
Physics at LHC and beyond
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Part2: challenges of CMS operations during LHC Run 1

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on behalf of CMS collaboration



The Compact Muon Solenoid during Run 1

CMS DETECTOR

Total mass ~12,500 t
Overall diameter ~13.0 m
Overall length ~15 m
Magnetic field ~3.8 T

STEEL RETURN YOKE

Pixel (100x150 μm) ~16m² ~66M channels

SUPERCONDUCTING SOLENOID

Niobium titanium coil carrying ~18,000A

MUON CHAMBERS

Barrel: 250 Drift Tube, 480 Resistive Plate Chambers
Endcaps: 468 Cathode Strip, 432 Resistive Plate Chambers

VER

Silicon strips ~16m² ~137,000 channels

FORWARD CALORIMETER

Quartz fibres ~2,000 Channels

CRYSTAL
ELECTROMAGNETIC
CALORIMETER (ECAL)
~76,000 scintillating PbWO₄ crystals

HADRON CALORIMETER (HCAL)
Brass + Plastic scintillator ~7,000 channels

operations

**An impressive level of physics performance and results quality:
which have been the keys for CMS to perform so well?**

An organized system for on-line operations

Versatile trigger configuration

Robust data acquisition system

Constant monitoring of sub-detector response

High quality of prompt reconstruction

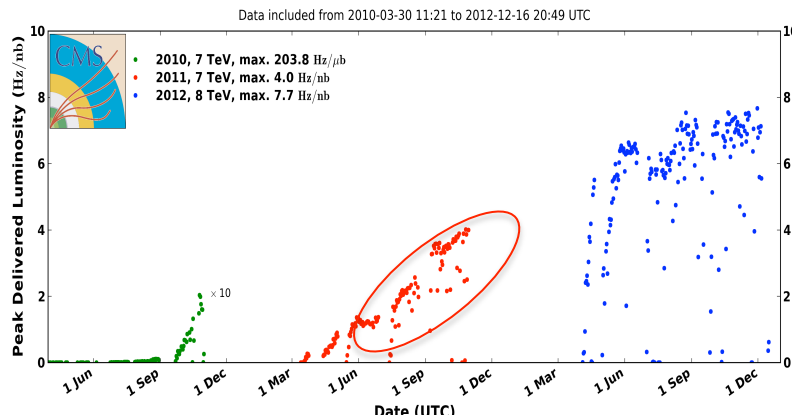
Meticulous data quality monitoring

Efficient storage and data processing

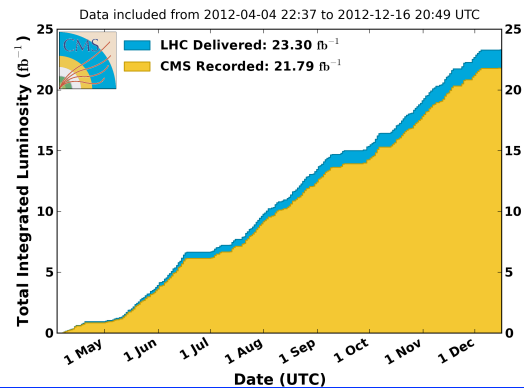


Challenges during LHC Run 1

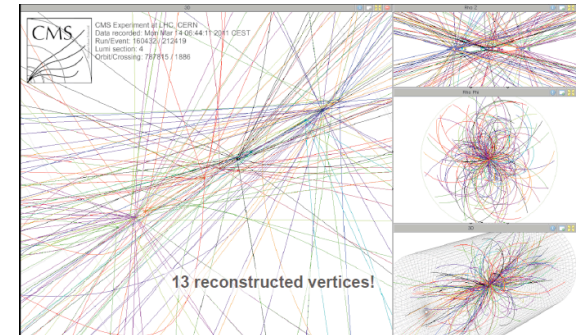
Increasing of peak lumi →
need revisiting of trigger paths



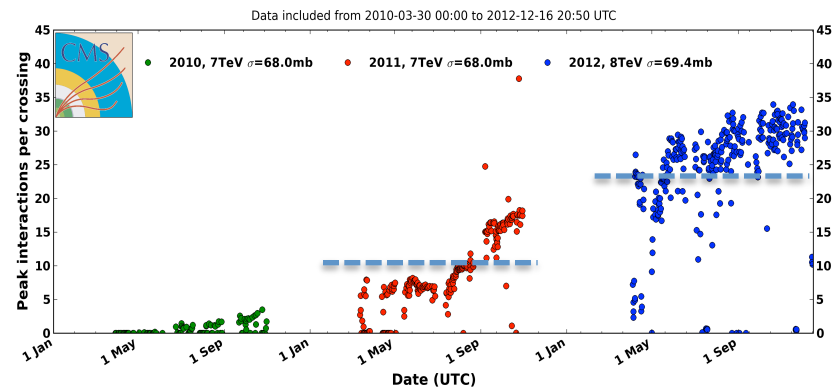
CMS Integrated Luminosity, pp, 2012, $\sqrt{s} = 8$ TeV



Increasing of pile-up (#proton/bunch) →
need tuning of reconstruction and triggers



CMS peak interactions per crossing, pp



Detector downtime → need automation of data acquisition



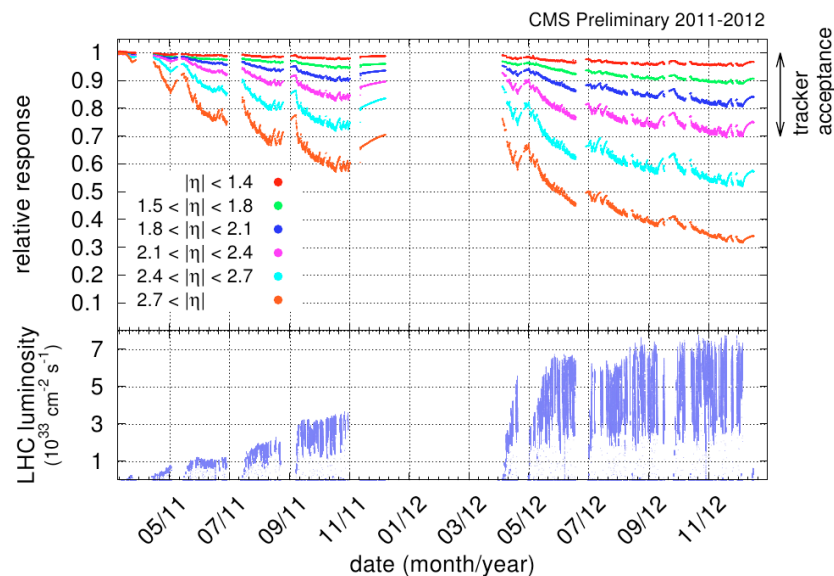
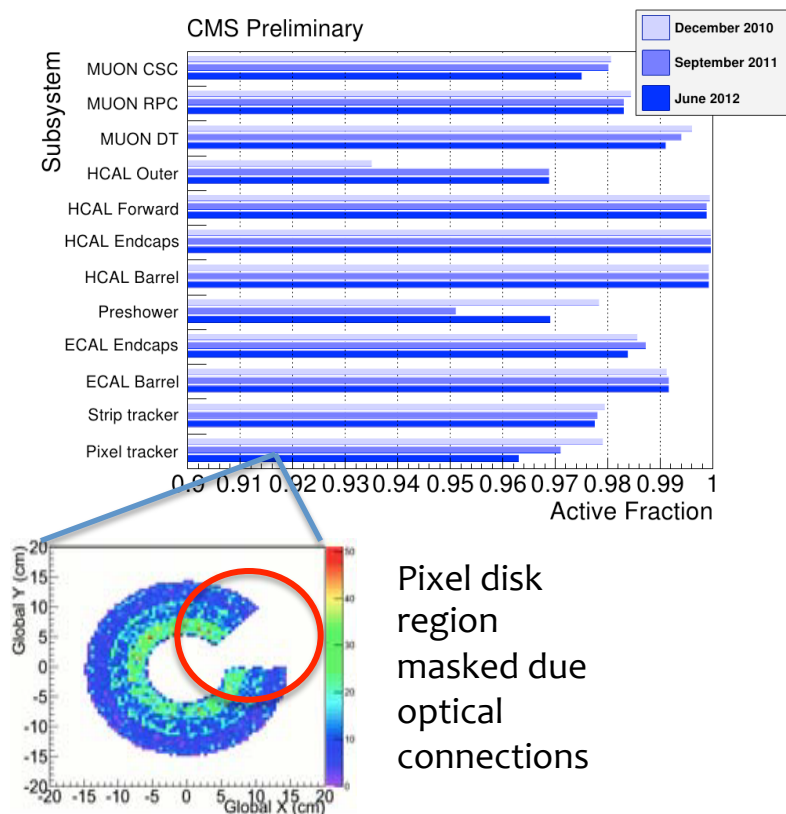
Challenges during LHC Run 1

Detector inactive module/channels →

most of the losses addressed during shutdown

Misalignment and miscalibration →

A fast workflow already during prompt reco



ECAL transparency loss used to correct physics data promptly



How did we tackle all this?



An organized system for on-line operations

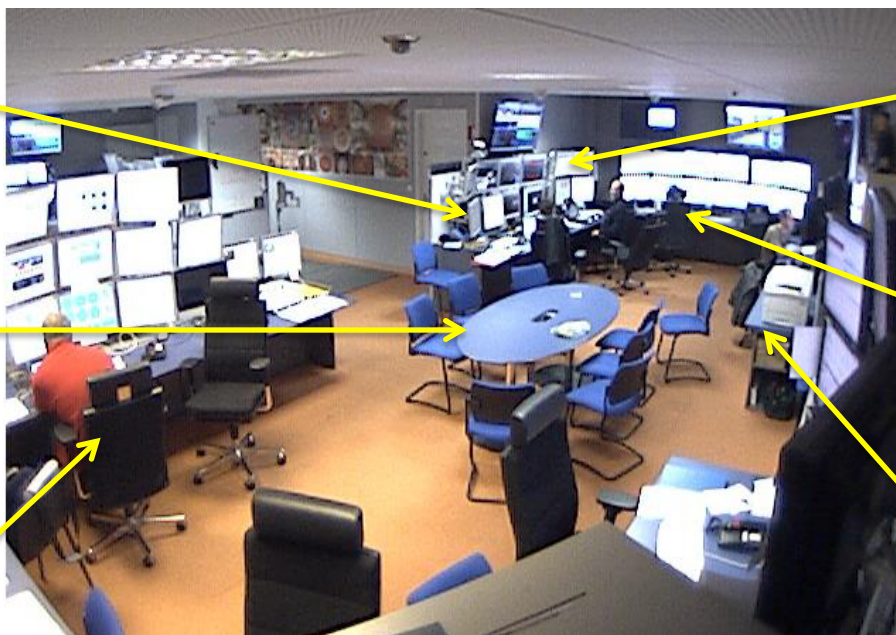
CMS control room: core of the operations at LHC Point 5

- ✧ **Most far of LHC points** from Meyrin site (where main experts reside)
- ✧ Built up an easy-to-access system for allowing key expert interventions **from remote**

CMS shift leader

Run Field manager

Detector Control System (DCS) shifter



Data Quality Monitor (DQM) shifter

On-line trigger shifter

Data Acquisition (DAQ) shifter

+ *Offline* shifter: run certifications, offline DQM, Operation Release Managers, etc..

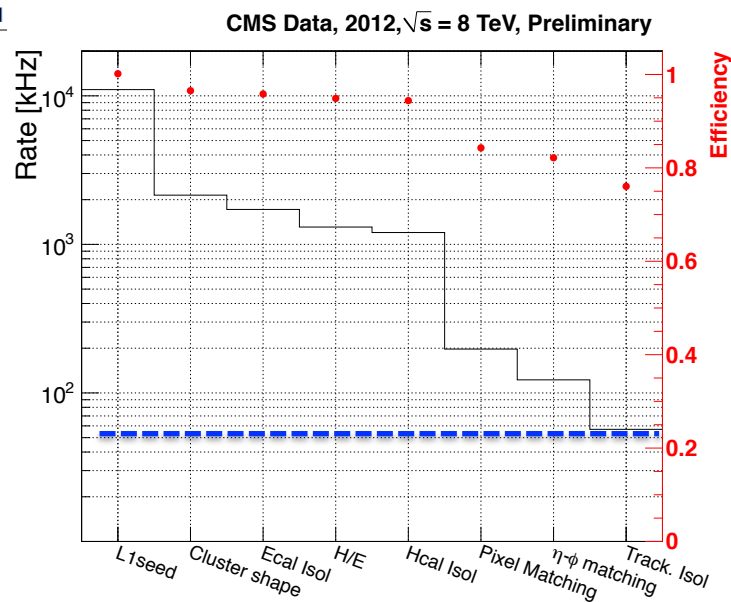
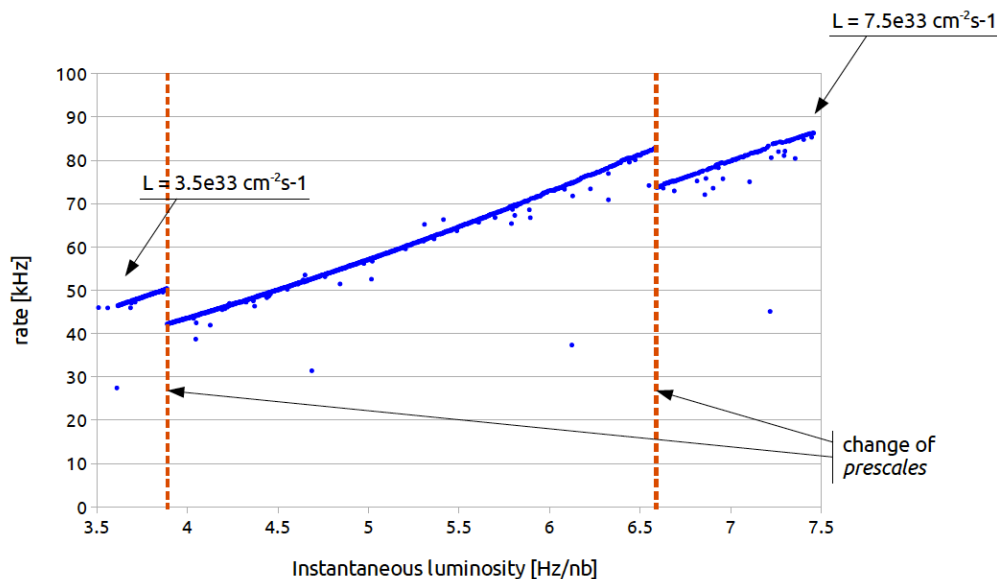
Level 1

- ✧ hardware based : **4 μ s** decision time
- ✧ 20-MHz bunch-crossing rate to **100 kHz**



High Level Trigger (HLT)

- ✧ Software based: **50-200 ms** decision time
- ✧ Reduce to **400 Hz (core) + 600 Hz (parked)**



strategy

- ✓ **Re-tuning** of trigger paths and seeds, **rather than prescaling physics paths**
- ✓ **“parking”** of loose HLT path dataset (processed during LS1)
- ✓ Improving tracking and **speeding up reconstruction**

Detector downtime:

- ✧ Periodic re-synchronization of sub-detectors during data taking
- ✧ Stand-by needed also **during LHC dump warning** (kicker at point 6)
- ✧ **Require Heavy automation** of DCS and DAQ

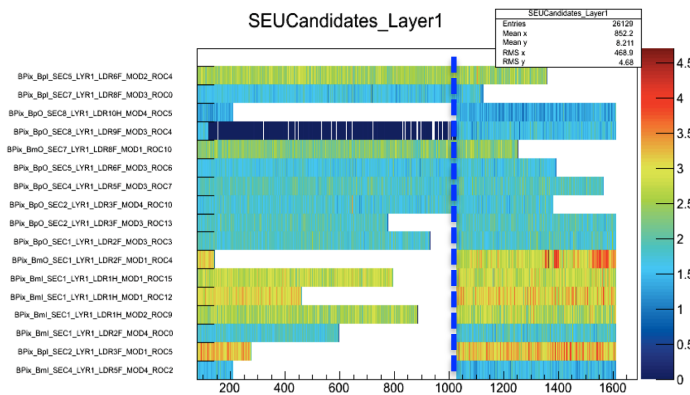
Downtime episodes during Run1

Tracker HV turn-on, need to be in stand-by until stable beam declared



- ✧ **Automatic ramping of HV at DAQ**
- ✧ Provided beam conditions met criteria in the **30 s** prior to the declaration of stable beam

1.5 bit flip / LHC fill in Pixel electronics caused by ionization



- ✧ Out Of Sync (OOS) errors
- ✧ Implemented at DAQ level
- ✧ **O(seconds)** to reconfigure

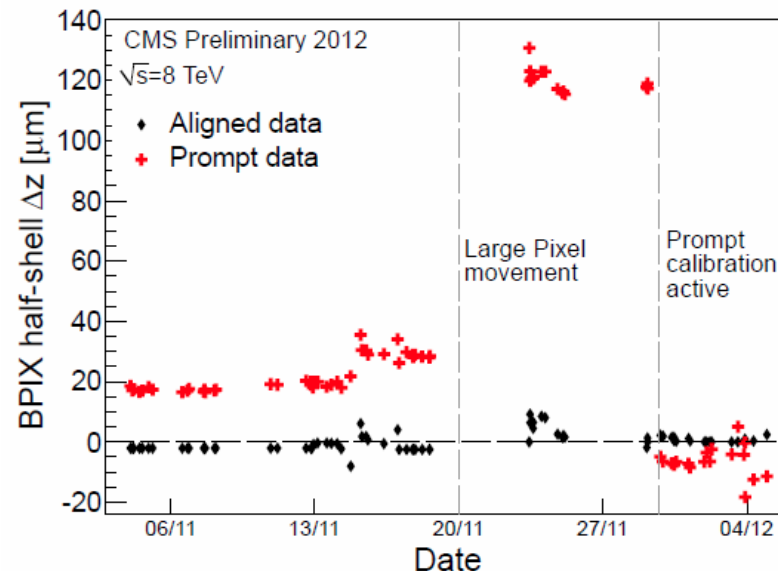
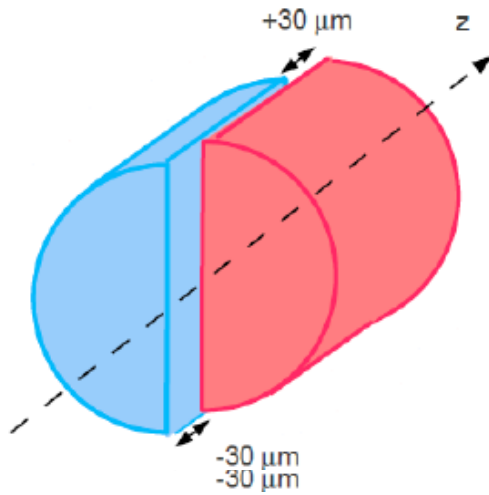


Constant monitoring of sub-detectors

Example: detector control system for CMS solenoid ($B=3.8\text{T}$, kept at $T=-268.5^\circ\text{C}$)

In general avoiding magnet recycling..

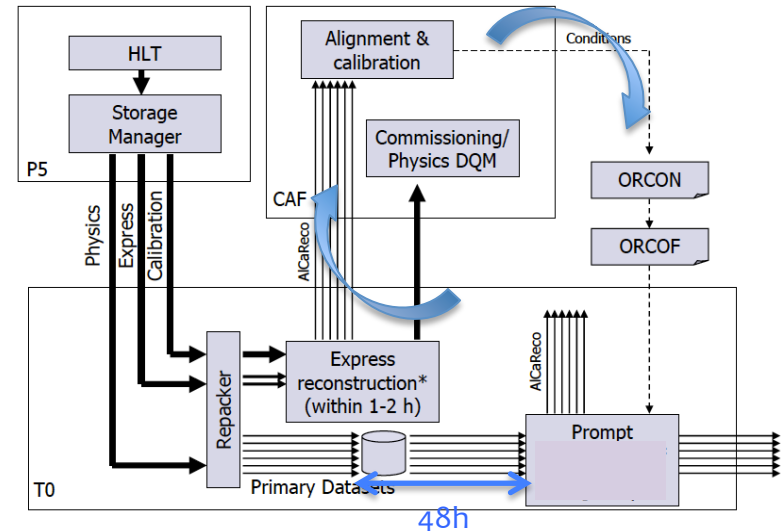
- ◆ Important downtime: **2-3 days for ramping up** (critical if around LHC fills)
..if anyway needed
- ◆ at least controlling non-negligible mechanical effects on the rest of sub-detectors:
 - ✧ Longitudinal **100 μm** shift of the 2 halves of Pixel detector by magnet thermal cycle
 - ✧ **Recovered** by quasi-prompt alignment \rightarrow **fully automated since Run2**





A prompt calibration loop in reconstruction

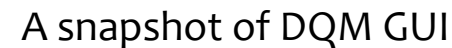
- ◆ Update-strategy based on delay between *express* and *prompt* reco (48h)
- ◆ Successfully used **during Run1** :
 - ✧ **beam-spot position** measured every Lumi Sections (LS= 23s of run)
 - ✧ **ECAL transparency corrections** measured with laser pulses



- ◆ Also conditions which need to be monitored (and updated if necessary):
 - ✧ **Tracker problematic channels** → HV trips/noise
 - ✧ **Calorimeter problematic channels** → mask hot channels
 - ✧ **Pixel alignment (since Run2)** → monitoring large structure shifts using tracks

CMS published physics measurements and discoveries out of prompt reco!

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- The diagram illustrates the LumiChimera workflow, which is divided into two main paths: **Offline Online** and **Detector & Operation**.
- Offline Online Path:**
- Simulation Validation** leads to **Release Validation**.
 - Release Validation** leads to **Tier-1s**.
 - Tier-1s** leads to **CAF** (Data Processing).
 - CAF** leads to **Conditions** and **Conditions** (Visualisation).
 - Conditions** and **Conditions** lead to **Run Registry** (Certification).
 - Run Registry** leads to **JSON file of certified LumiSections** (Sign-off).
- Detector & Operation Path:**
- The **Detector & Operation** path involves the **Run Registry** (Certification) and the **JSON file of certified LumiSections** (Sign-off).
 - The **Run Registry** is linked to a **Physics Data Certification** timeline showing 1/day, 2/day, and daytime operations.
 - The **Detector & Operation** path also includes a **Detector & Operation** timeline showing 24/7 operation.
- The workflow is supported by **Data Processing**, **Visualisation**, **Certification**, and **Sign-off** stages.

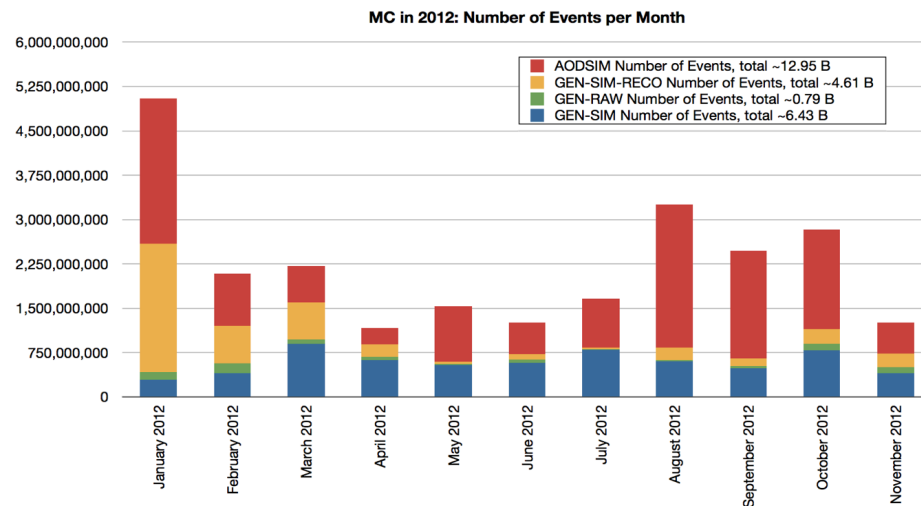
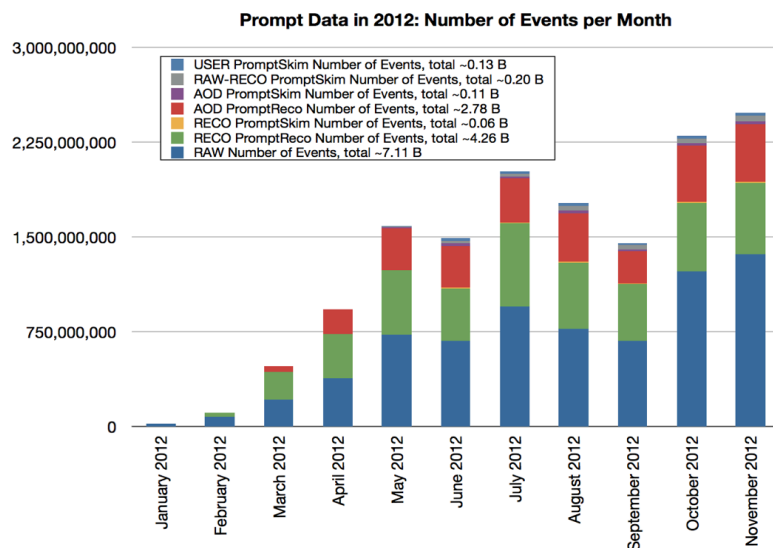


- ◆ Web site (GUI) for browsing data quality histograms for a given dataset/run
- ◆ **Selection of LS** considered for physics performed **weekly** by offline detector experts and shifters
- ◆ Final list distribute in **JSON format** to use for filtering in the analysis jobs



An efficient storage and data flow

- ◆ 2012 was the busiest of the Run I years in terms of data collection and storage
 - ✧ **7 B physics events** were collected: 4 B prompt-reco + parked data
 - ✧ All 2012 data was reprocessed later in 2013:
 - Only few re-reco, thanks to timely **release validations** and **prompt calibration**
 - ✧ **13 B MonteCarlo simulated** events have been produced



Computing was used at 100% , no large problems which required recovering



Run 1: a success for CMS operations (and LHC machine)

Peak instantaneous luminosity	$7.67 \cdot 10^{33} \text{ cm}^{-2} \text{ s}^{-1}$
Max interactions per bunch crossing (PU)	34.55
Maximum colliding bunches	1380
Best recording efficiency by lumi for one fill	98.93% [171.20 pb^{-1}]
Maximum Recorded lumi in one day	280.07 pb^{-1}
L1 trigger output rate	100 kHz
HLT physics stream output rate	400 Hz
HLT physics stream output rate (for parked data)	600 Hz

- ◆ Major improvements and challenges foreseen:
 - ✧ **Trigger, Tracking** : facing higher PU and out-of-time PU (operations at 25ns)
 - ✧ **Prompt calibration** workflows: more automatized
 - ✧ **Computing**: the scale of the problem will increase by factor 6 in 2015 (x 2.5 evt reco time)

Many lessons from Run1 and CMS is working to keep the standard high for Run2

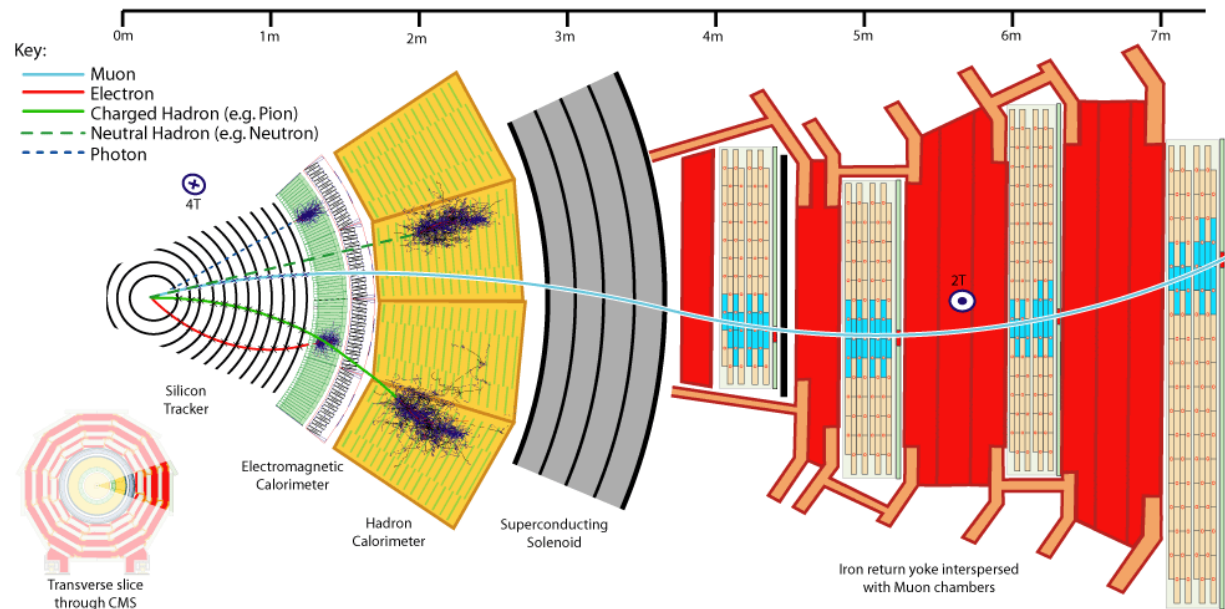


BACKUP



The tool: a Compact Muon Solenoid

- ◆ From particle reconstruction: muons, electrons, hadrons (charged and neutral), photons



... to physics objects: muons, electrons, jets, photons

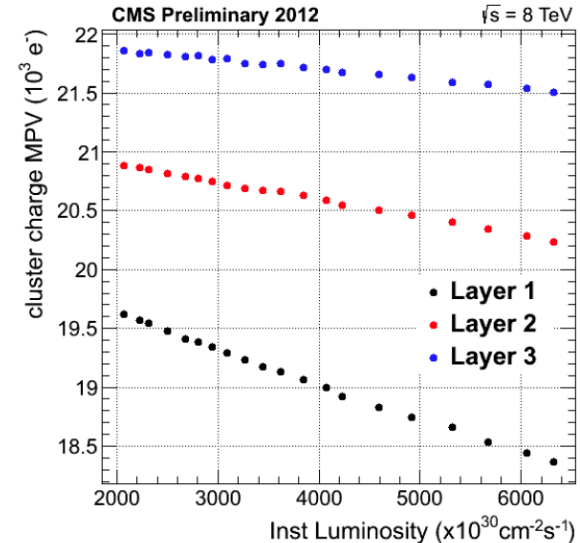
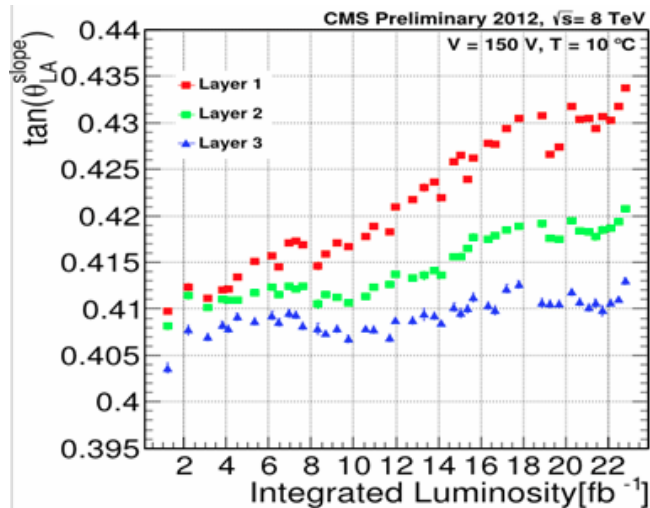
- ◆ Excellent detector performance:
 - ✧ Track-finding efficiency is more than 99%
 - ✧ Transverse momentum resolution: $\sigma(p_T)/p_T = 1.5 - 3\%$ for tracks of $p_T \sim 100$ GeV
 - ✧ Energy resolution for electrons and photons: $\sigma(E)/E \sim 1\%$



Effects of pile-up and luminosity increase in Pixels

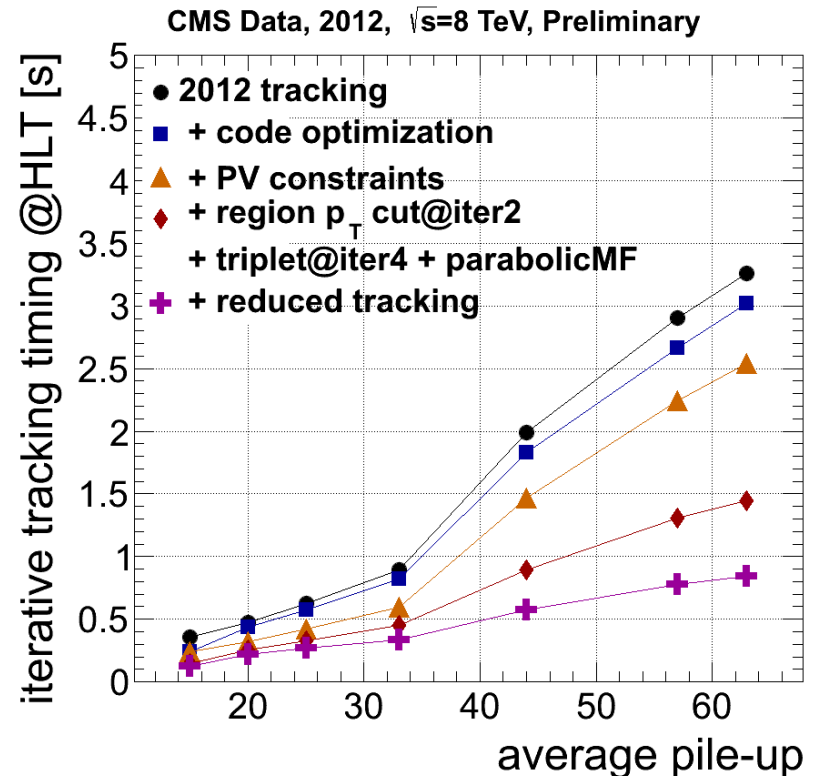
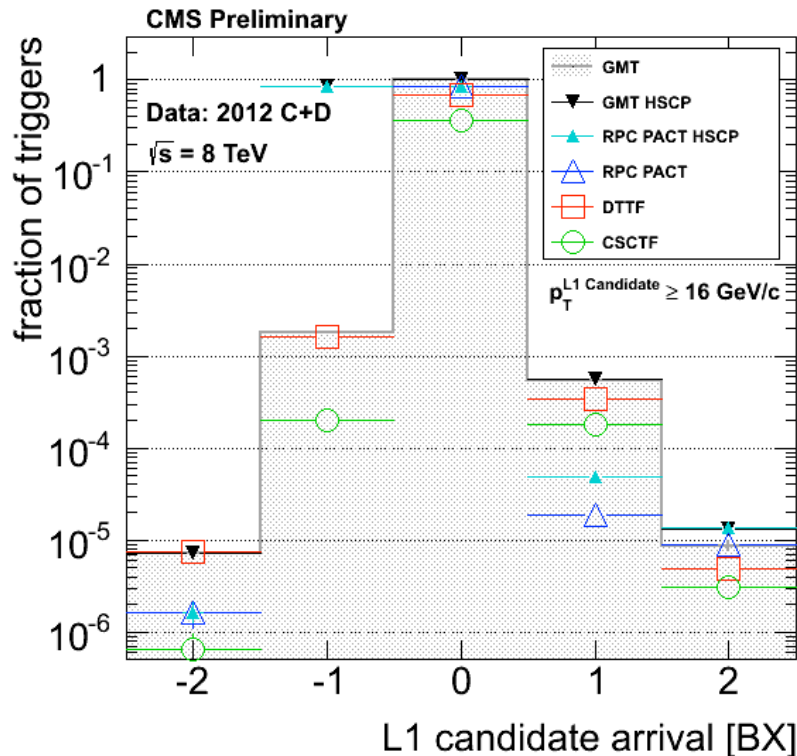
A Short term effect:

- ◆ Higher occupancy increases the power consumption and therefore the temperature in the ROCs
→ pixel charge gain calibration is temperature dependent



A long term-effect:

- ◆ Lorentz-angle measurement :
 - ◇ Also depends on integrated luminosity
 - ◇ Highly depends on bias voltage
 - ◇ Influences charge-sharing among pixels



L1: fraction of L1 muon triggers in the different bunch crosses

HLT: many studies and improvements have been developed during LS1 in order to mitigate the track reconstruction timing