



Track based alignment of the ATLAS Silicon Tracker



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on behalf of the ATLAS ID Alignment group

LHC

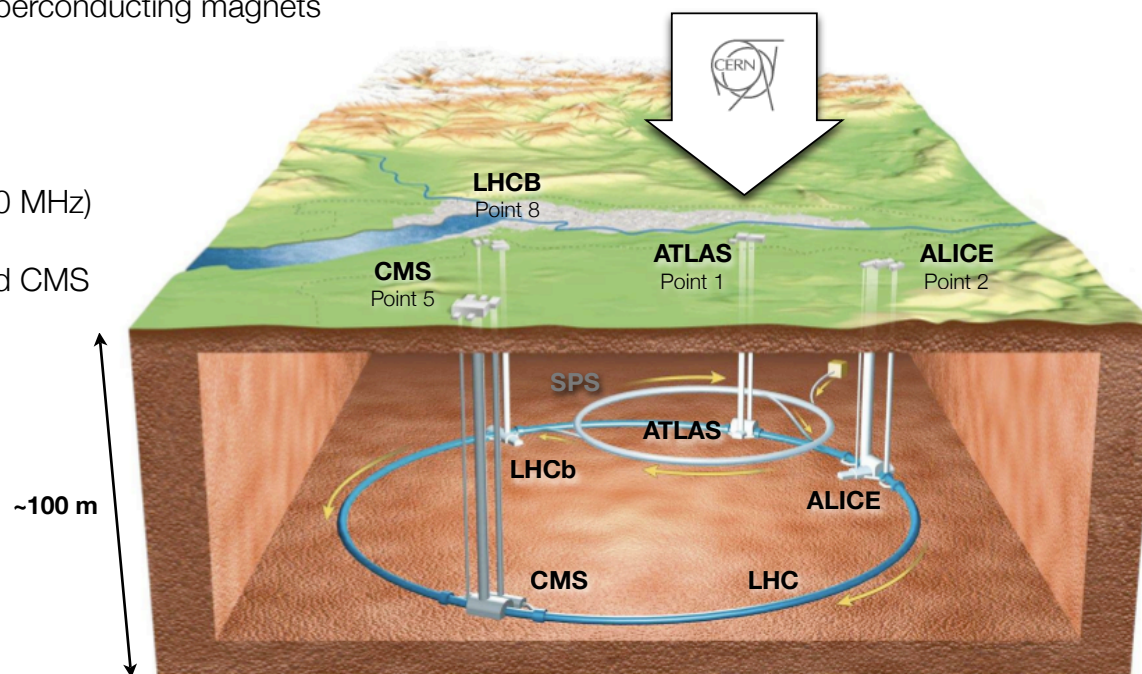
Large Hadron Collider (LHC)

- **It is a *pp* accelerator:**

- 7 TeV per beam
 - 5 TeV at start-up, 2008
- 27 km of circumference with superconducting magnets
 - B field: 8.33 T
 - Temperature: 1.9 K
- Design luminosity: $10^{34} \text{ cm}^{-2} \text{ s}^{-1}$
 - In 2008, $10^{31} \text{ cm}^{-2} \text{ s}^{-1}$
- Bunch crossings every 25 ns (40 MHz)
- 4 Experiments:
 - General purpose: ATLAS and CMS
 - B Physics: LHCb
 - Heavy ions: ALICE

- **Main Physics program:**

- Precise Standard Model (SM)
 - Top quark measurements
- Higgs Searches
- SUSY Models
- Extra Dimensions
- Microscopic Black Holes



Expected start-up summer 2008!

Would happen one of the following days... ;-)

ATLAS Experiment

A Toroidal LHC Apparatus (ATLAS)

Muon System

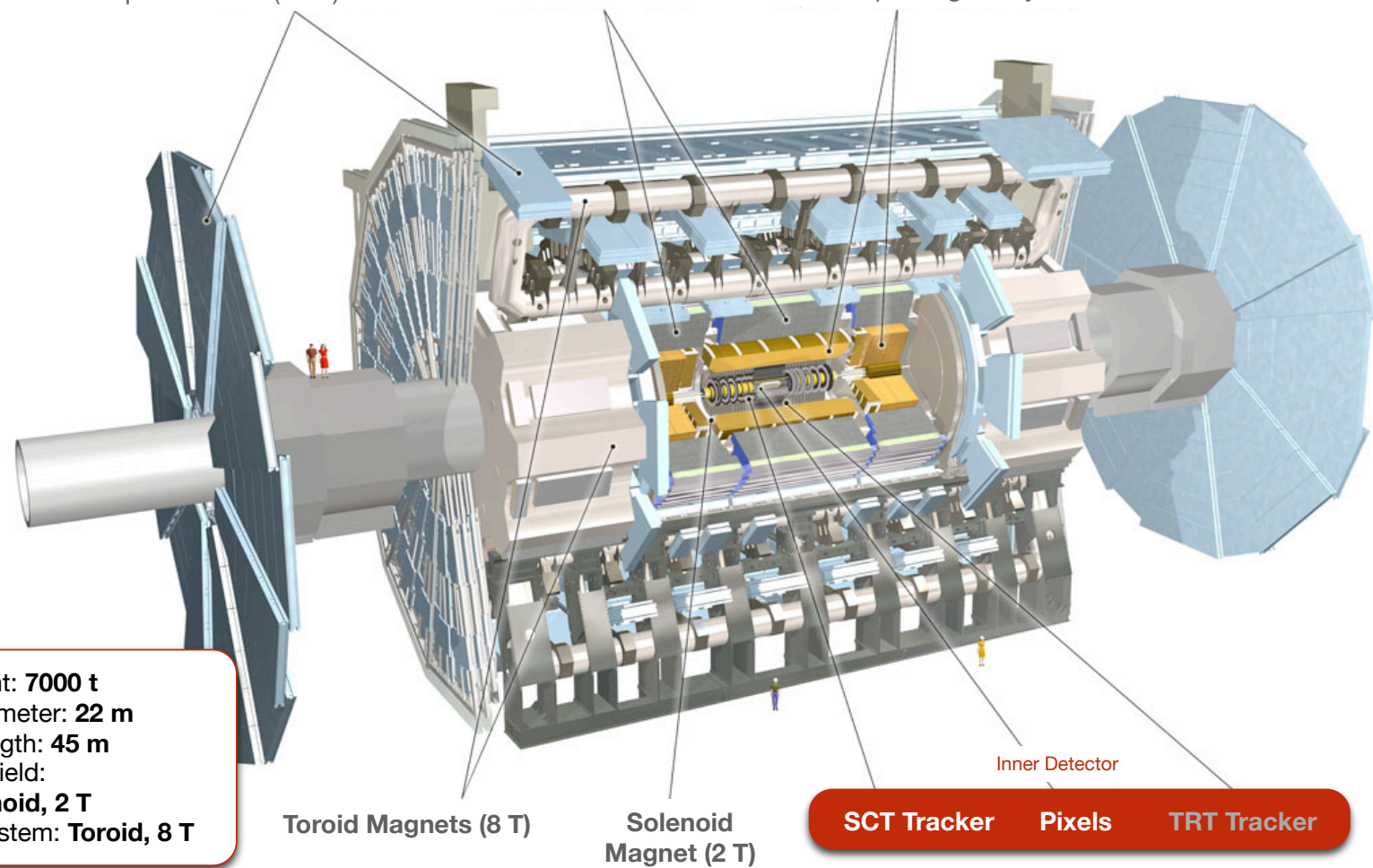
Monitored Drift Tube Chambers (MDTs)
Cathode Strip Chambers (CSC)

Hadronic Calorimeter

Tile Calorimeter Modules

Electromagnetic Calorimeter

Liquid Argon Cryostat



ATLAS Inner Detector

Inner Detector (ID)

Efficient track reconstruction, precise momentum measurement and vertex determination (b-tagging).

Three technologies used, all mounted in Barrel/EndCaps layout:

● Pixel detector

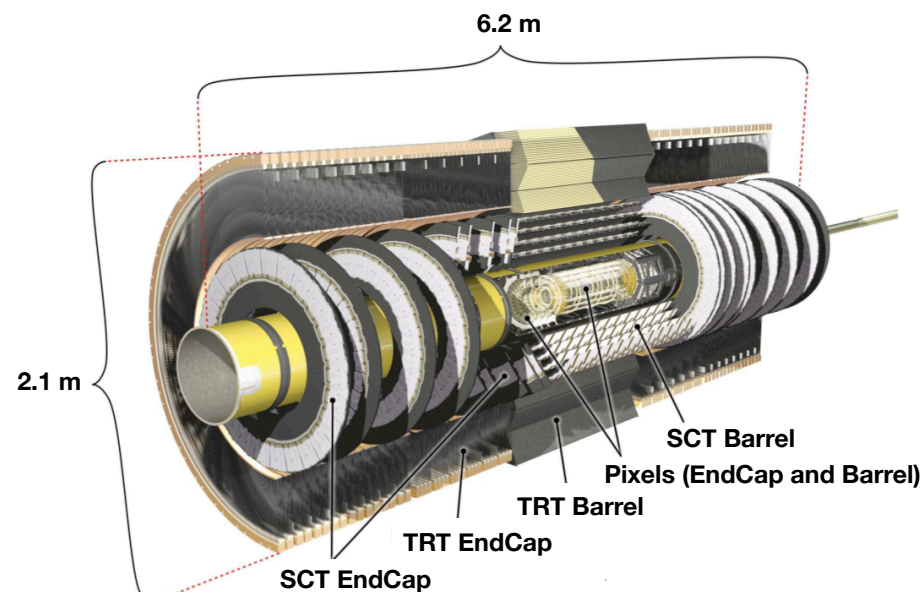
- Silicon pixels
- Size: $(50 \times 400) \mu\text{m}^2$
- Single module design
- Analogue readout
- Intrinsic point resolution: $(14 \times 115) \mu\text{m}$
- 3 layers (Barrel) and 2x3 disks (EndCaps)

● SemiConductor Tracker (SCT)

- Silicon microstrips
- Strip pitch:
 - $80 \mu\text{m}$ (barrel)
 - $57\text{--}90 \mu\text{m}$ (endcap, fan-out structure)
- Barrel and EndCap module design: 5 topologies
- Binary readout
- Intrinsic resolution: $23 \mu\text{m}$
- 3D spacepoint by stereo angle (resol. $580 \mu\text{m}$ in Z)
 - Barrel: 4 layers (Barrel) and 2x9 disks (EndCaps)

● Transition Radiation Tracker (TRT)

- Gaseous drift tubes with gold wire
- Straw tube diameter: 2 mm
- Time dependence: Drift time
- Straw resolution: $170 \mu\text{m}$
- 96 modules in 3 layers (Barrel)
- 35 hits per track on average

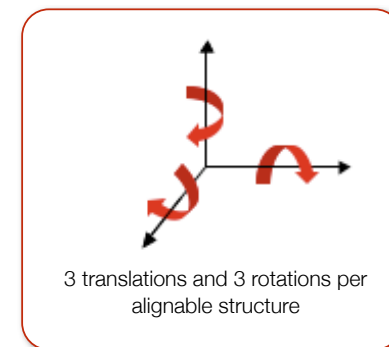


	Pixels	SCT	TRT
Technology	Silicon pixels	Silicon microstrips	Gaseous drift-tubes
Modules	1744	4088	988
Intrinsic resolution	$\sim 14 \mu\text{m}$ (r Φ) $\sim 115 \mu\text{m}$ (z)	$\sim 23 \mu\text{m}$ (r Φ)	$\sim 130 \mu\text{m}$ (r Φ)

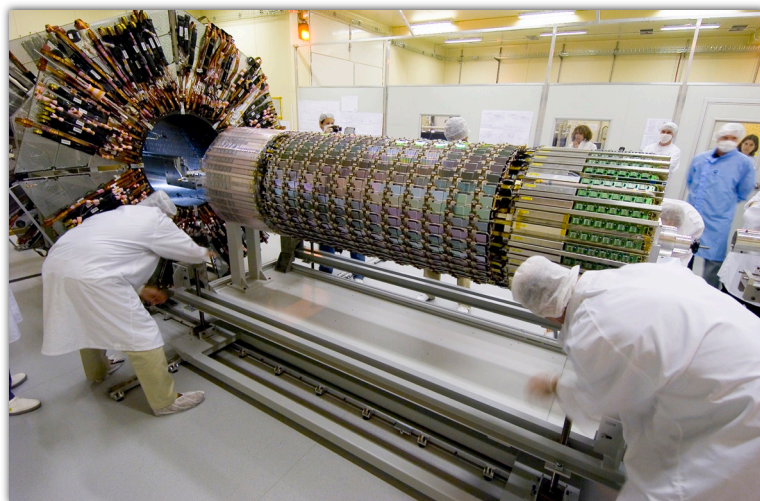
Silicon Alignment Challenge

To achieve the ATLAS physics goals, we need...

- Exploit the excellent intrinsic resolution of our precision tracking devices.
 - Mounting and survey precision $O(100\text{ }\mu\text{m})$, depending on subdetector.
- Requirements
 - Don't degrade resolution of track parameters $> 20\%$
 - Systematic error $M(W) < 15\text{ MeV}/c^2$
 - b-tagging efficiency drops by 10% with a misalignment of $O(10\text{ }\mu\text{m})$, so...
- We need high accuracy alignment: precision in $r\Phi < 10\text{ }\mu\text{m}$
- **Ultimate precision reached with track-based alignment algorithms!!!**



I will focus on just the Silicon Alignment....



	Barrel		EndCap	
Detector	Pixels	SCT	Pixels	SCT
Nbr. of Layer/Disks	3	4	2x3	2x9
Nbr. of modules	1456	2112	2x144	2x988
Subtotal	3568		2264	
Total	5832			

5832 modules \rightarrow **34992 DoFs**

- 6 DoF per module (rigid body)
- Large number of DoFs to solve!

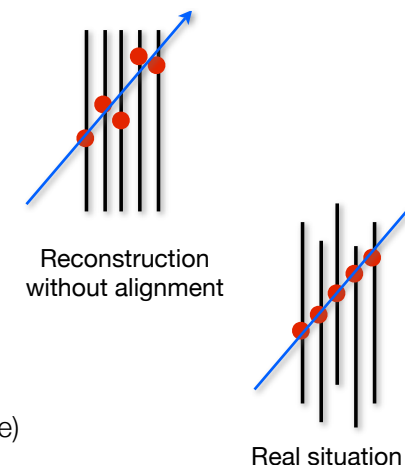
What's next? bows and bends

- Due to temperature, B fields and material load

Track-based alignment

Several approaches implemented within the ATLAS software framework (called Athena)

- Nowadays, we use independent alignment algs for silicon and for the TRT
 - Relative alignment of the TRT wrt the silicon by track extrapolation
 - Working on the unification
- Implemented methods for Silicon:
 - **GlobalChi2:**
 - In-plane residuals use to build the chi2 to minimise: 6 DoF per module
 - Correlations managed, therefore small number of iterations
 - Inherent challenge of large matrix handling and solving (35k x 35k): whole system in one step
 - **LocalChi2:**
 - Similar to GlobalChi2 (particular case, in theory), but inversion of small 6x6 matrix (one per module)
 - No inter-module nor MCS correlations (diagonal covariance matrix), but 6 DoF per module
 - Large number of iterations to get compensate the lack of correlations
 - **Robust:**
 - Centres residual and overlap distributions without minimisation (histogramming method^h)
 - Use weighted residuals, z and r overlap residuals of neighboring modules
 - 2 or 3 DoF within plane (x, y, gamma)
 - Intrinsic iterative procedure (many iterations)



covariance matrix (V)

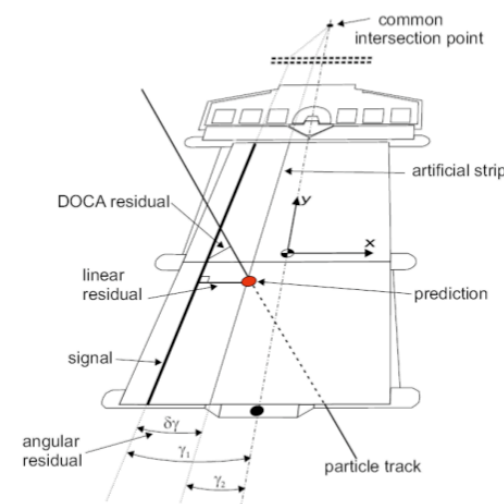
$$\chi^2 = \sum_{tracks} r^T V^{-1} r$$

$$\frac{d\chi^2}{da} = -M^{-1}v$$

vector residuals: $r = r(\pi, a)$

- π : track parameters
- a : alignment parameters

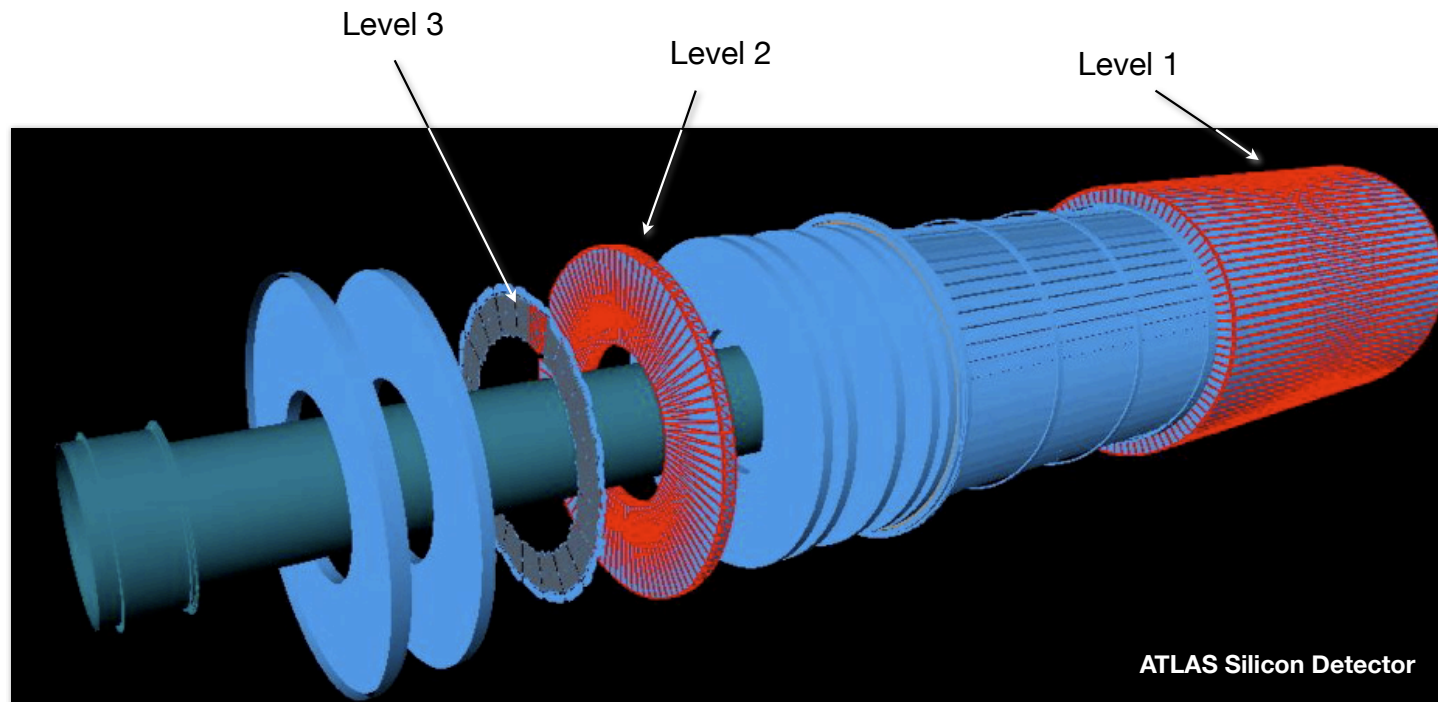
• For the GlobalChi2, requires inversion of a symmetric 35k x 35k matrix



Track-based alignment

Alignment Levels

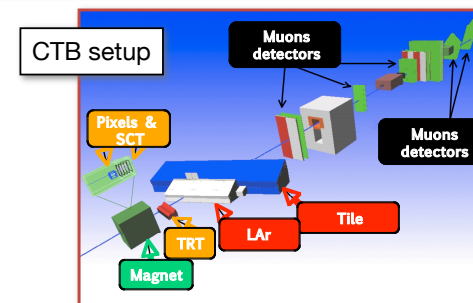
- Detector description in terms of geometrical primitives (GeoModel)
 - Logical volumes grouped in hierarchical nodes
 - Alignment infrastructure based on alignable nodes
- Three different alignment levels:
 - Level 1: entire subdetectors (whole Pixel, SCT barrel and end-caps)
 - Level 2: silicon layers & disks
 - Level 3: silicon modules



Earlier Alignment Tests: CTB and SR1 Cosmics

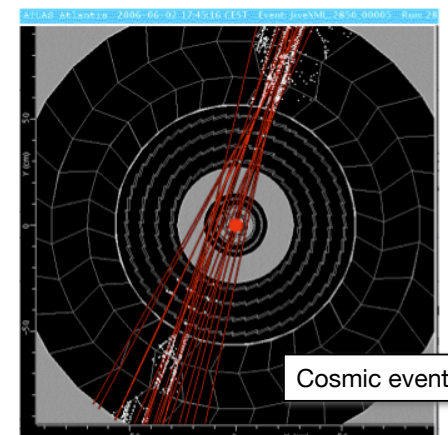
Combined TestBeam (2004)

- First ever 'ATLAS data' from subsystems combined
 - Large statistics (~20M tracks) at different beam momenta (2-180 GeV/c²)
 - e⁺, e⁻ and π with (1.4 T) and without magnetic field
- Challenge: small setup, collimated beam through narrow tower of modules
 - (just an ATLAS barrel slice, so certain DoFs unconstrained)
- Achived resolution: 5 μm for Pixels and 10 μm for the SCT
- Results submitted to JINST: arXiv:0805.3984v1 [physics.ins-det]

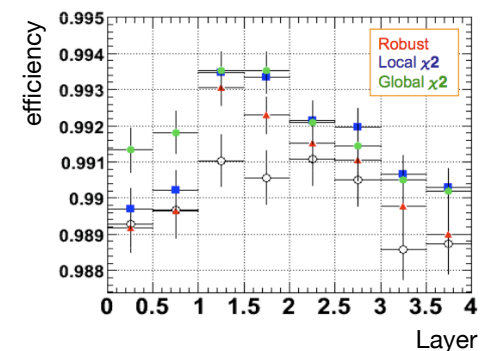
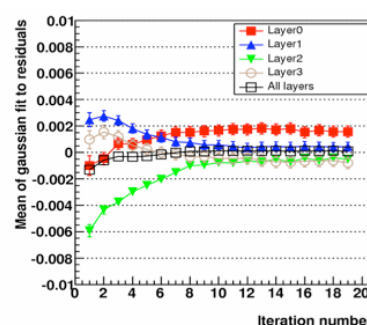
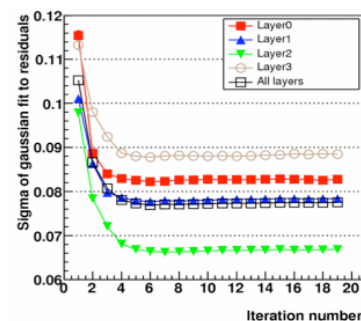


SR1 Cosmics (2006)

- First ever 'SCT+TRT cosmic data'
 - Data-taking at surface (SR1 clean room)
 - 22% of the SCT Barrel and 13% of the TRT Barrel
 - ~400k events recorded
 - No B field → No momentum estimation
 - MSC important for tracks with $p \leq 10$ GeV/c² (Spectrum dominant)
 - Larger residuals than CTB
- Challenge for alignment: small setup, collimated beam through narrow tower of modules (certain DoFs unconstrained)

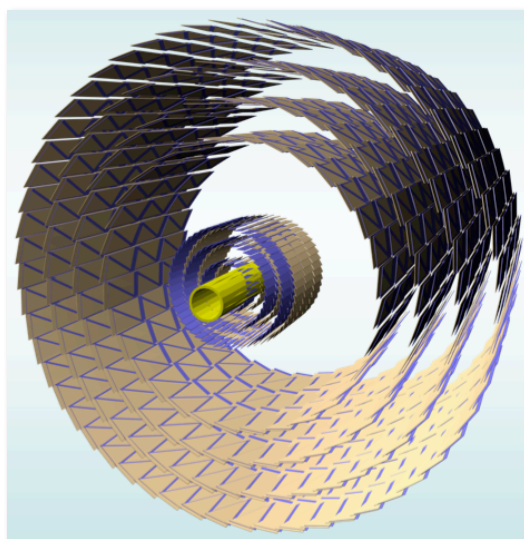


Alignment
convergence for
SR1 Cosmic run
alignment

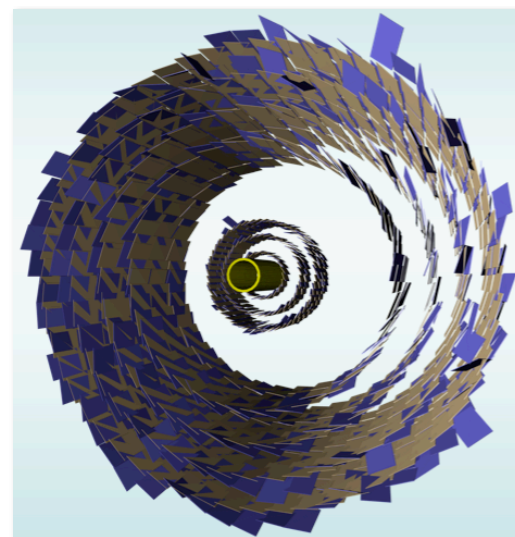


Computing System Commissioning (CSC)

- First ever simulations using realistic as-built geometry
- Testbed for the ID algorithms to test its performance and to get ready for real conditions
 - All physics productions performed with misaligned geometry
- Underlying hardware reflected in structure of alignment constants
 - CSC misalignments:
 - Shifted and rotated magnetic field
 - Misalignments at all levels:
 - Level 1: Translations $O(1 \text{ mm})$, Rotations $O(0.1 \text{ mrad})$ - Surveyed $O(\text{several mm})$
 - Level 2: Translations $O(100 \text{ }\mu\text{m})$, Rotations $O(1 \text{ mrad})$ - Surveyed $O(100 \text{ }\mu\text{m})$
 - Level 3: Translations $O(100 \text{ }\mu\text{m})$, Rotations $O(1 \text{ mrad})$ - Surveyed $O(30\text{-}100 \text{ }\mu\text{m})$



Ideal ATLAS Silicon Barrel Detector



Misaligned ATLAS Silicon Barrel Detector
(Displacements exaggerated by a factor 100)

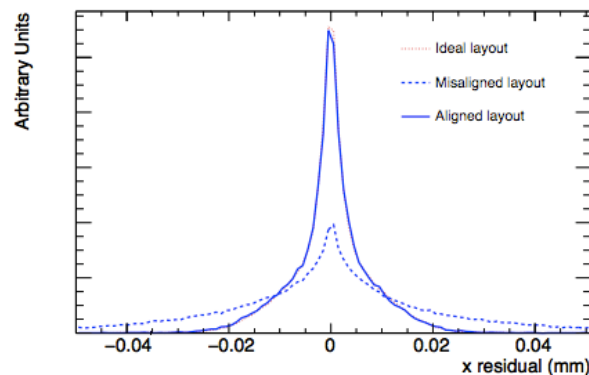
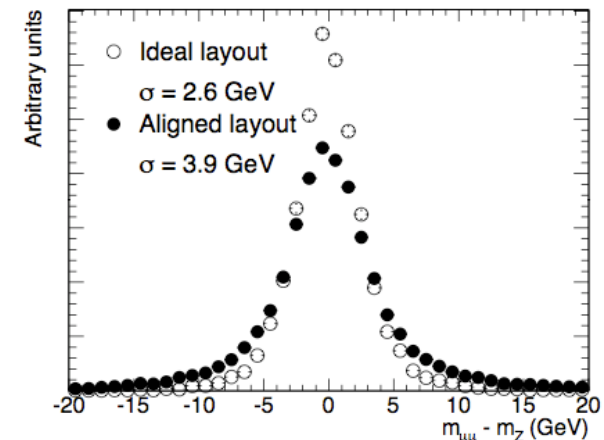
Computing System Commissioning (CSC)

Alignment Performance

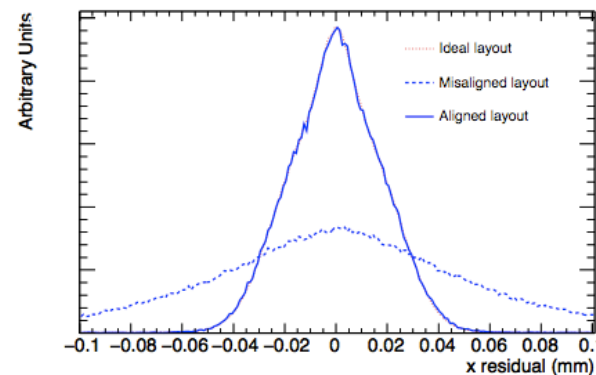
Algorithms converging (almost perfect residuals)

Using a multimMuon sample

- 10 muons/event
- $\sigma_{xy} = 15 \mu\text{m}$; $\sigma_z = 56 \text{ mm}$
- $p_T = [2, 50] \text{ GeV}/c^2$
- O(100) plots to validate the alignment results/convergence
- InDetAlignMonitor (athena package) and GlobalChi2 monitor (root macros)
 - Ideal layout means as-built geometry
 - Misaligned layout means nominal geometry
 - Aligned layout was after running our alignment algorithms
- What do we learn?
 - Improved residuals do not mean that the detector is correctly aligned
 - We discovered that our track parameters were biased because of the systematic effects (weak modes)
 - algs cannot fix them: need additional constrains and handles (more studies are required) → *off-axis events*



(a) Pixel barrel



(b) SCT barrel

CSC and Milestones

Cosmic tracks simulations

High momentum tracks ($> 2 \text{ GeV}/c^2$)

Simulations done and available with and without magnetic field

- No B-Field \rightarrow constrains pT biasing modes

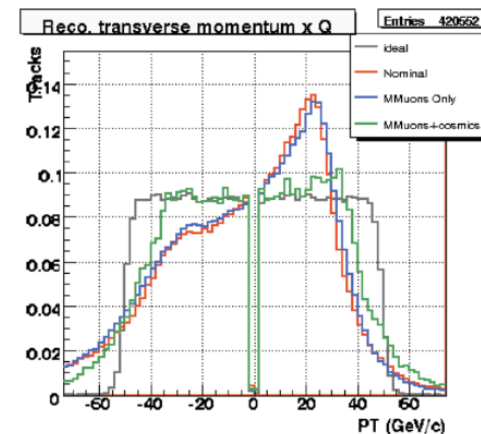
Introduce correlations between top and bottom hemisphere \rightarrow constrains telescope mode

Off-axis \rightarrow constrains twist, elliptical distortions

Low rate (MC simulation: 0.5 Hz through Pixel barrel), non-uniform illumination

Real data taking in the pit: Milestone weeks (M6)

- Commissioning in the cavern using cosmic rays without B field
 - Very low statistics
- SCT barrel module misalignments were better than expected!



Adding cosemics improved the momentum reconstruction

Beam Halo and Beam-gas events

Recently, beam halo events have been considered.

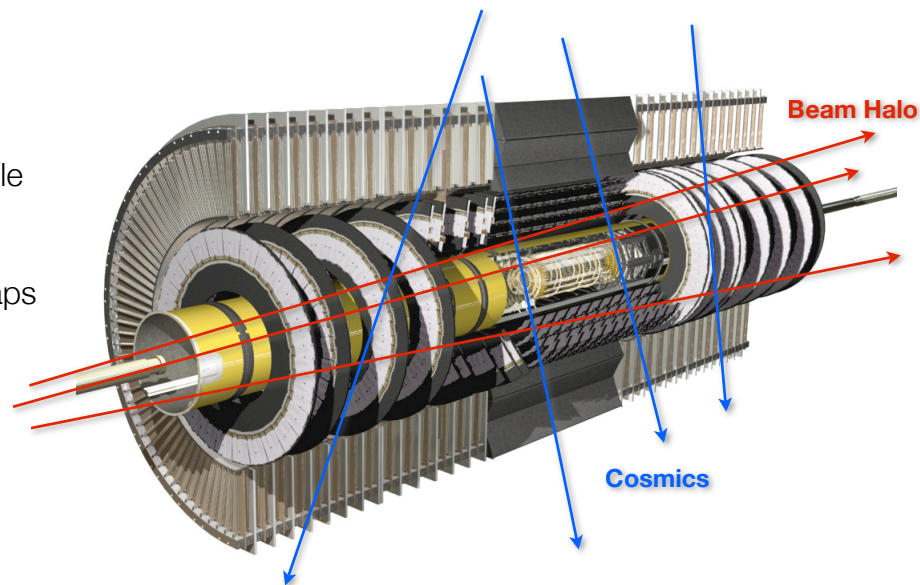
- Simulations with detector misalignments are available
- Need to be studied

Complementary events (in angle) to Cosmic rays

Cosmics good for Barrel and Beam Halo good for EndCaps

How to trigger?

- Using the Hadronic Calorimeter (TileCal)
- Expected rate: $\sim 10 \text{ Hz}$



Full Dress Rehearsal (FDR)

The latest challenge where the alignment team has tested the alignment algorithms is the Full Dress Rehearsal (FDR). It is an exercise where the full data acquisition chain is tested, emulating a data sample roughly equivalent to one day or more of real data-taking

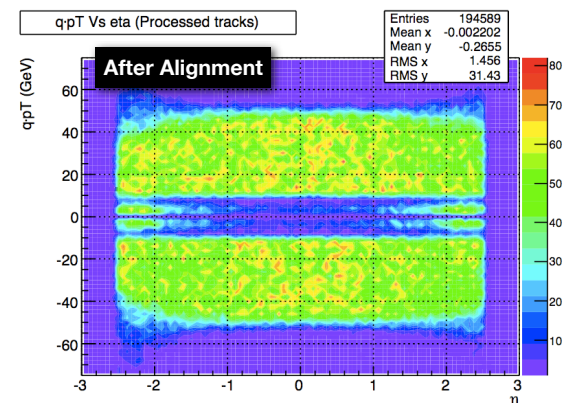
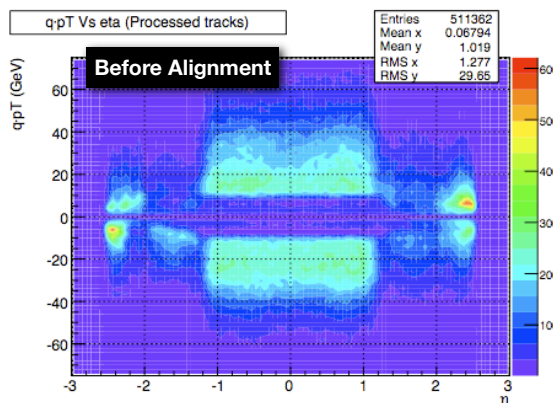
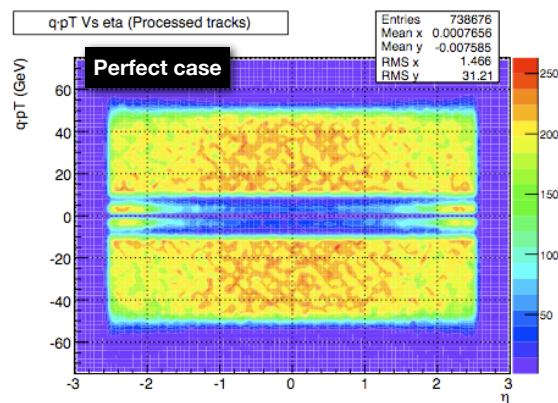
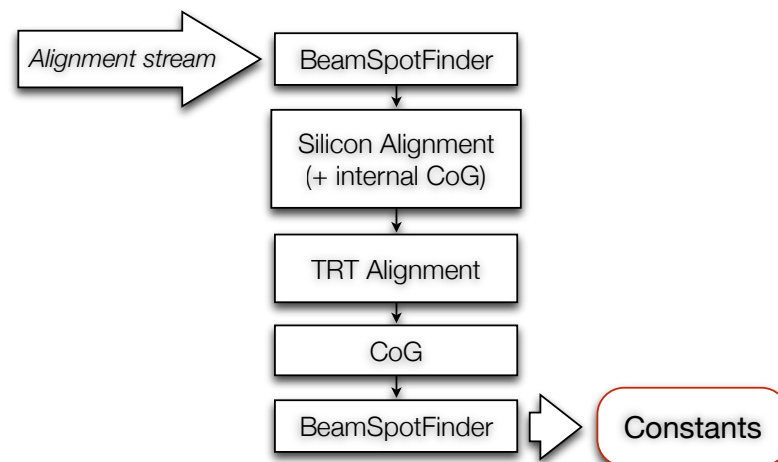
- Goal: Run the whole ATLAS computing system as for real data and try to find early the problems we'll have with data

Phases:

- FDR1 run (1 week starting 4th February 2008)
- FDR2 run (1 week starting 2^{on} June 2008)
- FDR2a run (1 week starting 22^{on} July 2008)

FDR for alignment:

- Use the idcalibration stream:
 - 1M Single track events (single pions) with $p_T=[10, 50]$ GeV/c
 - 41k Cosmic events (~11k tracks) with B field
- Parallel environment: 80 CPUs



Weak Modes

Global Distortions, so-called Weak Modes

By definition the weak modes are such movements that the track-based residual minimisation (with collision tracks) cannot resolve, because they leave the χ^2 unchanged.

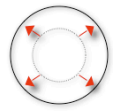
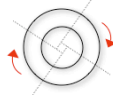

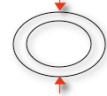
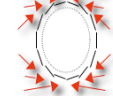


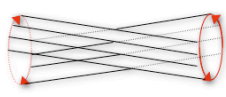
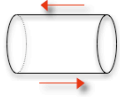
It is not question of maths, the only option is the use of 'extra' information, generally called 'external constrains'

Candidates:

- Common vertex for a group of tracks
- Constrains on track parameters or vertex position (external tracking, resonant mass, etc...)
- Off-axis events: Cosmic rays, Beam Halo / Beam Gas tracks
- External constrains on alignment parameters: survey data, hardware systems (FSI), etc...

Weak Mode Study Strategy

- Simulations with global distortions on top of them
 - Some of them have been already produced and propagated to physics/performance groups.
 - We must evaluate systematic uncertainty on measurements originating from systematic deformations

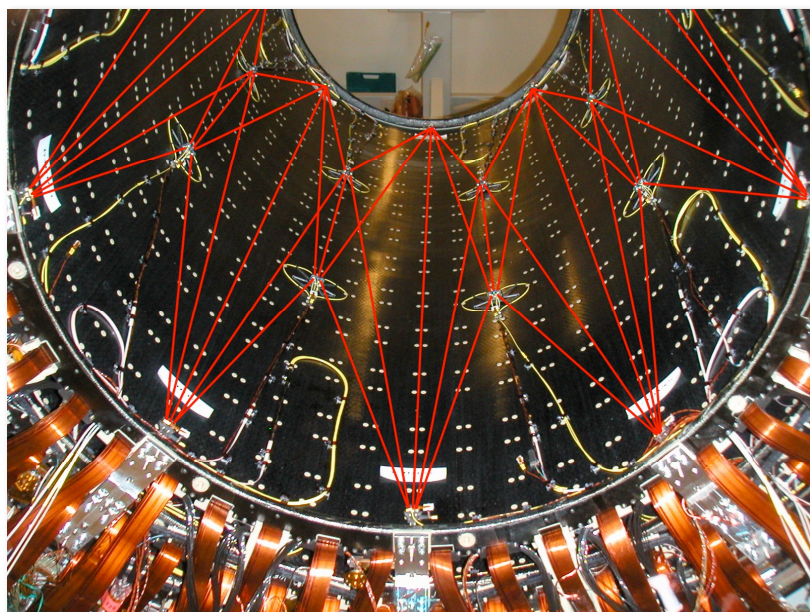
	ΔR	$\Delta\phi$	ΔZ
R	Radial Expansion (distance scale) 	Curl (Charge asymmetry) 	Telescope (CM boost) 
ϕ	Elliptical (vertex mass) 	Clamshell (vertex displacement) 	Skew (Z momentum) 
Z	Bowing (total momentum) 	Twist (vertexing) 	Z expansion (distance scale) 

Hardware-based alignment

Frequency Scanning Interferometry (FSI)

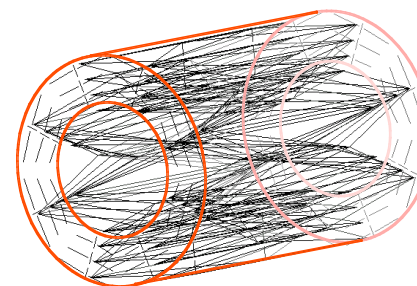
Geodetic grid of 842 simultaneous length measurements in between nodes on the SCT structure

- Distance measurements between grid nodes precise to $\sim 1 \mu\text{m}$
- 3D grid geometry can be reconstructed to a precision of $< 5 \mu\text{m}$ in the critical direction
- Will be used intensively before and during the early runs
 - track-based alignment and FSI interplay has to be tested
- Already installed and tested in the ATLAS cavern
 - All grid lines have been illuminated and read out



Time + spatial frequency sensitivity of FSI complements track based alignment:

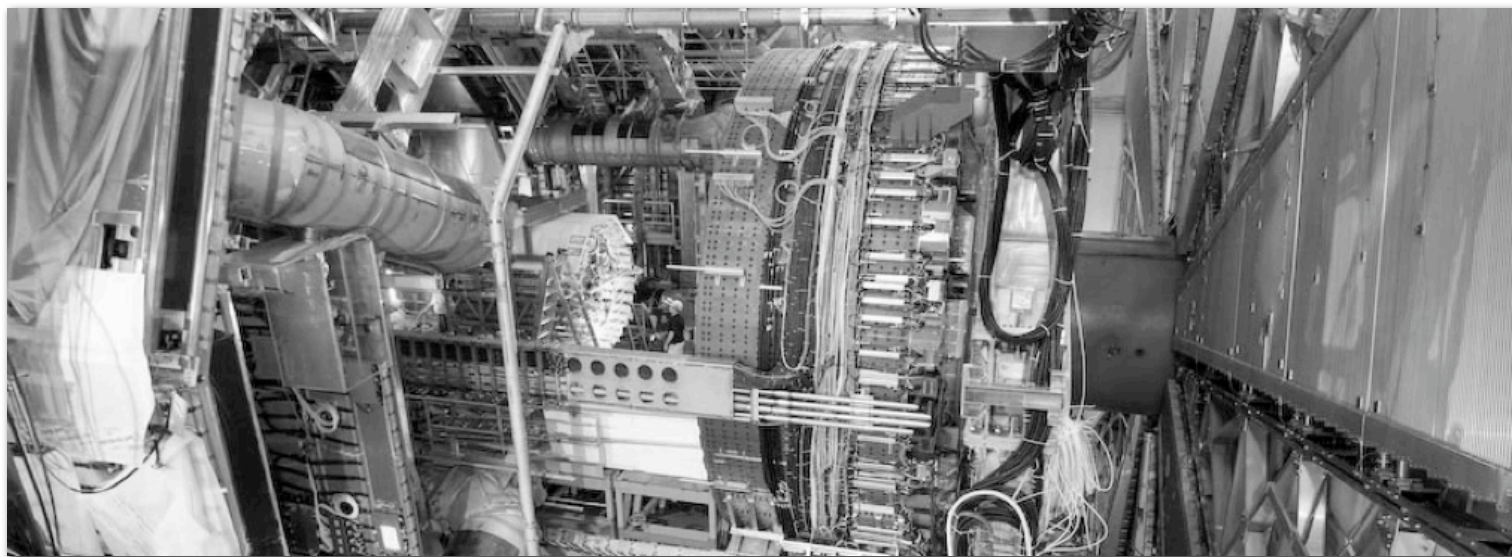
- Track alignment average over $\sim 24 \text{ h}$
- FSI timescale: $\sim 10 \text{ min}$



SCT Barrel Grid (512 measurements)

Summary

- Various alignment algorithms are adapted to optimally align the ATLAS Silicon Tracker
 - TRT uses similar algorithms
- All track-based approaches are ready and have been proved, tested and validated with simulation and real data
 - Real Data
 - Combined Testbeam, CERN SPS H8 beamline, 2004
 - SR1 Cosmic run, at the surface, 2006
 - Milestone 6, cosmics in the pit, 2008
 - Simulations
 - Simulations with as-built geometry (expected misalignments at three levels)
 - Computing System Commissioning (CSC)
 - Physics stream (collision samples) and alignment stream (multimuon sample)
 - Cosmics in the pit with/without magnetic field
 - Beam Halo events
 - Full Dress Rehearsal
 - Final tests before the LHC start-up
 - The full alignment chain is tested during these exercise
 - Run the whole ATLAS computing system as for real data and try to find early the problems we'll have with data
- We realised that weak modes were very important issues, therefore...
 - Weak Modes are very important for the determination of alignment constants
 - Performing systematic studies from simulations to determine the effect on physics observables
- Frequency Scanning Interferometry (FSI) is ready to play its role with early data
 - Track-based alignment and FSI interplay will be tested



Thank you for your attention

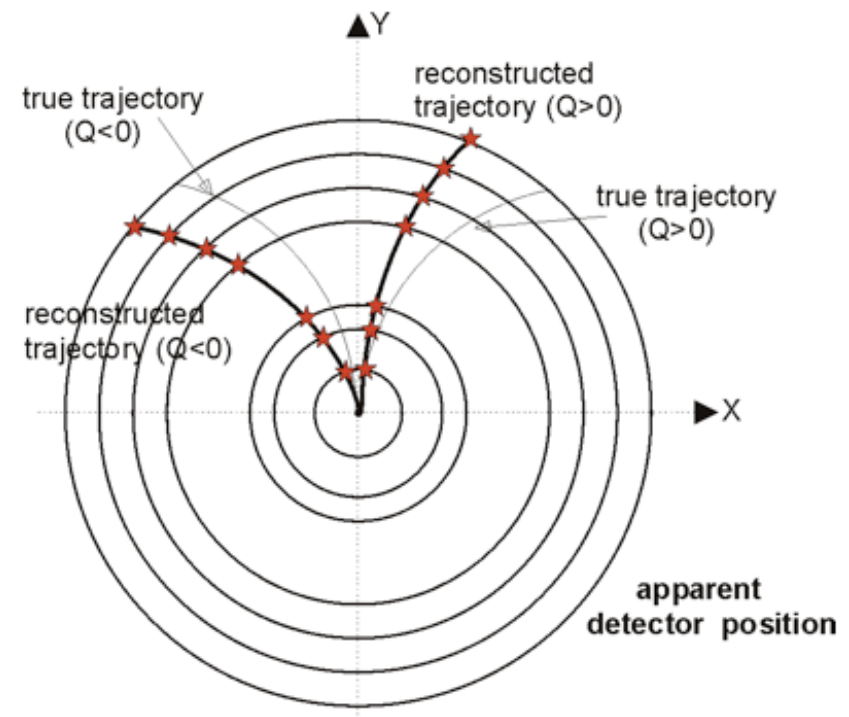
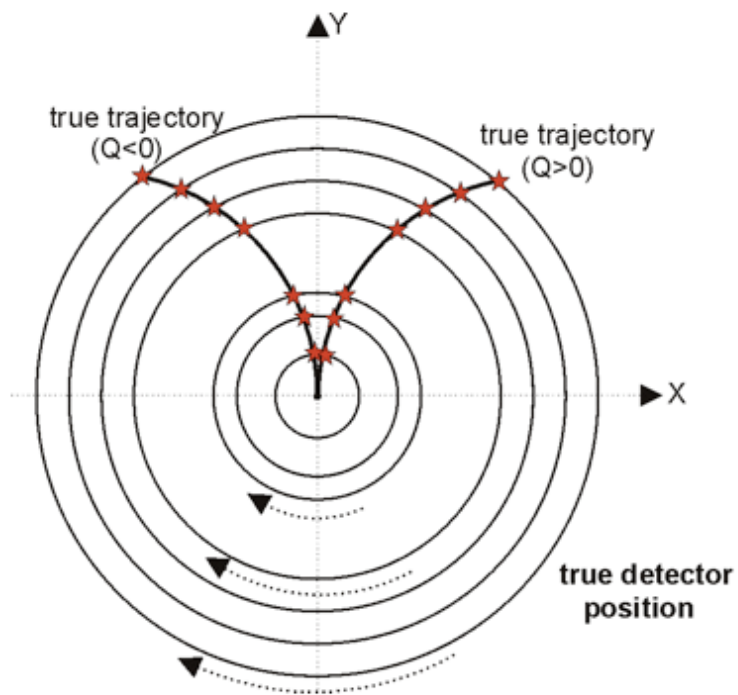


Backup slides

Weak Modes: example

Sagitta distortions


- Bias in track parameters \rightarrow *but helical path maintained*
- χ^2 of the tracks blind to these global deformations
- Produce momentum asymmetries



The GlobalChi2 Approach

The method consists of minimizing the giant Chi2 resulting from a simultaneous fit of all particle trajectories and alignment parameters:

$$\chi^2 = \sum_{\text{tracks}} r^T V^{-1} r \quad \text{where} \quad r \equiv (\vec{e}(\pi, a) - \vec{m}) \cdot \hat{k}$$


 Intrinsic measurement error + MCS

Let us consequently use the linear expansion (we assume all second order derivatives are negligible). The track fit is solved by:

$$\pi = \pi_0 + \delta\pi = \pi_0 - \left(\frac{\partial e^T}{\partial \pi_0} V^{-1} \frac{\partial e}{\partial \pi_0} \right)^{-1} \frac{\partial e^T}{\partial \pi_0} V^{-1} r(\pi_0, a)$$

while the alignment parameters are given by:

key relation

$$\frac{d\chi^2}{da} = 0 \quad \Rightarrow \quad \sum_{\text{tracks}} \frac{dr^T}{da} V^{-1} r = 0$$

$$\frac{dr}{da} = \frac{\partial r}{\partial a} + \frac{\partial r}{\partial \pi} \frac{d\pi}{da}$$

$$\delta a = - \underbrace{\left(\sum_{\text{tracks}} \frac{\partial r^T}{\partial a_0} W \frac{\partial r}{\partial a_0} \right)^{-1}}_{\mathcal{M}} \underbrace{\sum_{\text{tracks}} \frac{\partial r^T}{\partial a_0} W r(\pi_0, a_0)}_{\mathcal{V}}$$

$$W \equiv V^{-1} \hat{W} \equiv V^{-1} - V^{-1} E (E^T V^{-1} E)^{-1} E^T V^{-1} \quad E \equiv \frac{\partial e}{\partial \pi_0}$$