

Some physical aspects of tactile probes

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1st PACMAN-Workshop, CERN

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AGENDA



- 01** Introduction
- 02** Basic principles of Touch-Trigger-Probes
- 03** Basic principles of Scanning-Probes
- 04** Aspects of calibration
- 05** Touching deformable surfaces
- 06** Checking stability/quality/repeatability of probes (ISO-Tests)
- 07** Concluding remarks

Hexagon Group

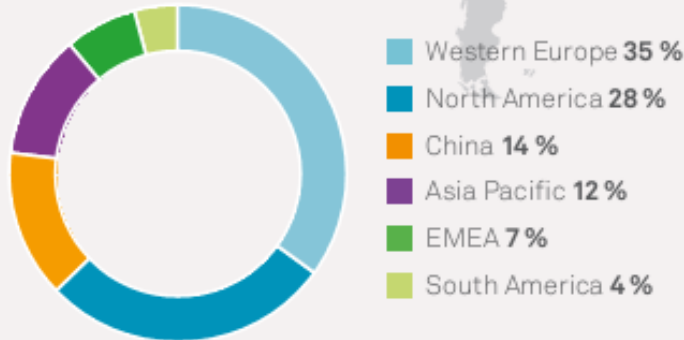
GLOBAL COVERAGE, LOCAL PRESENCE

Hexagon has a strong local presence across a well-diversified geographical customer base in nearly all industries throughout the world. No individual customer represents more than 1.5 per cent of Hexagon's net sales.

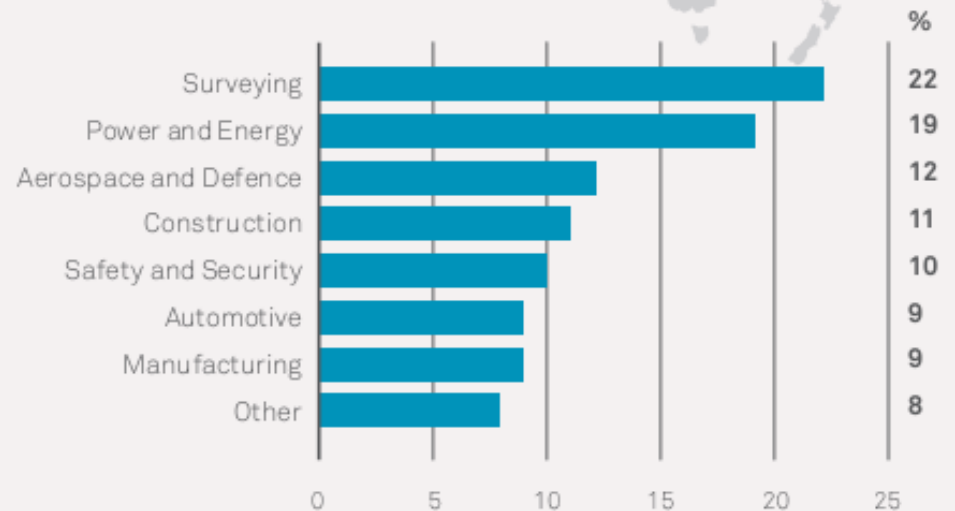
2011 NET SALES
2.2 BN EUR

OPERATIONS IN OVER
40 COUNTRIES

NET SALES BY REGION 2011



NET SALES BY CUSTOMER GROUP 2011



Hexagon Divisions



GEOSYSTEMS

SHARE OF
NET SALES



36%



METROLOGY

SHARE OF
NET SALES



30%



TECHNOLOGY

SHARE OF
NET SALES



34%

Measurement of
Environment and
Infrastructure

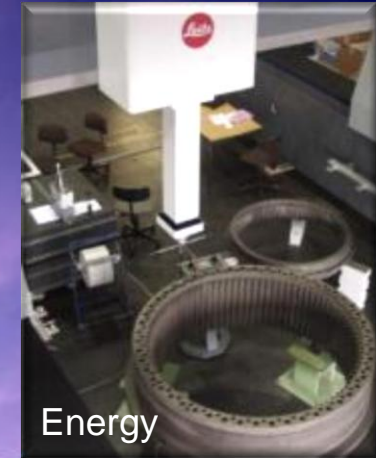
High precision
measurement of
industry components

Software for company
engineering;
navigation and satellite
systems

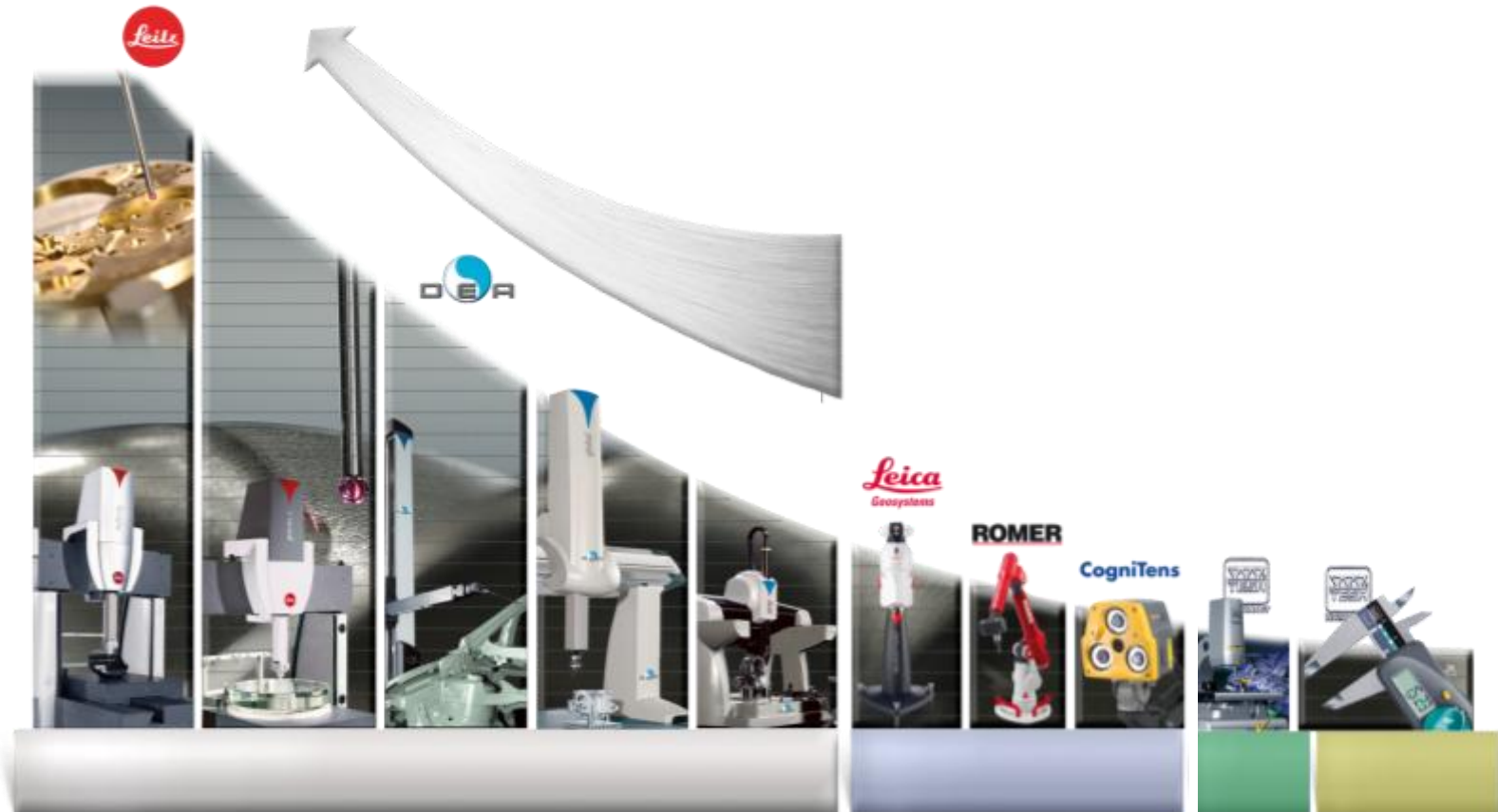
Hexagon Metrology GmbH: Leitz Factory

Industries served:

- Automotive
- Machine Tool
- Energy Generation
- Aircraft/Aerospace
- Heavy Industry



Complete Product Portfolio



← (0.3 μ m) Increasing Accuracy

Leitz PMM-G: Now up to 4.5m in Y – Second Generation



*Sizes (up to **84 m³** measuring volume)*

from 30.20.12
to **70.45.30**

Accuracies (for Z = 12)

MPE **E** **2.4 + L/400 μ m**
MPE **P** 1.9 μ m
MPE **THP** 3.3 μ m / 58 s

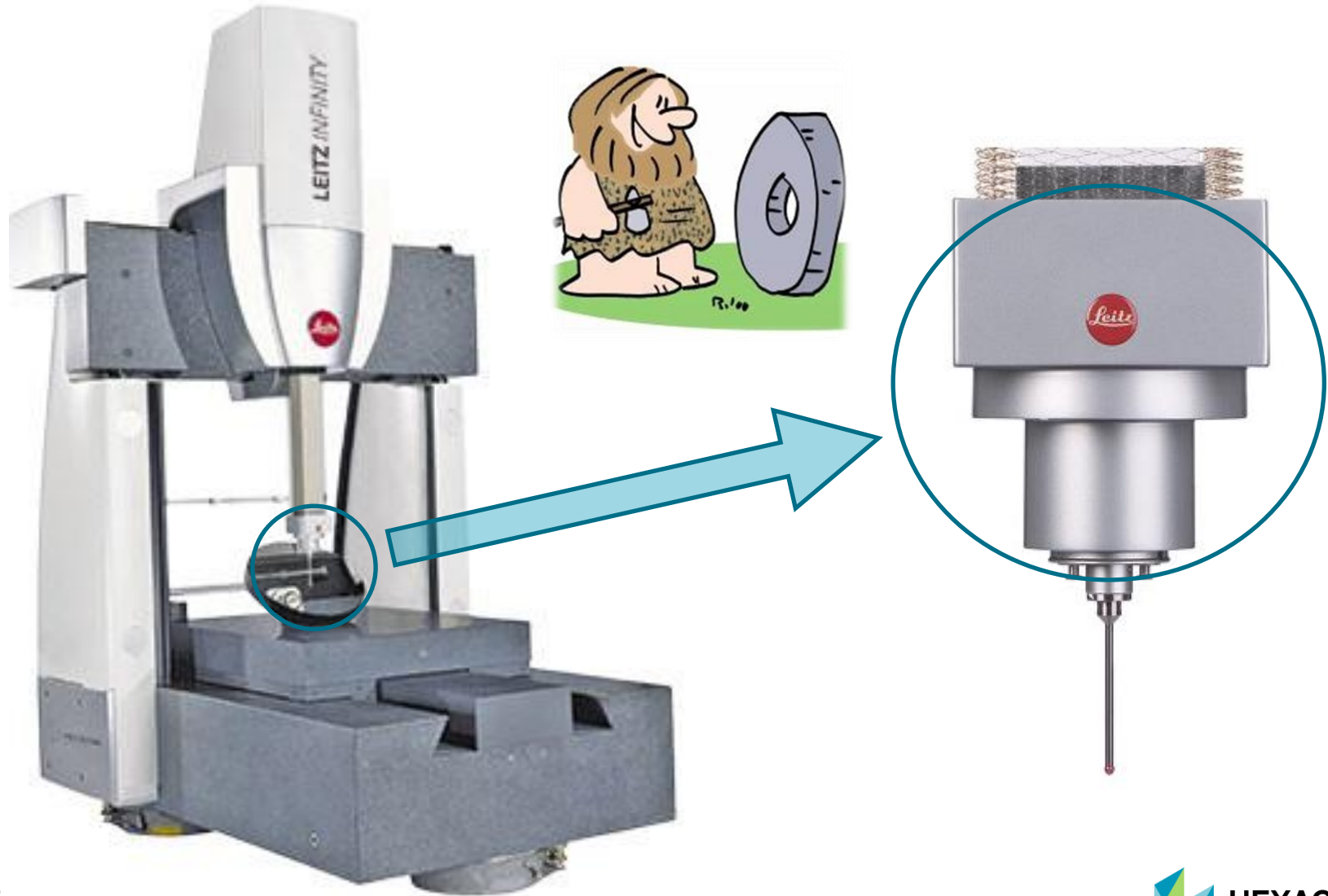
Systems installed

PMM-G 41 ↘ Over 100 installed
Gantry 62 ↗ systems

Some references

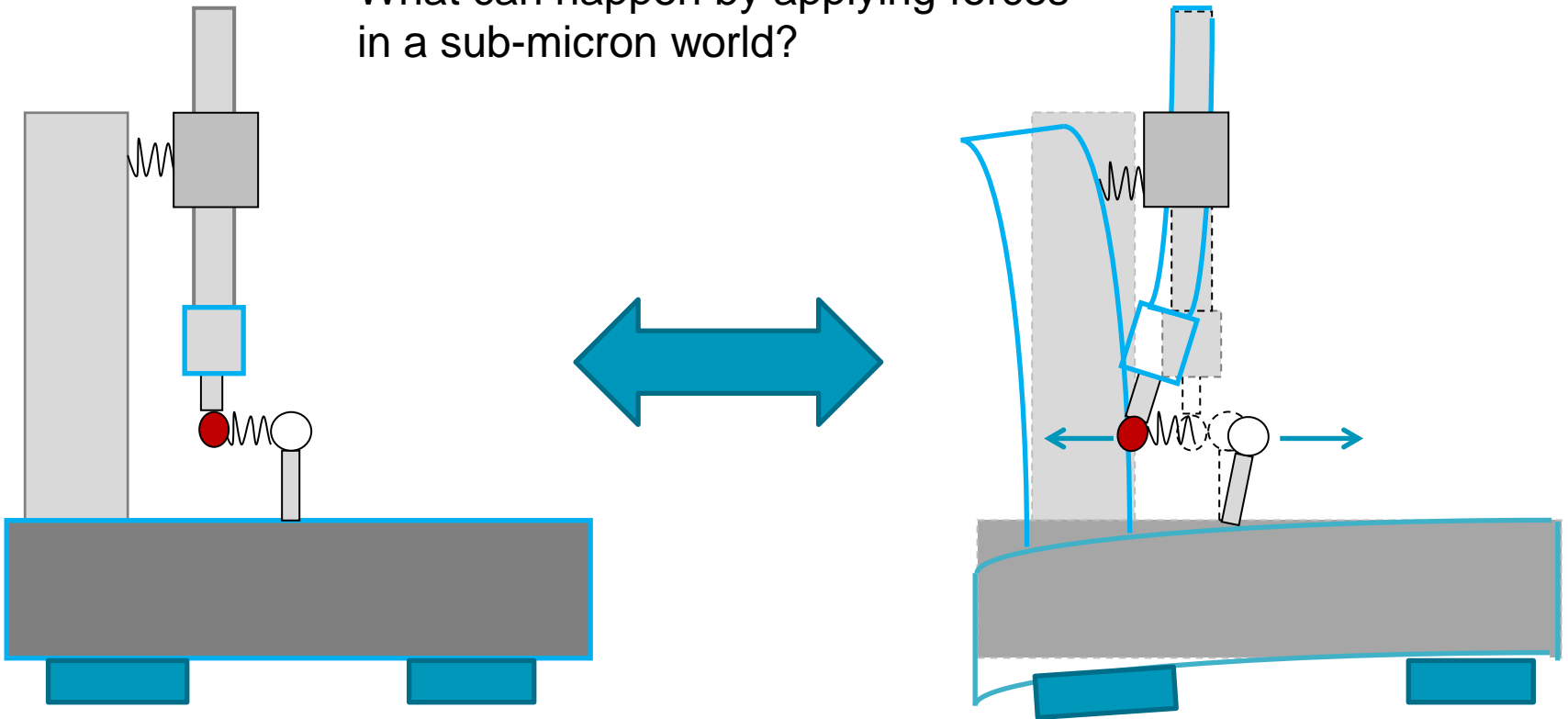
- ▶ Flender, Germany
- ▶ CMD, France
- ▶ Hansen Transmission, Belgium

Introduction – Machine and probehead

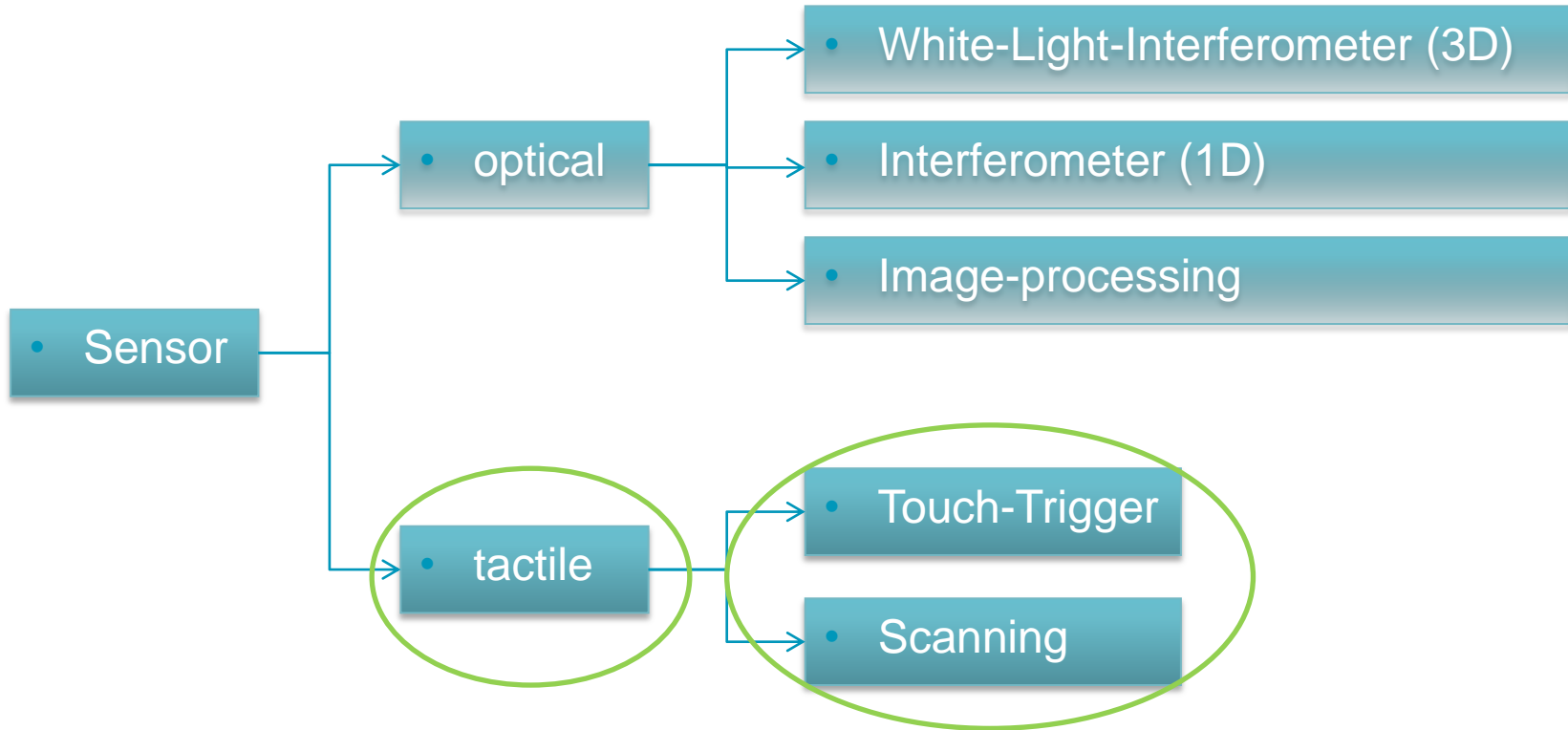


Introduction - Rigid-body vs. deformable-body

What can happen by applying forces in a sub-micron world?



Sensors for a CMM



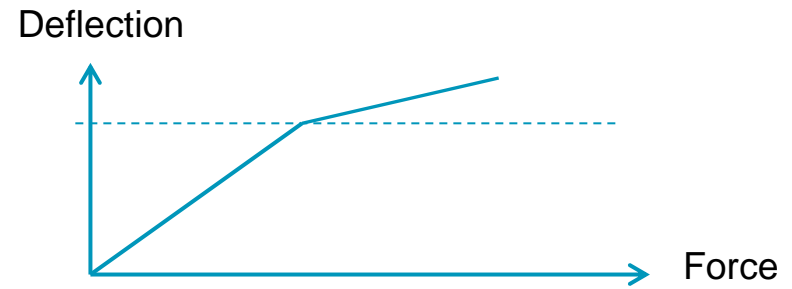
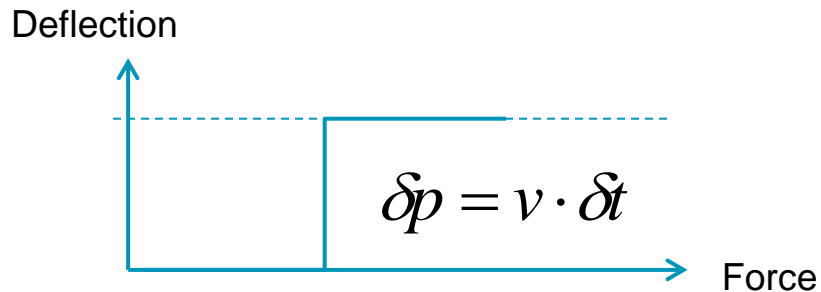
Different types of probeheads for tactile measurement

• Touch-trigger probes

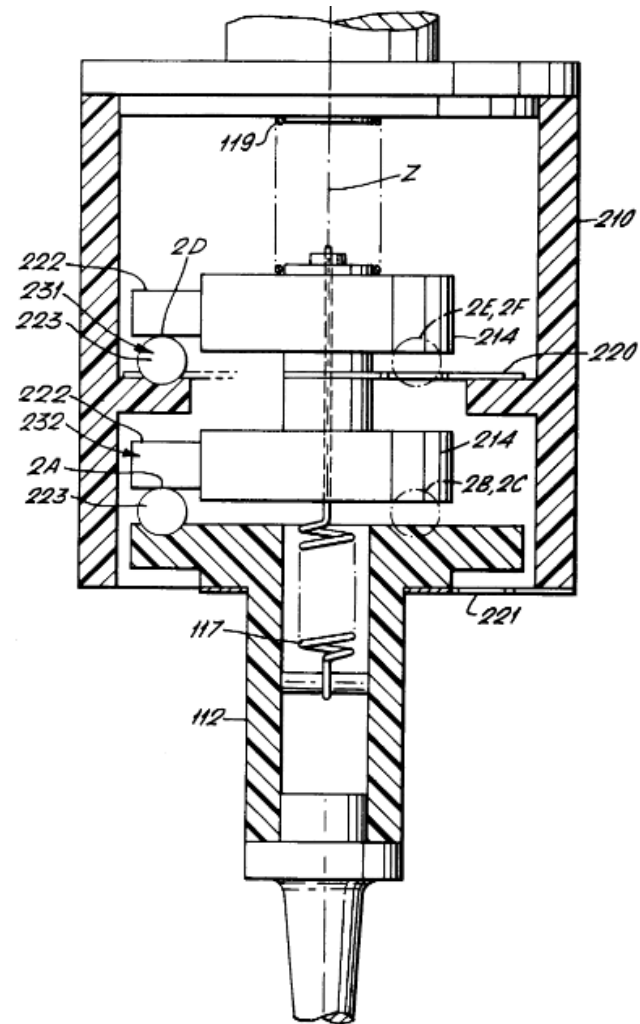
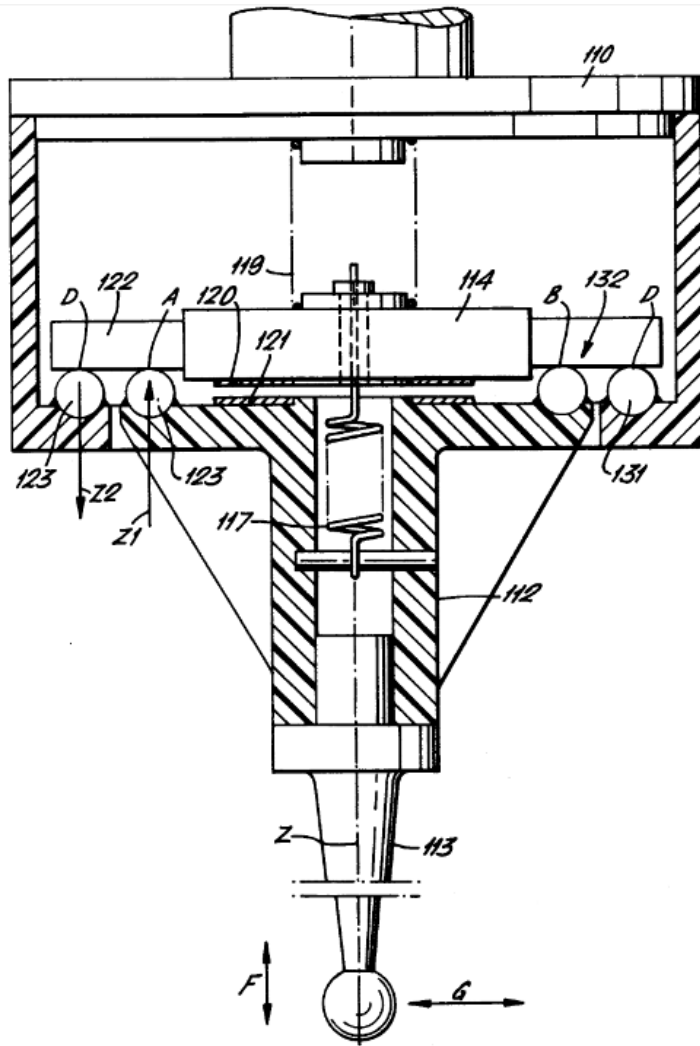
- Some advantages
 - lower cost,
 - smaller size
 - Fast probing
- Some disadvantages
 - Lower accuracy
 - Surface-normal cannot be determined (Variation due to bending cannot be taken into account)
 - Result depending on sampling-time and probing-speed

• Scanning probes

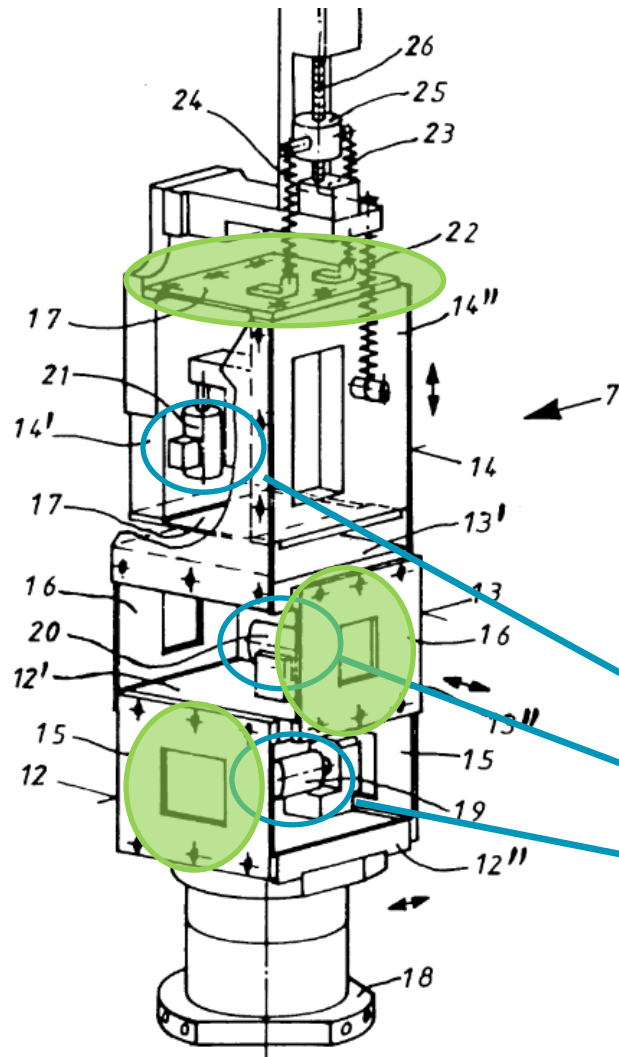
- Some advantages
 - Higher accuracy
 - Surface-normal determined
- Some disadvantages
 - Higher cost
 - Bigger size
 - Probing takes more time



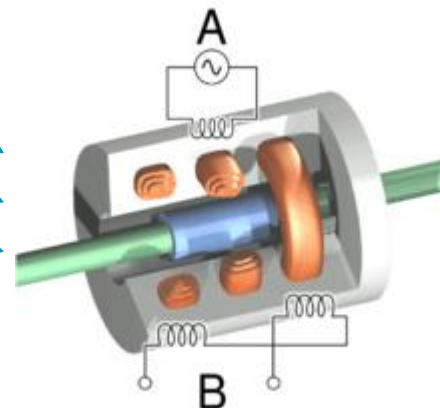
Touch-Trigger-Probe (McMurty, 1976)



Basic principles of scanning probes



- Leaf-springs to achieve certain forces during probing
- Linear behaviour of springs in a wide range
- Independent movement of the axis
- Compact building
- Damping needed
- Weight balance of probes
- Measuring the displacement in each axis



Example for a compact probehead with leaf-spring

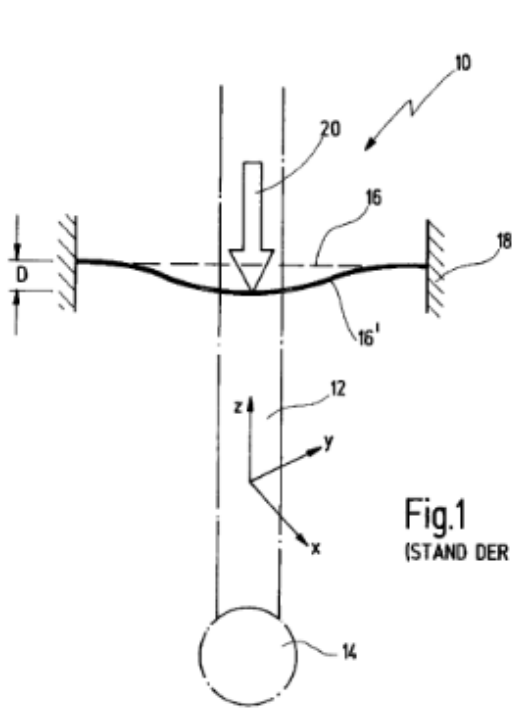


Fig.1
(STAND DER TECHNIK)

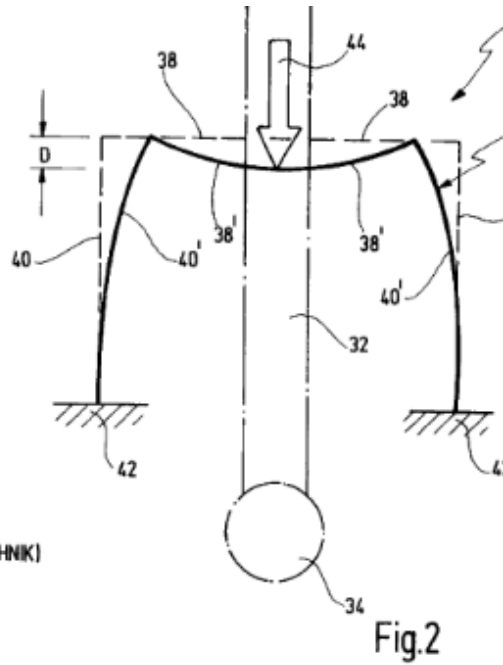


Fig.2

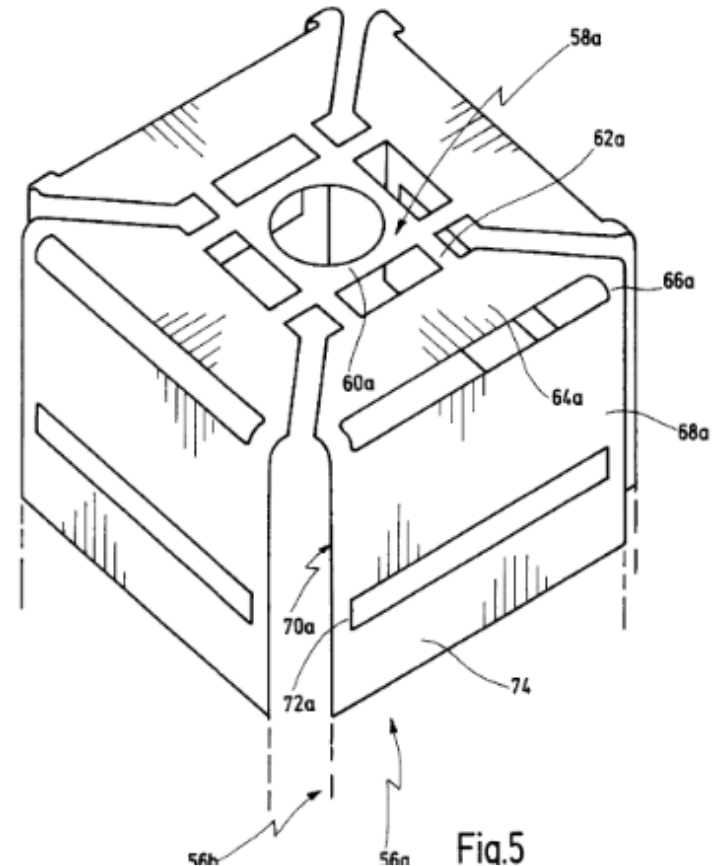
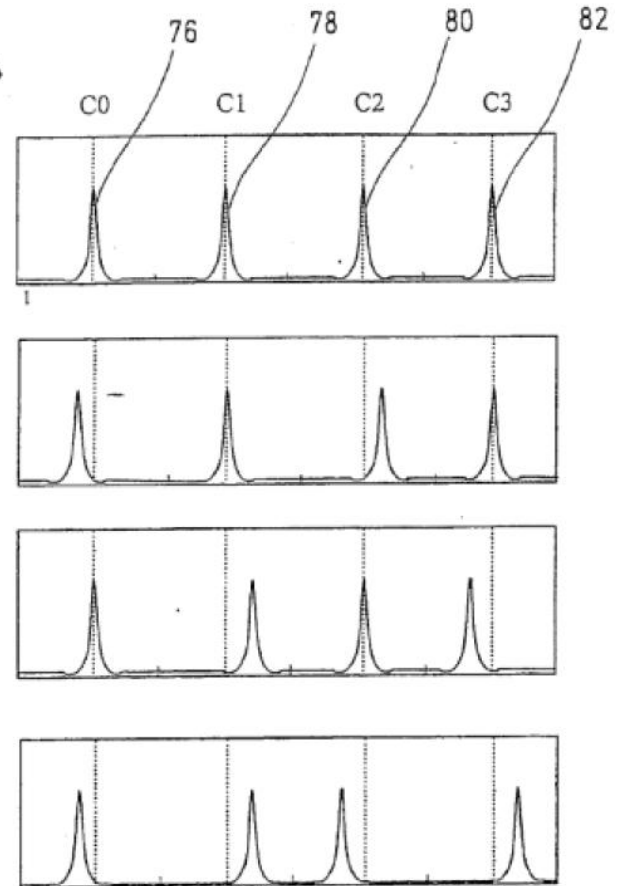
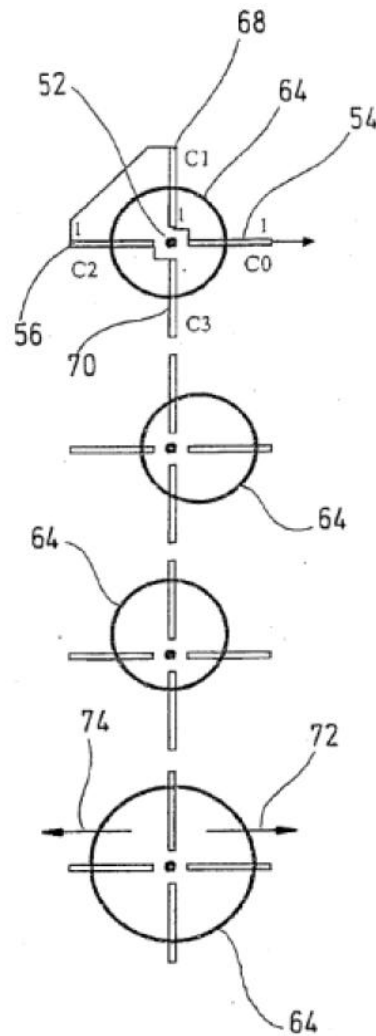
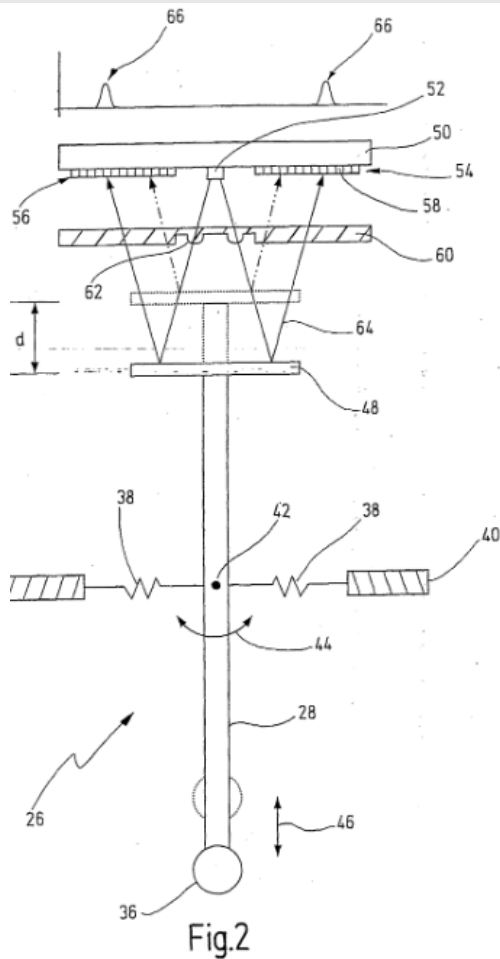
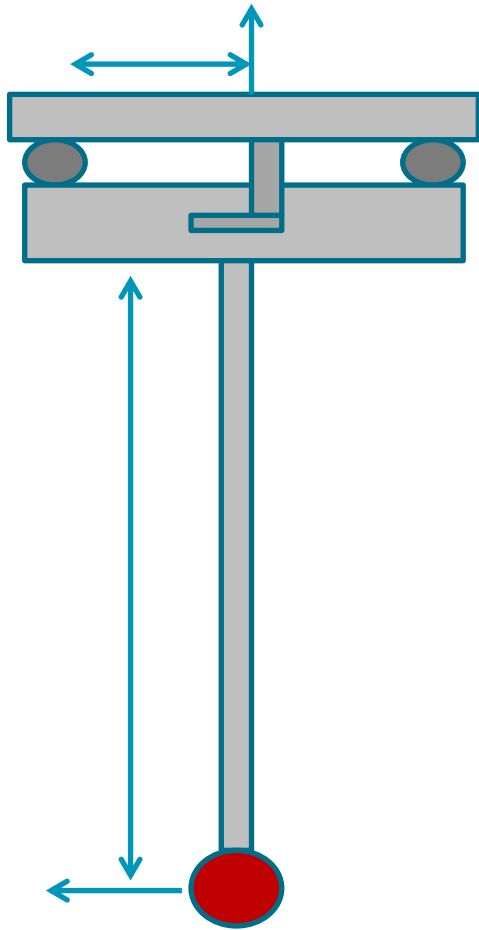


Fig.5

Optical measurement of the displacement

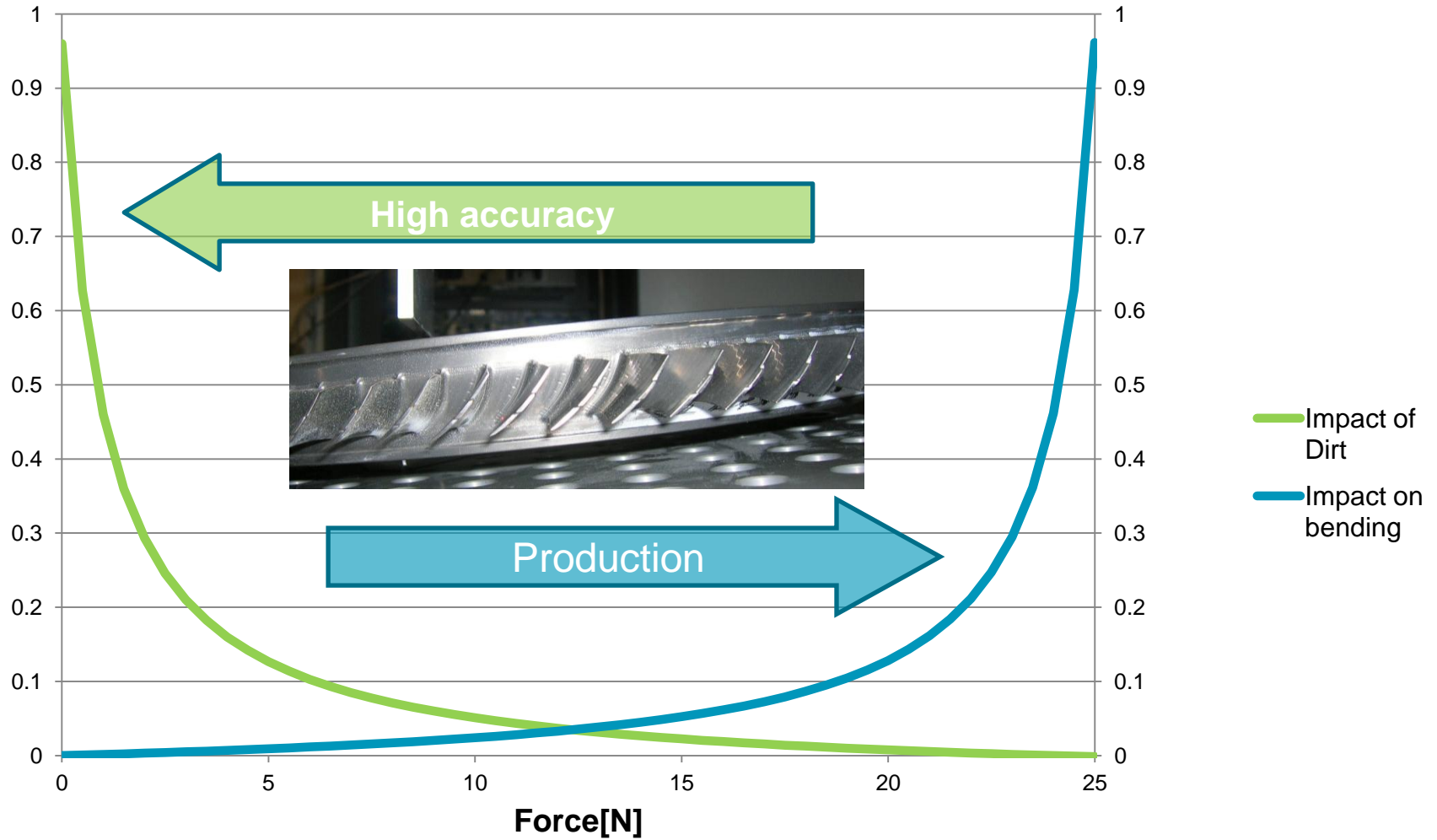


Max. forces according to momentum

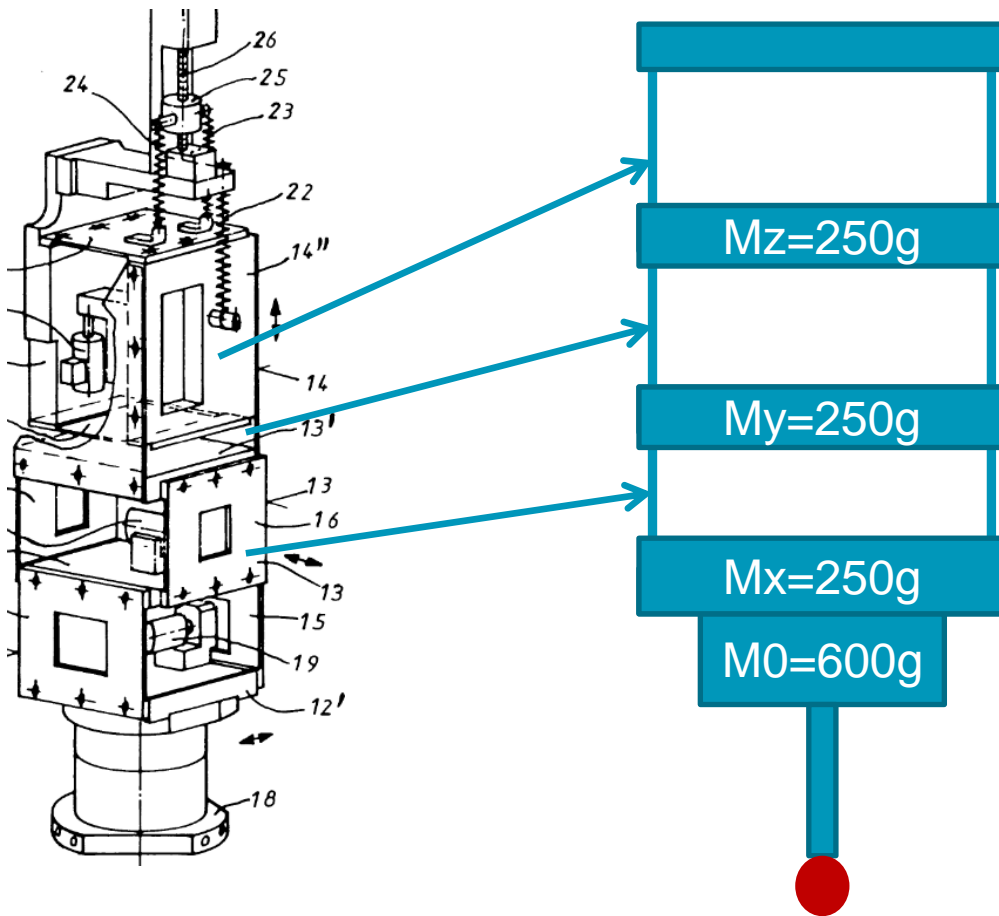


- Angular momentum: e.g. 300N for the gripper
 - D1 at platform: 2cm
 - Max. length of stylus 1m
 - Max. force: 1.2N
- ↓
- Max. momentum: 1.2Nm
 - Max. allowed momentum: 6Nm
- Use low forces to
 - avoid deforming
 - Avoid critical angular momentum

High- and low-force probing

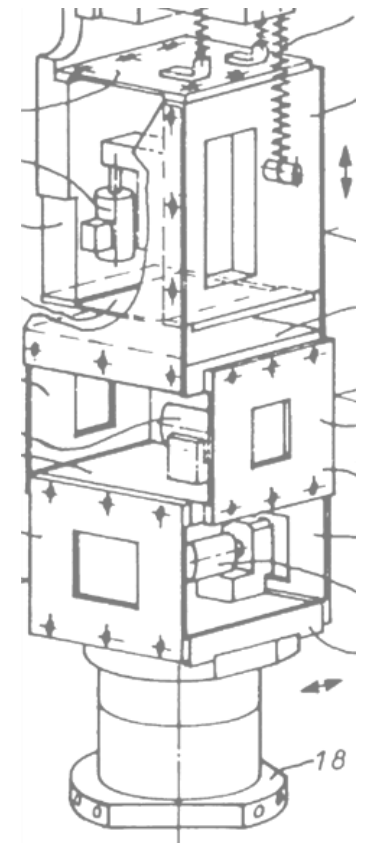
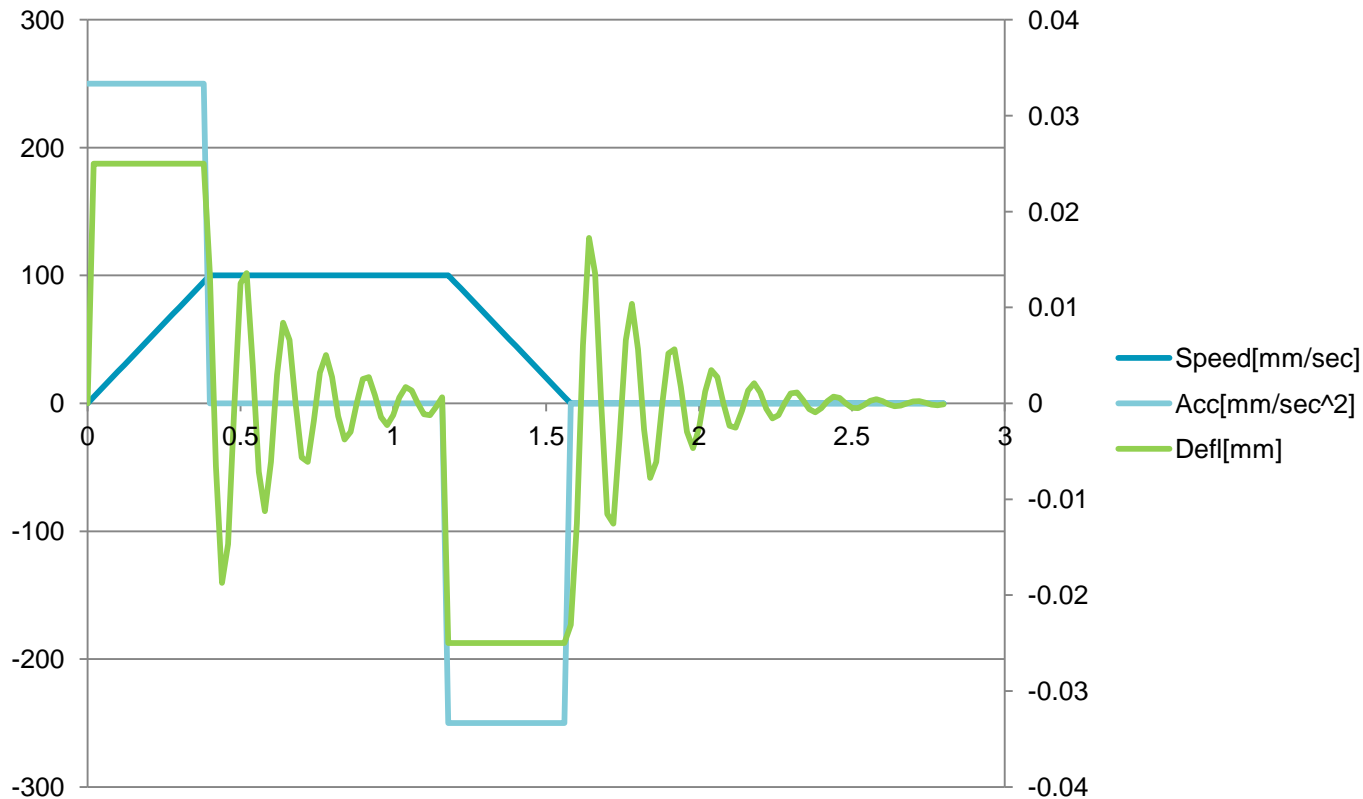


Effects of inertial mass

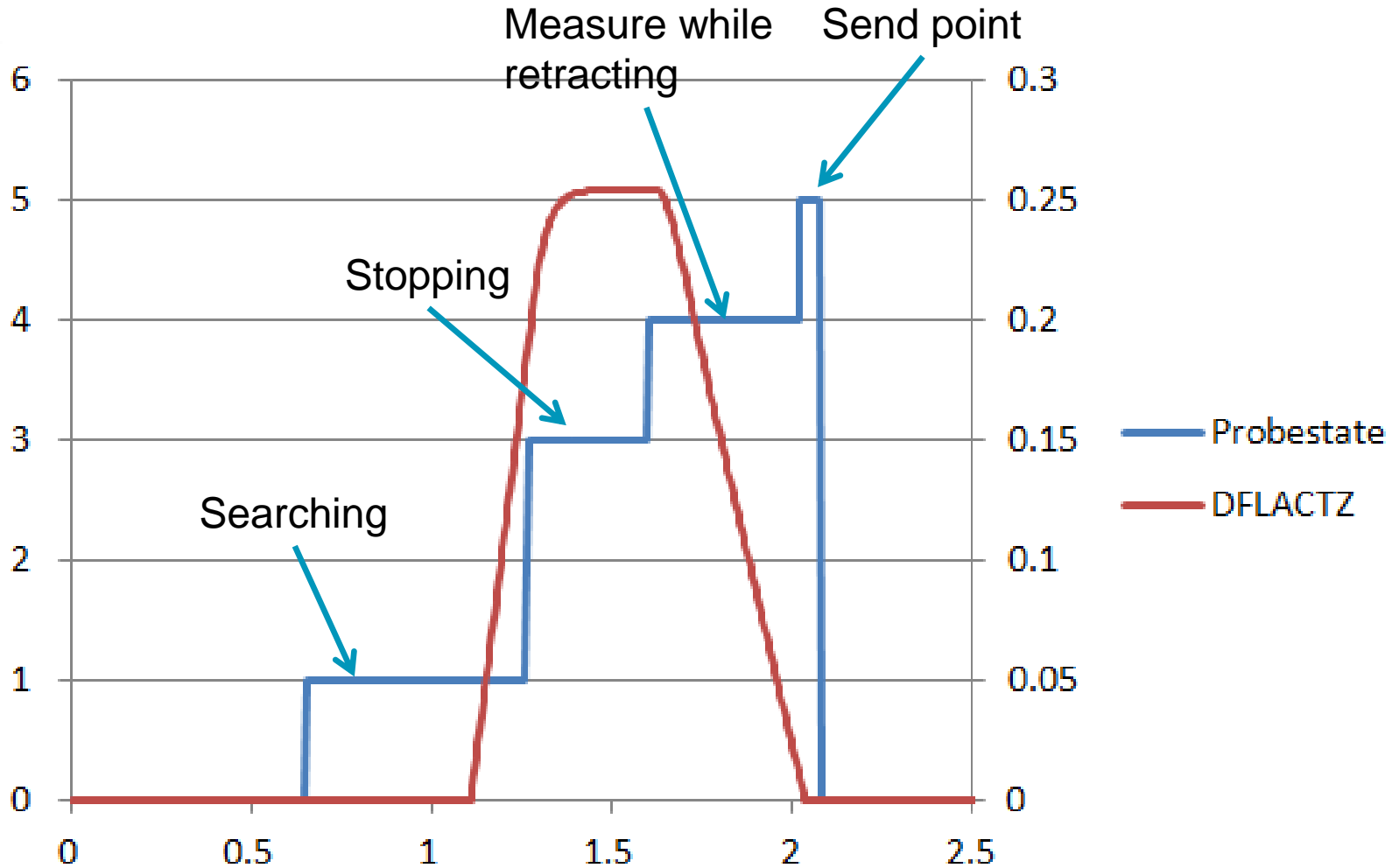


	MTK-4	MTK-5
Mass[kg]	1.45	0.61
Spring-const[N/mm]	1.60	5.00
Accel[mm/s ²]	MTK-4 [μm]	MTK-5 [μm]
1.00	0.91	0.12
5.00	4.53	0.61
10.00	9.06	1.22
25.00	22.66	3.05
50.00	45.31	6.10
250.00	226.56	30.50
600.00	543.75	73.20
2000.00	1812.50	244.00

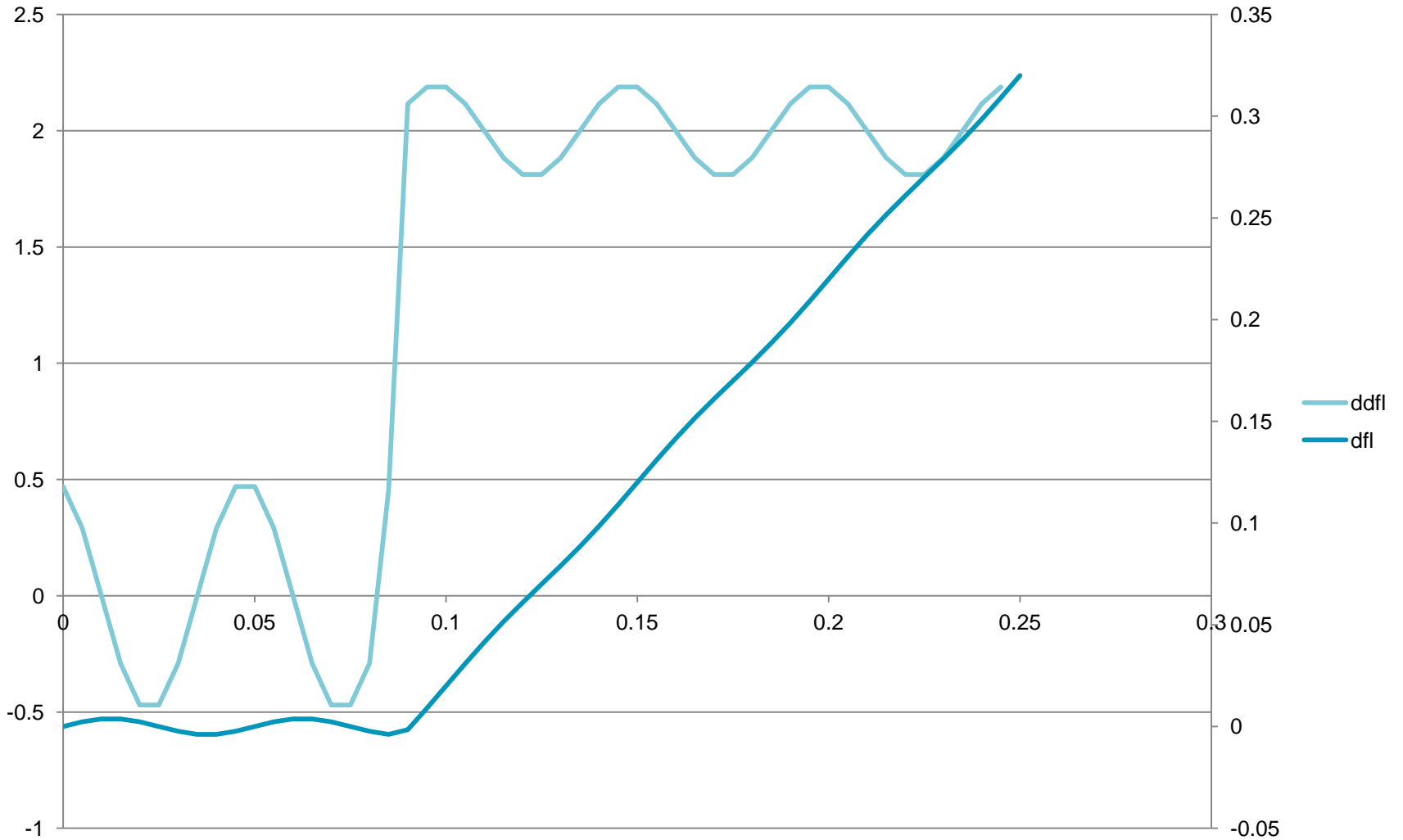
Damping and clamping of a probehead



Typical probing of a surface

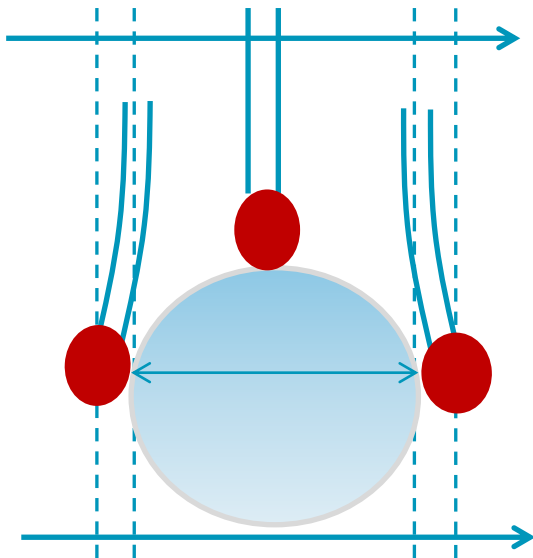


How to detect a probing



Physical aspects of calibration procedures

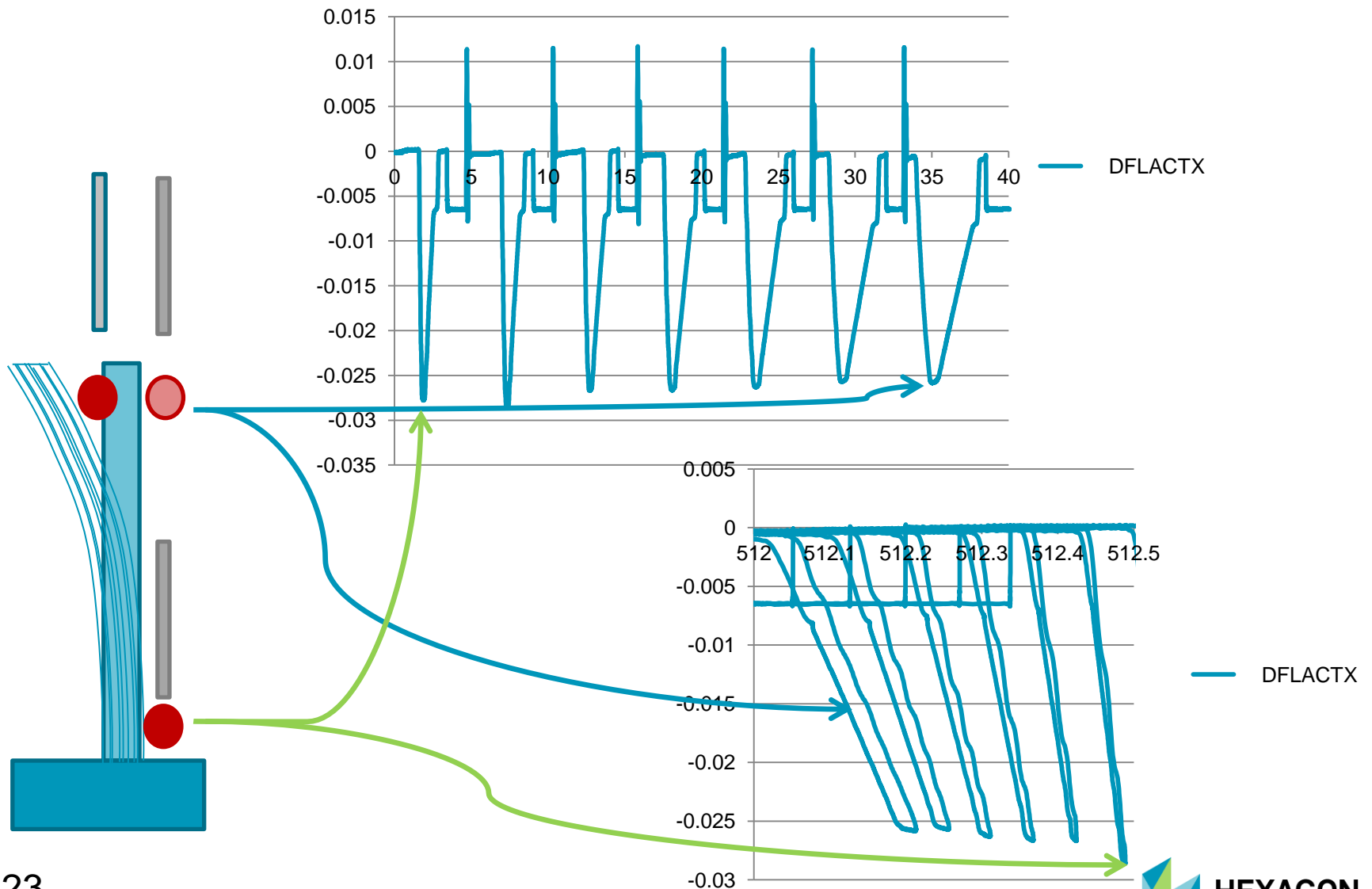
- Preconditons
 - machine has to reproduce in a certain way
 - errors are mapped so that the machine shows the same behaviour at every position
- Calibration takes care of different sensors and probetips or even surfaces



$$p(x_2) + d(x_2) + b_x \cdot d(x_2) - p(x_1) - d(x_1) - b_x \cdot d(x_1) \\ = 2 \cdot (R_{sphere} + R_{Probe})$$

$$\vec{p}_a = \vec{p} + \vec{d} + \begin{pmatrix} b_{xx} & b_{xy} & b_{xz} \\ b_{yx} & b_{yy} & b_{yz} \\ b_{zx} & b_{zy} & b_{zz} \end{pmatrix} \cdot \vec{d}$$

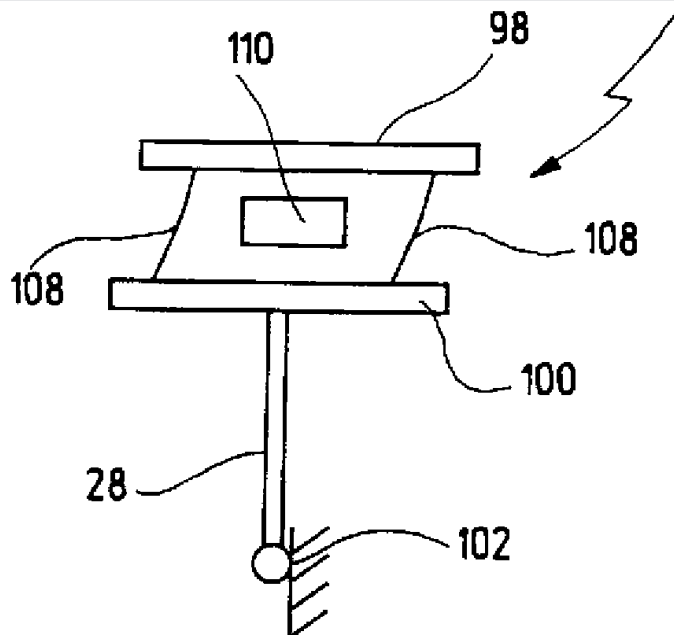
Practical example: a knife-edge



Checking stability of calibration

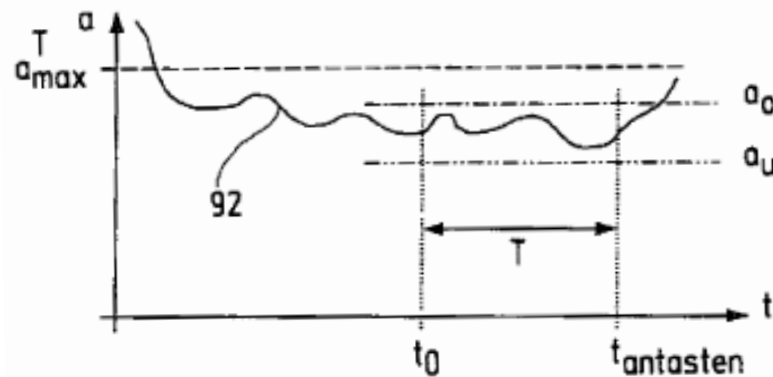
- Check certain qualifying parameters by re-calibrating (e.g. bending-parameters) by comparing the values over time
- For a known calibrated probetip the calibration-parameters can be checked in certain intervals

Checking stability/quality/repeatability of probes



DE 10 2004 038416 B4

- Check the acceleration in the probehead
- If the acceleration is too high give a warning or redo measurements



Check signals with acceleration sensor

FIG.18

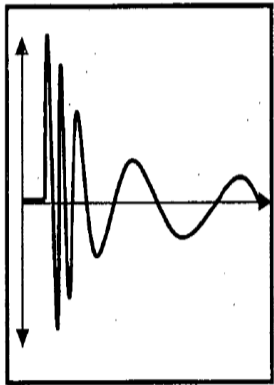
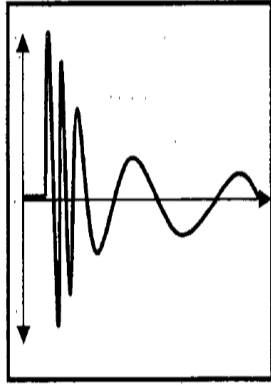


FIG.19



- Keep deflection signal and filter acceleration-effects

FIG.20

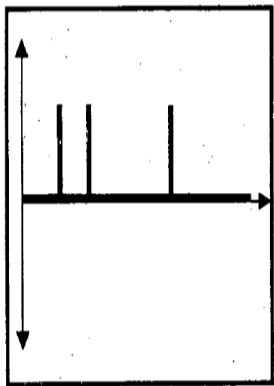


FIG.21

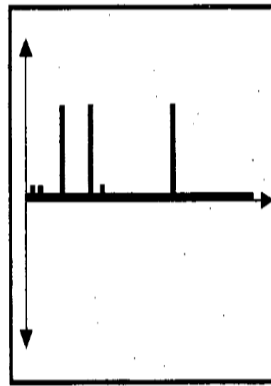
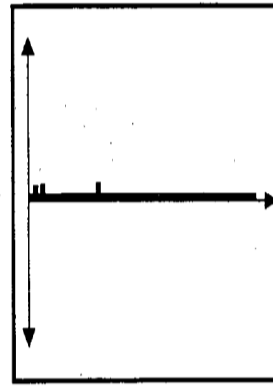
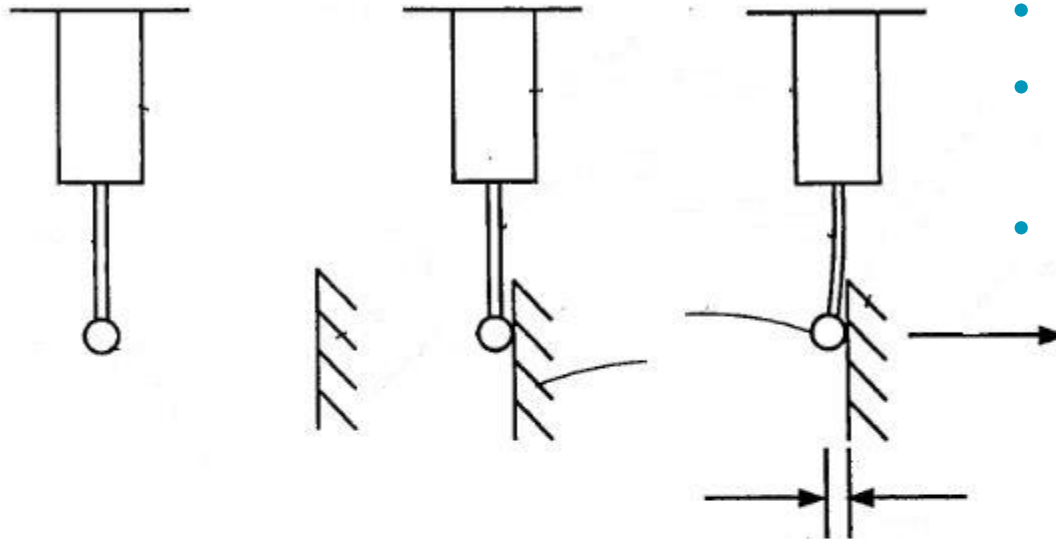


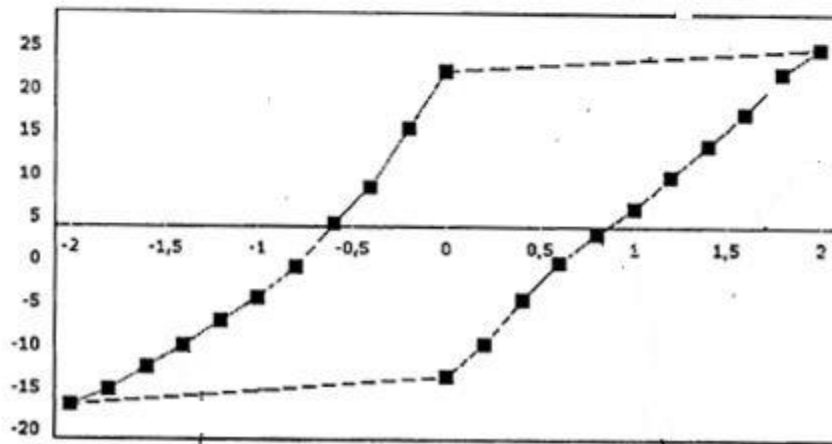
FIG.22



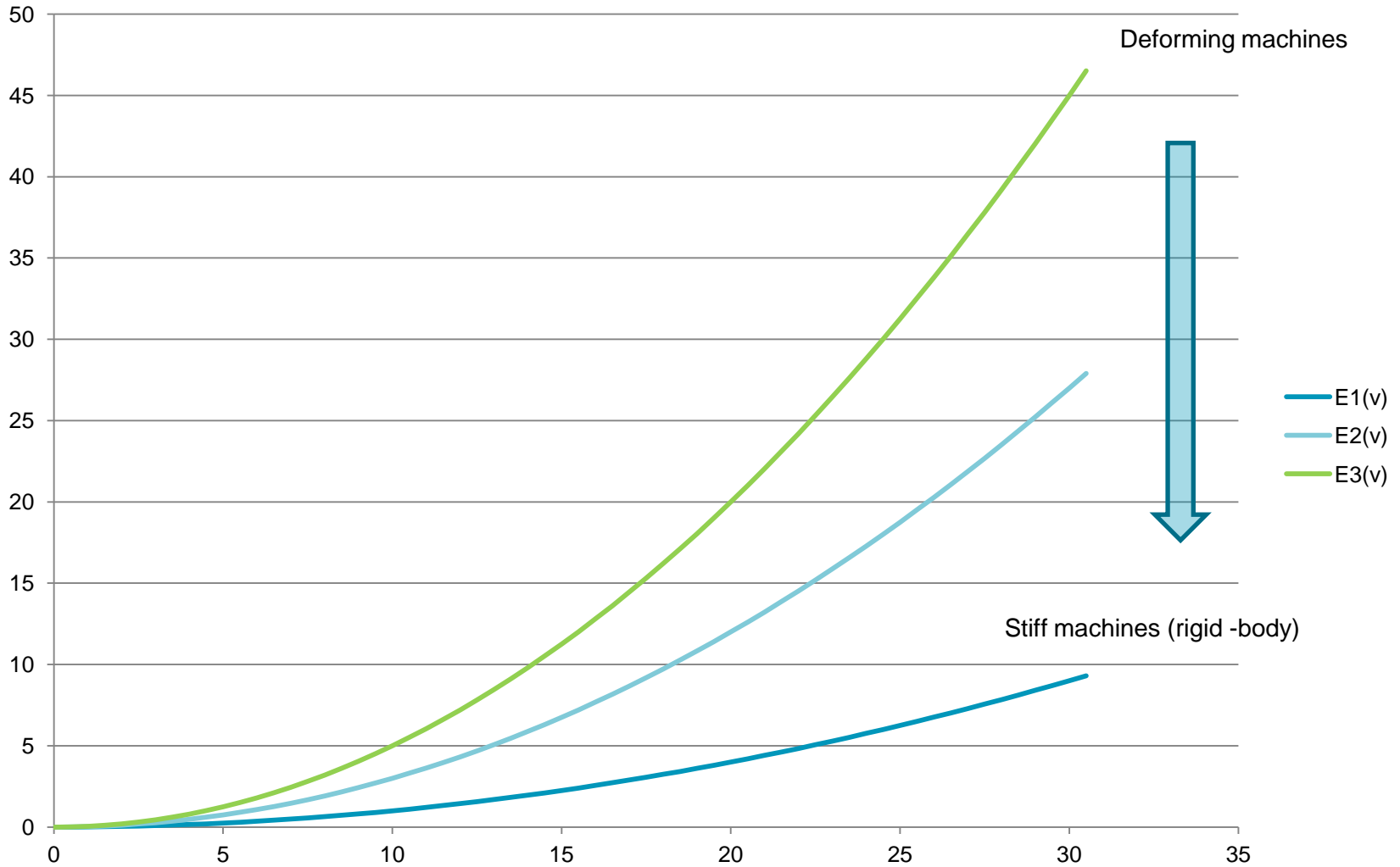
Checking hysteresis (electrical and mechanical)



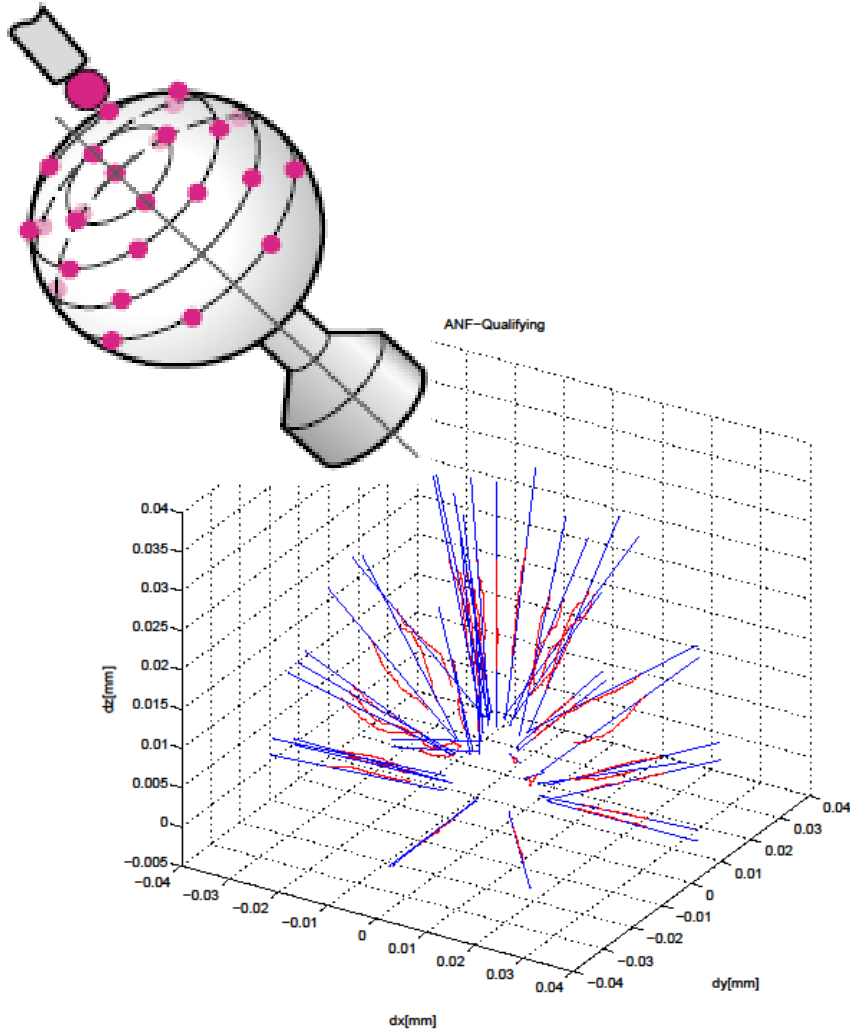
- Delay due to
- Filtering of electronic components
- Mechanical nonlinearity



Compensate dynamic errors



Checking stability/quality/repeatability of probes (ISO-Tests 10360-5)

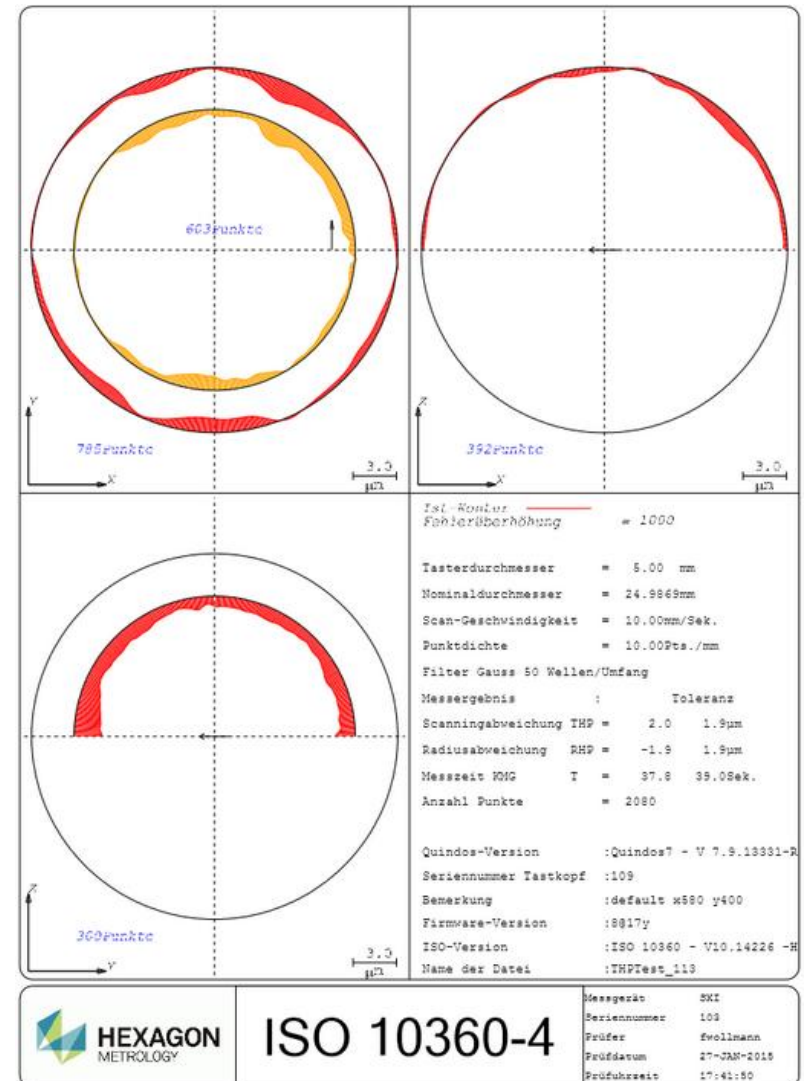
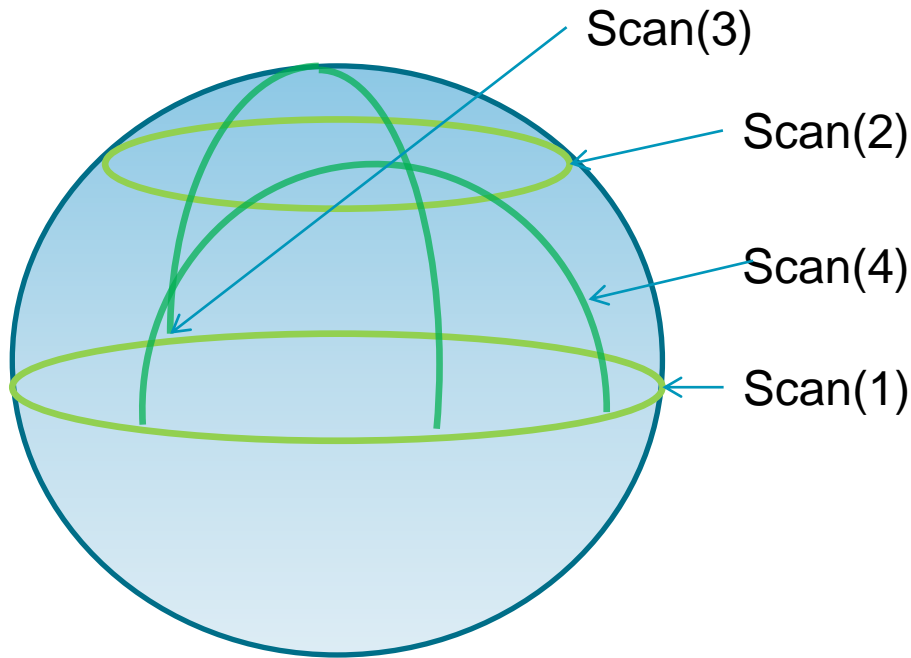


Kunde		VW Salzgitter	Prüfer		fwoillmann
Meßgerät		SXI	Prüfdatum		27-JAN-2015 / 17:22:28
Seriennummer		103	Standort		Halle 1
S/N Tastkopf		109	Bemerkung		Itps x390 y400
MPE P(FTU) / P(STU) [µm]		1.90 / 0.00	Temperaturen während der Messung		
Parameter der Kugel	Durchmesser	24.9869	Temp. X-Achse	20.00	Kompensation
	X-Mittelpunkt	-48.1	Temp. Y-Achse	20.00	
	Y-Mittelpunkt	-2.7	Temp. Z-Achse	20.00	Aut
	Z-Mittelpunkt	120.8	Temp. Werkstück	24.26	
Quindos Version		Quindos7 - V 7.9.13331-Release-3	Firmware Version		8@17y
ISO Programm Version		ISO 10360 - V10.14226 -HexPts	Dateiname		PTest_030

PT NR.	ABW. [µ]	-TOL/2	GRAFIK	+TOL/2	PT NR.	ABW. [µ]	-TOL/2	GRAFIK	+TOL/2
1	0.73		.	*	14	0.07		.	*
2	-0.17		*	.	15	0.13		.	*
3	0.60		.	*	16	0.13		.	*
4	0.09		.	*	17	0.12		.	*
5	0.08		.	*	18	-0.15		*	.
6	-0.44		.	*	19	-0.20		*	.
7	-0.67		.	*	20	0.50		.	*
8	0.24		.	*	21	-0.49		*	.
9	0.09		.	*	22	-0.46		*	.
10	-0.47		.	*	23	0.29		.	*
11	0.31		.	*	24	0.27		.	*
12	0.04		.	*	25	-0.41		*	.
13	-0.21		*	.					

Zusammenfassung	
Größe positive Abweichung :	0.73 µm bei Punktnummer 1
Größe negative Abweichung :	-0.67 µm bei Punktnummer 7
Toleranz MPEp =	1.90 µm
Spanne der Abweichungen =	1.40 µm
Testergebnis:	<u>bestanden !</u>

Checking stability/quality/repeatability of probes (ISO 10360-4)



Concluding remarks

- The world of CMMs is quite rich and complicated and therefore still very interesting
- Studying patents can provide a broad knowledge-base of what's already achieved
- Reproducibility is most important for accuracy



"So much for the wheel —
Now to invent the *casino!*"



Questions?

