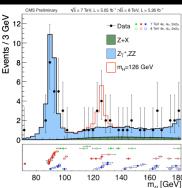
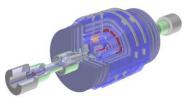


ROOT, I/O and Concurrency

Philippe Canal Fermilab







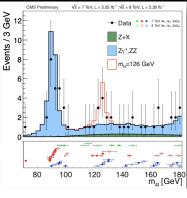
Overview

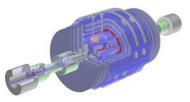


• ROOT

• I/O

Concurrency



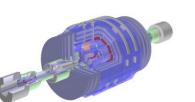




ROOT Guiding Principles



- User Oriented
 - Support and Feedback is essential
 - HEP is main but not sole user/target
- C++: Interpreter and Reflection
- High performance (many dimensions)
- Release early and often



- Open-ended
 - Include interfaces to other languages
 - Help promote associated project (RooFit, etc.)



I/O Long Term Goals



Performance

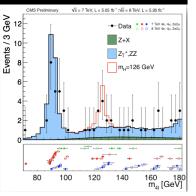
- Keep up / Pass competition
 - With StreamerInfo layer and JIT, large opportunities for optimizations

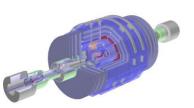
Features

- Maintain and enhance schema evolution support
- Adapt to new hardware landscape
 - Today: multitask, vectorization; Tomorrow: transactional memory.

Interoperability

- -Open their ecosystem to using ROOT [I/O]
- Open ROOT users to use the other ecosystem(s)





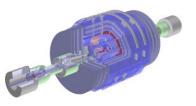


I/O Priorities



Multi-processing / Multi-threading

- Performances improvements
 - Amdahl, File Format, Streaming, Vectorization
- Interface Simplification and Clarification
 - Leverage C++11 for ease of use/documentation
- Interoperability
 - HDF5, R, Python, Blaze, numpy, etc.



Additional statistics and Feedback on I/O Perf.

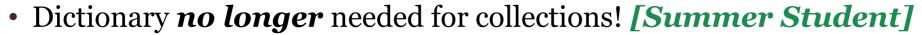


Here comes cling



• *Cling* introduces binary compatible Just In Time compilation of script and code snippets.

- Will allow:
 - I/O for 'interpreted' classes
 - Runtime generation of CollectionProxy



- Run-time compilation of *I/O* Customization rules
 - including those carried in **ROOT** file.
- Derivation of 'interpreted' class from compiled class
 - In particular **TObject**
- Faster, smarter TTreeFormula
- Potential performance enhancement of *I/O*
 - · Optimize hotspot by generating/compiling new code on demand
- Interface simplification thanks to full C++ support
 - New, simpler TTree interface (TTreeReader) [Summer Contributor]





Challenges



- Two distinct user bases
 - Individual Users
 - Want everything automatic / just works
 - Framework Developers
 - Want to control everything (want no surprise)
- Two distinct mode of operations
 - Thread based
 - Task based
- Must support all 4 combinations
- Concurrent access must not cost (too much) for nonthreaded use.



User / Thread Example



- Simple merge histo interface.
 - User add 'only' the lines (*)

```
// Main Thread
        TDirectory *merger = new THistoMerger(nthreads); // (*)
// Each thread init
                                 // Each thread init
merger->cd(); // (*)
                                 merger->cd(); // (*)
TH1F* h = new THF1("h",...);
                                 TH1F* h = new THF1("h",...);
                                 // Each thread event loop
// Each thread event loop
                                 h->Fill(value);
h->Fill(value);
                // Tear down or end
                merger->Merge(); // (*)
                ouputdir->cd();
                merger->Write();
```



User / Task Example



- Simple merge histo interface.
 - User add 'only' the lines (*)

```
// Main initialization
              TDirectory *merger = new THistoMerger(nthreads); // (*)
// Each task init
                                          // Each task init
TH1F* h = new THF1("h",...);
                                          TH1F* h = new THF1("h",...);
h->SetDirectrory(merger); // (*)
                                          merger->Append(h); // (*)
// Each task iteration
                                          // Each task iteration
h->Fill(value);
                                          h->Fill(value);
                      // Final task
                      merger->Merge(); // (*)
                      ouputdir->cd();
                      merger->Write();
```



Framework example



Framework want to owns histos.

```
// Each thread/task init
TH1F* h = new THF1("h",...);
fwk_ownlist->push_back(h);

// Each thread/task event loop
h->Fill(value);

// Tear down or end
foreach h in ownlist(s) (or equiv)
   TList *lst = complex_code_to_gather_histo(fwk_threadlist);
   merged = Merge(lst);
   outputdir->WriteObject(merged);
```

- But what about the case where there is 100,000 of histo?
 - Especially if filled rapidly (so need lock less Fill)



100,000 of histos on several threads



• Questions:

- What is the use case really like?
 - What is the required performance ('where' can we put a lock)
- When is the data merge done?
 - Every Fill
 - Every so many calls fills
 - One of the threads
 - A merger thread?
 - Why is it better that one histo per threads
- Are TH* really heavy weight?
 - What is the real over-head?
 - When/how is the allocate-the-bins-only-when needed used?
- Related concerns
 - Should variable size and fixed size bins histo be more clearly separated?
 - Improve performance, Reduce over head (of fixed size case)
 - Is it making the interface harder to use/explain?



Another interface idea.



```
// Main initialization
             TH1F *mainh = new TH1F("h",....)
// Each task init
                                       // Each task init
HistoTaskHandle h(mainh);
                                       HistoTaskHandle h(mainh);
h->SetBufferSize(...);
                                       h->SetBufferSize(...);
// Each task iteration
                                       // Each task iteration
h->Fill(value);
                                       h->Fill(value);
              // Final task
              foreach handle h:
                 mainh->Add(h);
              outputdir->Write(mainh);
```



Another interface idea.



Spot the difference ©

```
// Main initialization
             TH1F *mainh = new TH1F("h",....)
// Each task init
                                       // Each task init
TH1*h = mainh->Clone();
                                       TH1*h = mainh->Clone();
h->SetBufferSize(...);
                                       h->SetBufferSize(...);
// Each task iteration
                                       // Each task iteration
                                       h->Fill(value);
h->Fill(value);
              // Final task
              foreach handle h:
                 Ist->Add(h);
               mainh->Merge(lst);
               outputdir->Write(mainh);
```



Framework Requirements



- If ROOT uses threads that should be not computationally intensive
 - Example: prefetching thread
- If ROOT wants to run cpu-intensive tasks they must (be able to be forced to) request CPU time from the framework
 - For example a parallel unzipping would need to be a Task pushed on the TBB stack
 - Implies that when adding improvement that uses parallel execution we ought to follow a task model



Task vs. Thread



- Task model simpler to use
 - Delegate load balancing to 'framework'
 - Similar to Proof
 - However task more 'flexible' control flow
 - Proof more extensive (over more hardware config)
 - Should we promote the task mode (tutorials, etc.)?
- Requirements
 - Need (virtual) Interface
 - To allow replacing TBB with Apple GCD.
 - Need always available default implementation
 - Which is easily replaceable by the user controlled one.
 - Need to be pluggable/controllable by the user
- Other Utilities we could offer
 - Similar to boost::thread_specific smart pointer.



PROOF vs. Task Models



- What are the difference?
- i.e. can PROOF(lite-with-thread) be (extended to be) our interface?
- If not how do we provide a smooth experience
 - From single stream of operation
 - To many streams of operation
 - To many machine with many streams of operations
 - Without changing the code?



Vectorization

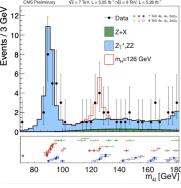


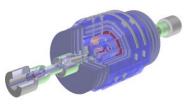
- Many alternative vectorization techniques
 - VC, VDT, Cuda, by hand, etc.
- GeantV uses template techniques and traits to steer the choice.
- Should we adopt the same techniques
 - and share/distribute the common parts?





Backup slides





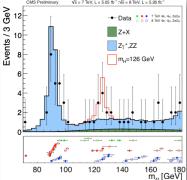


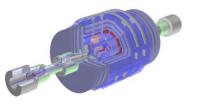
Priorities



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- Interface Simplification and Clarification
 - Leverage *C*++11 for ease of use/documentation
- Interoperability
 - HDF5, R, Python, Blaze, numpy, etc.
- Additional statistics and Feedback on I/O Perf.







Multi-Processing



- Import Chris' changes to **v5.34** and port to **v6.02**
- Extend the ability to disable auto-add
 - Limited to TH* so far
 - Remove use of *I/O* in *TH*::Clone*



As shown in the CMS condition database example





Multi-Processing



- *Histogram* and multi-threading
 - Need to start prototyping & testing asap
 - New interface to incrementally merge histograms from multiple threads



- Read/Write TTree branches in multiple user thread
 - Need to start prototyping/testing asap
 - Do we need new/simpler interface?
 - Need to design the limit and semantics
 - Extra complexity/cost to conserve basket clustering
 - Require *TFile* synchronization



Thread Safety



- Cling enables support for robust multi-thread I/O
 - *Cling* has clear separation of database engine and execution engine allowing to lock them independently
- Chris' changes allow multi-threaded *I/O* as long as
 - Each TFile and TTree objects are accessed by only one thread (or the user code is explicitly locking the access to them)
 - Interpreter is *not* the top level entry point.
 - Cling will allow to remove the second limitation.
- More has to be done to optimize
 - Some object layout leads to poor performance and poor scalability
 - Reduce number of 'class/version/checksum' searches
 - To reduce the number of atomic and thread local uses



Parallel Merge Challenges



- Need official daemon/thread parallelMergeServer
 - Could use **Zero MQ** as underlying transport.
- Need to efficiently deal with many histograms
 - Each of them still need to be merged at the end
- Lack of ordering of the output of the workers
 - No enforcing of luminosity block boundaries for example
 - Support for ordering increases worker/server coupling
 - Space reservation is challenging (variable entry)
- Need a new concept (an Entry Block)
 - Set of entries that are semantically related'
 - To be used to gather those entries together 'automatically'
 - Need flexible/customizable marker
 - Is it really worth the extra complexity?



Parallel merge



- Fully tested and performing version requires
 - Parallel Merge Thread
 - Parallel Merge Daemon (authorization, auto-start, error handling)
 - Parallel Merge for Histogram (proper set of benchmarks, performance improvement, etc.)



- Still to be designed
- Based on existing example (some multithread) and new example based of the *Event* test.
- Based on experiment uses cases.





Other Possible Parallel Processing



- Read/Write branches using internals thread/tasks
 - Need to partially back out memory optimization
 - Require *TFile* synchronization
- Offload work (compression) to separate thread
 - Need to work well with task based scheduler
- Thread safe version of *TFile*
 - Not quite sure of semantic
 - Need to be cost-neutral for traditional uses



- Support for 'multiple' interpreter state
 - Decide on need / interface / use limitations
 - shared libraries (their PCMs) shared between interpreters?



Vectorization



• In *TTree*

- Eg. TTree::Draw execute formula on more than one element at a time
- New interface allowing retrieval of multiple entries at once.

In Streaming

 Changing endianess would also merging and vectorization of even more streaming actions.



Interoperability



- HDF5, R, Python, Blaze, numpy, etc.
 - These ecosystems has their strengths and weaknesses as well some similarities and significant differences with *ROOT*
 - What can we learn from them?
 - How can *ROOT [I/O]* can be leveraged to enhance them?
 - How could our workflows benefit from using directly or indirectly any part of these ecosystems?
 - Who can help?



Why one thread/schedule per TTree



- When reading TTree holds:
 - Static State:
 - List of branches, their types their data location on file.
 - Dynamic State:
 - Current entry number, *TTreeCache* buffer (per *TTree*), User object ptr (one per (top level) branch), Decompressed basket (one per branch)
 - Separating both would decrease efficiency
- Advantages
 - Works now!
 - No need for locks or synchronization
 - Decoupling of the access patterns
- Disadvantages
 - Duplication of some data and some buffers.
 - However this is usually small compare to the dynamic state.
 - Duplication of work if access overlap



