



Transport and Handling Considerations for the FCC


Ingo Rühl / CERN - EN-HE

First Annual Meeting of the Future Circular Collider Study
Washington D.C., 23-27 March 2015



- General issues
- FCC geographical data
- Vertical handling aspects
 - Lifts
 - Cranes
- Tunnel transport aspects
 - Automatic guided vehicles (AGVs)
- Conclusion



- Delivery of components
 - Assembly
 - Test
 - Storage (just on time?)
 - Transfer to shaft (road transport)
 - **Surface**  **Underground transfer (crane or lift)**
 - Loading underground
 - **Transport along tunnel**
 - Unloading / Transfer onto supports
 - Removal for repair
- Integrate transport and handling design requirements into equipment and infrastructure design as early as possible.



FCC Geographical Data - Option 1a (93km)



Alignment Shaft Tools

Choose alignment option
93km quasi-circular

Tunnel depth at centre: 299mASL

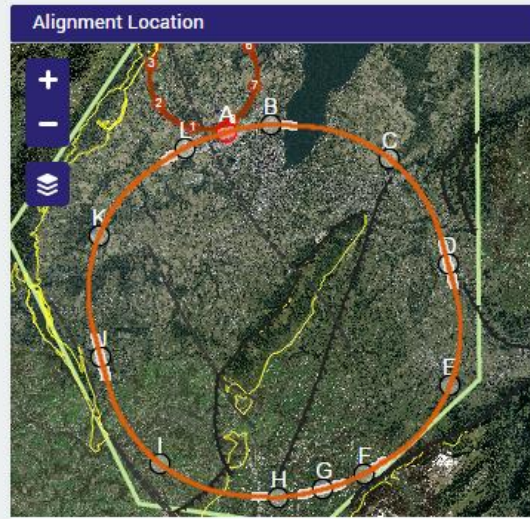
Gradient Parameters

Azimuth (°): -15
Slope Angle x-x(%): .5
Slope Angle y-y(%): 0

CALCULATE

Alignment centre
X: 2499812 Y: 1106889

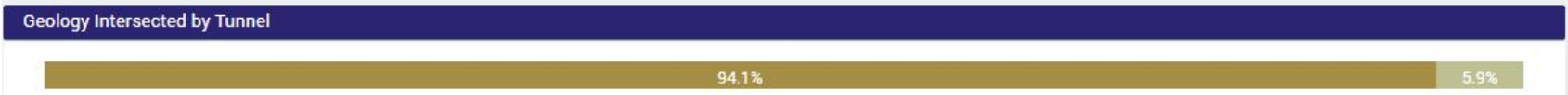
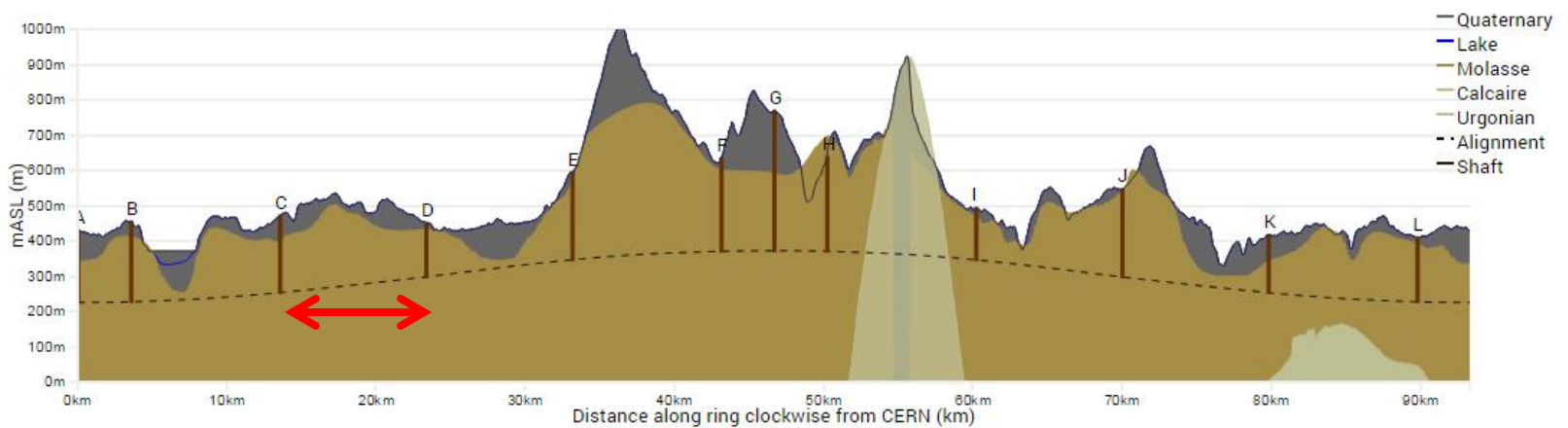
LHC Intersection	CP 1	CP 2
Angle		
Depth	586m	587m



Geology Intersected by Shafts Shaft Depths

Point	Shaft Depth (m)			Geology (m)			
	Actual	Min	Max	Quaternary	Molasse	Urgonian	Calcaire
A	203	204	204	93	111	0	0
B	226	224	224	42	185	0	0
C	218	217	217	75	143	0	0
D	153	154	154	19	134	0	0
E	247	249	249	24	223	0	0
F	262	269	269	32	230	0	0
G	396	393	393	177	220	0	0
H	266	274	274	0	325	0	0
I	146	144	144	26	120	0	0
J	248	251	251	6	242	0	0
K	163	159	159	76	87	0	0
L	182	184	184	17	165	0	0
Total	2711	2657	2867	586	2184	0	0

Alignment Profile



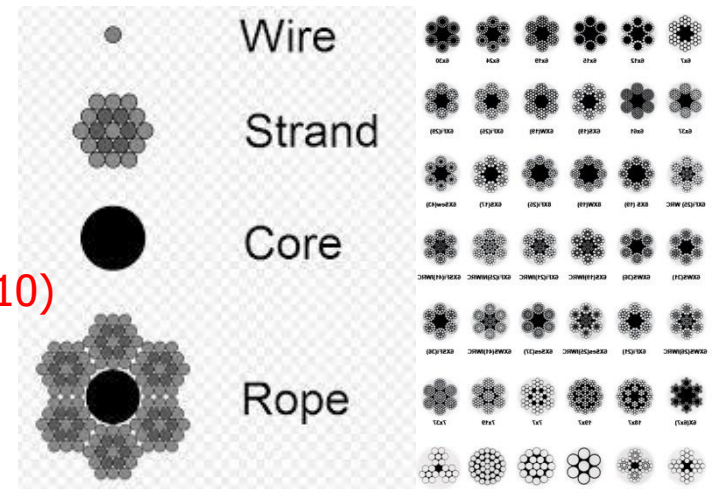
Safety Factor: Ratio strength of rope / working load
 wire rope strength 10,000 pounds / working load 2,000 pounds → safety factor 5

Safety Factor depends not only on the loads applied, but also on:

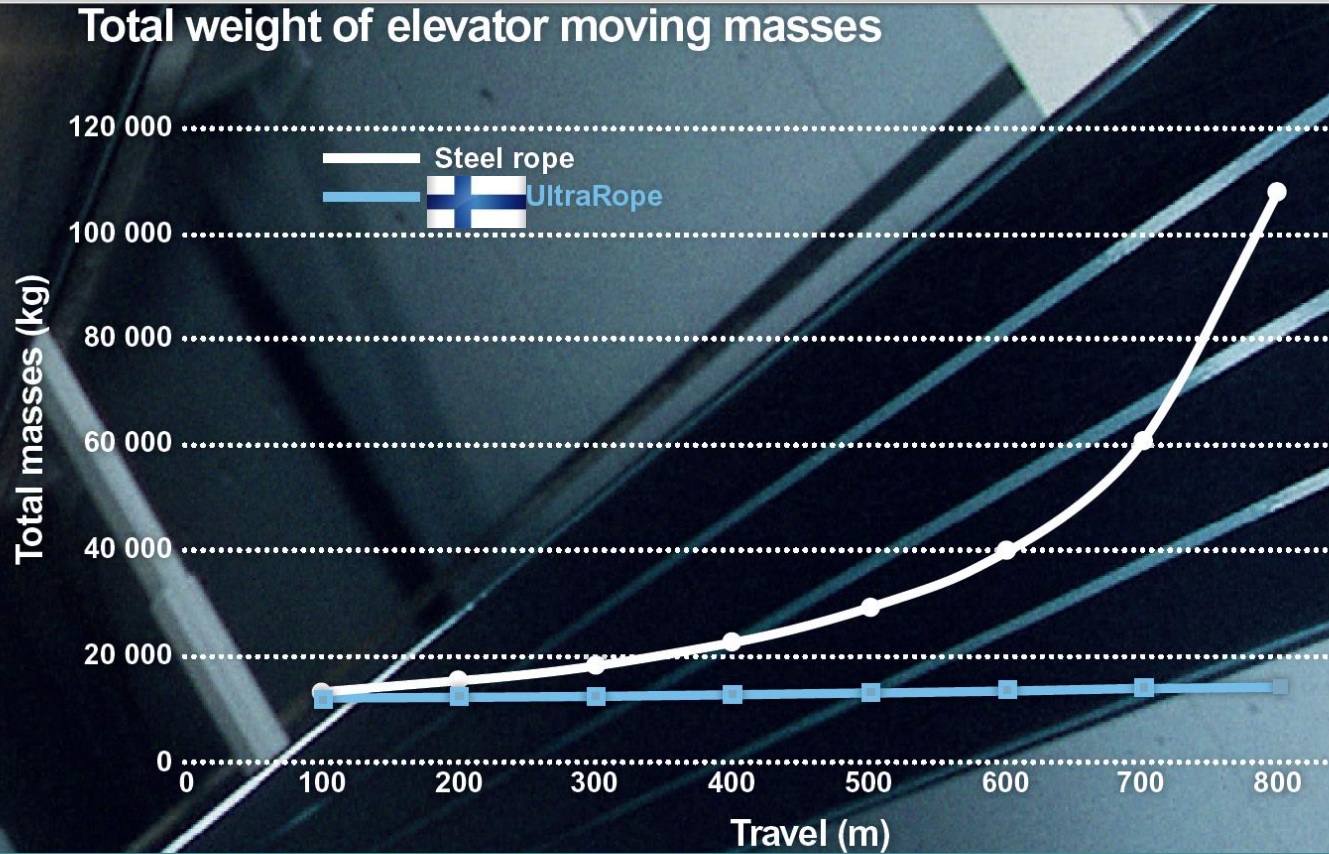
- speed of operation;
- the acceleration and deceleration;
- the length of rope;
- number, size and location of sheaves and drums (bending radius / forces);
- the type of fittings used for securing the rope ends;
- the factors causing abrasion and corrosion...

Safety Factors (only a guide)

- **Miscellaneous Hoisting Equipment** 5 to 6
- **LIFTS** 12 (US + Japan 10)
- **Mine Shafts** 8.0 for depths to 500ft.
 - 7.0 for depths 500-1000ft.
 - 6.0 for depths 1000-2000ft.
 - 5.0 for depths 2000-3000ft.
 - 4.0 for depths 3000ft. and more



<http://www.seile.com/>



Lift travel of ~500m considered as maximum feasible due to SF of 12
Latest development by KONE lifts – carbon fibre ropes (Bending $\sigma > 1m$)
1st time commercialized in 2014; Lift travel of 1000 m and more
Lower mass = Lower wear + Energy savings + Higher speed (16m/s)

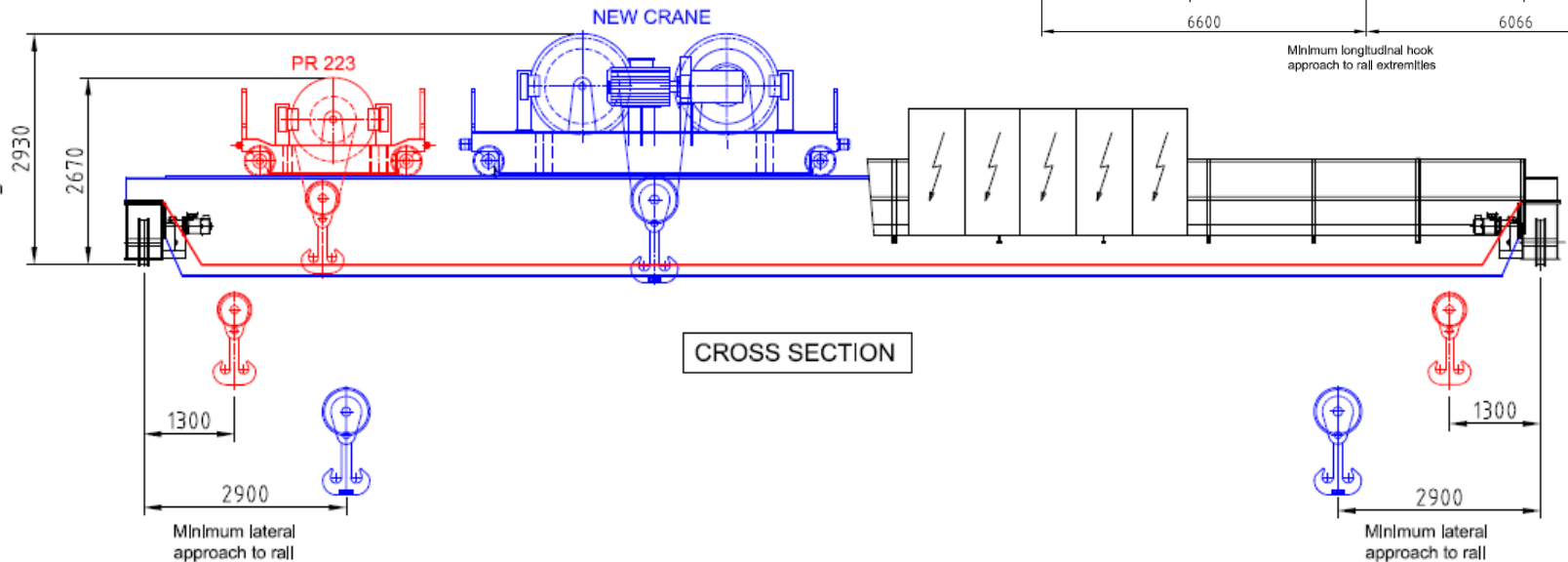
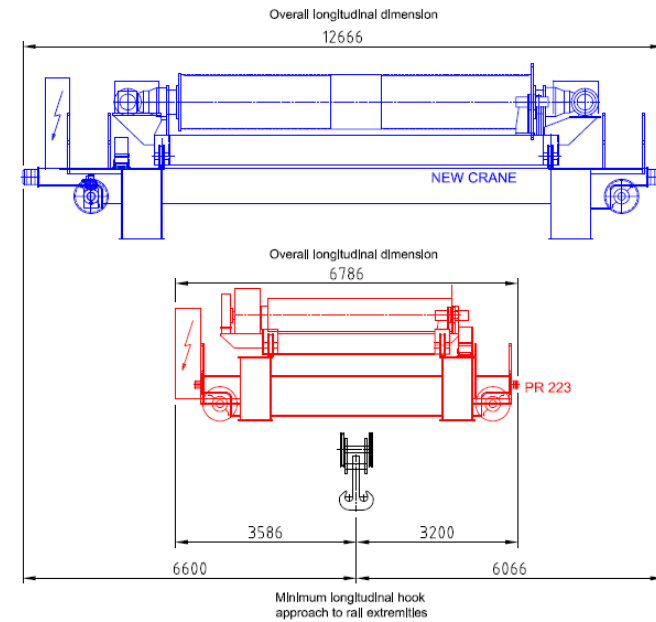
- Lifts with standard steel wire ropes should still do for shaft depths of 400m but
 - Will require fix landing systems for 3t lift due to rope extension/flexibility when loading/unloading lift cabin
 - Lift redundancy a must (i.e. one 3t/35people and one 350kg/4people lift operating next to each other in the same shaft)
 - Higher lift speed (min. 5 m/s for 3t lift and 10 m/s for 350kg lift) requires more pit depth and top clearance
 - n° of people in tunnel depends on evacuation means → lift capacity and speed
 - Will not be possible to simply take over the shaft, pit & machine room dimensions from LHC!
- By the time of the FCC construction carbon fibre cables in lifts could have become a standard ...



- Crane lifting heights of $\sim 3000\text{m}$ currently feasible and in operation - offshore and mining industry
- Lifting heights of 400m is in itself is not a problem but problematic with standard EOT crane layout
 - Twin rope drum system \rightarrow major impact on bldg. height and width
 - Or multiple layers of ropes ... normally not applied on EOT cranes
 - Push and pull system combined with strand jack lifting systems as applied for CMS also remains an option for handling heavy detector components

CRANE	PR 223 (SMI2 CRANE)	New crane
CAPACITY	40 TON	40 TON
SPAN	19,76 m	20 m
LIFTING HEIGHT	52,5 m	300 m
HOIST CONCEPTION	Single rope drum with emergency brake	Two rope drums operating simultaneously (no mechanical connection) ; emergency brake on both drums
DRUM DIAMETER/LENGTH	660 mm / 3800 mm	1070 mm / 7000 mm
LIFTING MOTOR POWER	90 kW	2 x 75 kW
LIFTING SPEED	10 m/mln (100% load) / 20 m/mln (25% load)	10 m/mln (100% load) / 20 m/mln (25% load)
CROSS TRAVEL SPEED	20 m/mln	10 m/mln
LONG TRAVEL SPEED	16 m/mln	20 m/mln
TOTAL WEIGHT	30,500 kg	~ 48,000 kg

LONGITUDINAL SECTION



CROSS SECTION



RL-K 4200

Offshore Cranes Series)
Lifting Cranes (RL)
Type Cranes (MTC)
Lift Offshore
a Cranes
200
500

The RL-K 4200 with knuckle boom and AHC (Active Heave Compensation) can lift up to 100 t at 20 m radius.

Technical Key Facts:

- 42000 kNm - maximum dynamic overturning moment
- Modular boom system
- Continuous outreach from max. 30 m up to max 45 m on customer specification
- Possible to hoist and lower of full capacity
- Optimized boom geometry
- Optimized rope guidance for increase rope life
- Modular hoisting gear system

Additionally the RL-K can be equipped with a NRS for universal offshore working cycles. The Litronic Crane Management System is in charge of the crane movement and data recording.

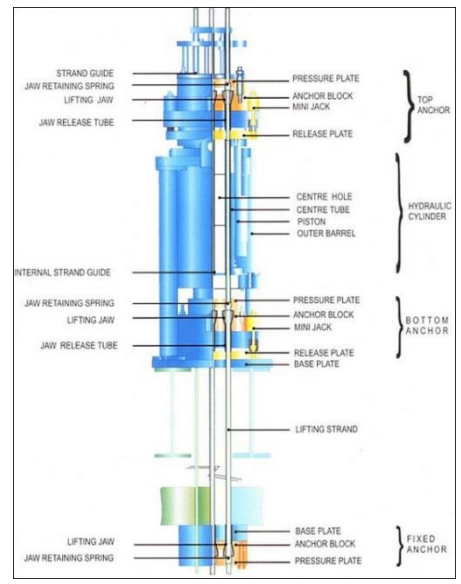
Technical data	Images	Downloads
Lifting capacity		up to 100 t
Radius		30 - 50 m

Technical data Images Downloads

Lifting capacity up to 100 t

Radius 30 - 50 m

Top Print preview



Offshore Cranes Series)
Lifting Cranes (RL)
Type Cranes (MTC)
Lift Offshore
a Cranes
200
500

The RL-K 7500 Heavetronic® with knuckle boom and AHC (Active Heave Compensation) for subsea operations can lift up to 270 t above the surface of the water and handle loads down to a depth of 3,600 m. As a heavy lift crane (without subsea functionality) lifting capacities up to 300 t are possible.

Technical Key Facts:

- 75000 kNm - maximum dynamic overturning moment
- Modular boom system
- Continuous outreach from max. 35 m up to max 55 m on customer specification
- Possible to hoist and lower of full capacity
- Optimized boom geometry
- Optimized rope guidance for increase rope life
- Modular hoisting gear system

Technical data	Images	Downloads
Lifting capacity		up to 300 t
Radius		35 - 55 m

Technical data Images Downloads

Lifting capacity up to 300 t

Radius 35 - 55 m

Top Print preview

Subsea Crane RL-K 7500 Heavetronic®

Encyclopedie de la Manutention (~1980)

- "rampe $\geq 7\%$ = problème délicate"
 - needs for example continuous forced ventilation for brakes and motors
- with increased slope the load capacity or the use factor reduces
- **Effect of 2% slope is to double traction force needed compared with flat surface**



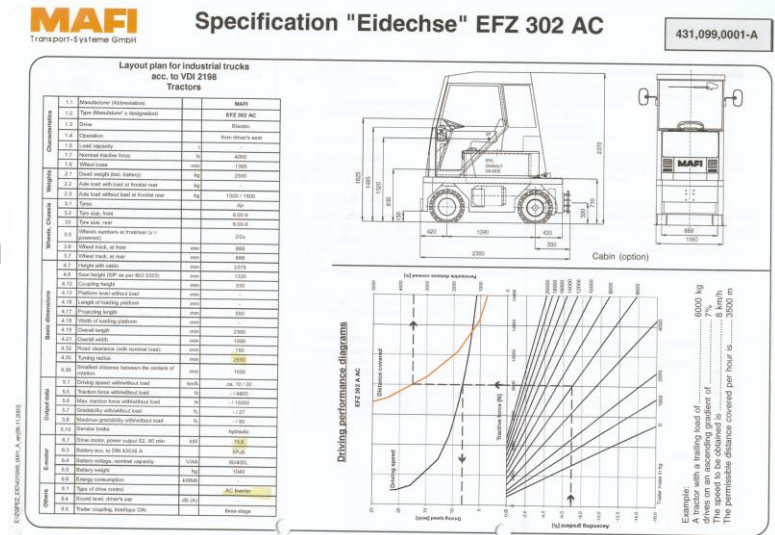
➤ stronger / bigger equipment

Example:

Towing tractor nominal capacity 20t at 10km/h

At a 7% slope

towing capacity 6 t at 3.5 km/h



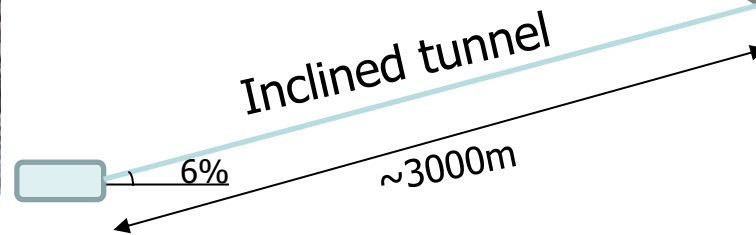


Detector cavern access

Vertical Shaft vs. Inclined tunnel?



- Tunnel \varnothing = Biggest component
- + Transport equipment
- + Safety clearance(s)
- + Tunnel infrastructure (ventilation ducts etc.)



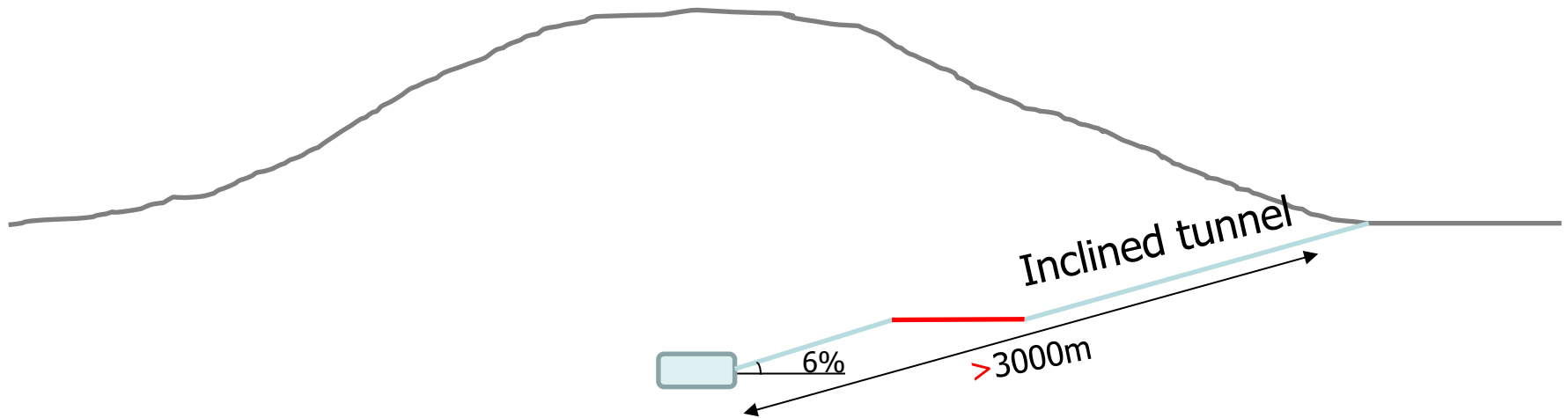


Detector cavern access

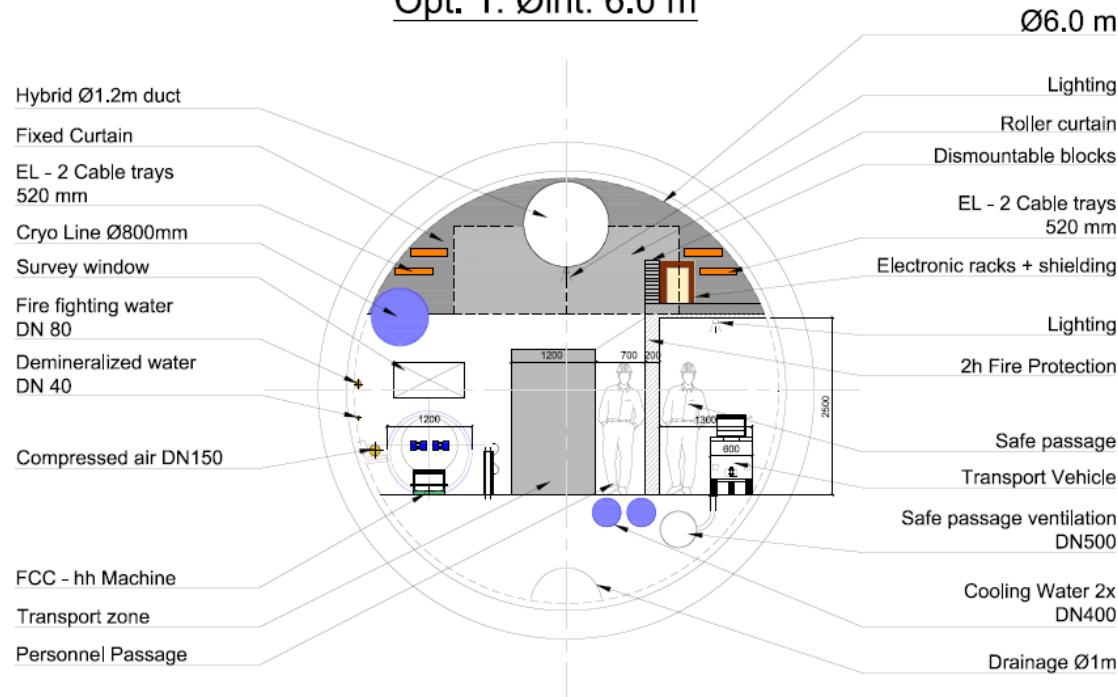
Vertical Shaft vs. Inclined tunnel?



Need of flat 'parking' station(s)
(escape lane(s)!) somewhere
along the inclined tunnel!



Opt. 1: Øint: 6.0 m



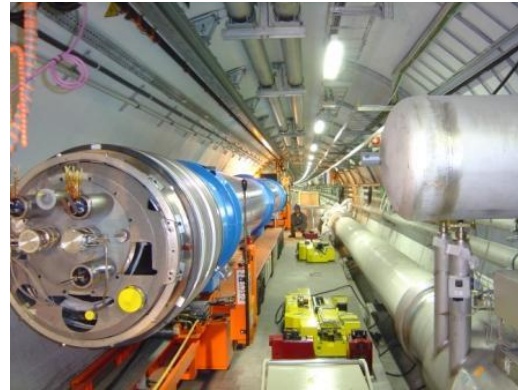
E	20.02.15	A.SANCHEZ		LIGHTNING ADDED, GENERAL UPDATE
D	05.02.15	A.SANCHEZ		ALL PIPE DIMENSIONS CHECKED
C	04.02.15	A.SANCHEZ		OPTION 1B ADDED. GENERAL UPDATE
B	03.02.15	A.SANCHEZ		FIXED CURTAIN, ROLLER CURTAIN AND TRANSPORT VEHICLE ADDED, 400MM WALL FIRE PROT.
A	29.01.15	A.SANCHEZ		FLOOR HEIGHT CHANGED TO HAVE 300mm MORE OF WIDTH
IND.	DATE	NOM/NAME	ZONE	MODIFICATION

"PLAN FOR INFORMATION"	
FCC-HH POSSIBLE TUNNEL CROSS SECTION	
OPT.1: SINGLE TUNNEL LONG, VENTILATION Ø6m	
FCC-HH TUNNEL POSSIBLE CROSS SECTION	
OPT.1: SINGLE LONG, TUNNEL VENTILATION Ø6m	
CERN	NOT VALID FOR EXECUTION NON VALABLE POUR EXECUTION

EHELLE SCALE 1/150	DES/DRA.	A. Sanchez	04/02/2015
	CONTROLLED	R. Fernandez	16/02/2015
	RELEASED	J. A. Osborne	16/02/2015
	APPROVED		
DRAWING UNITY		MM	
FCC-CE-1.0000.0001		SIZE	IND.
		3	D



CERN LHC conventional-magnet installation
 Capacity: 9 t per buggy
 Eq. height: 560 mm



CERN LHC cryo-magnet installation
 Capacity: 35t/20t
 Eq. height: 500mm (TES 300mm)

These **4** solutions incorporate the longitudinal transport and lateral transfer!
 Boundary condition:
Sufficient clearance under the accelerator components!!!

Eq. height: n.a.



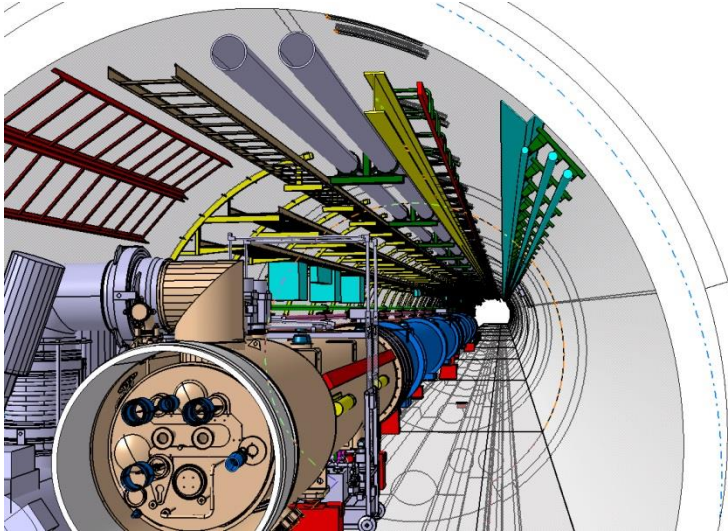
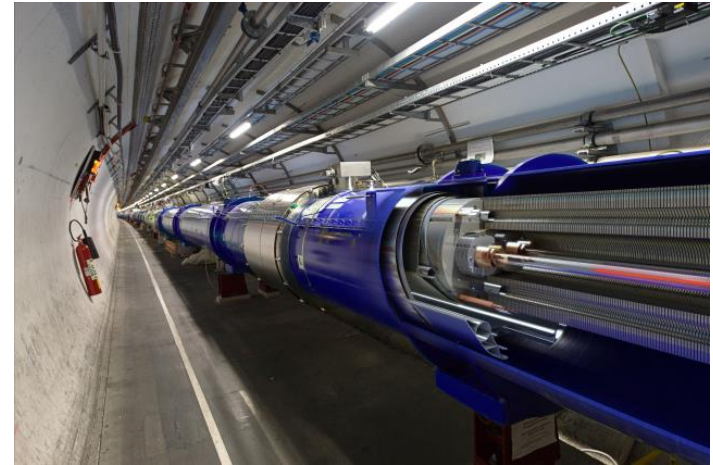
CERN SPS conventional-magnet installation
 Capacity: 20 t
 Eq. height: 800 mm



DESY XFEL installation
 Capacity: 6.t per lifting platform
 Lifting height: 2.4m

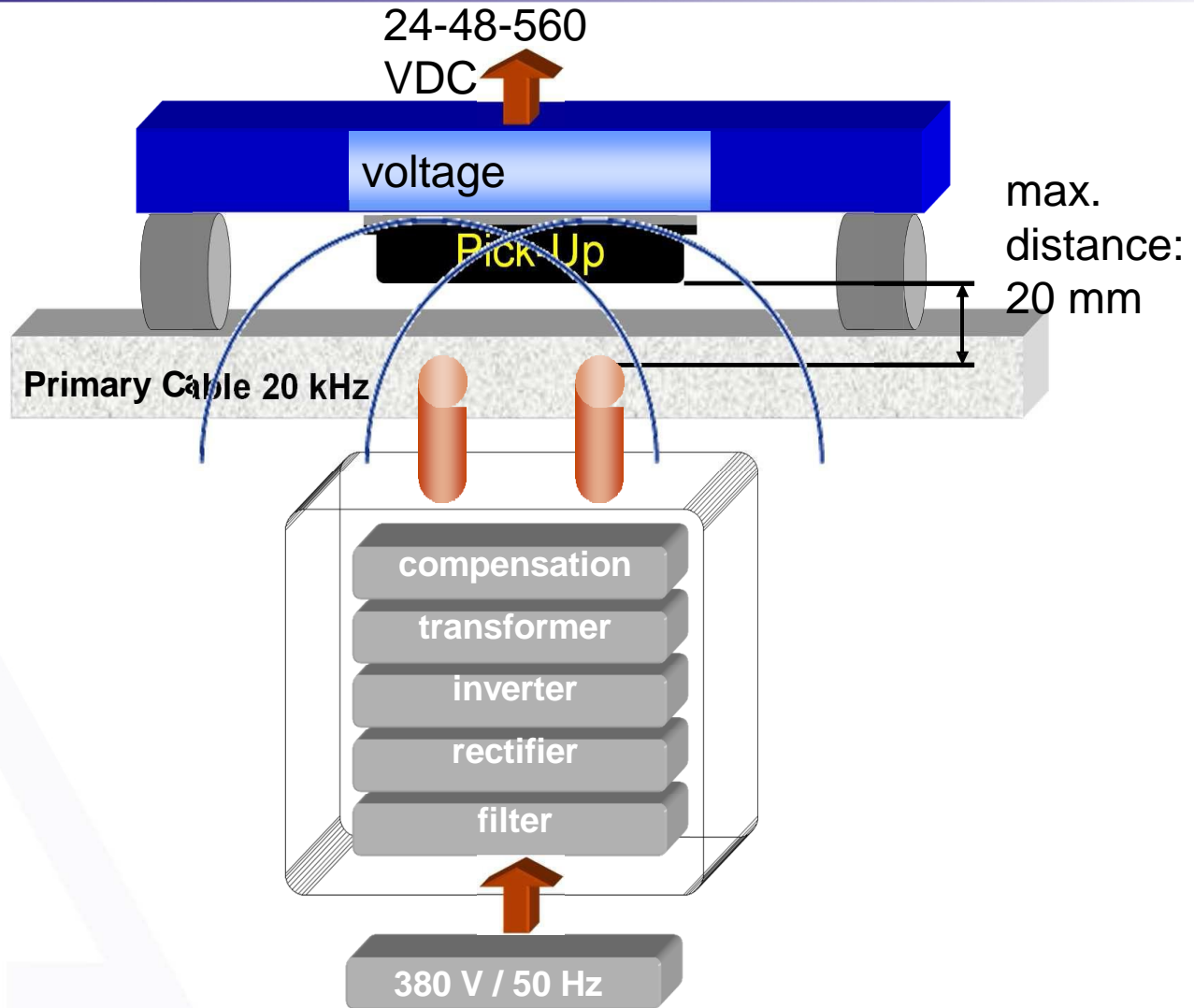


DESY conventional-magnet installation
 Capacity: ???
 Eq. height: ???

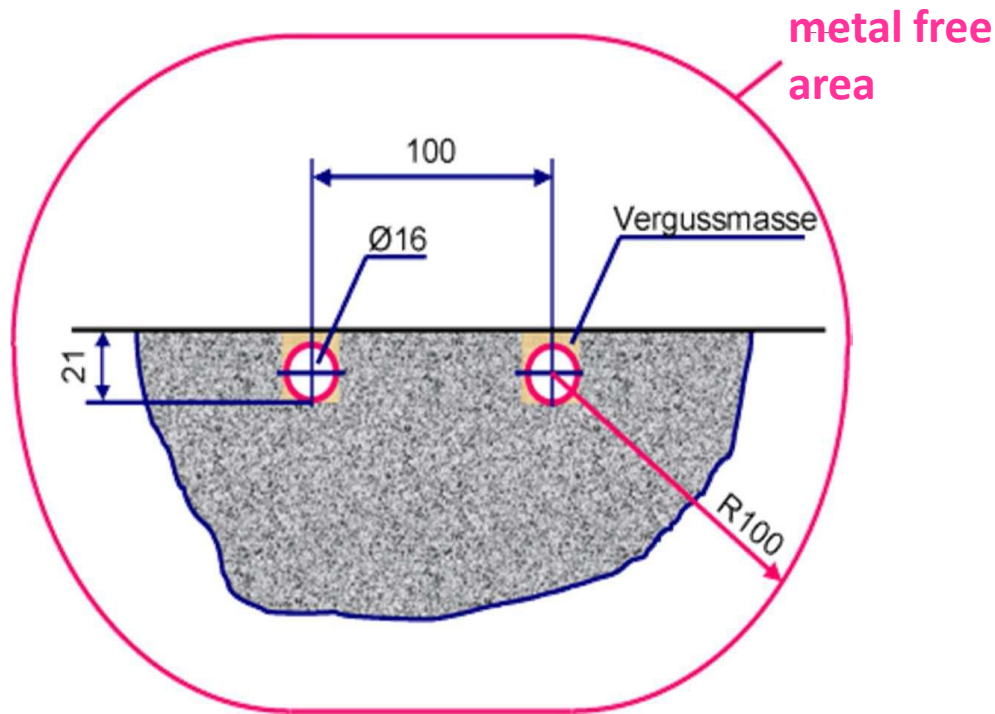


Principle of function

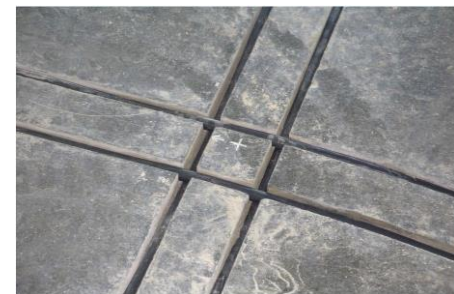
AGV application



Under floor primary cable installation



Min. clearance of 100mm to surrounding steel



Flat-style Pick-Up



PS 08

Output:
24 VDC 500W or
24-27 VDC with battery charging
system



Primary Inverter cabinet

available power: 11, 45, 90 KW

flat version



PS19

compact version



Output:
560-680 VDC 3000W, &
24VDC auxiliary power
supply

UCAP's



Track Guiding Sensor for detecting the electro-magnetic field of
the Primary cable

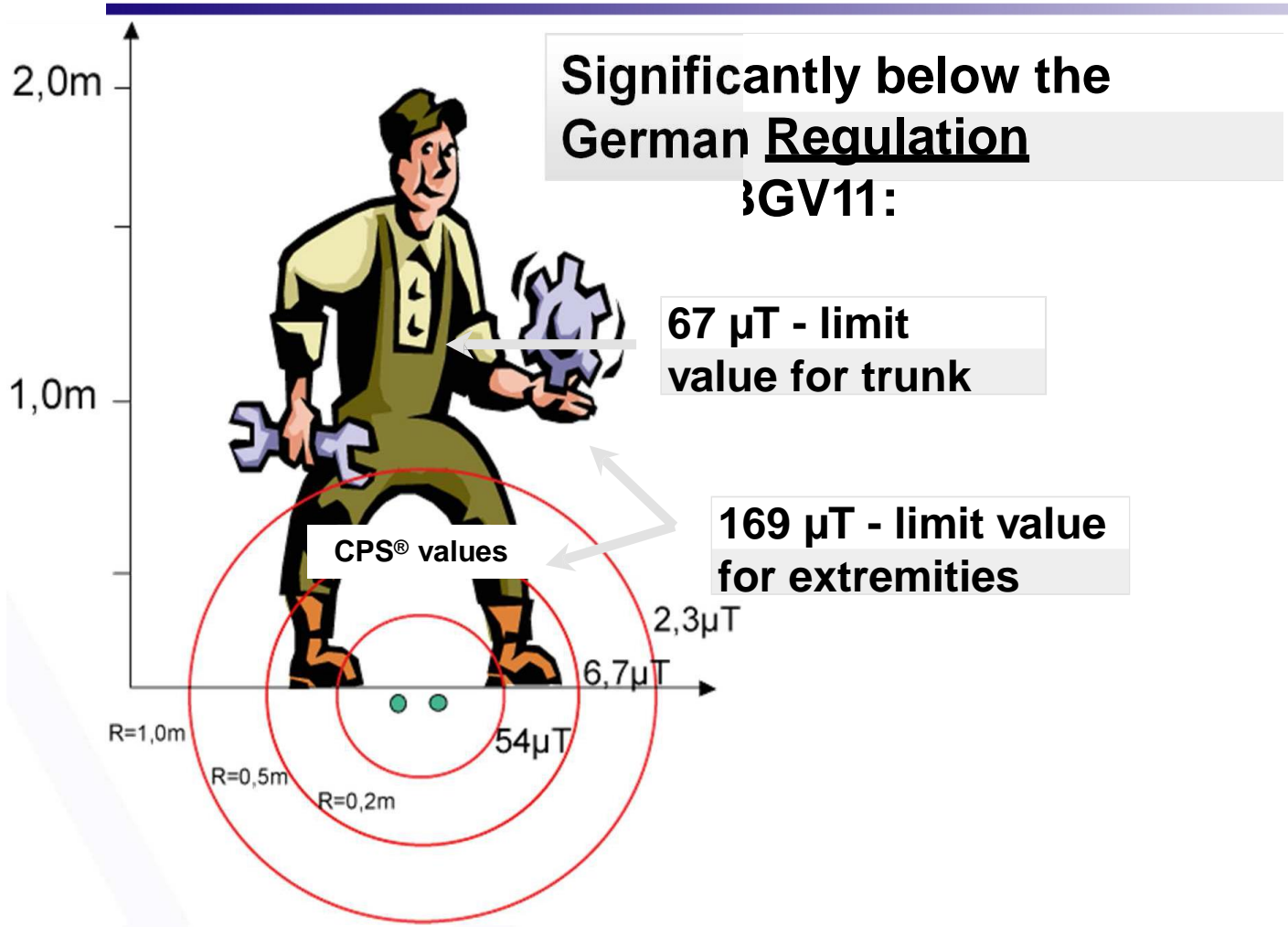
analog output signal,
0-5V, 0-10V and 0-20mA for vehicle steering control

digital output signal Profibus,
RS485

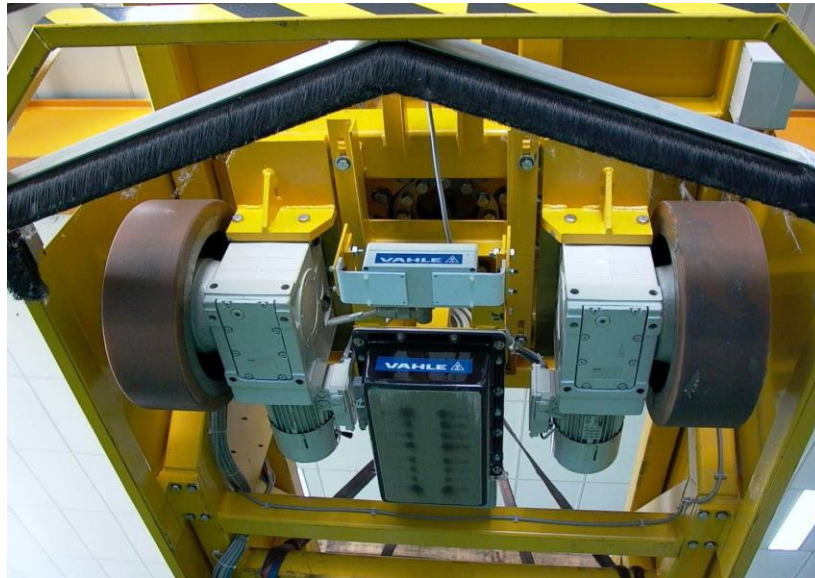
suitable for curves and track
switches



Magnetic flux density (EMF)



CPS®forAGV



	LHC system	AGV system	Remarks
Installation powering & guiding system			
<i>time</i>	-	+++	AGV power supply cabinets at a distance of ~1km - less frequent than for LHC but bigger in size. Component compatibility when machine on?
<i>costs</i>	-	+	
<i>integration</i>	-	++	
Maintenance	-	+++	Practically no mechanical wear
Operation			
<i>safety</i>	+	+(?)	EMF limits to be confirmed
<i>manpower</i>	-	++	Very limited operation manpower required for AGVs
<i>acceleration / speed</i>	o	+	Not really an issue for heavy accel. component transports. Higher speeds possible with AGVs (up to 20 km/h) for smaller/lighter components and passenger transport
Powering			
<i>Conductor</i>	+	-	Direct power supply or via Battery or Hybrid possible for both solutions
<i>Inductive</i>	-	+	
<i>Battery</i>	+	+	
Guidance			
<i>Optical</i>	+	-	Very cumbersome & maintenance intensive
<i>Inductive</i>	-	+	Low maintenance; variable tracks
<i>Manual</i>	+	+	Always necessary for a few manoeuvres
Machine Interference			
<i>installation phase</i>	+	+	Not an issue
<i>Techn. stops / operation phase</i>	+	?	AGV/EMF interference when machine in stand-by?
Remote Monitoring & Control System	-	+++	Small team of operators and maintenance staff can operate several AGV convoys at a time

If not compatible, then
inductive guiding system
 plus
defined charging stations,
 which requires
important battery capacities
 for the AGVs.

- Lifts for shaft depth of up to 400m should be feasible with standard solutions but will require some additional technical features
- Cranes for shaft depths of up to 400m still feasible with standard EOT cranes but will require more studies regarding existing industrial equipment / applications
- For both cases the standard LHC layout for buildings and shafts cannot be applied!
- Keep tunnel slope as low as possible ($<2\%$)
- Allow for sufficient clearance under accelerator components to allow transport and handling vehicles with incorporated lateral transfer systems
- **Compatibility between an inductive guiding and powering system and accelerator components when in stand-by mode to be further assessed**



There are plenty of technical challenges regarding transport and handling aspects for the FCC that need some in-depth studies but no show stoppers so far (based on the present tunnel and shaft configurations)!!!

Thanks

- **KONE Corporation Finland**

KONE Oyj
Keilasatama 3
P.O. Box 7
Espoo, FIN-02150

Titre : [Encyclopédie de la manutention](#) / Syndicat des industries de matériels de manutention

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D-89584 Ehingen/Donau

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- **Paul Vahle GmbH & Co. KG**

Westicker Str. 52
D-59174 Kamen