

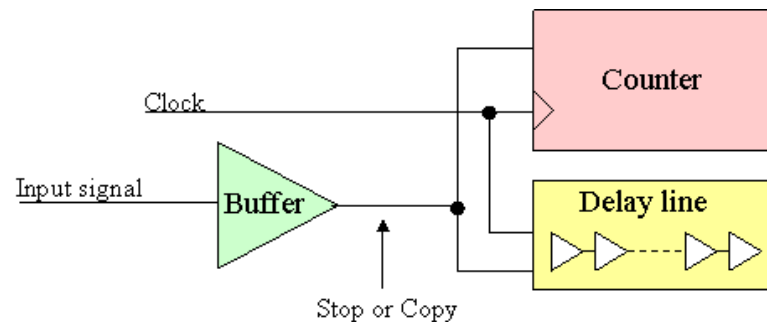
# Measuring time with a 5-ps precision at the system level with the WaveCatcher family of SCA-based fast digitizers

D.Breton, J.Maalmi, P.Rusquart (LAL Orsay), E.Delagnes (CEA/IRFU)



- The technologies have evolved at an amazing rate in the last decade, and during this period our electronics engineer everyday work has been transformed consequently
- Sometimes we have to design systems housing **only few channels**, for instance for our test or characterization benches, other times **large scale systems** for physics experiments, thus pushing us to look for the best solution to perform as **precise** as possible signal measurements at the **lowest cost and power consumption**
- Our consecutive developments thus made us use high-end commercial **ADCs** as well as developing high performance **TDCs** and **analog memories**
- Now we deal with many **GS/s**, which actually permits getting closer to **ps** => we can aim at measuring the time using waveform digitization ...

- Current most performant TDC use digital counters and Delay Line Loops (DLLs):
  - => advantage: produces directly the encoded digital value
  - => but the resolution is at least limited by the DLL step (often by environmental factors)
- Actual time resolution of today's available most advanced ASICs: ~ 20 ps
- New developments are ongoing



BUT a TDC needs a **digital** input signal

⇒ analog input signal has to be translated to digital with a **discriminator**

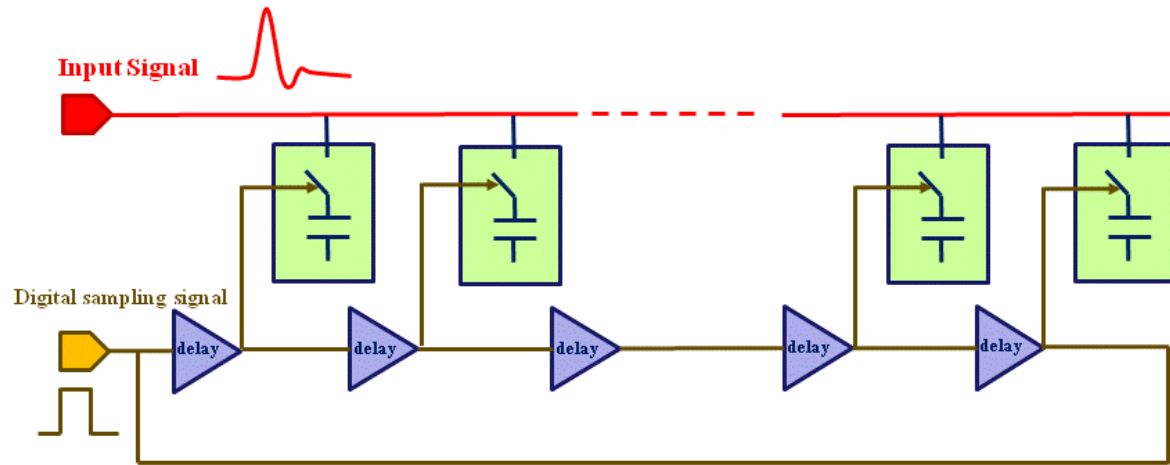
⇒ additional jitter and residues of time walk effect enter the game

⇒ overall timing resolution is given by the **quadratic sum of the discriminator and TDC timing resolutions**

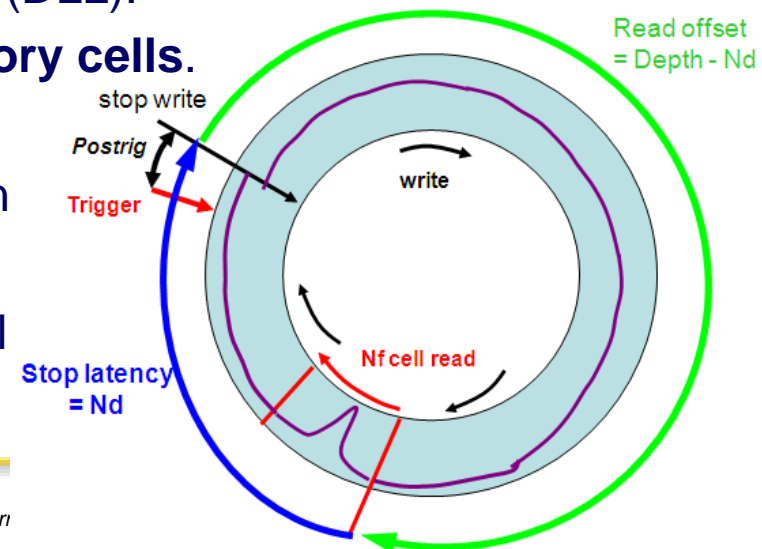
- Actually, the best way to precisely measure the arrival time of a signal is to digitize it with a very fast and precise ADC.
- Indeed, once data is digitized, one can perform a digital treatment of data to precisely extract time information
  - Waveform contains all information (if properly digitized)
  - Depending on the information requested (amplitude, charge, time, FFT, ...), different types of algorithms can be used
  - One of the goals is to find the both simplest and most effective algorithms which could be integrated within companion FPGAs
- ⇒ **Waveform sampling can be used for designing high performance TDCs**
- ⇒ **It was shown that > 1GS/s sampling rate together with a good SNR (>10bits) was leading way to the ps level**
- Caution: **signal to noise ratio** is always an issue, even for a TDC

- As said before, a perfect digitizer for fast signals would be for instance a 10-GS/s 12-bit flash ADC.
  - The 120Gbits/s output data rate per channel could make anybody nauseous, especially at large scale ...
  - Moreover, 10 GS/s sampling doesn't give enough time to process the sampled signal in real time
  - ⇒ the idea to **digitize only the interesting part** of the signal rises!
  - ⇒ storing the analog signal at high sampling rate and stopping the recording whenever something interesting occurs, just the time to digitize and transfer data to the next readout stage
    - ⇒ This **reduces the power and the dataflow** by a huge factor
    - ⇒ But ... this induces **dead-time** for digitization
- Depending on the application, dead-time can be more or less bothering ...

An analog memory can record waveforms at very high sampling rate ( $\gg$ GS/s)  
After trigger, they are digitized at much lower rate with an ADC ( $\sim$ 10/20 MHz)



- A write pulse is running along a folded **delay line** (DLL).
- It drives the recording of signal into **analog memory cells**.
- Sampling stops upon a **trigger signal**.
- **Readout** can target an area of interest, which can be only a **subset** of the whole channel
- **Dead time** due to readout should remain as small as possible ( $<100\text{ns}$  / sample).

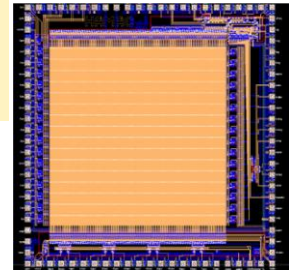




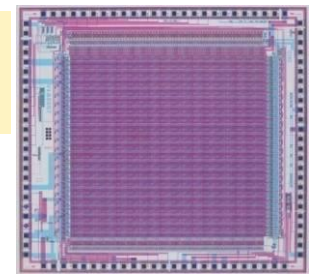
# Our favourite solution: a Sampling Matrix

- We started designing analog memories in 1992 with the first prototype of the Switched Capacitor Array (SCA) for the ATLAS LARG calorimeter. **80,000 chips** produced in 2002, now **on duty on the LHC**.
- Since 2002, 3 new generations of fast samplers have been designed (ARS, MATAcq, SAM): total of more than **30,000 chips in use**.

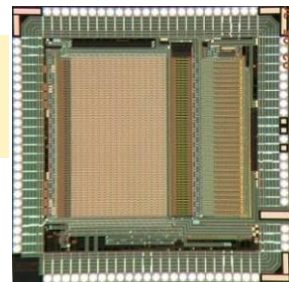
HAMAC  
1998-2002



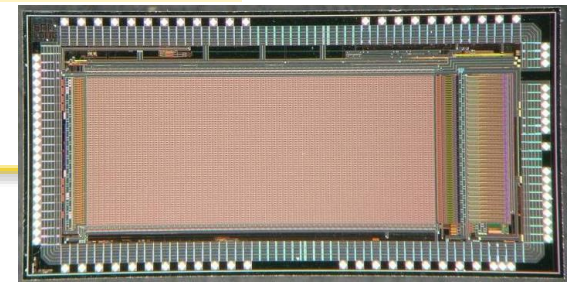
MATAcq  
2000-2003



SAM  
2005



SAMLONG  
2010-2012



Sampling at 3.2GS/s

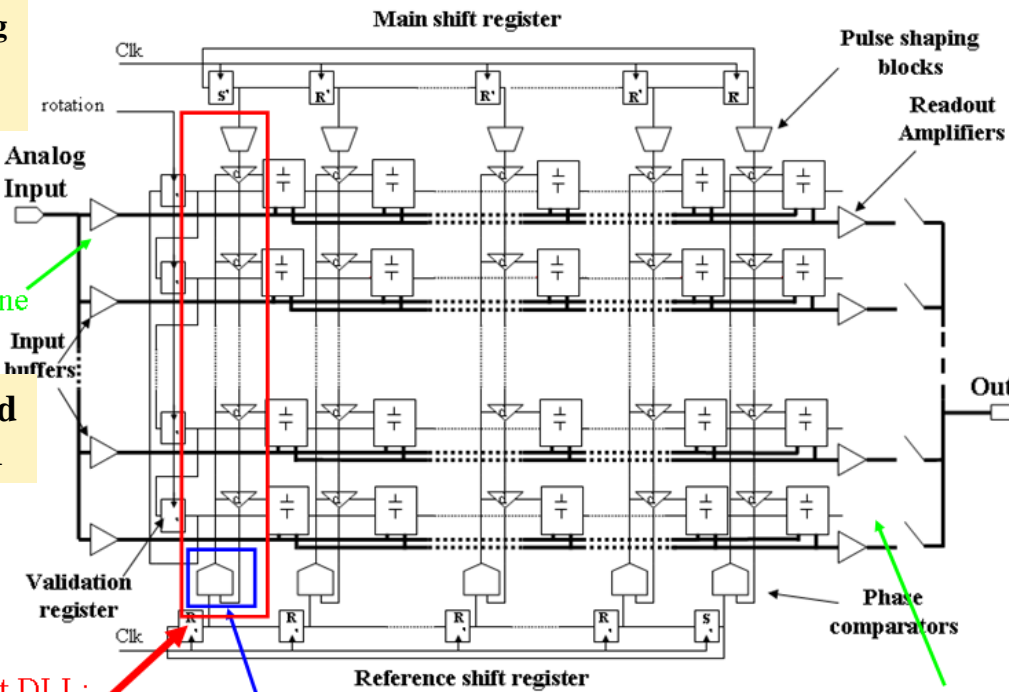
1 ampli/line

Patented in 2001

short DLL: less jitter

1 delay servo-control /col: stability

Parallellized Readout

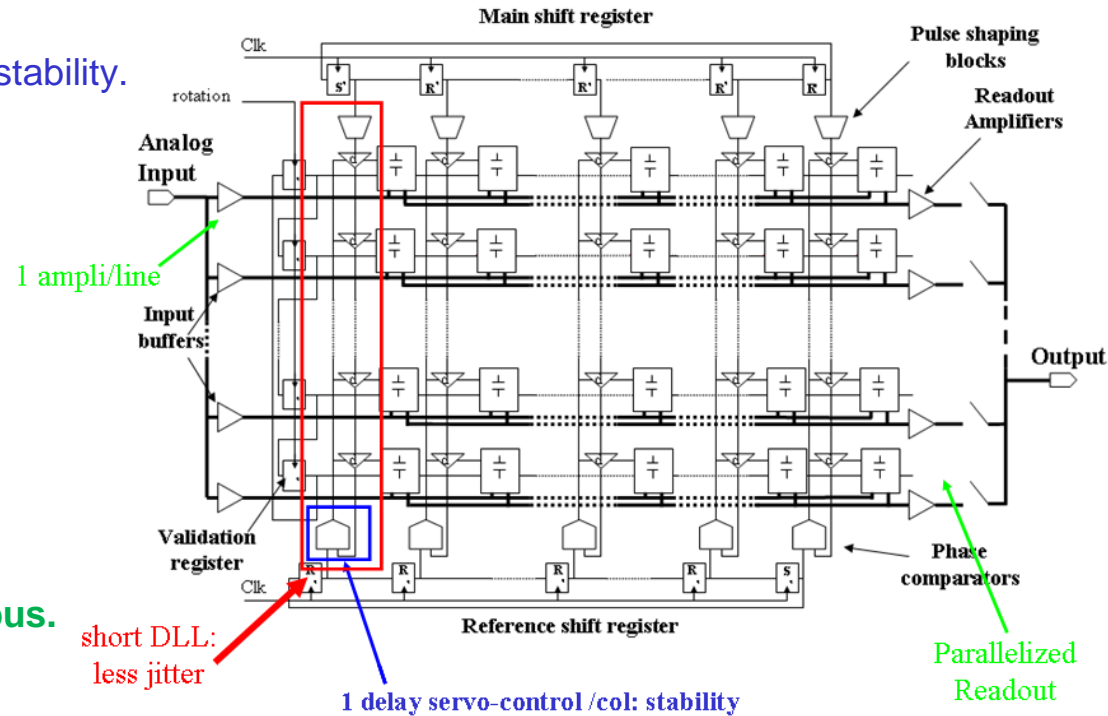


Readout 12 bits  
10/20 MHz



- Short DLL:
  - **Smallest cumulative jitter.**
  - **Junction between DLL.**
- 1 servo control of Delay / Column => high stability.
- Analog Input Buffering:
  - High input impedance:
    - **Linearity**
    - No DC input current
    - No Ringing. Flat response
  - Power consumption
  - BW limitation
- Analog bus split in divisions: lines
  - Shortest analog bus :
    - More uniform bandwidth.
    - **Less analog delay along the bus.**
  - Parallel readout => faster readout.
  - 1 buffer / line :
    - Better analog BW/power consumption FOM
    - **No ghost pulse or baseline shift effect at high signal rate**
    - **Offset between lines (corrected by DAC on-chip).**
- Initial philosophy: possibility to work with **no off-chip correction** (pedestal, amplitude, time) => limit external computing

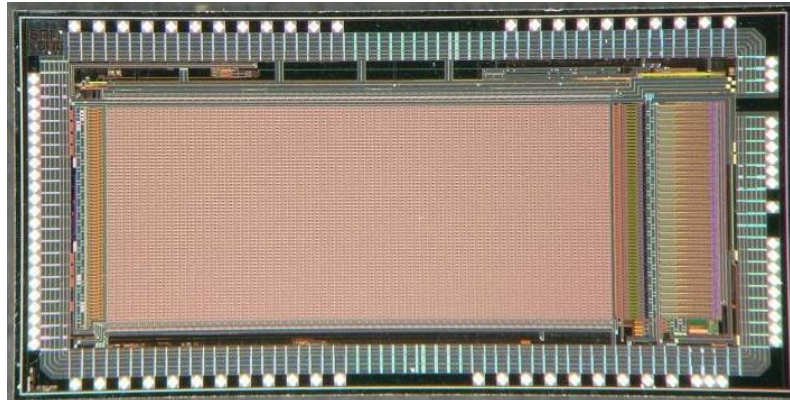
Analog design is fully differential





- **Analog memories** actually look like perfect candidates for **high precision measurements at large scale**:
  - Like ADCs they catch the **signal waveform**
  - **TDC is built-in** (position in the memory gives the time)
  - Only the useful information is digitized (vs ADCs) => **reduced dataflow and power**
  - **Any type of digital post processing** can be used
  - Main design difficulty is less sampling frequency than signal **bandwidth**
- Their drawbacks:
  - The limited recording **depth**
  - The readout **dead-time** limiting the input rate
- But:
  - Only a few samples/hit can be read => this may limit the dead time
  - **Simultaneous write/read** operation is feasible, which may further reduce the dead time

## Board and system developments based on SAMLONG.



# The USB\_WaveCatcher board (V6)

Pulsers for reflectometry applications

1.5 GHz BW amplifier.

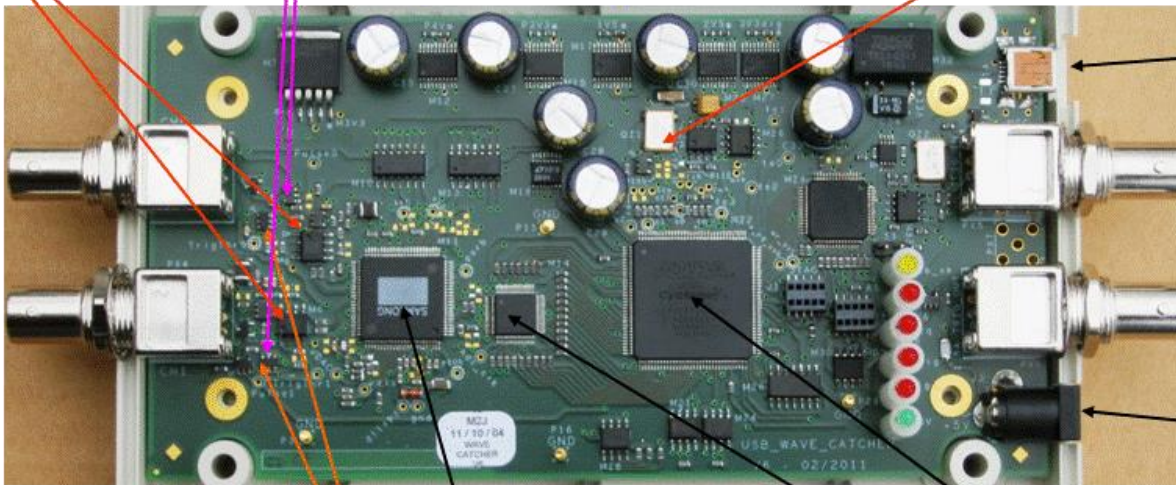
Board has to be powered by USB  
=> power consumption  $\leq 2.5W$

Reference clock:  
200MHz => 3.2GS/s

2008/2010

2 analog inputs.  
DC Coupled.

The autonomous test bench



- μ USB
- Trigger input
- Trigger output
- +5V Jack plug

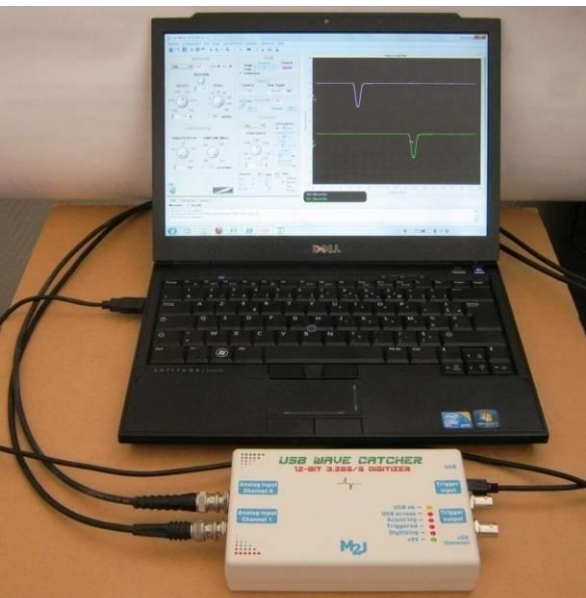
SAM Chip

Cyclone FPGA

Trigger discriminators

Dual 12-bit ADC

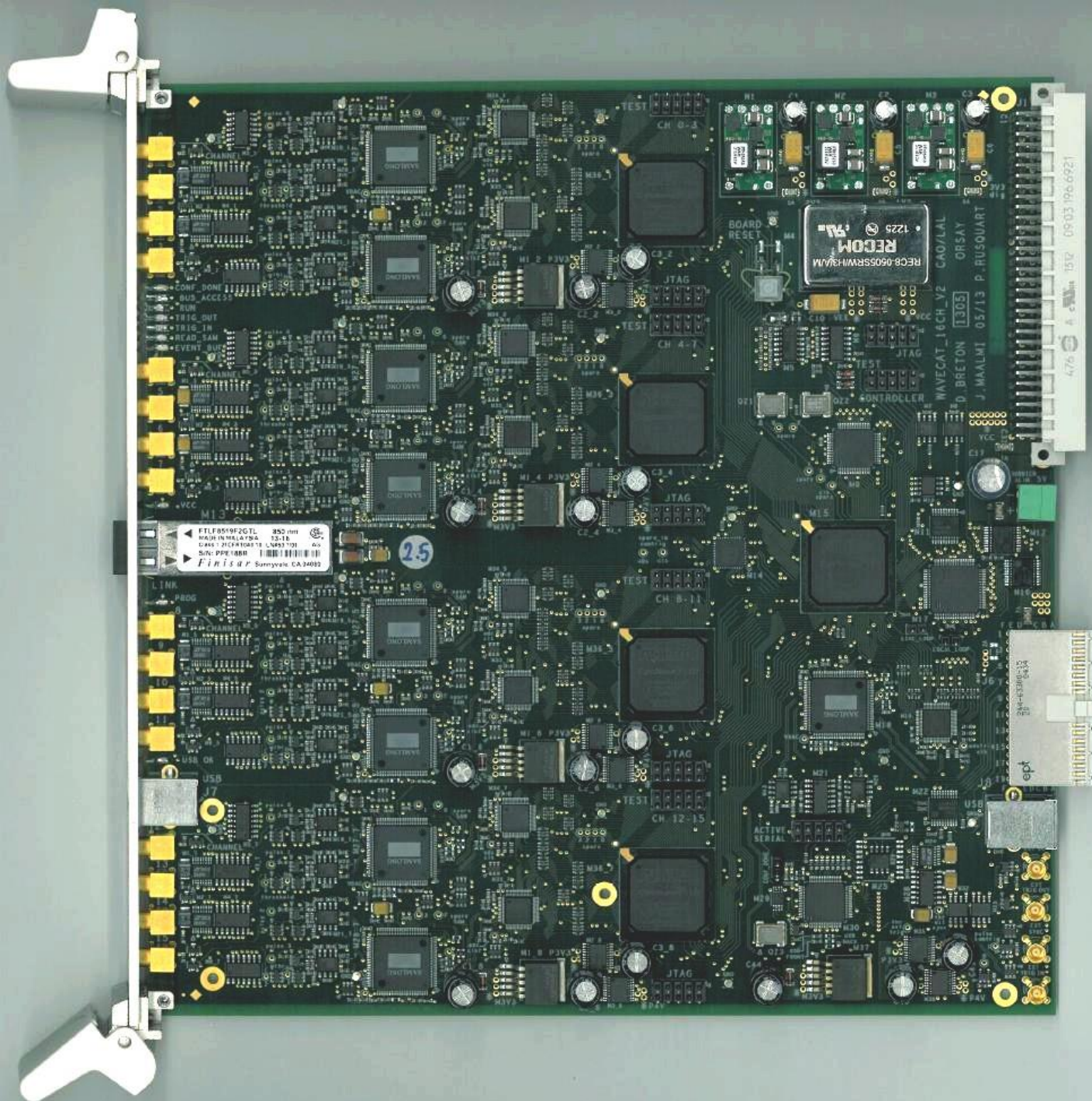
The historical 2-Channel module



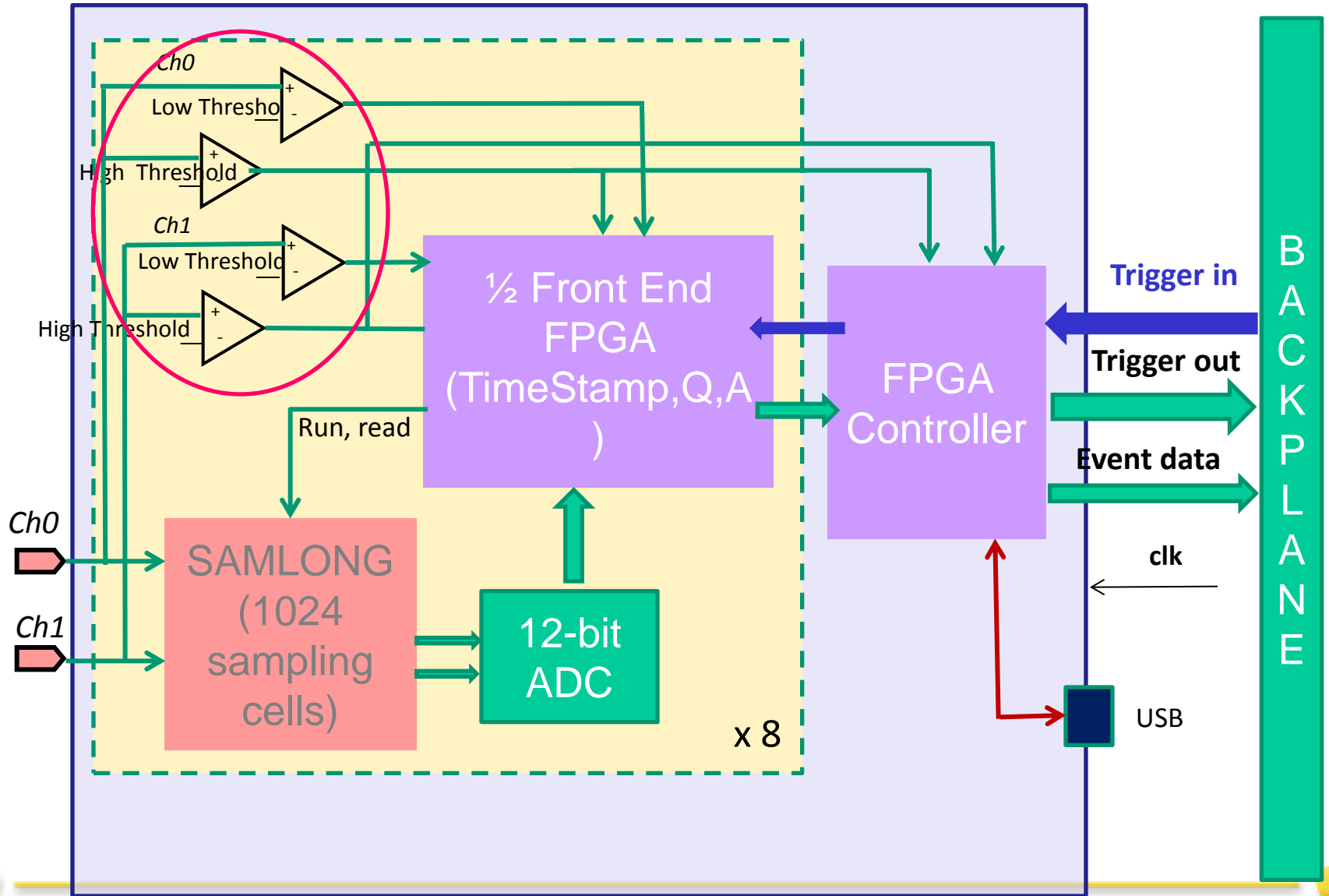


## The 16/18-channel board

- 1.6mm thick
- 10 layers
- 233 x 220 mm<sup>2</sup>
- **3200 components**
- 25 power supplies (5 global, 20 local)
- Four **4-channel blocks** (can be used as **mezzanines** on other boards)
- **2 extra channels** dedicated to « digital » signals



# 2-channel front-end diagram





# Front-end block can be used as a mezzanine

The latter's design is compatible with the **CAEN X743** digitizer board family



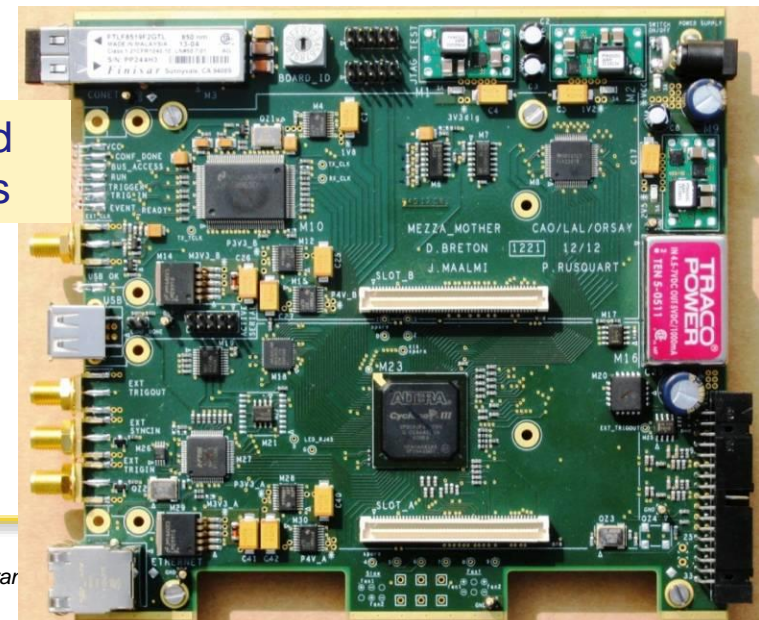
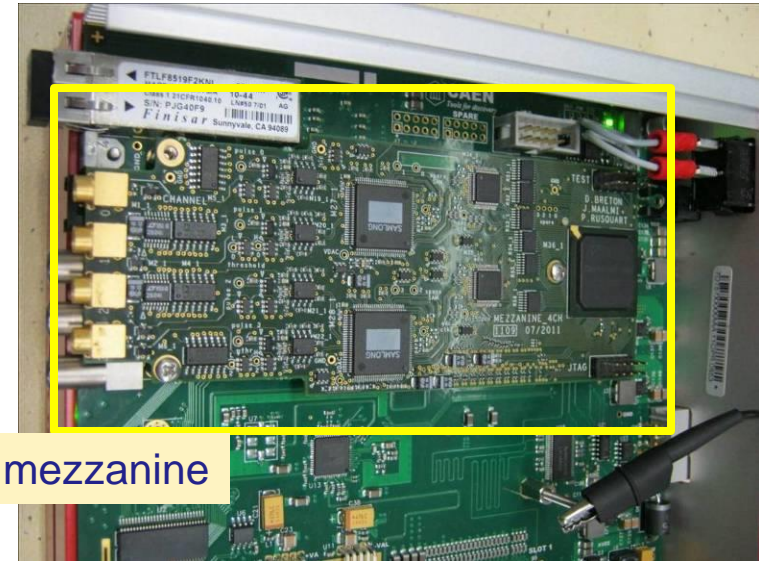
2013

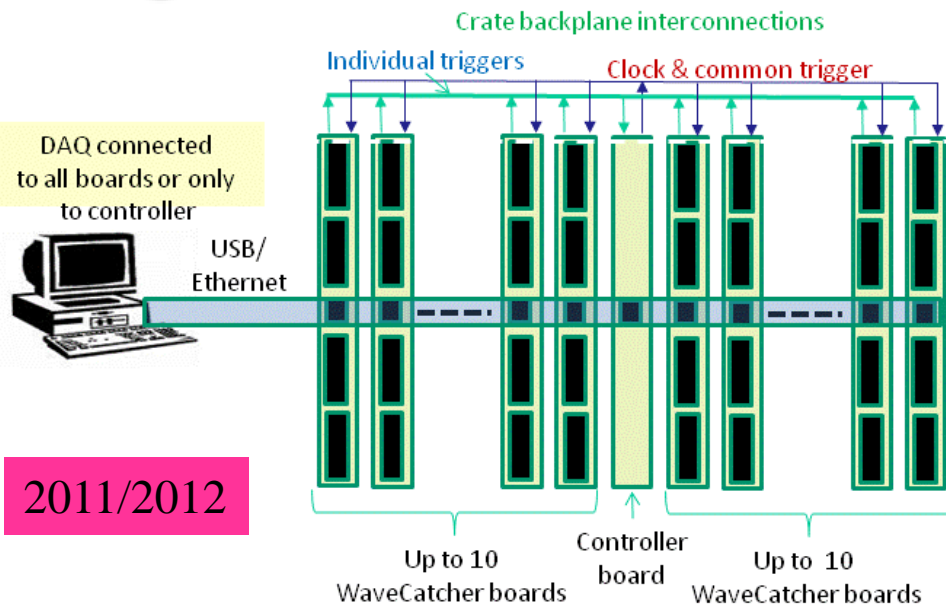
2011

Front-end mezzanine

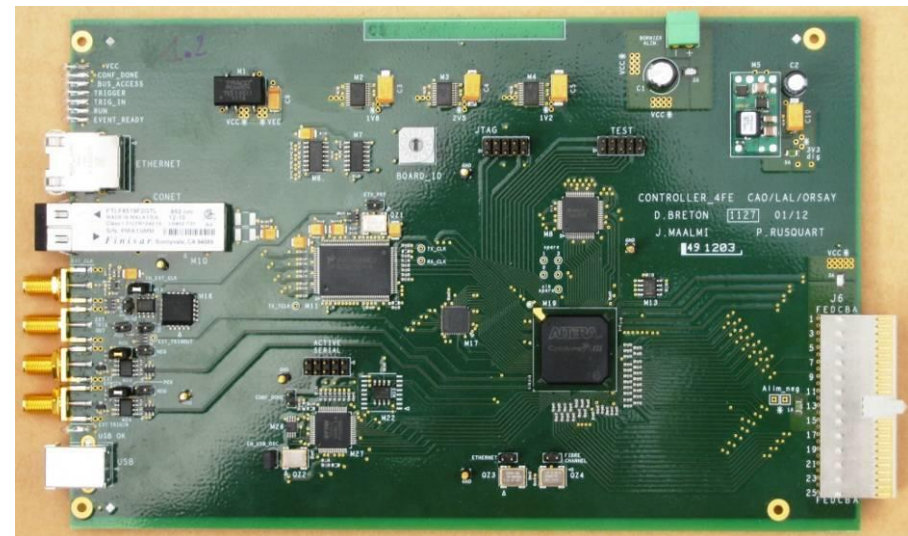
LAL motherboard for 2 mezzanines

2012





The controller board



64-channel backplane



- To **synchronise** many boards a **controller board** is needed, plus a backplane for the interconnections
- we have built a very compact 64+8-channel system:
  - ➔ already used for the CORTO Cosmic Ray Telescope at Orsay and for a prototype of new Gamma Spectrometer for particle detection, soon at CERN for beam characterization
- we are also building a 960-channel system based on 3 6U-crates (for the first module of the future SuperNemo neutrino experiment)




# The 64+8-channel digitizer

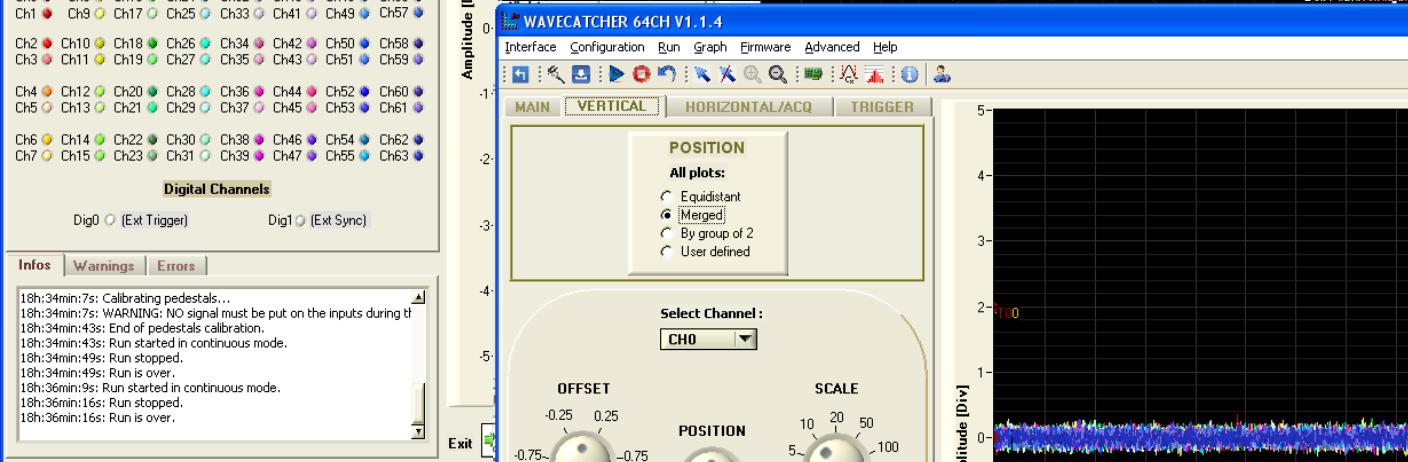
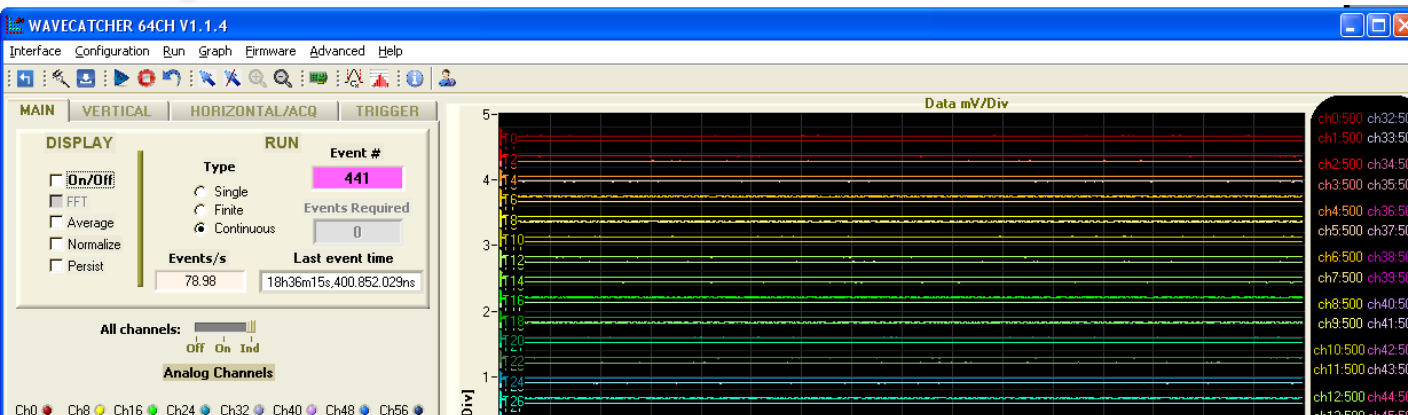


2013

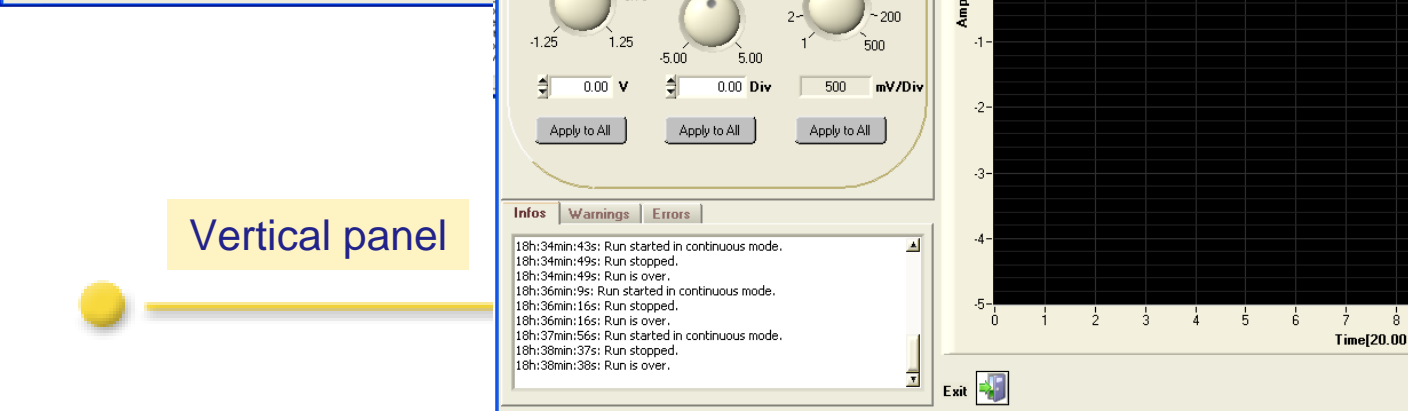


- ❖ Possibility to add an **individual DC offset** on each channel
- ❖ **Individual trigger discriminator** on each channel
- ❖ Integrated **raw trigger rate counter** on each channel
- ❖ External & internal trigger + different modes for **coincidence triggering**
- ❖ **2 extra memory channels** for « digital » signals on 16-channel board  
=> **can be used as additional analog inputs**
- ❖ One **pulse generator** on each input
- ❖ **External clock** input for multi-board applications (8, 16 & 64-channel)
- ❖ Embedded **USB, UDP and Gigabit optical interfaces** (8, 16 & 64-channel)
- ❖ Possibility to upgrade the firmware via **US**
- ❖ **Embedded charge extraction**
- ❖ **Embedded signal amplitude and baseline extraction** 
- ❖ **Embedded digital CFD for time measurement**

Main panel:  
oscilloscope  
like, but  
64 channels !



Vertical panel





**WAVECATCHER 64CH V1.1.2**

Interface Configuration Run Graph Firmware Advanced Help

MAIN VERTICAL HORIZONTAL/ACQ TRIGGER

**TRIGGER DELAY**

27.00 36.00  
18.00 45.00  
9.00 -54.00  
0.00 63.00

**SAMPLING [GS/s]**

1.07 1.28  
0.8 1.6  
0.53 -2.13  
0.4 3.2

0.00 Div 312 ps/sample

Recording depth: Shortened Full

Specified depth: 64 x 16 samples = 0.00 ns

Infos Warnings Errors

18h:2min:27s: Run started in continuous mode.  
18h:2min:43s: Run stopped.  
18h:2min:43s: Run is over.  
18h:2min:43s: Run started in continuous mode.  
18h:2min:47s: Run stopped.  
18h:2min:47s: Run is over.  
18h:2min:47s: Run started in continuous mode.  
18h:4min:0s: Run stopped.  
18h:4min:1s: Run is over.

Exit

Horizontal/acq panel

**WAVECATCHER 64CH V1.1.4**

Interface Configuration Run Graph Firmware Advanced Help

MAIN VERTICAL HORIZONTAL/ACQ TRIGGER

**Trigger Sources:** All channels: OFF On Ind

Ch0	Ch8	Ch16	Ch24	Ch32	Ch40	Ch48	Ch56
Ch1	Ch9	Ch17	Ch25	Ch33	Ch41	Ch49	Ch57
Ch2	Ch10	Ch18	Ch26	Ch34	Ch42	Ch50	Ch58
Ch3	Ch11	Ch19	Ch27	Ch35	Ch43	Ch51	Ch59
Ch4	Ch12	Ch20	Ch28	Ch36	Ch44	Ch52	Ch60
Ch5	Ch13	Ch21	Ch29	Ch37	Ch45	Ch53	Ch61
Ch6	Ch14	Ch22	Ch30	Ch38	Ch46	Ch54	Ch62
Ch7	Ch15	Ch23	Ch31	Ch39	Ch47	Ch55	Ch63

Select Channel: CH0

**TriggerType**

- Software
- Normal
- Internal
- External
- Coincidence

THRESHOLD: 0.000

with ext trig

Gate Length: 10 ns @3.265/s

Edge:  FL   FR

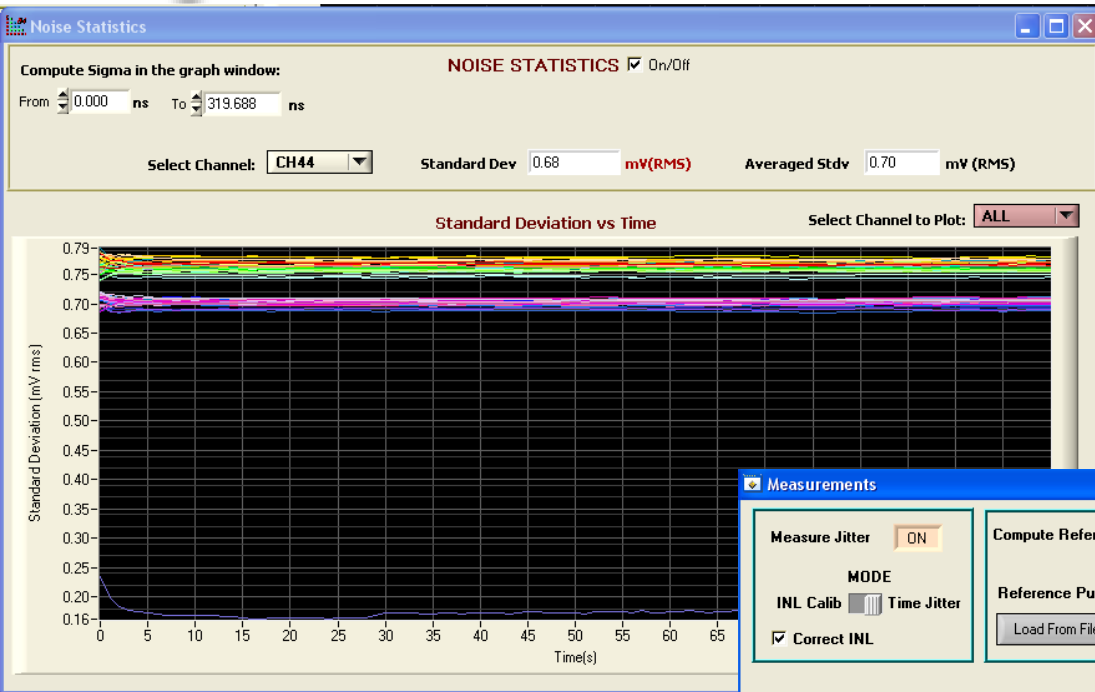
Apply to All

Infos Warnings Errors

18h:40min:21s: Run started in continuous mode.  
18h:40min:55s: Run stopped.  
18h:40min:55s: Run is over.  
18h:40min:55s: Run started in continuous mode.  
18h:40min:56s: Run stopped.  
18h:40min:57s: Run is over.  
18h:40min:57s: Run started in continuous mode.  
18h:41min:26s: Run stopped.  
18h:41min:26s: Run is over.

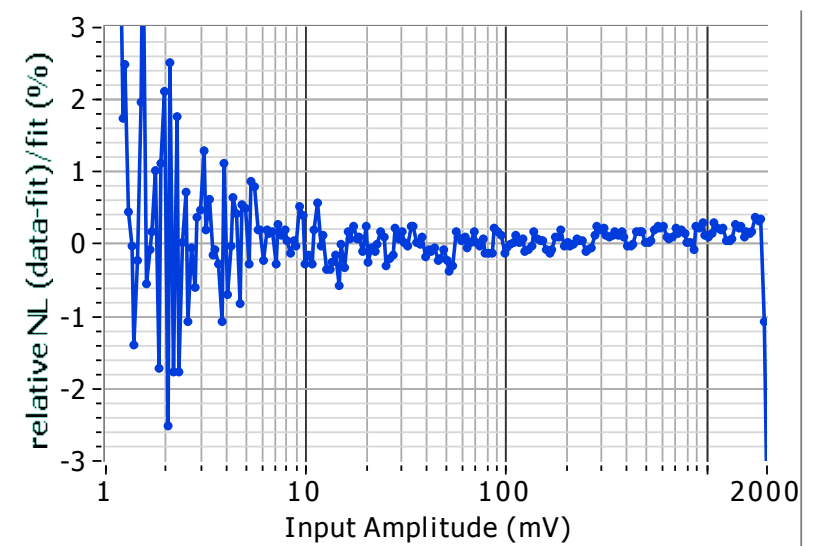
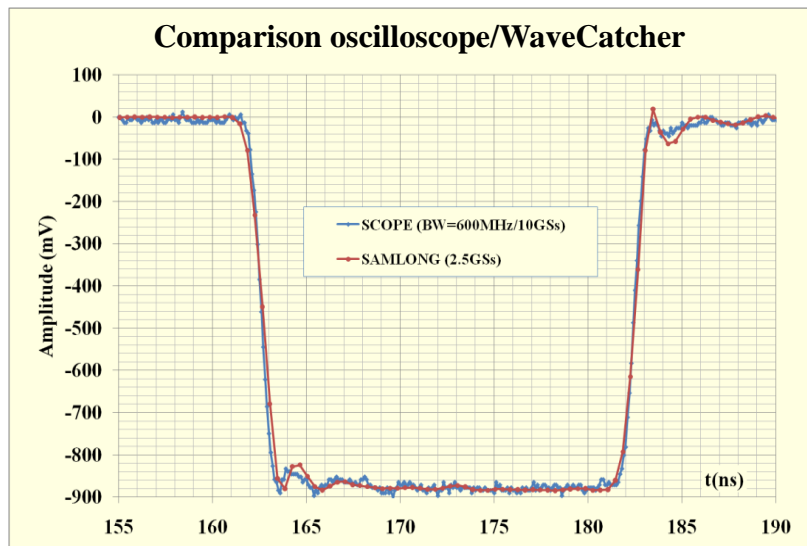
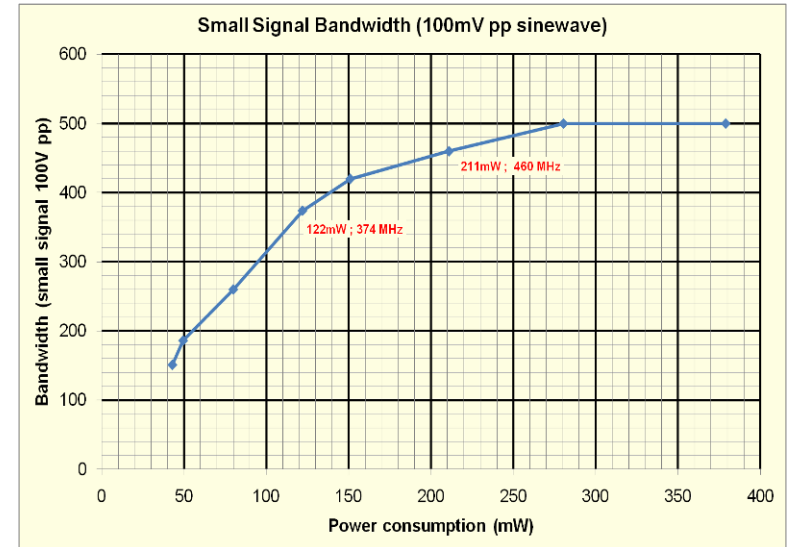
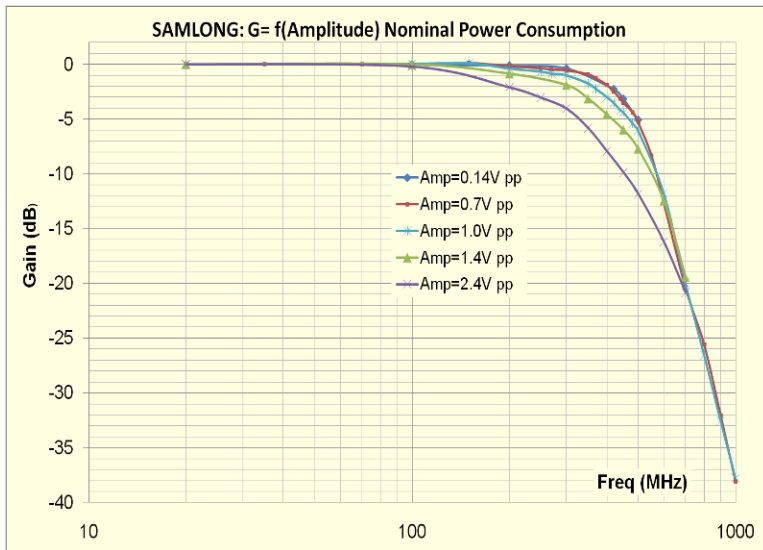
Exit

Trigger panel



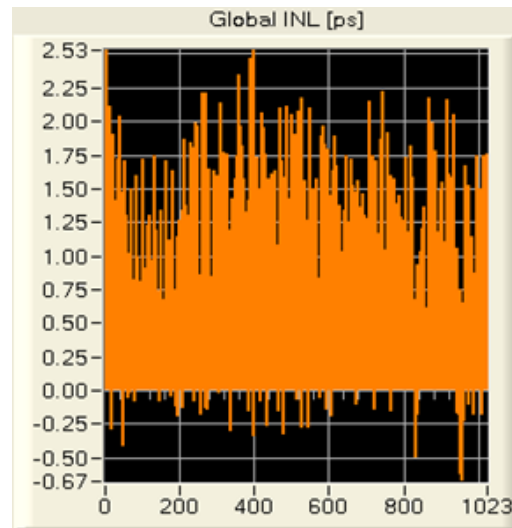
Noise statistics panel

➤ Software also comprises a powerful time measurement panel



- DC-coupled **1024-deep channels** with 50-Ohm active input impedance
- **$\pm 1.25\text{V}$**  dynamic Range, with full range 16-bit individual tunable offsets
- **Bandwidth  $\sim 500\text{MHz}$**
- **Signal/noise ratio: 11.7 bits rms** (noise =  **$700\ \mu\text{V RMS}$** )
- **Sampling Frequency: 400MS/s to 3.2GS/s**
- **SAMLONG power consumption:  $\sim 400\ \text{mW}$  for 2 channels (full bandwidth)**
- **2-channel readout dead-time for 1024 cells:  $125\ \mu\text{s}$  ( $66\ \mu\text{s}$  @ 20 MHz)**
- Acquisition rate (**full events**) is not limited by USB (30 Mbytes/s) but by the software and the capacity to store events on disk
- Acquisition rate (**data extraction in FPGA**): see next slides
- **Time performances will be described later in this talk**

# Time calibration and performances

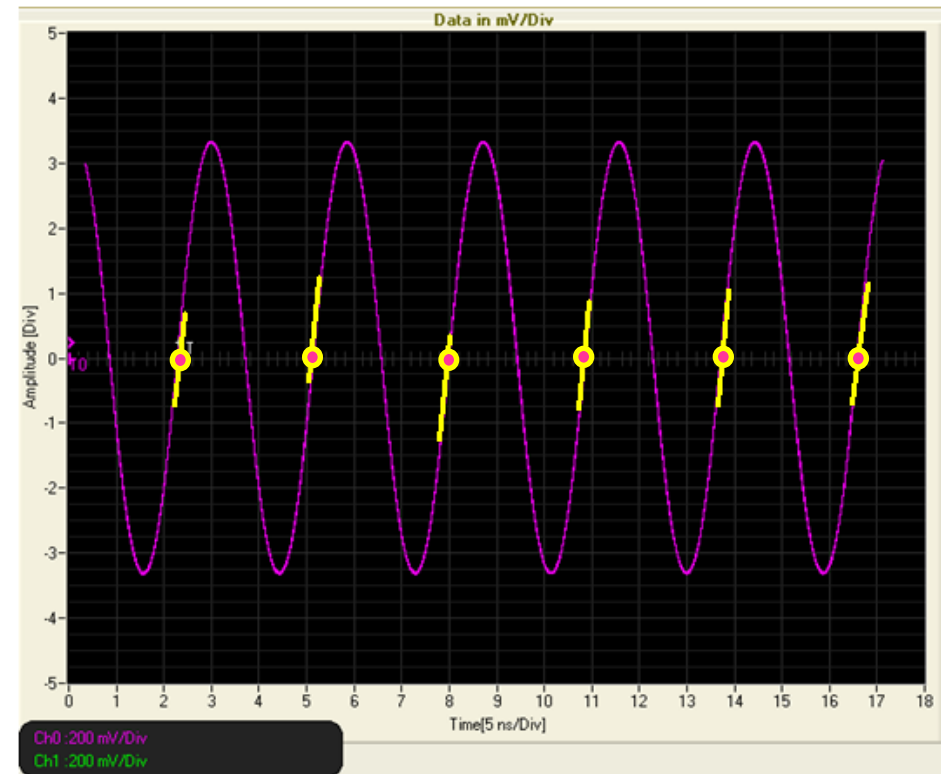




The basics of our calibration method have been described many times since TWEPP 2009 conference. This simple method is based both on statistics and on direct measurement performed on a repetitive signal. The absolute value of the measurements is based on the period of SAMLONG's main clock.

➤ Search of **zero-crossing** segments of a sine wave => **length and position**

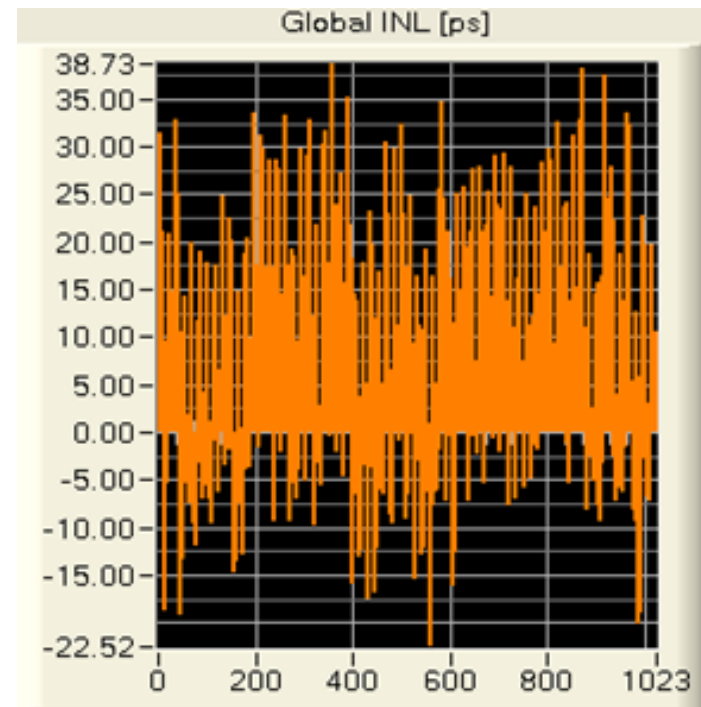
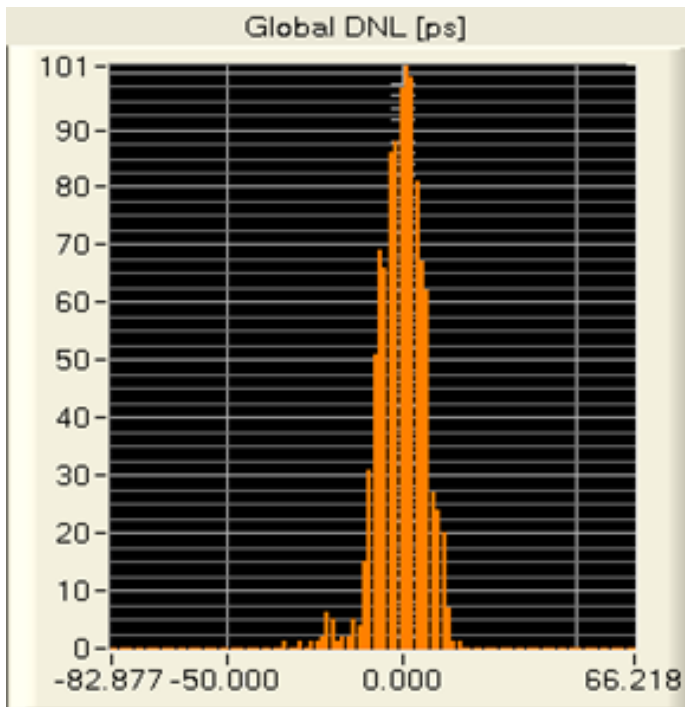
- **Length** is proportional to time step duration assuming that sine wave is a straight line (bias is very small). Due to the circular design of the memory, the sum of the segments is equal to the round trip, which corresponds to a known amount of SAMLONG clock periods.
- **Position** of zero-crossings is periodical so their distance should be constant.



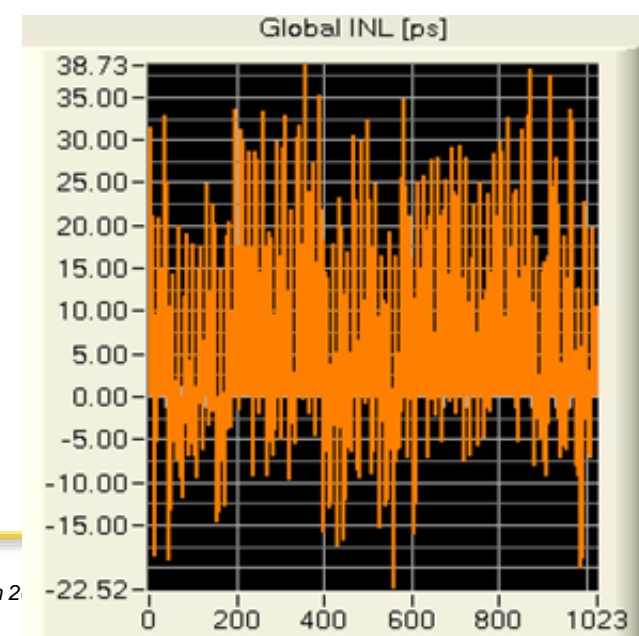
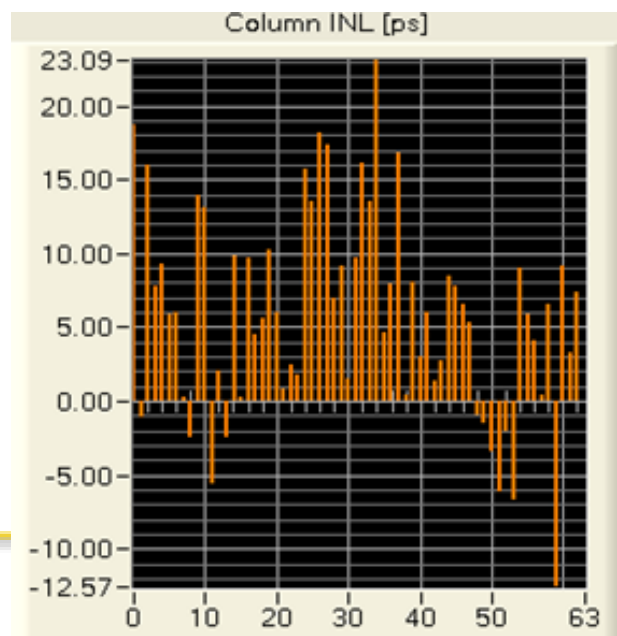
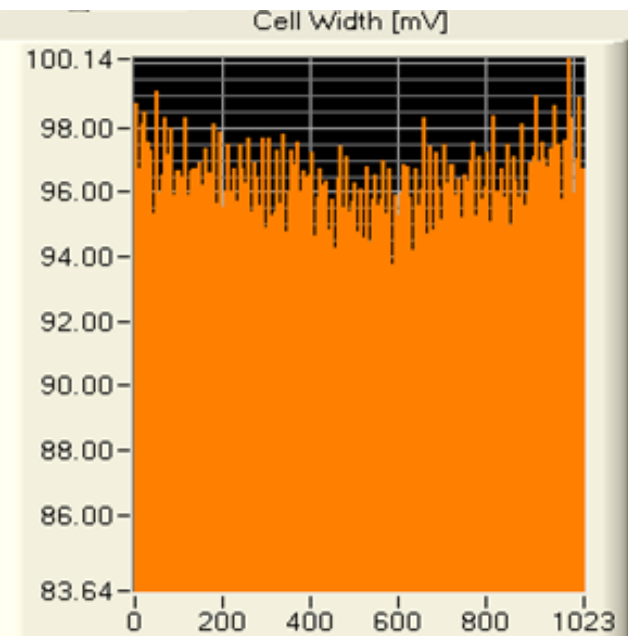
➤ **Without any time corrections, the levels of raw time DNL and INL already give a good time resolution of the order of 15 ps rms**

- Raw DNL is usually below 8 ps rms and raw global INL below 15 ps rms
- See example below, randomly extracted from a 16-channel WaveCatcher board

Global DNL 6.4 ps rms, Global INL 11.1 ps rms



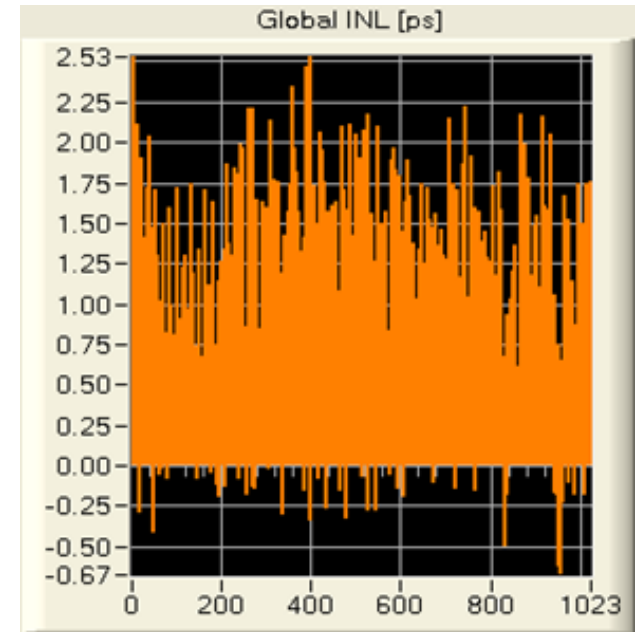
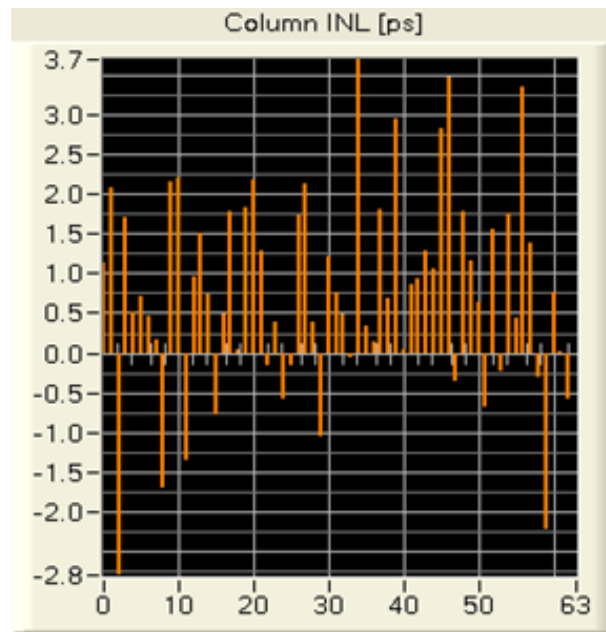
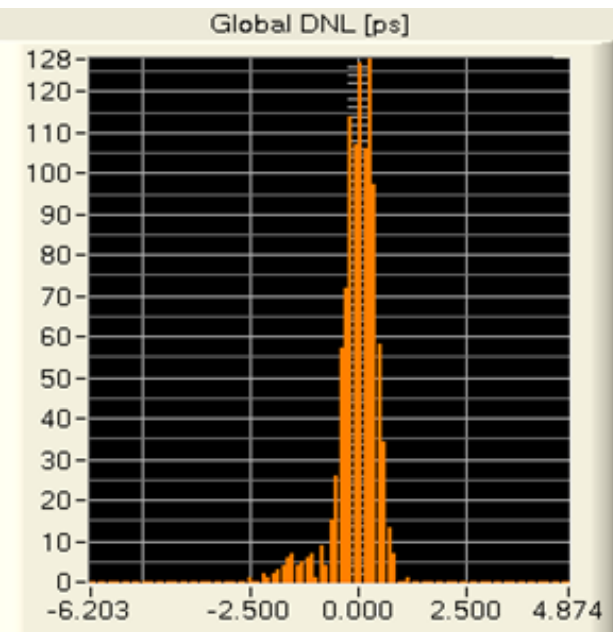
- **Due to the Matrix structure of the circuit, DNL is locally linked to columns**
  - Length of segments displays a structure modulo 16 which corresponds to the number of lines
- **Measuring the distance in samples between zero-crossings and knowing that the round trip around the memory is 320 ns (@3.2GS/s) gives the Column INL.**
- **Interconnecting the column DNL extracted from the segments with the column INL gives the global INL.**



➤ Relaunching the calibration with INL correction active gives an idea of the quality of said correction

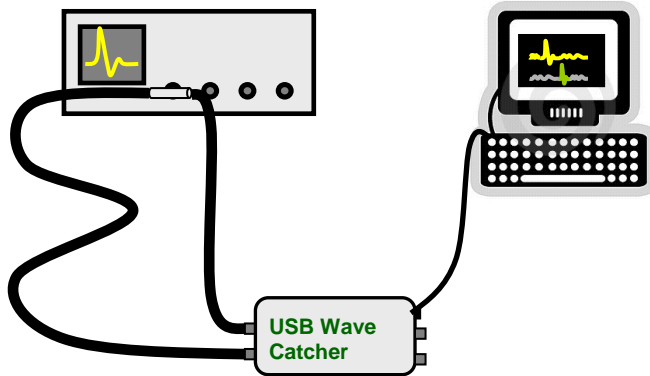
- Global DNL usually gets **below 0.5 ps rms**
- Global INL usually gets **below 1 ps rms**

Global DNL 0.53ps , Global INL 0.75ps



- **Source: asynchronous** set of two positive pulses hitting the memory wherever

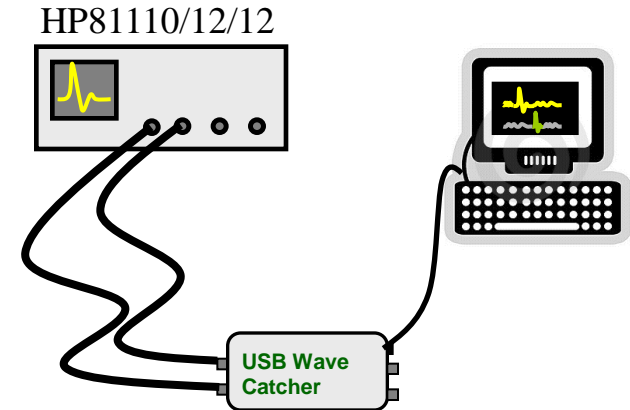
➤ For the least jitter



Same pulse splitted and sent to two different channels:  
distance between pulses depends only on  
the cable lengths

➔ with this setup, we can measure precisely the time difference between the pulses **independently of the timing characteristics of the generator!**

➤ For an easier setup



Two pulses coming from two different outputs of the generator:  
distance between pulses is programmable

➔ in this case, the jitter of the generator is added to the measurements.

## ➤ Pulses are produced by an AFG3252 arbitrary generator

- Rise and fall time are 2.5 ns
  - FWHM is 4 ns.
  - Amplitude is 1.25 V
- ⇒ Slope ~ 0.5V/ns

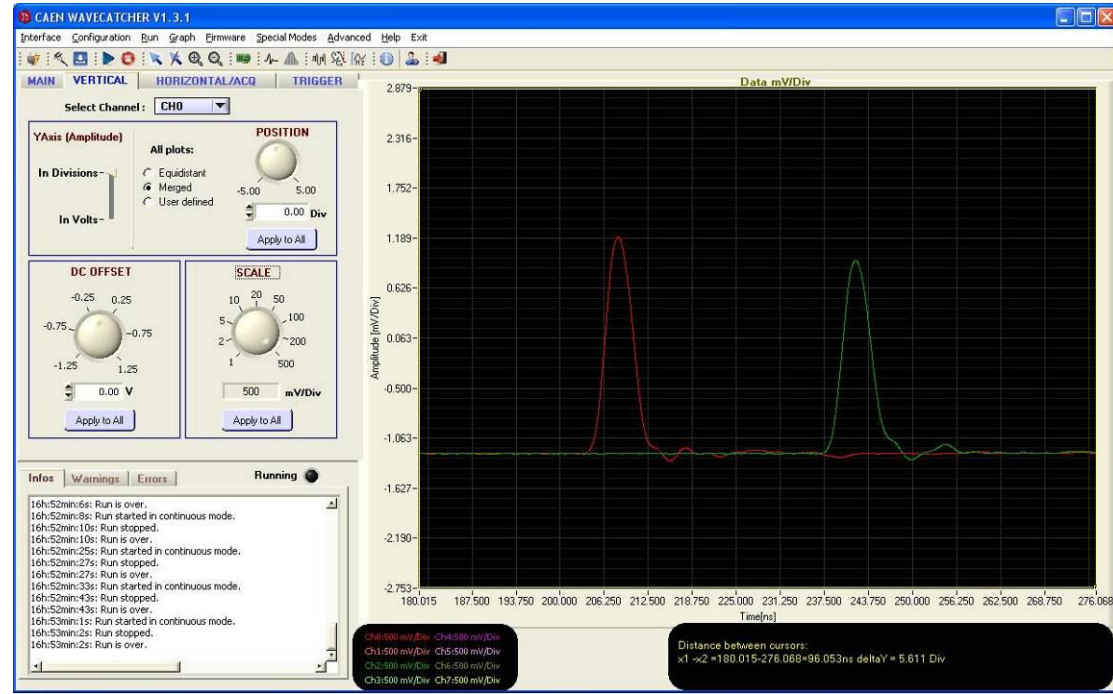
## ➤ We also use HP81110/12

- Rise and fall time are 1.6 ns
- FWHM is 2 ns.
- Amplitude is 0.7 V.

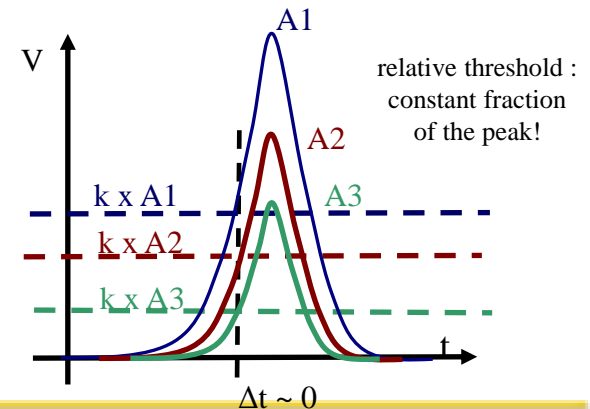
## ➤ Results are equivalent with both generators using delay cables

## ➤ We can use either a fixed threshold or a digital CFD (performed by software)

- Results are equivalent for digital pulses



## Constant Fraction Discriminator

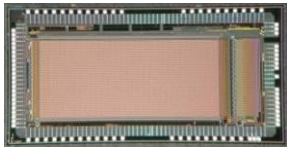




Delays are performed with cables to limit jitter. Trigger on signals.

➤ Reaching the ps level at the chip level is a challenge, keeping it at the system level is another.

- Difficulty here is the use of daughterboards



Ch0-Ch1

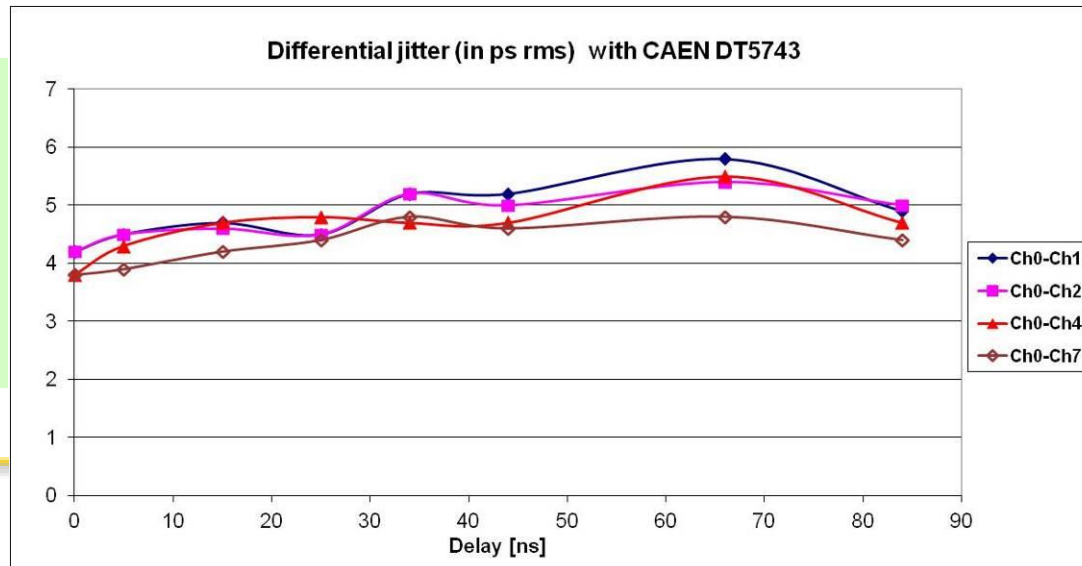


Ch0-Ch2



Ch0-Ch4  
Ch0-Ch7

Differential jitter between channels:  
4 to 6 ps rms  
almost flat and  
independent on  
channel location

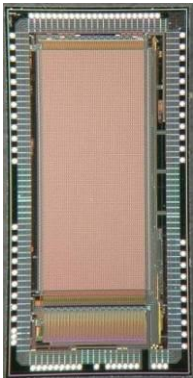


⇒ chip resolution  
~ 4 ps rms

Delays are performed with cables to limit jitter. Trigger on signals.

➤ **Difficulty here is the use of a backplane to distribute the clock.**

- Central control board is the source of the 200 MHz clock



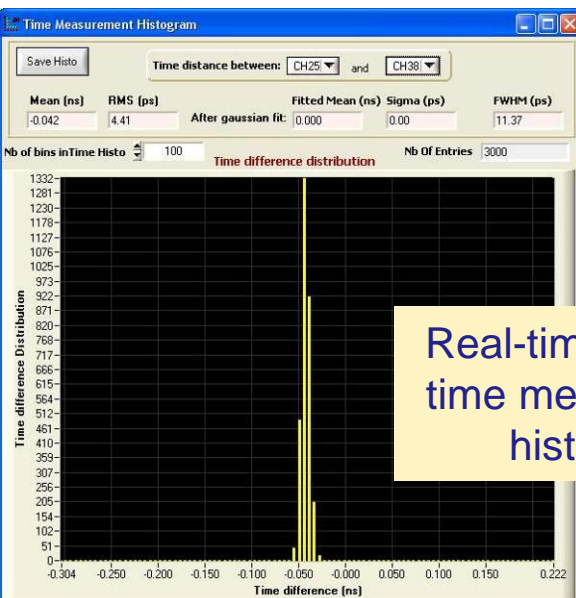
Ch0-Ch1



Ch0-Ch4

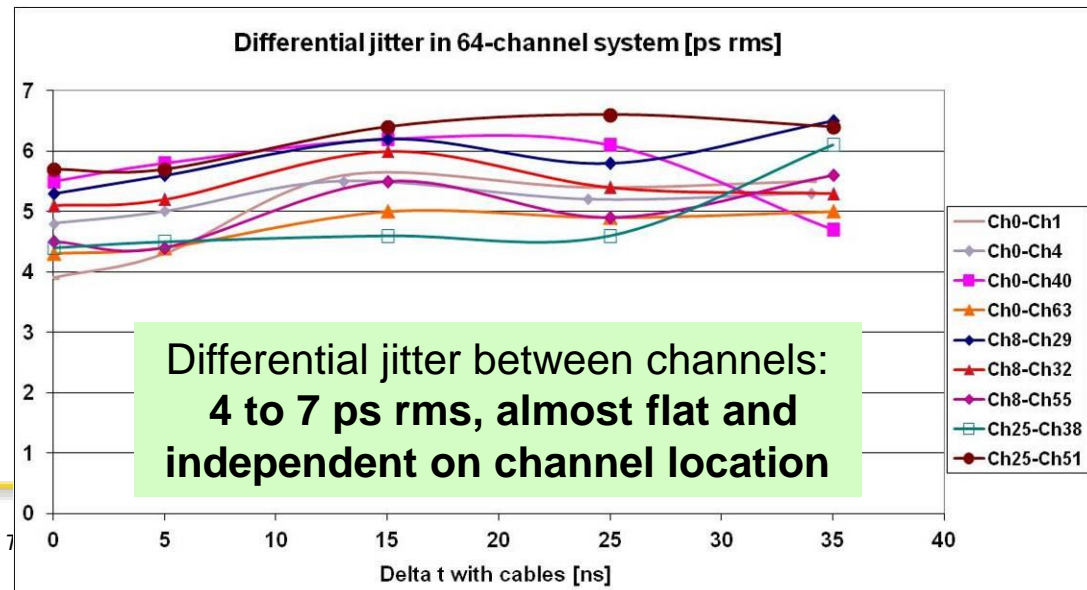


All other pairs

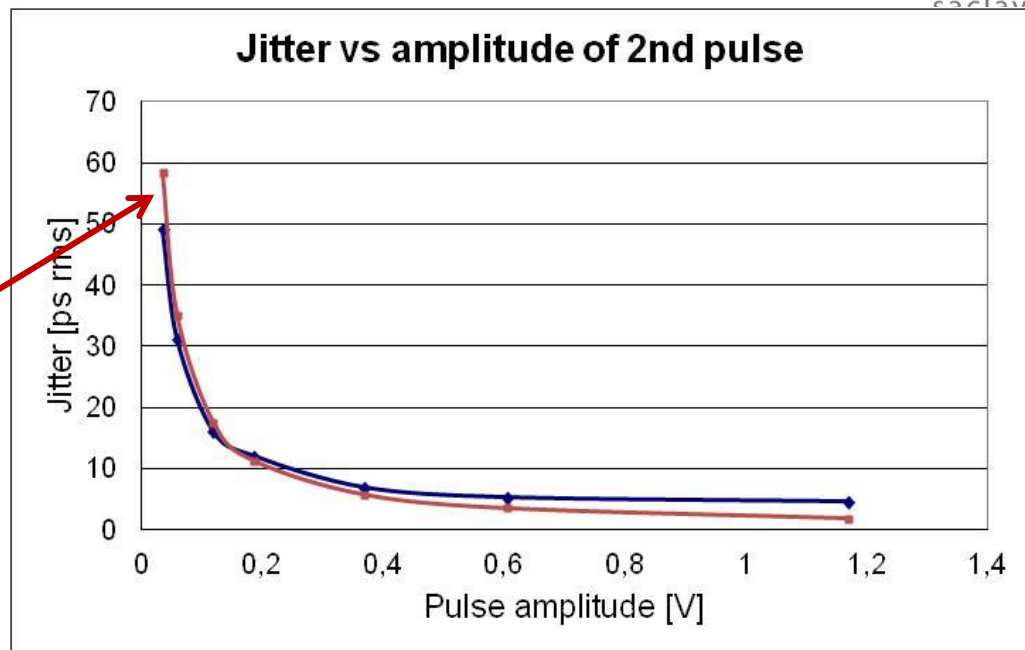


Real-time software time measurement histogram

D. Breton - Ps T



- Effect of the amplitude of the second pulse on the measured jitter
- Mode used is CFD
- **Signal slope to noise** ratio is dominant here
  - 0.7-mV noise theoretical contribution is displayed in brown
  - A more complex method than CFD (like chi2 ) would be necessary to improve time resolution for small signals



- **Reaching this level of performance, you become sensitive to any “detail”**
- Temperature is one of them!
  - Any uncompensated element in the measurement chain will modify the result
  - There is a sensitivity in the SAMLONG chip at the level of the phase comparator
  - Effect on the measurement seems of the order of **2 ps for a 5-degree difference with the calibration temperature** => for high precision measurement, cooling has to be mastered (could be a problem mainly for single boards, cooled by user)
  - We already have clues to still improve the temperature stability

- **One of the weak points of the analog memories is the readout dead-time:**

- Thanks to the posttrig system, the read pointer can target the area of interest where the signal seats, reducing the quantity of data to read if the full waveform is not necessary ...
- We worked on increasing the readout frequency (which is also the ADC frequency) **up to 20 MHz.**

Readout length	Nb of events in derandomizer	Dead-Time@ 10 MHz [ $\mu$ s]	Dead-Time@ 20 MHz [ $\mu$ s]
Max: 1024 cells (64 columns)	7	125	66
Min: 64 cells (4 columns)	97	19,6	11.8

- At 20MHz, noise level rises only by a few % (0.75mV).
- USB and software usually are the main limitation for dataflow, especially if complex correction algorithms have to be used.



- The very good level of performance of the SAMLONG chip without external correction permits implementing **an effective on-the-fly calculation directly on the board** (in its companion FPGA) :

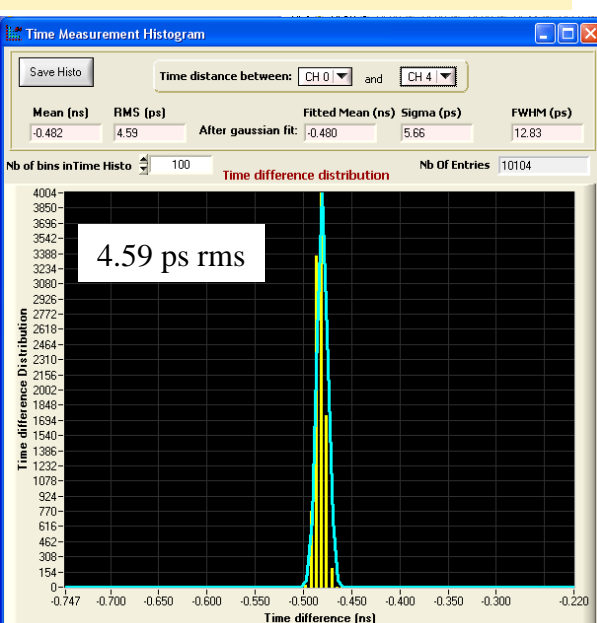
This information is extracted from raw data directly coming from SAMLONG (with on-chip correction of the line offsets)

- **Baseline** (16 bits)
- **Peak** (16 bits)
- **Charge** (23 bits)
- **Real Digital CFD on Rising and Falling edge Time** : (18 bits : bin of **1.22 ps**)
- **Absolute Time** : given by the FPGA **40-bit TDC timestamp**

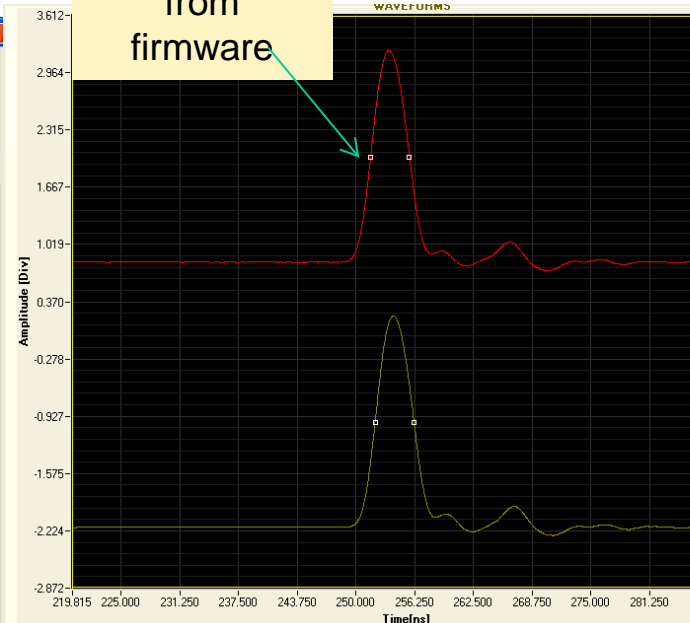
(Logic elements used for this calculation in the Cyclone 3C16 FPGA < 1000 per channel)

- The **Raw Time Resolution** of extracted CFD time is **~15 ps rms**
- Time resolution after **INL correction** on both edges is **3 to 4 ps rms**
  - **This result is equivalent to that obtained with Software Time extraction on the waveform**
  - **The INL correction will also be implemented inside the FPGA.**

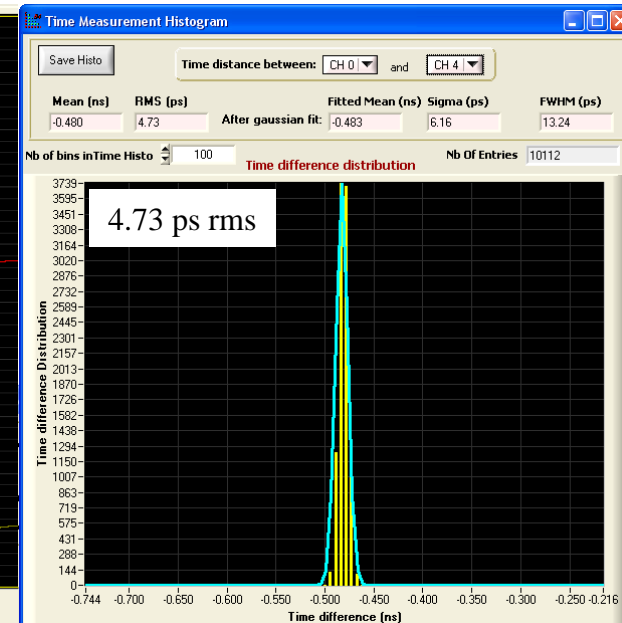
## Software Time extraction



CFD points  
received  
from  
firmware



## Firmware Time extraction



For systems with a high number of channels, the type of software data treatment is constrained by three factors that are linked to the system :

1. **Trigger Rate** : the data rate is directly linked to it
2. **Capacity to save data on disk** : the more data per event, the bigger the time to store it and the bigger space needed on disk
3. **Capacity to perform online treatment** :
  - Takes time **but** reduces the data flow
  - If complex → takes more time

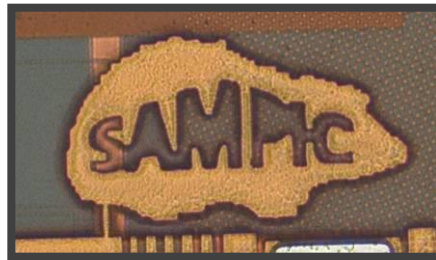
An ideal optimized system would follow the trigger rate and store on disk only data fulfilling the experiment requirements.

This is why for **High Trigger Rate** systems, online data treatment has to be **as limited as possible**, nevertheless offering a **very good precision** (for instance, high-degree polynomial fit of signal does not seem to be a reasonable option for on-line calculation, but ok for off-line studies)

For very fast acquisition system, **firmware extracted data is the ideal solution ( → no software online treatment )** : with the WaveCacher systems it gives an almost similar time precision (up to 64 channels as of today)

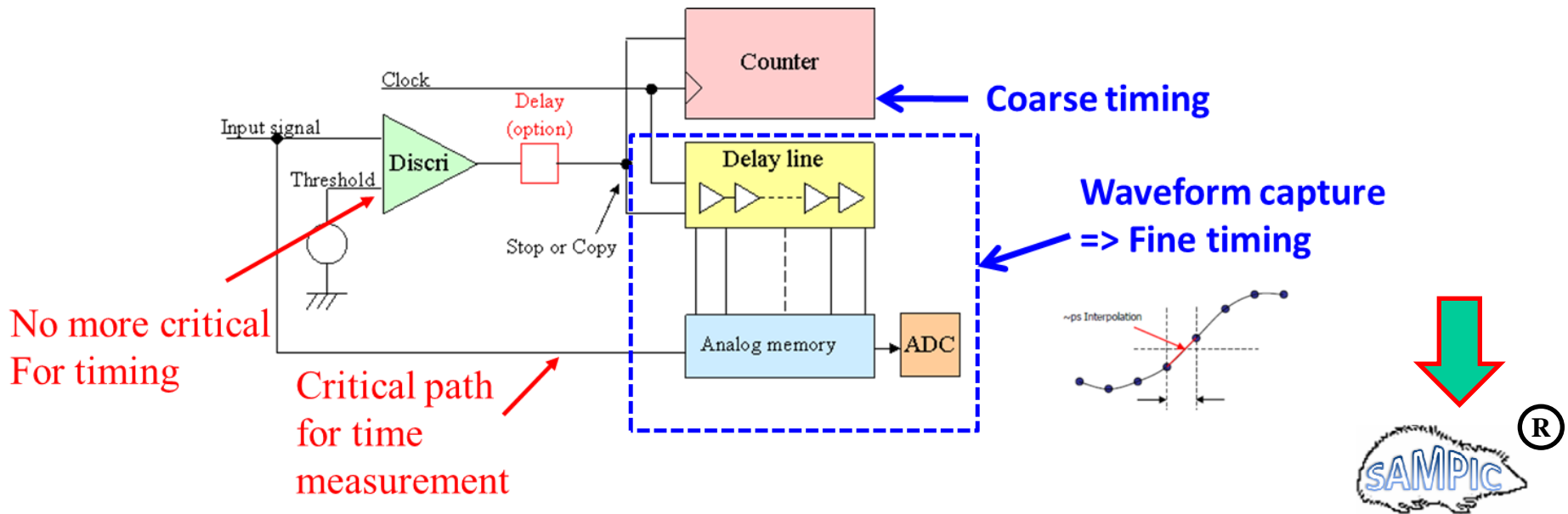
→ expected event rate with 16-ch board > **10 000 evts/s**.

Now, let's follow the Hedgehog ...





- So, from all that was said before, what about a TDC mixed with an analog memory and an ADC ?
  - => Introducing the new concept of **Waveform TDC**
    - Works on analog signals!
- Time, Waveform Shape, Charge, Amplitude are all available

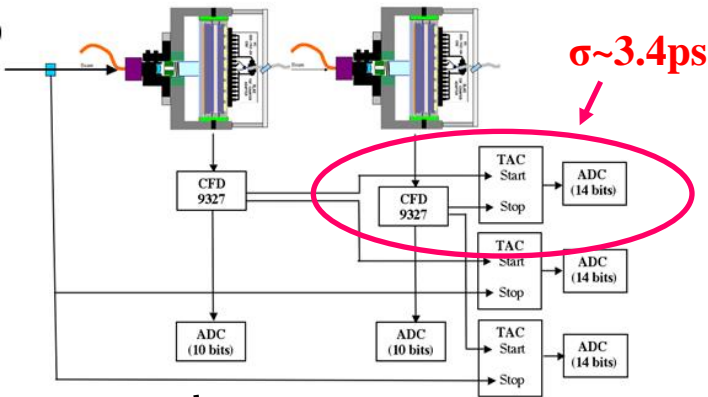


- ✓ **Waveform sampling** permits **high precision time measurements** (a few ps rms)
  - ADCs would do the job nicely but at least 99% of data would go to the bin at owner's expense! (power, FPGA, ...)
- ✓ **Analog memories** actually look well adapted to the task at large scale and for reasonable trigger rates:
  - **Dead-time remains a limitation: recently reduced in our system down to 12  $\mu$ s**
  - **Embedded time extraction inside the FPGA permits benefiting of the minimum dead-time and reducing the dataflow: we presented the **First Embedded Timing Resolution results obtained with Analog Memories** => ~3 to 4 ps rms!**
  - **We'll go on optimizing this feature extraction**
- ✓ Merging the advantages of a TDC and of analog memories:
  - **SAMPIC, the **Waveform TDC** ... (see talk by E.Delagnes)**

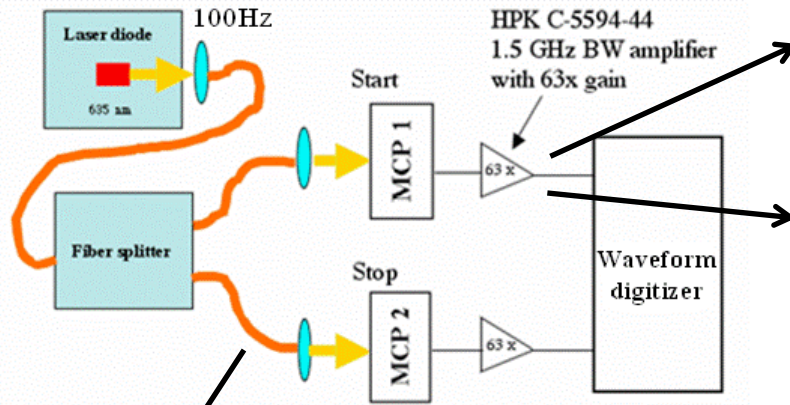
# Backup slides

Goal was to compare different electronics for measuring the signal time difference between 2 MCPPMTs => **NIM paper A 629 (2011) 123–132**

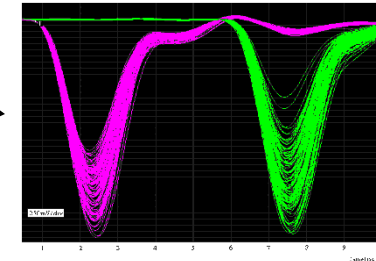
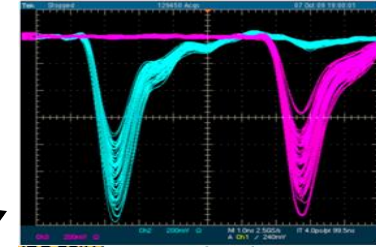
## Using Ortec modules



## Using Waveform Digitizers

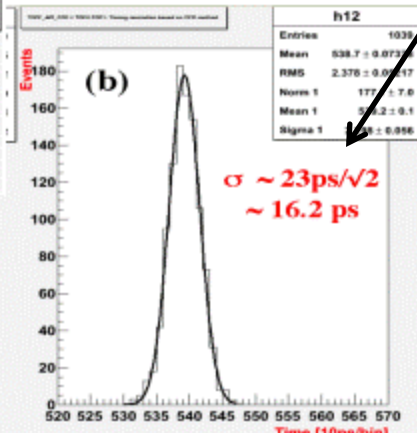
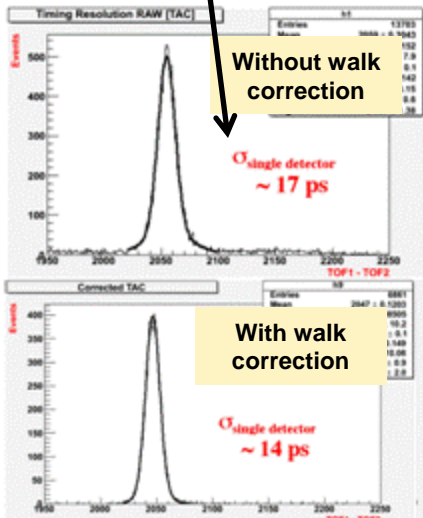


## Tektronix oscilloscope

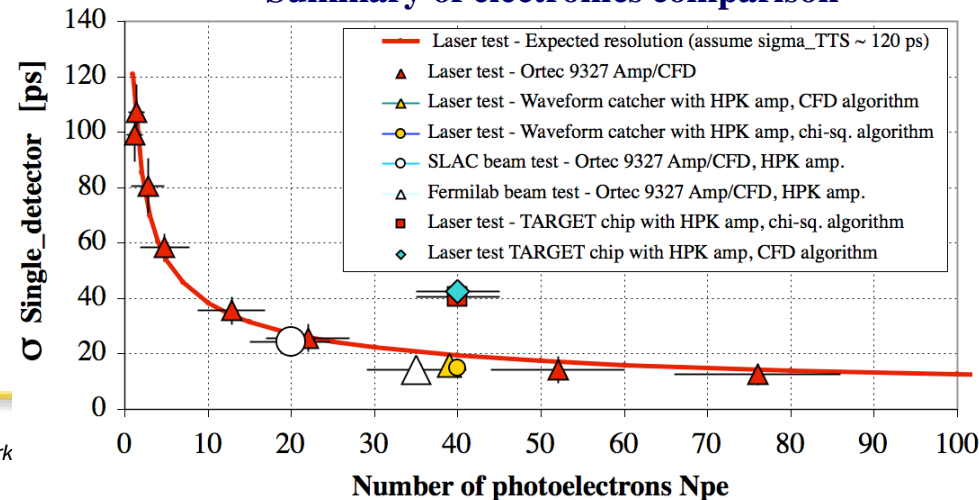


## WaveCatcher board

## Digital CFD method was used

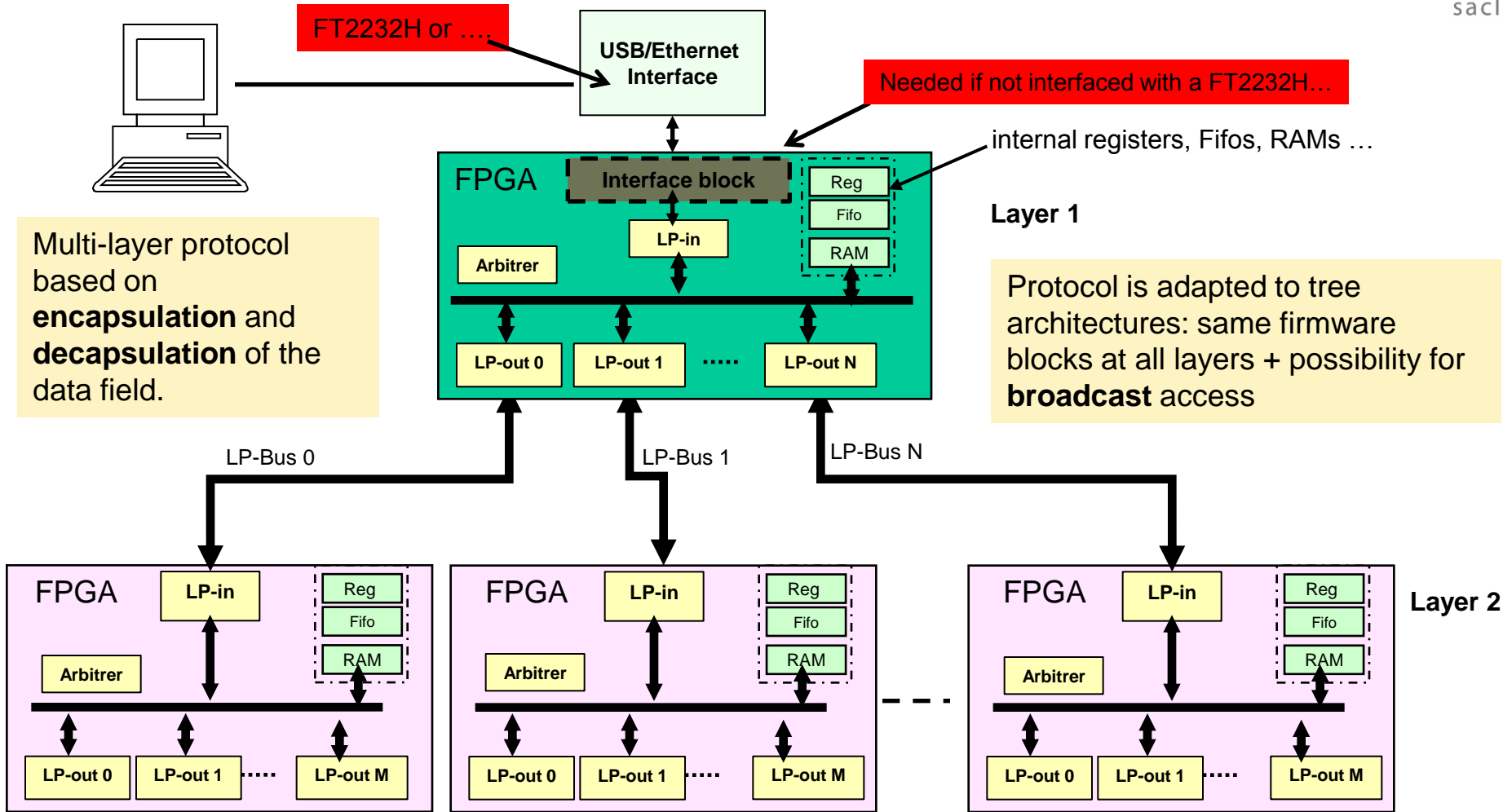


## Summary of electronics comparison





# A flexible architecture thanks to LAL-Usb & LP-Bus



Event fragments are **pushed** towards USB => this permits a **sparsified readout**