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Workshop on Cloud Services for File Synchronisation and Sharing CERN, November 2014

Mysteries of Dropbox

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We're here because we care about synchronization!

Actually, a lot of people care about synchronization

And they care a **Ot**

~200M

So... Is yours correct?

What does that even mean??

Goals

- Ultimate goal: Answer this question rigorously
 - i.e., give a *complete* and *precise* definition of how a synchronization service should behave (from the point of view of users, not protocols)
 - i.e., write down a *formal specification* that, for each observed interaction with a synchronization service (involving several replicas being read and written over time), says whether or not it is OK
- Goal for this talk:
 - Report on baby steps in this direction

A Little History



- Unison is the only synchronizer based on a formal specification (AFAIK)
- Main designers
 - Trevor Jim, Jerome Vouillon, and BCP
- First version distributed in 1998
 - Earlier prototypes going back to 1995
 - Still widely used
- Open-source, multi-platform (Windows, OSX, Linux)
- Very few reported bugs with potential to lose data

But the world has changed...

Synchronization tools: (bidirectional, sync operations explicit)

• Unison, ...

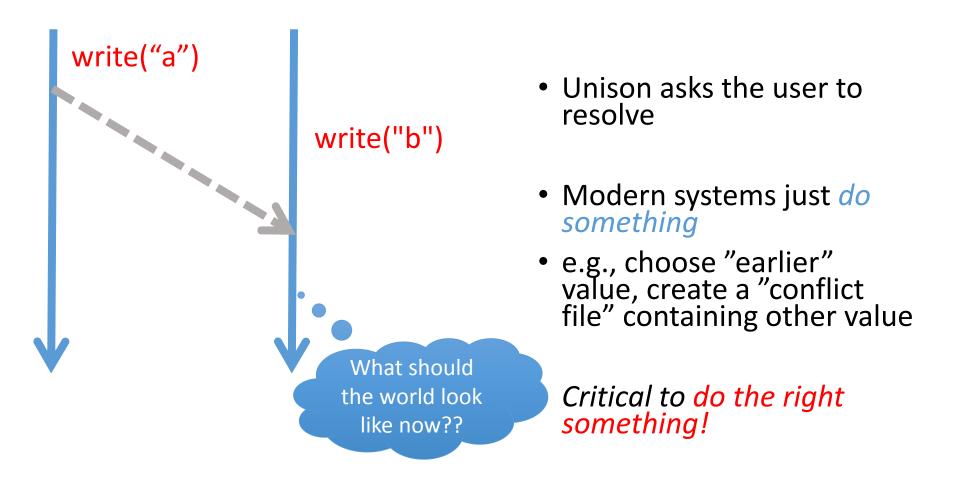
Synchronization services: (multi-directional, sync in background)

- Central server ("cloud-based")
 concentrate on these
 - Dropbox, Google Drive, OneDrive, Owncloud, SpiderOak, Sugarsync, Box.net, Seafile, Pulse, Wuala, Teamdrive, Cloudme, Cx, Amazon cloud service, ...
 - Also distributed filesystems (Coda, GFS, ...)
- Peer to Peer
 - Bittorrentsync

Challenges

- Syncing in background produces inherently nondeterministic behaviour
 - Our specification will need to specify sets of legal behaviors
- Similar to weak memory models for multi-core processors...
- But harder!
 - directory structure
 - deletion
 - conflicts
 - ...

One challenge: Conflicts



Another challenge:

How can we test that our specification is accurate??

This is hard!

So...

Don't write tests!

Generate them

QuickCheck



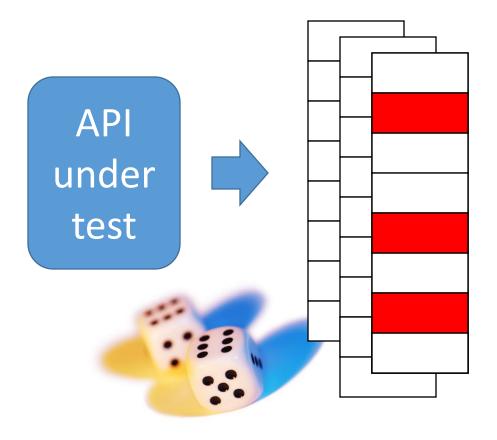
1999—invented by Koen Claessen and John Hughes, for Haskell

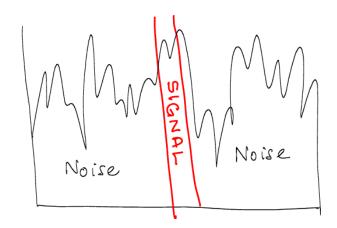
2006—Quviq founded, marketing Erlang version

Many extensions

Finding deep bugs for Ericsson, Volvo Cars, Basho, etc...

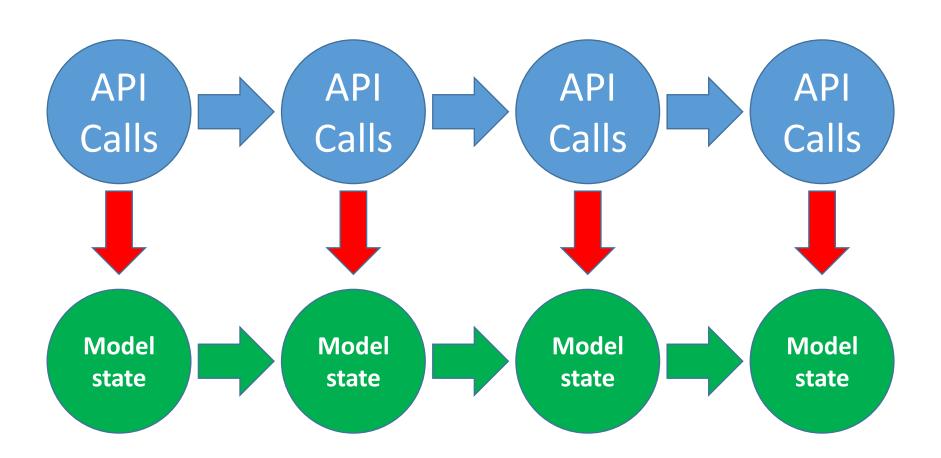
QuickCheck



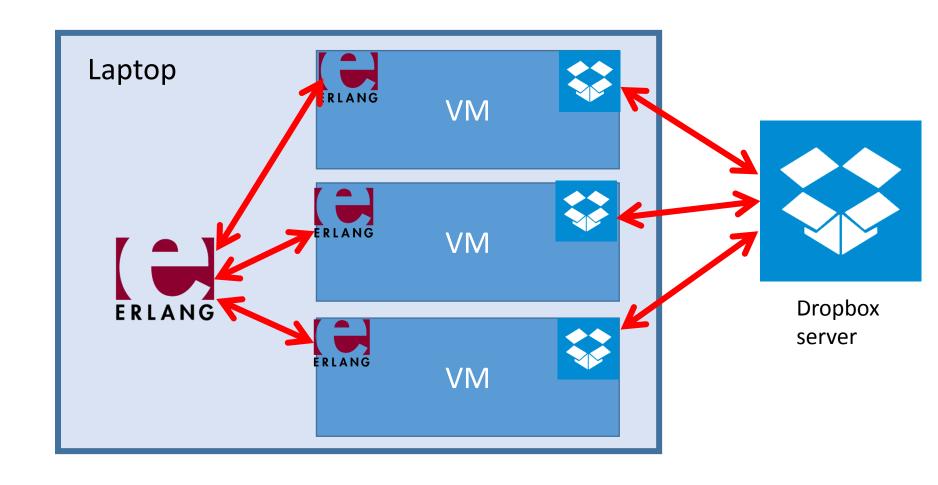


A minimal failing example

State Machine Models



Test Setup



Challenges of testing

- Uniformity
 - *Many* synchronization services
 - → Want a single specification and test framework that applies to multiple systems
- File synchronizers are SLOOOOWWWW!!!
 - Exponential back-off
 - No such thing as waiting "long enough"
 - Tests must adapt to the speed of the synchronizer
- Interference between tests
 - Reads/writes/deletes in the same directory
 - → Isolate tests by using many directories
 - Test setup:
 - Delete old directories, and wait
 - Create new directories, and wait...

A small simplification

Real-world filesystems are pretty complicated So let's start with something a little simpler...

"Filesystem" = 1 file
Operations: read, write
(and, later, delete)

Tests are sequences of commands

- read(Node)
- write(Node,V)
- sleep
- synchronize?
- stabilize
 - Wait for value observed on each node to be the same (Also conflict files)

Observations

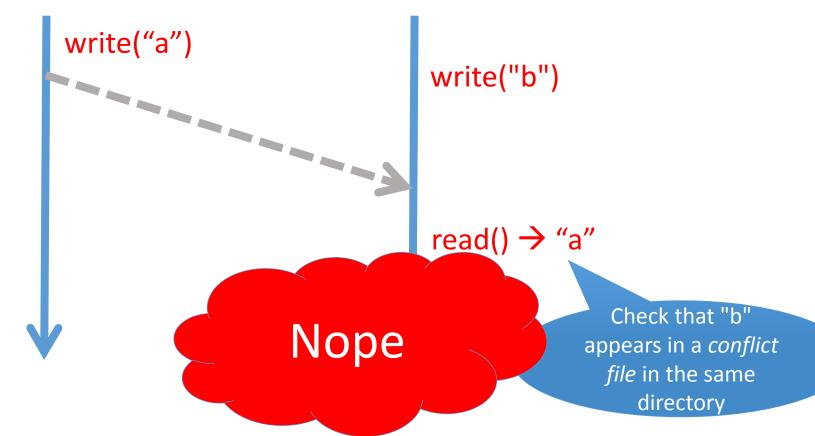
 Made dynamically; the specification says which observation sequences are valid

- What do we observe?
 - read(N) → V
 - write(N,Vnew) \rightarrow ()
 - Conflicts??

No: write(N,Vnew) → Vold
It matters what we
overwrite!

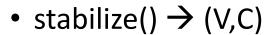
Observing conflicts?

 First try: when a write creates a conflict, check that one of the conflicting values appears in a conflict file



Observing conflicts... eventually!

New observation:



stable value (same everywhere)

set of values found in conflict files (same everywhere)

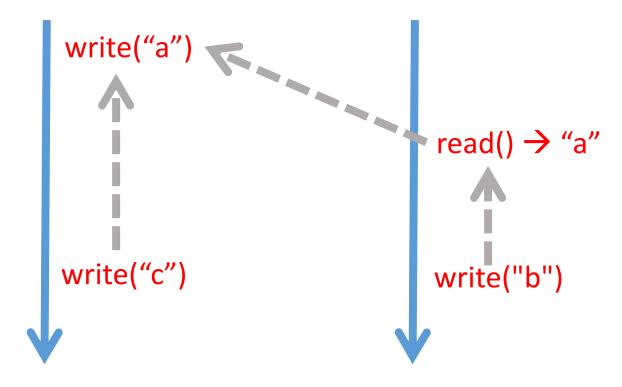
Now...

What should our specification look like?

A dead end

But what about repeated values? E.g. deletion?

• Compute a "happened before" relation (à la weak memory models) and express correctness in terms of that...



A Better Idea

- Model the whole system state including the server
- Update the state after each observation
- Add "conjectured actions" to the observed ones up(N) node N uploads its value to the server down(N) node N is refreshed by the server
- Corollary: there may be many possible states at each stage in a test; a test fails when there are no possible states that explain the observations that have been made

Modelling the state

- Stable value (i.e., the one on the server)
- Conflict set (only ever grows)
- For each node:
 - Current local value
 - "Fresh" or "stale"
 - "Clean" or "dirty"

i.e., has the global value changed since this node's last communication with the server

i.e., has the local value been written since this node was last refreshed by the server

Modelling the operations

- read(N) \rightarrow V
 - Valid when: V = local value on node N
 - Action: state unchanged
- write(N,Vnew) → Vold
 - Valid when: Vold = local value on node N
 - Action: local value on node N becomes Vnew node N becomes dirty
- stabilize() → (V,C)
 - Valid when: V = global value, C = global conflict set, all nodes fresh and clean
 - Action: state unchanged

Modelling the operations continued...

- down(N)
 - Valid when: N is neither dirty nor fresh
 - Action: take N's local value from global value
 N becomes fresh

Modelling the operations...

- up(N)
 - Valid when: node N is dirty
 - Action: if node N is fresh then

take global value from node N's local value

N becomes clean

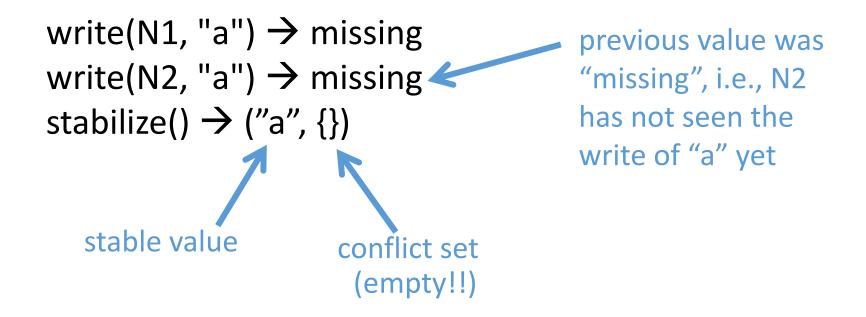
other nodes become stale

else

add N's local value to conflicts

N becomes clean

Surprise!



Specification and implementation disagree... Is it a feature or a bug?

Refining the specification...

 Add special cases in specifications of up and down commands when the local and global values are identical

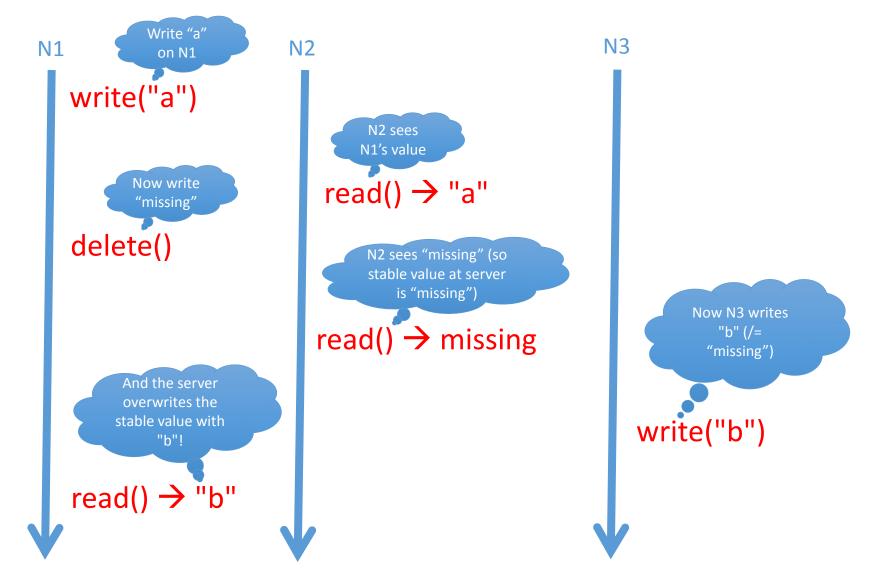
The test now passes

Dealing with Deletion

 Deletion can easily be added to the model: delete(N) just means write(N, missing)

Try adding this and run some tests...

Surprise!



Refining the specification...

- Add special cases for "missing" in up and down actions:
 - When "missing" encounters another value during an up or down, the other value always wins
 - I.e., when a write and a delete conflict, the delete gets undone

Another surprise!

sleep(2 seconds)

sleep(.5 second)

sleep(.5 second)

sleep(.75 second)

write("a")

delete()

write("c")

read() → missing???

write("b")

An Even Bigger Surprise!

```
write(N1, "b") -> missing
sleep(.75 second)
delete(N1) -> "b"
sleep(.75 second)
read(N1) -> "b"
```

b came back after being deleted!?!

Work in progress!

Current state:

- Formal specification of single-file behavior of Dropbox and related services
- One apparent bug in Dropbox so far
- Prototype validation harness in Erlang QuickCheck

Next steps:

- Add directories
- Test *your* synchronizer :-)

Resources

- Unison www.cis.upenn.edu/~bcpierce/unison/
- Unison specification
 google "What is a File Synchronizer?"
 google "What's in Unison?"
- Quviq testing tools www.quviq.com
- Lenses

http://cis.upenn.edu/~bcpierce/papers/index.shtml#Lenses (a more general theory of bidirectional information propagation between related structures)



