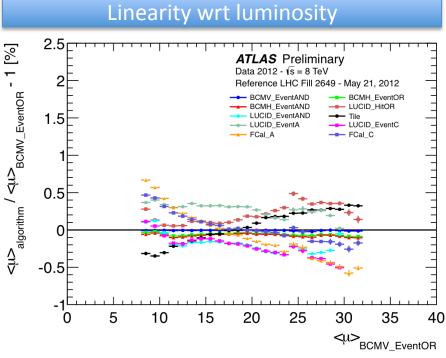
Uncertainties: long-term stability



- Long-term stability is monitored by the long-term consistency of different luminosity detectors
 - Redundancy is key

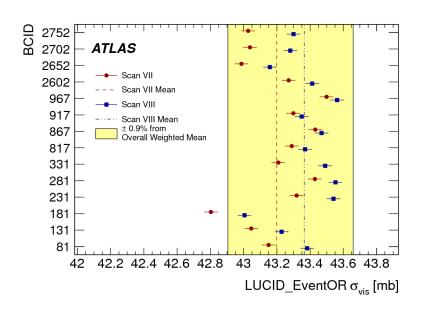
Uncertainties: detector-related



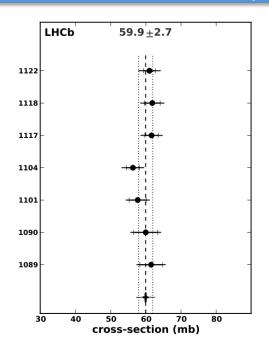


Uncertainties: reproducibility

Bunch-by-bunch consistency



Scan-to-scan consistency



 Consistency of calibration results among different bunches and among scans is used to estimate uncertainties due to unknown effects