

RF HARDWARE OPTIONS

Very preliminary!

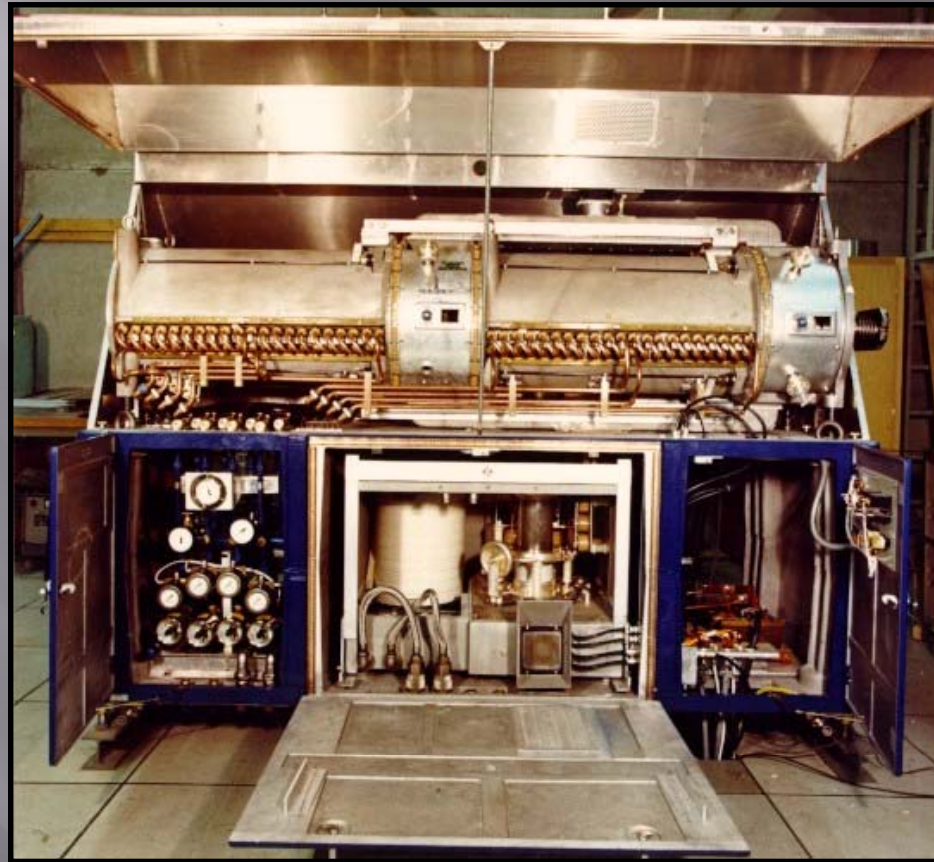
E. Jensen, 29-May-08

The 10 MHz route

- ▣ Present PS 10 MHz system:
 - 10+1 cavities, 2 gaps/cavity, 10 kV/gap
 - 2.7 ... 10 MHz tuning range
 - longitudinal imp. 3.5 k Ω /gap, reduced to 110 Ω with FB. (total 70 k Ω w/o FB, 2.2 k Ω with FB)
 - 2.4 m length/cavity (24 m long straight sections)

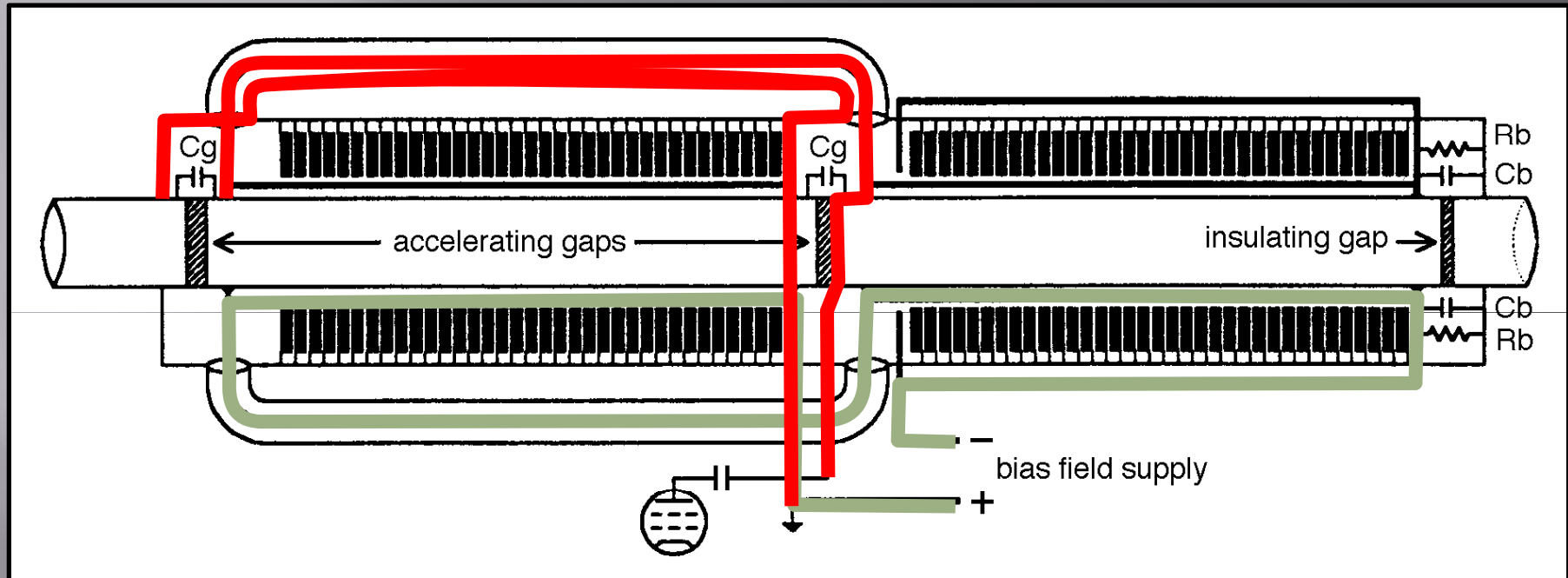
- ▣ Required in PS2 @ 10 MHz:
 - 500 kV (i.e. around 26 of these cavities or 60 m straight sections)
 - 13, 20, 40 and 80 MHz system, similar to present systems would also be required.
 - If the space is available, this can be done; no significant R&D required.

Present PS 10 MHz cavity



Installed around 1971

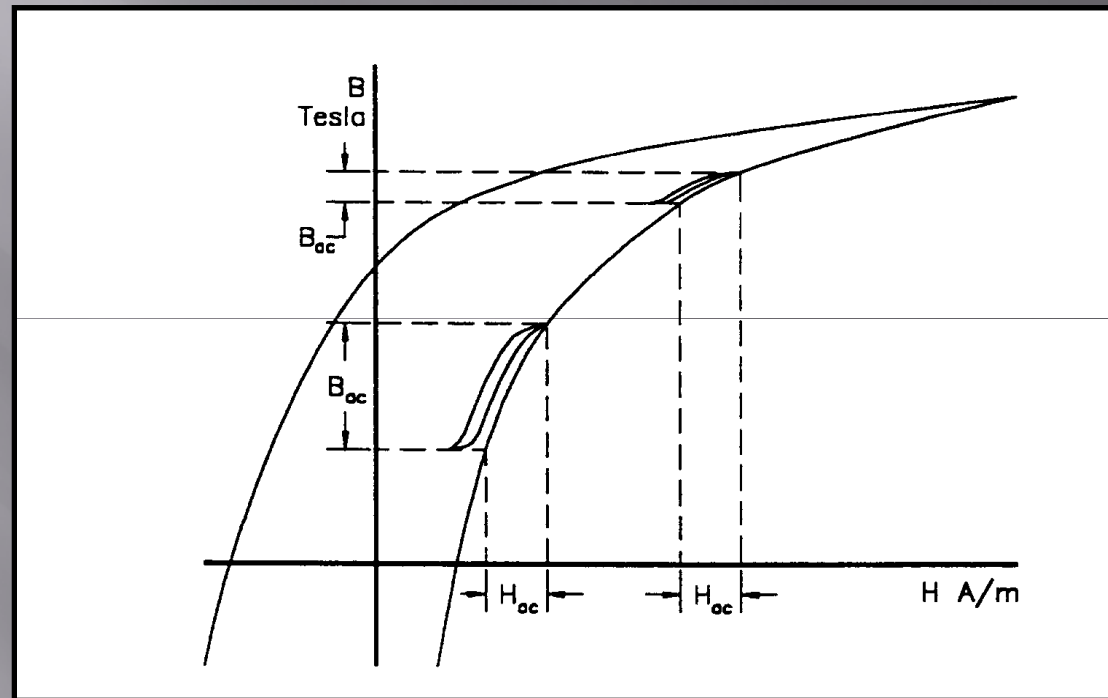
“standard” ferrite cavity



Tuning bias current circuit: azimuthal magnetization, ferrite toroid stacks in anti-series and with figure-of-8 current.

RF: 2 gaps (Cg) and input of coaxial lines (variable L) in parallel for the amplifier (in series for the beam). The RF magnetic field is azimuthal (parallel to DC magnetization).

μ : slope of magnetization curve



$$f \propto \frac{1}{\sqrt{L}} \propto \frac{1}{\sqrt{\mu}}$$

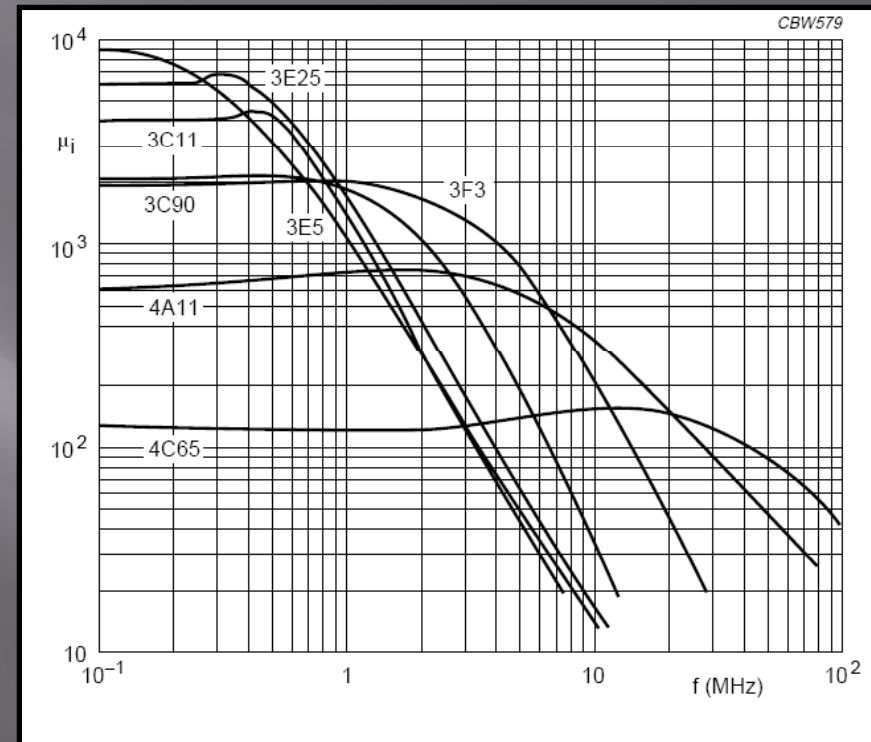
But: area inside hysteresis loop corresponds to losses. Loaded Q about 30.

The 40 MHz route

- ▣ Required:
1.5 MV, 18.5 ... 40 MHz
- ▣ Also required: new LEIR h=10 system, 10 ... 18.5 MHz, ≈ 15 kV; not considered here (easier than the PS RF system). Straight section available in LEIR? Alternative?
- ▣ Obvious question: can the concept of “standard” ferrite cavities be extrapolated to higher frequencies?

“Standard” ferrite cavity at higher f ?

- In principle yes, but
 - μ_i decreases with f !
 - smaller μ_i , smaller tuning range



- Losses grow with f
e.g. decreasing resistivity for NiZn ferrites:

FREQUENCY (MHz)	RESISTIVITY (Ωm)
0.1	$\approx 10^5$
1	$\approx 5 \cdot 10^4$
10	$\approx 10^4$
100	$\approx 10^3$

Excerpt from Ferroxcube® catalog

MATERIALS FOR PARTICLE ACCELERATORS					
Materials and relevant values					
PARAMETER	8C11	8C12	4M2	4E2	4B3
μ_i ($\pm 20\%$)	1200	900	140	25	300
μ_{rem} approx.	850	600	130	20	–
B_s 25 °C (mT, 800 A/m)	≥ 300	280	250	250	≥ 300
B_s 40 °C (mT, 800 A/m)	≥ 280	250	220	220	–
H_c (A/m, after 800 A/m)	≤ 20	30	100	500	< 80
ρ DC (Ωm)	$> 10^5$	$> 10^5$	$> 10^5$	$> 10^5$	$> 10^5$
T_C (°C)	≥ 125	≥ 125	≥ 150	≥ 400	≥ 250
μ_Q in remanence 10 MHz:			1×10^3		
5 mT			12×10^3		
10 mT			10×10^3		
μ_Q in remanence 80 MHz:				2.5×10^3	
1 mT					
μ_Q in remanence 100 MHz				2×10^3	
Decrease in μ_Q (%), measured 10 ms after application of DC bias (approx.)		10	15	30	
μ_Δ with DC bias field (approx.):					
0 A/m		600	130		
250 A/m		120	80		
500 A/m		50	40		
1000 A/m		22	22		
2000 A/m		8	12		
3000 A/m		5.5	8		
Frequency range (with or without DC bias) in MHz		up to 2	2 to 10	20 to 100	
Application area and special features	kicker magnets; high resistance	high frequency ratio possible with DC bias	fast recovery after magnetic bias	high frequency material	high ($B_s + B_r$)

“Standard” ferrite cavity at higher f ?

- Due to reduced μ_i , the tuning range will become smaller.
- Due to higher losses, the shunt impedance will become smaller, i.e. more power is needed for the same voltage.
- This increased power will not only have to be produced, but also cooled away.
- The table of existing systems confirms that a reasonable upper f -limit for “standard” ferrite cavities is around 20 MHz.
- Alternatives? → Perpendicular bias!

Some existing ferrite RF systems

Synchrotron	No. of Cavs.	No. of Gaps per cavity	Tuning Range (MHz)	Accelerating Time (s)	Max. df/dt (MHz/s)	Gap Capacity (pF)	Ind. Range (μ H)	Type of Ferrite	B _{max} in Ferrite (T)	Bias Current Range (Amps)	Tuning System Bandwidth (kHz)
ISIS	6	2	1.3 - 3.1	0.01	325	2200	6.8 - 1.3	Philips 4M2	0.01	200 - 2300	6
CERN-PS	11	2	2.8 - 9.6	0.7				Philips 4L2		3100	
CERN-PSB	1/ring	1	3 - 8.4	0.45		80		Philips 4L2		60 - 800	15
CERN-LEAR now: CERN-AD	2	1	0.38 - 3.5	0.10		500-3000		Philips 8C12/ Toshiba PE17		0 - 800	
DESY-III	1	2	3.27 - 10.33	3.6						160 - 2000	
SACLAY-MIMAS	2		0.15 - 2.5	0.2	14			TDK C4 SY7		0 - 400	
SACLAY-SATURNE	2		1.7 - 8.3	0.5							
CELSIUS	1		0.4 - 2 1 - 5							1500	
KEK-PS	4	2	6 - 8	0.8	14.5	100	7 - 4	Toshiba M4B23 μ ~100	0.007	80 - 400	3
KEK-BOOSTER	2	2	2.2 - 6	0.025	265	650	8 - 1	Toshiba M4A23 μ ~150	0.01	250 - 2200	1
FNL-BOOSTER	18		30.3 - 52.8	0.033	3000			Stackpole and Toshiba			
BROOKHAVEN-AGS	10	4	2.32 - 4.40	0.0							
BROOKHAVEN-BOOSTER	2	4	2.4 - 4.2	0.062		395	115 - 37	Philips 4M2		145 - 900	
GSI-SIS	2	1	0.85 - 5.5					Philips FXC8C12			

Perpendicular bias!

Perpendicular bias

Smythe 1983:

The Effective Permeability

If we choose one axis (say the x-axis) parallel to the bias field, then the tensor μ_{ij} is diagonal and has only two distinct values. To find them we write:

$$\vec{B} = B_x \hat{i} + B_y \hat{j} = (H_x \hat{i} + H_y \hat{j}) \left[1 + \frac{4\pi M_s}{H} f(H) \right], \quad (3)$$

where:

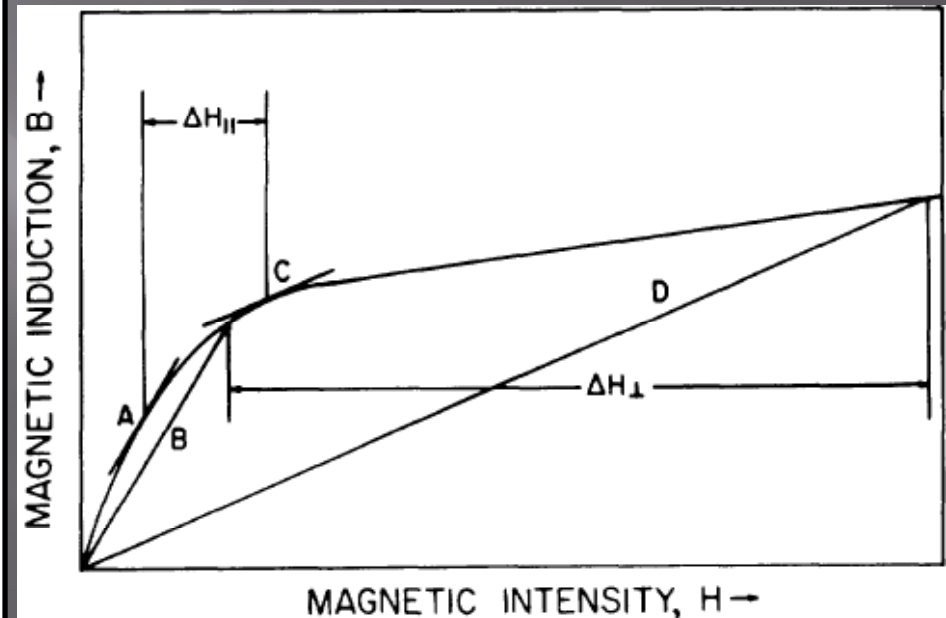
$$H = \sqrt{(H_x^2 + H_y^2)}.$$

For the parallel bias ($\vec{H}_{rf} \parallel \vec{H}_{dc}$) case the effective rf permeability is the well known result:

$$\mu_{xx} = 1 + \frac{4\pi M_s}{H} f'(H) = \frac{\partial B}{\partial H}, \quad (4)$$

while in the perpendicular bias case ($\vec{H}_{rf} \perp \vec{H}_{dc}$) the effective permeability reduces to the surprisingly simple expression:

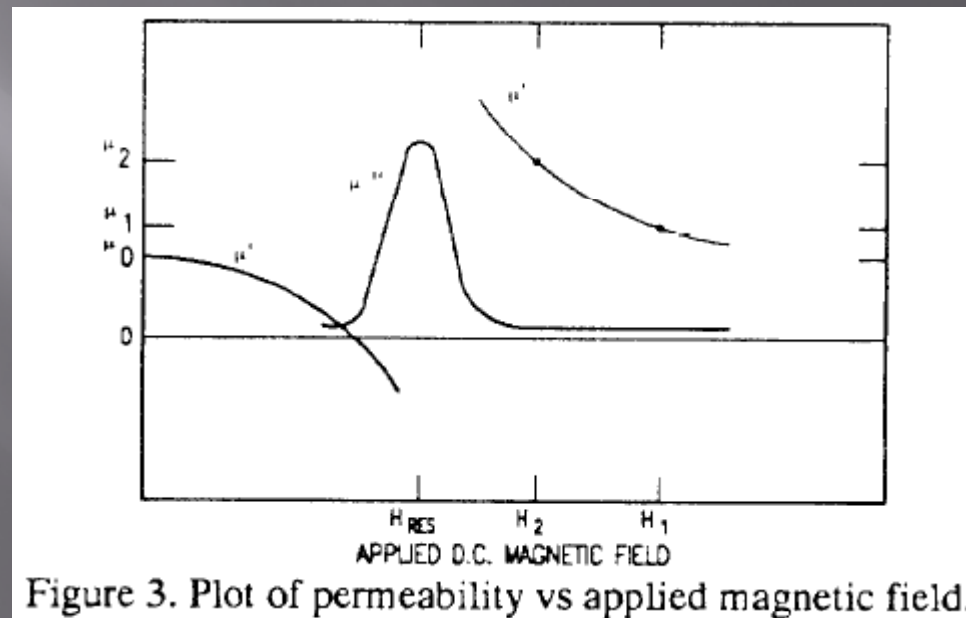
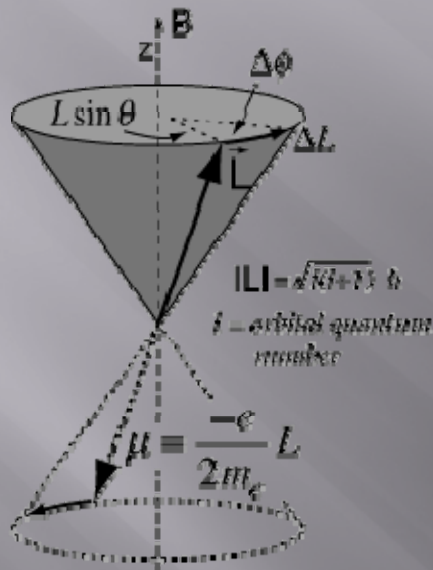
$$\mu_{yy} = 1 + \frac{4\pi M_s}{H} f(H) = \frac{B}{H}. \quad (5)$$



Advantage: always in saturation, i.e. reduced hysteresis loss → potentially higher Q

Gyromagnetic resonance

Poirier, PAC 1993:



resonance at:



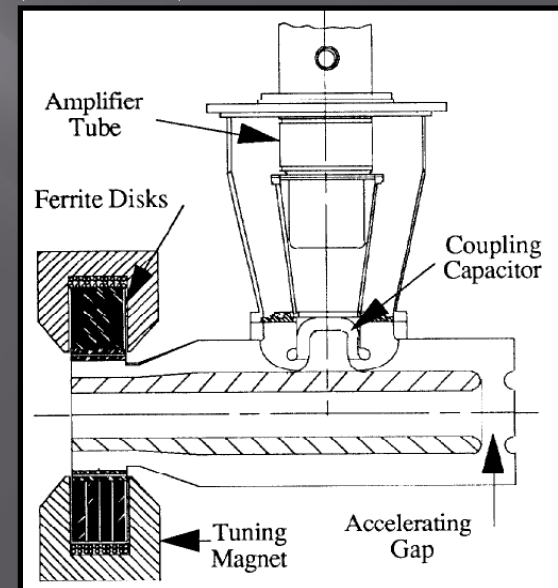
typical bias: 10 ... 200 kA/m

At fields above the gyromagnetic resonance, this is consistent with the $\mu \propto H$ dependence in saturation given by Smythe.

Perpendicular bias RF systems

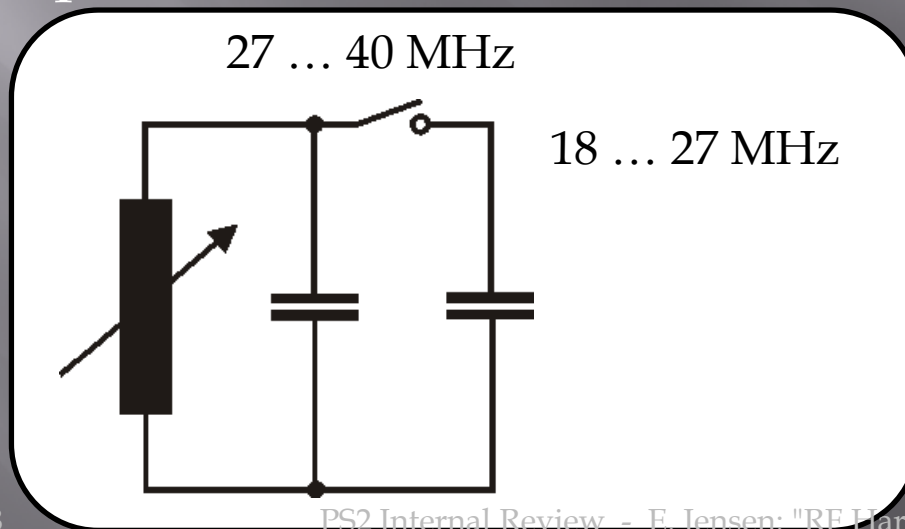
- FNAL Booster (2001)
 - 100 kV with 150 kW, 36 ... 53 MHz, bias < 1000 A
- LAMPFF, later SSCL LEB, 1984 - 1993
 - 127 kV with 150 kW, 47...60 MHz, Q above 1000
- TRIUMF Kaon Factory Booster (1998)
 - 62 kV, 46 ... 62 MHz

“generic” conceptual design:



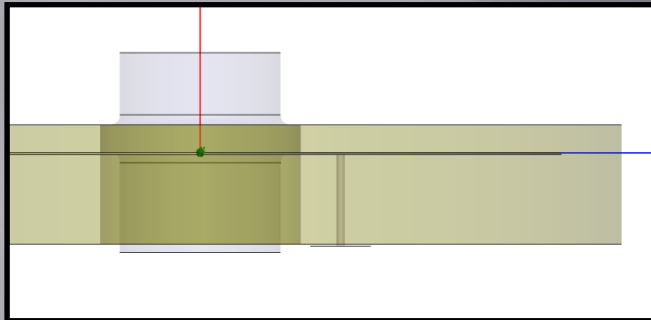
Concluded from these:

- ❑ Systems around 50 MHz with a tuning range of 1.5 can be done.
- ❑ For our f range (18 ... 40 MHz), things would be simpler rather than more complicated.
- ❑ With a switchable gap capacitor it should be possible to make the tuning range in 2 sub-ranges – is this acceptable?



Can 1 octave tuning range be reached?

- Simplified geometries tried in HFSS, e.g.



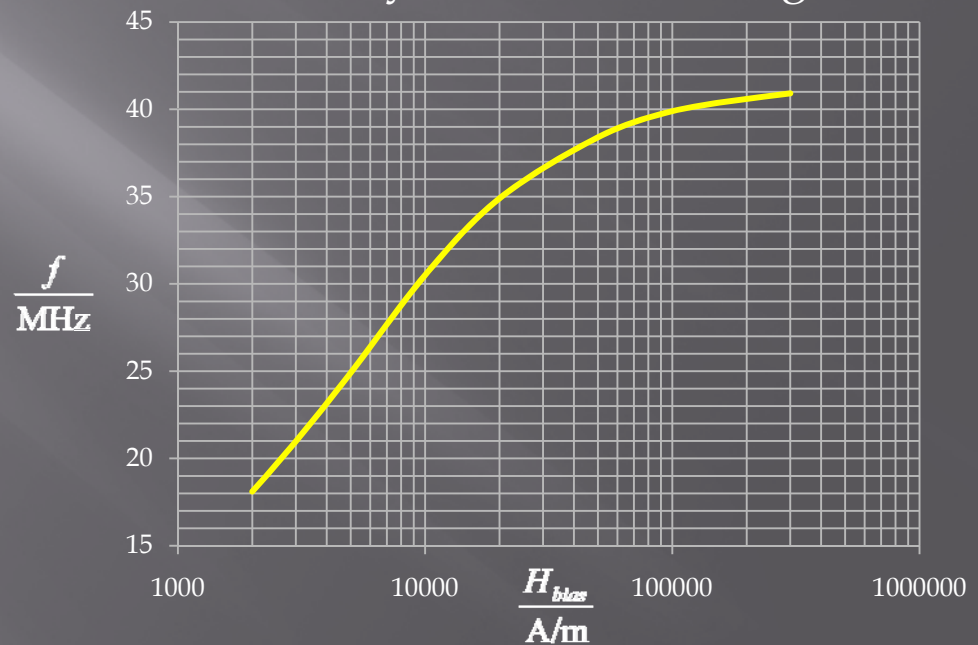
Ferrite: YIG
(Yttrium-Iron-Garnet)
with (realistic)

$$\tan \delta \approx 2 \times 10^{-4}$$

$$M_s = 100 \text{ kA/m}$$

$$\Delta H = 10 \text{ Oe}$$

Preliminary result for a tuning curve:



Preliminary answer:

Octave can be reached, **but:** for bias below 5000 A/m, the Q becomes very small!

YIG ferrites can be tailored

E.g.:

- Substitution of some Y with Gd (see plot), Vd or Ca reduces the saturation magnetization.
- Substitution of some Fe with In reduces the linewidth.

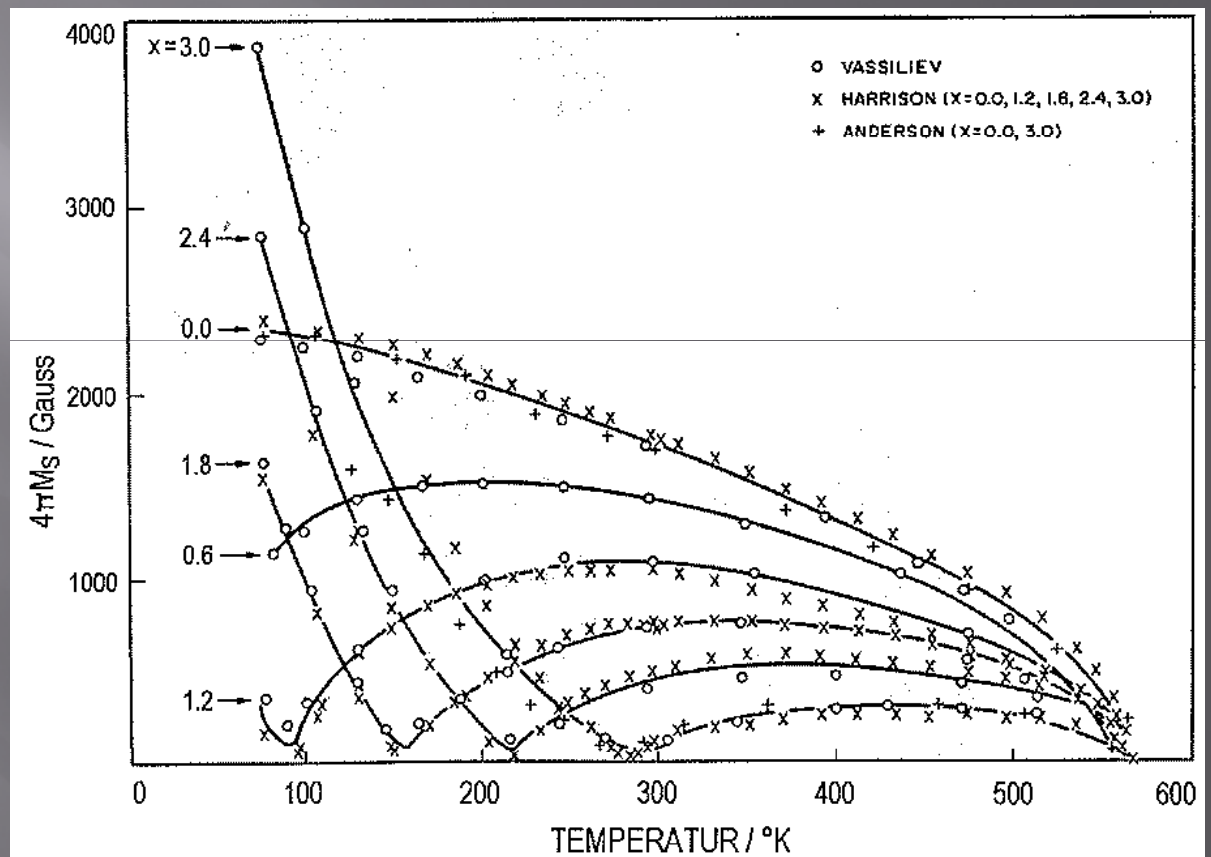
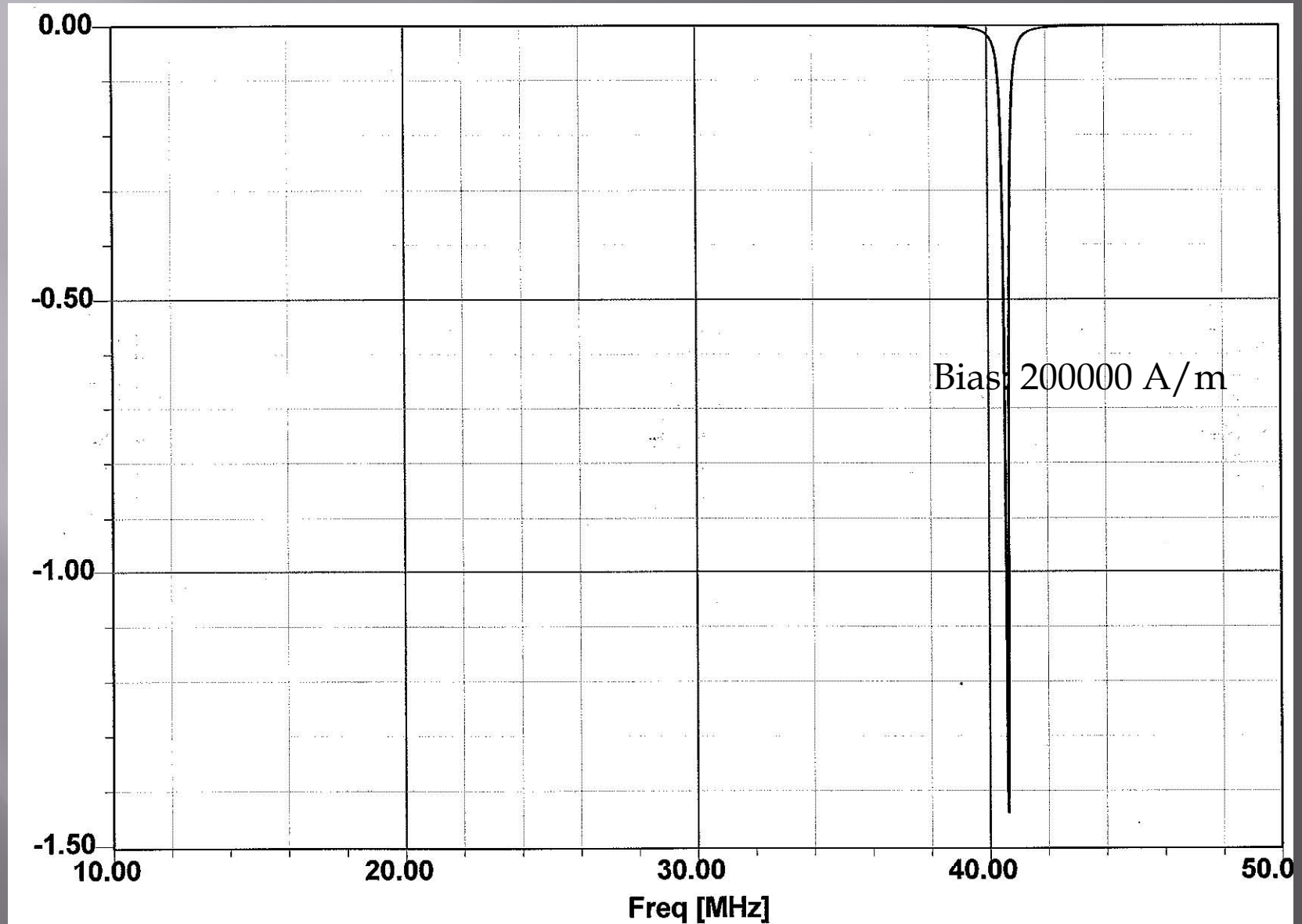


Bild 8.7: Gd-Substitution in YIG:
Sättigungsmagnetisierung über der Temperatur
für verschiedene x in $Gd_x Y_{3-x} Fe_5 O_{12}$

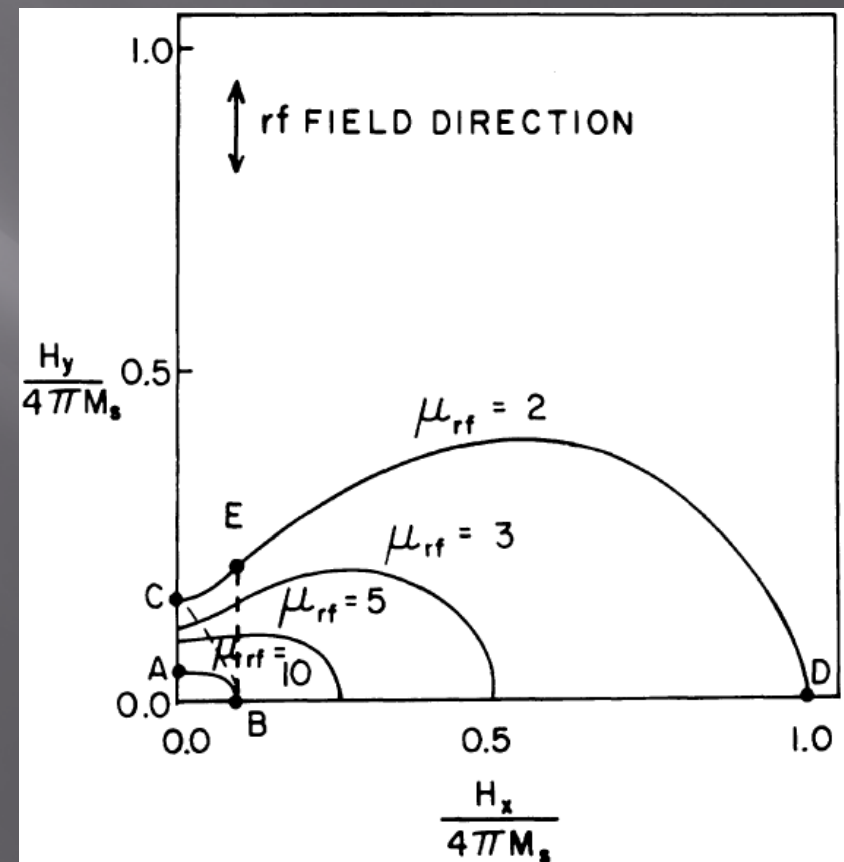
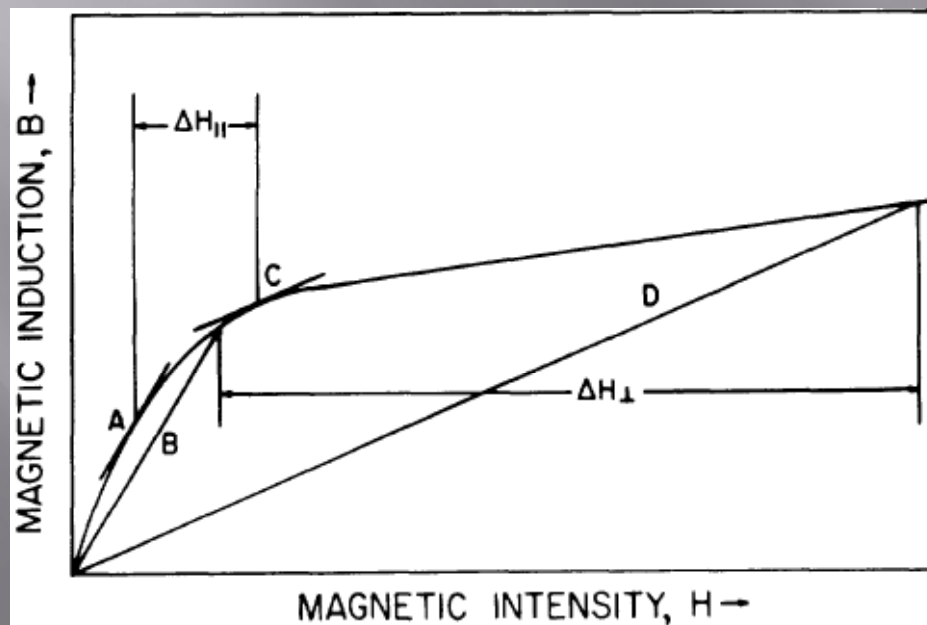
from L. Michalowsky: "Weichmagnetische Ferrite", expert verlag, Renningen, 2006

Preliminary HFSS results:



Parallel plus perpendicular biasing?

- Smythe suggested in 1983 to use
 - transverse bias to get into saturation (lower losses)
 - add'l. parallel bias for tuning (less bias).
- Could this work? (I'd like to try!)



Next steps

- ▣ Characterize YIG ferrite samples with different saturation and line width under different bias conditions in our f -range. (This requires a dedicated test set-up).
- ▣ This will allow to advance a cavity design.
- ▣ My guess today: If the split f -range is possible, 40 kV, 50 kW units should be possible; this would require around 40 systems for the 1.5 MV requirement.