

*Advanced Control Engineering:
Academia - Industry*

Control and simulation of cryogenic plants at CERN

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- **Introduction**
 - Motivation
- **Dynamic simulator for cryogenic systems**
 - Control and simulation architecture for cryogenics
 - Cryogenic Modeling
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 - 1.8 K refrigeration units: Cold compressors control
 - Warm compressor stations: High Pressure control
 - Warm compressor stations: Energy optimization
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Motivation

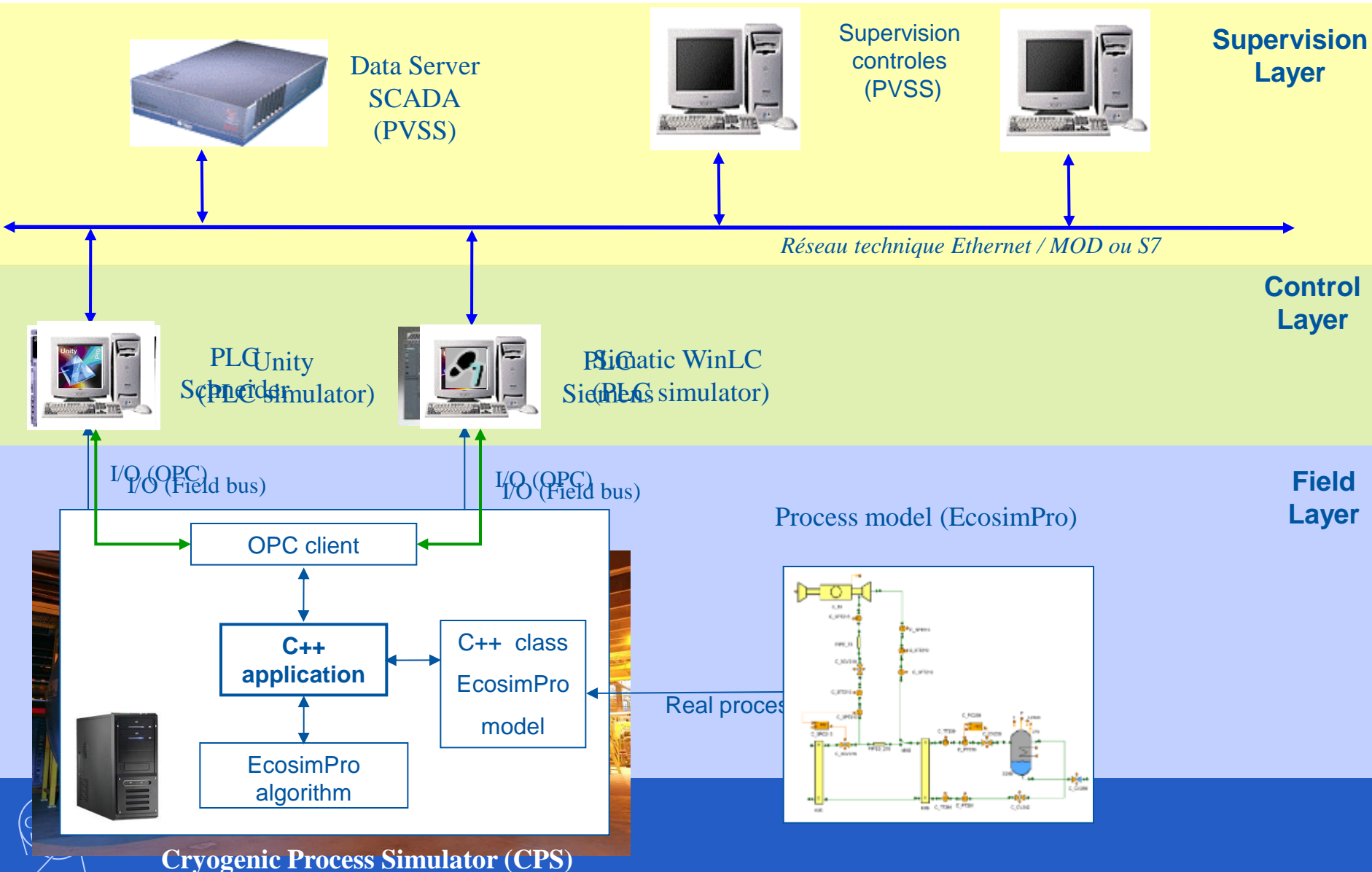
Develop a dynamic simulator for CERN cryogenic systems
→ Model Large-Scale helium refrigerators

- CERN cryogenic systems: **large scale complex** systems
 - ✓ Similar to other large industrial systems (Petroleum refineries, food industry...)
 - ✓ LHC cryogenics : 42 000 I/O & 5 000 control loops
- **Non-linearity** of helium properties (wide operation ranges)
 - ✓ Temperature : 1.8 K to 300 K
 - ✓ Pressure : 14 mbar to 20 bar
- **Unique** systems
 - ✓ Built to be operated at nominal conditions
 - ✓ Poor insight about transients and out of operation points predefined
- **Dynamic simulation** is a great tool for :
 - ✓ Train operators safely and in degraded conditions
 - ✓ Test new control strategies without disturbing real operation 
 - ✓ Validate control and supervision systems in simulation : « Virtual Commissioning »

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Control and simulation architecture for cryogenics



Cryogenic modelling

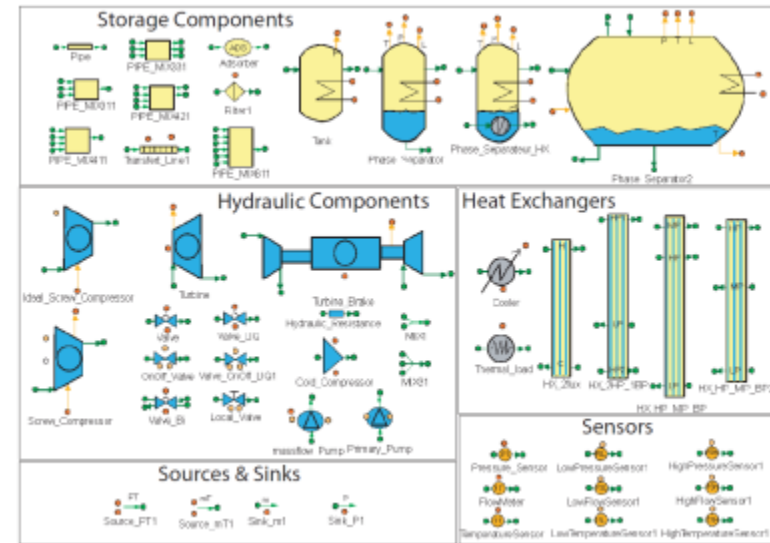
- **Macroscopic** modelling in 0D/1D

- ✓ Knowledge model based on physics
 - ✓ Thermodynamic
 - ✓ Fluid mechanics
 - ✓ ...



- Use of a commercial software: **EcosimPro**

- ✓ Object oriented modelling approach (1 component= 1 process equipment)
 - ✓ Modelling of fluids (water, helium...)
 - ✓ Modelling of actuators (valves, pumps, compressors...)
 - ✓ Modelling of passive equipment (pipes, vessels,...)
 - ✓ Modelling of sensors (temperature, pressure, massflow...)
- ✓ Non-causal modelling
- ✓ Differential Algebraic Equations (DAE)
- ✓ Manual spatial discretisation for 1D components
- ✓ Nice Graphical User Interface



- Use of a cryogenic library (**CRYOLIB**)

- ✓ Developed at CERN
- ✓ Technology transferred and commercialized by EcosimPro

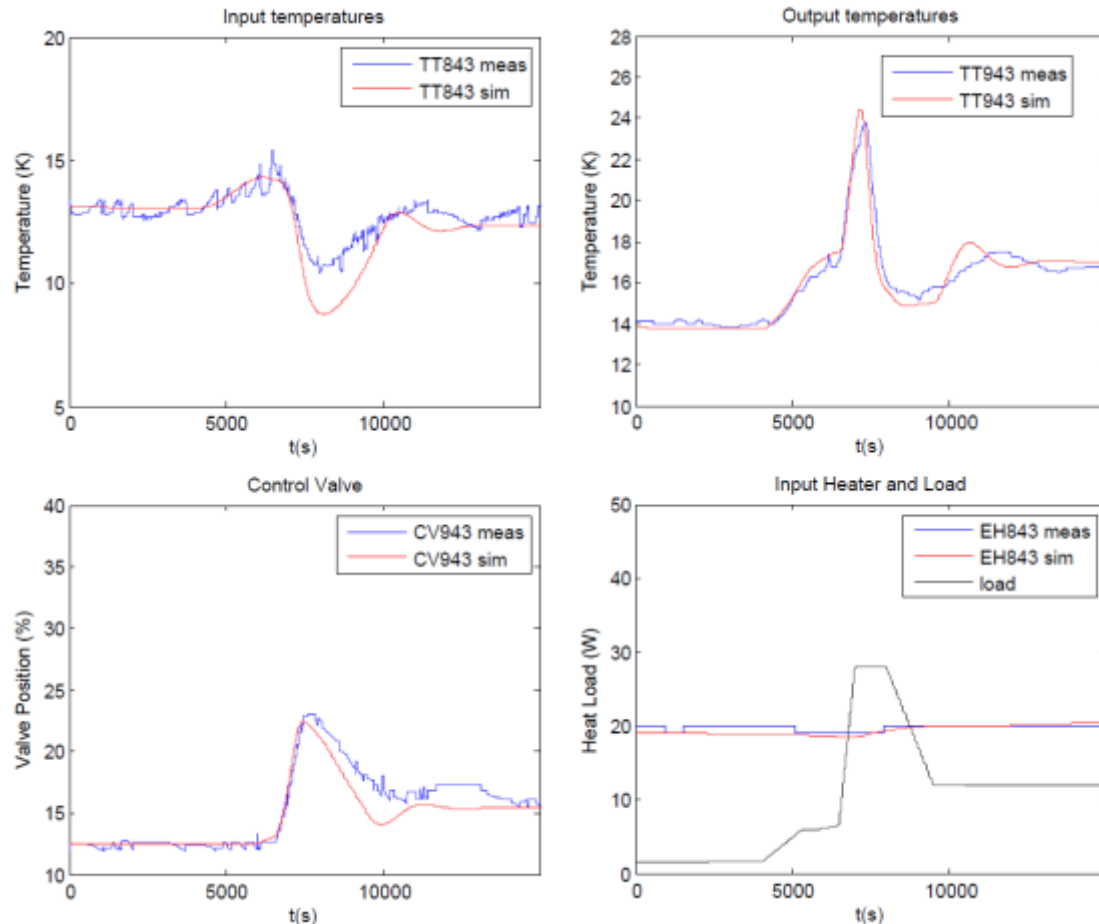
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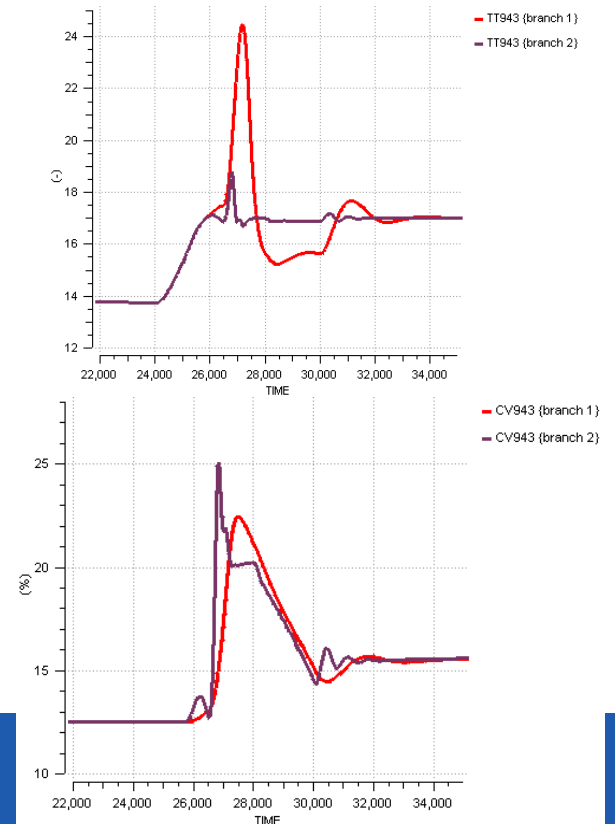
Beam screens cooling: PID tuning

- Output temperature of beam screens must be below 20 K to ensure ultra high vacuum in LHC
- Heat peak is induced during the beam injection in LHC. Temperature was sometimes rising up to 20 K
- Reproduction in simulation and tuning of controller to reduce the peak

Model validation with experimental data

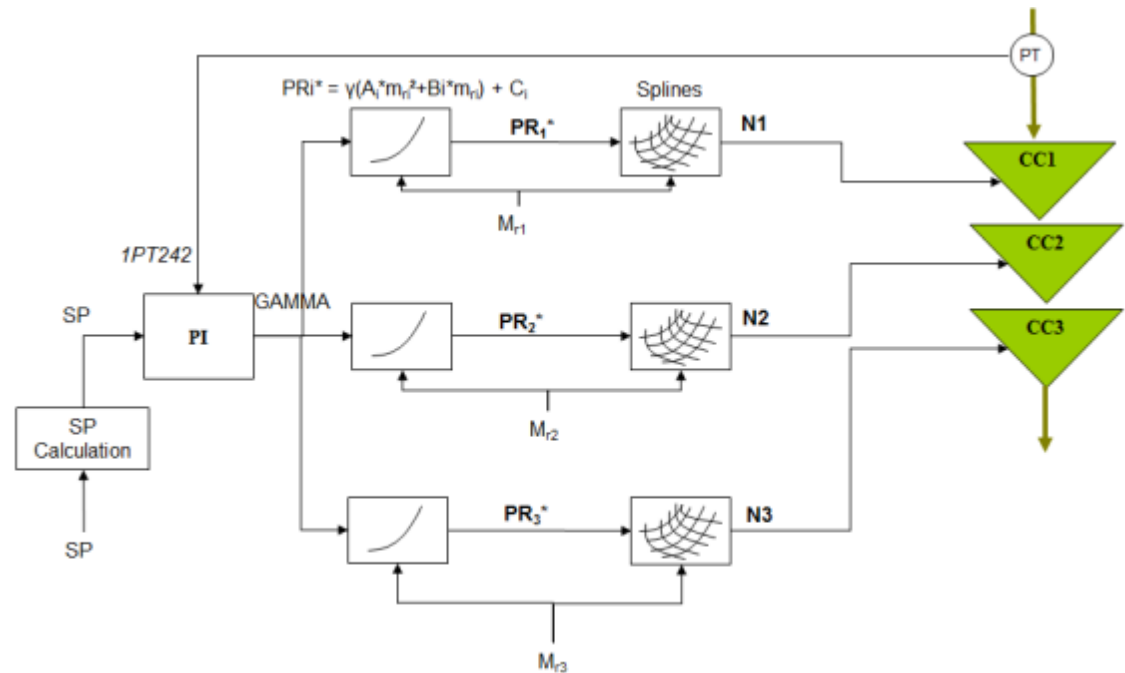
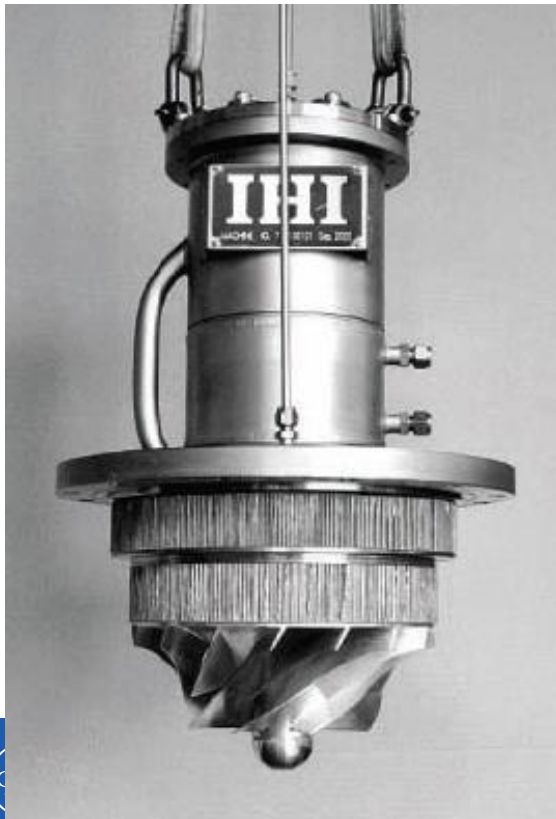


Simulation with new PID including some data filtering



Cold compressor control (1/2)

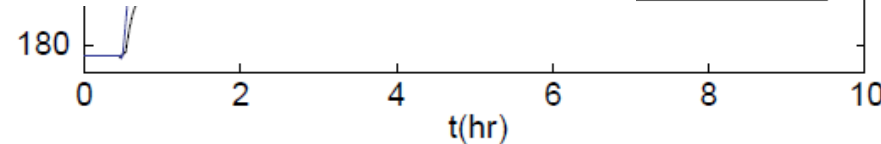
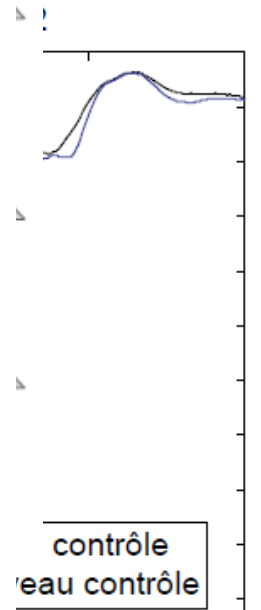
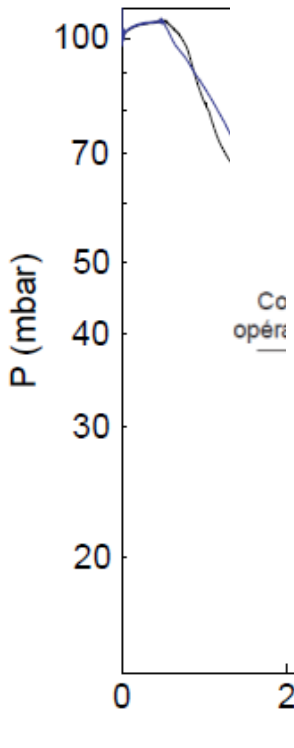
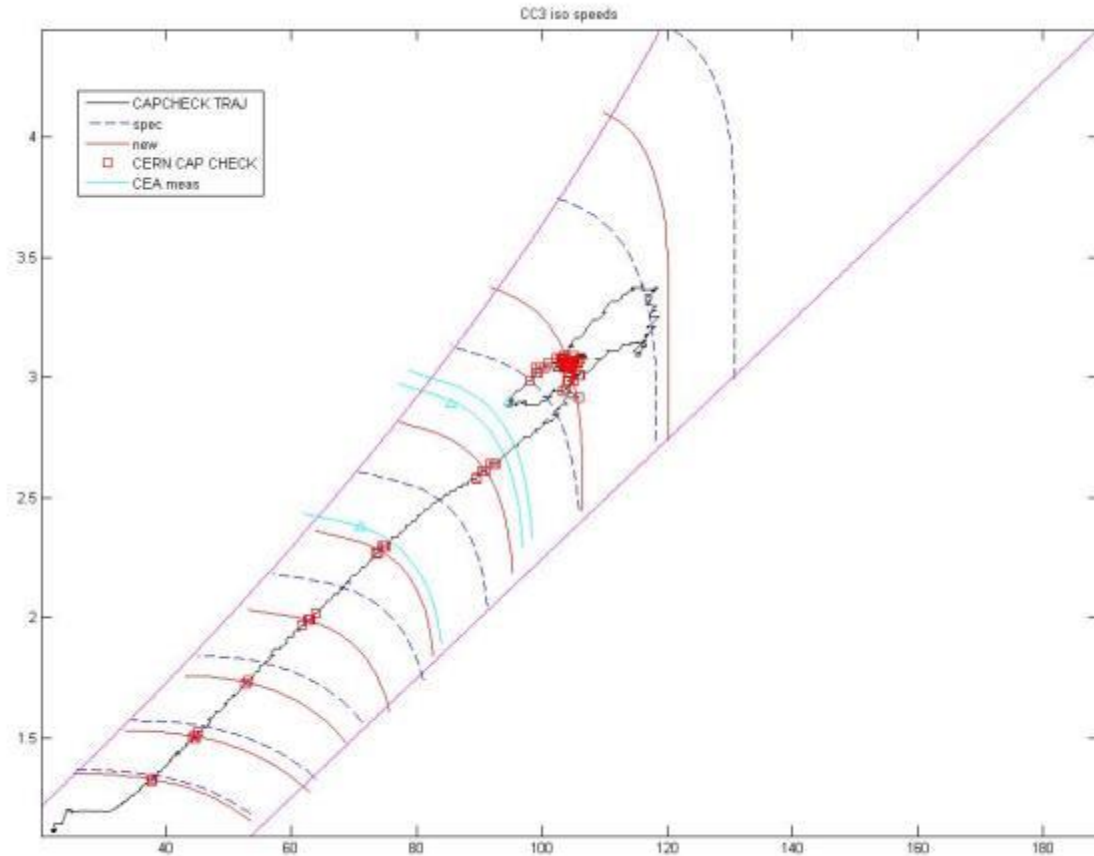
- Cold compressors are complex hydrodynamic machines
 - ✓ Allow to pump helium at 16 mbar at 3 K to reach 1.8 K in LHC magnets
 - ✓ A narrow pressure field has to be respected
- Original control was too slow or too “brutal” during pumping sequence



Cold compressor control (2/2)

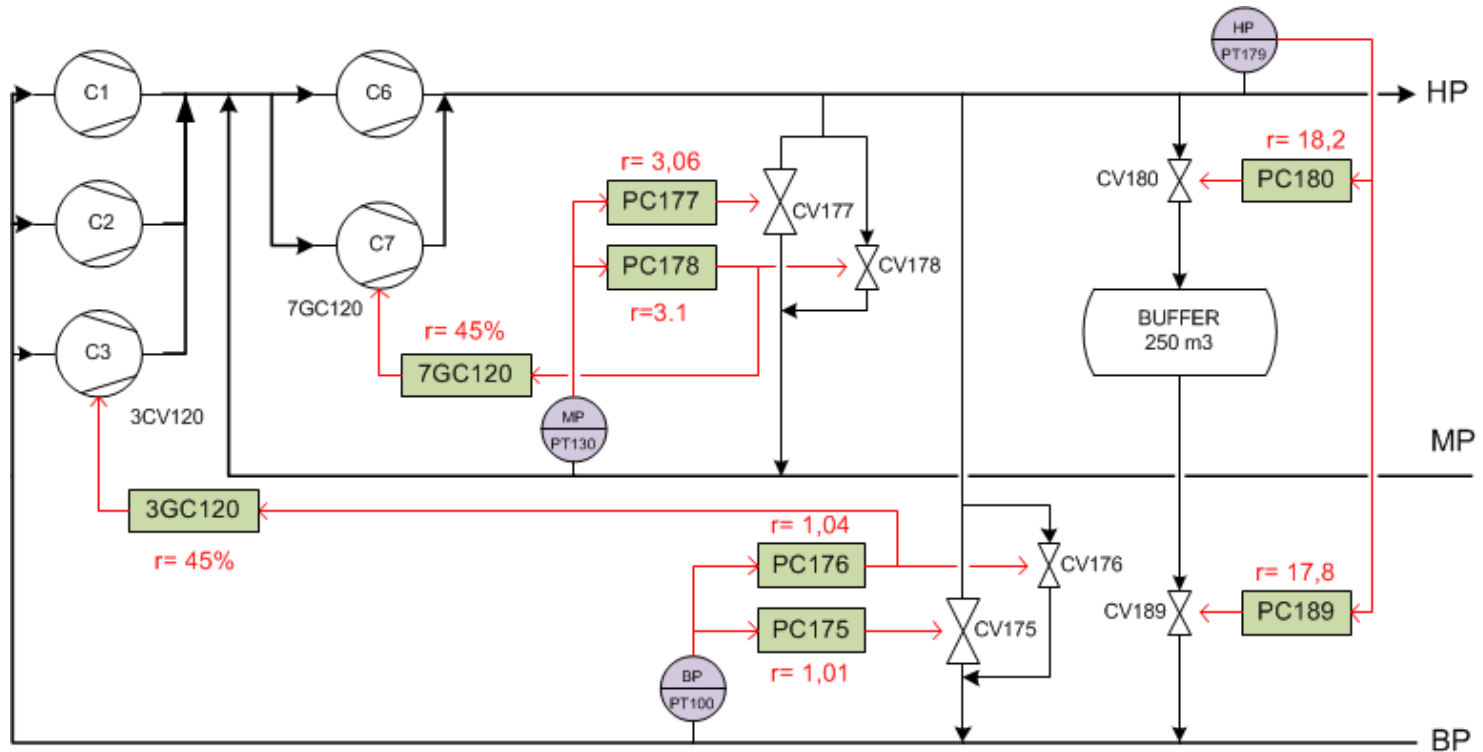
- Modeling and identification of pressure fields using optimization techniques
- Design of
- Pumping
 - No n
 - S
 - E

the trajectory



Warm Compression Station Control (1/3)

- Compress 1.6 kg/s of warm helium from 1 bar to 18 bar
- Electrical consumption : 4.5 MW → x8 = 36 MW
- 5 compressors + 6 valves + buffer tank + piping
- Objective = maintain constant pressures
 - ✓ High Pressure, Low Pressure, Medium Pressure
- Usually controlled by 8 PID controllers



Warm Compression Station Control (2/3)

IMC Control: Internal Model Control

- Linear Model Synthesis from physics

$$\frac{dP}{dt} = \frac{d\rho}{dt} \cdot \bar{R} \cdot T = \frac{dM}{dt} \cdot \frac{\bar{R} \cdot T}{V}$$

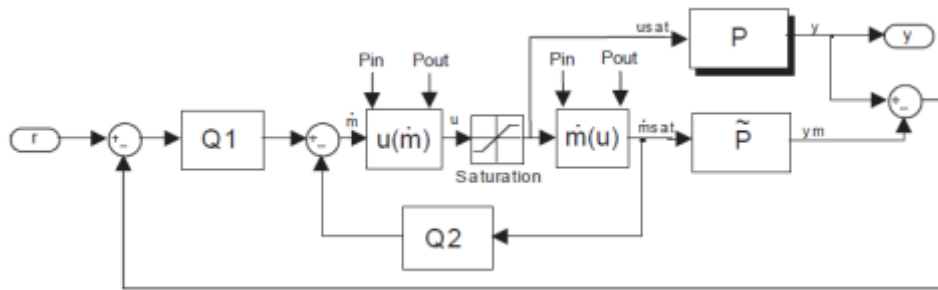
- Model uncertainties evaluations

$$lm(j\omega) = \frac{P(j\omega) - \hat{P}(j\omega)}{\hat{P}(j\omega)}$$

- Synthesis of the controller Q using a robust tuning

$$\min_Q \sup_{\omega} (|\eta \bar{lm}| + |\epsilon w|) \quad \forall \omega \in \mathbb{R}_+$$

- Guarantee stability for the worst case
- Adapt model in real-time (according to current state)
- Take into account saturation of valves (« *anti-windup* »)



Optimal LQ Control: Linear Quadratic Control

- Linear Model Synthesis from physics

$$\frac{dP}{dt} = \frac{d\rho}{dt} \cdot \bar{R} \cdot T = \frac{dM}{dt} \cdot \frac{\bar{R} \cdot T}{V}$$

- Calculation of the error regarding set-point

$$x_{\epsilon} = x - x_{sp}$$

- Integrate the error

$$x_{I\epsilon} = x_{I\epsilon} + x_{\epsilon}$$

- Compute the virtual control effort

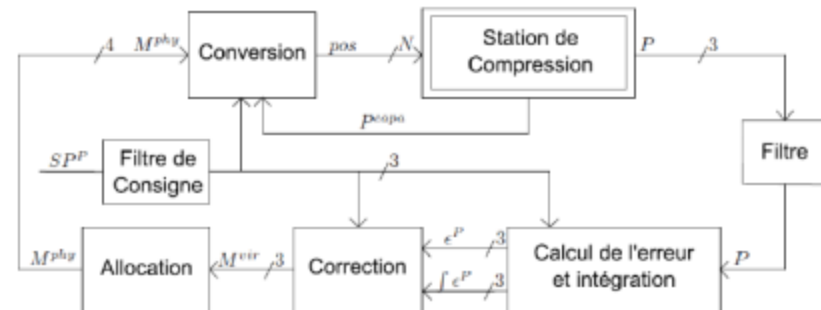
$$u_{vir} = K \cdot [x_{\epsilon} \ x_{I\epsilon}]$$

- Project on the admissible space

$$u_{phy} = \mathcal{P}(u_{vir})$$

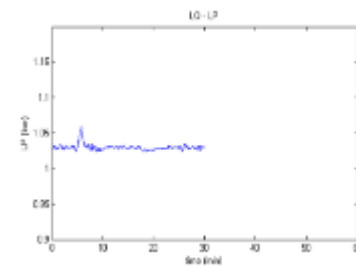
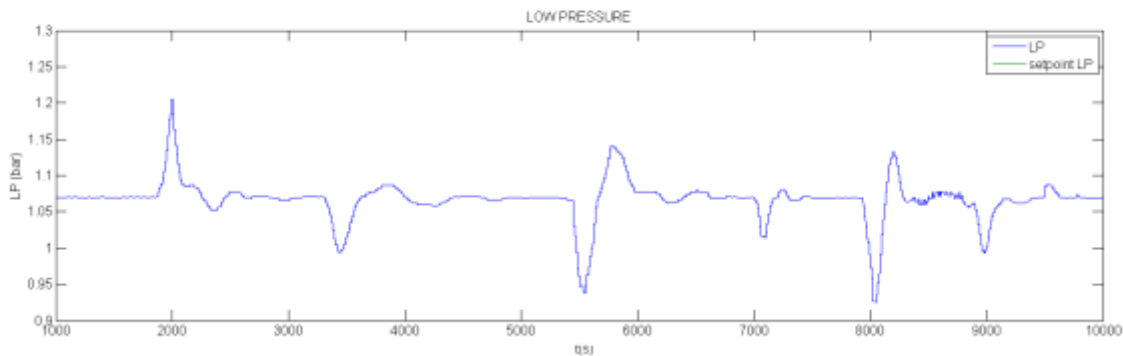
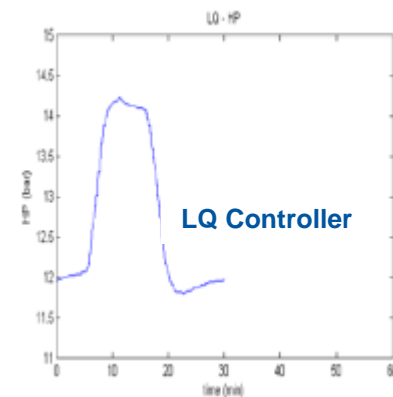
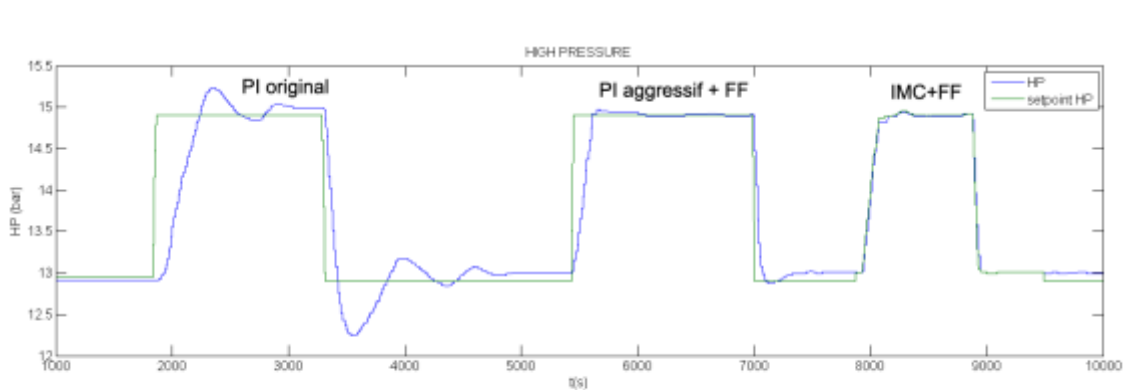
- Transformation from flowrate to actual control effort

$$u_{phy} \rightarrow u$$



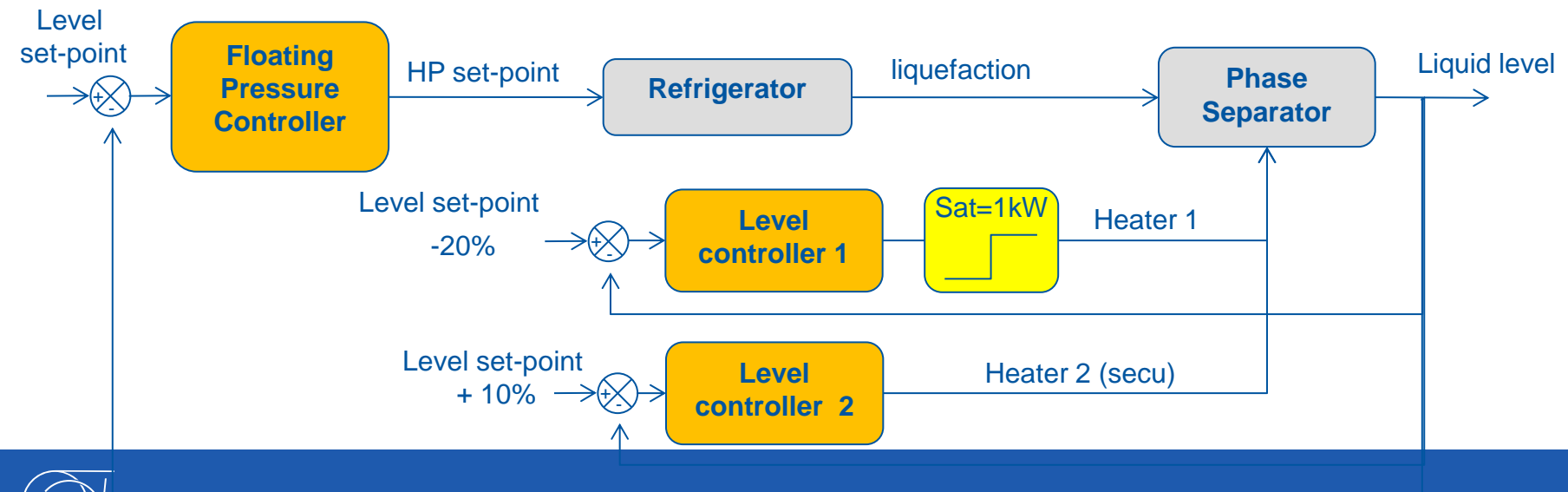
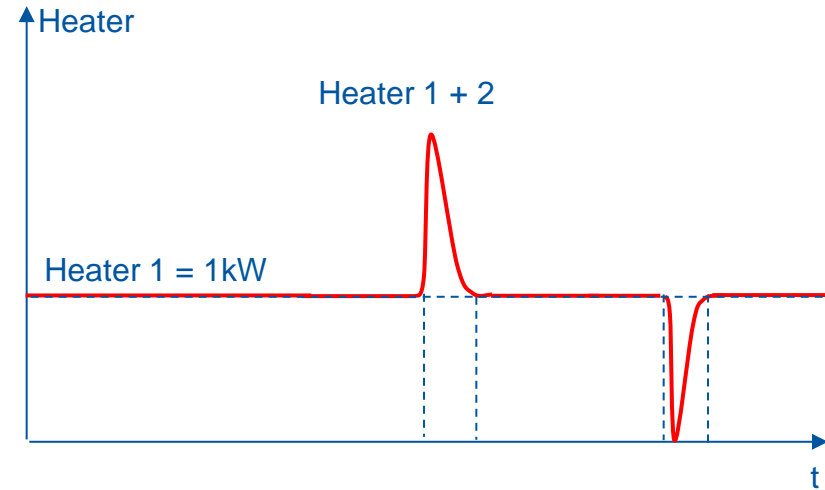
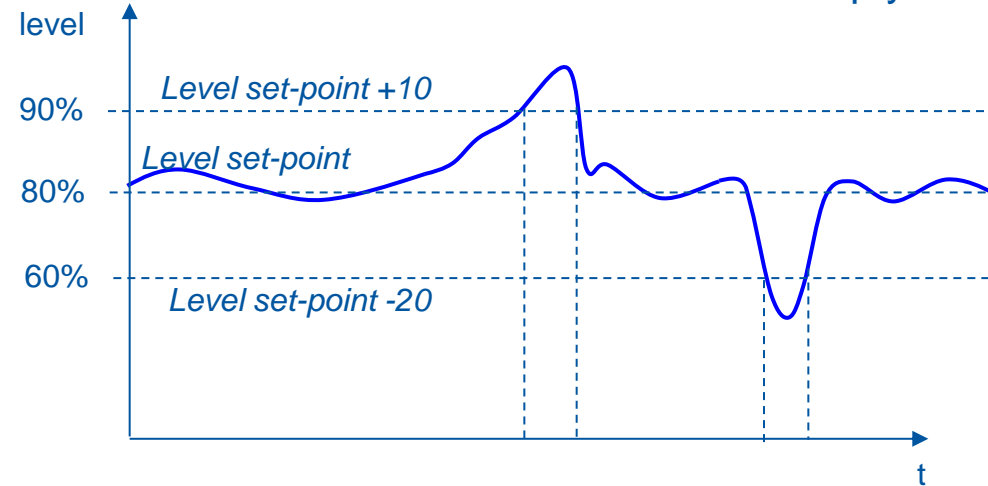
Warm Compression Station Control (3/3)

- Comparison of different regulation techniques (sim + real)
 - ✓ Original PI controllers
 - ✓ Aggressive PI controllers + Feed-Forward
 - ✓ IMC + Feed-Forward
 - ✓ Optimal Multivariable LQ controller



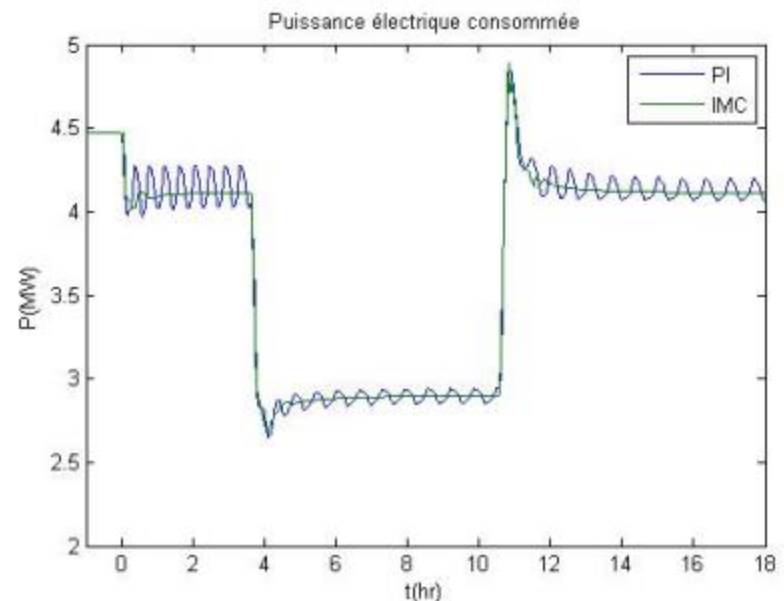
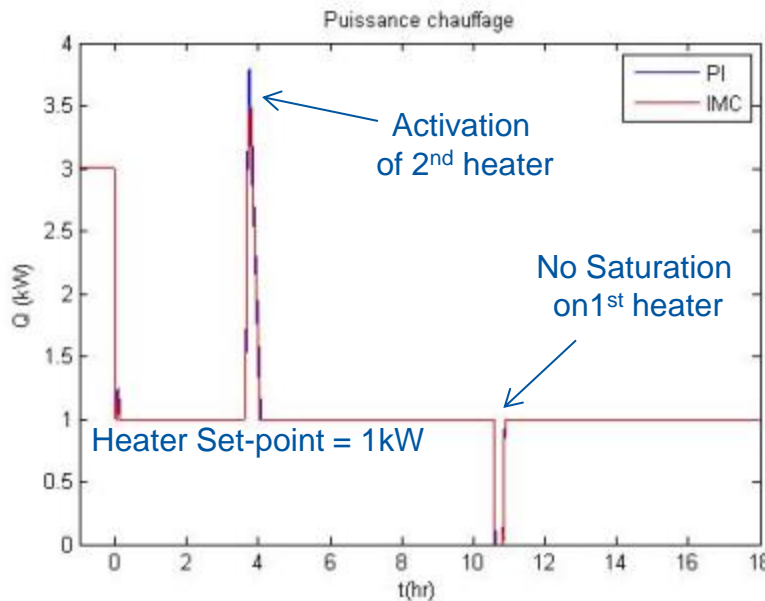
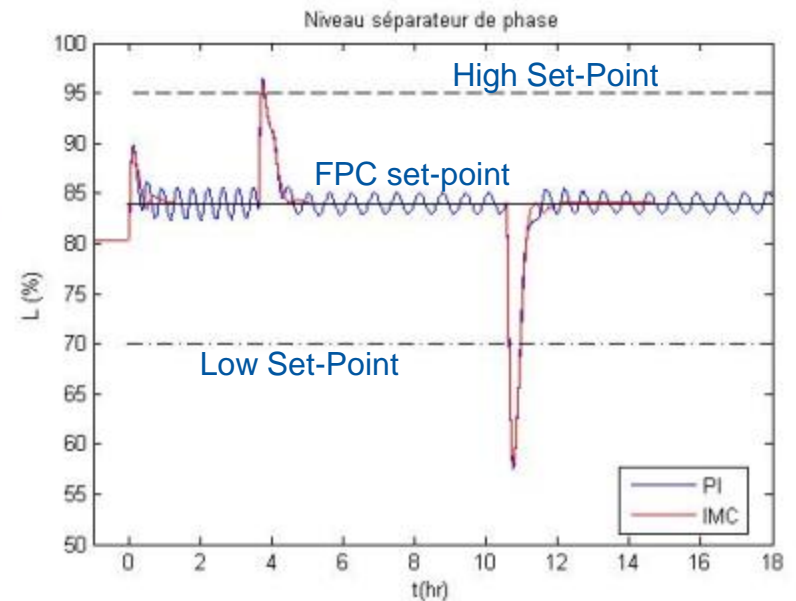
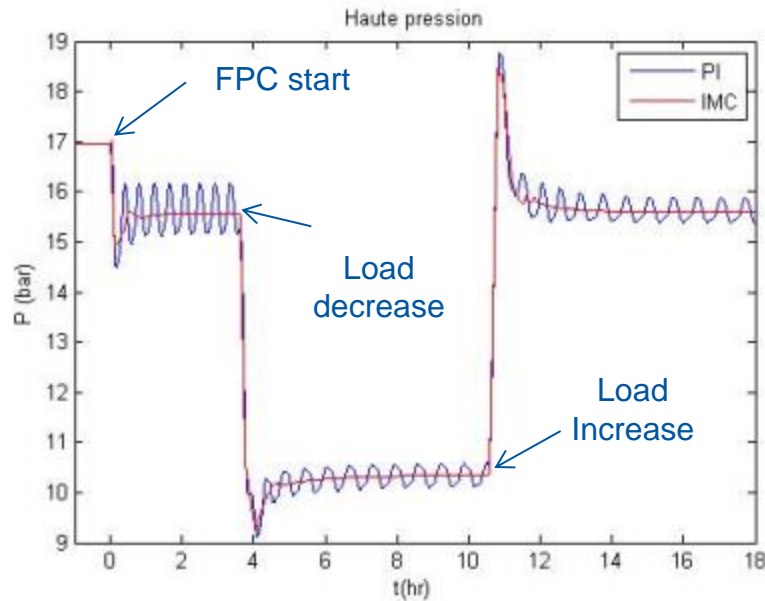
Energy Optimization (1/2)

- Include a new control loop to optimize energy consumption (cascade)
- User Heater control to avoid to empty the phase separator or to have an overflow



Energy Optimization (2/2)

Simulations:



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Conclusion & Perspectives

- Cryogenics are very complex processes
 - ✓ Large-Scale
 - ✓ Multivariable
 - ✓ Non-Linear
- Dynamic simulation is an adequate tool to validate new control schemes
- Cryogenics (as other processes) is using mainly PI controllers
- Cryogenics begins to use advanced control to optimize controls