

SALAT Telescope Arm

Alejandro Pérez

IPHC – CNRS Strasbourg



CENTRE NATIONAL
DE LA RECHERCHE
SCIENTIFIQUE



PICSEL GROUP



PHYSICS WITH INTEGRATED CMOS SENSORS AND ELECTRON MACHINES

Outline

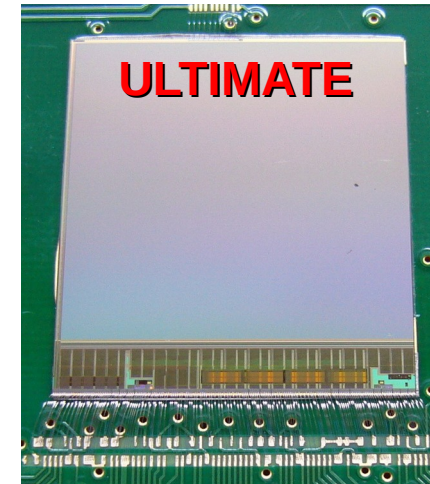
- Reminder on SALAT Prototype
- Preliminary results on SALAT Beam-Test @ CERN-SPS
- SALAT delivery
- Summary

Reminder on SALAT prototype

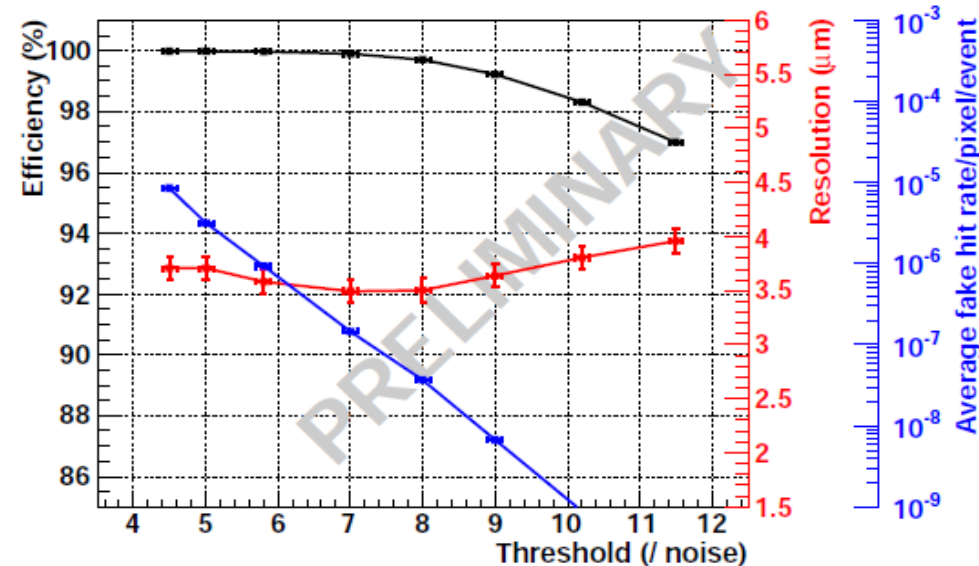
The Sensors: ULTIMATE (MIMOSA-28)

ULTIMATE main characteristics

- CMOS sensor (0.35 μm AMS) high-resistive Epi-layer-15 μm
Sensor thinned to 50 μm (total thickness)
- Column || architecture with in-pixel CDS & amplification
- End-of-column discriminator & binary charge encoding, followed by \emptyset -suppression
- 960x928 (columns x rows): pitch 20.7 μm (19.9x19.2 mm²)
- $t_{\text{r.o.}} \lesssim 200\mu\text{s}$ ($\sim 5 \times 10^3$ frames/s) \Rightarrow suited to $> 10^6$ part./cm²/s
- 2 outputs @ 160 MHz
- Power consumption $\sim 150\text{mW/cm}^2$
- Running at room temp. ($T = 30\text{C}^\circ$)



MIMOSA 28 - epi 15 μm



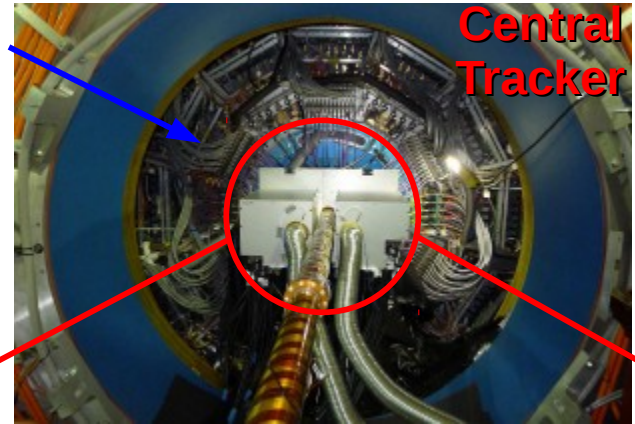
ULTIMATE Performances

- $\sigma_{\text{sp}} \gtrsim 3.5\mu\text{m}$
- Efficiency $\lesssim 99.9\%$
- Fake rate $\lesssim 10^{-5}$

ULTIMATE @ STAR: STAR-PXL detector

STAR-TPC

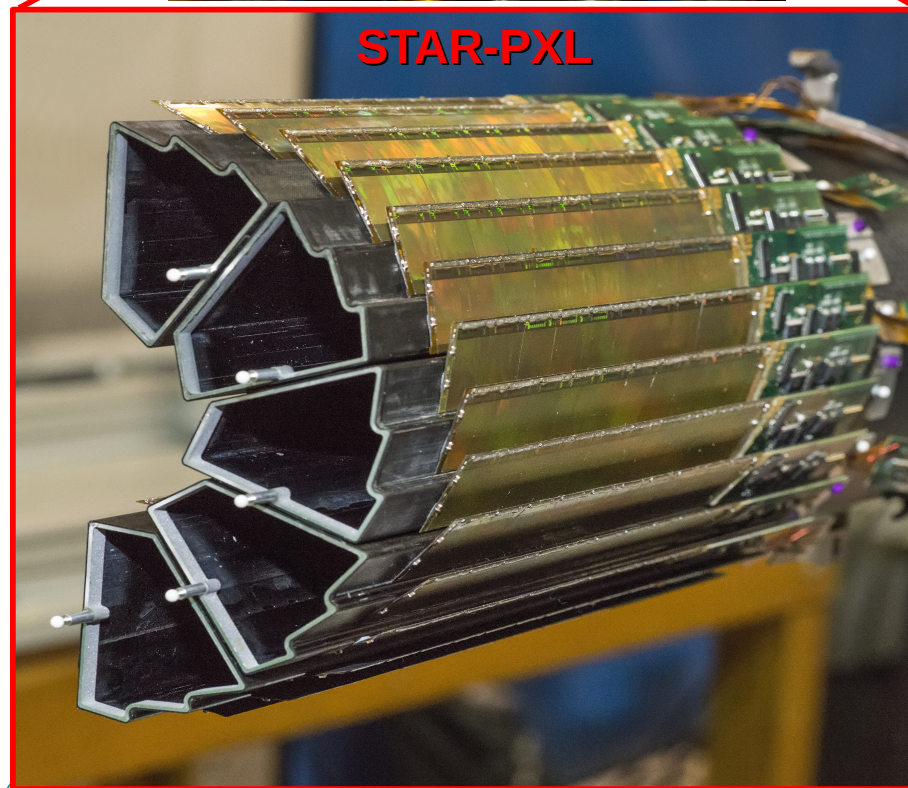
Central Tracker



STAR-PXL HALF-BARREL

- 2 layers: 20 ladders ($0.37\% X_0$)
- 200 sensors
- 180×10^6 pixels
- Air flow cooling: $T \leq 35^\circ\text{C}$
- $\sigma_{\text{sp}} \lesssim 4\mu\text{m}$
- Rad. Load $150\text{kRad} + 3 \times 10^{12}$ n.e.q
(Full life-time)
- $t_{\text{o.r.}} \lesssim 200\mu\text{s}$

STAR-PXL



SALAT final plane

- **LAT motivations**
 - Big surface and thin reference planes

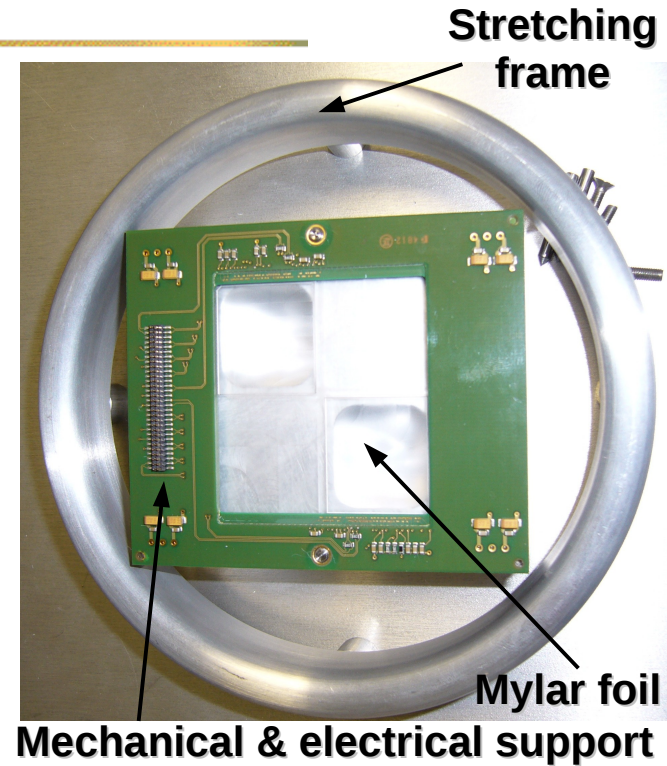
SALAT final plane

■ LAT motivations

- Big surface and thin reference planes

■ Assembly

- Stretched 50 μm Mylar foil ($X_0^{\text{Mylar}} \sim 3 \times X_0^{\text{Si}}$)



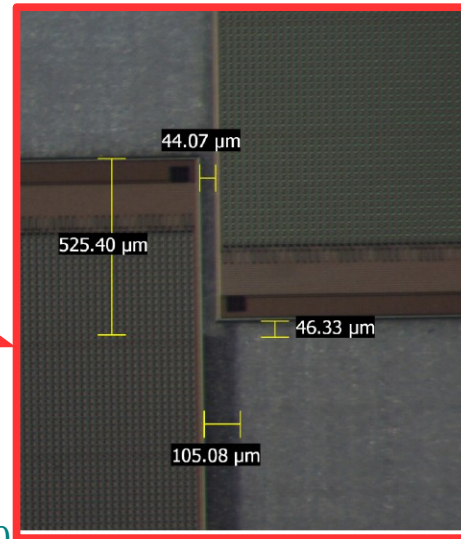
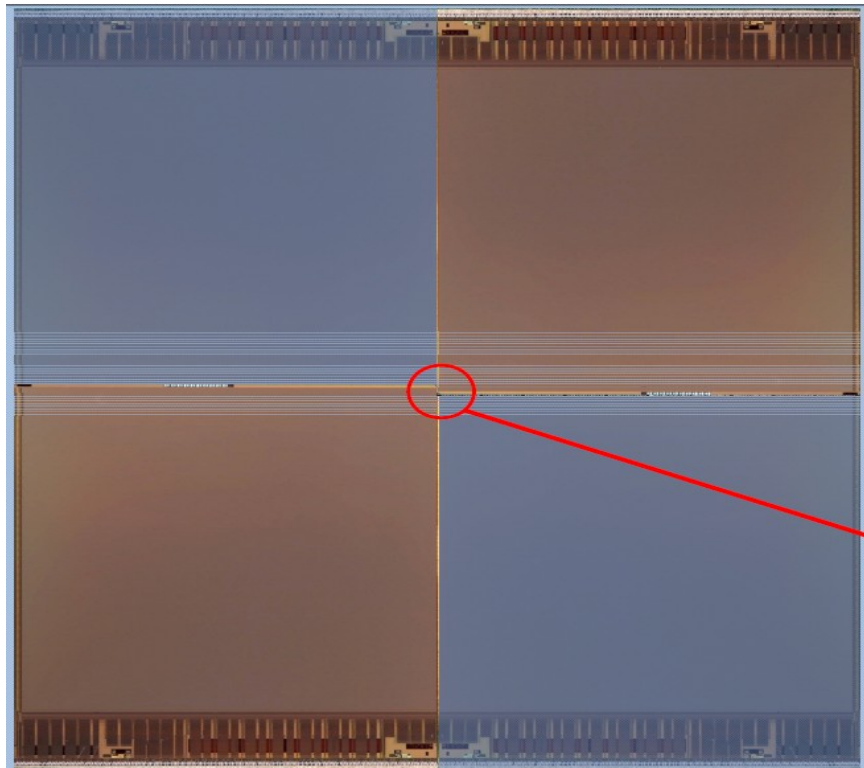
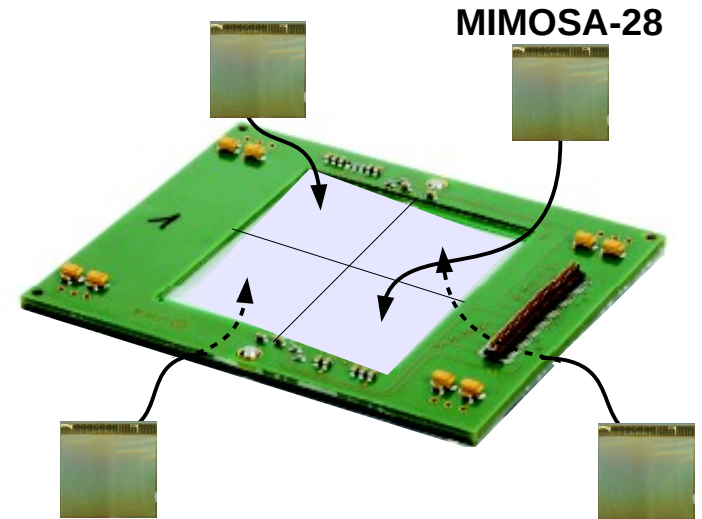
SALAT final plane

LAT motivations

- Big surface and thin reference planes

Assembly

- Stretched 50 μm Mylar foil ($X_0^{\text{Mylar}} \sim 3 \times X_0^{\text{Si}}$)
- Layout: 2 staggered sensors on each side



Vertical space between sensors

- Clear region: $\sim 5\mu\text{m}$
- Sealing line: $\sim 10\mu\text{m}$
- Cutting edge: $\sim 10\mu\text{m}$

Expect gap between neighbouring pixels of $\sim 100\mu\text{m}$

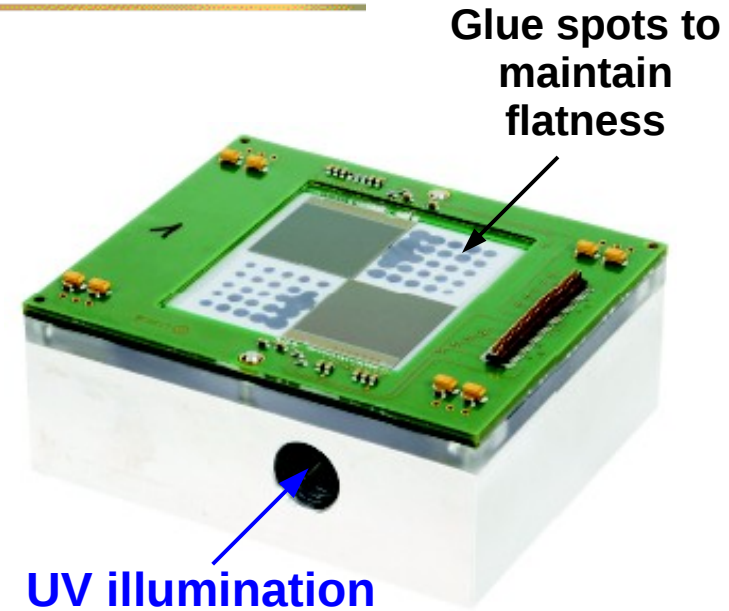
SALAT final plane

■ LAT motivations

- Big surface and thin reference planes

■ Assembly

- Stretched 50 μ m Mylar foil ($X_0^{\text{Mylar}} \sim 3 \times X_0^{\text{Si}}$)
- Layout: 2 staggered sensors on each side
- UV cured gluing



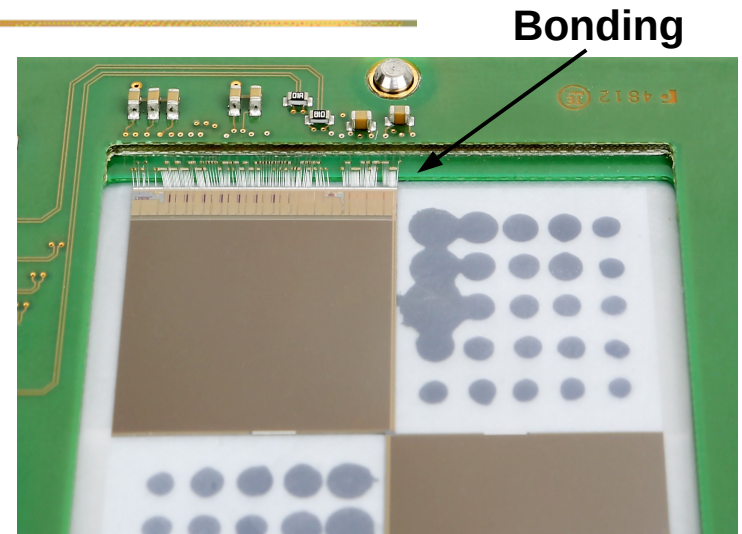
SALAT final plane

■ LAT motivations

- Big surface and thin reference planes

■ Assembly

- Stretched 50 μ m Mylar foil ($X_0^{\text{Mylar}} \sim 3 \times X_0^{\text{Si}}$)
- Layout: 2 staggered sensors on each side
- UV cured gluing
- Sensor bonding



SALAT final plane

LAT motivations

- Big surface and thin reference planes

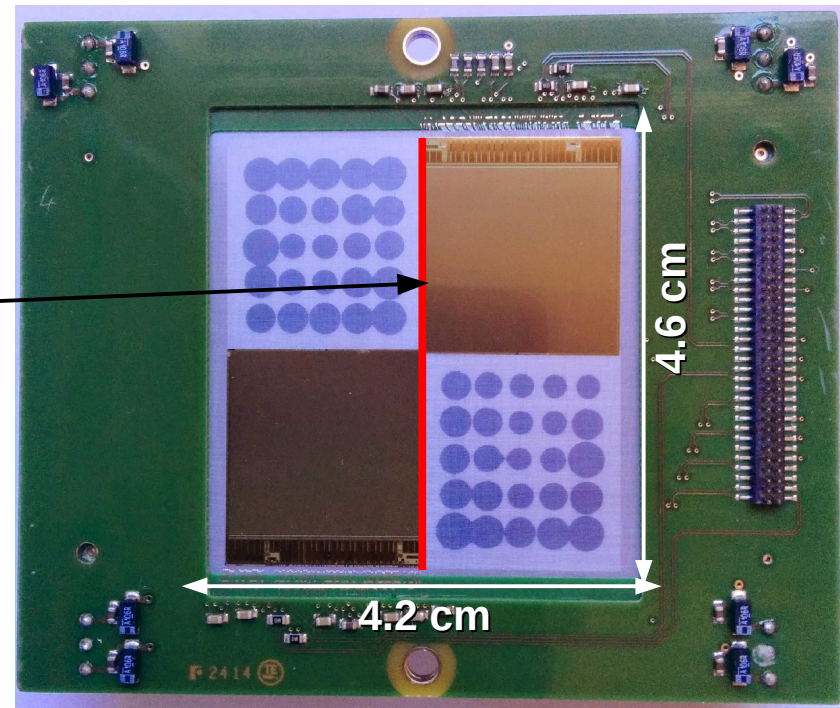
Assembly

- Stretched 50 μ m Mylar foil ($X_0^{\text{Mylar}} \sim 3 \times X_0^{\text{Si}}$)
- Layout: 2 staggered sensors on each side
- UV cured gluing
- Sensor bonding

Basic numbers

- 3.6 M-pixels over 15.3 cm²
- < 200 μ s integration time
- Inensitive areas \sim 100 μ m

Sensing area = 4 x 3.8cm²



SALAT final plane

■ LAT motivations

- Big surface and thin reference planes

■ Assembly

- Stretched 50 μ m Mylar foil ($X_0^{\text{Mylar}} \sim 3 \times X_0^{\text{Si}}$)
- Layout: 2 staggered sensors on each side
- UV cured gluing
- Sensor bonding

■ Basic numbers

- 3.6 M-pixels over 15.3 cm²
- < 200 μ s integration time
- Inensitive areas \sim 100 μ m

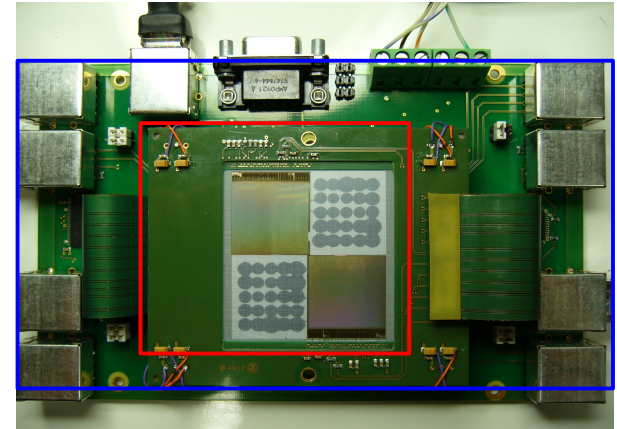
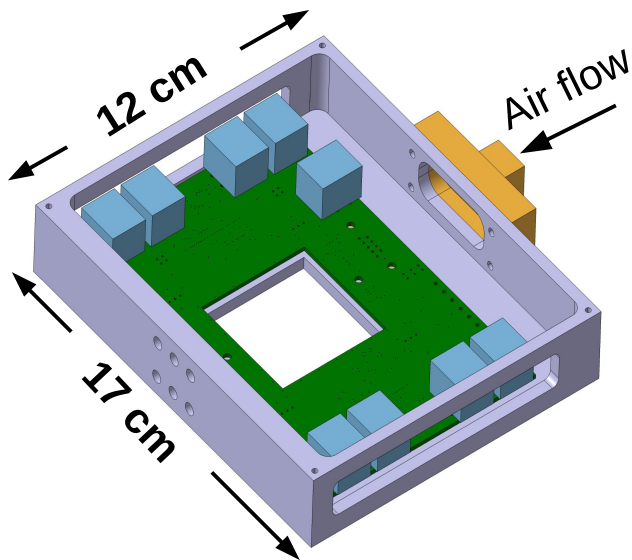
■ Production

- Several SALAT modules fully operational
 - 13 Modules mounted
 - 4 Modules fully validated (including beam test): 8, 11, 15 and 16

SALAT PCB, Mechanics and Cooling

PCB design

- Mother (10x16 cm²) and daughter (7x8 cm²) design and production at IPHC micro-tech group

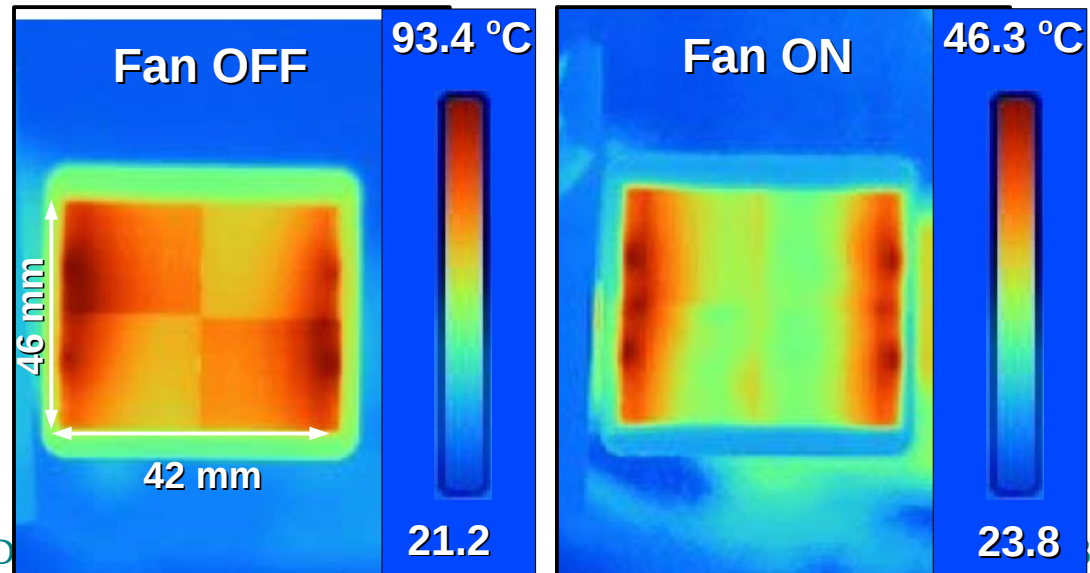


Mechanical structure

- Design and production at IPHC mechanical workshop

Cooling system

- Chip works with no cooling (relatively high noise)
- Modest cooling required
- Few m/s of ambient air



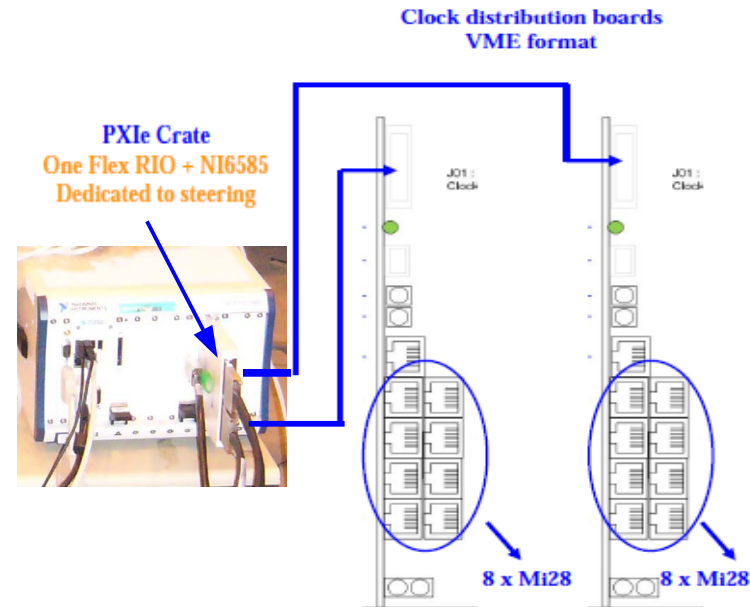
SALAT Data Acquisition System

Context of IPHC contribution

- Standalone system driving sensors, acquiring and storing data
 - PXI crate and boards, separated clock distribution board
- No interface with higher system
- Provides TLU interface (EUDET handshake) but not tested

New developments

- **Additional NI-6585 + Flex-RIO boards in PXI**
- New clock distribution board to synchronize 3 SALAT planes (12 Mi-28) and up to 4 SALAT planes if required (16 Mi-28)
- New software to read 4 SALAT planes (16 Mi-28)
 - Readout validated for up to 14 Mi-28 sensors



SALAT beam test @ CERN-SPS

Preliminary results

November test beam @ CERN: overview

Conditions @ CERN-SPS: 23 – 28 Nov. 2014

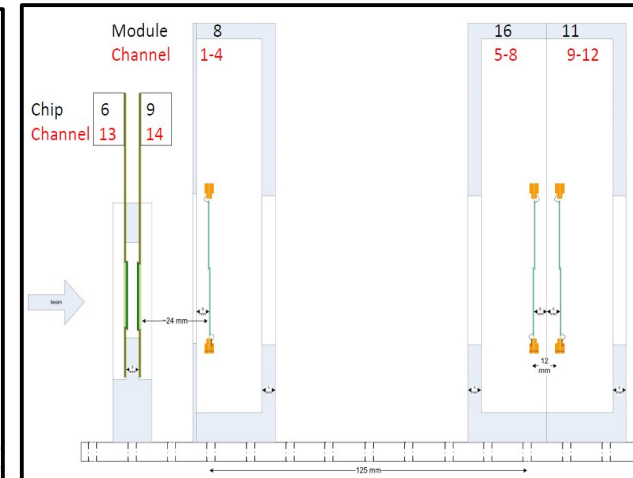
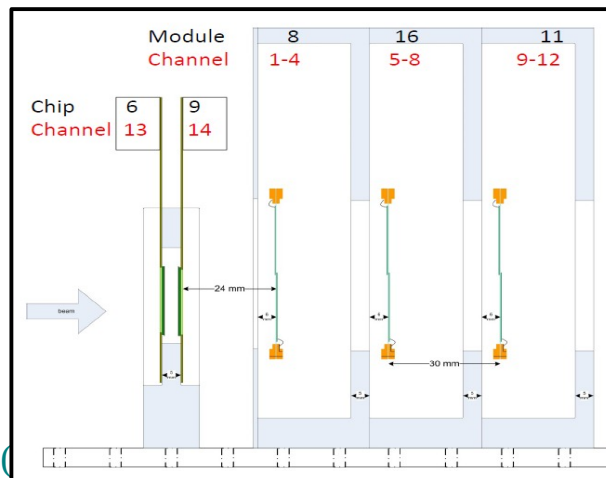
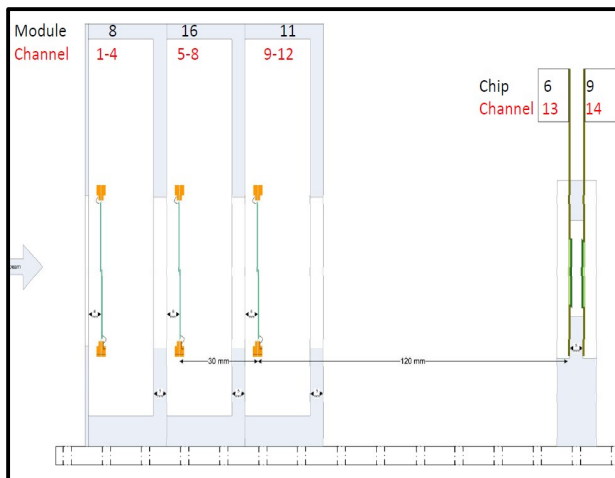
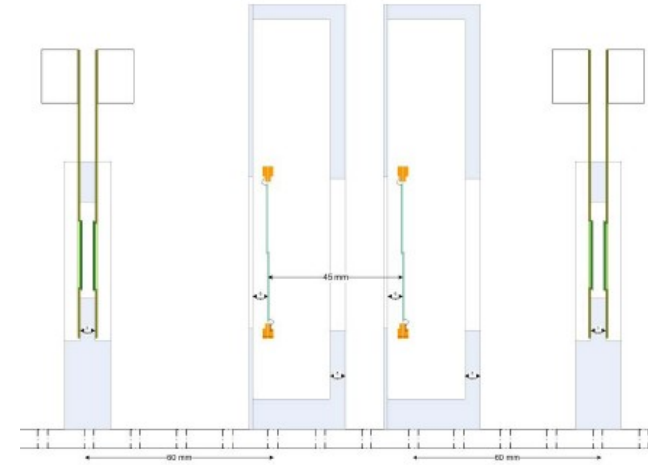
- π^- beam with energy of 120 GeV
- Different trigger rates: 1 – 50kHz ($\sim 1 \text{ cm}^2$ scintillator)
- Air cooling for SALAT moduli

SALAT moduli alignment

- Relative alignment of Mi-28 sensors in SALAT module

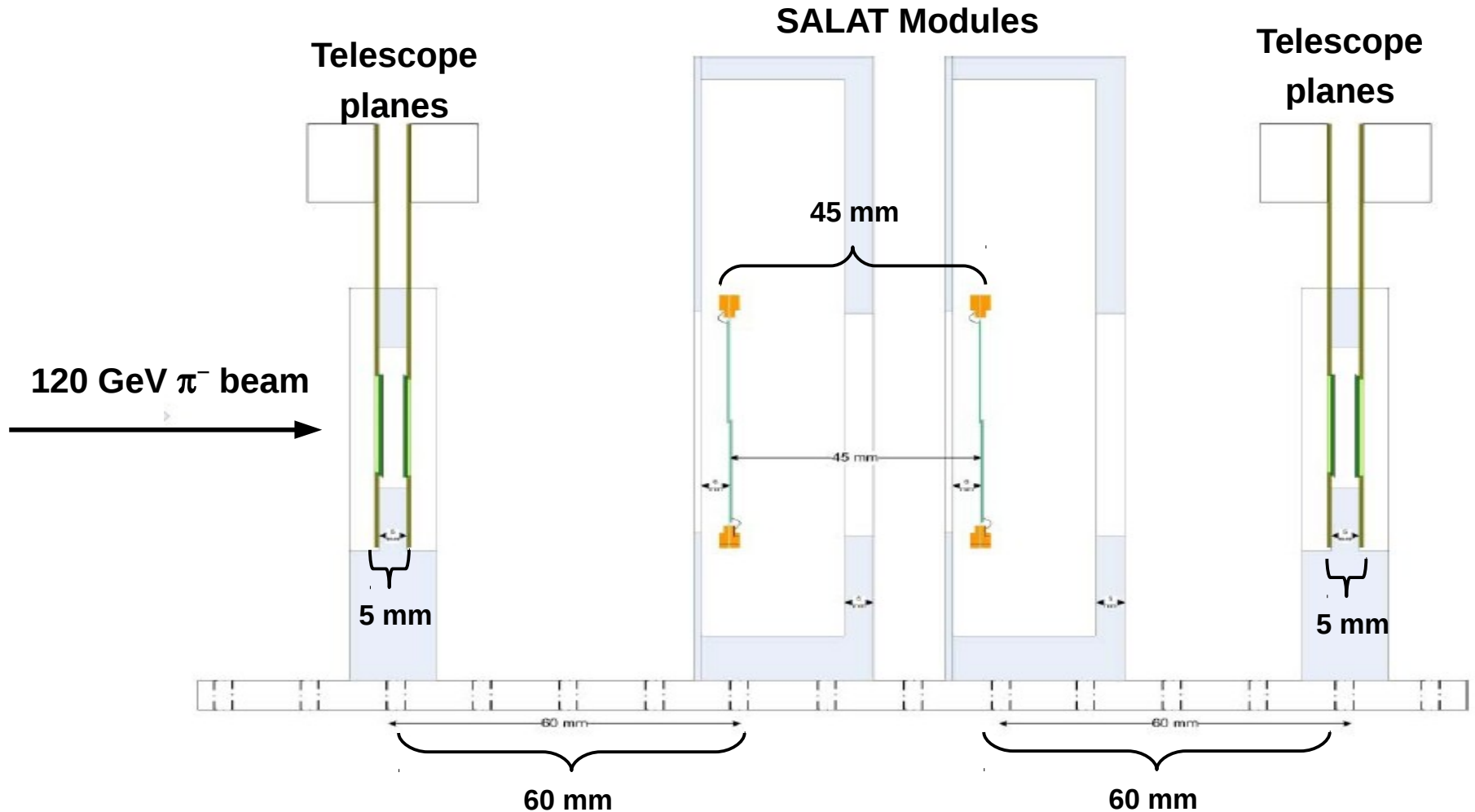
Telescope with 3 SALAT moduli

- Different geometrical configurations with 3 SALAT modules + 2 Mi-sensors as DUT



Relative Alignment of SALAT sensors: set-up

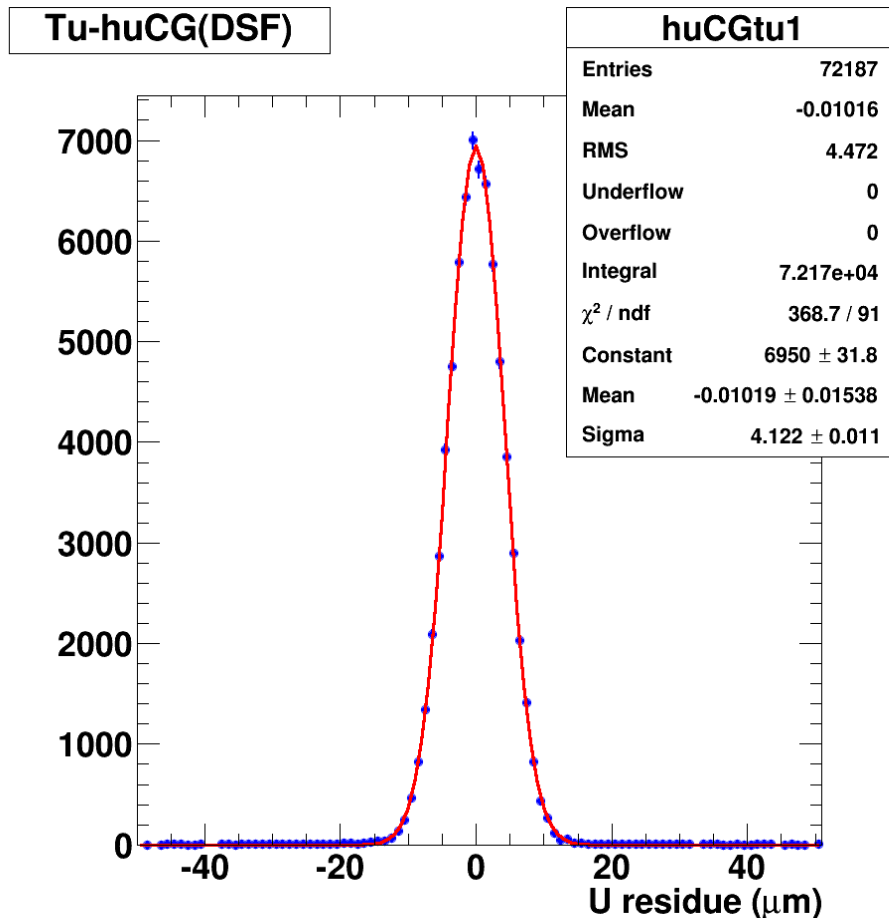
- **Configuration:** 4 reference planes (Telescope) and two SALAT modules
 - Relative alignment of the sensor in SALAT module



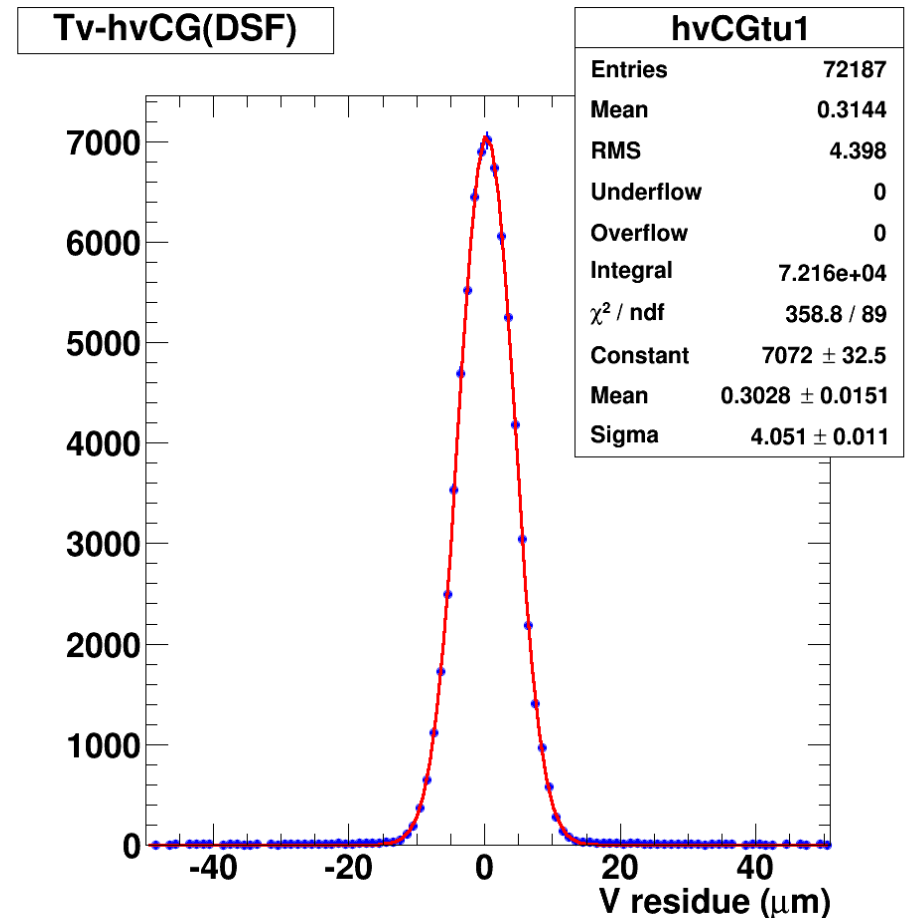
Relative Alignment of SALAT sensors: residues

Example: one of the sensor of Module 16
THR @ 8x noise

Residual U



Residual V

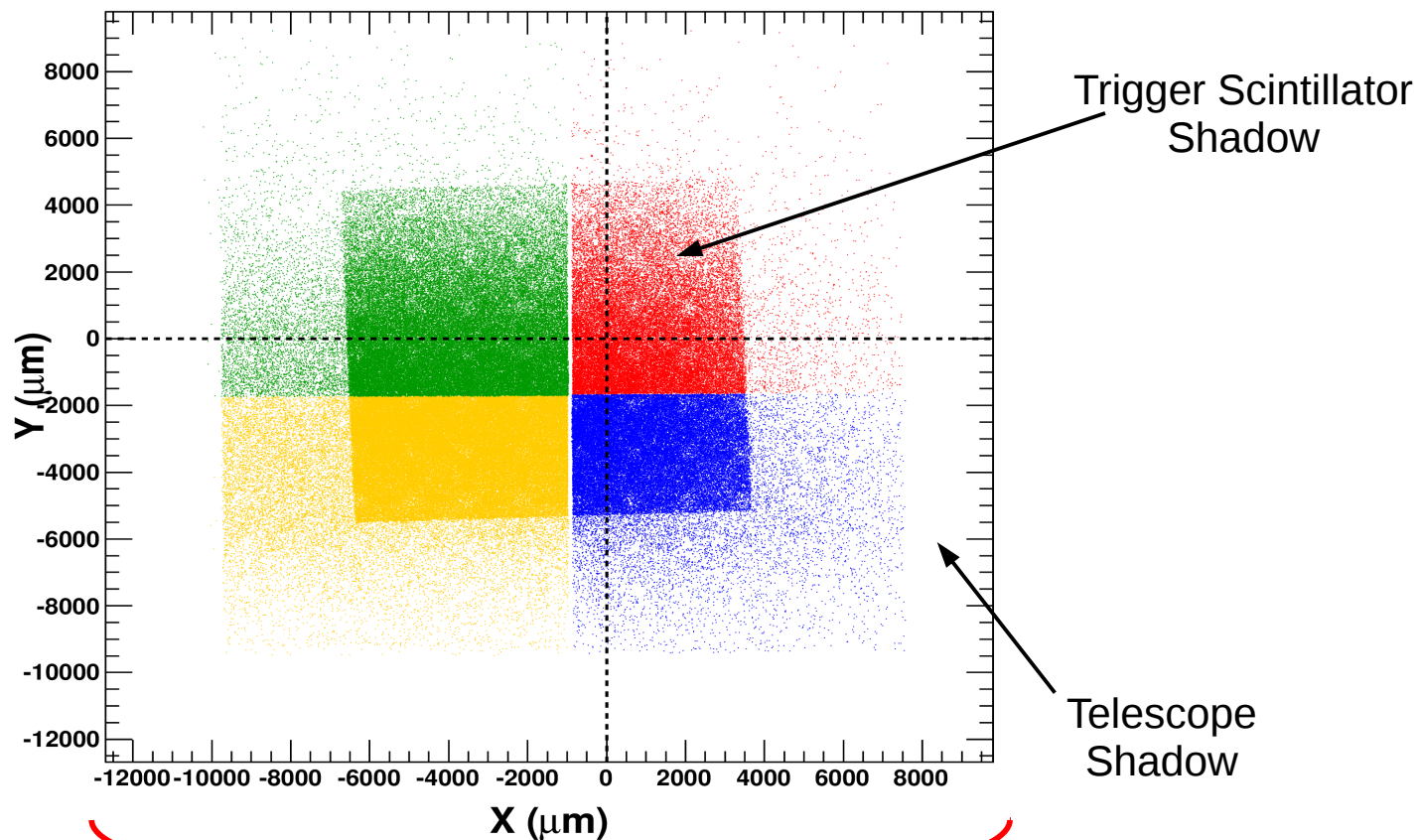


Relative Alignment of SALAT sensors: Insensitive Zones

π^- beam 

Module 8

Hit associated to Track Map



Each Quadrant = one MIMOSA-28 Corner

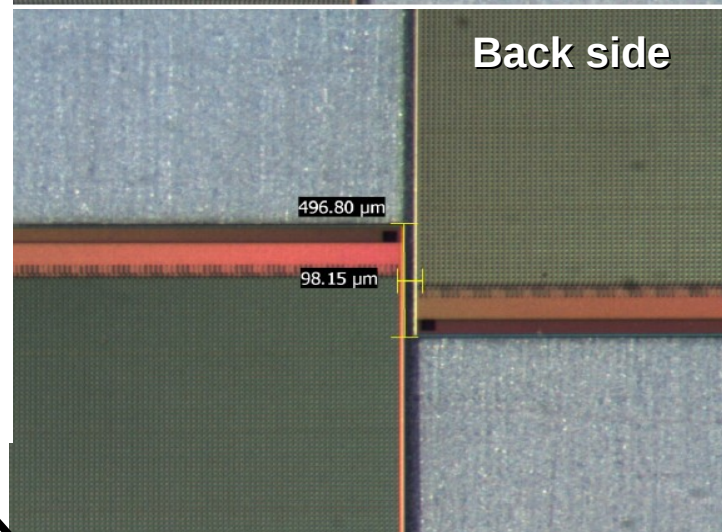
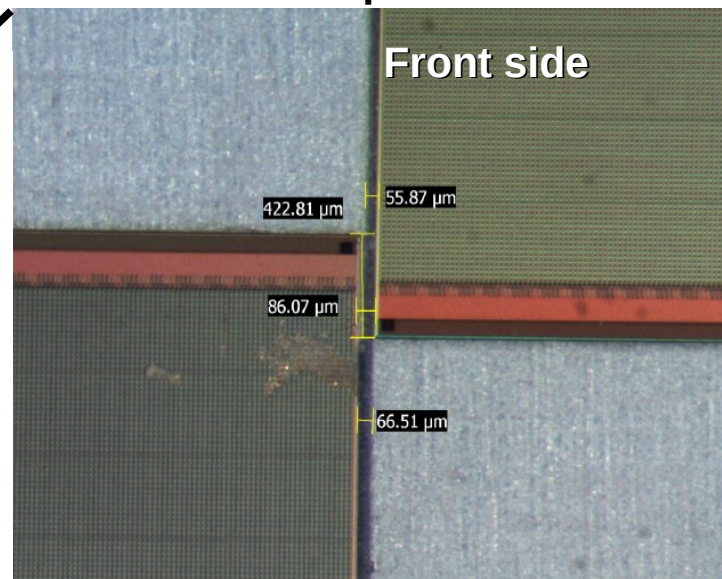
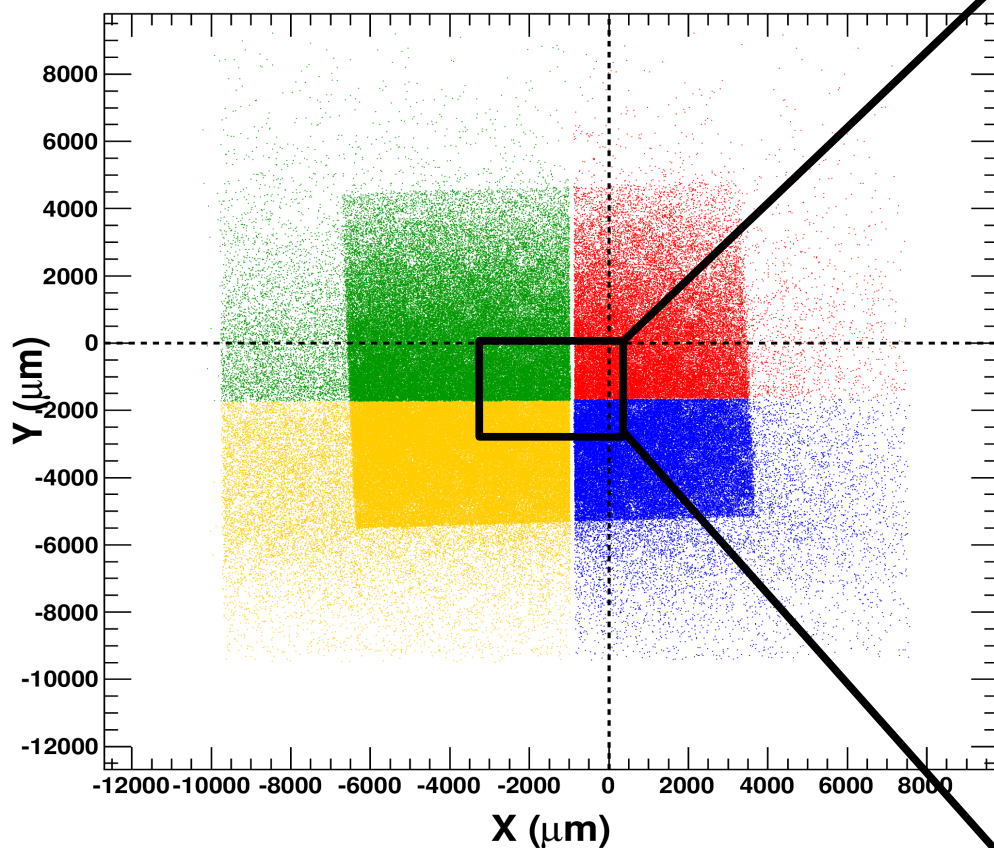
Relative Alignment of SALAT sensors: Insensitive Zones

π^- beam 

Module 8

Visual inspection

Hit associated to Track Map

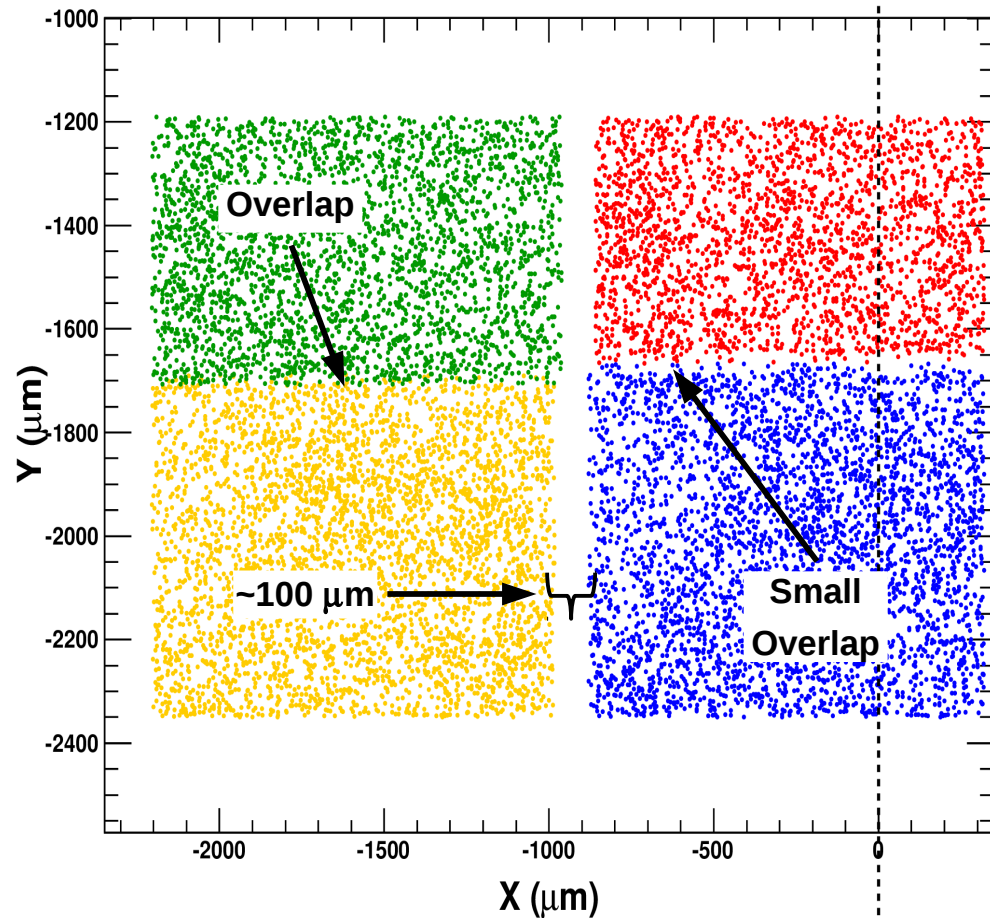


Relative Alignment of SALAT sensors: Insensitive Zones

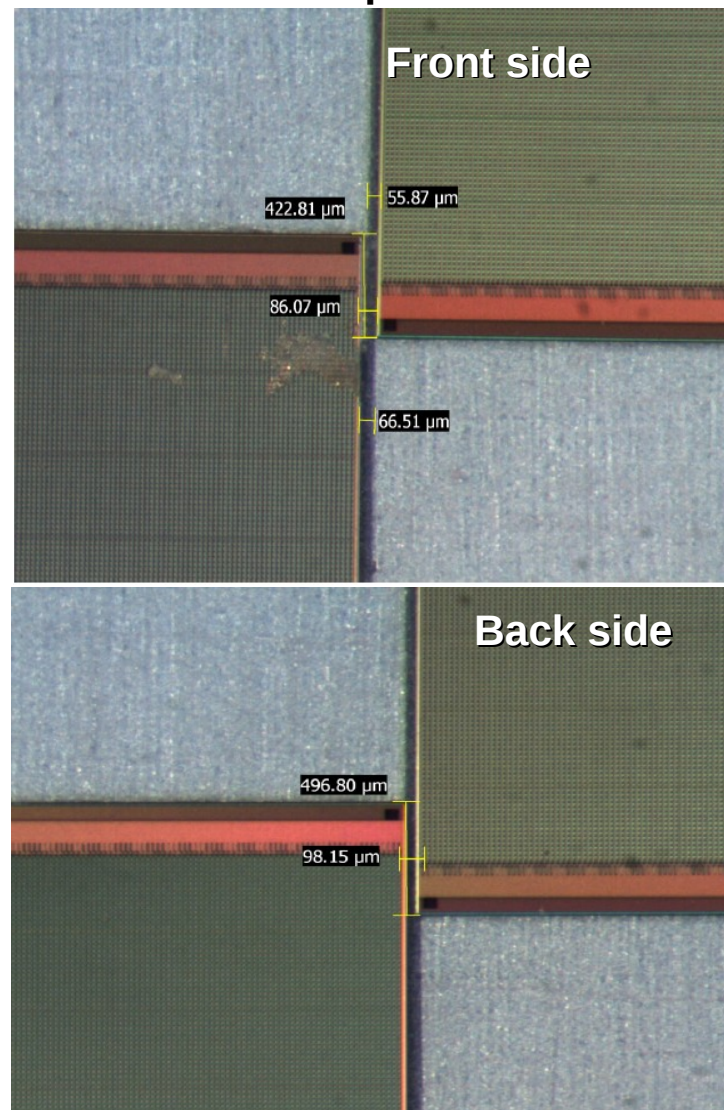
π^- beam 

Module 8

Hit associated to Track Map



Visual inspection

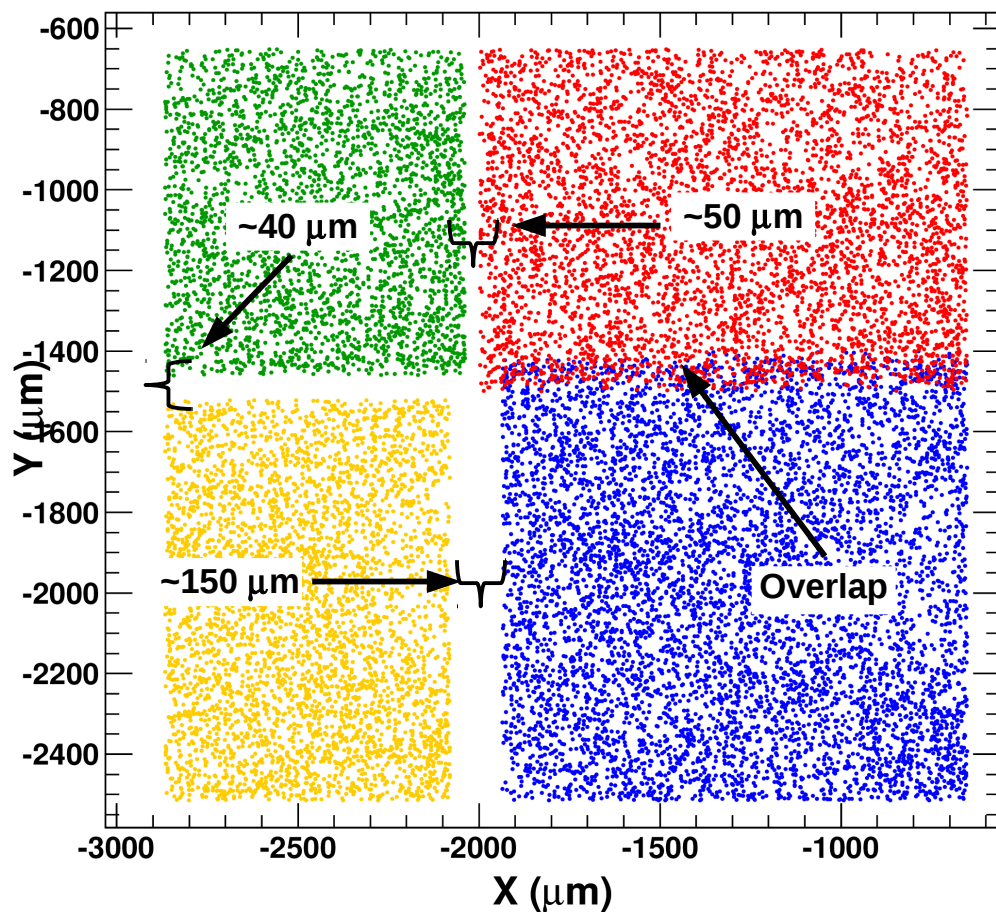


Relative Alignment of SALAT sensors: Insensitive Zones

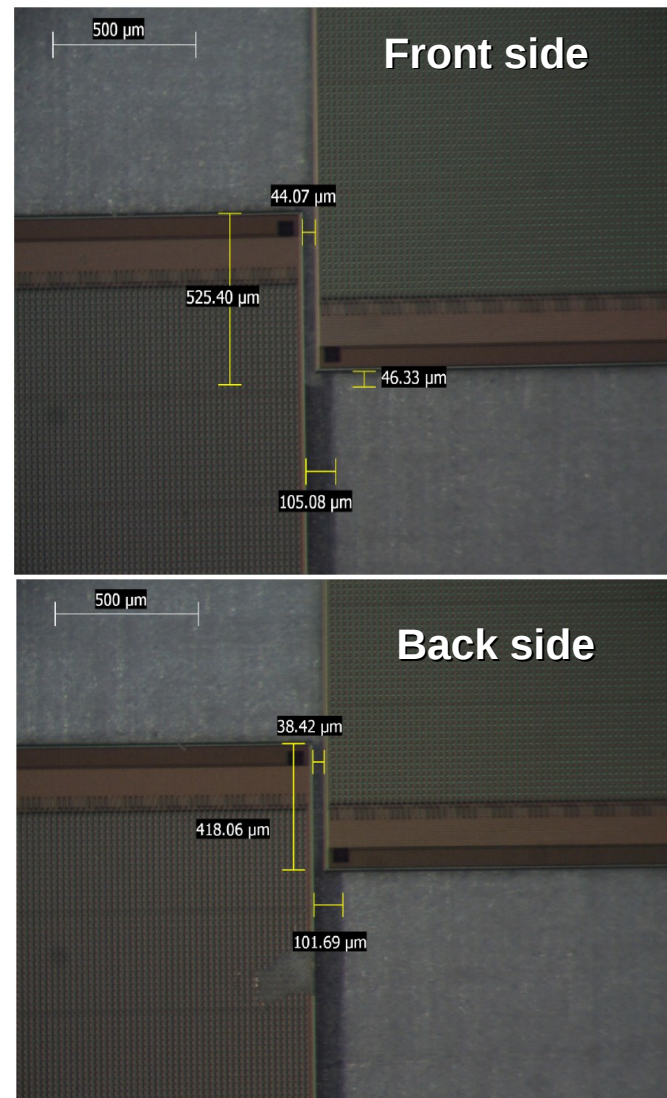
π^- beam 

Module 16

Hit associated to Track Map

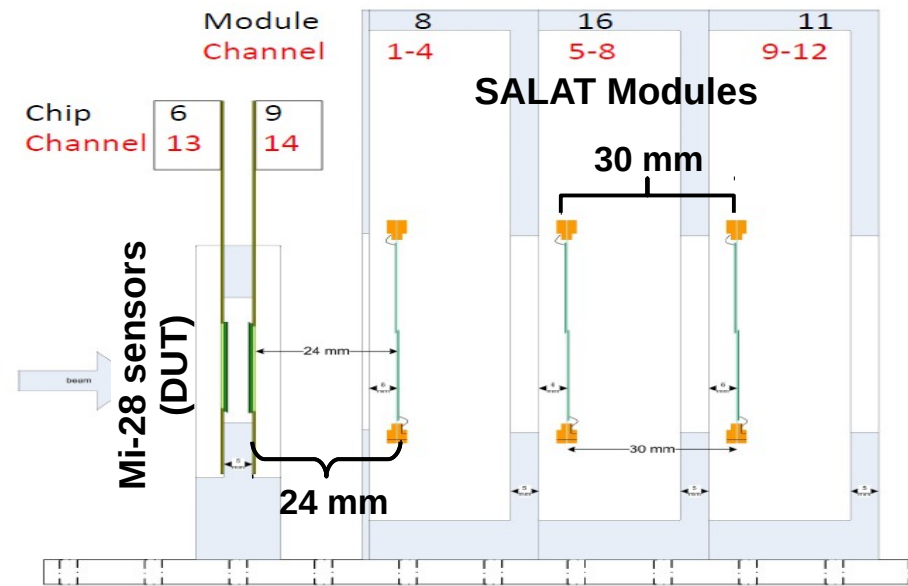
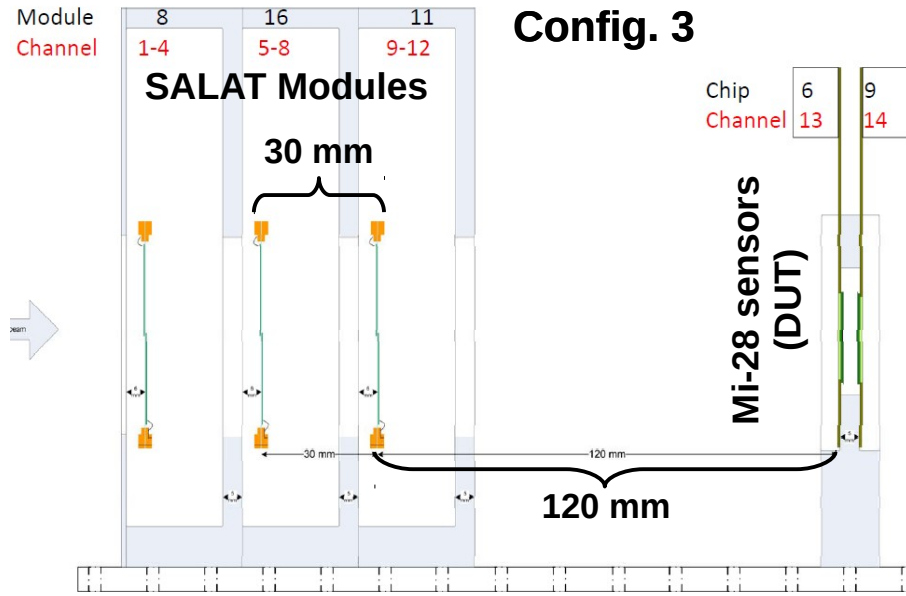


Visual inspection

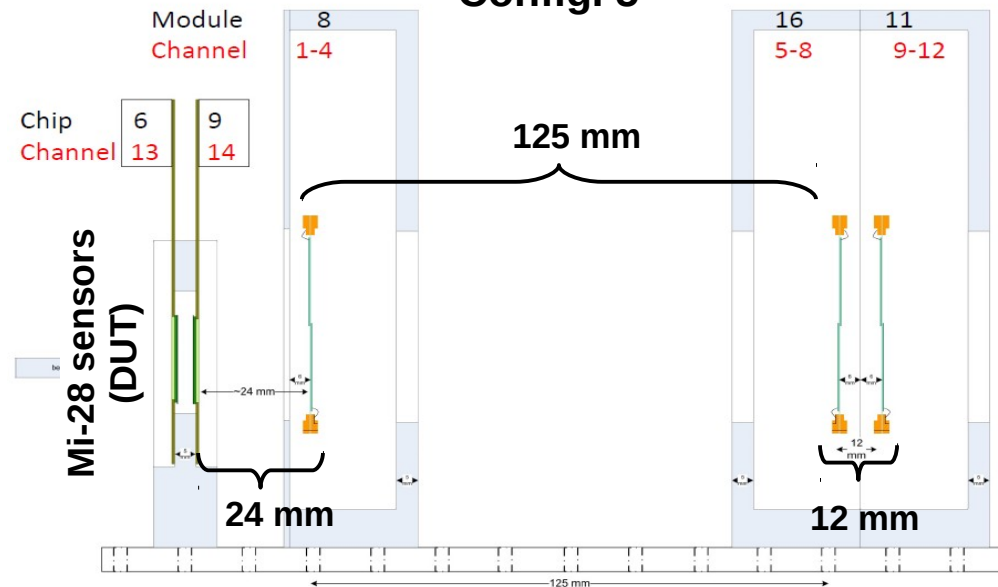


Telescope with SALAT modules: set-up

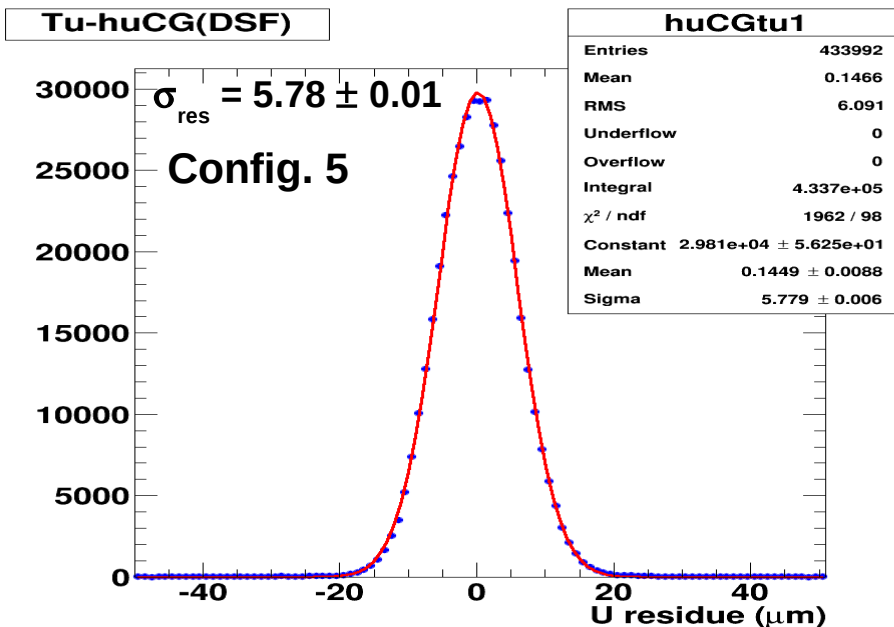
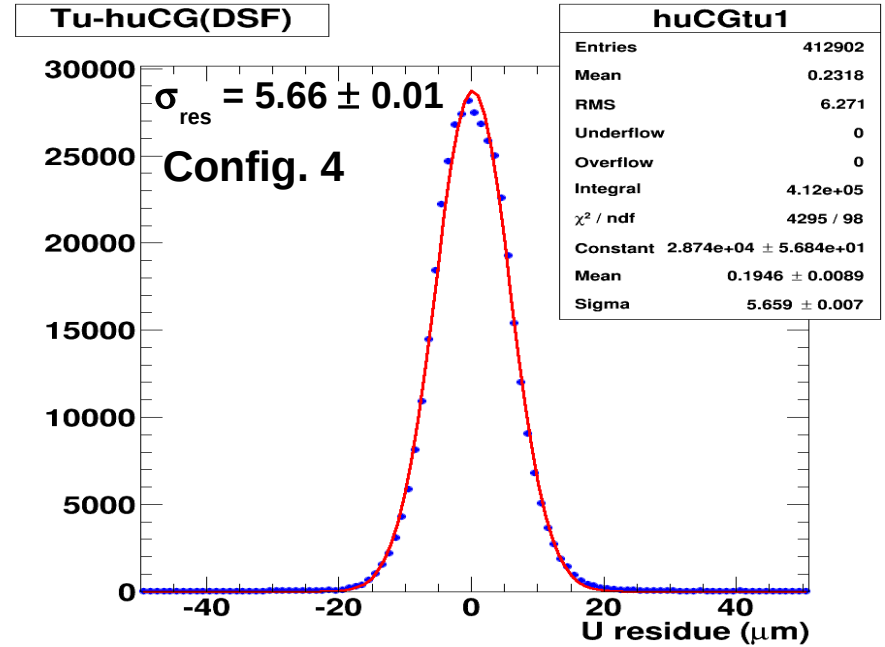
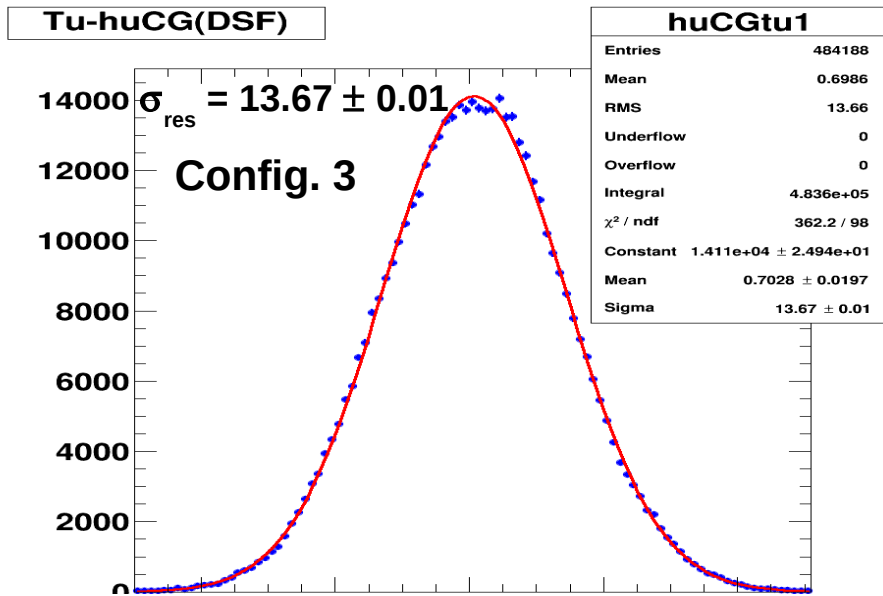
Config. 4



Config. 5



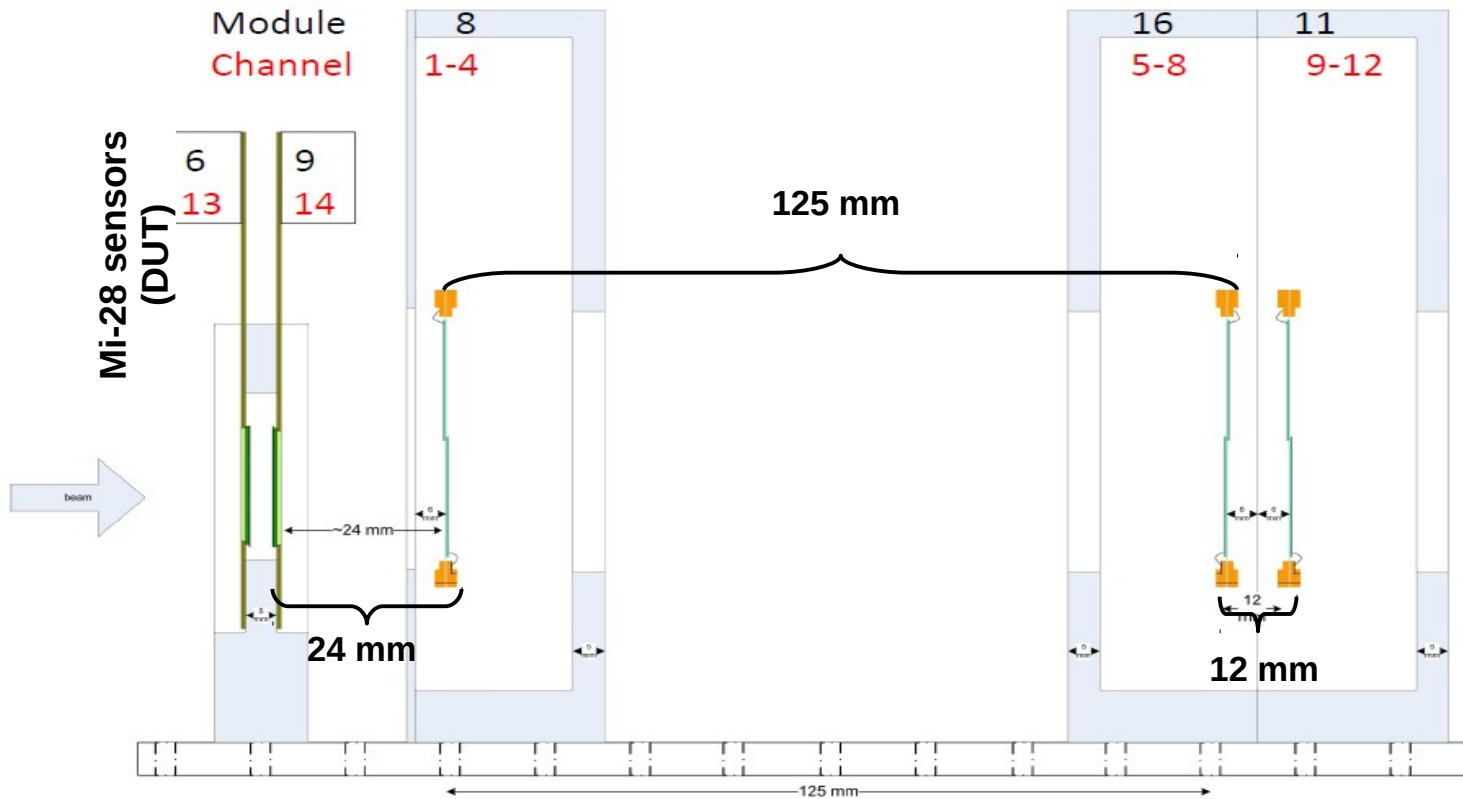
Telescope with SALAT modules: Telescope precision



Config.	$\sigma_{res} (\mu\text{m})$	$\sigma_{tel}^{\text{exp}} (\mu\text{m})$	$\sigma_{tel}^{\text{theo}} (\mu\text{m})$
3	13.67 ± 0.01	13.21 ± 0.01	13.0
4	5.66 ± 0.01	4.44 ± 0.01	4.9
5	5.78 ± 0.01	4.60 ± 0.01	4.2

Telescope with SALAT modules: Multi-tracking

- Configuration 5: Study of tracking performances of the SALAT modules

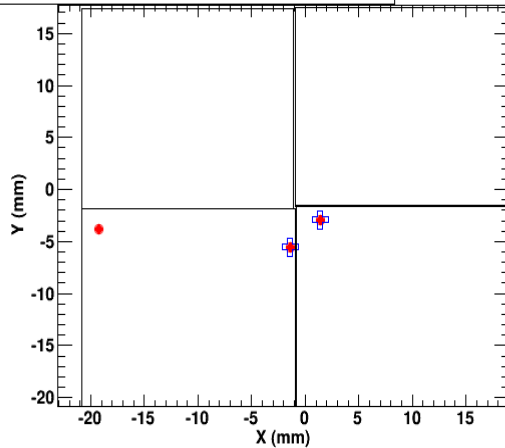


Telescope with SALAT modules: Multi-tracking

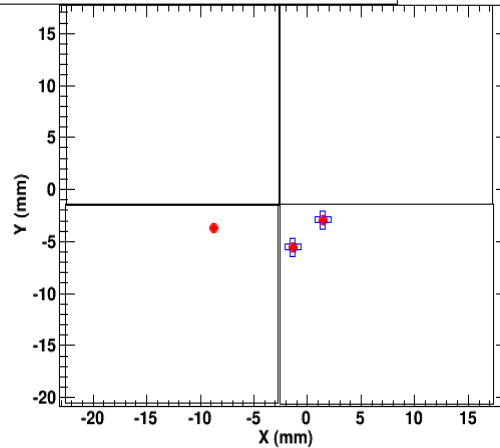
- $R_{\text{trigger}} \sim 1 \text{ kHz}$, Evt 6805, $N_{\text{rec}} \text{ tracks} = 2$
- Tracking only with SALAT planes (Mod-8,16,11). Planes 1 and 2 are DUT

Run 28849 Event 6805

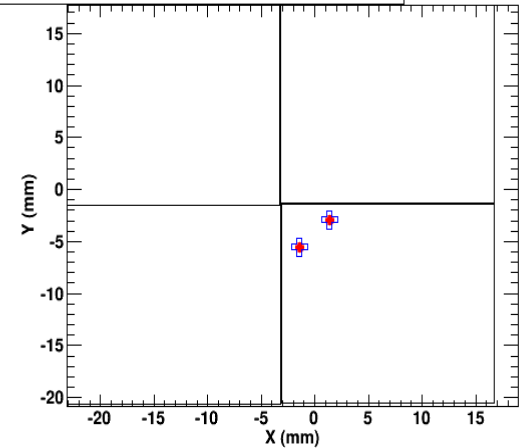
Hit map Telescope on SALAT mod-8



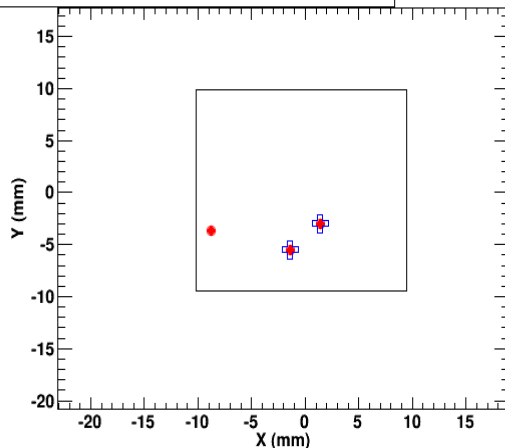
Hit map Telescope on SALAT mod-16



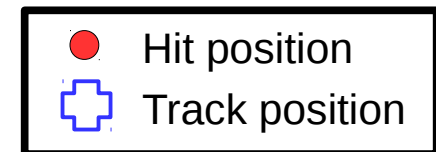
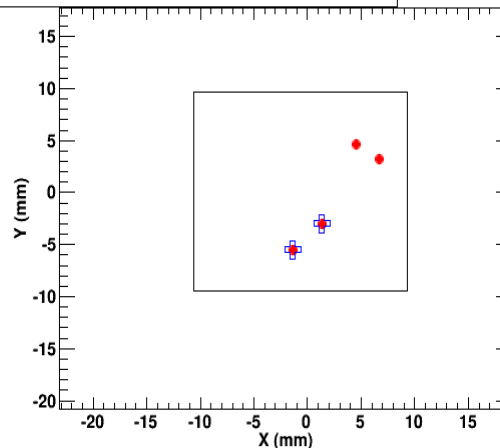
Hit map Telescope on SALAT mod-11



Hit map Telescope on Plane 1



Hit map Telescope on Plane 2

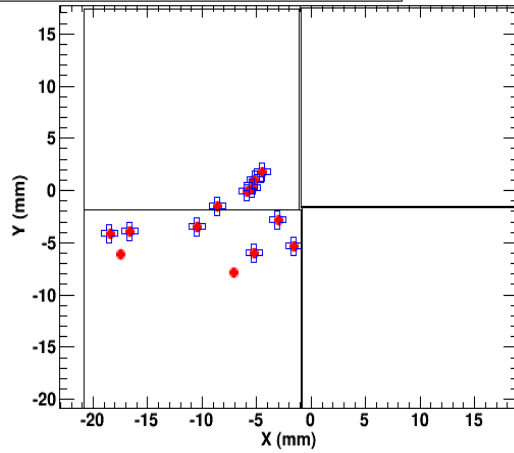


Telescope with SALAT modules: Multi-tracking

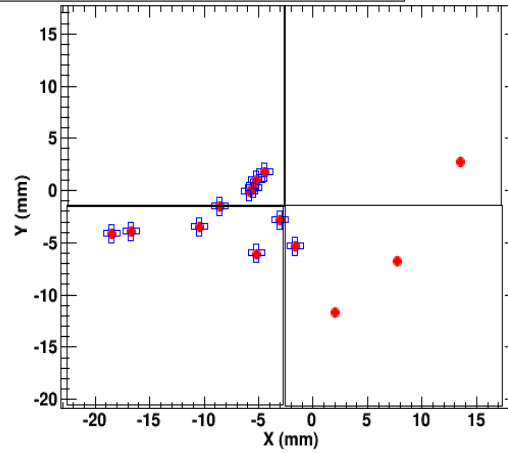
- $R_{\text{trigger}} \sim 1 \text{ kHz}$, Evt 4802, $N_{\text{rec}} \text{ tracks} = 10$
- Tracking only with SALAT planes (Mod-8,16,11). Planes 1 and 2 are DUT

Run 28849 Event 4802

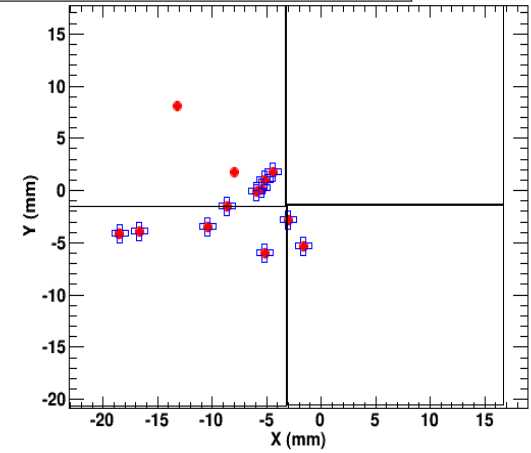
Hit map Telescope on SALAT mod-8



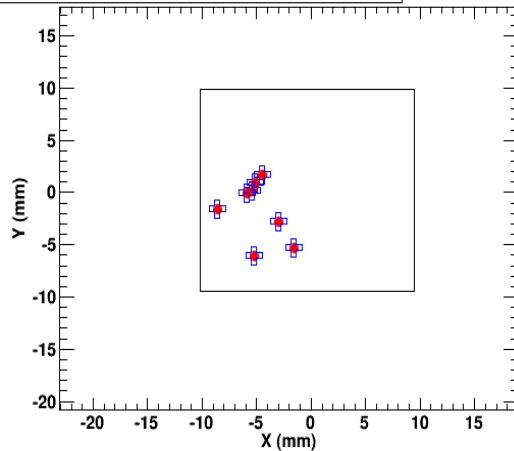
Hit map Telescope on SALAT mod-16



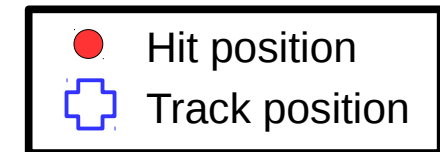
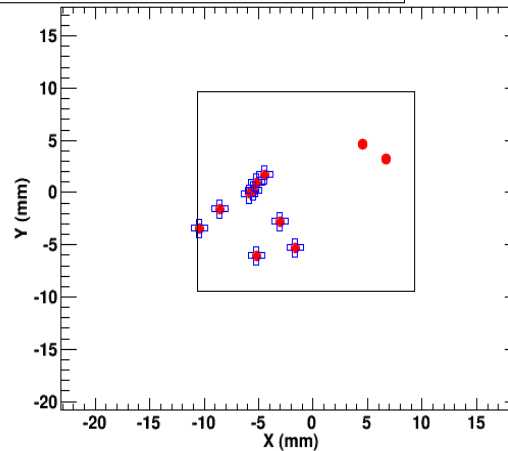
Hit map Telescope on SALAT mod-11



Hit map Telescope on Plane 1



Hit map Telescope on Plane 2

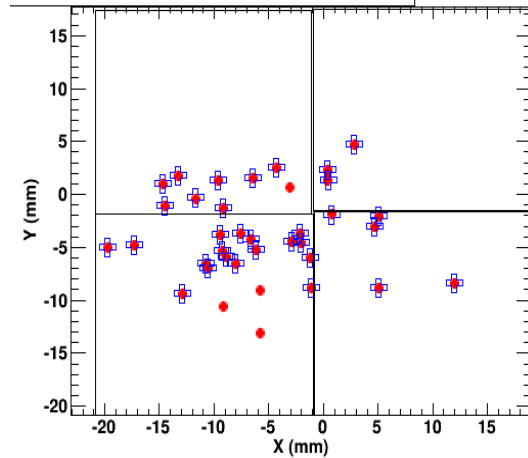


Telescope with SALAT modules: Multi-tracking

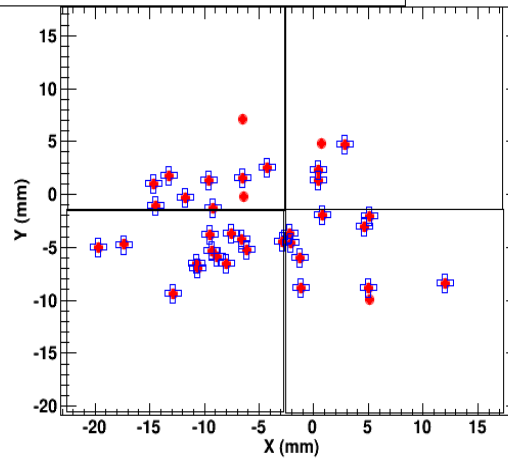
- $R_{\text{trigger}} \sim 5 \text{ kHz}$, Evt 15879, $N_{\text{rec tracks}} = 33$
- Tracking only with SALAT planes (Mod-8,16,11). Planes 1 and 2 are DUT

Run 28847 Event 15879

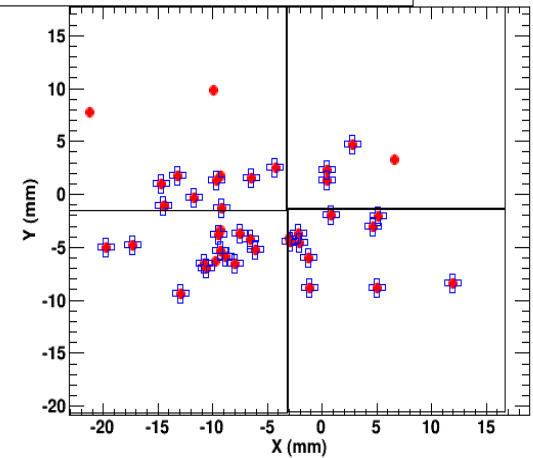
Hit map Telescope on SALAT mod-8



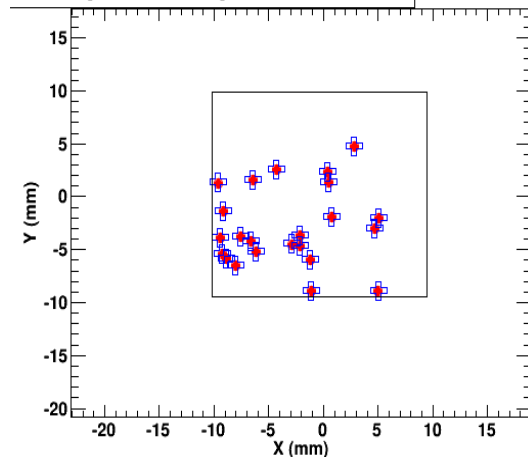
Hit map Telescope on SALAT mod-16



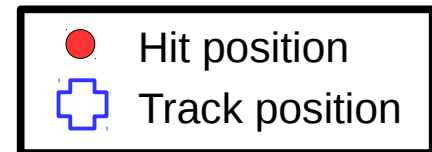
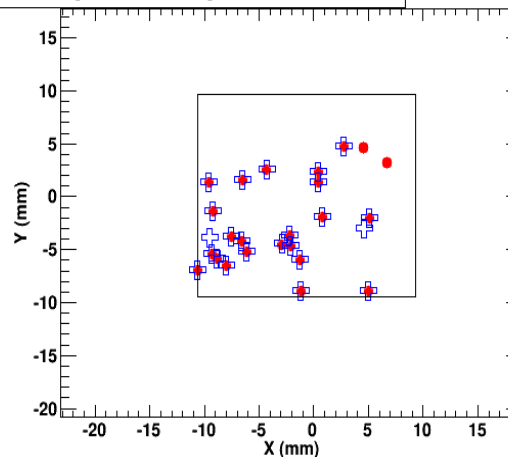
Hit map Telescope on SALAT mod-11



Hit map Telescope on Plane 1



Hit map Telescope on Plane 2

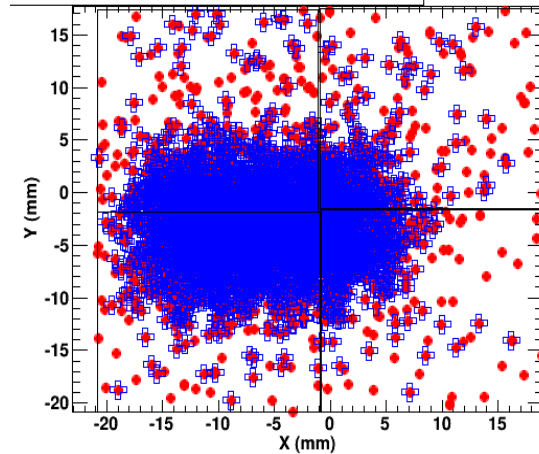


Telescope with SALAT modules: Multi-tracking

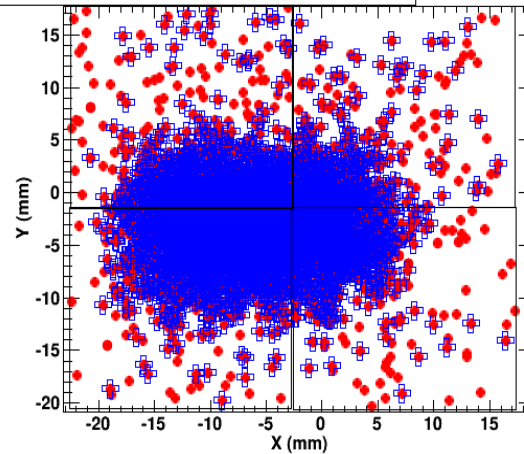
- $R_{\text{trigger}} \sim 50 \text{ kHz}$, Evt 25, $N_{\text{rec}} \text{ tracks} = 1372$
- Tracking only with SALAT planes (Mod-8,16,11). Planes 1 and 2 are DUT

Run 28848 Event 25

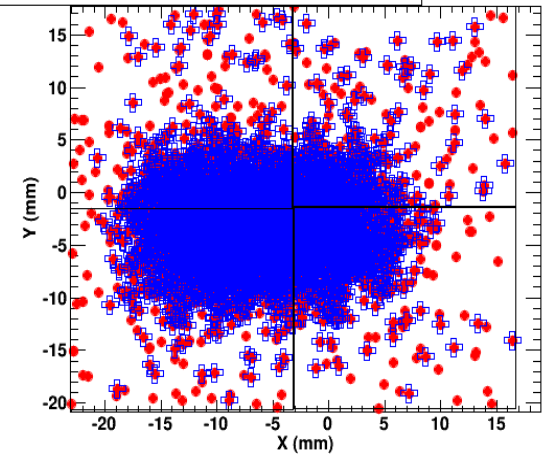
Hit map Telescope on SALAT mod-8



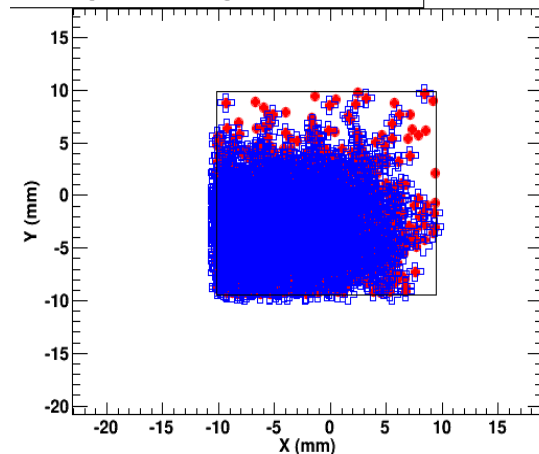
Hit map Telescope on SALAT mod-16



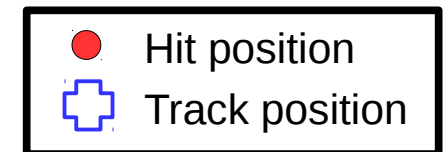
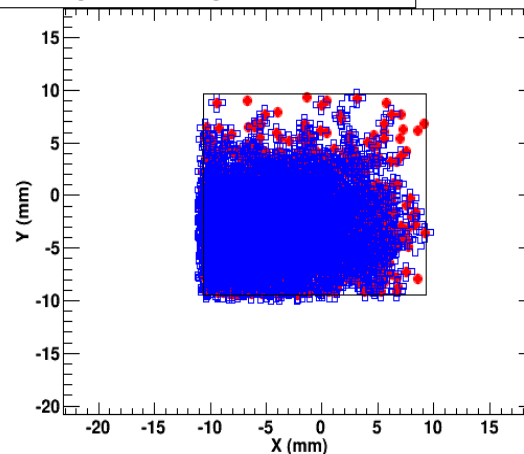
Hit map Telescope on SALAT mod-11



Hit map Telescope on Plane 1



Hit map Telescope on Plane 2

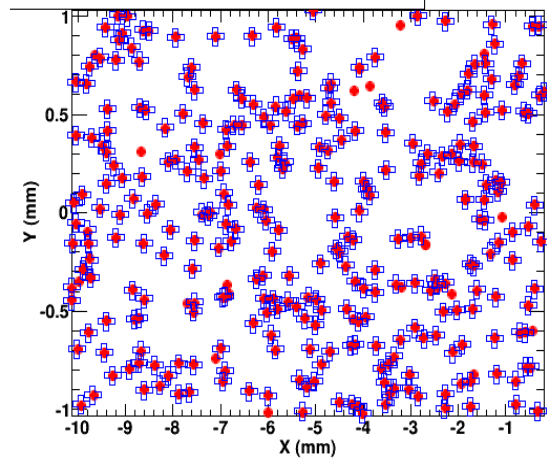


Telescope with SALAT modules: Multi-tracking

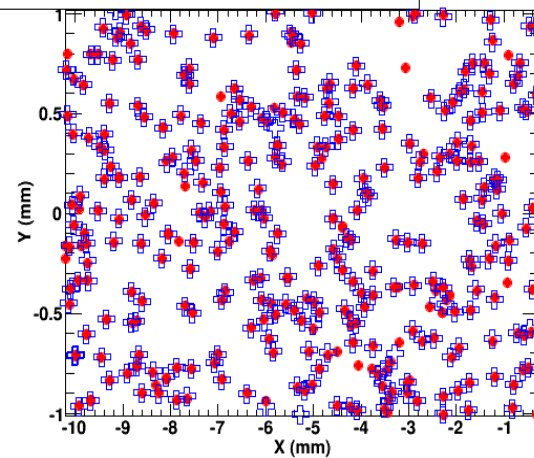
- $R_{\text{trigger}} \sim 50 \text{ kHz}$, Evt 25, $N_{\text{rec tracks}} = 1372$
- Tracking only with SALAT planes (Mod-8,16,11). Planes 1 and 2 are DUT

Run 28848 Event 25

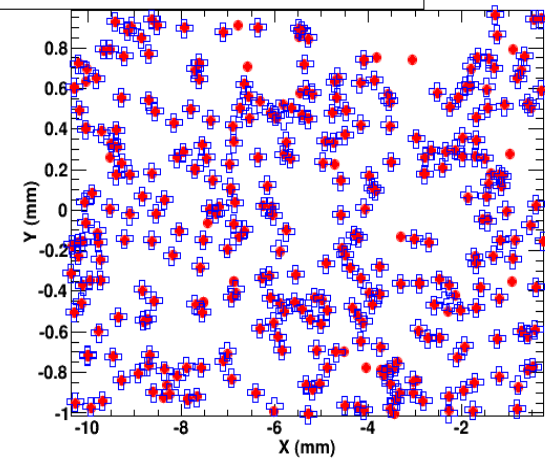
Hit map Telescope on SALAT mod-8



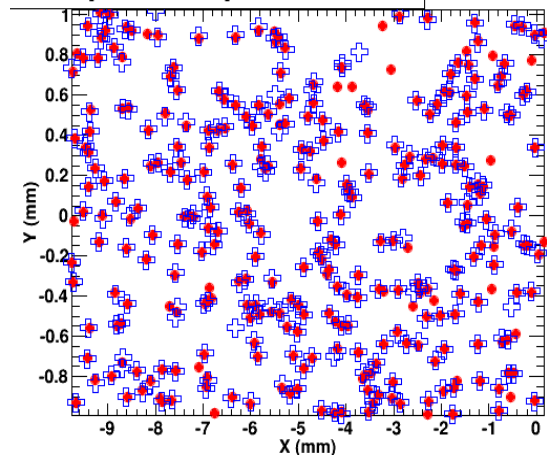
Hit map Telescope on SALAT mod-16



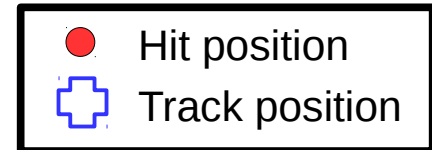
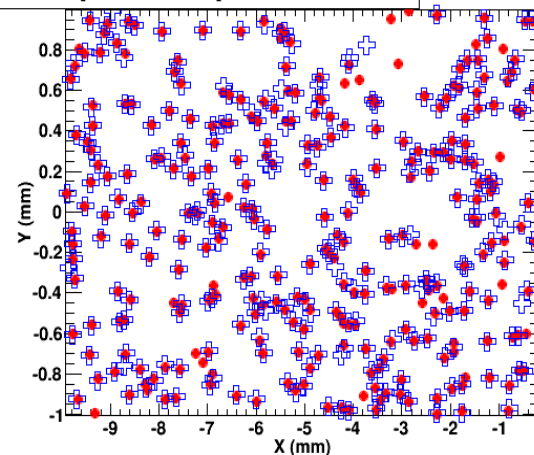
Hit map Telescope on SALAT mod-11



Hit map Telescope on Plane 1



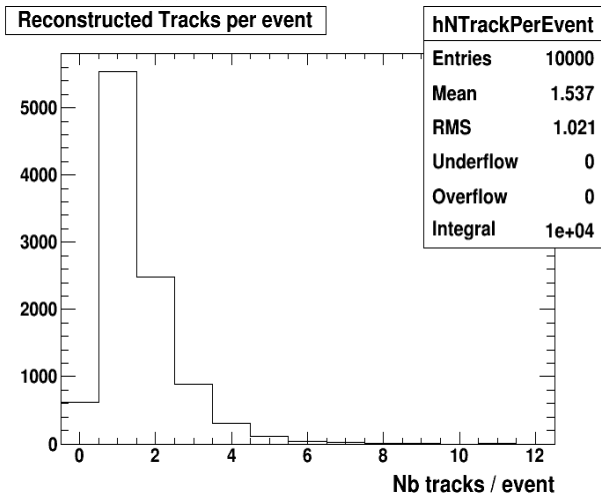
Hit map Telescope on Plane 2



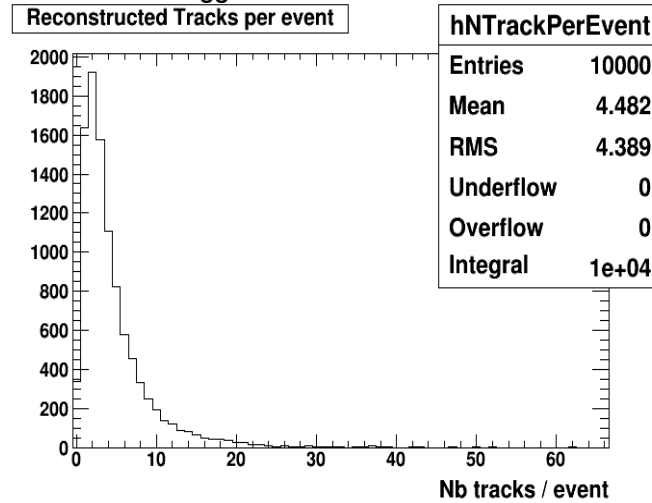
Telescope with SALAT modules: Multi-tracking

Mi-28 integration time = $200\mu\text{s}$ \Rightarrow readout rate of 5kHz

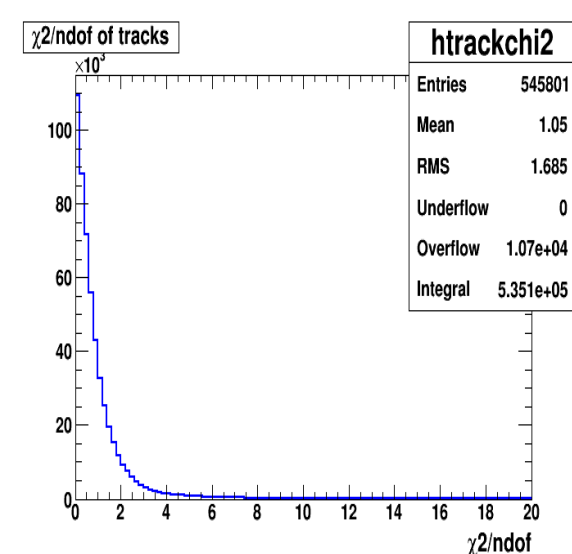
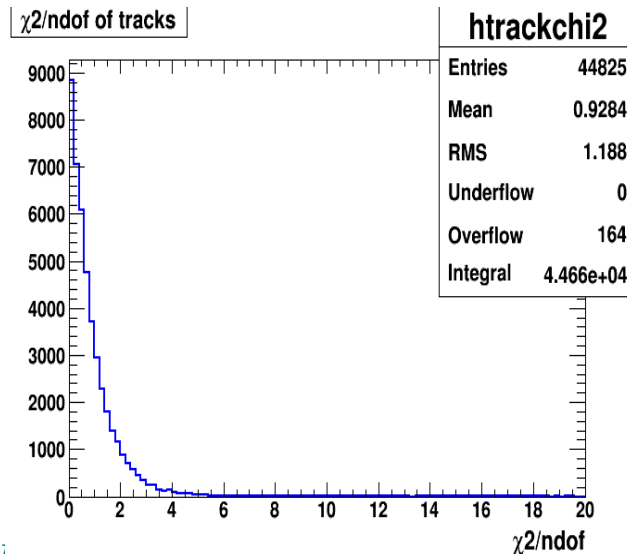
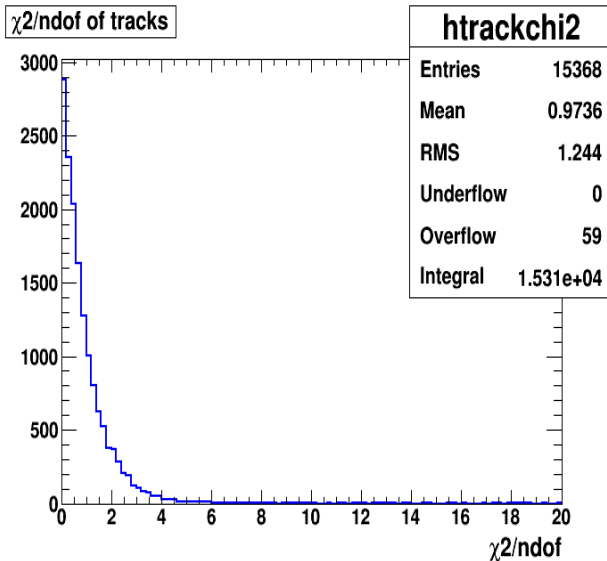
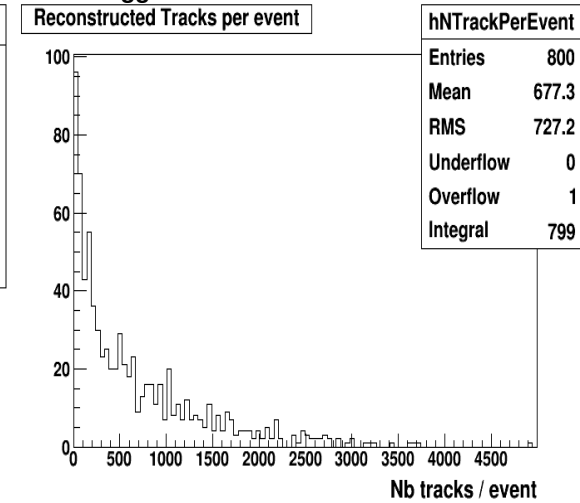
$R_{\text{trigger}} \sim 1 \text{ kHz (} / 1\text{cm}^2)$



$R_{\text{trigger}} \sim 5 \text{ kHz (} / 1\text{cm}^2)$



$R_{\text{trigger}} \sim 50 \text{ kHz (} / 1\text{cm}^2)$

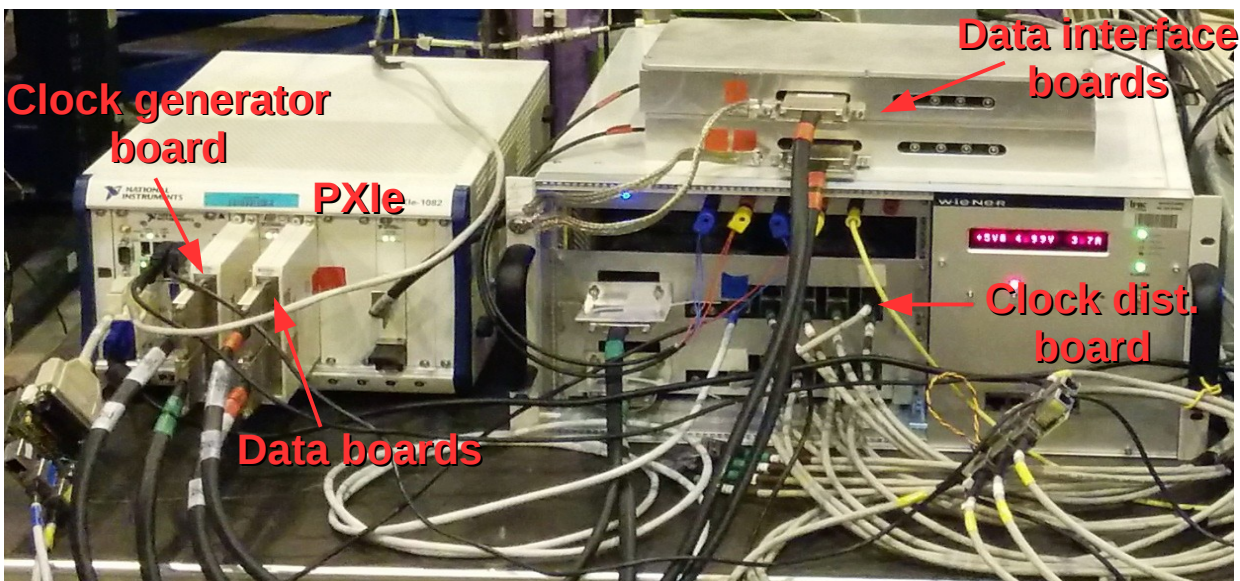
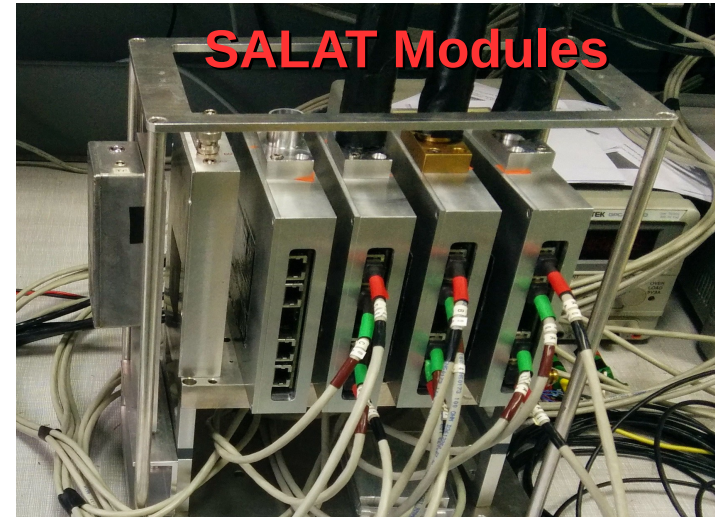


SALAT Delivery

SALAT Deliveries

Possible delivery by the end of Jan. 2015: Hardware + Doc

- 4 (3 + 1 spare) operational modules characterized in beam at CERN in Nov. 2014
 - Mechanic support + PCBS (daughter + mother)
 - Beam test data analysis in advance stage⇒ final results for beginning 2015
- 2 Clock distribution + JTAG + data interface boards
- Documentation (board and SALAT characterizations)
- Details to be defined w.r.t. IPHC priorities emerging in the coming weeks

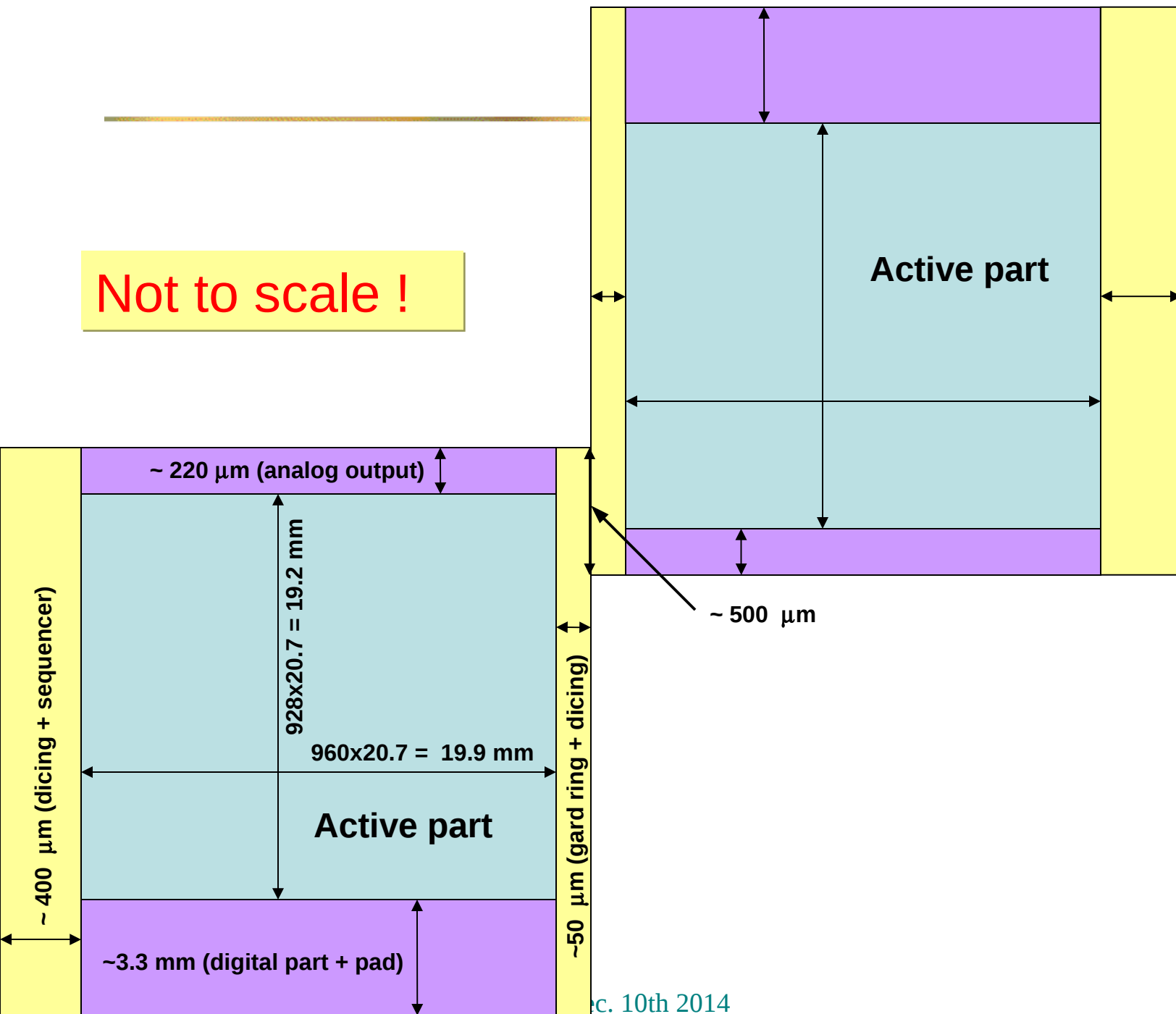


Summary

- **Large Area Telescope prototype produced at IPHC**
 - Based on very mature sensors (MIMOSA-28) already used in STAR
 - Full development of Integration, mechanics and DAQ
 - SALAT plane validation @ DESY and CERN-SPS
 - Still need to finish CERN beam-test data analysis ⇒ Full characterization of SALAT telescope
- **Deliveries**
 - 4 (3 + 1 spare) fully operation SALAT modules
 - Clock distribution + JTAG + data interface boards

Back up Slides

Not to scale !

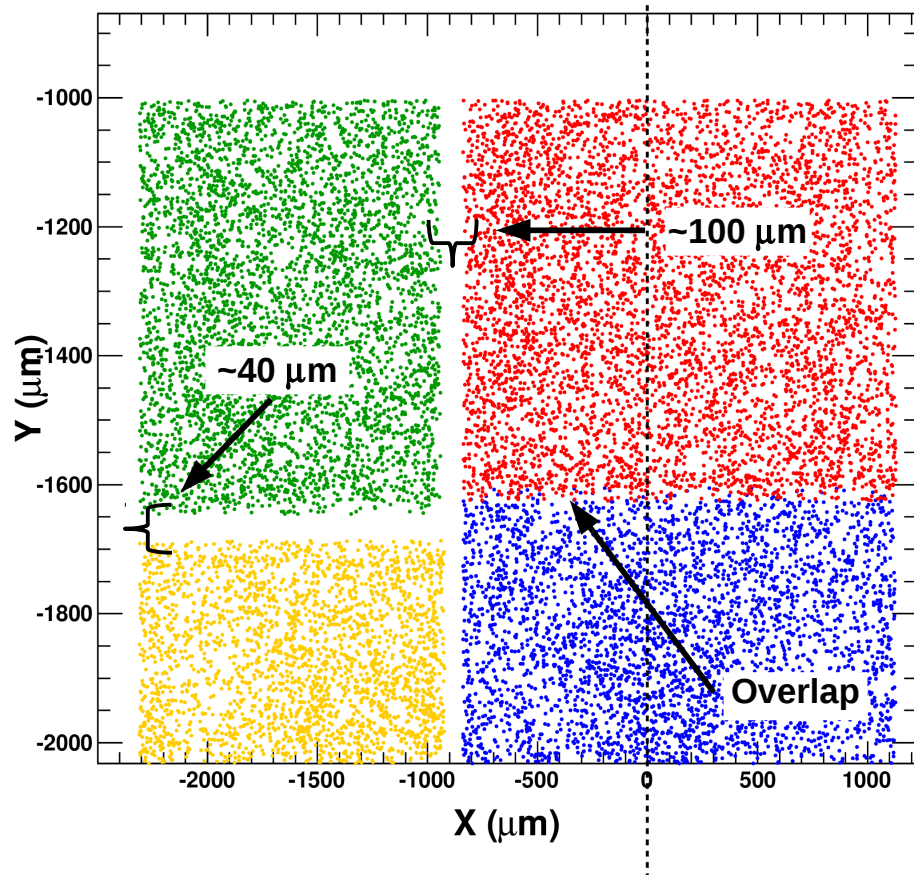


Relative Alignment of SALAT sensors: Insensitive Zones

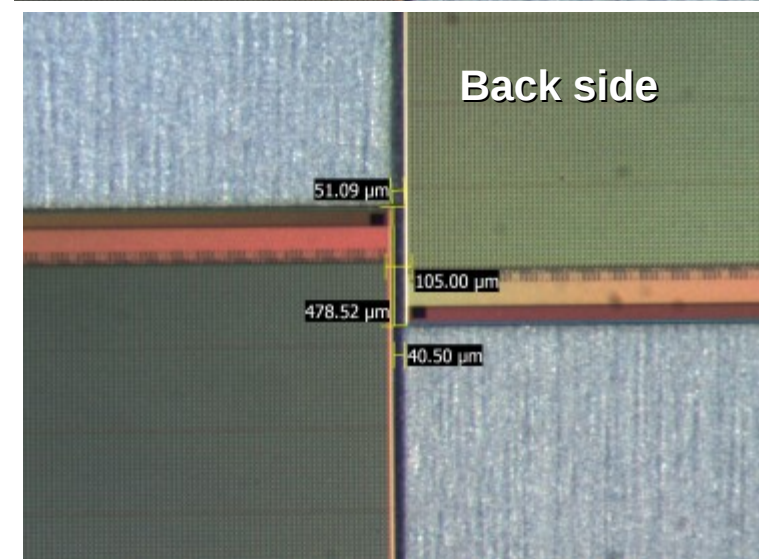
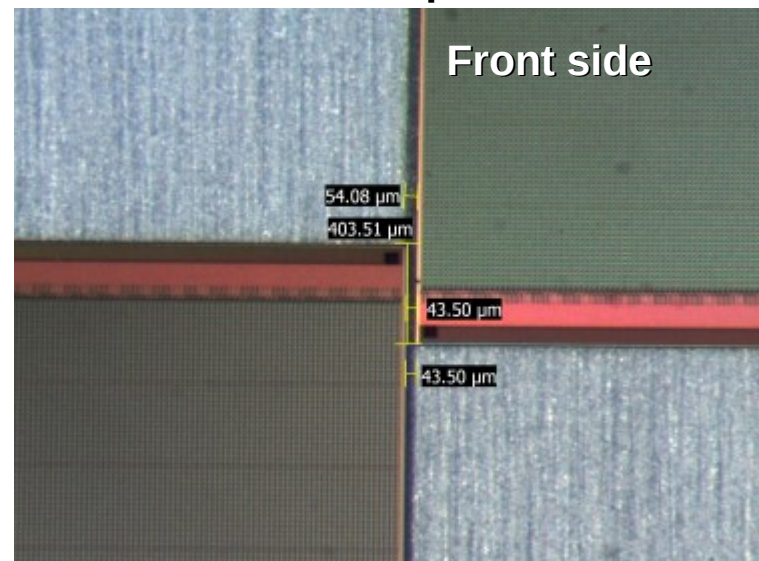
π^- beam 

Module 11

Hit associated to Track Map



Visual inspection

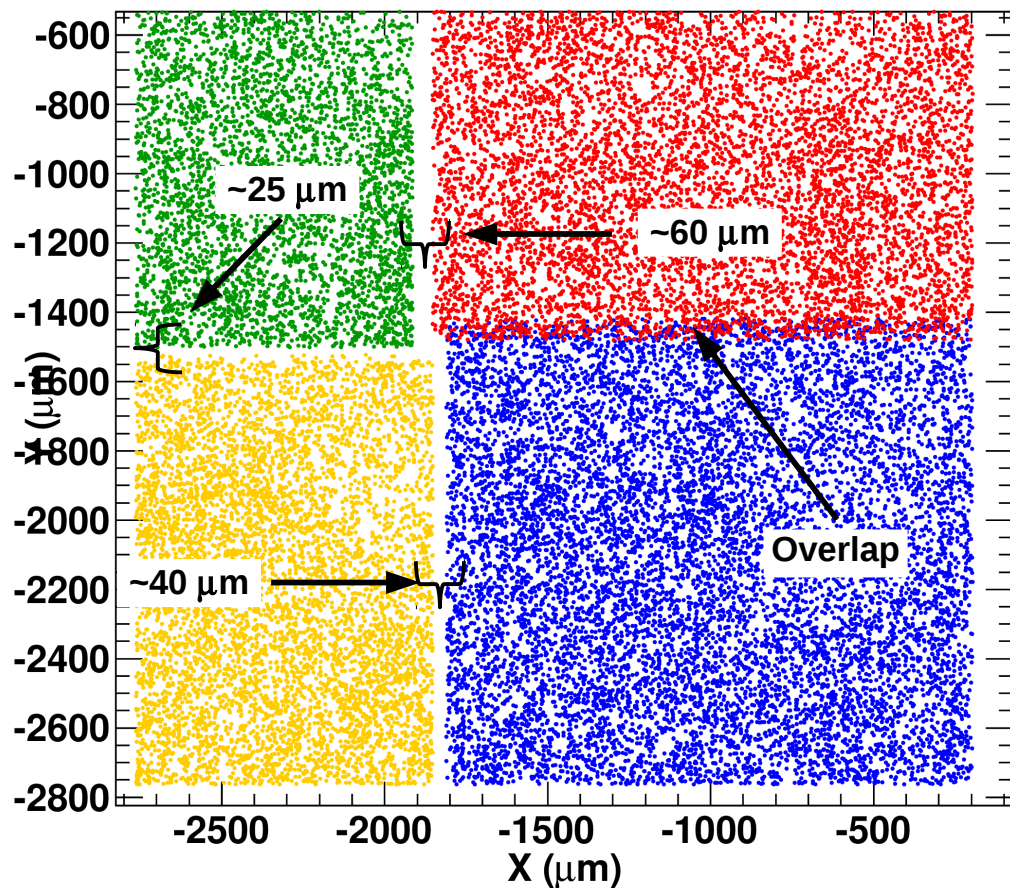


Relative Alignment of SALAT sensors: Insensitive Zones

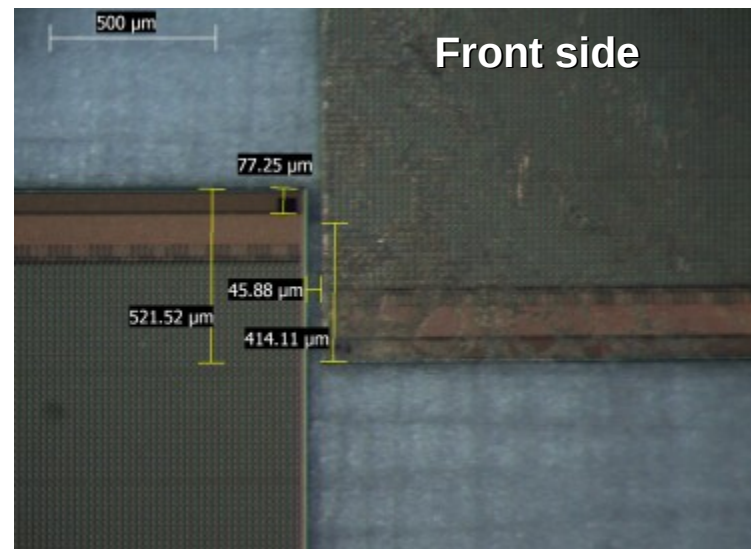
π^- beam 

Module 15

Hit associated to Track Map



Visual inspection



SALAT Deliveries

■ Possible delivery by the end of Jan. 2015: Hardware + Doc.

- 4 operational modules characterized in beam at CERN in Nov. 2014
 - Mechanic support + PCBS (daughter + mother)
 - Beam test data analysis in advance stage \Rightarrow final results for beginning 2015
- SALAT planes power supply board
- 1 JTAG auxiliary board + 1 JTAG distribution board + 2 Clock distribution boards
- 2 Data boards \Rightarrow RJ45 to VHDCI converter (1 board = 8 x Mi28 max)
- Documentation (board and SALAT plane characterizations)
- Details to be defined w.r.t. IPHC priorities emerging in the coming weeks

SALAT Deliveries

■ Possible delivery by the end of Apr. 2015: Hardware + DAQ

- To be confirmed at the beginning 2015 (**depending on IPHC priorities**)
 - Hardware (as in previous point)
 - Code source software ⇒ **to be interfaced to with EUDET framework**
 - Code source firmware
- Procedure ⇒ **Expected delivery by April 2015**
 - **DESY provides PXIe crates (CPU + 2 FlexRio + NI6562 boards + Raid interface board) and send it to IPHC ASAP**
 - Setup of all system at IPHC in April 2015 with Hendrik Jansen