Status and roadmap of the AlFa Framework



Mohammad Al-Turany GSI-IT/CERN-PH-AIP

Just to remind you what is "AlFa"

- Will rely on a data-flow based model (Message Queues).
- It will contain
 - Transport layer (based on: ZeroMQ, NanoMSG)
 - Configuration, building and testing tools (infrastructure)
 - Management and monitoring tools
- Provide unified access to configuration parameters and databases.
- It will include support for a heterogeneous and distributed computing system.
- Incorporate common data processing components

And What is **NOT** in Alfa

- Monte-Carlo simulation (Transport)
 - AlFa will use the output of the Monte-Carlo simulation for developing the re-construction

GRID

 AlFa Should be seen as an application which could run in any distributed system Grid or what ever will be there in 2018

Where we are now?

 We can choose between two transport layers and we could add new options if needed

– ZeroMQ

Nanomsg

Alexey Rybalchenko

ZeroMQ vs. nanomsg

https://github.com/nanomsg/nanomsg/issues/206

local throughput (Mb/s)

message size	1B	1KB	100KB	1MB
ZeroMQ 3.2.4	46	6694	22703	19096
nanomsg master branch 2013-12-10	7	5791	19304	DNF

remote latency (µs)

message size	1B	1KB	100KB	1MB
ZeroMQ 3.2.4	186	256	1152	9860
nanomsg master branch 2013-12-10	162	219	1170	DNF'

results confirmed by nanomsg developer:

"Dez 10 10:26:46 <sustrik> [...] the performance wasn't tuned up yet"

Alexey Rybalchenko

Protocol buffers

- Google Protocol Buffers support is now implemented
 - Example in Tutorial 3 in FairRoot.

- To use protobuf, run cmake as follows:
 - cmake -DUSE_PROTOBUF=1

nicolas Winckler

Boost serialization

- Code portability depend only on ANSI C++ facilities.
- Code economy exploit features of C++ such as RTTI, templates, and multiple inheritance, etc. where appropriate to make code shorter and simpler to use.
- Independent versioning for each class definition. That is, when a class definition changed, older files can still be imported to the new version of the class.
- Deep pointer save and restore. That is, save and restore of pointers saves and restores the data pointed to.
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http://www.boost.org/doc/libs/1_55_0/libs/serialization/doc/index.html

This is used already by the CBM Online group in Frankfurt and to we need it to communicate with them!

Ricolas Windelerenko Protobuf, Boost or Manual Nicolas Rybalchenko Protobuf, Boost or Manual Serialization?

- Boost:
 - we are generic in the tasks but intrusive in the data class (digi, hit, timestamp)
- Manual and Protobuf
 - we are generic in the class but intrusive in the tasks (need to fill/access payloads from class with set/get x, y, z etc).

Manual method is still the fastest, protobuf is 20% slower and boost is 30% slower.

Dynamic Deployment System

- Deploy executables
- Use (utilize) any RMS (Slurm, Grid Engine, ...),
- Secure execution of nodes (watchdog),
- Support different topologies and user process dependencies,
- Support a central log engine
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See talk by Anar today

Andrey Lebedey

Templated Digi-loader and File-sink are under development

- This is the interface between the simulation data driven framework.
- Data is read from ROOT files, converted to raw data format (if necessary) and then send as messages over the network.
- (de)serialise of digis and/or hits
- It can use manual serialization of messages, boost serialization and/or protobuf





- Use the existing geometry of the ITS and TPC detectors
- Port the stepping managers to FairRoot
- Make a simple simulation of ALICE detector that can be used with the generic digi-loader as a first step for developing algorithms in AlFa later.

Charalambosilos

FAIR: Next steps

 Testing the full reconstruction chain with the First Level Event Selector cluster (FLES) of the CBM experiment

 Integrate the GPU triplet finder (CUDA code) of PANDA experiment into the Framework

ALICE: Next steps

- Continue developing the simulation proto type (see talk by Charis today)
- Implement (port) the TPC and ITS digitization to the proto type and adapt them to the pile up simulation in FairRoot
- Use the generic loaders (data samplers) on the time frames generated by the proto type