

# HTS Roebel Cable strand alignment within cables and during coil winding

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# Contents

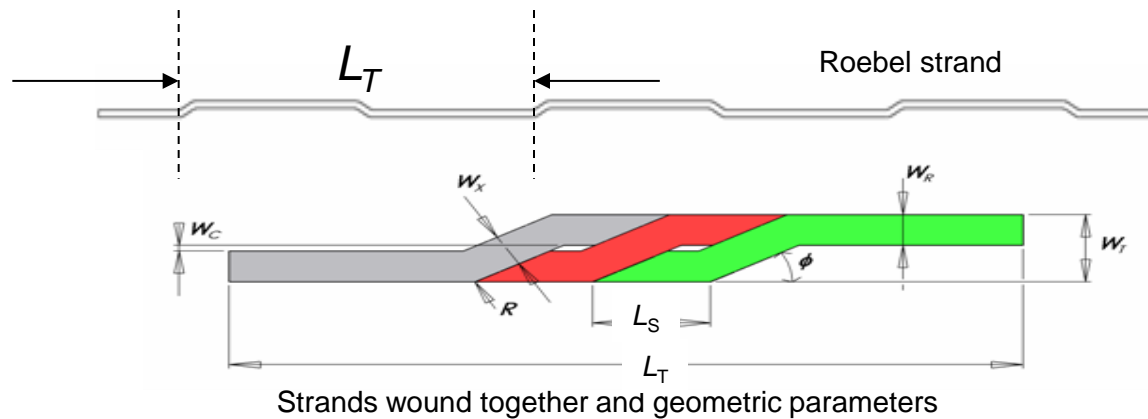
- Strand alignment in HTS Roebel cables
- Simple model: Effect of random error  $\Delta L_T$  for strands
- Strand manufacturing process
- Results for individual transposition lengths
- Results averaged over longer strand lengths
- Cable assembly
- Coil winding
- Next steps
- Conclusions

# HTS Roebel cable



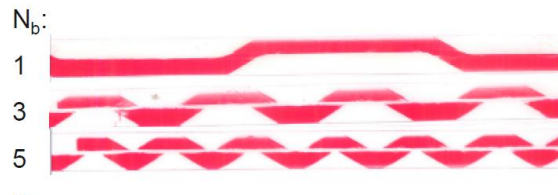
## Fundamental issue

- Geometry of strands is fixed before cable and coil assembly



- For a fixed architecture ( $N$ ,  $L_T$ ,  $W_x$ ,  $\phi$ ) there is an absolute minimum  $L_S$  (strand-strand spacing), this is point at which strands mechanically contact
- A higher practical minimum  $L_S$  may be set by behaviour with transverse stress

Recall Fleiter et al,  
WAMHTS-1



# Simple random error model

- Assume  $(L_T)_i = \bar{L}_T + \Delta x_i$
- Cumulative error  $(\Delta X)^2 = n(\Delta x)^2 = \left(\frac{L}{L_T}\right)(\Delta x)^2$   $n = \#$  of transpositions
- Maximum length of cable that can be wound

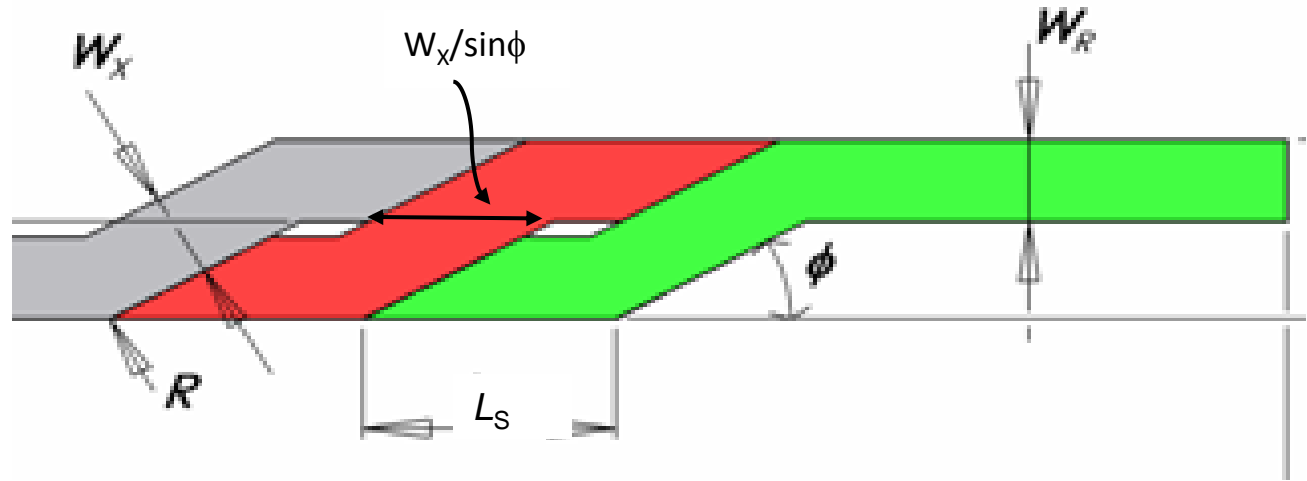
$$L_{max} = L_T \left( \frac{\Delta X_c}{\Delta x} \right)^2$$

- Maximum cumulative error

$$\Delta X_c = \frac{L_S - (L_S)_{min}}{2} \quad L_S = L_T/N, \text{ designed spacing}$$

- Need to estimate  $(L_S)_{min}$

Geometry...



$$(L_s)_{\min} = W_x/\sin\phi$$

For 15/5 cable with  $L_T = 300$  mm

$$L_s = 20$$
 mm

$$\text{Absolute } (L_s)_{\min} = 12.0$$
 mm

$$\Delta X_c = 4.00$$
 mm,

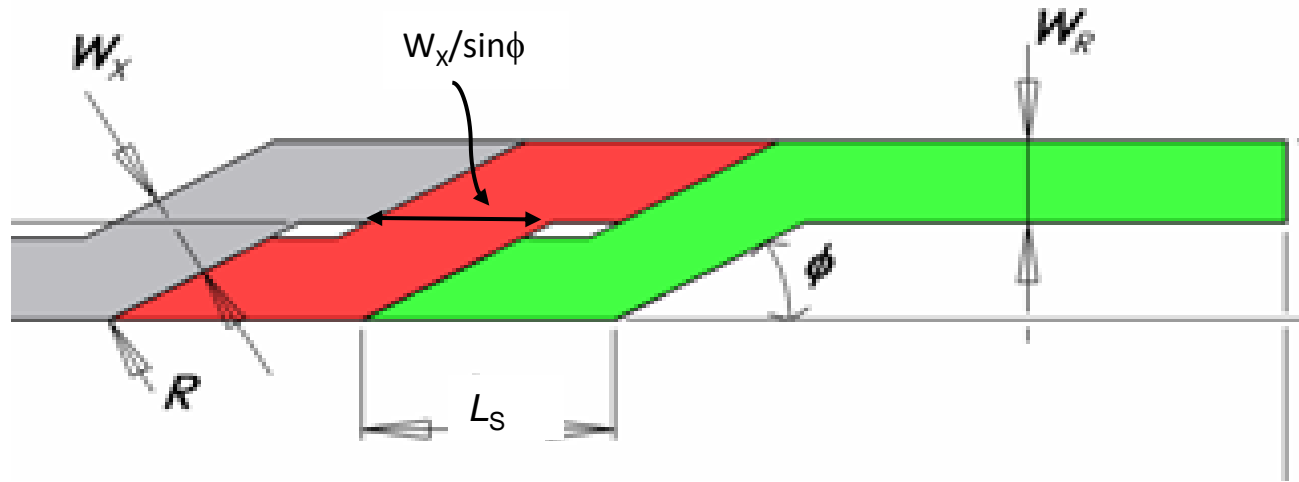
E.g.  $\Delta x = 1$  mm (0.3% of  $L_T$ )

$$L_{\max} = 0.3 * 4^2 = 4.8$$
 m

$\Delta x = 100$   $\mu$ m (0.03%)

$$L_{\max} = 0.3 * 40^2 = 480$$
 m

Geometry...



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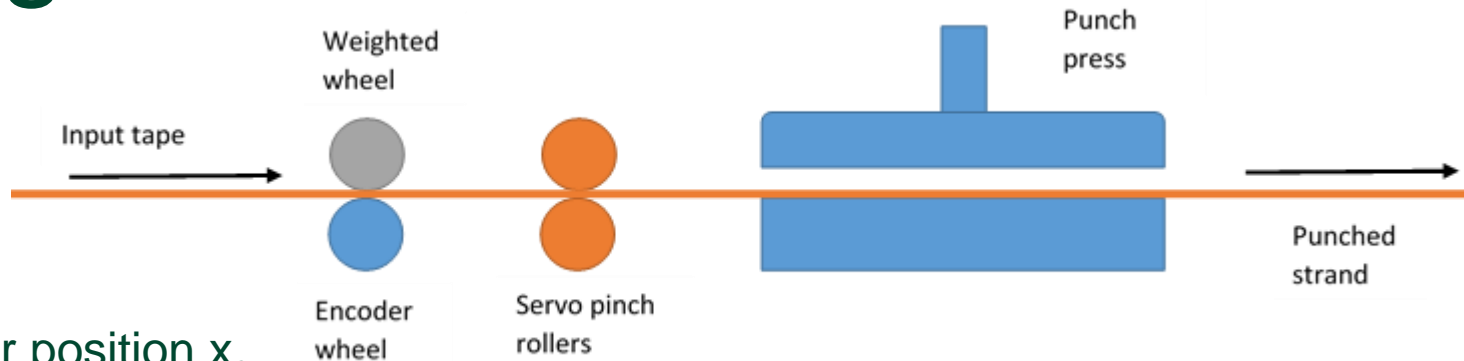
$\Delta x = 100$   $\mu$ m (0.03%)

$L_{\max} = 0.3 * 40^2 = 480$  m

Systematic strand-strand error is much more problematic

$$\Delta X_c = n * \Delta x_c$$

# Length control



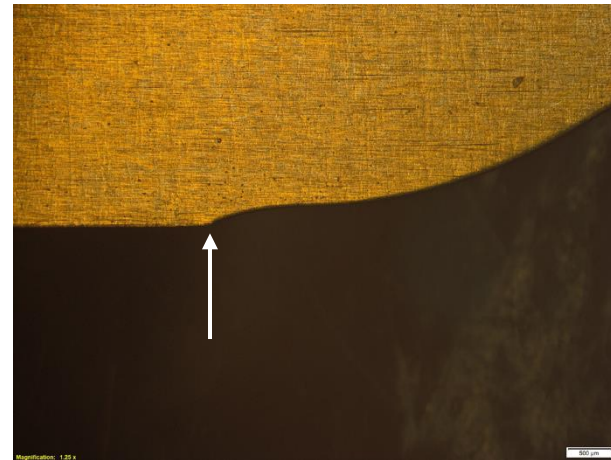
- Encoder position  $x_e$
- Roller position  $x_r$
- Rollers have a PID control – can undershoot or overshoot target position (can't go backwards)
- Algorithm
  - Calculate error  $E_e = (x_e - x_{0e}) - nL_T$
  - Feed (full speed)  $0.9L_T - E_e$
  - Calculate error  $E_e = (x_e - x_{0e}) - (n+0.9)L_T$
  - Feed (half speed)  $0.1L_T - E_e$
  - Punch
- Assumed trade off between speed and accuracy of each  $(L_T)_i$
- Algorithm continually corrects for previous errors

# Measuring $L_T$

- Distance measured with laser interferometer on a 4 m bench
- Requires locating punching 'defect' in strand with microscope
- 10 N tension applied to strand



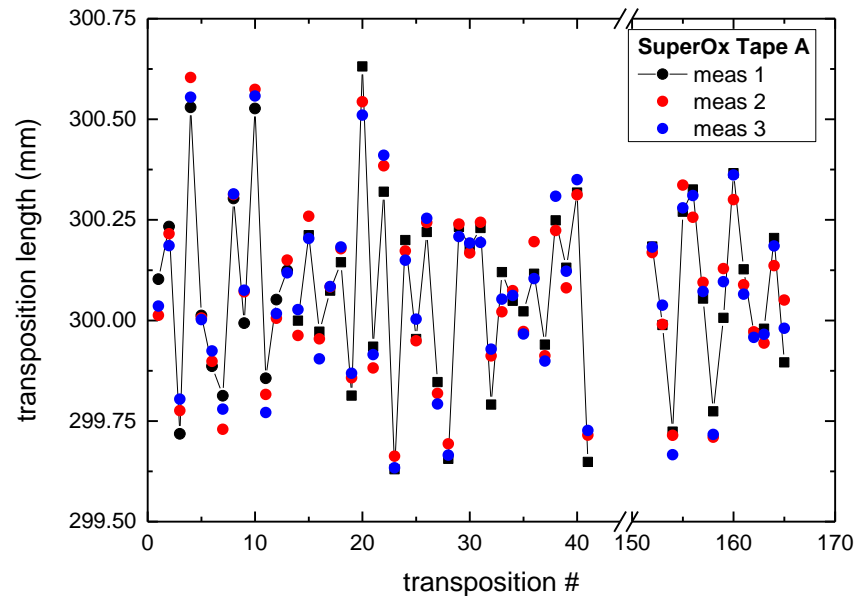
Length standards laboratory





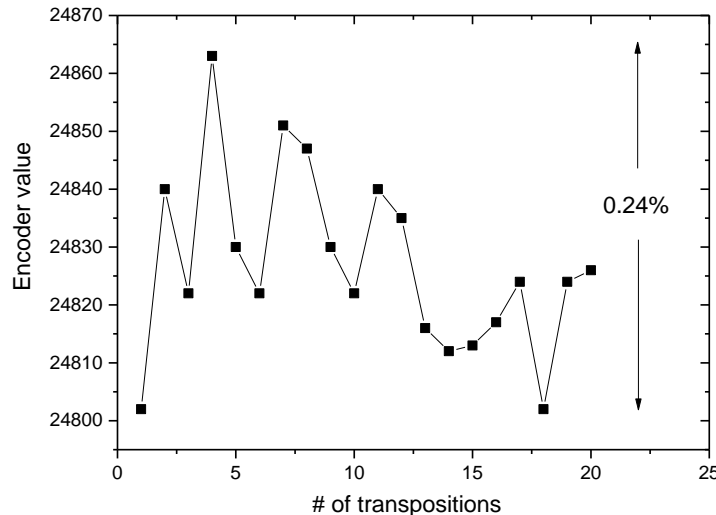
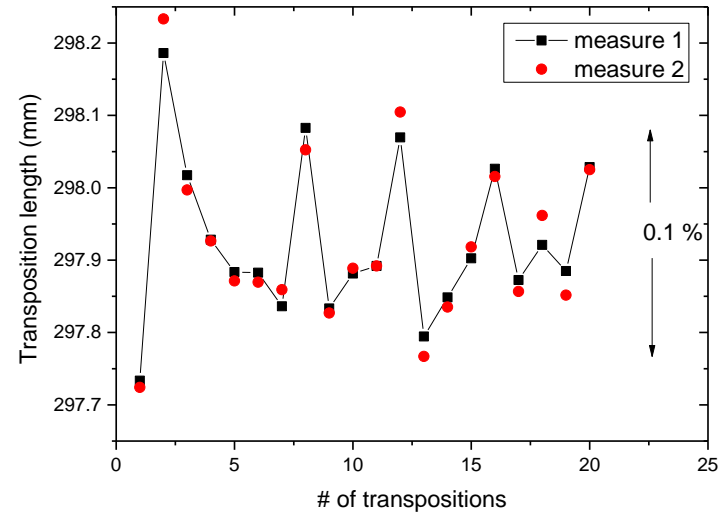
# Individual transpositions

- Any individual measurement has reproducibility of  $\sim 30 \mu\text{m}$
- $(L_T)_{i+1} - (L_T)_i \sim 0.75 \text{ mm}$  (0.25%)
- Tend to get an oscillating structure to measurements
- Origin: feed roller or encoder or measurement error?



# Experiment: Feed fixed roller increments and mark tape

- Length error is  $\sim 0.1\%$
- Then check encoder values
- Encoder variation  $\sim 0.24\%$



Conclusion: encoder less accurate than roll feeder  
- May still have measurement error

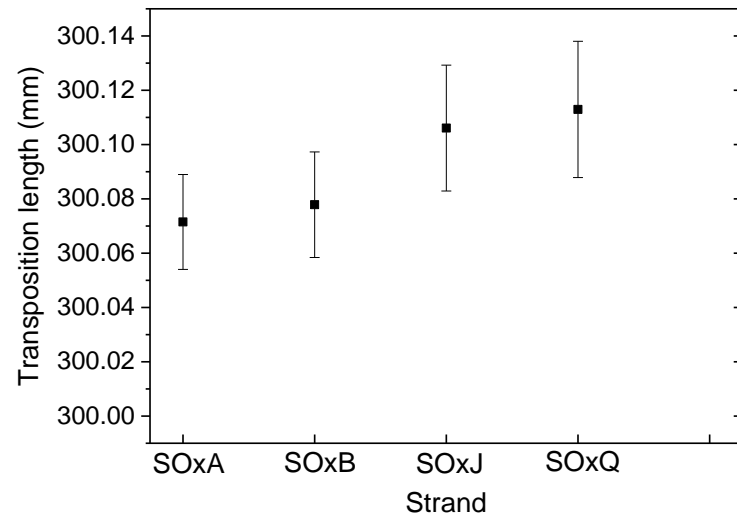
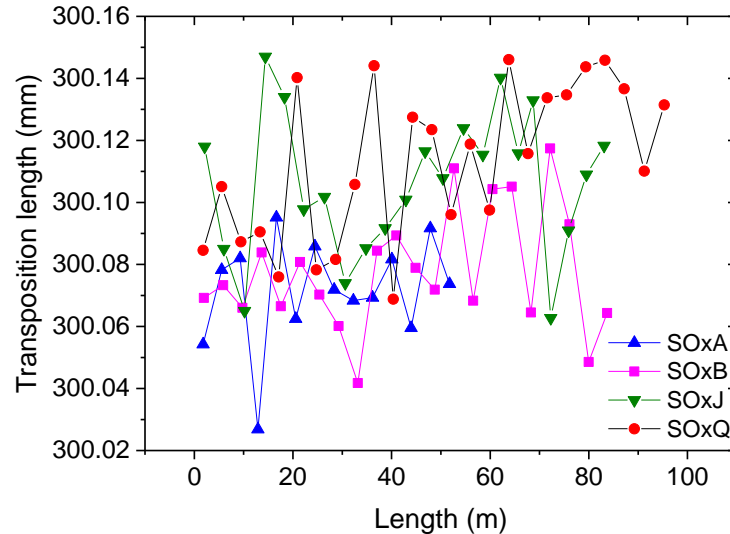
# Averaged transpositions (4 m)

- Punched SuperOx 'dummy' tape
- Much more consistent  $\bar{L}_T$
- Results for up to 90 m length
- Overall random  $\sigma = 25 \mu\text{m}$
- Some evidence for systematic errors between tapes  $\Delta x \sim 20 \mu\text{m}$
- Systematic  $\Delta x \sim 20 \mu\text{m}$  limits cable length to

$$L_{max} = L_T \frac{\Delta X_c}{\Delta x}$$

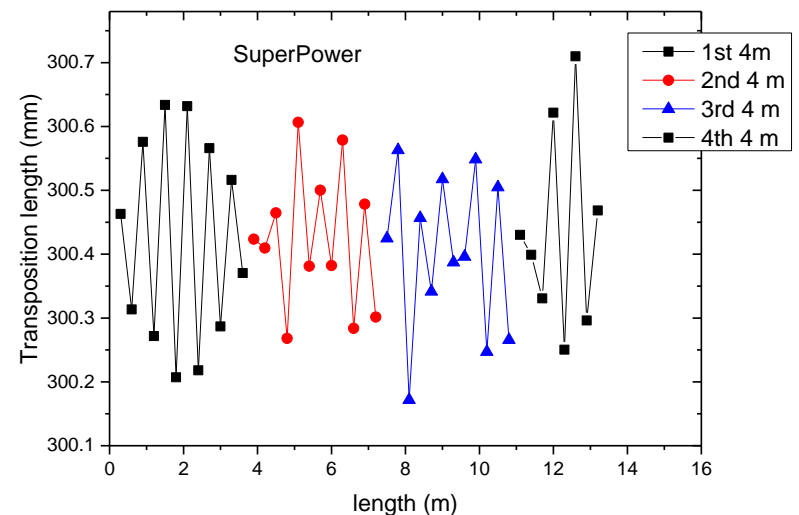
$$L_{max} = 0.3 * 4e-3 / 20e-6$$

$$= 60 \text{ m}$$



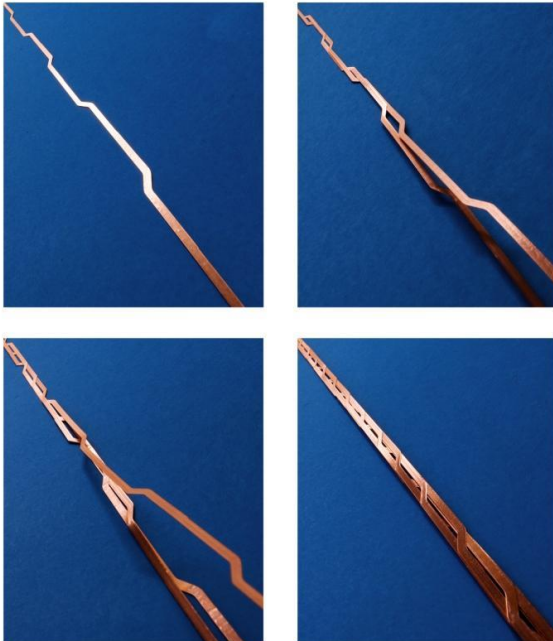
# Conclusions on $\delta L_T$

- Adjacent transposition variations are large at present settings
- Averaged random errors are acceptable
- Systematic errors need more investigation
- No difference between tape manufacturers



# Cable assembly

Illustration of the assembly process



Automated planetary wind system for 15/5 cable

# Assembly issues

- How to set initial alignment of strands?
  - To date done 'by eye'
  - Can we average over more than 1 transposition?
  - 'By eye' means error of +/- 1 mm
- Current assembly process uses low tension; tension of strands along cable axis is not constant during winding
  - Does this matter?
- Does a caterpillar take-up help strand alignment?
- Is a large diameter take up spool necessary?  $d \gg L_T$

This is all work in progress!

# Winding coils

- Simplest case: solenoid coil
  - Strands equivalent; no relative shifts of position due to winding
- Racetrack

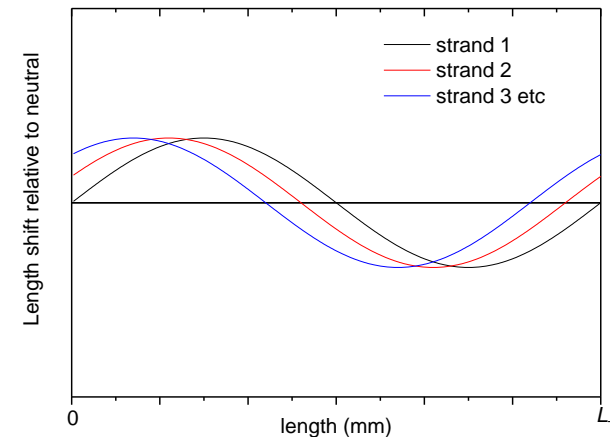
- Relative strand positions shift around a curve
- Model by W. Nick

$$\delta r = A \cos\left(\frac{2\pi x}{L}\right)$$

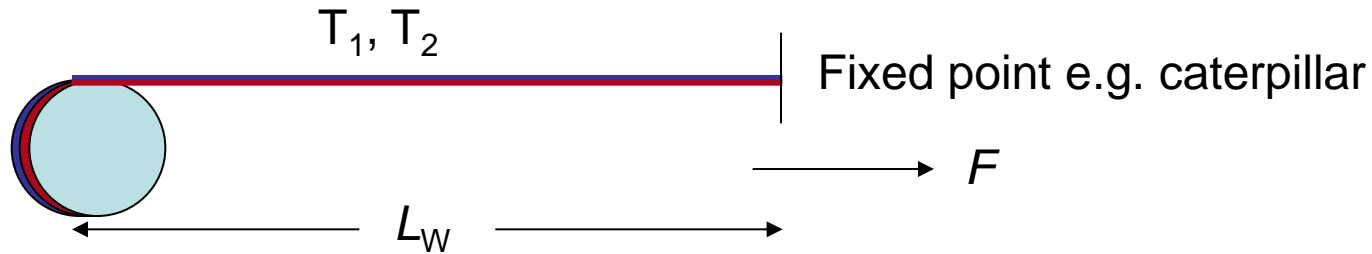
Position of strand relative to neutral axis of cable

$$\delta L = A \frac{\pi \sin X}{2 X}, X = \frac{\pi^2 R}{2L}$$

- E.g. for 15/5, corner radius,  $90^\circ$ ,  $R = 100$  mm, maximum shift is  $\delta L = 0.4$  mm
- Question is how this shift is accommodated...
- Also, how it adds to other errors...



# Winding coils (cont)...



- Imagine 2-strand cable, wind on by  $\pi$
- $\Delta l = d * \pi$  ( $d \sim$  cable thickness)
- Now  $T_1 \neq T_2$
- Apply force,  $F$ , to ensure strands in tension
- Implies a minimum  $L_w$  (to keep higher strain below  $\varepsilon_{irr}$ )

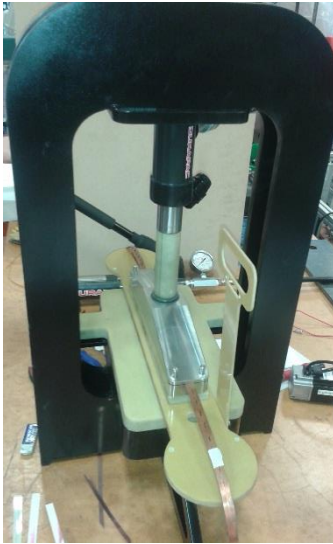


# Roebel coil results

- RRI transformer solenoid
  - Successful  $I_c$  retention
  - 15/5 cable, 220 N winding force, not potted, single turn, Young's modulus  $E=31.3$  Gpa
  - Drum pay-off
- Siemens small racetracks
  - Successful  $I_c$  retention
  - 7/5 reinforced cable, potted, 6-10 turns, similar Young's modulus
  - Caterpillar pay-off

# Further work

- What is a more realistic limit of  $\Delta X_c$ ?
  - transverse stress testing of bare and potted cable
  - In-situ  $I_c$  measurement



Work in progress!

# Further work

- $L_T$  variations
  - Improve encoder mechanics
- Cable assembly
  - Testing of caterpillar
  - Long length alignment
- Coil winding
  - Can strand shift be accommodated by geometry choices?

# Conclusions

- Data for  $\Delta L_T$  shows random and systematic errors
  - No issues for short length cables
  - Systematic errors require investigation – will limit length
- Work on assembly issues is in progress
- Coil winding creates strand shifts which can be modelled
- Understanding  $\Delta X_c$  issues is in progress through pressure –  $I_c$  measurements

Thank you for your attention!