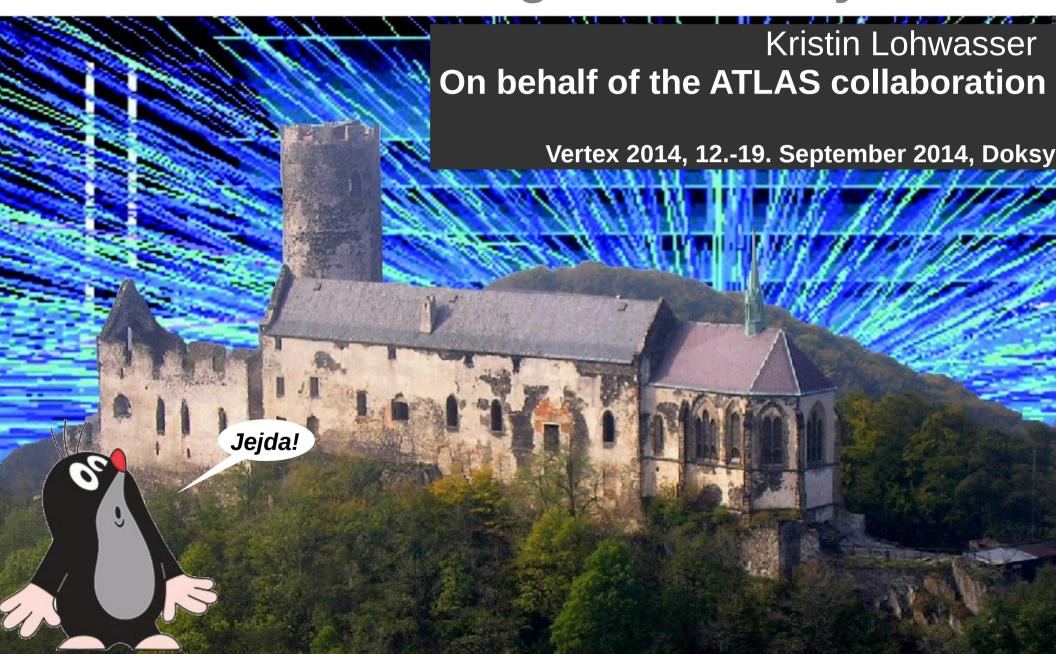
Upgrade of the ATLAS inner strip detector for the high luminosity LHC





2009 <u>LHC</u>

 $\sqrt{s} = 7~8 \text{ TeV}$

2012 Startup

 $L = 6 \times 10^{33} \text{cm}^{-2} \text{s}^{-1}$, BS=50 ns

∫Ldt~25 fb⁻¹
Discovery of
Higgs boson

Phase 0

Go to nominal energy

New beam pipe, additional b-layer (IBL)





LHC **Startup**

 $\sqrt{s} = 7 \sim 8 \text{ TeV}$ $L = 6 \times 10^{33} \text{cm}^{-2} \text{s}^{-1}$, BS=50 ns

\int Ldt \cdot 25 \text{ fb}^{-1} Discovery of Higgs boson

Phase 0 Go to nominal energy New beam pipe, additional b-layer (IBL)

TODAY!

2015 2018

LHC Design $\sqrt{s} = 13~14 \text{ TeV}$

Parameters L~1x10³⁴cm⁻²s⁻¹, BS=25 ns

∫Ldt~75-100 fb⁻¹ Extra dimension@9 TeV Compositeness@30 TeV Leptoquarks m=1.5TeV

Phase 1

Injector Upgrade

New Muon Small Wheels, Fast Track Trigger

2019

Ultimate

 \sqrt{s} = 14 TeV

2021

Luminosity

L~2x10³⁴cm⁻²s⁻¹, BS=25 ns

∫L*dt*~300 fb⁻¹ Compositeness@40 TeV TeV resonances

in WW scattering



LHC Startup

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TODAY!

LHC Design $\sqrt{s} = 13~14 \text{ TeV}$

Parameters L~1x10³⁴cm⁻²s⁻¹, BS=25 ns

\(\Ldt \sim 75 - 100 \text{ fb}^{-1} \) Extra dimension@9 TeV Compositeness@30 TeV Leptoquarks m=1.5TeV

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 $\sqrt{s} = 14 \text{ TeV}$

Luminosity

L~2x10³⁴cm⁻²s⁻¹, BS=25 ns

\int Ldt \ \ 350 \text{ fb}^{-1} Compositeness@40 TeV TeV resonances in WW scattering

Phase 2

Upgrade, interaction regions, crab cavities?

Replacement of inner detector, calo/muon upgrades, L1 track trigger

2025

High

 \sqrt{s} = 14 TeV

Luminosity 2035

L~5x10³⁴cm⁻²s⁻¹, lumi leveling

∫L*dt*~3000 fb⁻¹ Z' @ 5 TeV Ultimate precision of Higgs properties



High luminosity LHC (HL-LHC)

"Europe's top priority should be the exploitation of the full potential of the LHC, including the high-luminosity upgrade of the machine and detectors with a view to collecting ten times more data than in the initial design, by around 2030"

The European Strategy for Particle Physics — March 2013 CERN-Council-S/106 https://indico.cern.ch/getFile.py/access?resId=0&materialId=0&confld=217656

→ Simillar statement in the report of the Particle Physics Project Prioritization Panel (P5)

To fully exploit increase in available integrated luminosity and decreased statistical uncertainty,

try to maintain same (or better) detector performance

Fully replace current inner detector tracker (ITK)

Face challenges of HL-LHC:

Radiation damage Occupancy



Challenges: Radiation Hardness

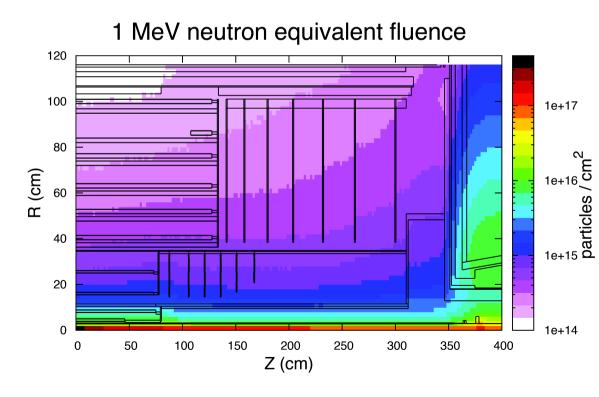
- Below < 1 m radius: severe radiation damage to components
- Current ATLAS strip detector can endure fluences of only 2 x $10^{14} n_{eq}/cm^2$ (1 MeV neutron equivalent / cm²)

corresponding to a luminosity of ~700 fb⁻¹

 Required for strip detector at the HL-LHC:

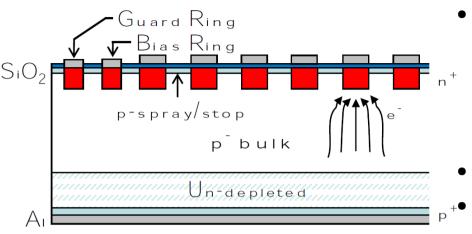
fluence of $2 \times 10^{15} n_{eq}/cm^2$ (expected: $8.1 \times 10^{14} n_{eq}/cm^2$, allow for safety margin)

luminosity of 3000 fb⁻¹ (or even more)





Current Solution: Sensors



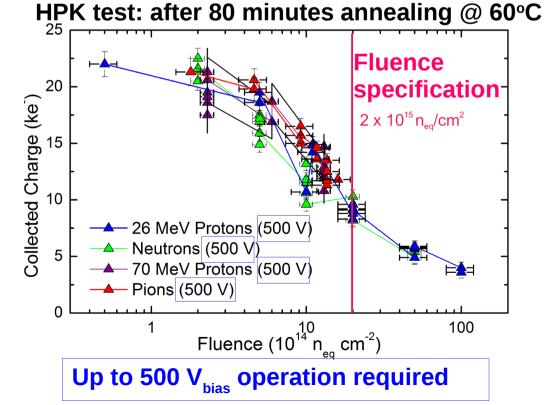
- AC-coupled sensors with n-type implants in p-type float zone
 - → electron collection, no type inversion
 (single sided process → cheaper)
- Barrel: \sim 98×98 mm² area, 74.5 μ m pitch
- Endcap: varying size, similar pitch (near bond pad)
- Thickness: 320 \pm 15 μ m (could be reduced, additional costs)
- Prototype programme (2008, 2012)
- Signal to noise better than 10:1

Barrel: 23-25

Endcap: 17-26 (radial strips!!)

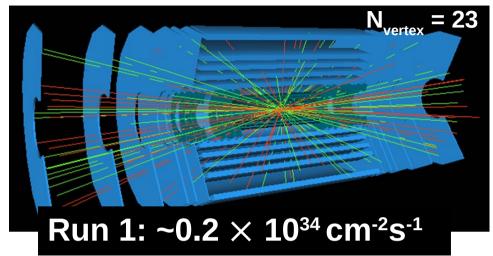
Module tests: similar results

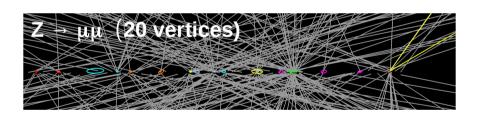
 Market surveys to investigate alternative suppliers



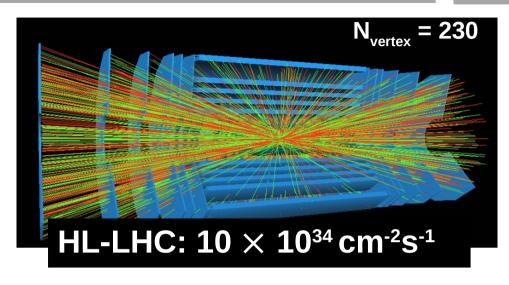


Challenges: Occupancy





- Average N_{vertex} ~ <20>
- Run 1: Excellent performance
- Current inner detector working very well under current conditions

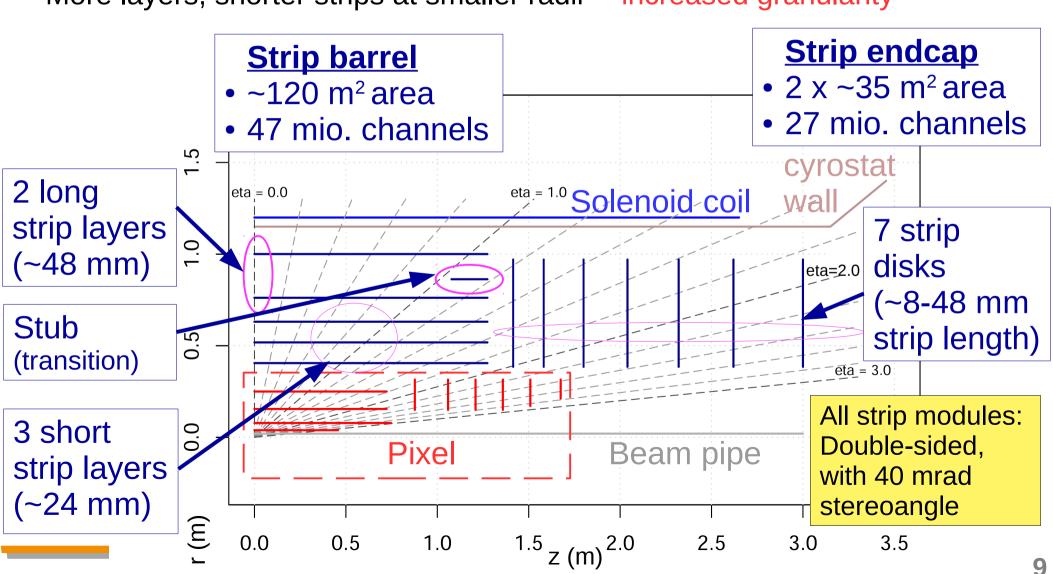


- Average $N_{\text{vertex}} \sim <140>$ up to 230 multiple interactions, 1000 tracks per $\Delta \eta = 1.0$
- Challenge for > 1m radius are high Pile-up and trigger rates
- ullet Data losses above 3 imes 10³⁴ cm⁻²s⁻¹ link between ABCD front-end chip and read out driver cards
- Increased reconstruction complexity



Current Solution: New Layout

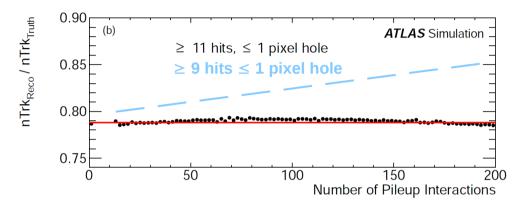
- Larger outer active radius → improving momentum resolution
 Outer strip layer and disk are placed at largest possible r / z position
- Re-routing of services out of active area → decreasing dead material
- More layers, shorter strips at smaller radii → increased granularity



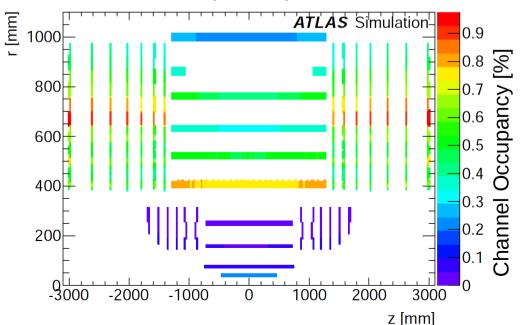


Simulation Results

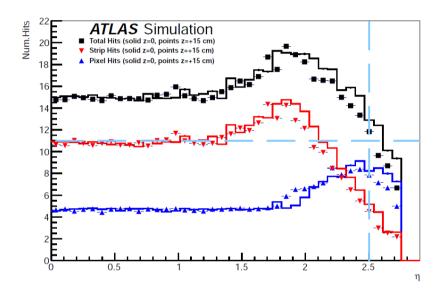
 Pile-up causes fake tracks, removed by requiring ≥ 11 hits



 Occupancy < 1% everywhere, even for 200 pile-up events



• Achieved up to $|\eta| = 2.5$, on average 14 hits in central barrel robust tracking despite dead modules

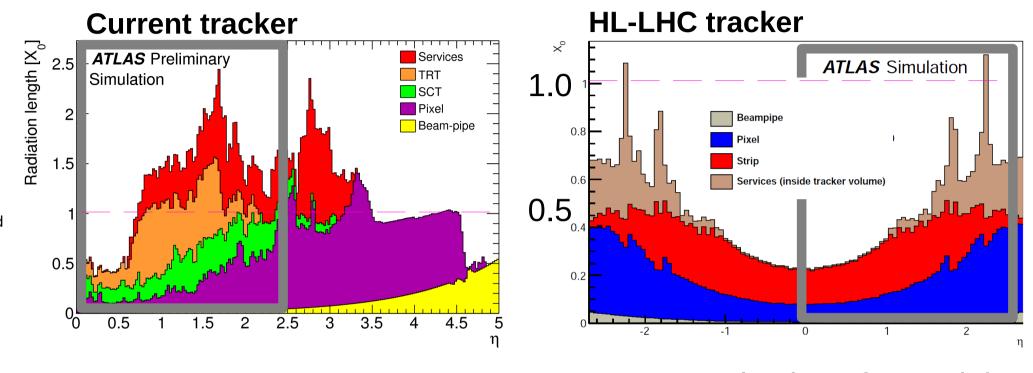


Track parameter (η)	Current tracker (for pT $\rightarrow \infty$)	HL-LHC tracker (for pT $\rightarrow \infty$)
q/p _T [/TeV]	0.3	0.2
d ₀ [μm]	8	8
z ₀ [μm]	65	50

assuming: 200 pp-interactions



Material budget



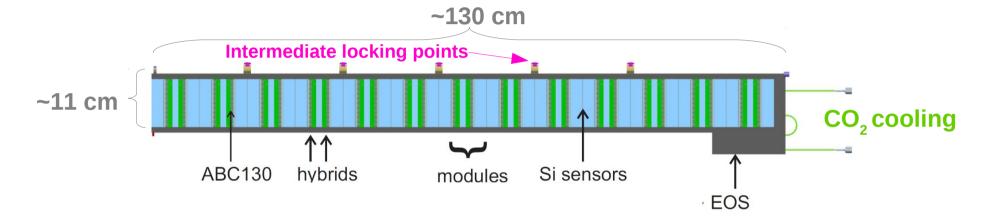
- New support structures (light carbon fibre) → Reduction of material
- Up to a factor of 2-3 for $\eta > 1.0$
- Will greatly reduce bremsstrahlungs losses for electrons, enhances performance

All Requirements are met with current layout – but can we actually build it?

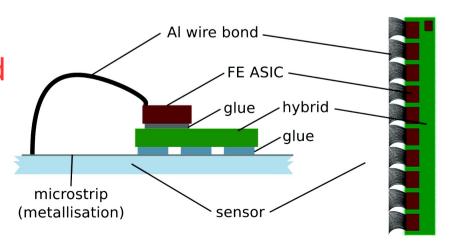


A closer look: Barrel...

- Barrel detector composed of staves (cooling and mechanical support)
- 26 modules (13 per side) glued on carbon composite structure form half-barrel (for A and C side respectively)



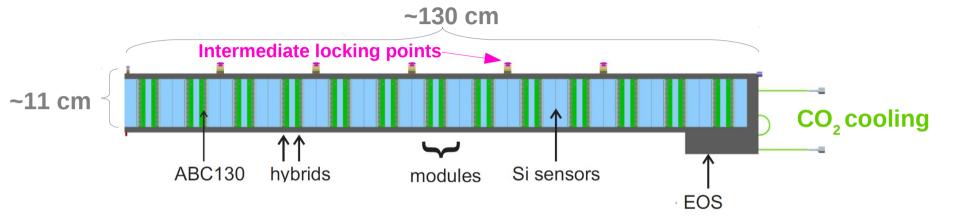
- Front-end chips ABC130 nm on kapton circuits → hybrid
- Glued and wire bonded to silicon sensor
 - → module

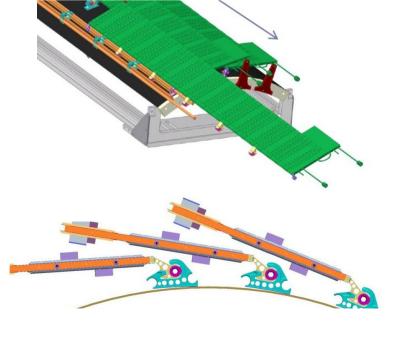




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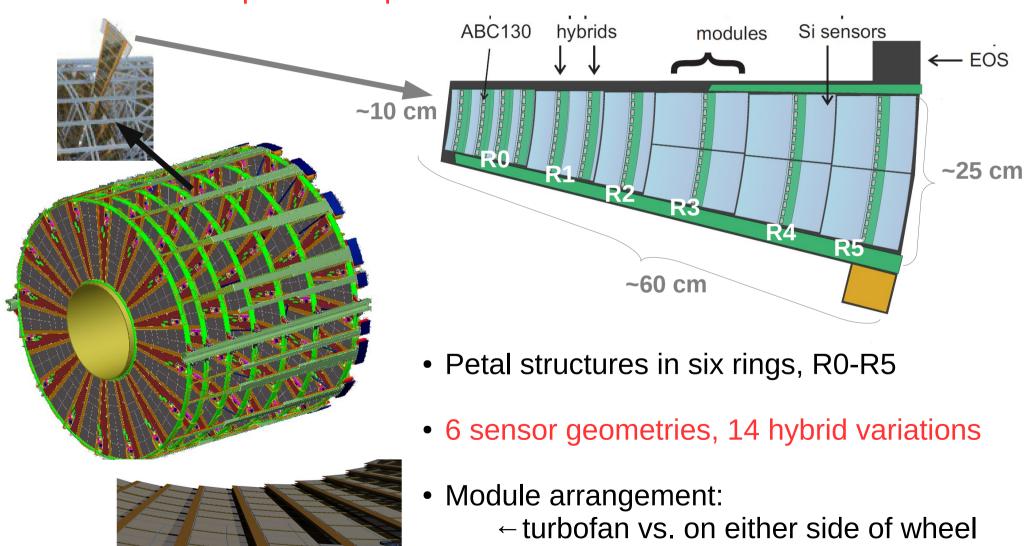


- Emphasis on high modularity, robustness
- Insert staves from end of barrel in pre-built support structures
- Total: 472 staves, ~13000 modules
- Tilt angle ≥ 10° → hermetic down to 1 GeV, minimise charge spread due to Lorentz-angle



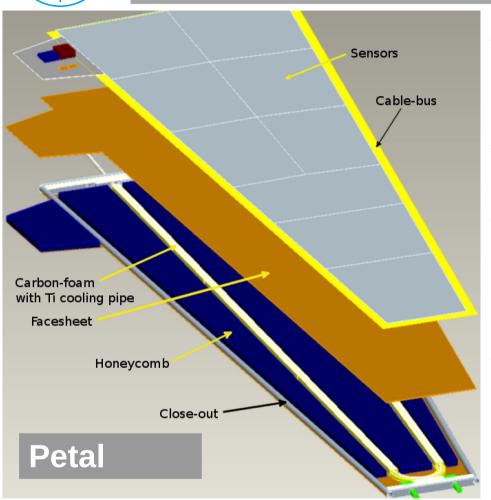
... and Endcap

- Endcap detector composed of *petals* (same ideas as for barrel/staves)
- 7 wheels per end-cap, 32 petals per wheel, 18 modules per petal 4032 modules per endcap





Support and cooling



- Carbon honeycomb + foam with embedded cooling pipe (CO²)
- Co-cured bus tape for data and power
- Stave production very advanced
 (geometry stable, past R&D,
 ~final procedures in place for full staves)
- Petal core prototyping close to finish (need now full design of petal)

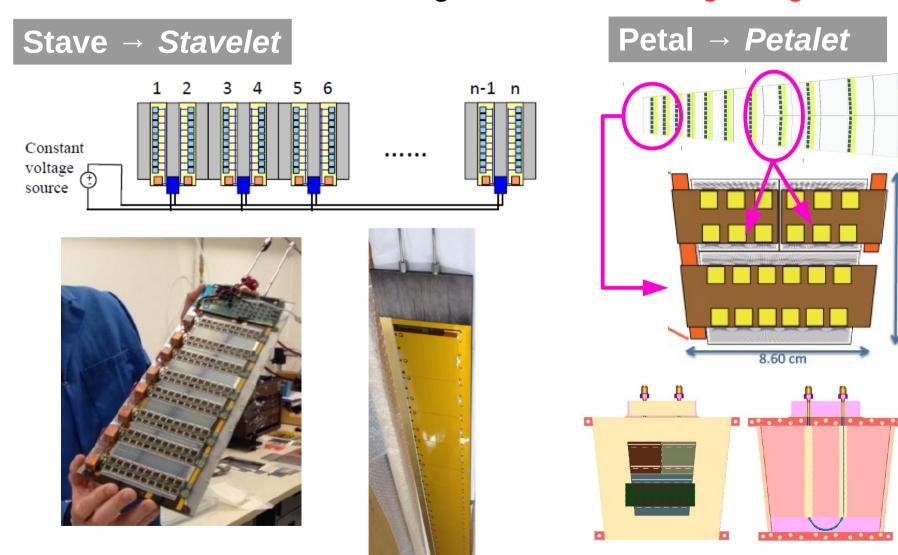
Stave: half the X0 is from module

	%X0
Stave core	0.55%
Bus tapes	0.30%
Modules	1.07%
Module to stave adhesives	0.06%
TOTAL	1.98%



R&D: Small scale prototypes

- Utilize modularity of design → test small scale prototypes (250nm ASIC)
- Cost efficient, valuable insights: construction, glueing, tooling



- 4 modules → 1 stavelet
- Full stave in construction

- 1 petalet: smallest module
 - + transition of 1 → 2 sensor

Petalet

1 side:

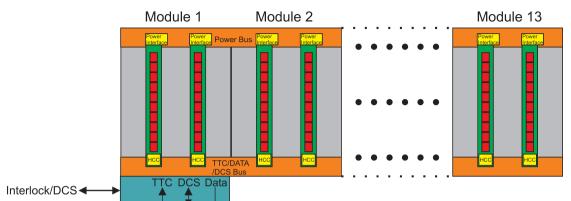
DC-DC powered

3 sensors

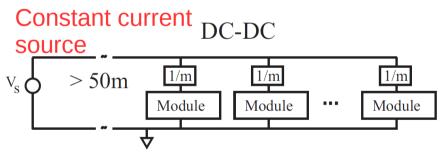
*hvbrid = PCB



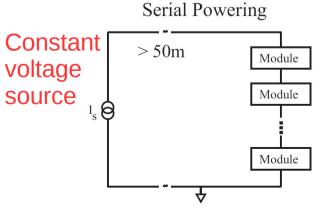
Stavelet electrical tests



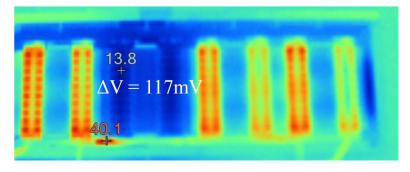
- 2 hybrids with 10 Chips (130 nm CMOS ASICs)
- Interfaced to EOS (end-of-stave) board with HCC (Hybrid Control)
- Bus tape: data/timing/trigger and power lines (single copper/aluminium/kapton tape laminated on core)



- DC-DC vs serial power (two-sided stavelet)
- Noise performance ok comparable to single module powered by power supply
- Decision after test with proper ABC130 nm



Radiation hard switches to turn off broken modules \rightarrow works!



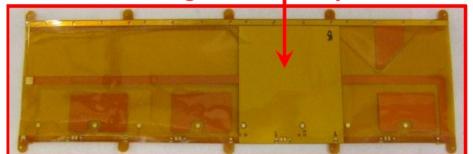


Stavelets: Materials

Ideal test bed for for construction and design, e.g.:
 Shieldless bus tape: Remove Al shielding → carbon fibre as shild

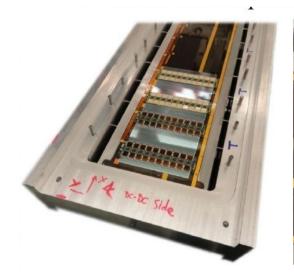
(8-10% material reduction from stave, cost reduction, curing easier)

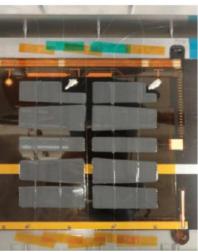
Shielding left for comparison



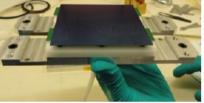
Shield-less tape

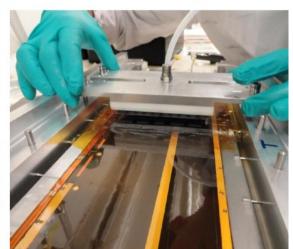
- New precision tools developed:
 Placement with X-Y precision with ~ 150 μm accuracy
- Glue thickness ~175 μm





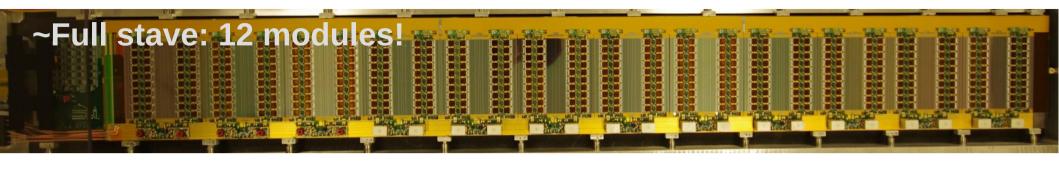


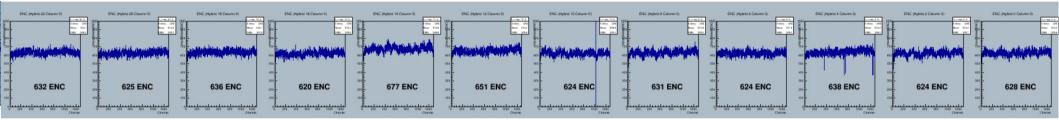






Stavelets → Staves





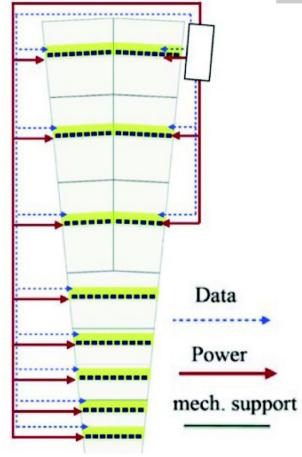
- DC-DC powered
- 4-segment power bus → each segment drives 4 modules
- Good noise behaviour → 600 677 ENC (equivalent noise charge)
- Work in progress: Full scale serial powered stave



Petalet

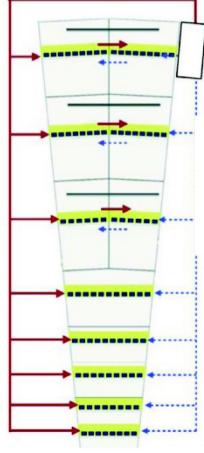
LAMB & FLAG

- Split hybrids
- data/power lines from same end





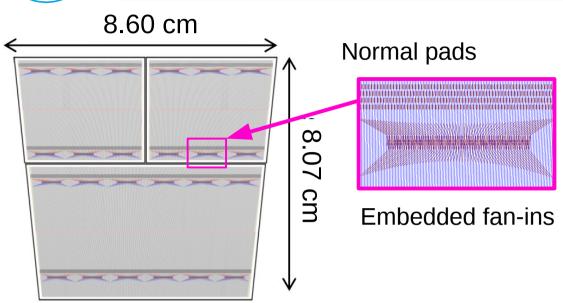
- 1 hybrids for 2 sensors
- data/power lines from two sides



- Two design options: Lamb&Flag versus The Bear
- 2 neighbour modules: Significant differences to stavelet electrical layout (HV routing, DCDC location)
- Plan: → Build 10 petalets with 250 nm ASICs
- DCDC powering prefered: varying number of ABC130
 - → varying power to be delivered to hybrid
- serial powering requires shunts to dissipate energy

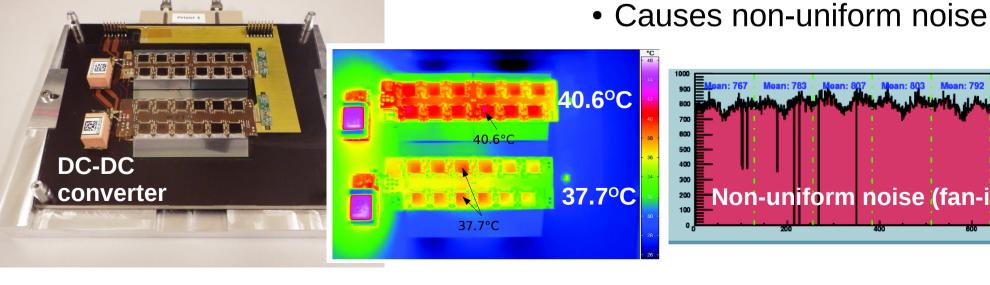


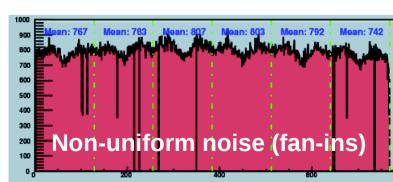
Petalet



- This year: First petalet assembled and tested
- Some differences to stavelet
 - → improved electrical layout
- Built-in stereo angle, fan-ins to bridge different strip pitch align Chip-Sensor pads

Full petalet

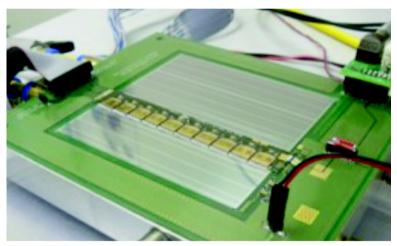




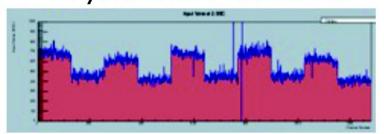
DESY

ABC130 nm

- Stavelet/Petalet R&D completed up to 80-90% using 250 nm Chips
- Advantages of 130nm technology: less power consumption less cooling needed → less material (cooling pipes/liquid...)



Hybrid with 5+5 ABC130



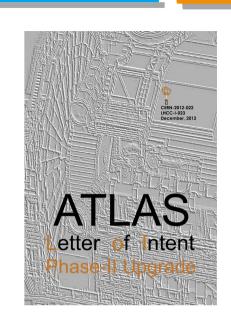
With one of two columns of strips bonded

- First tests with 130nm vs. 250nm: performance mostly as expected
- Hybrid/modules → already built
- Simpler wire-bonding
 - → collaboration with chip designers
- Noise as expected, extremely regular



Conclusions

- Significant progress towards
 design and construction of a new inner tracker
 for the ATLAS experiment
- All challenges of the HL-LHC can be met!
- Fully modular approach, allows for substiantial testing (and assembly) of ~all components before insertion into support structures
- Successfull R&D programme of small scale structures (stavelet and petalet) up to 80-90% completed
- Letter of Intent (2012) will be followed by Technical Design Report, envisaged date: 2016



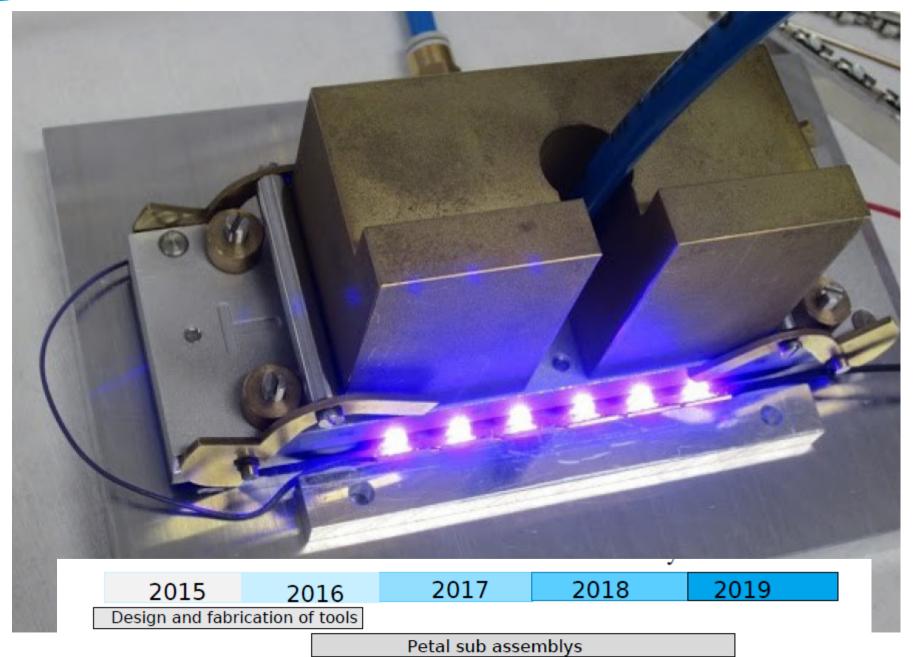


Thank you!





UV Glueing



Petal fabrication



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∫L*dt*~350 fb⁻¹

Compositeness@40 TeV TeV resonances in WW scattering

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Upgrade, interaction regions, crab cavities?

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High

 $\sqrt{s} = 14 \text{ TeV}$

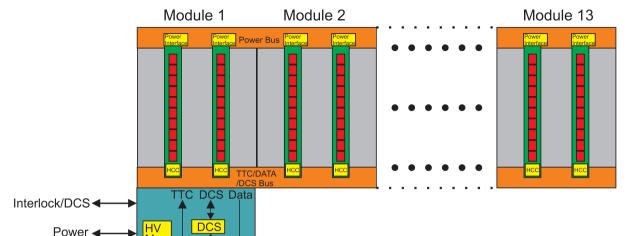
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∫L*dt*~3000 fb⁻¹ Z' @ 5 TeV Ultimate precision of Higgs properties 6



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The EOS has a GigaBit Transceiver (GBT) [31] that interfaces with the HCCs and a Versatile link (Vlink) [71]) fibre optic driver. LV and HV power connect to the EOS and are distributed to each hybrid via a power bus. A power interface connects each hybrid to the power bus. The nature of the power interface will depend upon which power architecture is chosen, either serial power or DC-DC conversion. There may be several detector slow control (DCS) links that communicate with each power interface from the EOS. DCS interlocks will also connect to the EOS from the overall ATLAS DCS system.