



# Introduction to seismic sensors

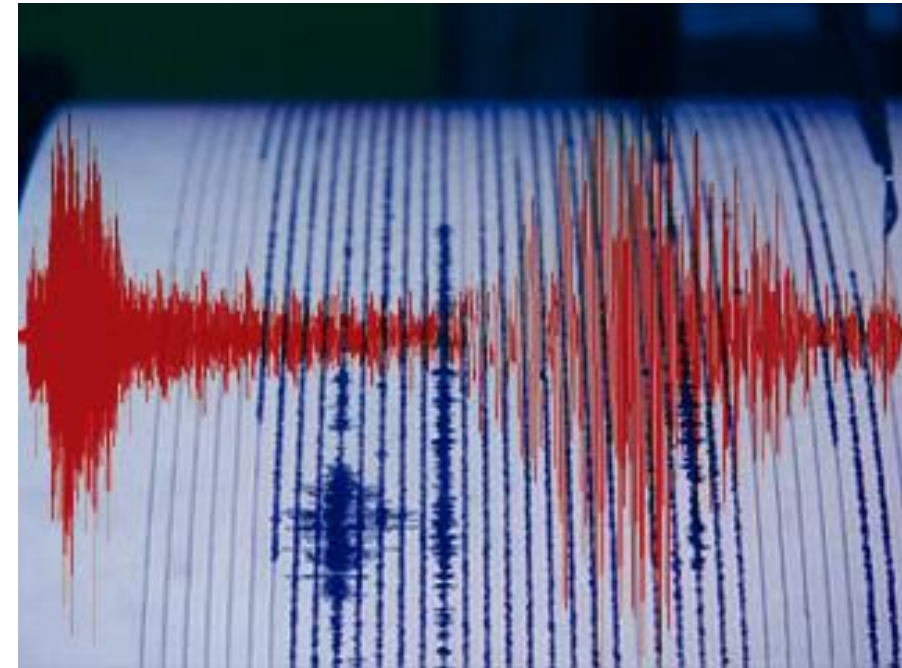
(subject 3.2)

Peter Novotny

PACMAN meeting, CERN, 7 October 2014



# What is seismic sensor?



Instrument which measures **ground motion**.

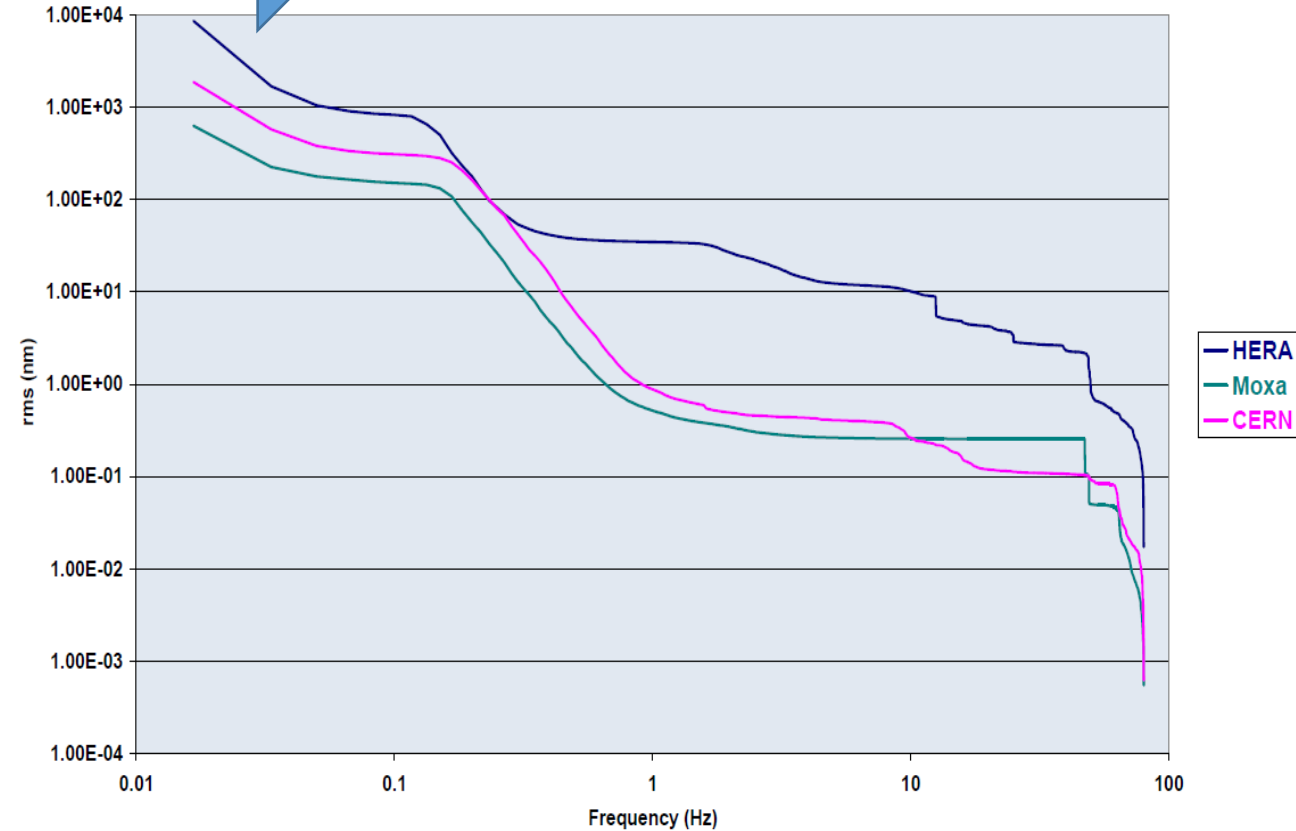
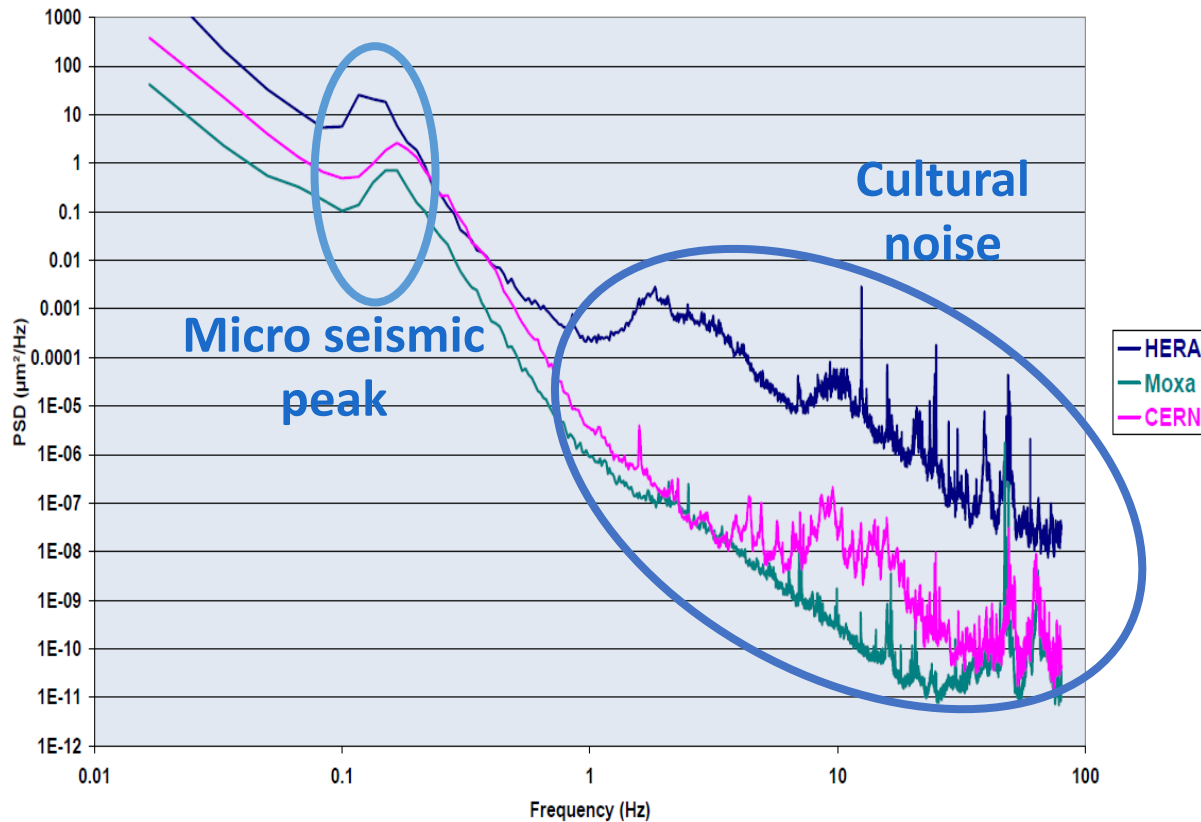
(Not only earthquakes!)

# Ground Motion in frequency domain

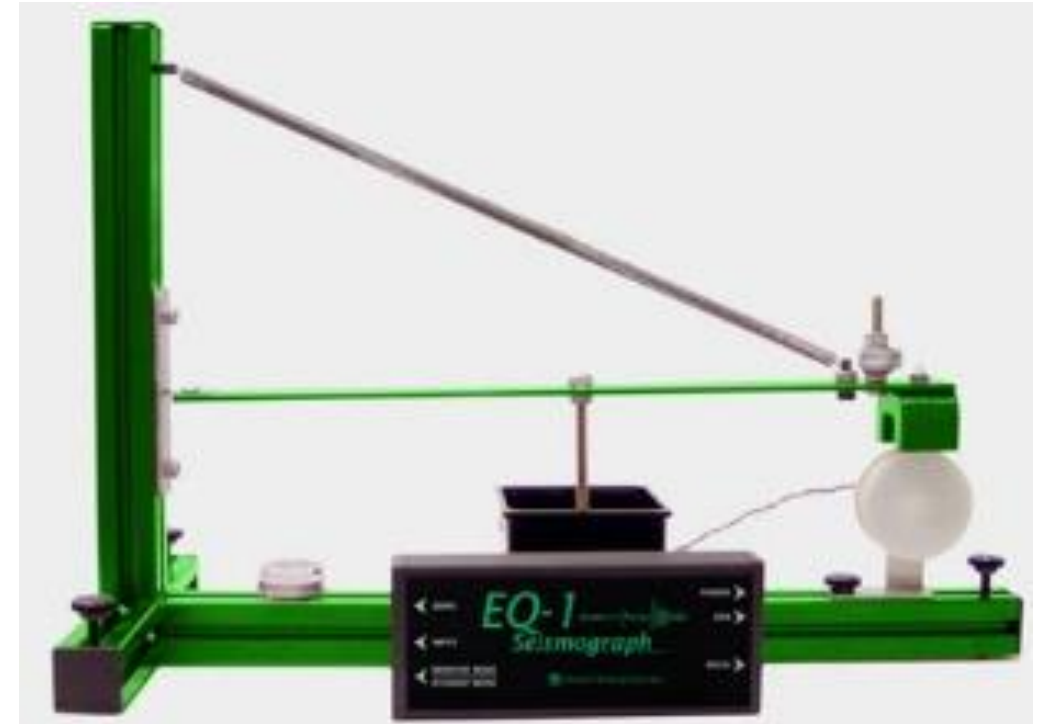
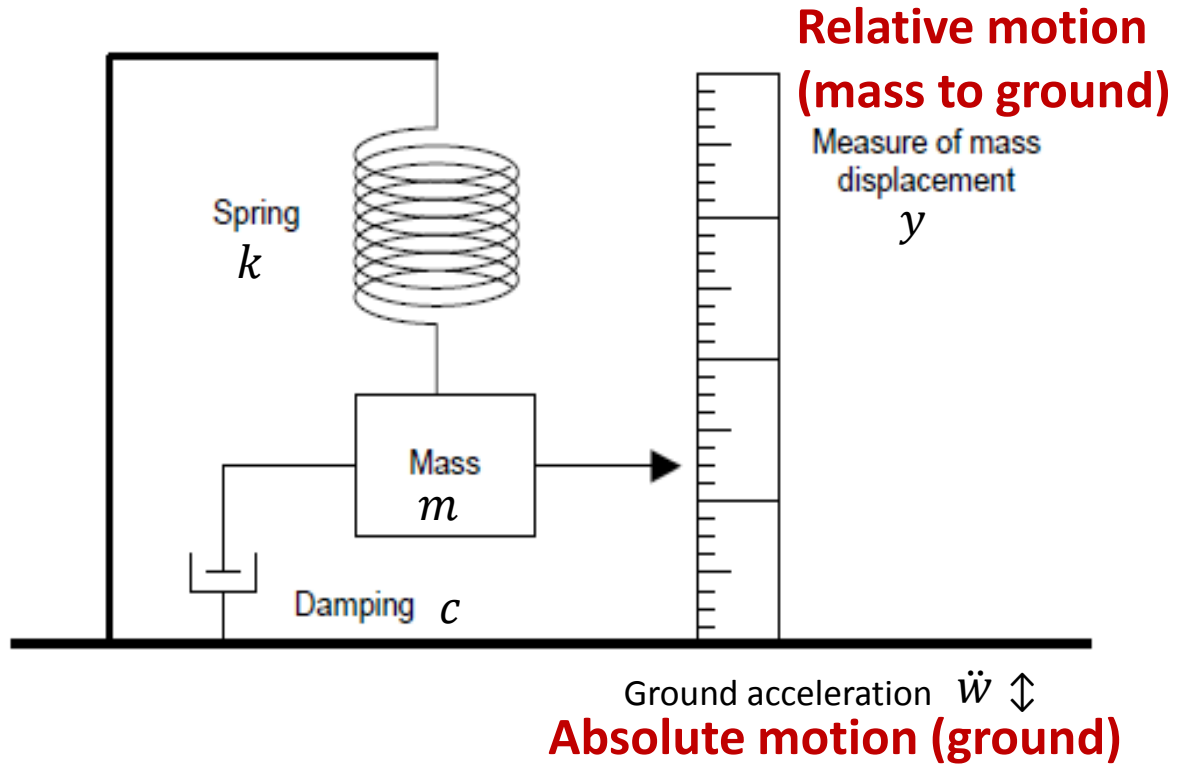
Power Spectral Density – PSD  
of ground motion

$$RMS\ motion = \sqrt{\int_{f_1}^{f_2} \left[ \frac{Amp(f)}{\sqrt{Hz}} \right]^2 df}$$

RMS of ground motion



# How does seismic sensor work?



Dynamic described by 2<sup>nd</sup> Newton's law => Forced damped harmonic oscillator.

$$m\ddot{y} + c\dot{y} + ky = -m\ddot{w}$$



# How does seismic sensor work?



Transfer functions:

Laplace transform

$$m\ddot{y} + c\dot{y} + ky = -m\ddot{w}$$

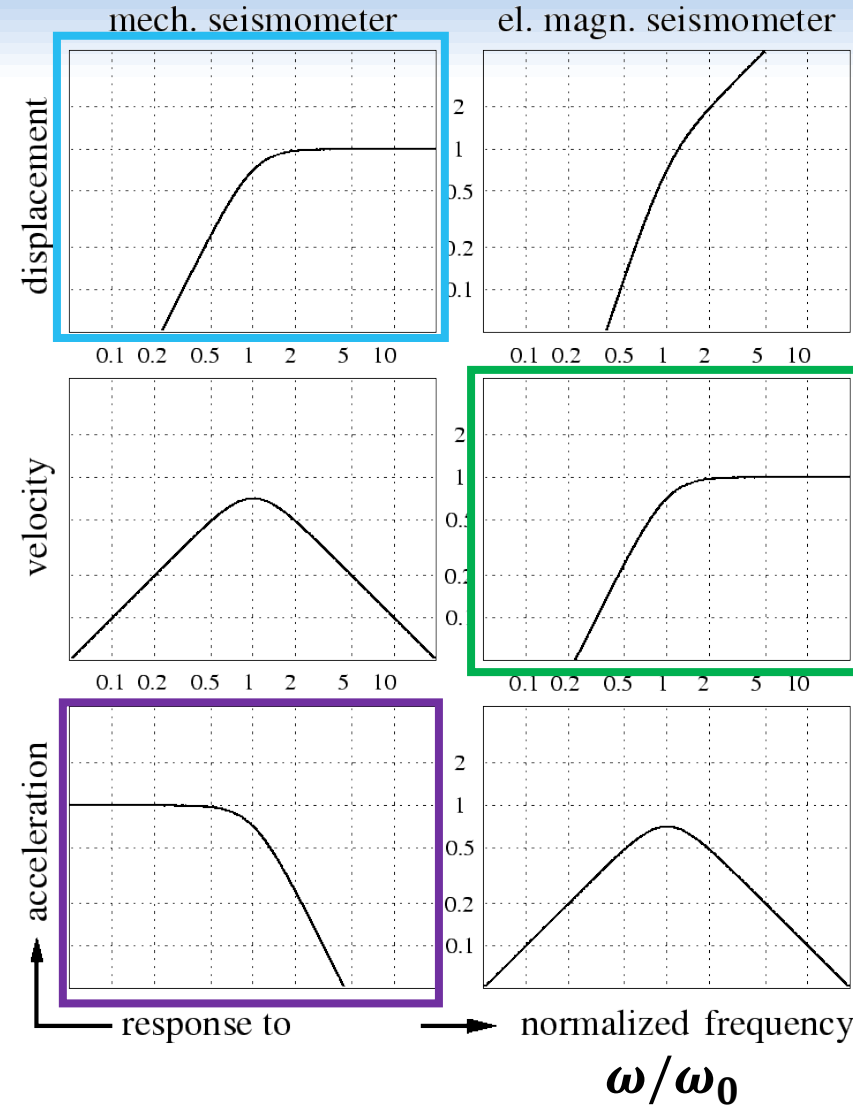
Natural frequency

$$\omega_0 = \sqrt{\frac{k}{m}}$$

$$T_{wy} = \frac{Y}{W} = \frac{\text{relative displacement}}{\text{absolute displacement}}$$

$$T_{\dot{w}y} = \frac{\dot{Y}}{\dot{W}} = \frac{\text{relative velocity}}{\text{absolute velocity}}$$

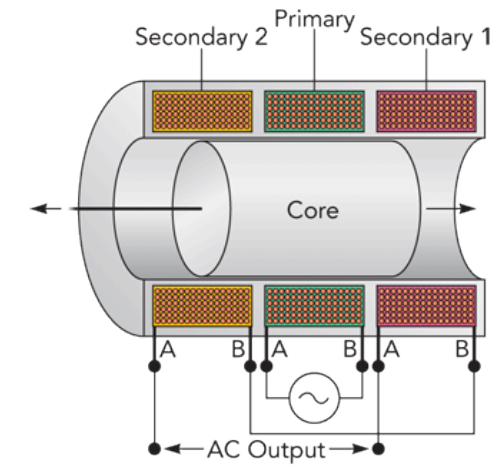
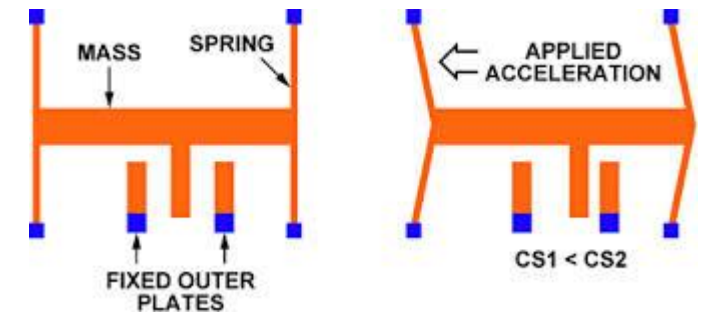
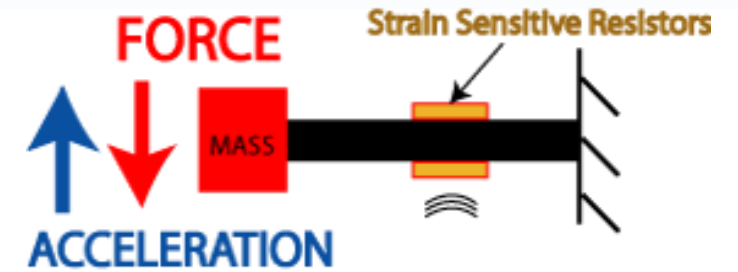
$$T_{\ddot{w}y} = \frac{Y}{\ddot{W}} = \frac{\text{relative displacement}}{\text{absolute acceleration}}$$



!! Information about absolute motion is in **relative motion**!!

## Using different types of transducers:

- Pen (mechanical seismometers - obsolete)
- Resistive
- Capacitive
- Piezoelectric
- Optical (Interferometers, encoders)
- Inductive – coil + magnet
- Eddy current
- LVDT - Linear variable differential transformer
- ...





# Seismic sensor parameters




- **Bandwidth** –  $f_{min} - f_{max}$
- **Sensitivity  $S$**  – conversion factor from D,V,A to Volts
- **Self noise  $N$**  – determine resolution
- **Resolution  $R = S/N$**  – smallest measureable value
- **Dynamic range** – Max/Min measureable value
- **Active/passive** – need of power supply
- ...

Velocity output bandwidth	<i>1 s – 100 Hz (Model CMG-6T-1), 10 s – 100 Hz (Standard) or 30 s – 100 Hz</i>
Velocity output sensitivity	<i>2 × 1200 V/m/s, (Standard) 2 × 2000 V/m/s or 2 × 1000 V/m/s</i>
Peak output	<i>±10 V (20 V peak-to-peak)</i>
Optional high gain sensitivity	<i>2 × 10000 V/m/s (adjustable)</i>
Lowest spurious resonance	<i>450 Hz</i>
Linearity	<i>&gt; 90 dB</i>
Cross-axis rejection	<i>&gt; 65 dB</i>
Electronics noise level	<i>–172 dB (rel. 1m2s-4Hz-1)</i>
Operating temperature	<i>–40 to +75 °C</i>
Temperature sensitivity	<i>&lt; 0.6 V per 10 °C</i>
Mass recentring range	<i>±3 ° from horizontal</i>
Materials	<i>Hard anodised aluminium case Gold plated contacts O-ring seals throughout</i>
Case diameter	<i>154 mm</i>
Case height (with handle)	<i>207 mm</i>
Weight	<i>2.49 kg</i>
Power supply	<i>10 – 36 V DC</i>
Optional low power sensor	<i>5 V DC supply (output ±4.5 V)</i>
Current at 12 V DC	<i>38 mA</i>



# requirements on sensor



- Bandwidth = (0.1 – 100) Hz
- Resolution =  $\uparrow$  Sensitivity and  $\downarrow$  Self-noise
  - for  R = 0.1 $\mu$ m
  - for NANO STABILISATION R = 0.1nm
- Stray magnetic fields resistance
- Weight < few kg & compact size
- Temperature stability
- “Radiation resistance” => only for stabilisation
- Price  $\approx$  4000 sensors for CLIC
- ...





# Geophones

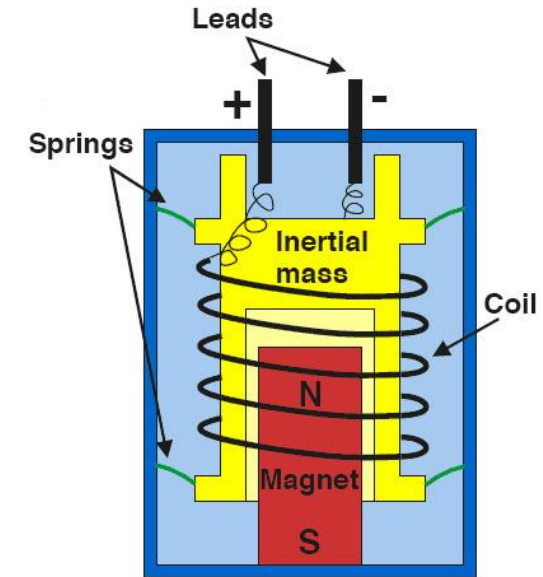
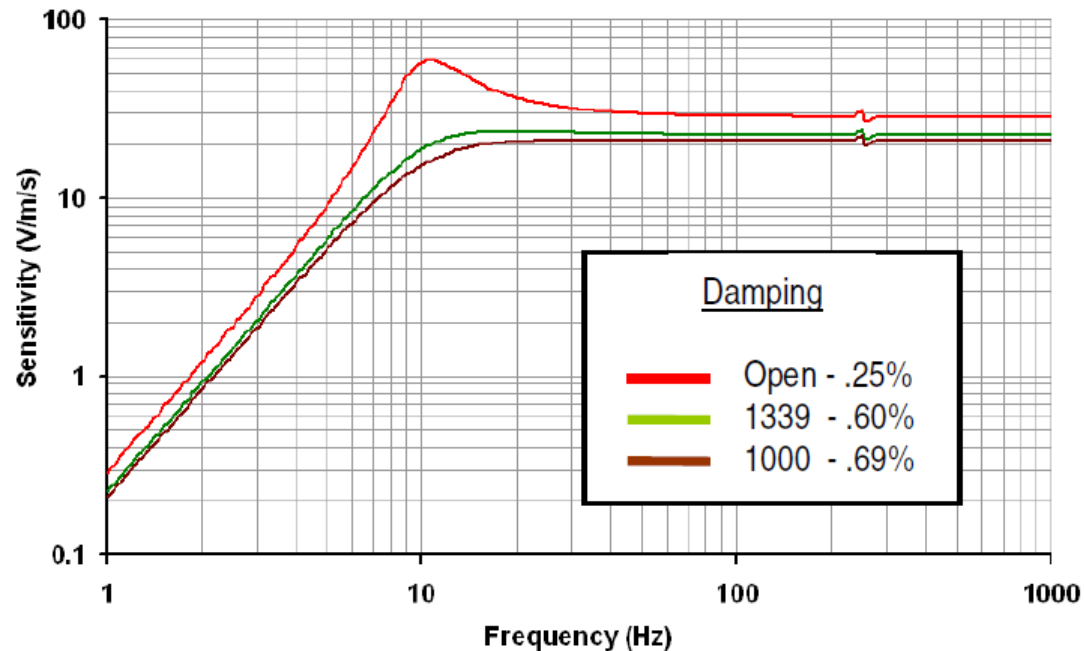


- Output voltage proportional to ground velocity above natural frequency.
- Simple and compact solution

 requirements

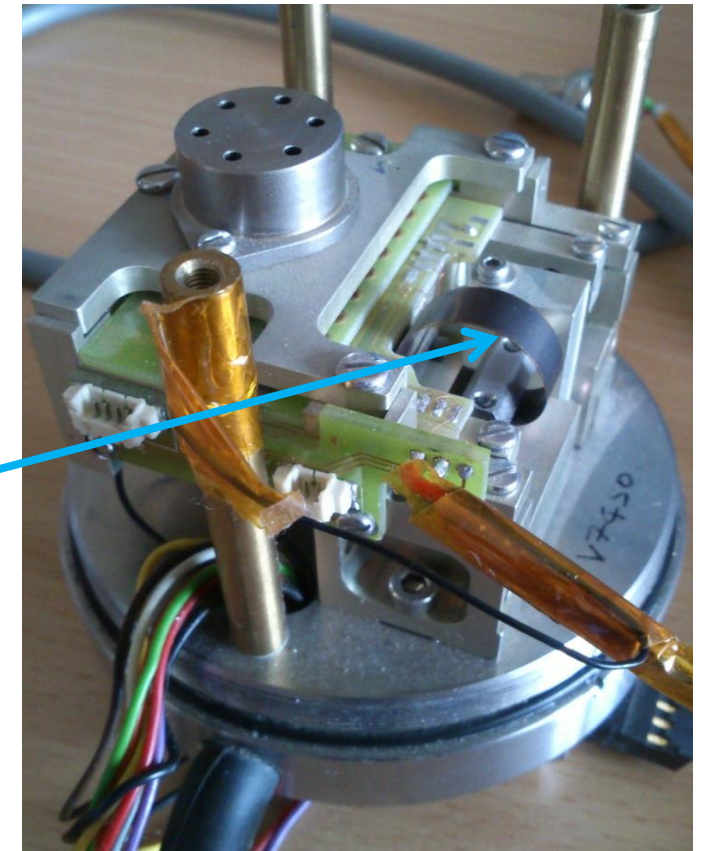
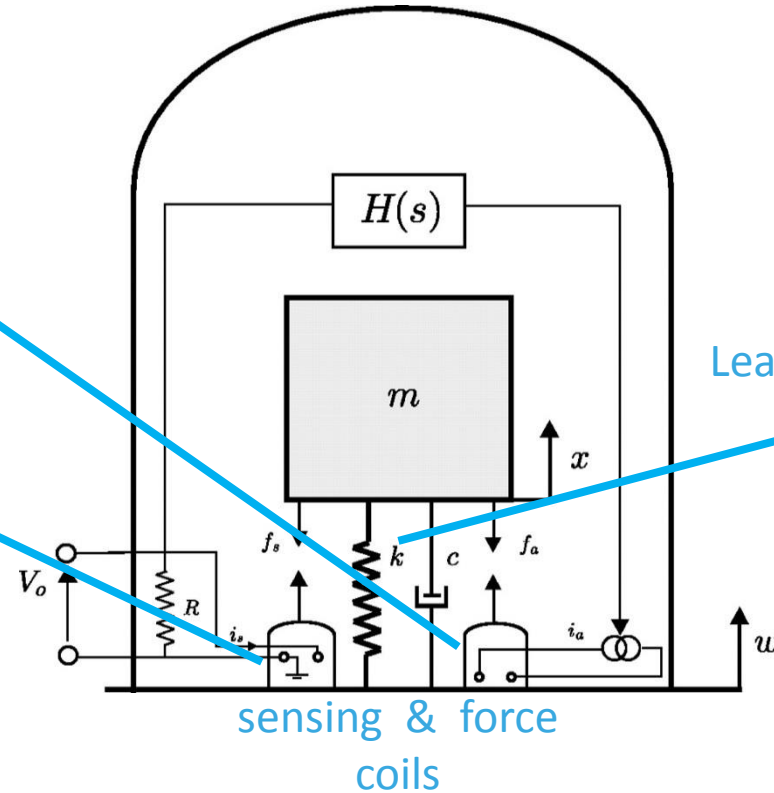
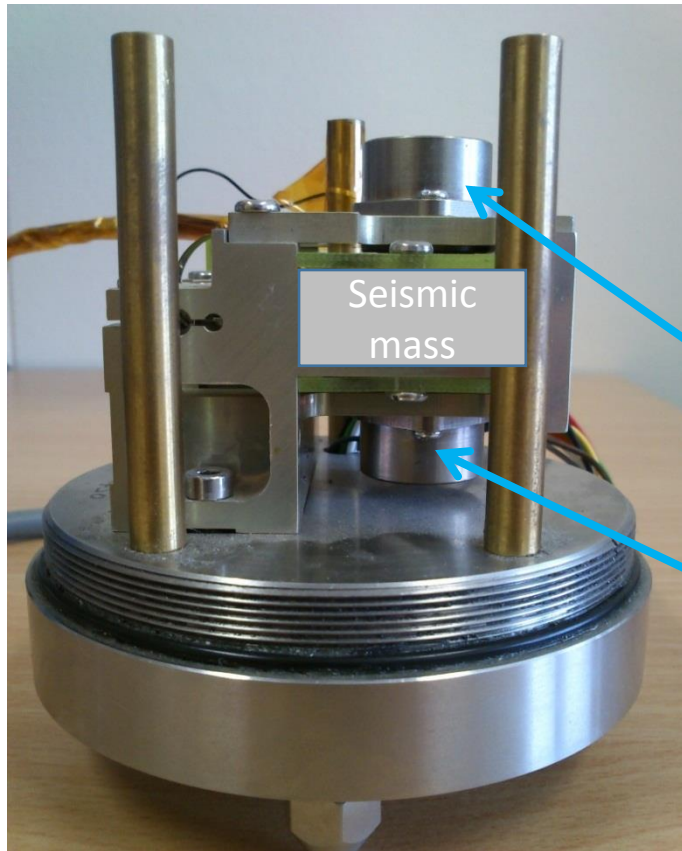
- ✓ Low noise
- ✓ Weight and size
- ✓ Price
- × Natural freq. > 10 Hz
- × Magnetic resistance

Geophone Response Curve – SM-24 10 Hz



# Geophones with feedback => seismometers

- Utilise the feedback control of mass position to extend bandwidth to low frequencies.



- Output voltage is proportional to ground velocity in certain frequency bandwidth.



## requirements

- ✓ Very low noise
- ✓ Resolution
- ✓ Broad bandwidth
- Weight and size
- ✗ Magnetic resistance
- ✗ Price

Velocity Response Comparison of IRIS/USGS GSN Instruments

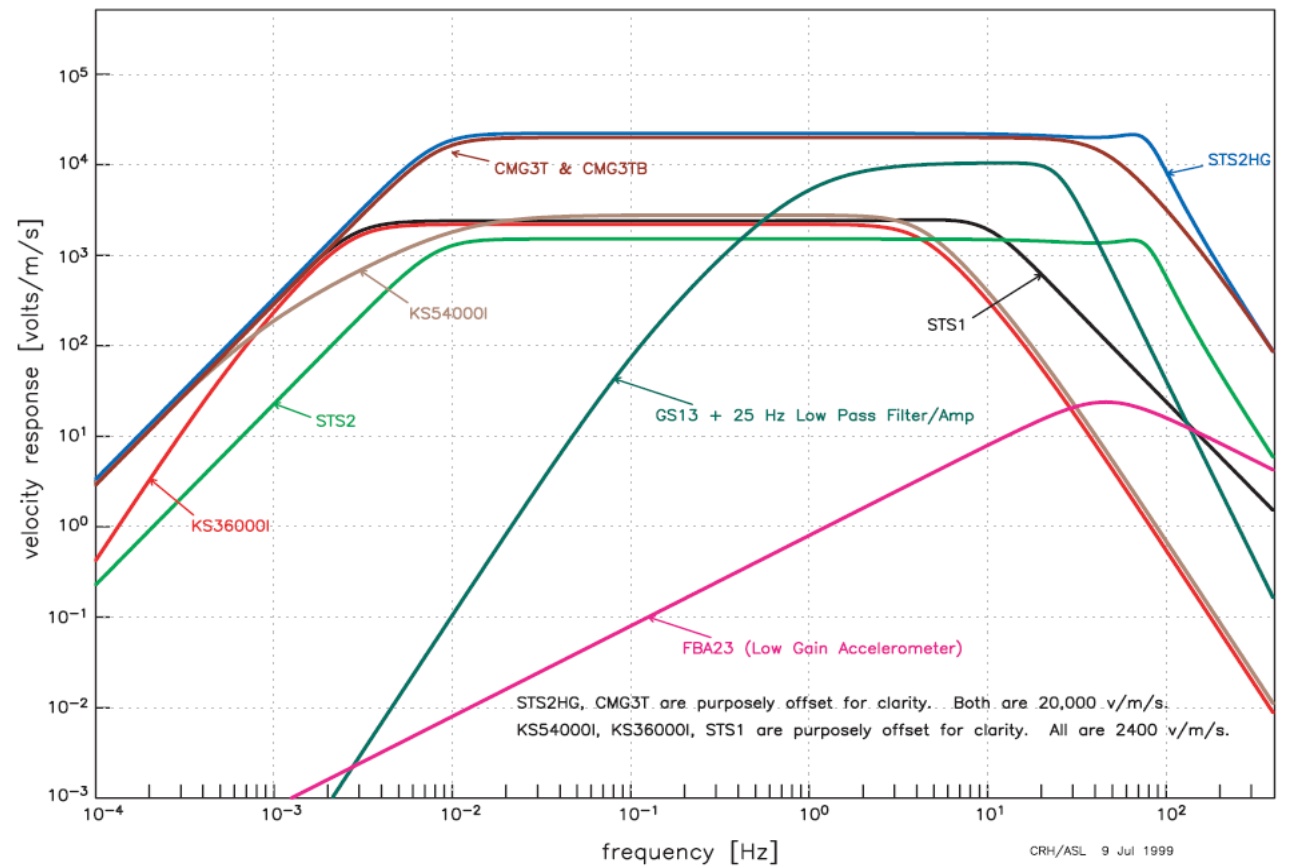


Figure 3. Frequency response of representative seismometers. Figure courtesy of R. Hutt, USGS/ASL.

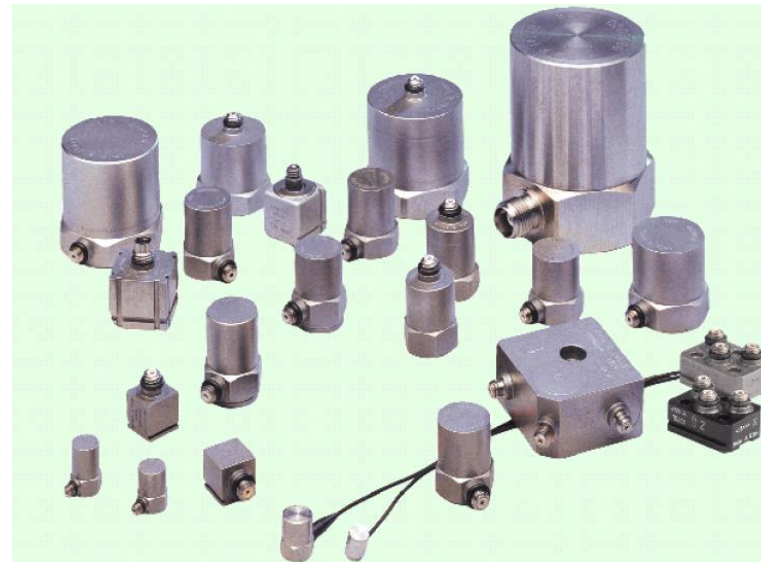
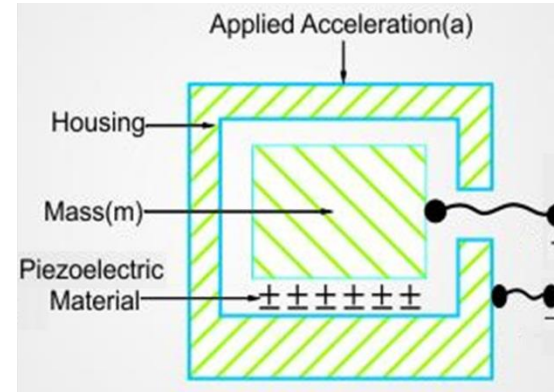
- Output voltage proportional to ground acceleration below natural frequency.
- Different types:
  - Piezoelectric, piezoresistive, capacitive, Force Balanced (FBA)
- Possibility of utilizing MEMS
  - + size and price reduction
  - high self noise



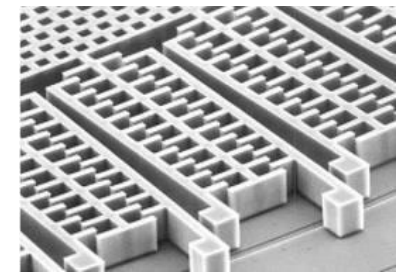
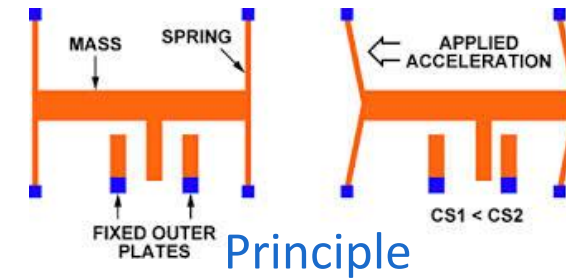
## requirements

- ✓ Bandwidth
- ✓ Magnetic resistance
- Price
- × Higher noise at lower freq.
- × Resolution

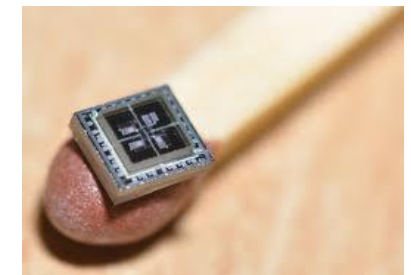
### Piezoelectric



### MEMS capacitive acc.

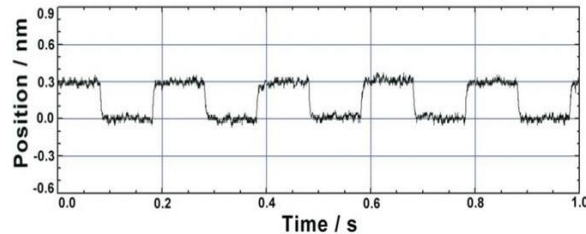
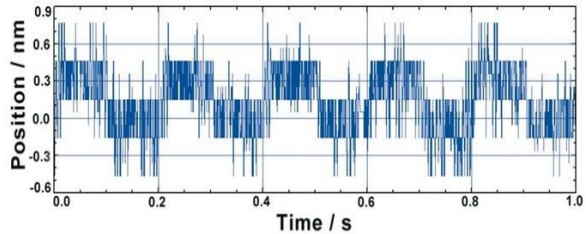


MEMS realisation

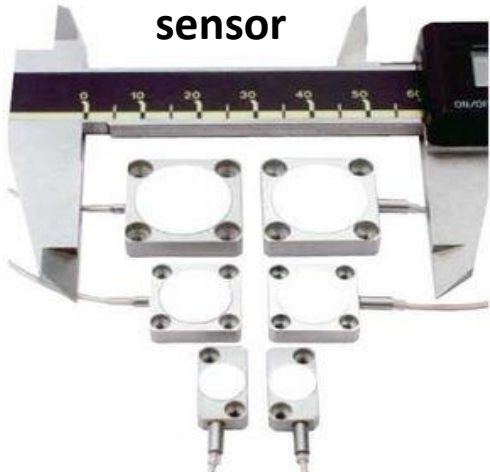


Final product

## Interferometer



## Capacitive sensor



## • Sources of noise:

### • Thermomechanical (Brownian) noise

- Molecular collisions with mass

### • Thermoelectrical (Johnson) noise

- Random thermal excitation of charge carriers

### • Schottky noise

- Random movement of charge across potential barriers

### • Flicker $1/f$ noise

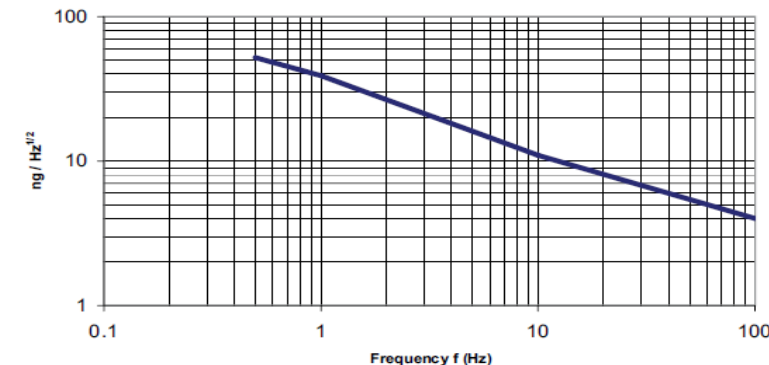
- Impurities in semiconductors

### • Discretisation noise

- ADC converters

Producer	Model	Noise [ $\mu\text{m}^2\text{s}^{-2}/\text{Hz}^{1/2}$ ]
Endevco	87	0.9 @1Hz 0.25 @10Hz 0.1 @100Hz bb rms <math>4\mu\text{m}^2\text{s}^{-2}</math>
Wilcoxon	731A	0.3 @2Hz 0.1 @10Hz 0.04 @100Hz
Brüel & Kjær	8340	14.7 @0.1Hz 14.7 @55Hz
PCB	393B31	0.6 @1Hz 0.1 @10Hz 0.04 @100Hz
COLIBRYS	SF1600S.A	3 in 0.1-100Hz BW
Metrozet	TSA-100S	rms 0.22@1Hz rms 0.2@10Hz rms 0.7@10Hz

Spectral Noise





# Classification of seismic sensors



## Output voltage proportional to:

- Displacement
- Velocity:
  - geophones
  - feedback geophones = seismometers
- Acceleration:
  - Accelerometers
  - Force Balanced Accelerometers (FBA)

## By type of sensing transducer:

- Capacitive
- Inductive
- Piezoelectric
- Optical
- ...

## Other classifications:

- Bandwidth
  - Short period, Long period, Broad band, Very BB
- Signal intensity
  - Strong motion, High sensitivity



# Few sensors and their producers



Producer	type of sensors
<b>GURALP</b>	Seismometers
<b>ion (Sensor Nederland B.V.)</b>	geophones
<b>Sercel (Mark Products)</b>	geophones
<b>Kinometrics (Streckeisen)</b>	Seismometers + FBA
<b>Nanometrics</b>	Seismometers
<b>REFTEK</b>	Seismometers
<b>Lennartz electronic</b>	Seismometers
<b>Metrozet</b>	Seismometers + FBA
<b>Eentec</b>	FDBCK MET geophones + FBA
<b>SINUS</b>	Piezo-velocity sensor
<b>GeoSIG</b>	geophones + FBA
<b>Endevco</b>	accelerometers
<b>Wilcoxon</b>	accelerometers
<b>DYTRAN</b>	accelerometers
<b>DJB Instruments</b>	accelerometers
<b>MMF</b>	accelerometers
<b>Brüel &amp; Kjær</b>	accelerometers
<b>PCB</b>	accelerometers
<b>COLIBRYS</b>	accelerometers
<b>R-sensors</b>	MET geophones + acc
<b>METTECH</b>	MET
<b>GEOTECH INSTRUMENTS</b>	Seismometers

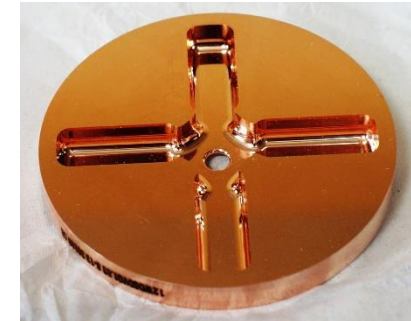




- Development of the seismic sensor for stabilisation of the Final Focus (of CLIC)
- Equivalent of 7 months (already started)
- Their measuring and control system



- High precision mechanic manufacturer



- 3 months starting in March 2015
- Project:
  - Measurement and adjustment techniques for precision applications



**Thank you for your  
attention!**

