WP9.3 AIDA Testbeam Telescope Offline Software

Eda Yildirim for the developers team AIDA Final Meeting CERN, 9-11 December 2014

Core developers

DESY:	Denys Lontkovsky (ZEUS), Alex Morton (ATLAS),
	Hanno Perrey (CMS), Igor Rubinskiy (ATLAS)
	Many thanks to Claus Kleinwort
Uni Goettingen:	Tobias Bisanz (ATLAS)

Many contributors from the R&D community

Nightly builds monitoring: Strip detectors integration: Geant4 simulations:

Various topics:



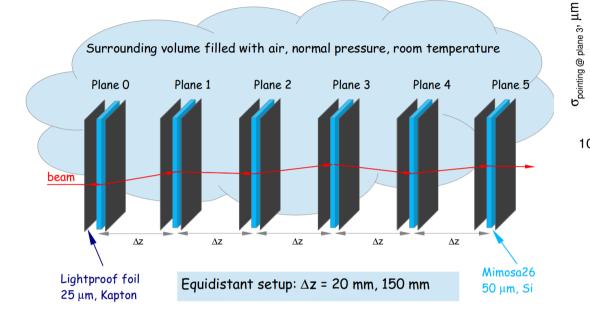
- DESY Philipp Hamnet (ATLAS), Thomas Eichorn(CMS), Simon Spannagel (CMS)
- DESY Yuri Soloviev (Belle II)
- DESY Eda Yildirim (ATLAS)
- CERN John Idarraga (NASA), Mathieu Benoit (CLICpix)

many users from Bellell, ATLAS, CMS, CLICpix, and R&D projects





EUDET/AIDA pixel beam telescope, tracking precision



The interplay between

- the telescope detector resolution, ٠
- multiple scattering, •
- distance between telescope planes ٠
- distance to the DUT (track fit "passive" plane) and their impact on alignment and tracking are well understood.

In many cases the R&D groups revise their DUT mechanics to get optimal track pointing precision on the DUT

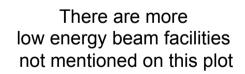


SLAC

DESY

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(beam momentum) p, GeV

 10^{2}

Equidistant telescope setup

plane #3 is treated as DUT

distance between the planes:

Mimosa26 intrinsic resolution 3.8 µm

tracking with 5 planes

∆z= 10 mm ∆z= 20 mm $\Delta z = 40 \text{ mm}$

 $\Delta z = 150 \text{ mm}$

CERN.

FNAL

Preliminary // work in progress.

10



 10^{3}

Software: Offline reconstruction

Over the four years of the AIDA project the EUTelescope library (part of the ILCSoft package for testbeam tracking) has undergone a major revision:

Code refactoring:

- Removed obsolete code (out of 150 k lines of code!)
- compile time warnings strongly reduced
- consistent approach to the messages (errors, warnings, info levels)
- code comments

Redesign:

- New geometry layout of the telescope setup (still with ILCSoft Gear)
- Navigation between sensitive and non sensitive layers with new class EUTelGeometry based on ROOT::TGeo
- Revised basic element class EUTelGenericPixel (fits also strips)
- Clustering in non-standard pixel detectors with EUTelGeo (for L-type pixels, honeycomb, etc.)
- Pattern Recognition, Alignment, Tracking with GBL+Millepede II libraries
- allows dead material layers and B-field presence
- Added one more package: Allpix for pixel/strip detectors digitisation models validation
- Well defined Examples
 - Introduced examples with reference data: Telescope only data, and with DUTs. Shows how the data processing flow should take place.

Nightly builds

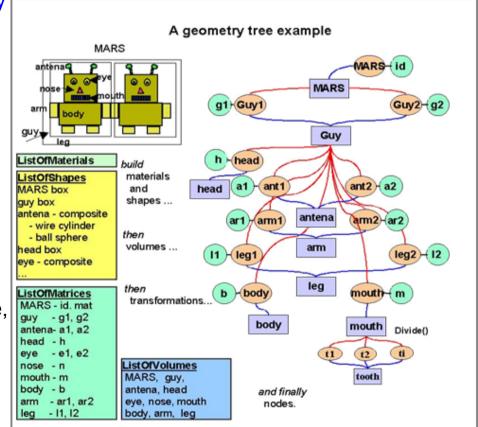
- For all examples nightly build tests are running and displayed with Aidasoft/Cdash, we get emails every morning about (un)successful changes to the repository
- GitHub: Decentralized repository and version control
 - Improves branching, tagging, interaction between developers by really a lot (same for EUDAQ)



... pixel beam telescope ° R&D Tracker, Offline Software 1/2

Reconstruction Software EUTelescope highlights

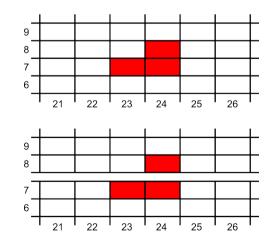
- based on ILCSoft/Marlin framework and LCIO data format
- generic implementation of data processing: clustering, alignment, tracking
- new implementation of the telescope geometry
 - relies on ROOT::TGeo as major construction block and benefits from built-in methods:
- new generic clustering algorithm
 - (TGeo neighbor search)
 - allowing generic pixel shapes
- navigation from one volume to next one:
 - fetch next volume ID
 - by global 3D point coordinate
 - Track incidence with next volume surface,
 - Track direction tilt to the volume surface
- coordinate system transformation
 - Global frame ↔ Local Measurement

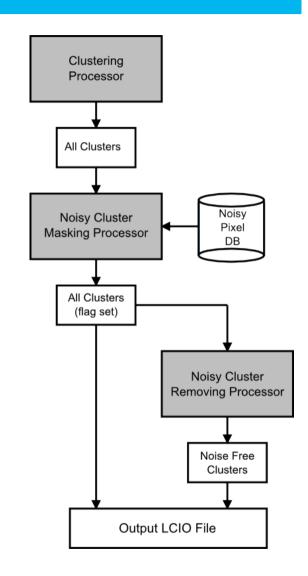




Updated Geometry Framework and New Noise Treatment

- Updated geometry framework
 - extends/replaces GEAR
 - based on ROOT's Tgeo
- Allows for more sophisticated pixel layouts
 - prolonged pixels (e.g. ATLAS pixel 4-chip modules)
 - staggered pixels
- New noise treatment scheme
 - more LCIO like
 - new processors for finding noisy pixels
 - and masking/removing them
- > New processor for geomtry based clustering:





... pixel beam telescope ° R&D Tracker, Offline Software 2/2

Reconstruction Software highlights (continues)

- General Broken Lines (GBL) for tracking and alignment via Millepede-II
 - implementation benefits a lot from new Geometry model
 - with new Geometry accurate description of all inactive material
 - more realistic Chi2 of the tracks for low energy beam
 - X0 map of the DUT

The result of the track fit now is a collection of track points (hits) on every scattering plane. Every track point contains X,Y (local, module frame) and incidence angle to the volume surface normal

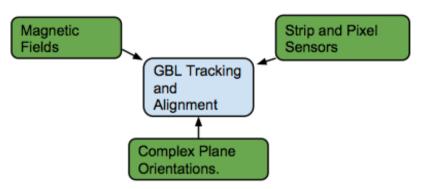
→ basically this is all we want to know about a track at DUT surface to match Cluster info.

Free way towards grazing angle test beams (high interest from RD50, ATLAS) And Lorentz Angle measurements for highly irradiated detectors (ATLAS, CMS)



Requirements from Tracking and Alignment

> Many interesting studies require a versatile track fitter and alignment procedure.



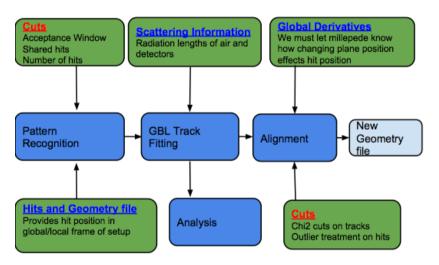
You want a single track fitter and alignment procedure to allow easy analysis of any test beam data.

- > We want to design software which is as plug and play as possible.
- > Allows a single analysis code to be written once for a multiple setups and DUTs.
- > Use past analyses as an example for future work.
- To achieve all these goals we use a combination of the General Broken Lines (GBL) for track fitting and millepede 2 to align the mimosa and DUT planes.
 - You can run a simple example after installing the EUTelescope software within jobsub/examples/GBL and following the README file.



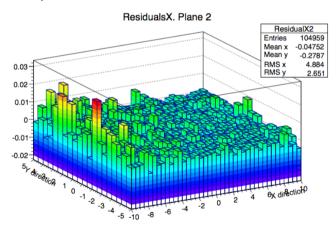
Tracking and Alignment

- > The GBL algorithm needs many input parameters to have the optimum track fit.
- > Pattern recognition based on predicted kinematics of beam particles provide hits to fit track



How the pattern recognition, GBL and alignment processors function together.

Certain input parameters are needed to find the correct tracks from a collection of hits on a series of planes. We must align before we do this. We use GBL tracks to align in steps. Each step producing a new geometry file and repeating process until we have aligned the planes. The final tracks can easily be used in some final analysis.



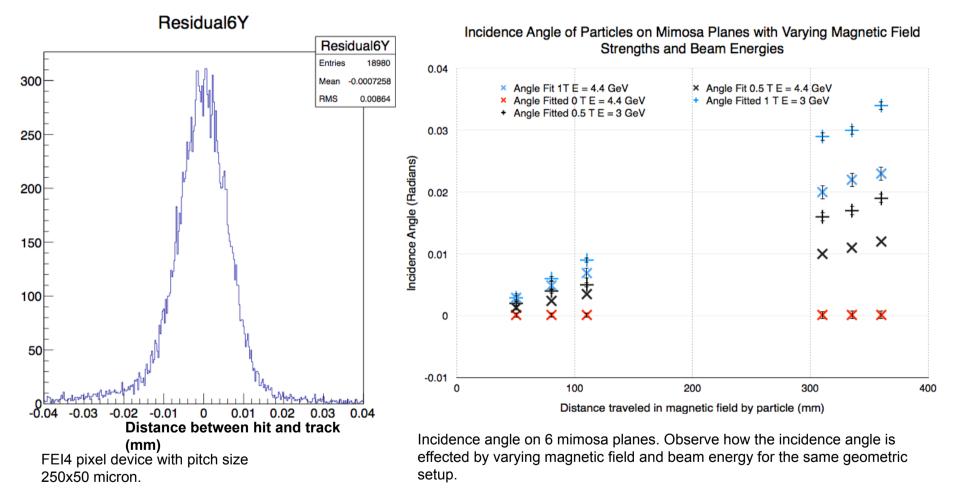
 Analysis code will work for any DUT using tracks produced by GBL processors.

> We can look at how residual of tracks varies with position on sensor. This example is one of the mimosa sensors with residual in X direction.



The GBL Track Fitting and Alignment in Action

> The fitting and alignment procedure has been used with DUTs and magnetic fields.

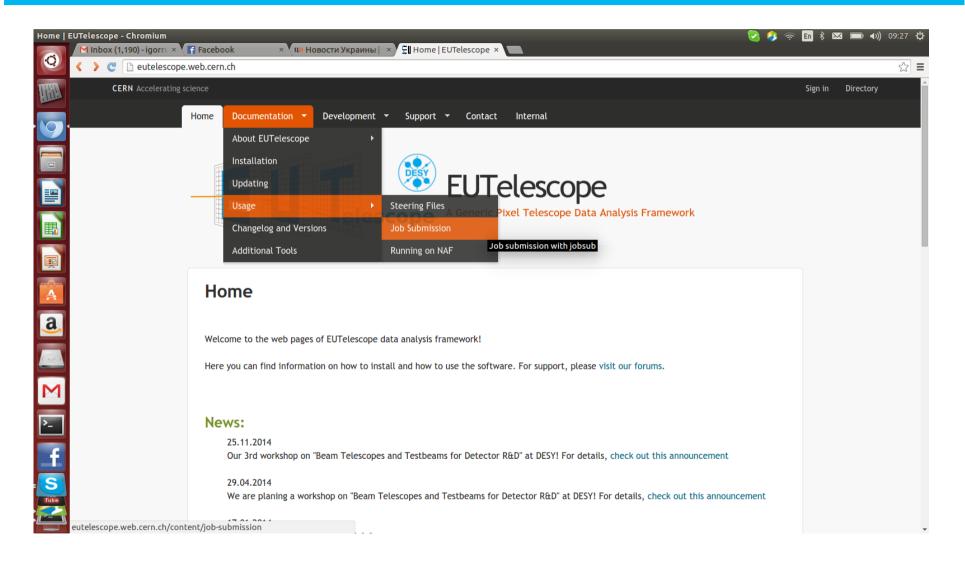


- > Software completed to work with strip sensors and tilted sensors
 - Testing still ongoing.



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Github – decentralized code development, and version control

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Github – decentralized code development, and version control

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Aidasoft / Cdash – nightly builds monitoring

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Aidasoft / Cdash – nightly builds monitoring

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Aidasoft / Cdash – nightly builds monitoring \rightarrow link to the latest build

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Workshop on "Beam Telescopes and Test beams for Detector R&D"From:19 January 2015To:21 January 2015DESY Hamburg

Experienced and non-experienced testbeamers are welcome to participate and contribute

Integration into existing and future telescopes

- Introduction to EUDET-family of telescopes and how to integrate
- The future AIDA pixel beam telescope
- Integration/usage by example: Telescope user's success stories
 How to build your own beam telescope

- Experience from EUDET, TimePix(3), CMS Pixel and others Developments for a common infrastructure and available tools

- cooling, powering, remote control, monitoring, rapid prototyping
 Features of and experiences with the different available beam lines

- DESY TB21-24, CERN, SLAC, low energy beams

Testbeam data analysis tools

Tracking and Alignment

Examples of interesting/challenging integrations and testbeam data analyzes Simulation of pixel devices and their behavior in a testbeam

- TCAD, Geant4, ...
- alternative tools/write your own

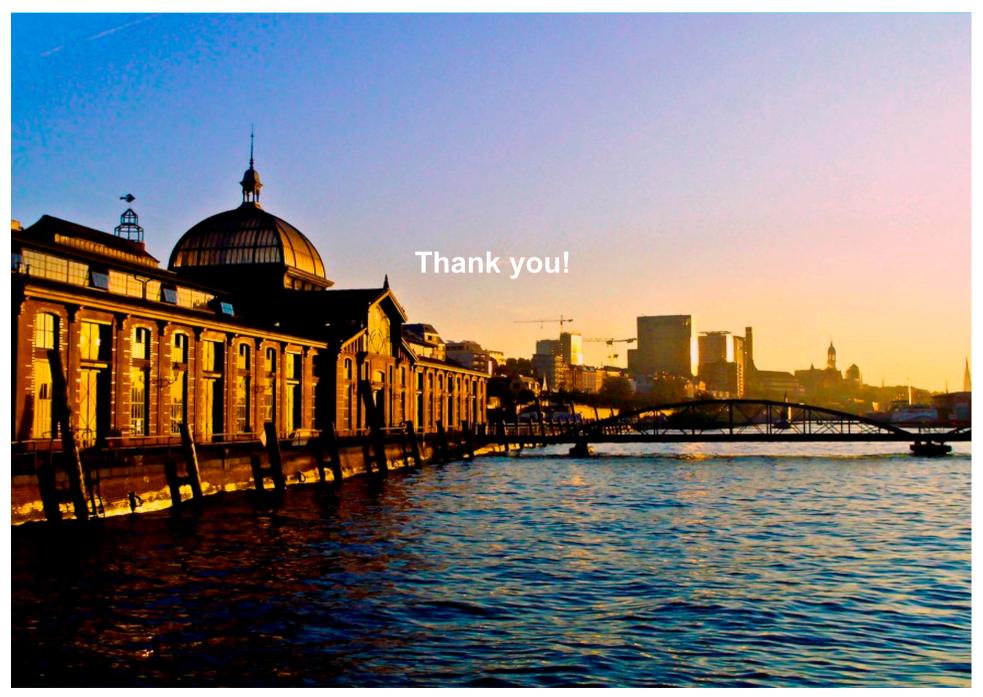
Tutorials

- Data analysis with EUTelescope
- Alignment Tips and Tricks
- other tools

https://indico.desy.de/conferenceDisplay.py?ovw=True&confld=10685

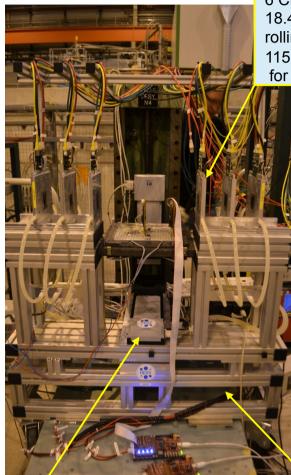


Full three days now!

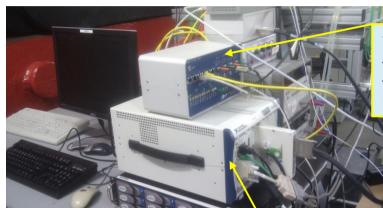




EUDET pixel beam telescope = high resolution R&D Tracker



6 CMOS pixel detectors (IPHC Strasbourg): Mimosa26 thinned₂to **50 µm thickness** 18.4 x 18.4 µm \rightarrow 1152 columns x 576 rows (2x1 cm) rolling shutter = continuous readout = deadtime free 115.2 µs integration time/frame \rightarrow 8.68 kFrames in 1 second for *always* sensitive telescope planes



Trigger Logic Unit (TLU): – 4 inputs from PMTs – trigger/busy handshake to connect up to 6 DAQ systems

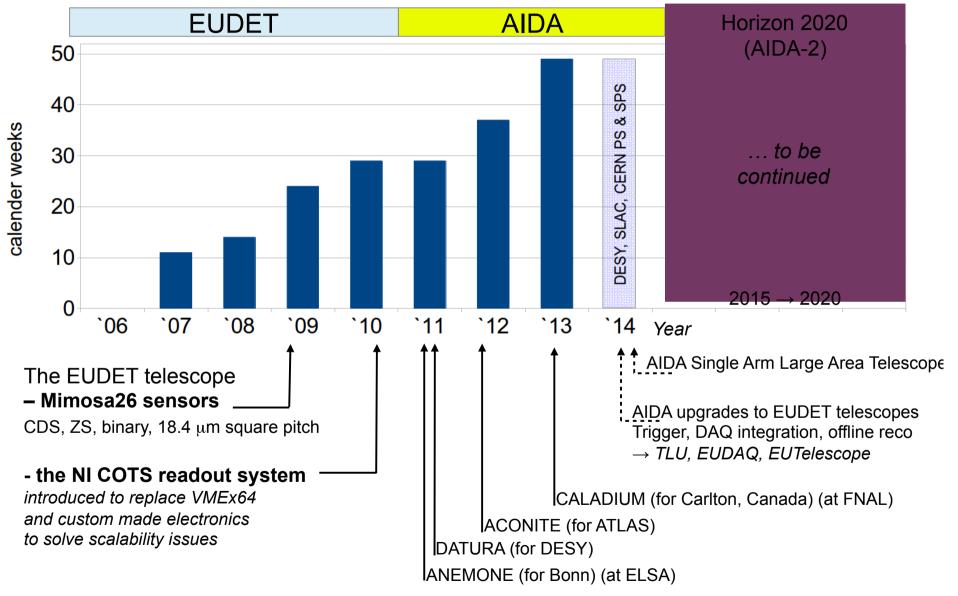
Mechanical support based on rigid Al profiles ~1 µm precision rotation in horizontal plane (µ- screw) COTS National Instruments Flex RIO (Vertex-5 FPGA) based solution for Mimosa26=1x2 cm2 (<20 MB/s)

Immediate writing on RAID

Device Under Test (DUT) with precise XY/rotation stage

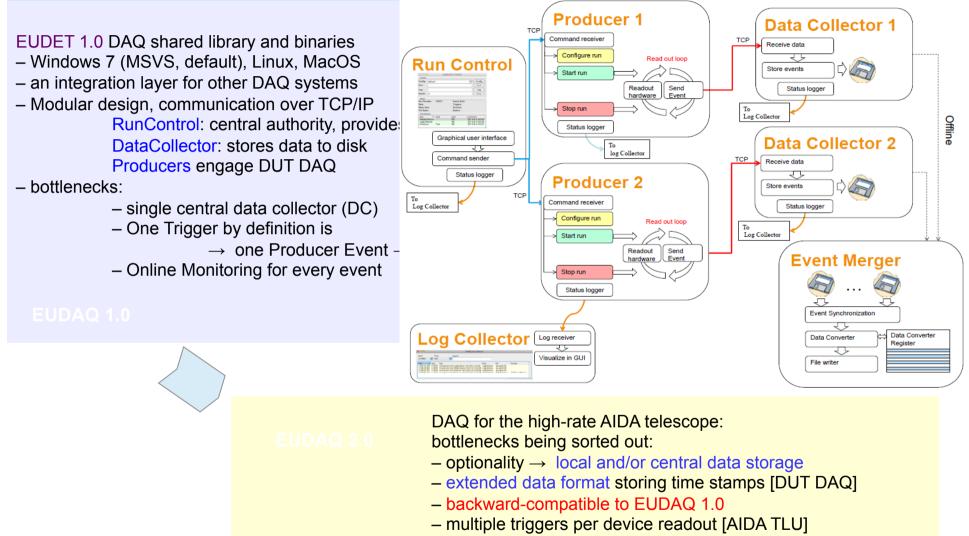
The DAQ components interact via Hard & Soft layers → miniTLU and **EUDAQ2** Data reconstruction within ILCSoft/Marlin/ **EUTelescope**

EUDET/AIDA telescope demand over the years





... pixel beam telescope = R&D Tracker, DAQ https://twiki.cern.ch/twiki/pub/MimosaTelescope/EUDAQ/EUDET-Memo-2010-01.pdf



- more flexible online verification and monitoring

