# MTCA.4 at DESY.

Uroš Mavrič on behalf of the DESY MTCA.4 Development. 8th meeting of the xTCA interest group, CERN, 17.03.2014





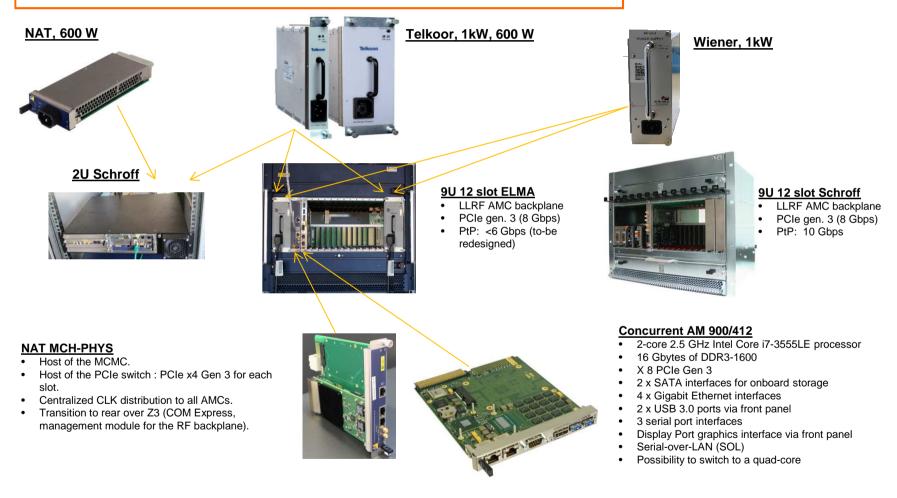
### Talk Overview.

- Hardware overview
- > Organization of the FPGA functionalities
- > Driver and software organization
- Management and interoperability
- > Applications



### **COTS HW Components.**

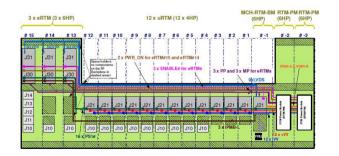
### Typical MTCA.4 crate configuration used at DESY.

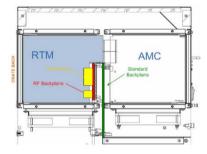


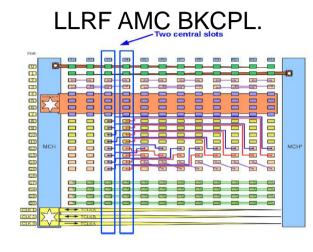


### Specific DESY/XFEL HW Demands.

- Vector sum systems require centralized slots with AMC cards that act as concentrators.
  - Modification of the standard PICMG AMC backplane.
  - LLL on ports 8-15 on slot 3,4 to all other slots.
  - Data throughput : 6.25 Gbps by 6 on Point-to-Point.
- Multichannel systems and limited space require compact signal distribution.
  - uRF Backplane located in the rear side of the standard MTCA.4 crate.
  - For the MCH, the uRF backplane is an extension of the front backplane.









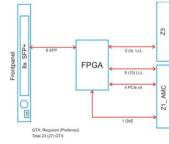
## **Typical AMC/RTM Pairs.**

#### DRTM-DWC10 / SIS8300L

- > 10 channel down-converter to IF (<80 MHz).
- > RF input 0.7 4 GHz
- > Variable attenuators
- > Low residual phase and amplitude noise.
- > 10 channels with 16 bit, 125 MSPS ADCs
- > Virtex 6, 4 x 4 Gbit DDR3

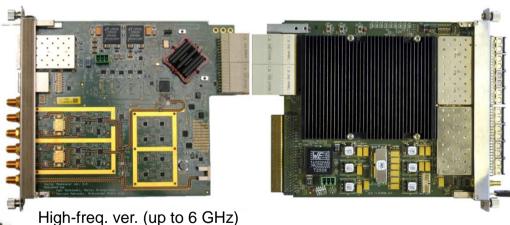
#### DRTM-VM2 / DAMC-TCK7

- > 2 I/Q modulators with RF switch driven by interlocks.
- > Spartan 6, 16- bit DACs
- > On-board CLK generation.
- > Data concentrator based on Kintex 7, 23 (27) GTXs.
- > LLL up to 12.5 Gbps.
- > PCIe Gen. 3 (16Gb/s/4 lanes)









Low-freq. ver. (0.1 – 1.5 GHz)



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### **General Purpose AMC Boards.**

#### DAMC-FMC25

- > A general purpose FMC Carrier
- > Two HPC connectors
- > Virtex 5 XC5VFX70T-2FF1136, DSP, application specific tasks, etc.
- > Spartan 6 XC6SLX45T-2CSG324I for on-board management

#### DAMC-FMC20

- > A general purpose low-cost FMC Carrier
- > One HPC connector and one LPC connector
- Spartan 6 XC6SLX45T (for PCIe conn.) and Spartan 6 XC6SLX150 (for appl. and Z3 conn.)

#### DAMC-DS800

- > Fast digitizer with 8 input channels at 0.8 GSPS or 4 at 1.6 GSPS
- > 4 x DACs
- > On-board fan-out for CLKs
- > Virtex 6







### Specific RTM boards.

#### DRTM-PZT4

- 4 power amplifiers with 0-100V, -100V/+100V
- > DAC outputs +/-5V, +/-10V, 0/5V, 0/10V
- > Each power amplifier can drive up to 10uF capacitance.
- > Remotely variable output analog filter
- > Possibility for external power supply

#### DRTM-LOG1300

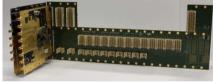
- > Generation of the LO and CLK signals from single REF input.
- > Distribution over uRF backplane.
- > Splitting of 3 RF signals to 9 x 3 RF outputs.
- > Fan-out of 22 LVPECL CLK signals.
- > Each RF and/or CLK channel can be switched off individually
- > Temperature control of the circuit via Peltier elements and TECs.

#### DRTM-DWC8VM1, DRTM-DS8VM1

- > Field detection and RF drive output on single RTM.
- Low frequency (direct sampling 5 MHz 450 MHz) and high frequency version (down conversion 0.7 – 6 GHz).
- > I/Q modulator with monitoring and RF switch.
- > On-board CLK generation via extr. REF or/and on-board VCXO.













### More FMC/RTM Cards.

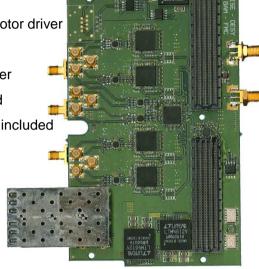
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#### DFMC-MD22

- Dual channel stepper motor driver
- LPC connector
- Includes motion controller
- > Monitoring of motor load
- Protection mechanisms included

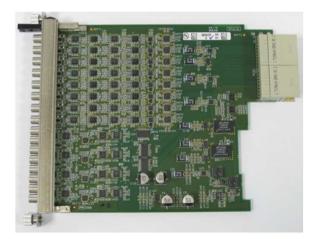


#### DFMC-BAM

Two ch. with interleaved sampling of 2 ADCs.

>

On-board CLK distribution and phase shifting

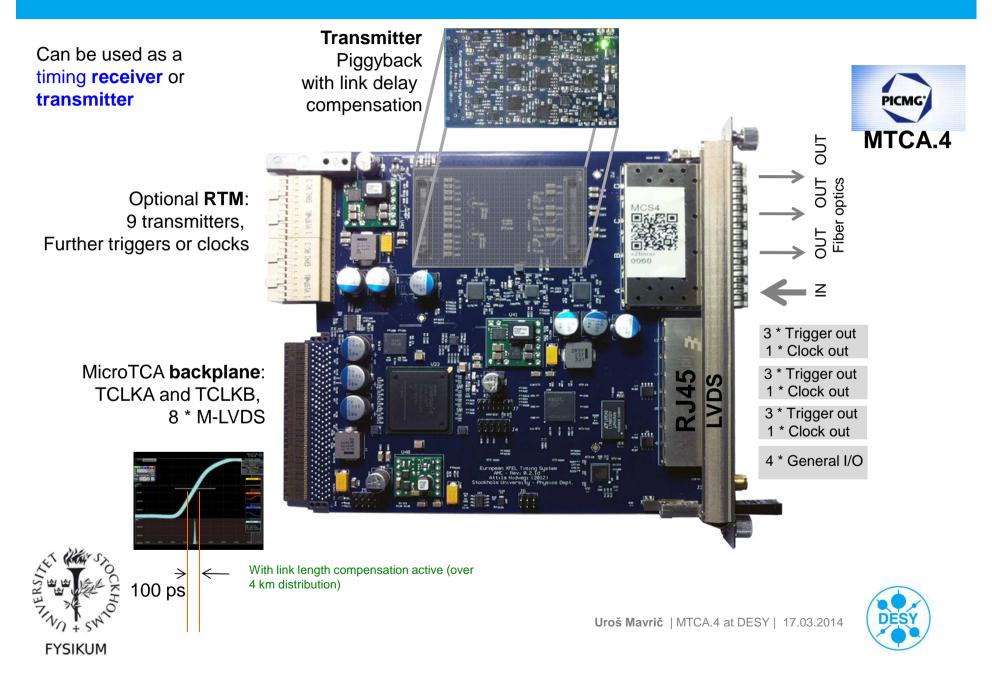


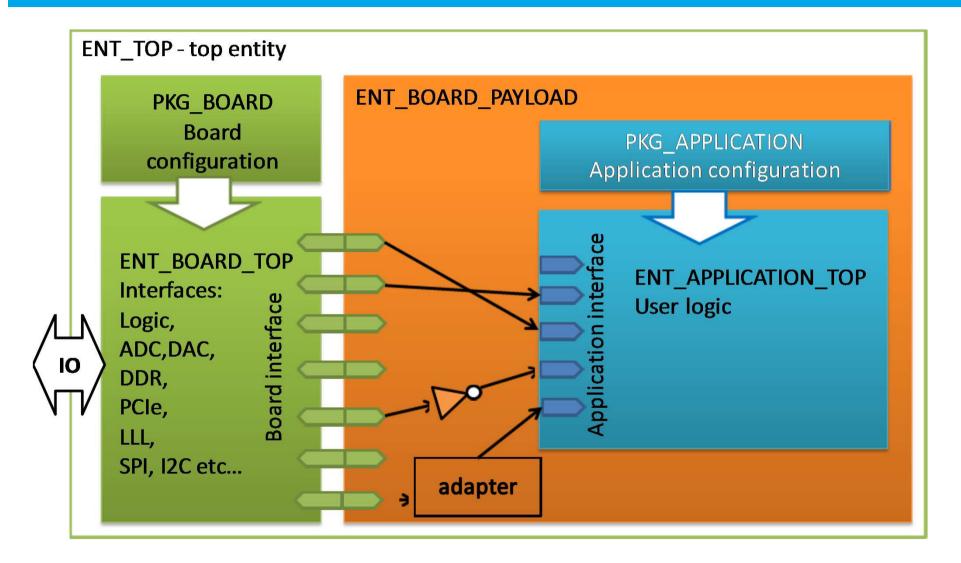
#### DRTM-AD84

- > 8 ADCs 10 MSPS, 4 DACs 1 MSPS
- > ADC : DC-95 MHz input BW, switchable ADC input impedance
- > DAC : DC-1 MHz output BW, 50 ohm output impedance



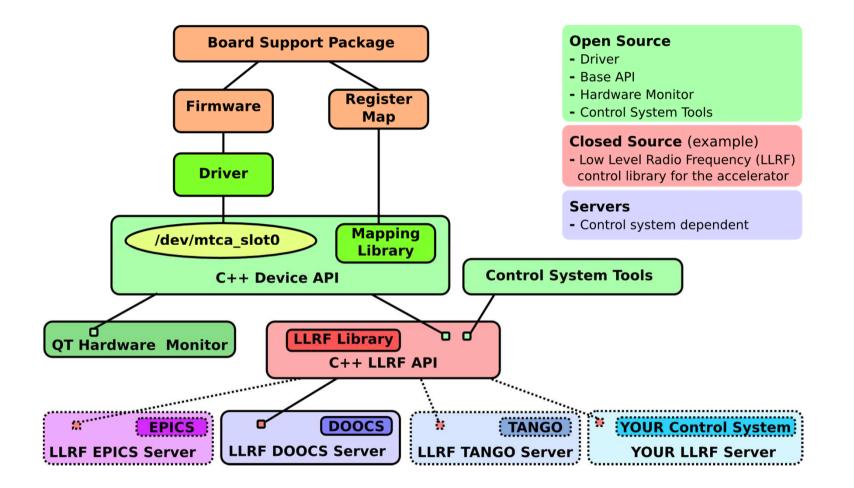
### ps Timing System for XFEL and FLASH





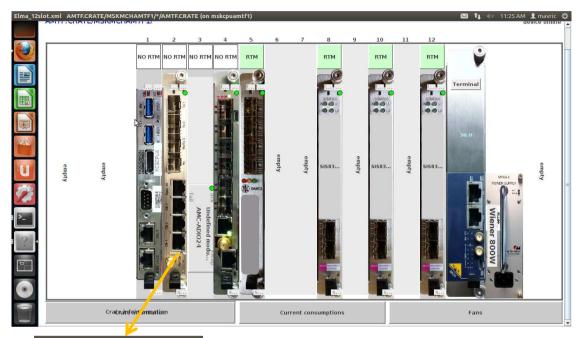


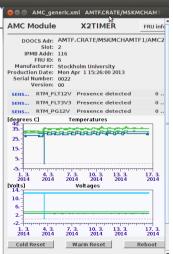
### SW and Driver.





### **Platform Status Monitoring.**





- jDDD based graphical interface for remote monitoring the HW status over IPMI (temperatures, voltages, currents, FRU information, HP status etc.)
- Individual board deactivation, remote crate/board restart, etc.



### **Platform Related Activities.**

- Platform related issue and Interoperability were a major "showstopper" at the beginning:
  - Platform management related (FW and HW)
  - Debugging in collaboration with industry
  - Long debugging periods
- > MTCA interoperability workshop
- > 2,5 years of debugging in collaboration with industry
- > Tracking of bugs:
  - RT (<u>https://rt-system.desy.de/</u>) ~80 bugs reported and solved
  - Redmine (<u>https://mskllrfredminesrv/projects/mtca4platform/issues?set\_filter=1&tracker\_id=1</u>)
  - DESY Log-book (<u>http://ttfinfo.desy.de/uTCAelog/index.jsp</u>) a list of bugs and procedures

Regular bi-weekly meetings on Tuesdays (e.g. tomorrow 18.03.2014) starting at 9:15.

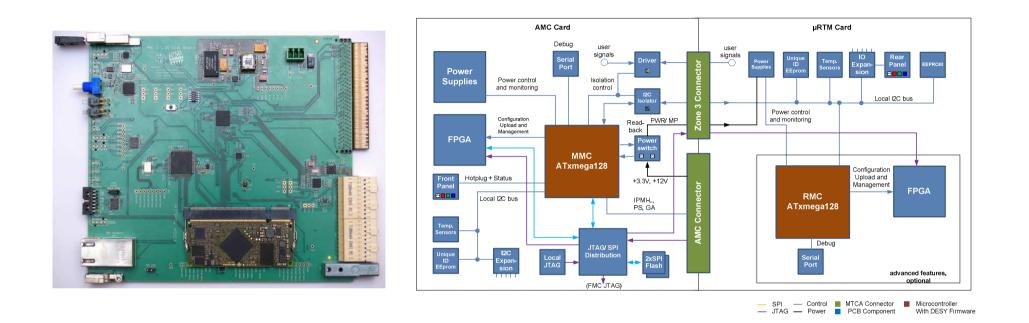
Everyone welcome to join!

Skype : mtca.4\_meeting

Emal : uros.mavric@desy.de



### MMC1.0.



- > MMC1.0 unifies the MMC functionality (HW and FW) on all the presented boards.
- It offers a tested, ready-to-use solution for the AMC and RTM management controllers and tackles demands of various complexities (advanced and basic versions).
- > A test/demo board is being tested and will be available (with FW).



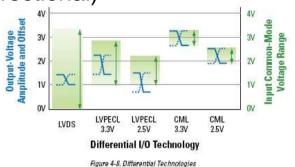
### Zone 3 Classes Recommendations in MTCA.4.

https://mtca.desy.de/resources/zone\_3\_recommendation/index\_eng.html

- > Class A1.x mainly for analog signal transmission over Zone 3
- > Class D1.x for digital signal transmission over Zone 3
- Recommendation no standardization to be open for future signal types
- > Requires AMC FPGA module based,
  - 2 ADF 30 pair (Mid-size) connectors
  - Class A1.x and D1.x needs not to be compatible



- Supports LVDS, LVCMOS, OC, CML, analog differential
  - Digital signals (single-, diff.-ended, bi-directional)
  - Analog signals
  - High-speed links
  - non-FPGA low-jitter clock signals
  - non-FPGA signals with fixed direction
  - ps-stable timing signals





# **MTCA.4 in Practice at DESY.**

### LLRF systems at FLASH, AMTF, CMTB, REGAE,...









### Electro-optical detector





Laser Synchronization



