

# ***Lecture 6***

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## **ACCELERATOR PHYSICS**

**MT 2014**

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## **Lecture 6 - Longitudinal dynamics II**

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# ***Recap of previous lecture***

## ***- Longitudinal dynamics I***

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- ◆ **RF Cavity Cells**
- ◆ **Phase stability**
- ◆ **Bucket and pendulum**
- ◆ **Closed orbit of an ideal machine**
- ◆ **Analogy with gravity**
- ◆ **Dispersion**
- ◆ **Dispersion in the SPS**
- ◆ **Dispersed beam cross sections**
- ◆ **Dispersion in a bend (approx)**
- ◆ **Dispersion – from the “sine and cosine” trajectories**
- ◆ **From “three by three” matrices..**

**Transition - does an accelerated particle catch up - it has further to go**

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$$f = \frac{\beta c}{2 \pi R}, \quad (\beta = v / c)$$

**Is a function of two, momentum dependent, terms  $\beta$  and  $R$ .**

$$p = \frac{E_0 \beta}{\sqrt{1 - \beta^2}} \quad \text{and} \quad R \approx R(\Delta p / p = 0) + D \frac{\Delta p}{p}$$

**Using partial differentials to define a slip factor:**

$$\frac{df}{dp} = \frac{\partial f}{\partial \beta} \frac{d\beta}{dp} + \frac{\partial f}{\partial R} \frac{dR}{dp}$$

$$\eta_{rf} = \frac{\Delta f / f}{\Delta p / p} = \frac{p}{\beta} \frac{d\beta}{dp} - \frac{p}{R} \frac{dR}{dp} = \frac{1}{\gamma^2} - \frac{\bar{D}}{R_0}$$

**This changes from negative to positive and is zero at 'transition' when:**

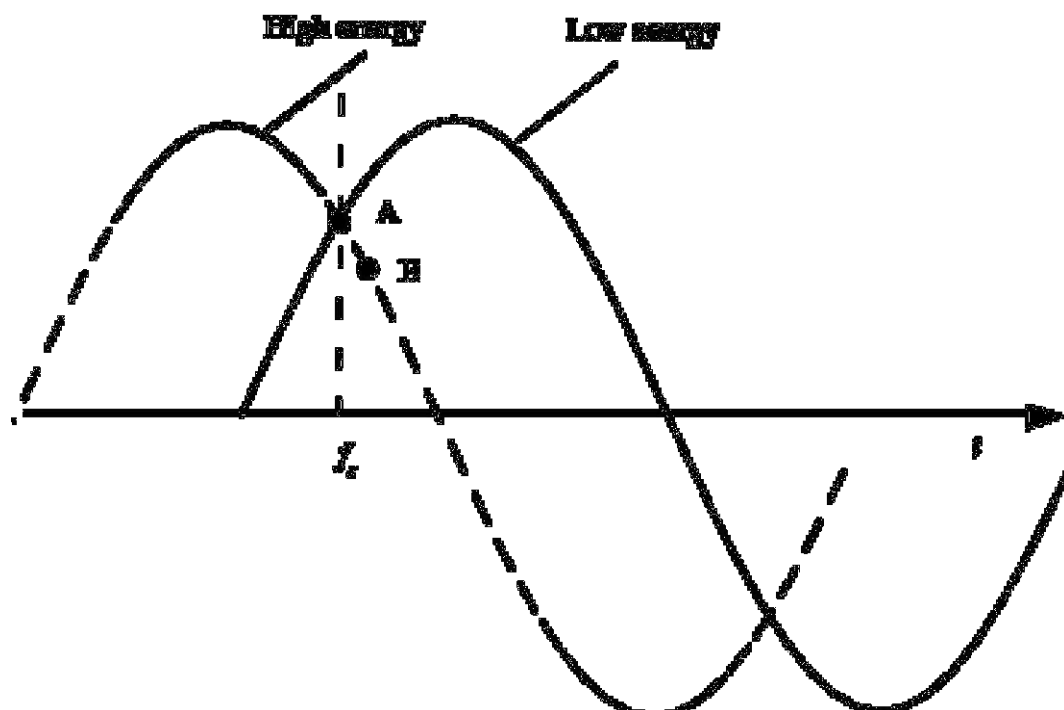
**GAMMA TRANSITION**

$$\frac{1}{\gamma_{tr}^2} = \frac{\bar{D}}{R}.$$

# Phase jump at transition

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**BECAUSE ....**  $\eta_{rf} == \frac{1}{\gamma^2} - \frac{1}{\gamma_{tr}^2}$



# Synchrotron motion

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✂ Recall  $p = m_0 c (\beta \gamma)$  .

✂ Elliptical trajectory for small amplitude

$$\Delta(\beta \gamma) = \Delta(\beta \gamma) \cos 2\pi f_s t$$

$$\phi = \hat{\phi} \sin 2\pi f_s t$$

✂ Note that frequency is rate of change of phase

✂ From definition of the slip factor  $\eta$

$$\dot{\phi} = 2\pi h [f(\beta \gamma) - f(0)] = 2\pi h \Delta f$$

✂ Substitute and differentiate again

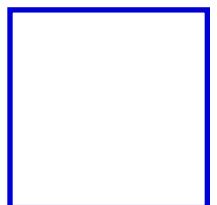
$$\Delta f = \eta f \frac{\Delta p}{p} = \eta f \frac{\Delta(\beta \gamma)}{(\beta \gamma)} = \frac{\eta f}{\beta^2} \frac{\Delta \gamma}{\gamma} = \frac{\eta f}{E_0 \beta^2 \gamma} \Delta E$$

$$\ddot{\phi} = -\frac{2\pi h \eta f^2}{E_0 \beta^2 \gamma} (\Delta E)$$

✂ But the extra acceleration is

✂ **THUS**  $\Delta E = V_0 (\sin \phi - \sin \phi_s)$

$$\ddot{\phi} = -\frac{2\pi V_0 h \eta f^2}{E_0 \beta^2 \gamma} (\sin \phi - \sin \phi_s)$$



# Synchrotron motion (continued)

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✂ This is a biased rigid pendulum

$$\ddot{\phi} = -\frac{2\pi V_0 h \eta f^2}{E_0 \beta^2 \gamma} (\sin \phi - \sin \phi_s)$$

✂ For small amplitudes

$$\ddot{\phi} + \frac{2\pi V_0 h \eta f^2}{E_0 \beta^2 \gamma} \phi = 0$$

✂ Synchrotron frequency

$$f_s = \sqrt{\frac{|\eta| h V_0 \cos \phi_s}{2\pi E_0 \beta^2 \gamma}} f .$$

✂ Synchrotron “tune”

$$Q_s = \frac{f_s}{f} = \sqrt{\frac{|\eta| h V_0 \cos \phi_s}{2\pi E_0 \beta^2 \gamma}} .$$

# Large amplitudes

$$\ddot{\phi} = -\frac{2\pi V_0 h \eta f^2}{E_0 \beta^2 \gamma} (\sin \phi - \sin \phi_s)$$

◆ and

◆ become

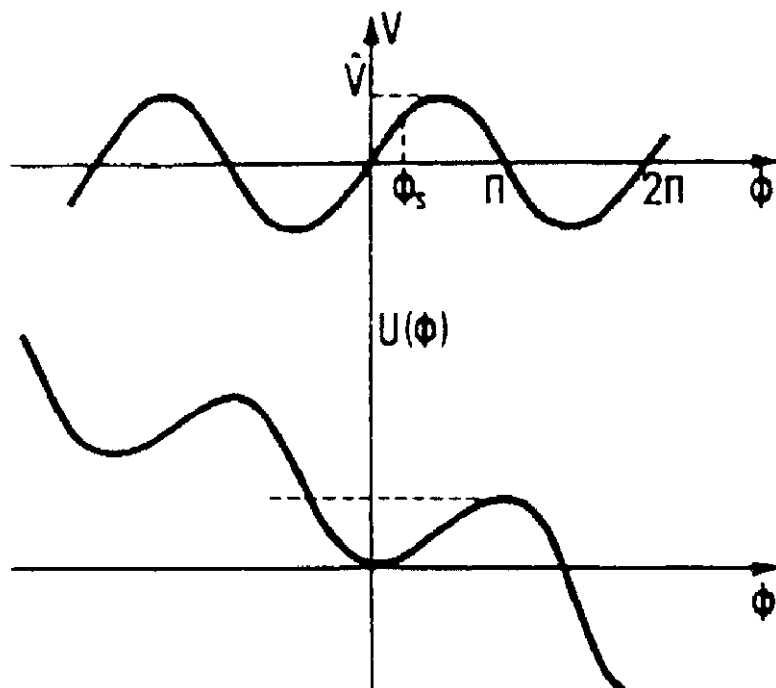
$$\Omega_s = \sqrt{\frac{|\eta| h V_0 \cos \phi_s}{2\pi E_0 \beta^2 \gamma}} \omega_{rev}.$$

$$\ddot{\phi} = -\frac{\Omega_s^2}{\cos \phi_s} (\sin \phi - \sin \phi_s)$$

◆ Integrated becomes an invariant

$$\frac{\dot{\phi}^2}{2} - \frac{\Omega_s^2}{\cos \phi_s} (\cos \phi + \phi \sin \phi_s) = \text{const.}$$

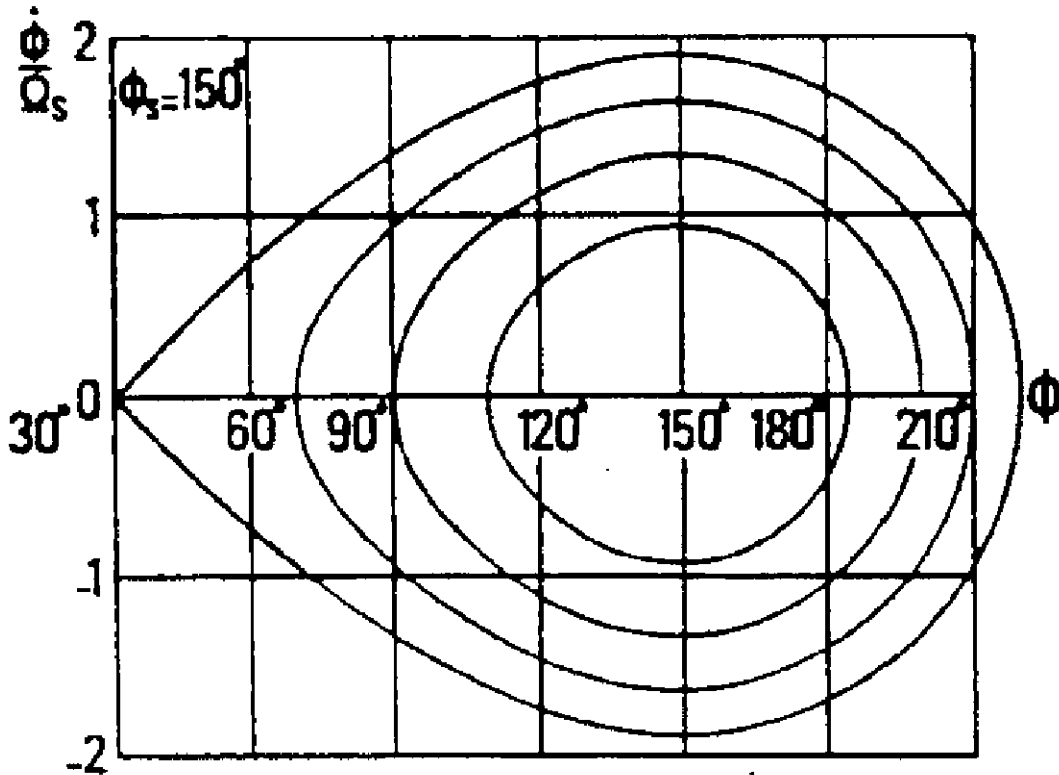
◆ The second term is the potential energy function





# Buckets

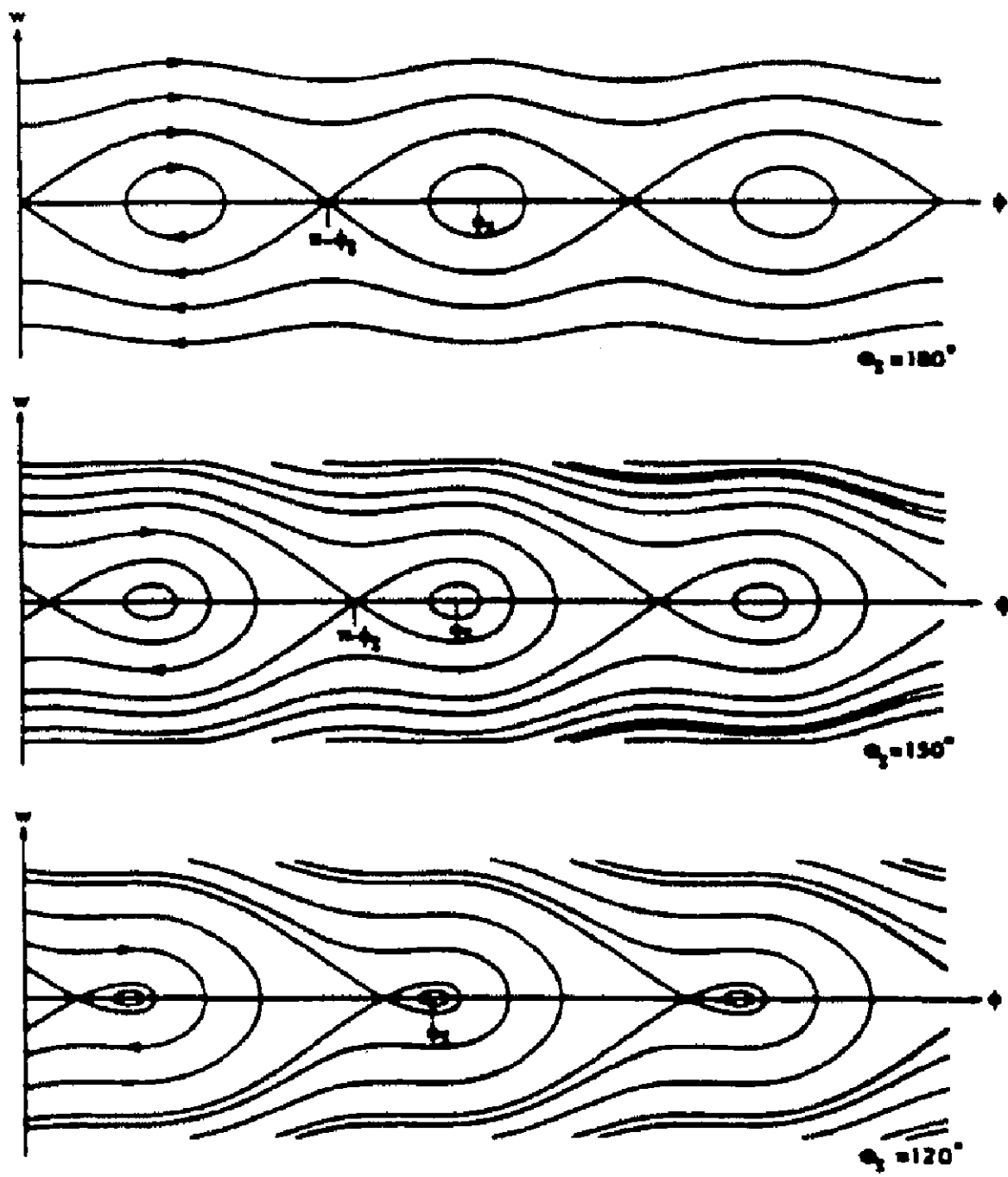
- ◆ Seen from above this is a bucket (in phase space) for different values of  $\phi_s$



- ◆ The equation of each separatrix is

$$\frac{\dot{\phi}^2}{2} - \frac{\Omega_s^2}{\cos \phi_s} (\cos \phi + \phi \sin \phi_s) = -\frac{\Omega_s^2}{\cos \phi_s} [\cos(\pi - \phi_s) + (\pi - \phi_s) \sin \phi_s]$$

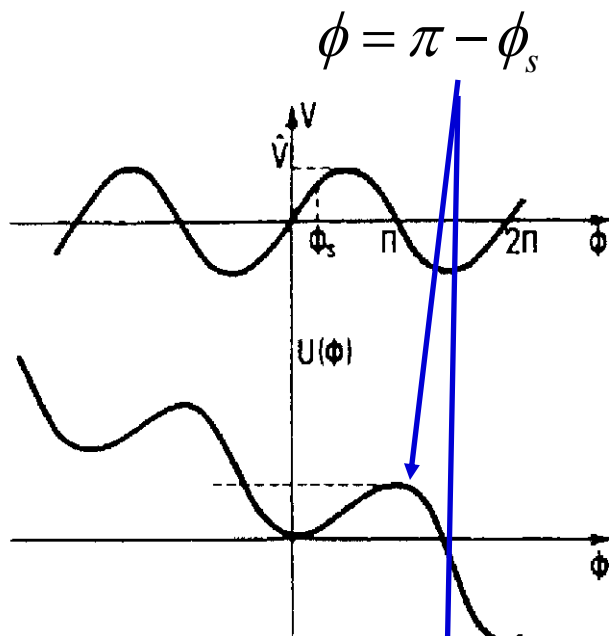
# A chain of buckets



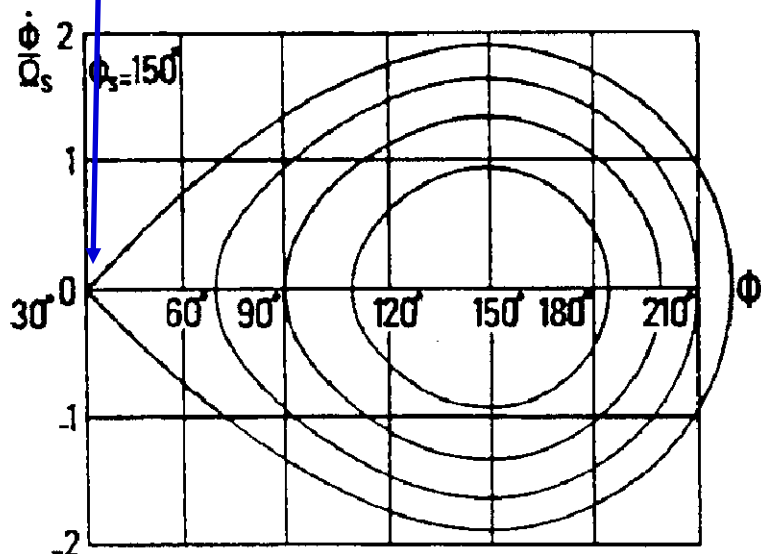
# Bucket length I

$$\ddot{\phi} = -\frac{2\pi V_0 h \eta f^2}{E_0 \beta^2 \gamma} (\sin \phi - \sin \phi_s)$$

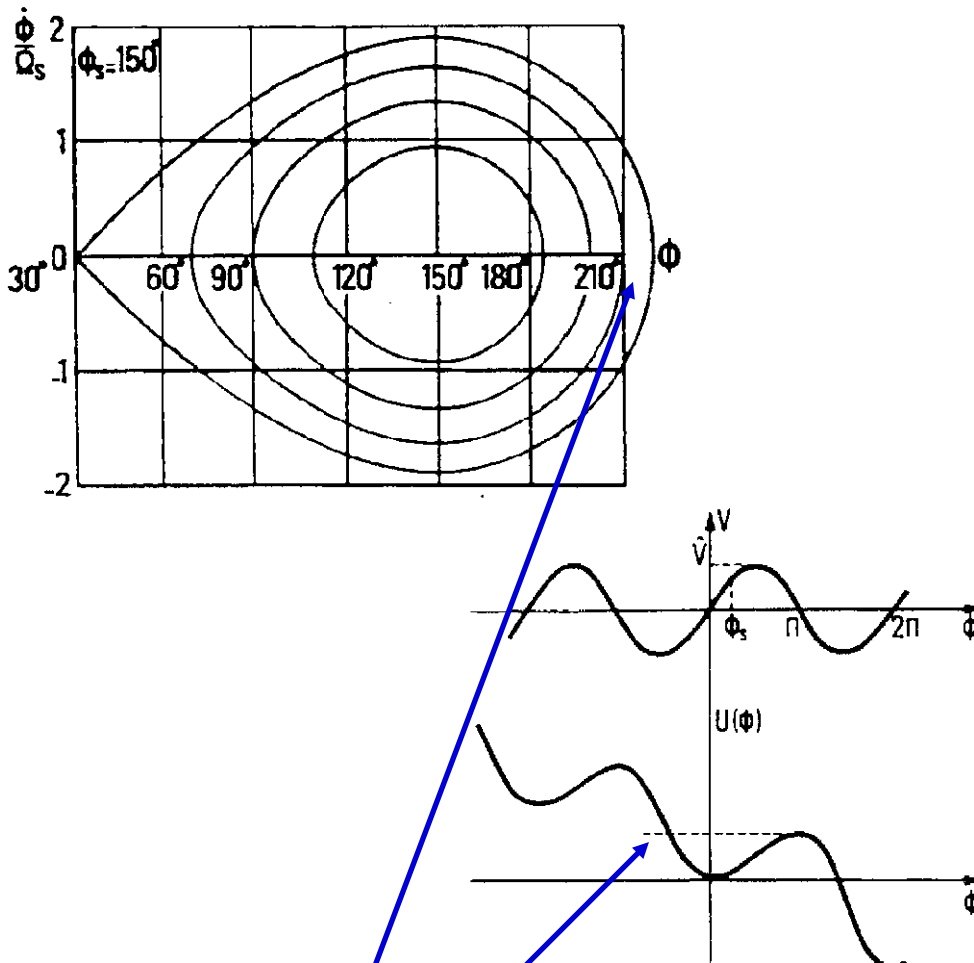
The right hand side is negative beyond:



This diagram is flipped left to right



# Bucket length II

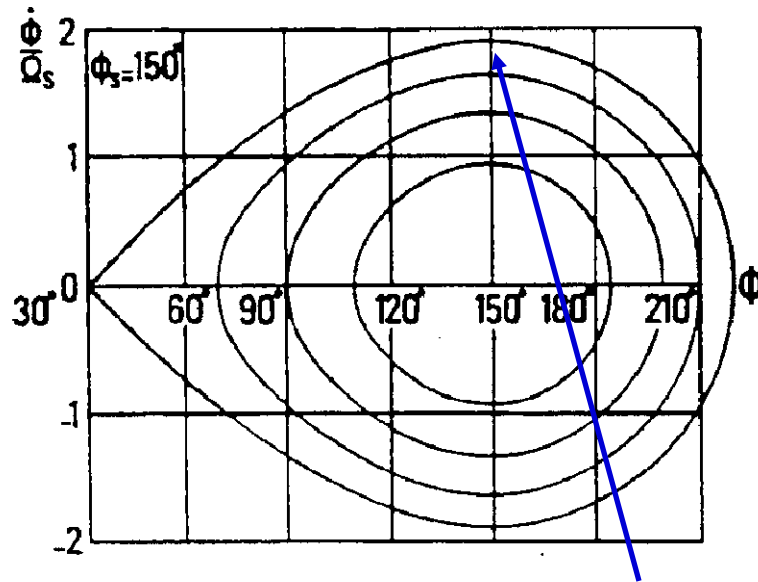


◆ And the other limit in phase when at

$$\phi = \phi_m \text{ where}$$

$$\cos \phi_m + \phi_m \sin \phi_s = \cos(\pi - \phi_s) + (\pi - \phi_s) \sin \phi_s$$

# Bucket height



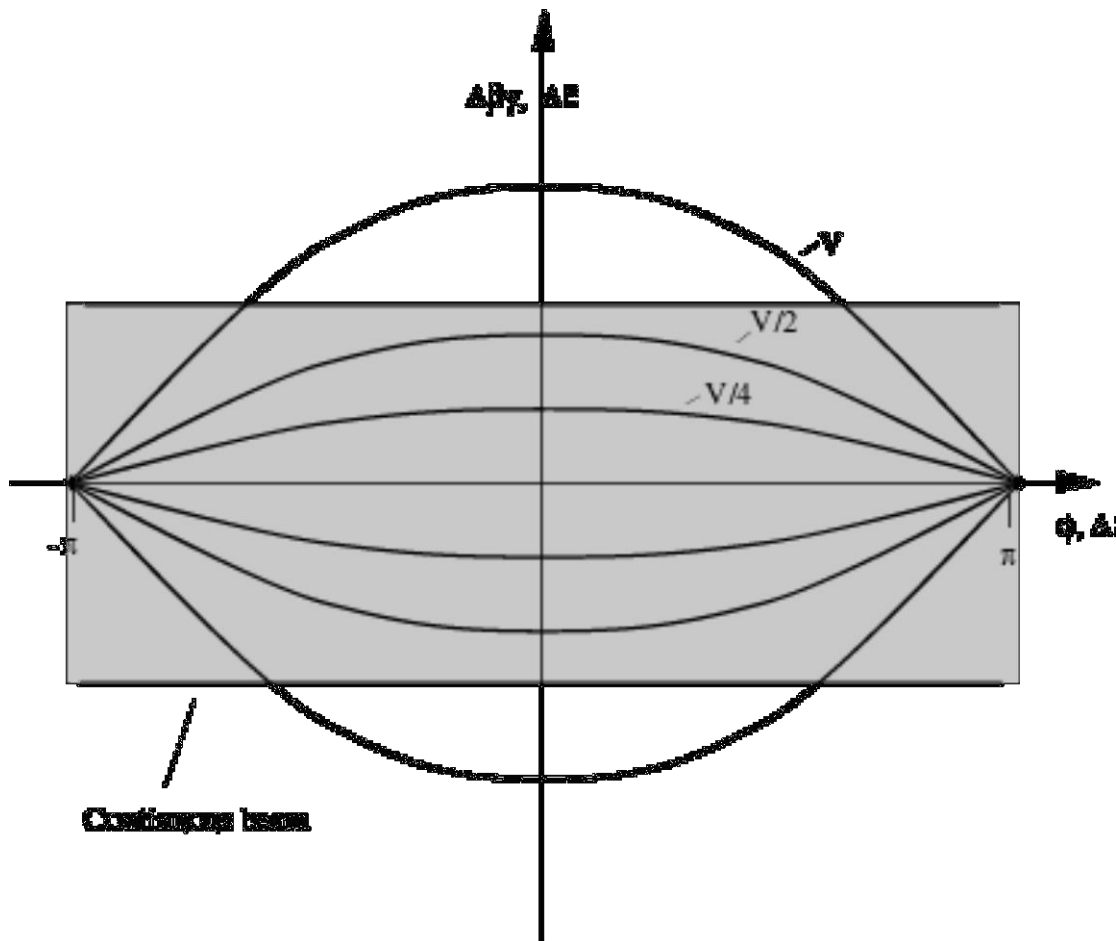
◆ And the half height when  $\ddot{\phi} = 0$  at

$$\left(\frac{\Delta E}{E_s}\right)_{\max} = \pm \beta \left\{ \frac{eV_0}{\pi \hbar \eta E_s} G(\phi_s) \right\}^{1/2}$$

$$G(\phi_s) = [2 \cos \phi_s - (\pi - 2\phi_s) \sin \phi_s]$$

$G$  varies from  $\pm 2$  to 0 as  $\sin \phi_s$  varies from 0 to 1

# Adiabatic capture



◆ Area of a stationary bucket is :

$$A_0 = 16\beta \sqrt{\frac{E_s e V_0}{\pi |\eta| h}} \quad \text{in units } [\Delta E \cdot \Delta\phi]$$

## ***Longitudinal Dynamics II – Summary***

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