Global PID MICE CM40 26/10/14

Celeste Pidcott University of Warwick



#### Status of PID at CM39

- Single (1D) variable framework has been in MAUS since v0.8.2
- Expansion of framework to use 2D PDFs in MAUS since v0.8.4
- Global PID documentation has been incorporated into MAUS User Guide since v0.9.0
- Global datastructure expanded to include KL and Ckov detector information, and code written to import KL information into global event, in MAUS since v0.9.0



Main points for this talk:

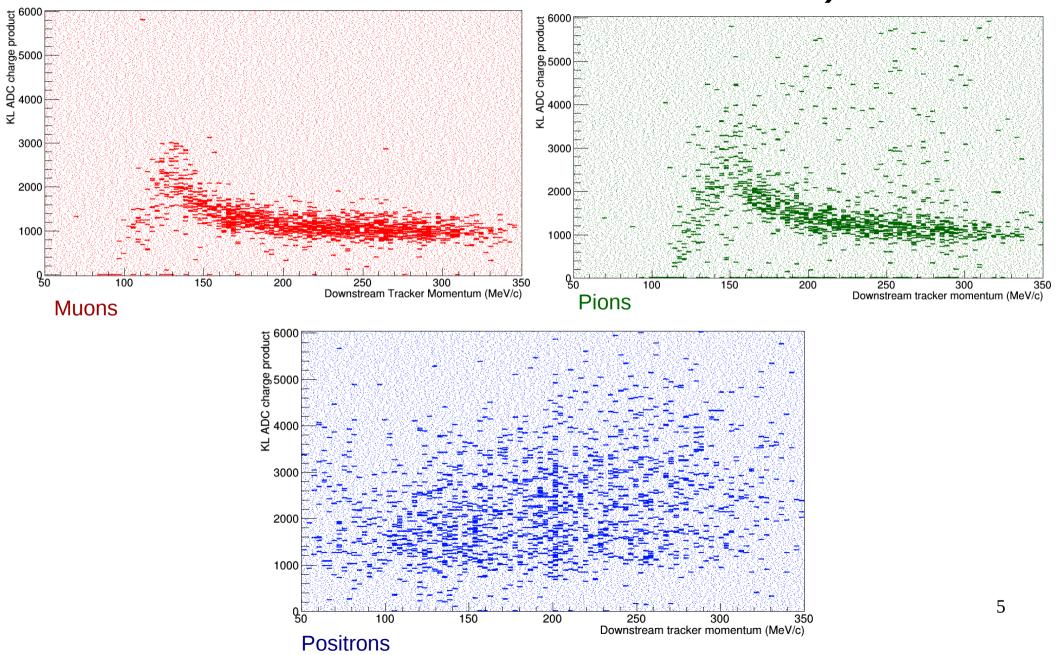
• Tracker/KL PID variable

• Efficiency and Purity of PID

#### PIDVarC (KL ADC charge product vs Downstream Tracker Momentum)

- KL is intended to separate muons from decay electrons
- ADC charge product measured by KL has a momentum dependence (see slide 15)
- PID variable incorporating ADC charge product with momentum measured in downstream tracker proposed to remove dependence
- Variable written, currently writing tests before submitting to MAUS

### PIDVarC (KL ADC charge product vs Downstream Tracker Momentum)



### Efficiency and Purity

- Work on determining preliminary efficiency and purity for Global PID has begun.
- Currently only considered case for a 200 MeV/c muon beam, with decays off, for PIDVarA and B separately. PIDVarC to follow.
- Next steps will be to consider beams of different momenta, and with a mix of particle species.
- Need global tracking to consider scatters and decays.

# Efficiency and Purity – Important definitions

- Undefined track : Value of PID variable has been calculated, however cannot be distinguished between particle hypotheses.
- Unsuitable track : One which does not meet the requirements to calculate the value of a PID variable, e.g. missing required detector information, and so cannot be identified
  - This is a problem with the reconstructed track, not the PID, and so when calculating the efficiency strictly for the PID should not be considered.

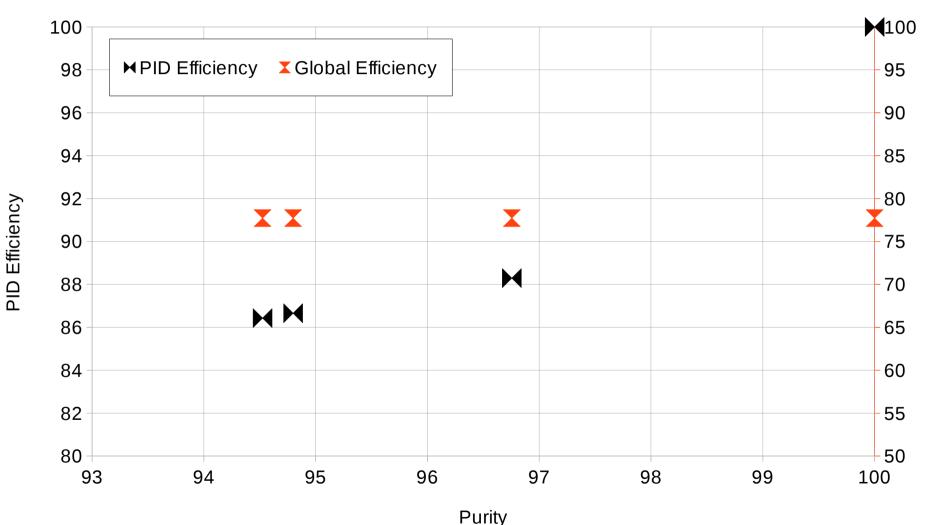
# Efficiency and Purity – Important definitions

Purity = <u># of correct PID tracks</u> # tracks assigned a PID

#### PID efficiency = <u># of correct PID tracks</u> # MC tracks - # unsuitable tracks

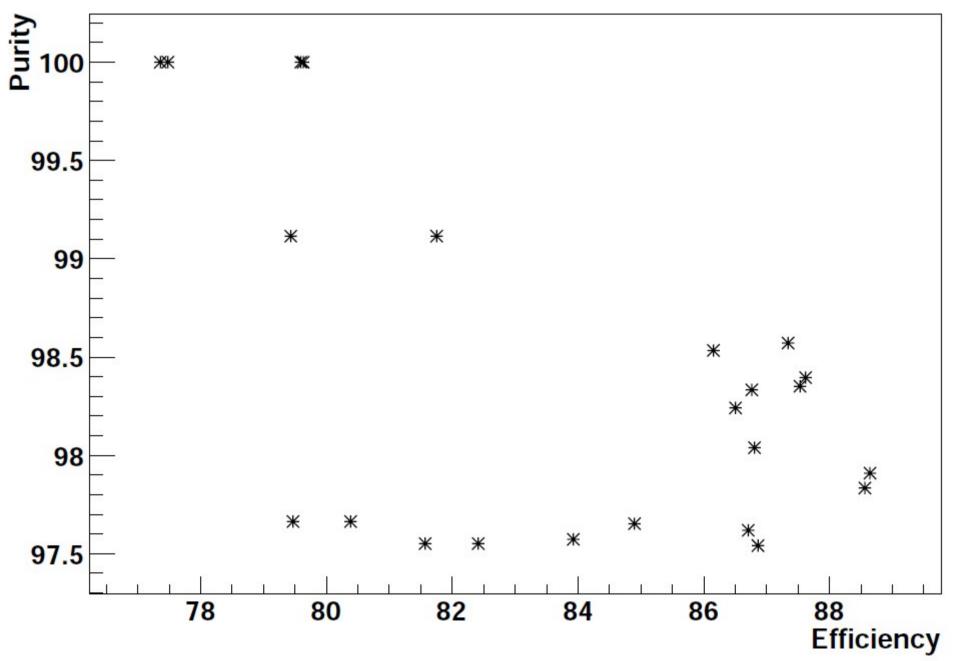
Global efficiency = <u># of correct PID tracks</u> # MC tracks

# Efficiency and Purity for PIDVarA (TOF1\_t - TOF0\_t)

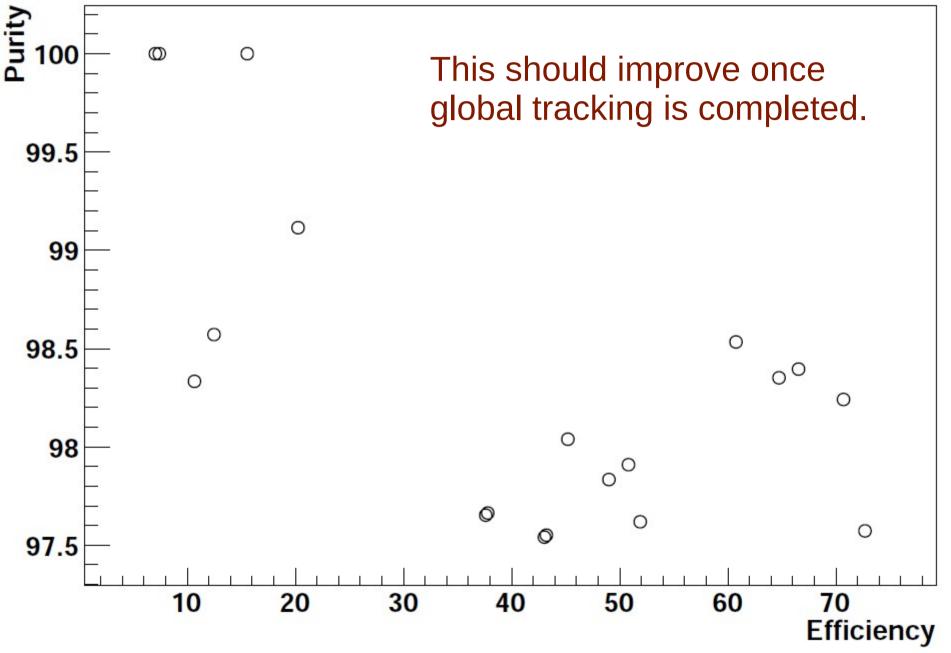


Global Efficiency

### PID Efficiency and Purity for PIDVarB (TOF/Tracker)



# Global Efficiency and Purity for PIDVarB

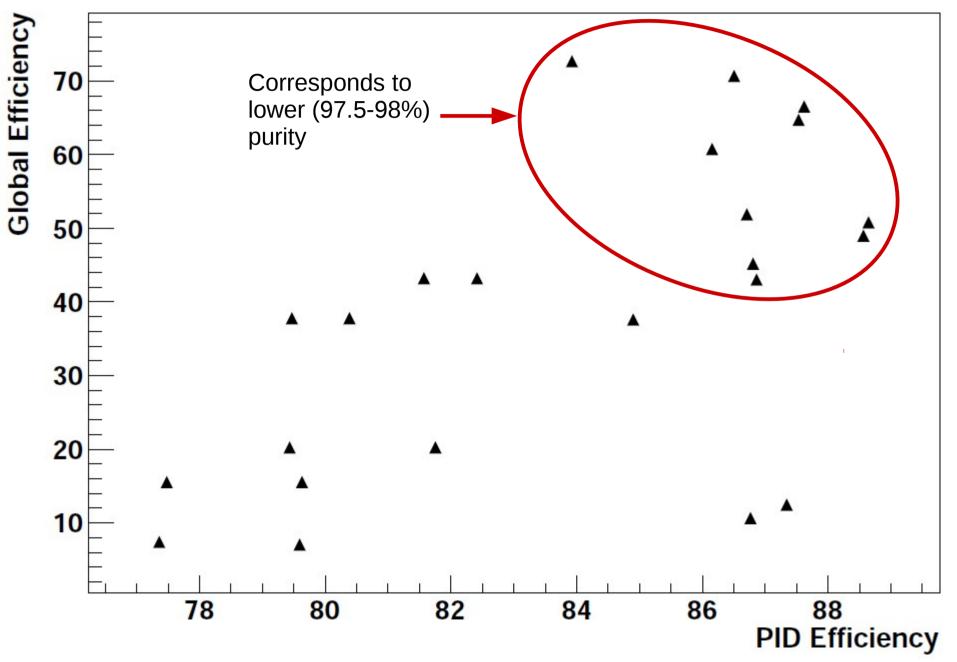


### Summary and next steps

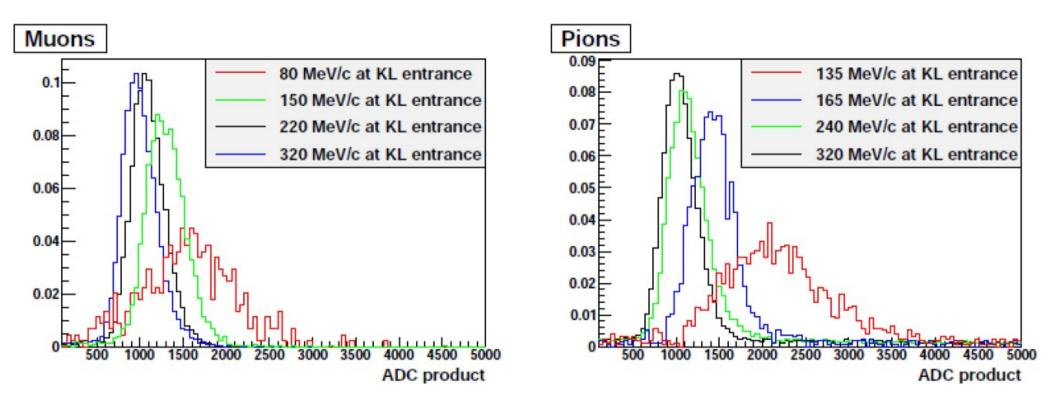
- A third PID variable, using the KL and downstream tracker has been developed.
- Work on determining the efficiency and purity of the PID has begun.
- Tests for PIDVarC currently being written, to then be uploaded to development branch and then added to MAUS.
- Continued work to be done on efficiency and purity.
- Once Ckov and EMR are included in MAUS, more PID variables will follow.

#### **Additional Slides**

### Global efficiency vs PID efficiency for PIDVarB



## KL ADC product momentum dependence



KL response (taken from arXiv:1203.4089v2)