

ACOUSTIC HOLOGRAPHIC VISION



Henrik D. Kjeldsen

henrik.daniel.kjeldsen@cern.ch

CERN openlab workshop
11th of November, 2014

Human Echolocation

and its technological reproduction

Reality:



smithsonianmag.com



entretags.de



CERN fire training (Anna Pantelia)



aisencaro.com

Vision:

“the visually impaired”



What to aim for?



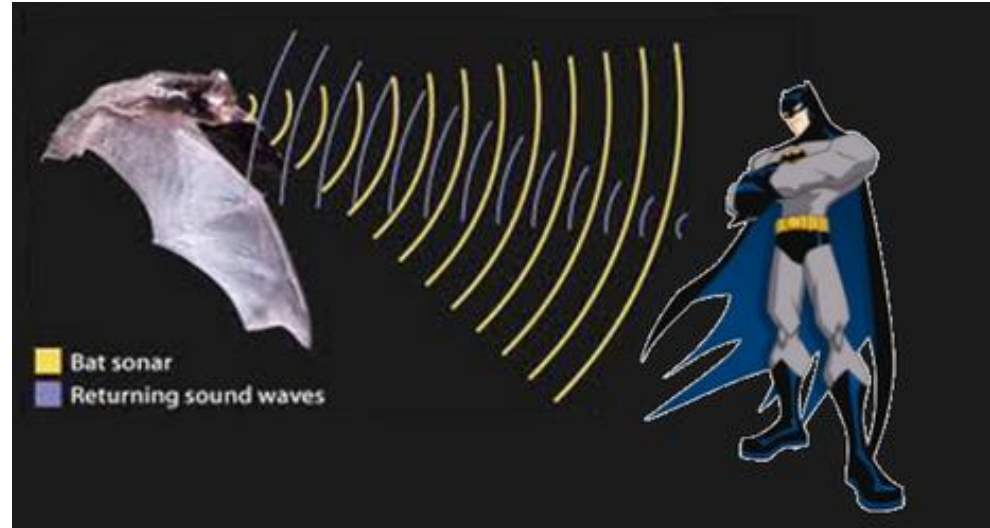
Animal Echolocation

Ultrasound is better:

Distance

Speed (acquisition)

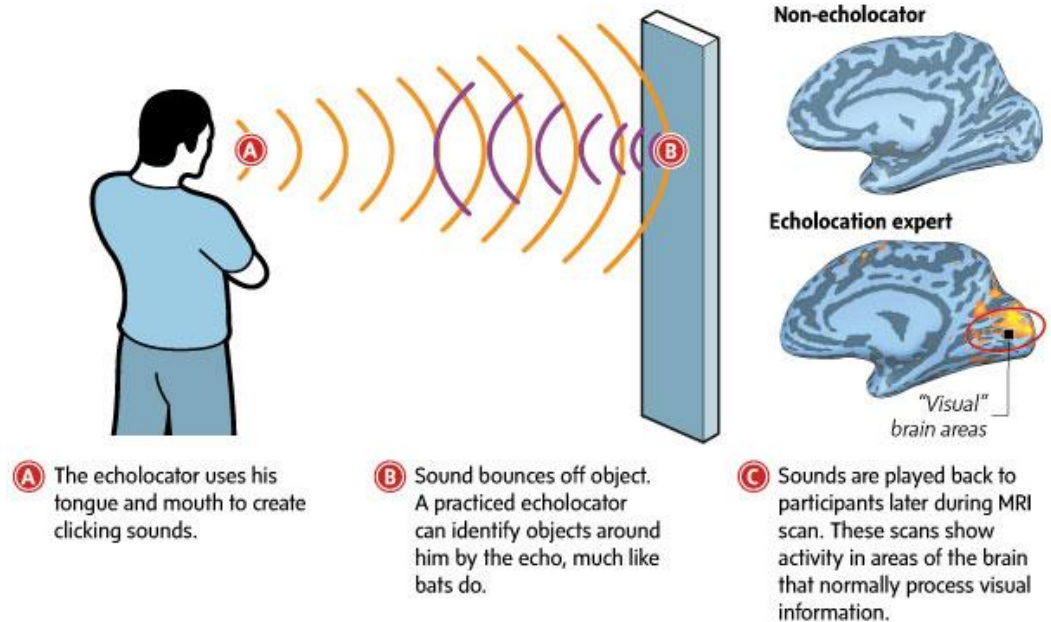
Directional



adurkin.weebly.com

Neuroscience:

Visual areas involved
imply advanced scene
reconstruction, but
no accepted neural
theory



Acoustic Holography

Issues:

1. Resolution
2. Processing power

Proposed solutions:

1. Compressive sensing via sparsity
2. Real-time cloud services

New mobile devices with
cloud services
How mobile?



Real-time Near-field Acoustic Holography



Figure 9. Measurement area with indication of array microphone positions (dots).

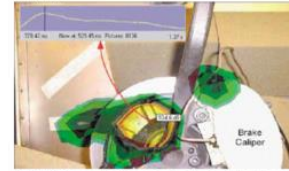


Figure 12. Contour plot of envelope active intensity. A time slice representing the position of the contour cursor is included. The contour interval is 1 dB.

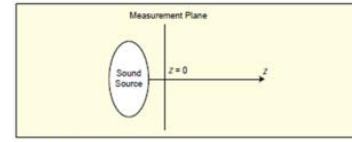


Figure 4. Measurement geometry.

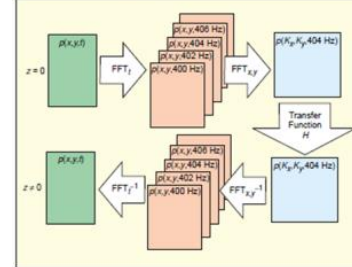
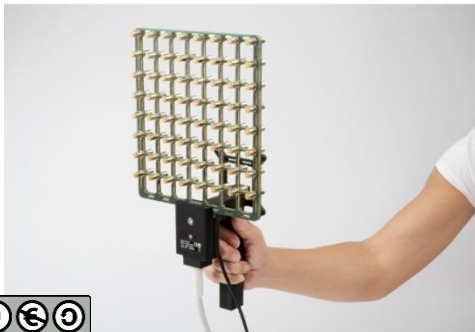
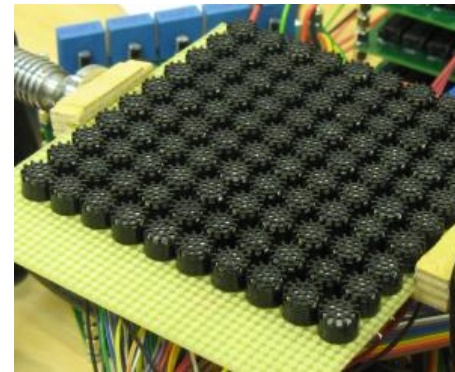


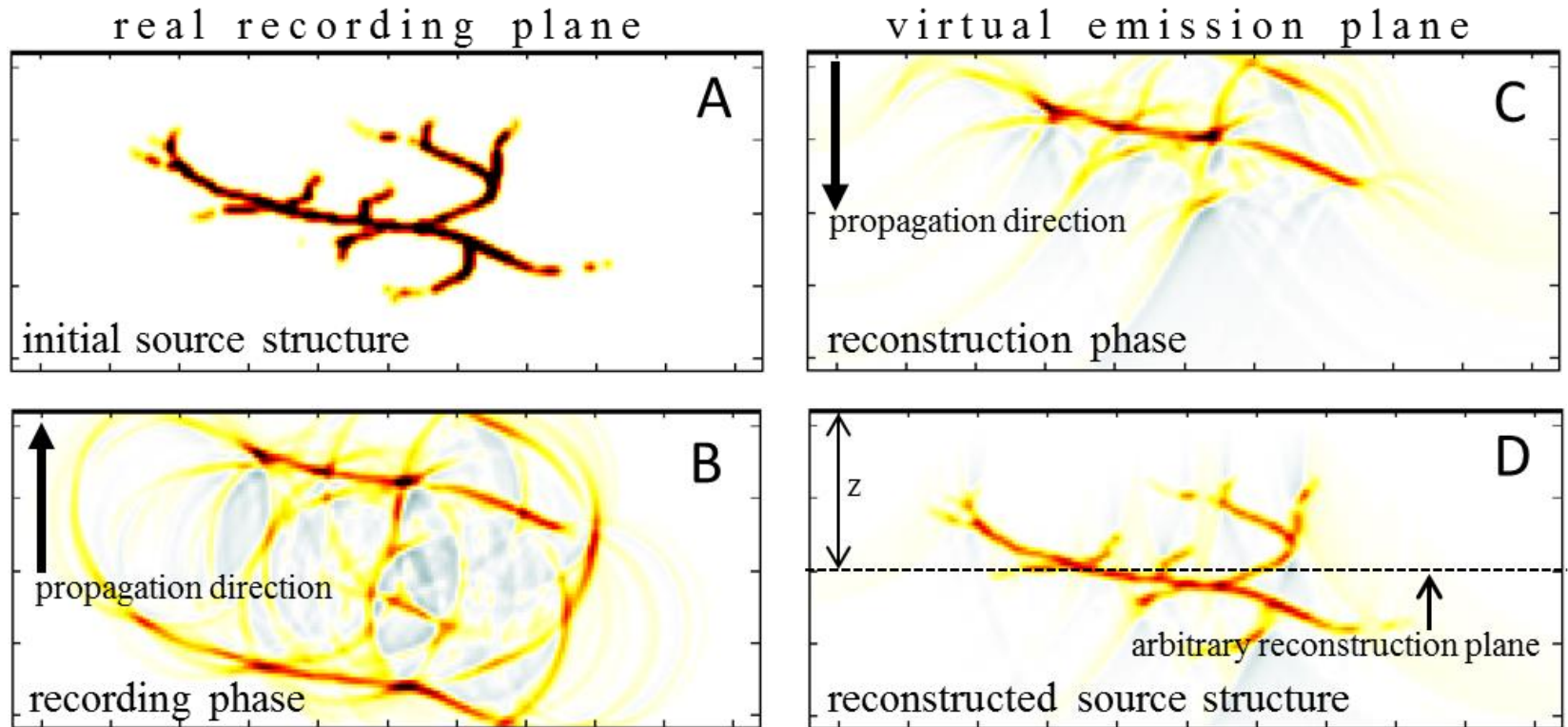
Figure 5. Data flow chart for time domain holography.

Jørgen Hald, Brüel & Kjær Sound & Vibration Measurement A/S, Nærum, Denmark
SOUND AND VIBRATION/FEBRUARY 2001



Acoustic Holography

Simulation example (one dimension suppressed):



K-WAVE Matlab Toolbox

Acoustic Holography with Compressive Sensing

Based on:



Nearfield Acoustic Holography using sparsity and compressive sampling principles

Gilles Chardon and Laurent Daudet
Institut Langevin, ESPCI ParisTech - Univ Paris Diderot - UPMC Univ Paris 06 - CNRS UMR 7587,
10 rue Vauquelin F-75005 Paris France

Antoine Peillot and François Ollivier
UPMC Univ Paris 06, UMR 7190 - Institut Jean Le Rond d'Alembert, F-75005 Paris France.

Nancy Bertin
CNRS - IRISA-UMR 6074, Campus de Beaulieu, F-35042 Rennes Cedex France

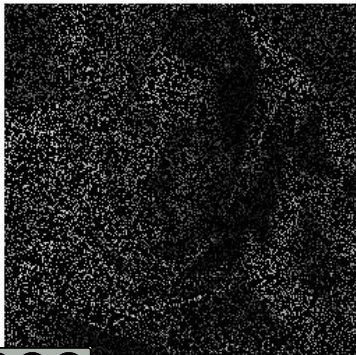
Rémi Gribonval
INRIA, Centre Inria Rennes - Bretagne Atlantique, Campus de Beaulieu, F-35042 Rennes Cedex France

24 Jul 2012

What is compressive sensing?
Sparsity is required (compressible)
Random sampling is key

Example:

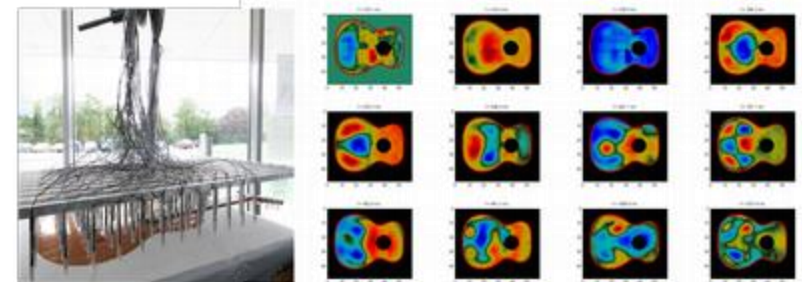
Corrupted image, 6.4106dB



Original image



Restored image, 26.7876dB



Can we
implement it?

Near-field Electromagnetic Holography

**MEA ELECTROMAGNETIC INCOHERENT
NEAR-FIELD HOLOGRAPHY**
for
super-resolution
spike localization and sorting in 3D
energy flow and dissipation
current source density, energy source density

Henrik D. Kjeldsen
henrik.kjeldsen@ncl.ac.uk

Venue
September, 2013



**Proven implementation of
a generalization of acoustic
holography**

**Most recent work
in experimental
neuroscience**

Background

Translation of known technique:

Near-field Acoustic Holography (NAH)



Real-time Near-field Acoustic Holography

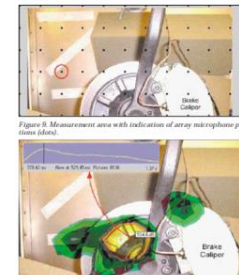


Figure 12. Contour plot of envelope active intensity. A time slice representing the position of the contour curve is included. The contour interval is 1 dB.

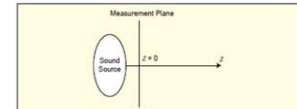


Figure 4. Measurement geometry.

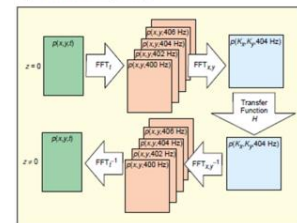
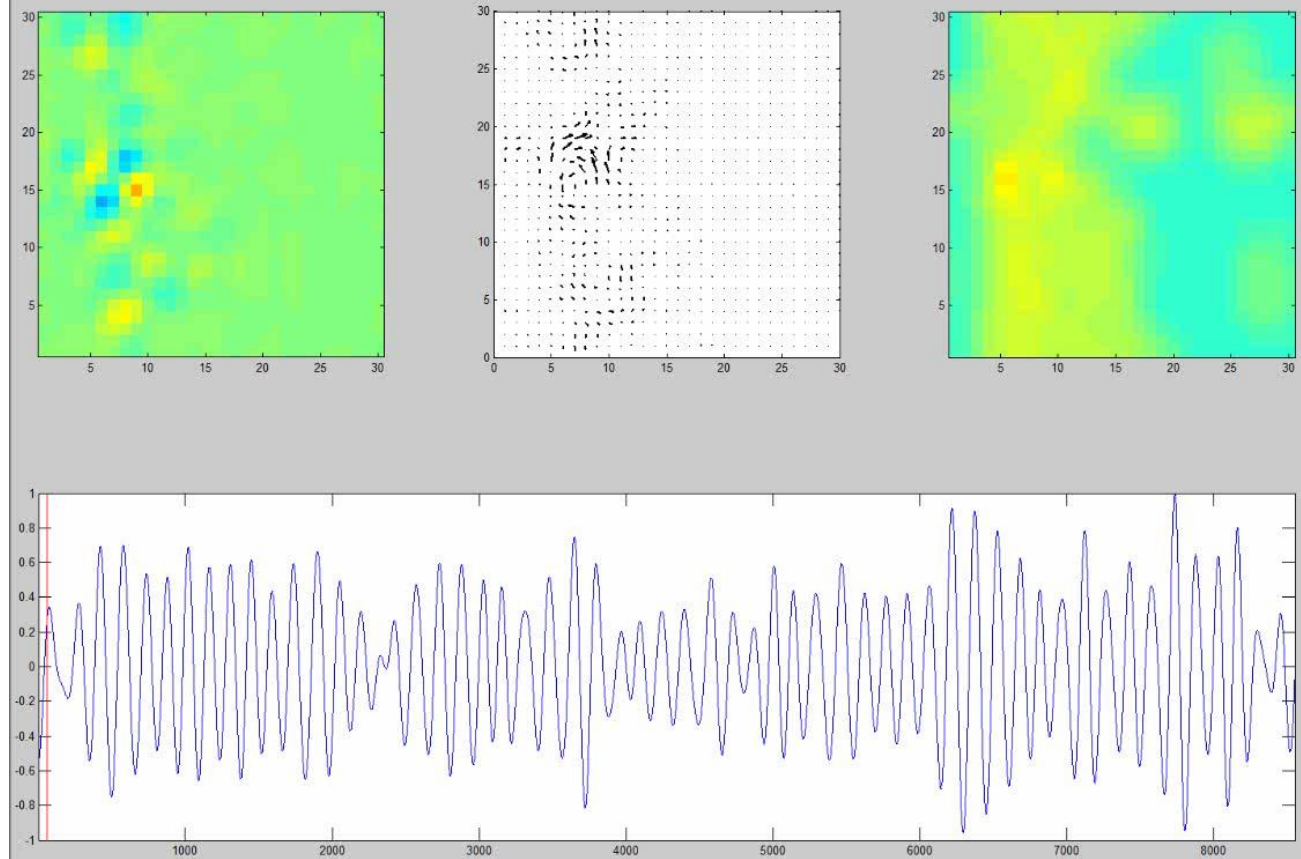
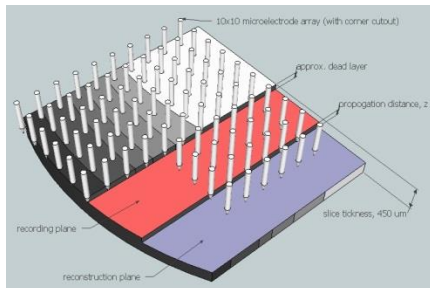
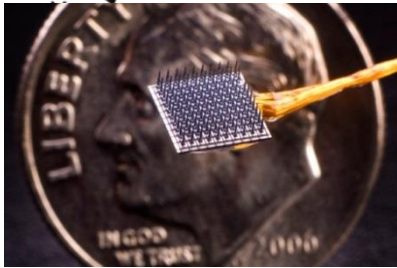
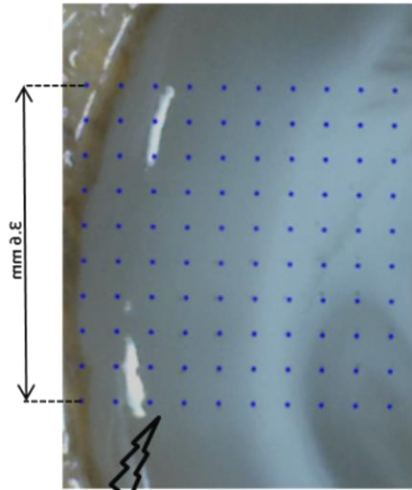


Figure 5. Data flow chart for time domain holography.

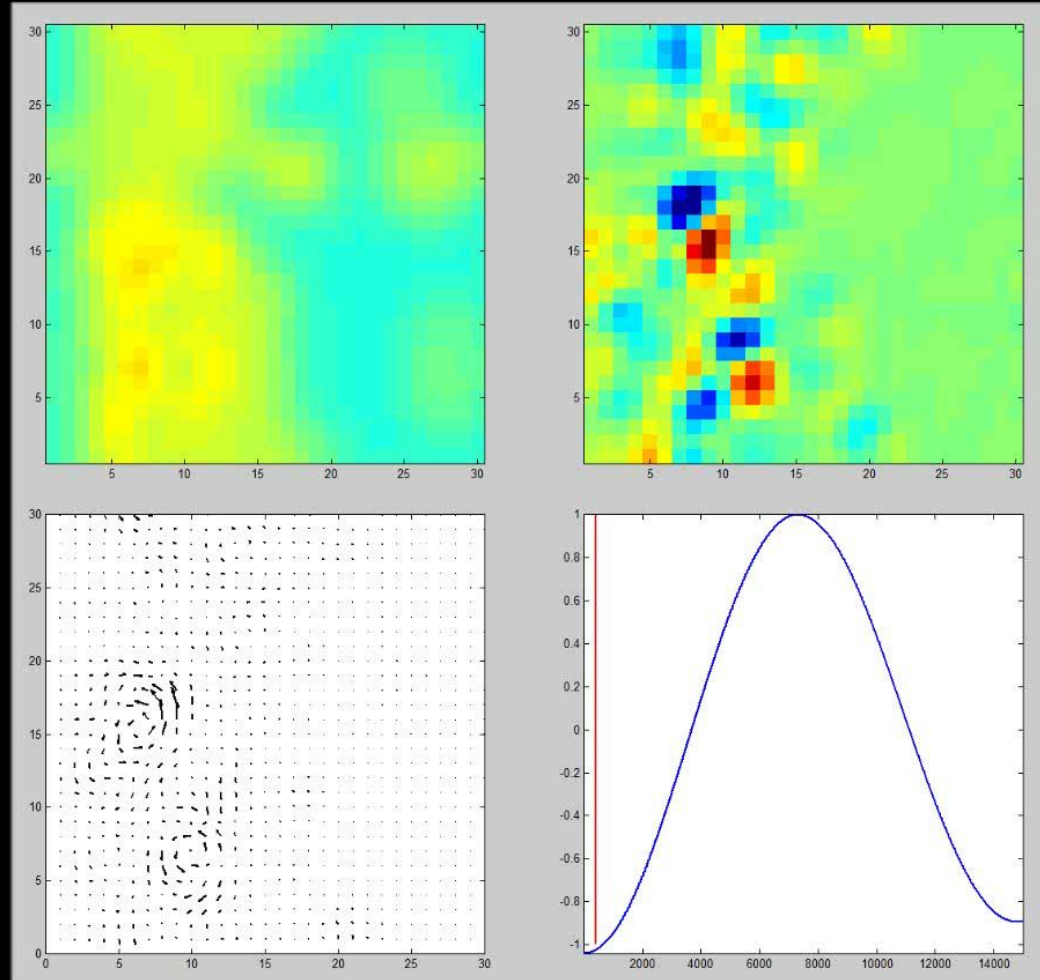
Example



Super-resolution: x3

Example

Energy flow
reveals
network
causality
patterns



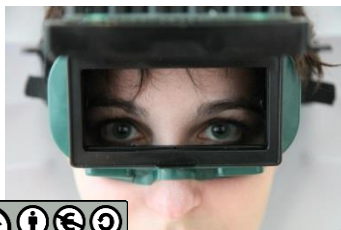
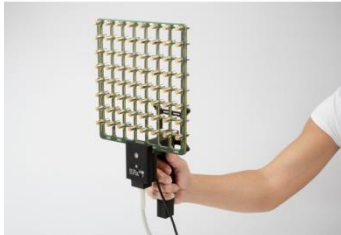
phase-locked
average of
previous clip

Acoustic Holographic Vision

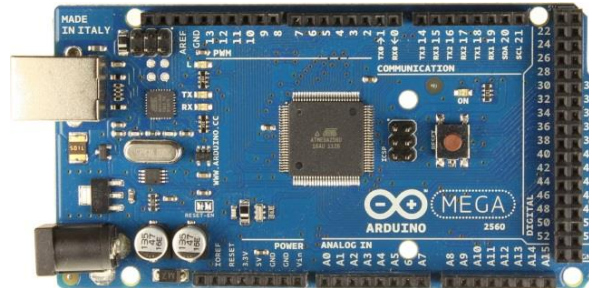
DESIGN SPECIFICATION OUTLINE:

Ultrasound holography with super-resolution via compressed sensing and real-time cloud services

Mobility



Computability



Quality



Recognition
Navigation
Response

Acknowledgements

Marcus Kaiser and Newcastle
Dynamic Connectome Lab

Miles Whittington and
York Oscillations Group

Gary Green and
York Neuroimaging Centre

Marco Manca and
CERN Medical Applications

