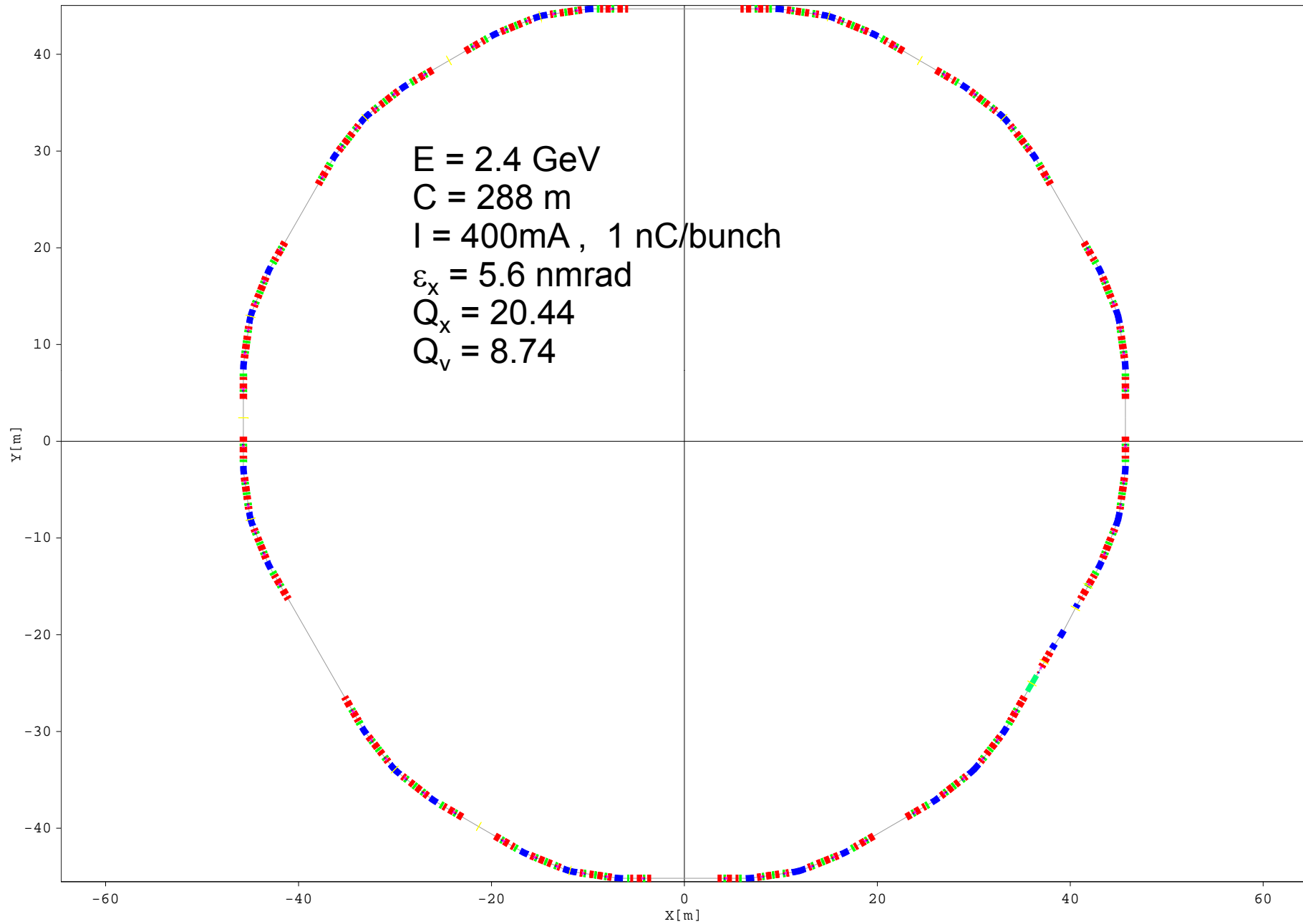


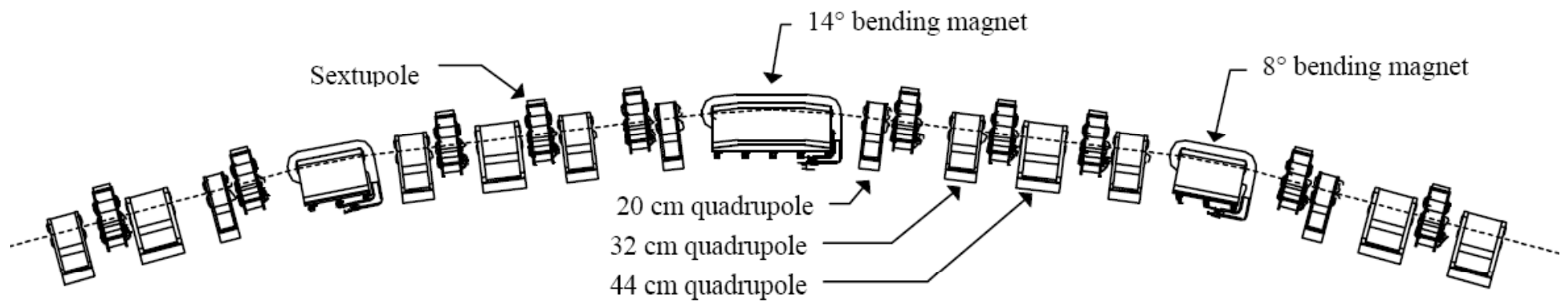
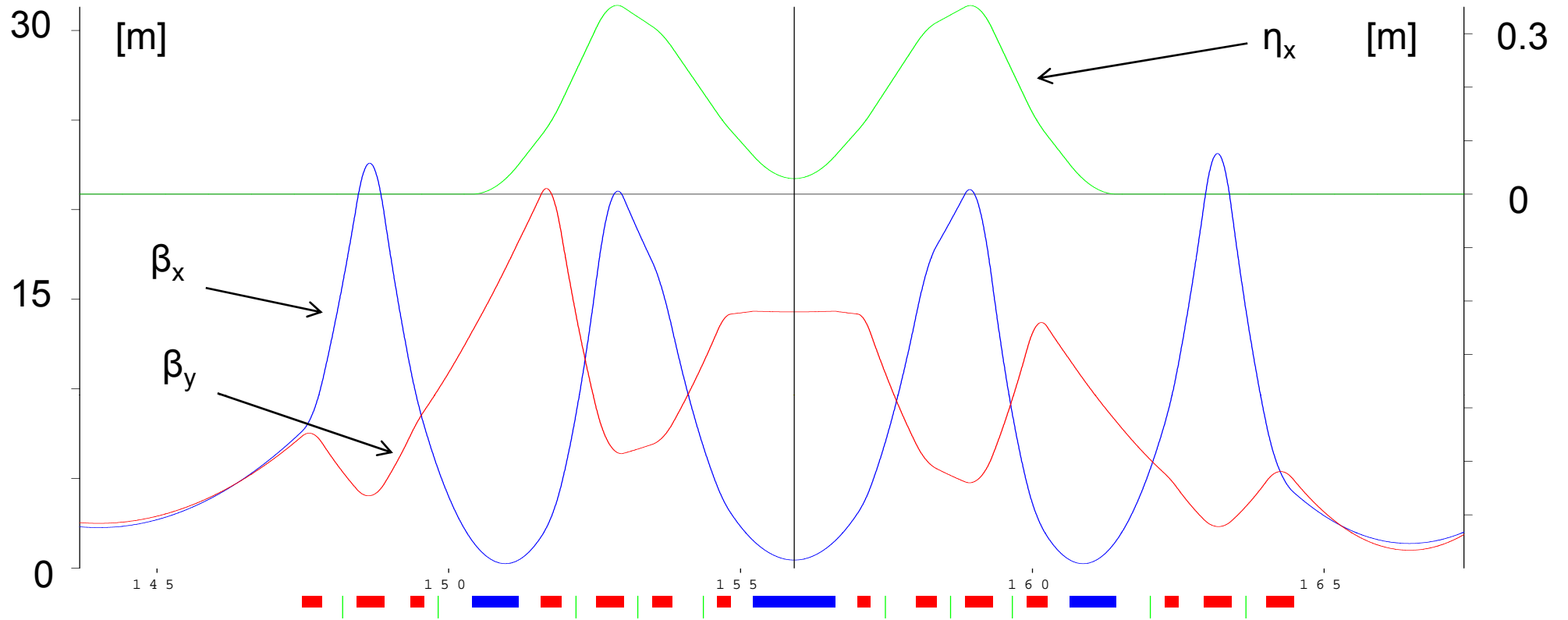
High Precision Emittance Measurements and Coupling Suppression in the SLS



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Emittances:
$$\varepsilon_{x,y} = \left(\sigma_{x,y}^2 - (\eta_{x,y} \sigma_\delta)^2 \right) / \beta_{x,y}$$

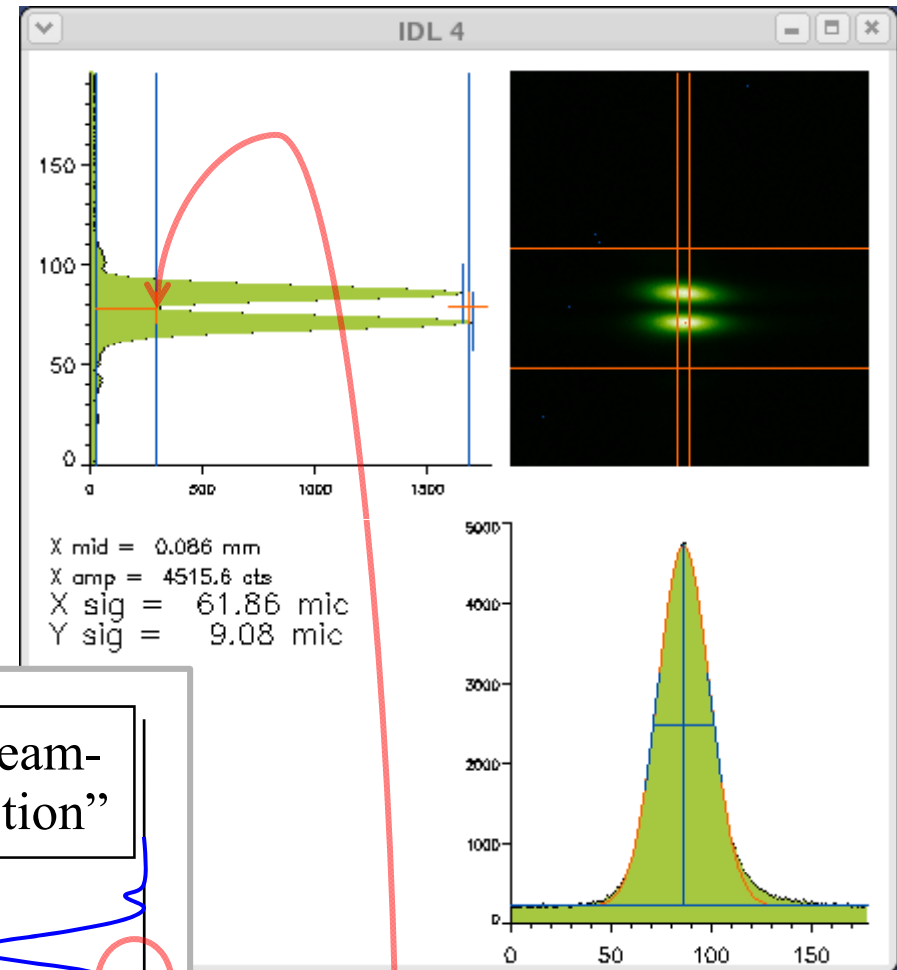
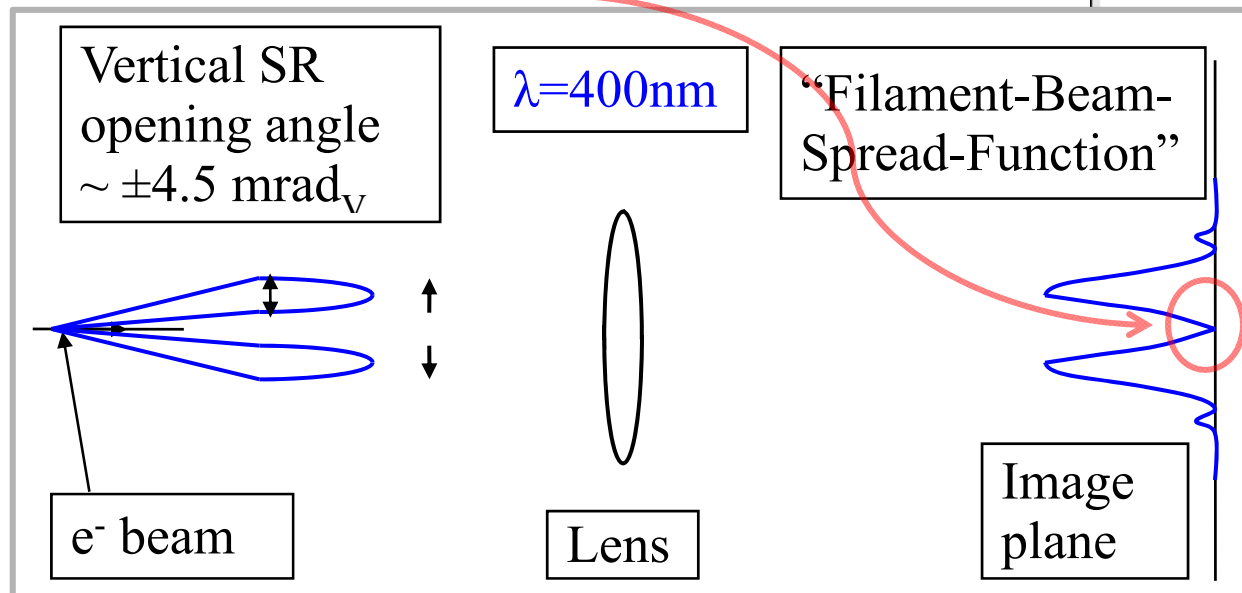
In the centre of the middle bending magnet we measure:

- Horizontal and vertical rms beam sizes, $\sigma_{x,y}$, and beam tilt angle.
- Horizontal and vertical dispersions $\eta_{x,y}$.
- We perform an entire measurement of the (average) horizontal and vertical beta functions in all 177 quadrupoles (1%, 0.5% rms precision), and use these to fit the model beta functions. The model gives the beta functions, $\beta_{x,y}$, in the centre of the dipole.
- The natural rms energy spread, σ_δ , is assumed to within 10%, since the beam shows longitudinal stability. Verified by streak camera measurement.

Beam size measurement

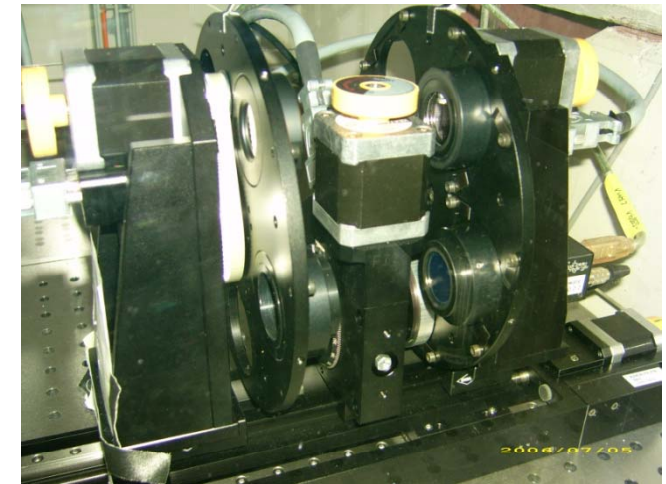
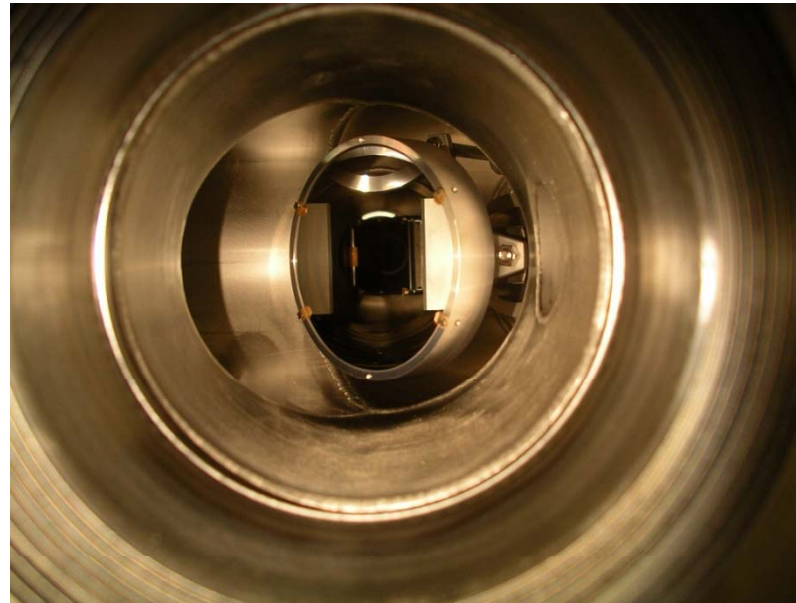
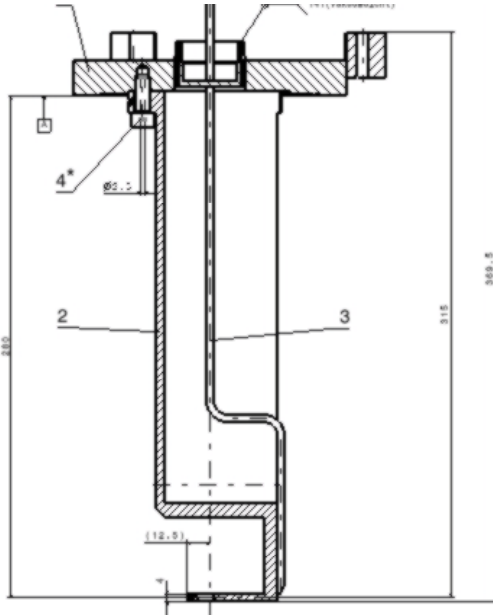
The π -polarization method^(*):
An image of the beam is formed from vertically polarized visible-UV synchrotron radiation.

A π phase shift between the two radiation lobes $\implies I_{y=0}=0$ in "FBSF"

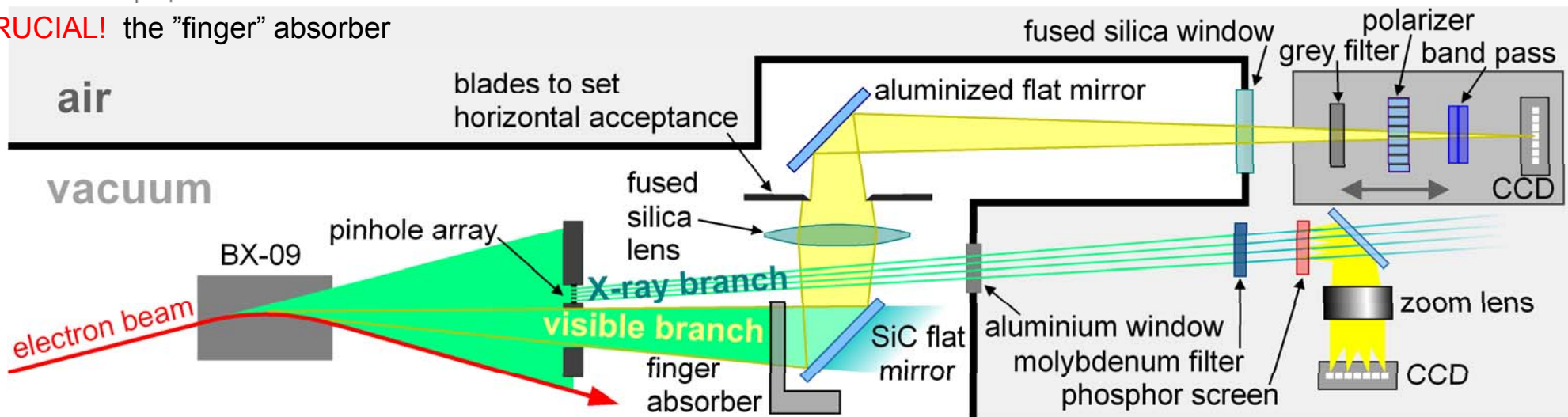


Finite vert. beam size \implies
Non-zero central intensity

Beam size measurement: beamline components

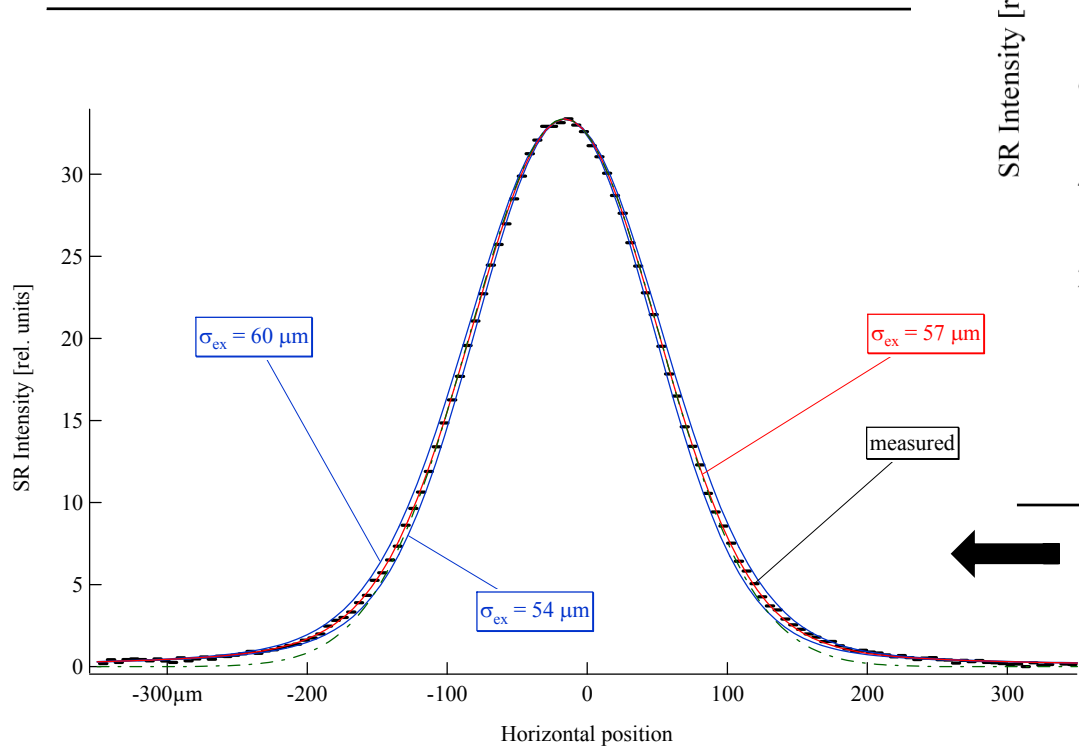
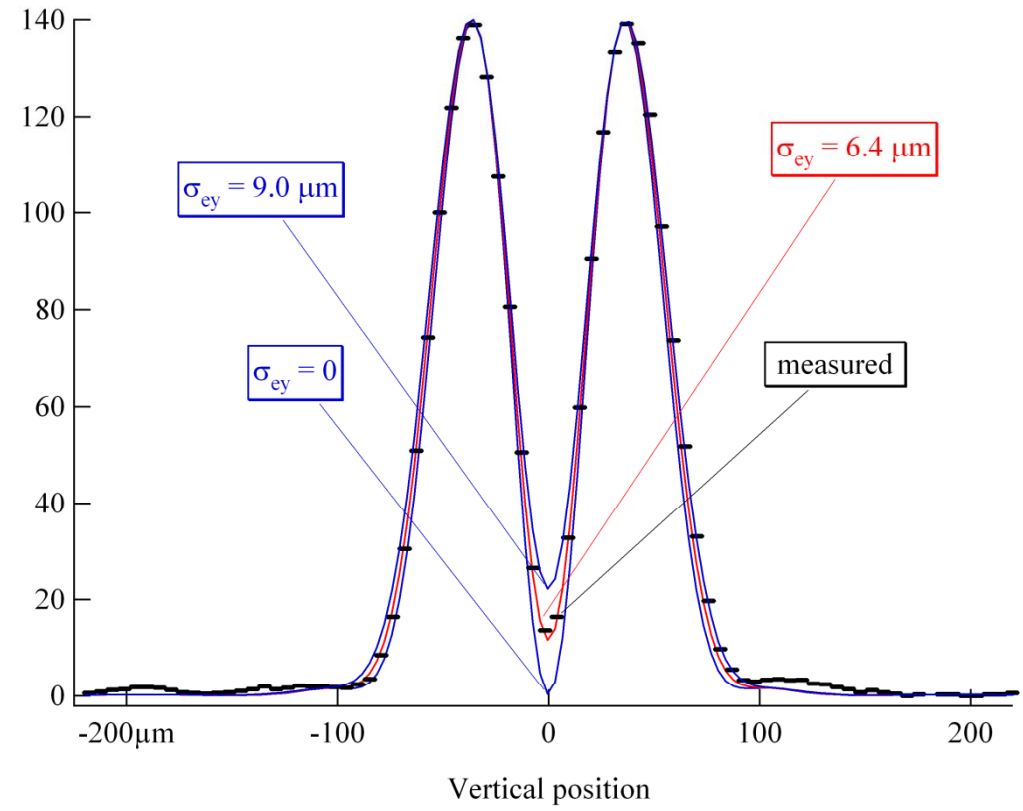


CRUCIAL! the "finger" absorber



Beam size measurement: precision

Vertical: Predicted profiles (SRW*) for beam height values 0, 6.4, 9.0 μm , and measured. Statistical rms error = 0.1 μm



Horizontal: Predicted profiles (SRW) for beam width values 54, 57, 60 μm , and measured. Statistical rms error = 0.3 μm

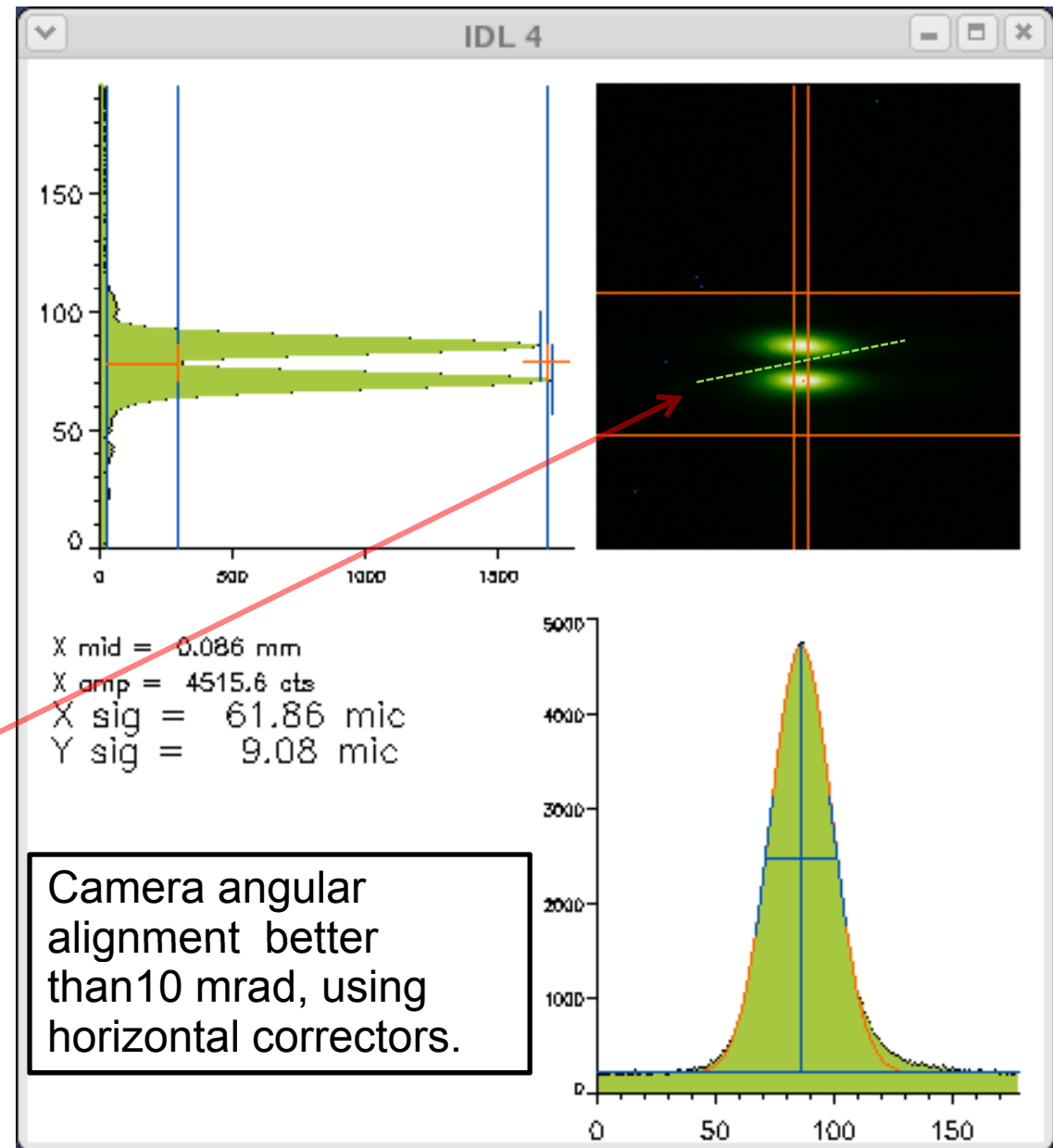
Dispersion measurements

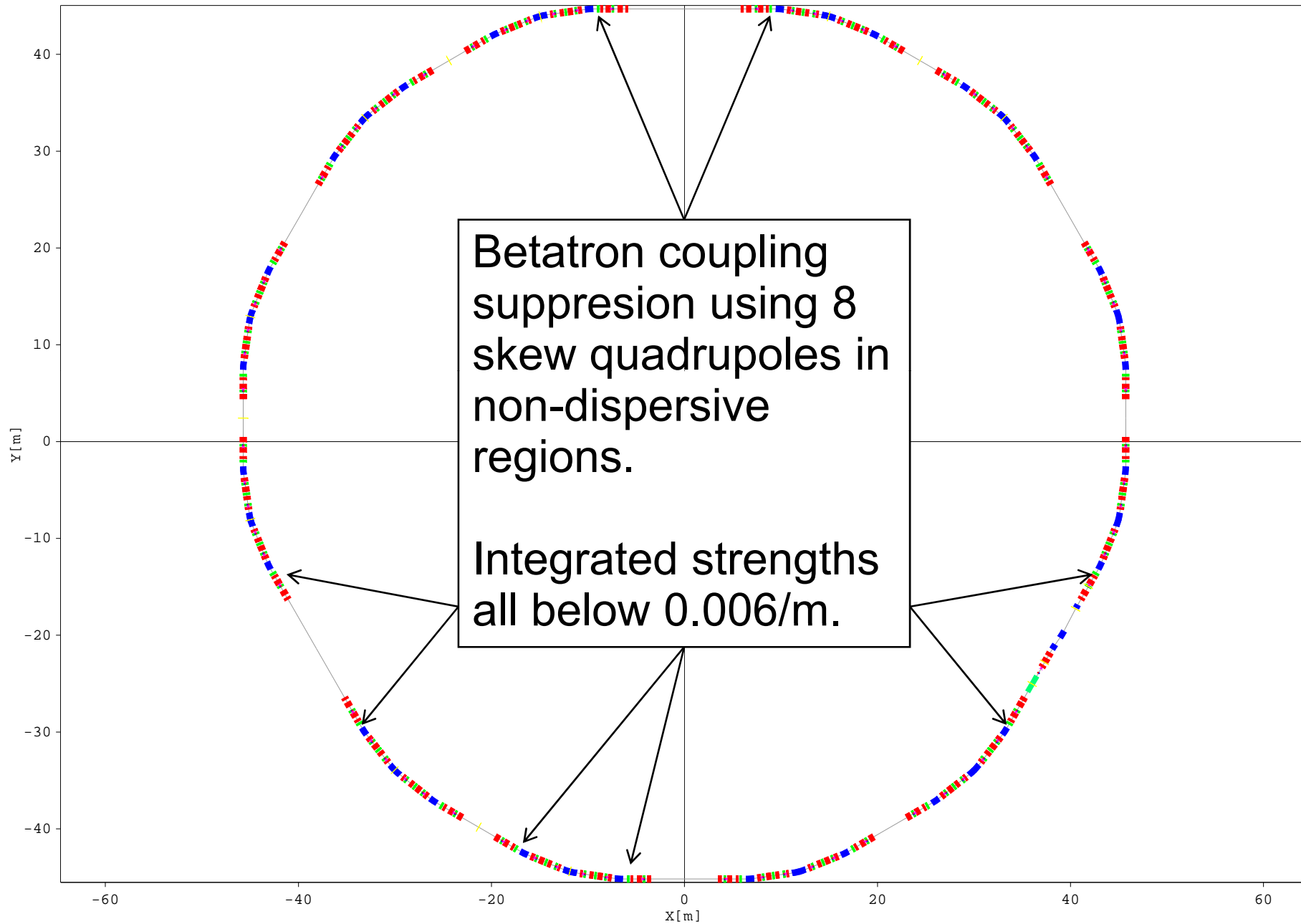
□ Dispersions are measured *in the same source point*, by tracking the image "centre of gravity"-movement for small RF changes.

□ ± 500 Hz \Leftrightarrow (α known)
 $\Delta E/E = \pm 0.165\%$ \Rightarrow
 $\Delta x \sim \pm 40 \mu\text{m}$; $\Delta y \sim \pm 4 \mu\text{m}$

□ Rms precision = $0.4 \mu\text{m}$

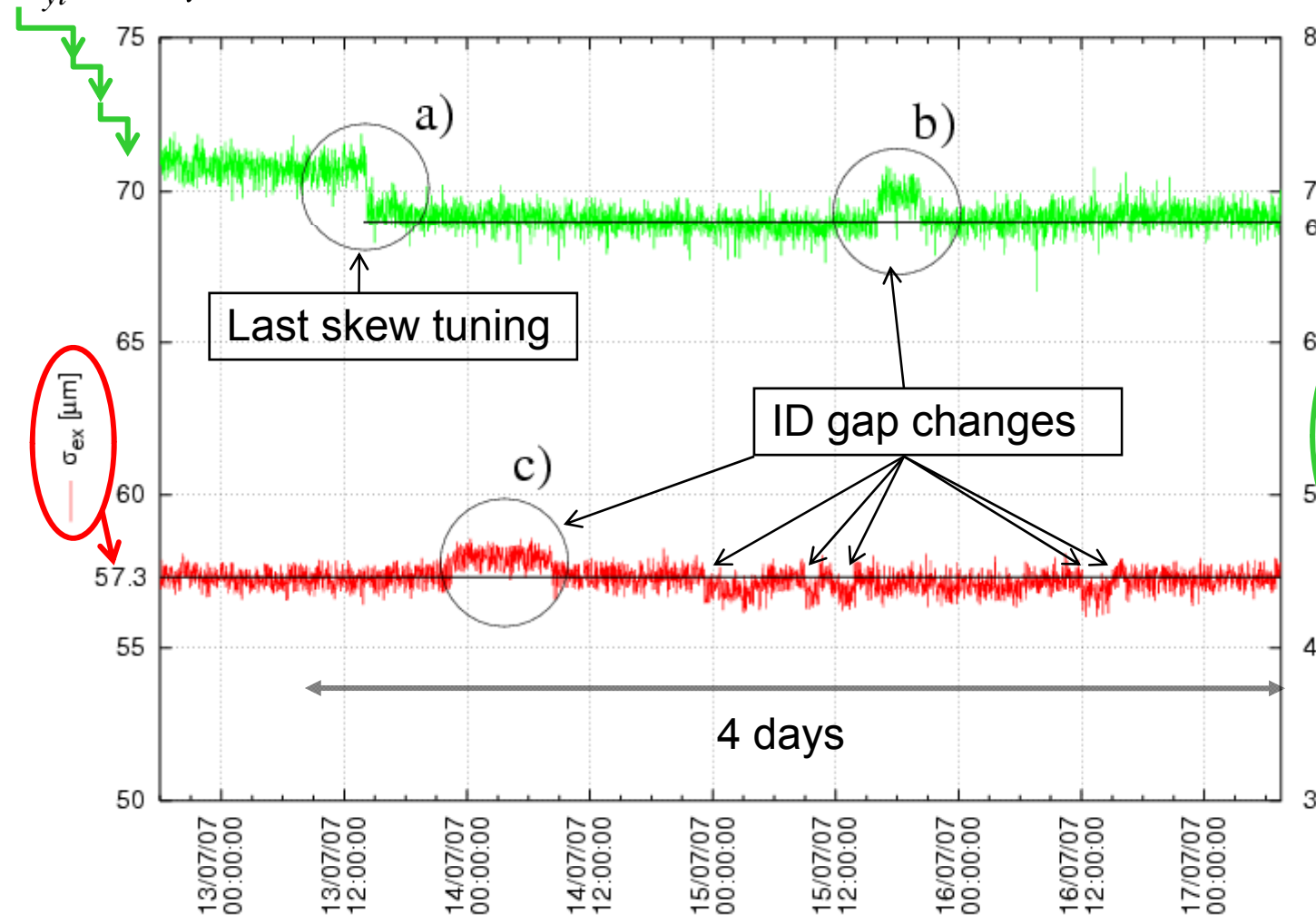
Rms precision in dispersion determination ~ 0.25 mm





ϵ_y reduction in user top-up operation, I=400mA

$\sigma_{yi} \approx 10 \mu\text{m}$



$$\beta_y = (13.55 \pm 0.14) \text{ m}$$

$$\eta_y = (2.3 \pm 0.55) \text{ mm}$$

$$\epsilon_y = (3.2 \pm 0.7) \text{ pm}$$

$$\frac{\epsilon_y}{\epsilon_x} = (0.05 \pm 0.02) \%$$

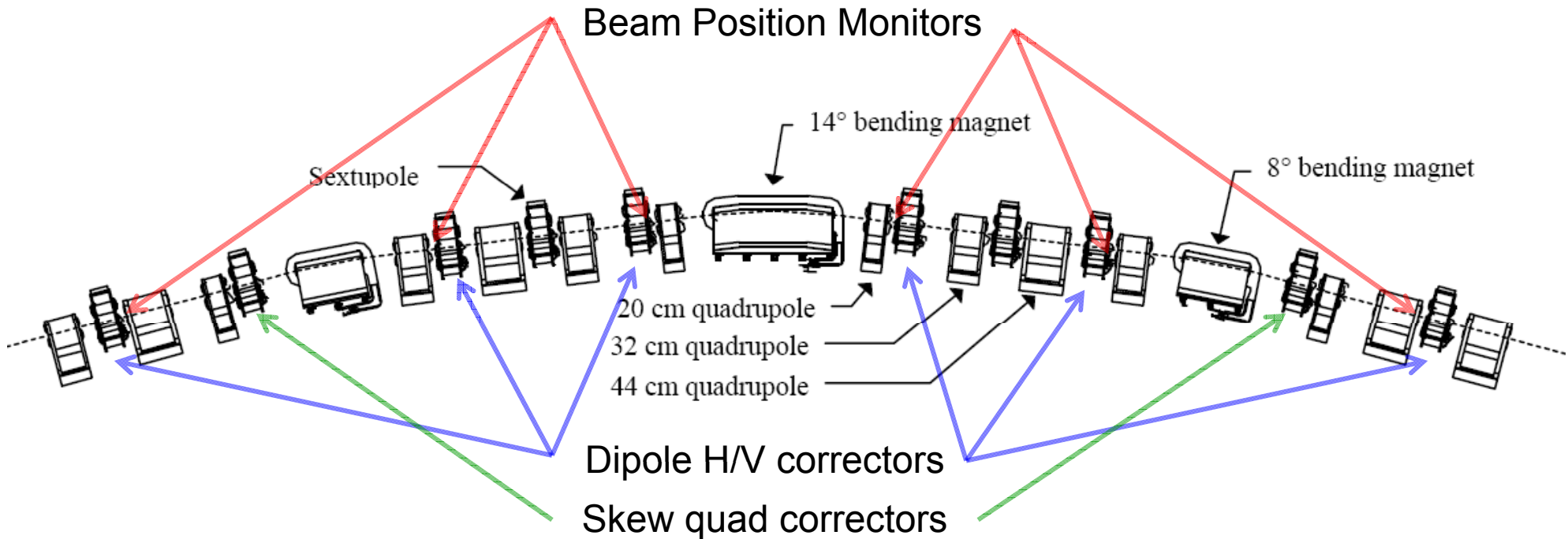
$$\beta_x = (0.431 \pm 0.009) \text{ m}$$

$$\eta_x = (27.3 \pm 1.0) \text{ mm}$$

$$\epsilon_x = (6.3 + 0.7 - 0.9) \text{ nm}$$

Which are the contributing factors for achieving the low emittance ratio in SLS?

Magnet Alignments and BPM/Corrector scheme



Alignment tolerances (rms)
Individual elem. on girders:

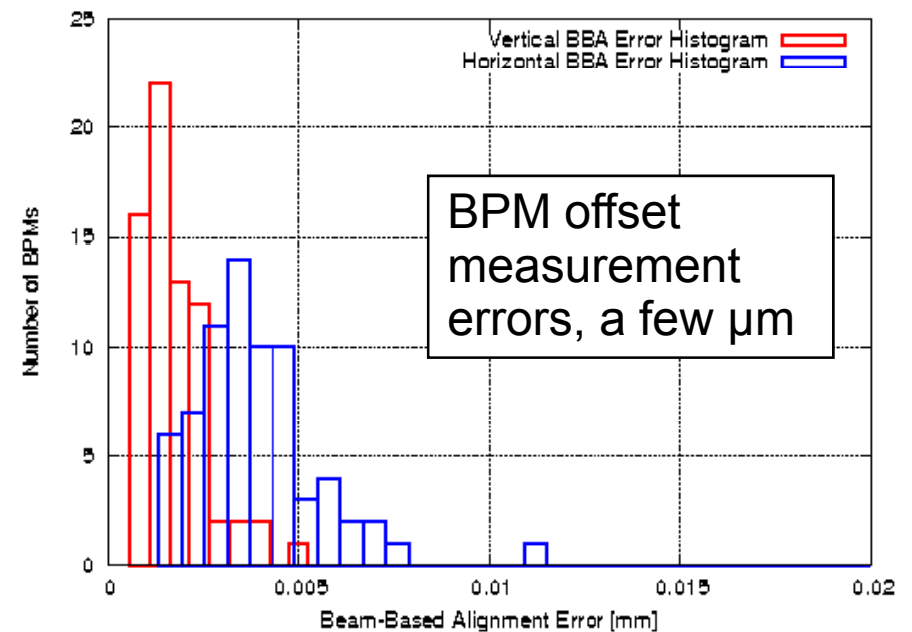
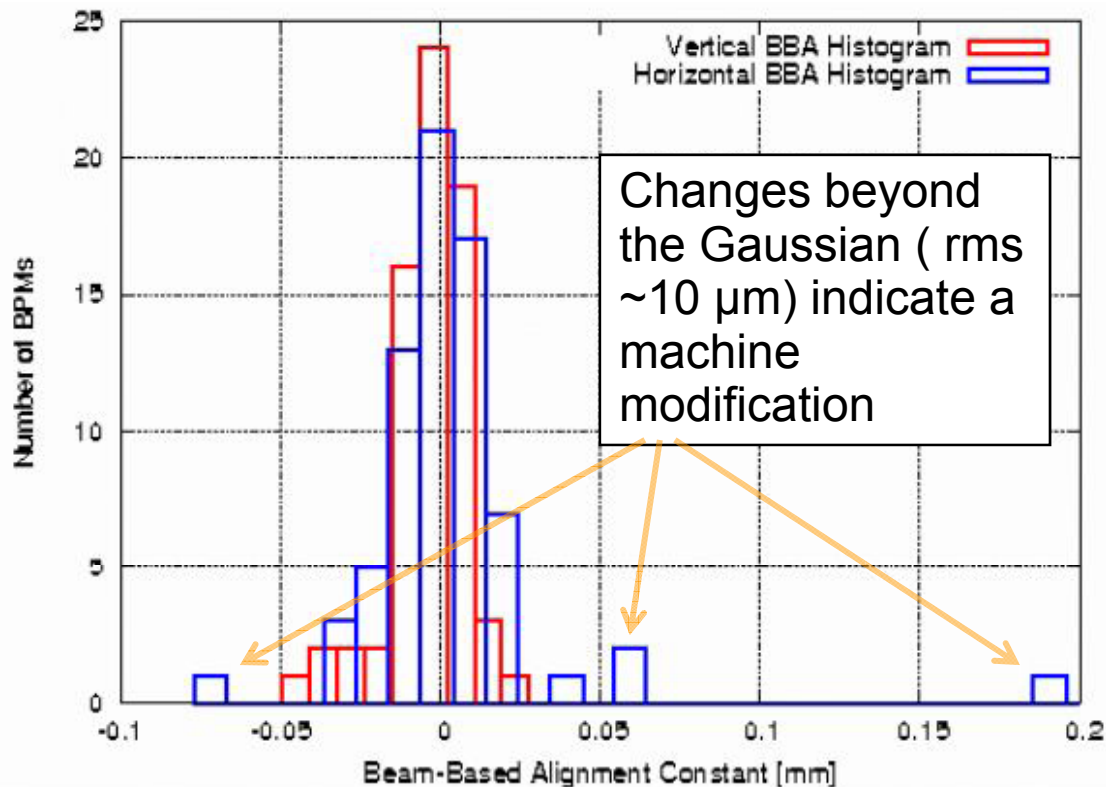
X,Y Quad, Sext	50 μm
Rolls	100 μrad

Average phase advance
between BPMs:

Y	43 deg
X	102 deg

Contr. 2: Frequent beam-based BPM check-ups

- In each sector the reference orbit is nailed to the centres of the six quadrupoles adjacent to the BPMs, by help of frequently repeated beam-based BPM offset check-ups.



User demands

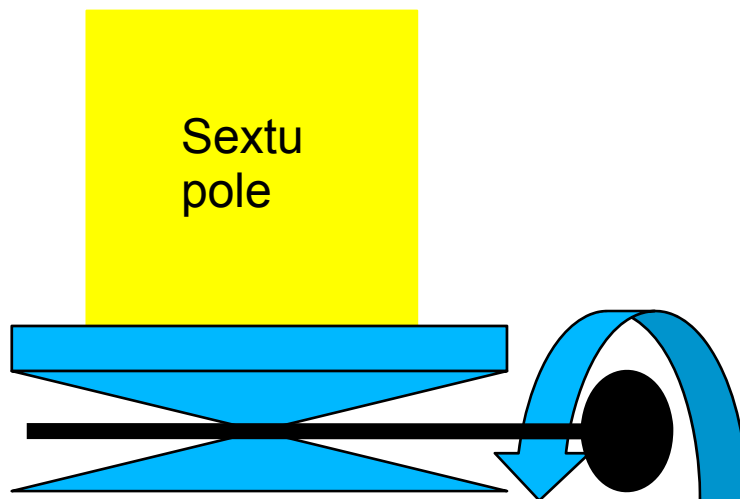
- **Orbit stability**, short term and long term ==>The orbit position is extremely well probed by the **numerous** beamlines. In principle, all orbit changes are carefully tracked down.
- **Constant beam current** (Top-up) ==> Thermal stability, possibility for careful fine tuning of skew correctors .
- **User orbit bumps?** No major problem if less than 300-400 μm . The smallest emittance ratio is reached **with** user bumps. Former, when being in the mm range, they caused $\varepsilon_y \approx 20\text{pm}$.
- **IDs?** As seen most ID changes have minor influence, and again, the smallest emittance ratio is reach during user operation **with** most ID gaps closed.

Outlook for coupling suppression in SLS:

- There is still a factor 6 to be gained in vertical emittance before the intrinsic limit 0.55 pmrad (due to the fundamental quantum nature of SR emission) in SLS is reached.
- The whole ring was equipped with 24 instead of the 8 skews in the non-dispersive regions. An SVD based correction scheme was applied, to minimize the coupling ==> Marginal effect on ϵ_y .
- Simulations show that residual vertical dispersion (rms ~3mm), induced by beam passages off mid-plane in sextupoles, is the major contribution to ϵ_y .
- 6 new skews in dispersive regions to attack the residual vertical dispersion.

Outlook for damping rings: Sextupoles

- For a ***dedicated damping ring***, one could contemplate adding ***shunts*** (and maybe even remote levelling) to each sextupole and do a proper ***Beam-Based Alignment*** of them (tedious, but maybe most effective?)

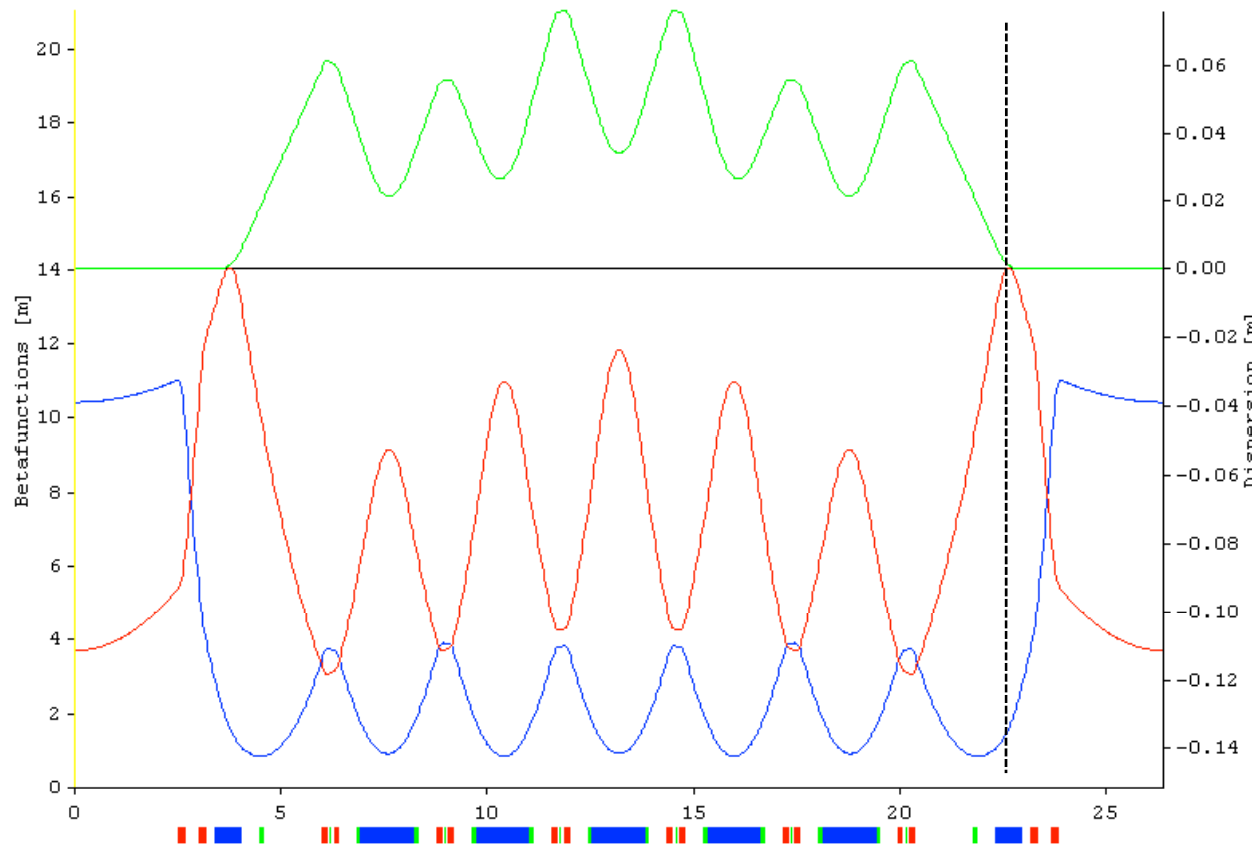


Outlook for damping rings: the π -polariz. method?

Ex:
Light
source
MAX IV



$E = 3 \text{ GeV}$
 $C = 528 \text{ m}$
 $I = 500 \text{ mA}$
 $\epsilon_x = 250 \text{ pmrad}$
 $\epsilon_y = 1 \text{ pmrad}$



$\beta_y = 14 \text{ m} \implies \sigma_y = 3.7 \mu\text{m} \text{ OK!}$
 $\beta_x = 1.8 \text{ m} \implies \sigma_x = 21 \mu\text{m}$
Large hor. acc. angle $\implies \text{OK!}$

