

*Simulation of Longitudinal
Beam Dynamics Problems in Synchrotrons
Lecture 1*

Numerical Methods of Longitudinal Beam Dynamics

Helga Timko

CERN, BE-RF

Inverted CERN School of Computing, 23-24 February 2015

Contents

- **Introduction**
 - What is longitudinal beam dynamics (LBD)?
- **Building blocks of numerical LBD**
 - Equations of motion
 - RF manipulations
 - Collective effects
 - Low power-level RF (LLRF) loops
- **Discussion about end-to-end simulations**
- **Take-home messages: given by you!**

Why model longitudinal beam dynamics?

INTRODUCTION

What is a beam?

- **Particle beam = collection of particles, usually confined in space**
 - In accelerator physics we use mainly charged beams, which can be manipulated via electromagnetic fields
 - Beam particles are selected to have the same charge state; particles with the same q/m move in the same way (Lorentz):

$$\frac{d}{dt}(\gamma\vec{v}) = \frac{q}{m}(\vec{E} + \vec{v} \times \vec{B}) \quad (1)$$

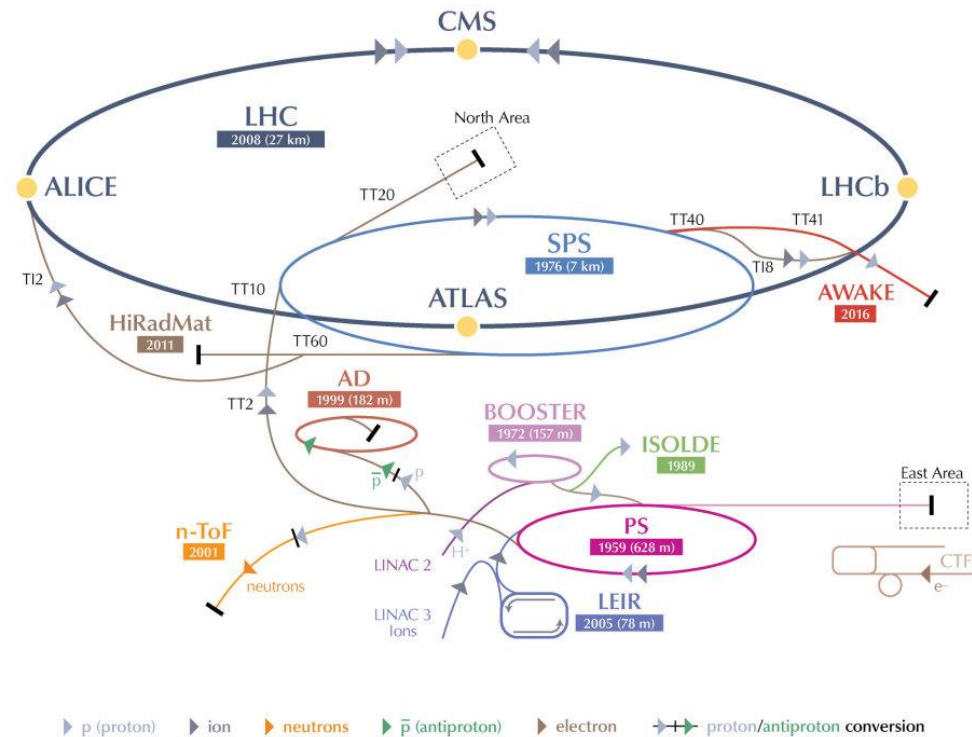
- **A beam is essentially a plasma**
 - In a plasma, spatial confinement is ensured by quasi-neutrality (many species, global charge is zero) and boundary conditions
 - In a beam, spatial confinement is ensured by the RF potential in the cavities (longitudinal) and magnetic focussing (transverse)

Beams at CERN

- **Various beams are being used at CERN for different purposes**
 - LHC and injectors: p (H^+), $^{208}\text{Pb}^{54+}$, $^{40}\text{Ar}^{11+}$
 - ISOLDE: large range of radioactive isotopes
 - AD and ELENA decelerators: anti-protons, anti-hydrogen
 - ...
- **LHC proton beam production**
 - Source \rightarrow Linac2 (Linac4) \rightarrow PSB \rightarrow PS \rightarrow SPS \rightarrow LHC
 - Extraction kinetic energies or momenta: 50 MeV (160 MeV) \rightarrow 1.4 GeV (2 GeV) \rightarrow 26 GeV/c \rightarrow 450 GeV/c \rightarrow 7 TeV
- **LHC ion beam production**
 - Source \rightarrow Linac3 \rightarrow LEIR \rightarrow PS \rightarrow SPS \rightarrow LHC

The CERN Accelerator Complex

CERN's Accelerator Complex



LHC Large Hadron Collider SPS Super Proton Synchrotron PS Proton Synchrotron

AD Antiproton Decelerator CTF3 Clic Test Facility AWAKE Advanced WAKEfield Experiment ISOLDE Isotope Separator OnLine DEvice

LEIR Low Energy Ion Ring LINAC LINear ACcelerator n-ToF Neutrons Time Of Flight HiRadMat High-Radiation to Materials

© CERN 2013



CERN Beams Department

- **A large range of activities:**
 - Accelerator operation, production & delivery of particle beams
 - Controls infrastructure for all accelerators
 - Accelerator systems
 - Machine and detector alignment
 - Hadron sources
 - Beam instrumentation
 - Accelerator physics studies and teaching activities
 - CERN Accelerator School (CAS): <http://cas.web.cern.ch/cas/>

Acceleration and synchrotrons

- **Lorentz equation \Rightarrow electric field accelerates, magnetic field changes the direction of velocity**
- **Two ways to accelerate particles**
 - Linacs: no bending magnets needed, but single passage through each cavity
 - Circular accelerators: repetitive passage through the cavities, but strong magnets are required to close the trajectory
 - LHC: 8 cavities/beam \rightarrow **accelerate**; 1232 dipole magnets \rightarrow **bend** with up to 8.33 T; 392 quadrupole magnets \rightarrow **focus** transversely
- **We'll focus on synchrotrons**
 - Magnetic field strength synchronised with the beam energy
 - Cavities' RF frequency and phase is synchronised as well

Acceleration

- **Using DC voltage**
 - Linear potential, uniform electric field
- **Using RF voltage**
 - Need to arrive in the right RF phase to gain energy

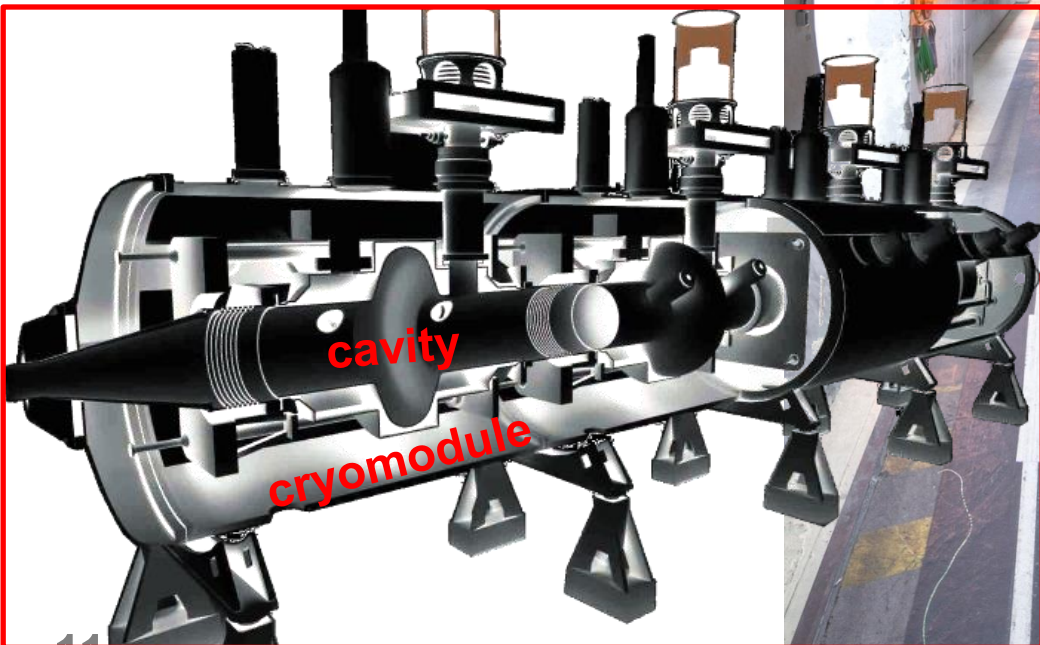
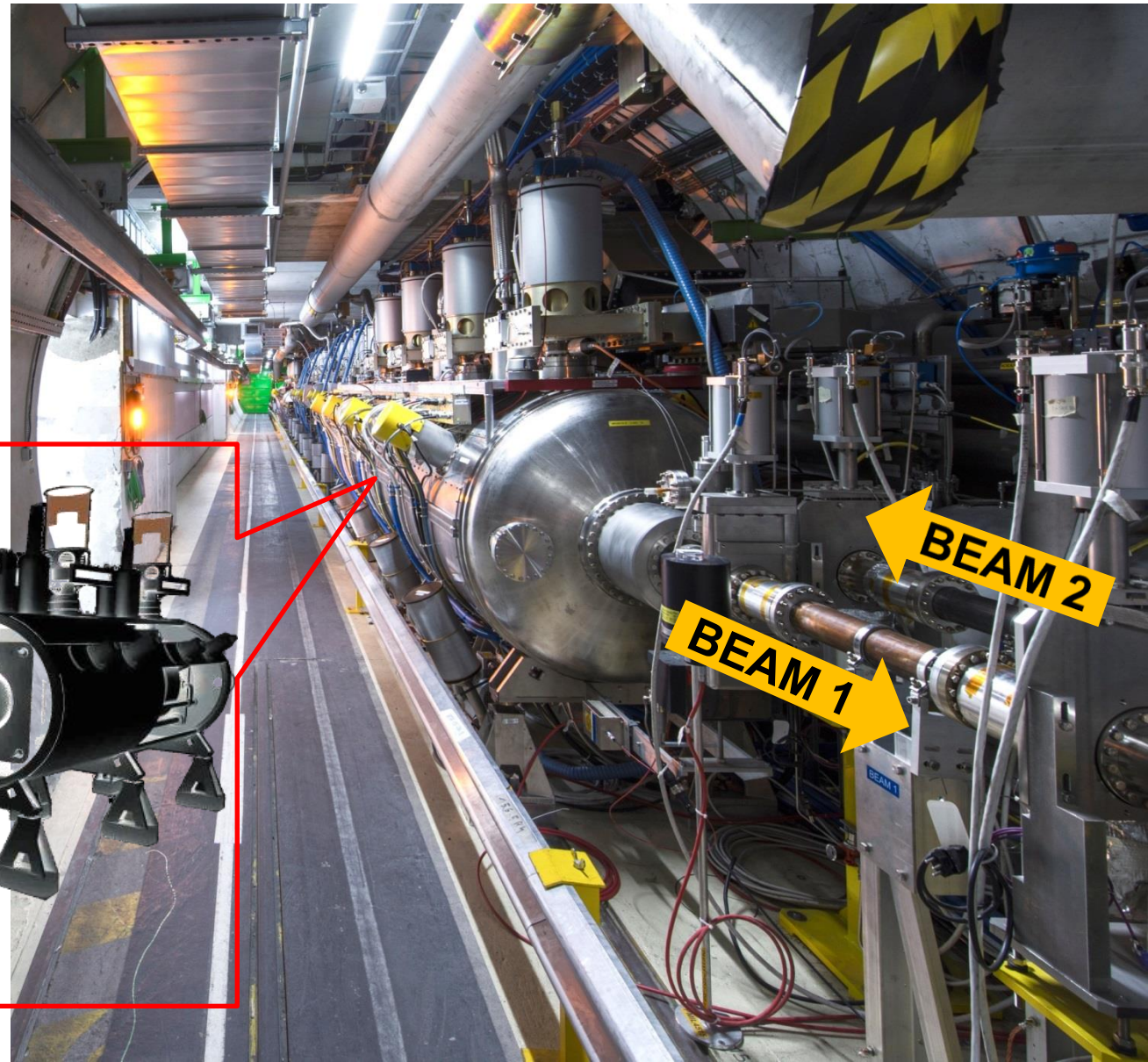


A simple linear accelerator



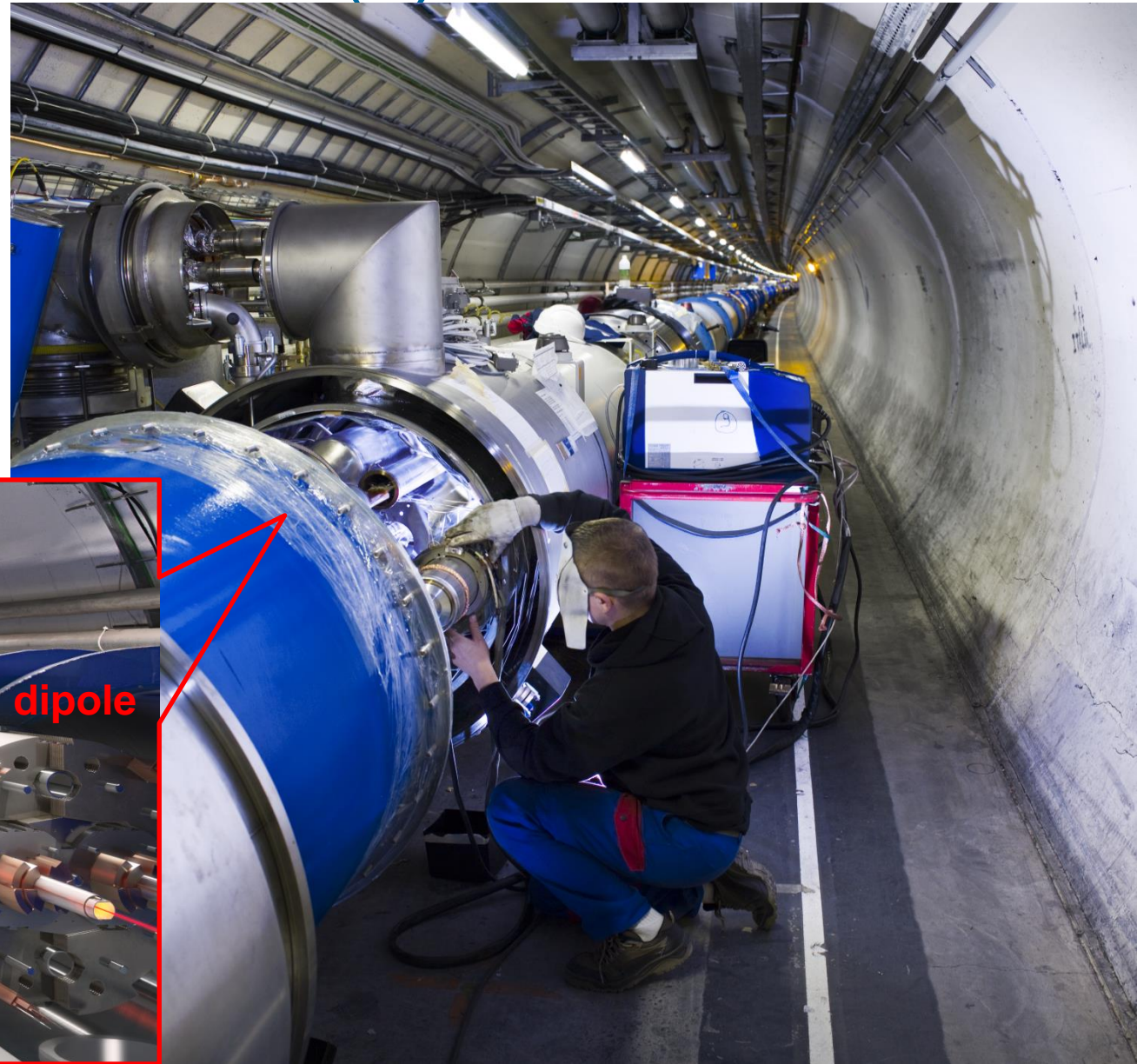
A synchrotron: the LHC (1)

- All accelerating cavities are placed in Point 4
- Straight section



A synchrotron: the LHC (2)

- Dipole and quadrupole magnets are placed all along
- So-called arcs



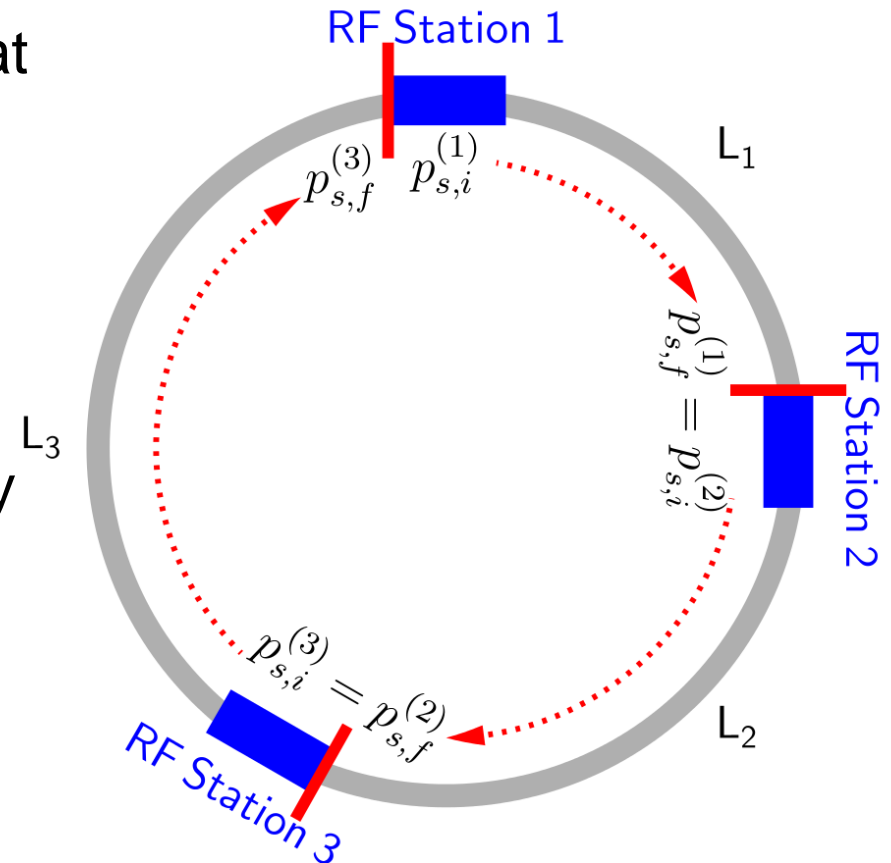
Longitudinal beam dynamics

- **Longitudinal = along, transverse = across the beam pipe**
- **Why do we care about the beam evolution over time?**
 - To design our machines
 - To control/manipulate the beam (splitting, shaping...)
 - PSB: 1 bunch (800 ns) in each of 4 rings, LHC: 2808 bunches (1.2 ns)
 - To ensure a certain beam quality and safe operation
 - Beam instabilities can lead to
 - Uncontrolled emittance (beam size) blow-up → deterioration of beam quality, loss of luminosity
 - Beam losses → loss of luminosity and radiation/safety issue (full LHC beam stores 350 MJ, can drill a hole into the beam pipe!)
- **Complex machines, numerical models needed!**

Motion of beam particles in the RF potential
EQUATIONS OF MOTION

Synchrotron model

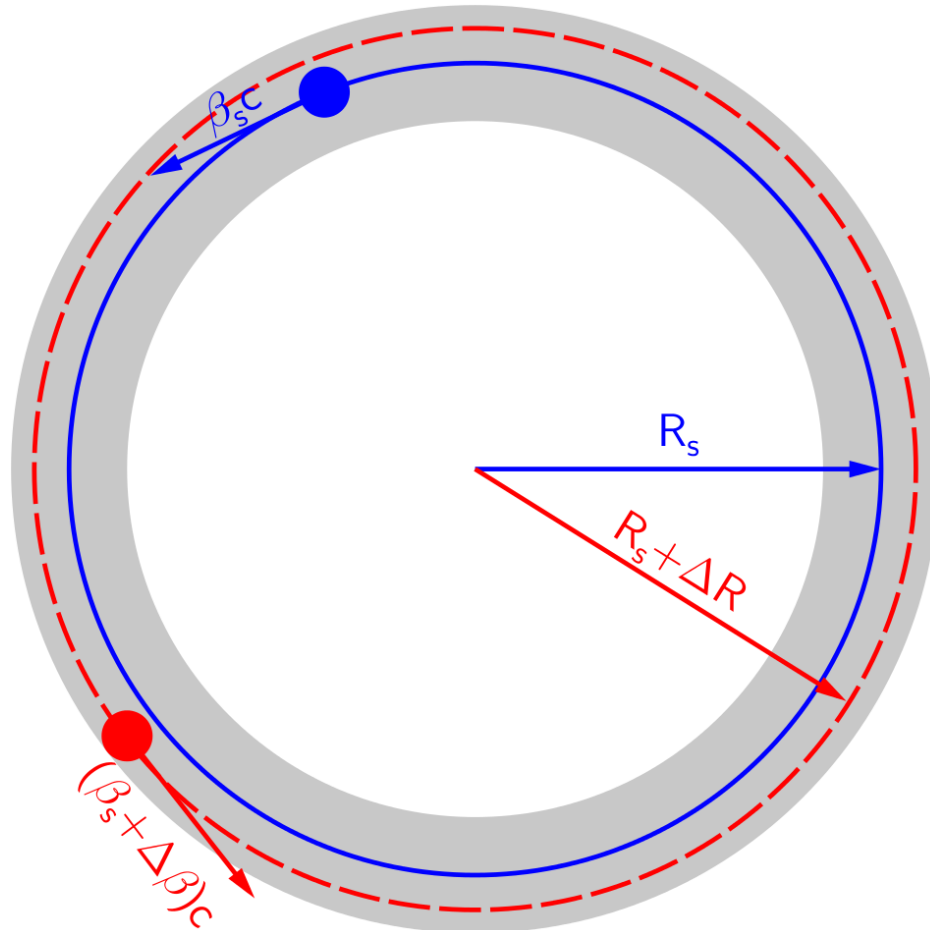
- **RF stations**
 - Contain cavities (may operate at different harmonics)
 - Keep the beam bundled
 - Described via energy kicks
- **Magnetic arcs**
 - Magnetic field to keep trajectory
 - RF synchronised to B-field
 - Arrival time to next station described via phase drifts
- **We'll focus on single-station machines (OK for protons/ions)**



The concept of slippage (1)

- **Ideally, all particles would exactly have the synchronous energy, arrive at the same time to the accelerating cavity, and thus see the same, synchronous RF phase**
 - The ‘dynamics’ would be quite simple
 - But this is actually not a stable system (see collective effects)
- **In reality, particles can have a slight energy/momentum offset**
 - Typical relative momentum offset, typically $\delta = \mathcal{O}(10^{-3} - 10^{-4})$
 - For the synchronous particle, one turn takes $T_0 = \frac{2\pi R_s}{\beta_s c}$, where $2\pi R_s$ is the length of the synchronous orbit and $\beta_s = \frac{v_s}{c}$
 - For an off-momentum particle, one turn takes $T = \frac{2\pi R}{\beta c}$, since the particle has a different velocity and also a different orbit

Slippage



- **By definition, the synchronous particle always returns after one turn to exactly the same position**
- **Note that we are interested in deviations from the synchronous particle, described in phase space**
 - Coordinate system fixed to the synchronous particle
 - Non-inertial
 - Possible change of coordinate system each turn

The concept of slippage (2)

- If $\delta > 0 \Rightarrow$ the particle travels faster, $\delta < 0 \Rightarrow$ travels slower than the synchronous particle
 - Intuitively, the effect is stronger for low energies and becomes negligible in the ultra-relativistic limit $\beta \rightarrow 1$
- How the orbit changes, depends on the magnetic lattice design of the machine, which determines the so-called *transition gamma* γ_T (or *transition energy* $\gamma_T mc^2$) $\frac{1}{\gamma_T^2} \equiv \frac{1}{R_s} \frac{dR}{d\delta}$
- **Below transition, $\gamma < \gamma_T$, speed ‘wins’ \Rightarrow higher energy** particles have higher rev. frequency $\omega \equiv \frac{\beta c}{R} > \frac{\beta_s c}{R_s} \equiv \omega_0$ for $\delta > 0$
- **Above transition, $\gamma > \gamma_T$, orbit ‘wins’ \Rightarrow higher energy particles** have lower rev. frequency $\omega < \omega_0$ for $\delta > 0$

The concept of slippage (3)

- Hence, the associated ‘**frequency slippage**’ depends both on the machine (γ_T) and the momentum offset (δ):

$$\frac{\Delta\omega}{\omega_0} \equiv -\eta(\delta)\delta \approx -(\eta_0 + \eta_1\delta + \eta_2\delta^2 + \dots)\delta \quad (2)$$

- $\eta(\delta)$ is the so-called slippage factor
- η_i are machine-dependent constants
 - Depend on β_s , γ_s , and ‘momentum compaction factors’ α_i
- Often the first approximation is sufficient,

$$\frac{\Delta\omega}{\omega_0} \approx -\eta_0\delta = -\left(\frac{1}{\gamma_T^2} - \frac{1}{\gamma_s^2}\right)\delta \quad (3)$$

Energy EOM: 'kick'

- A particle passing the cavity receives an energy kick* of**

$$E^{n+1} = E^n + eV^n \sin \varphi^n \quad (4)$$
 where φ^n is the RF phase when the particle crosses the cavity

- Relative to the synchronous particle, the energy offset is**

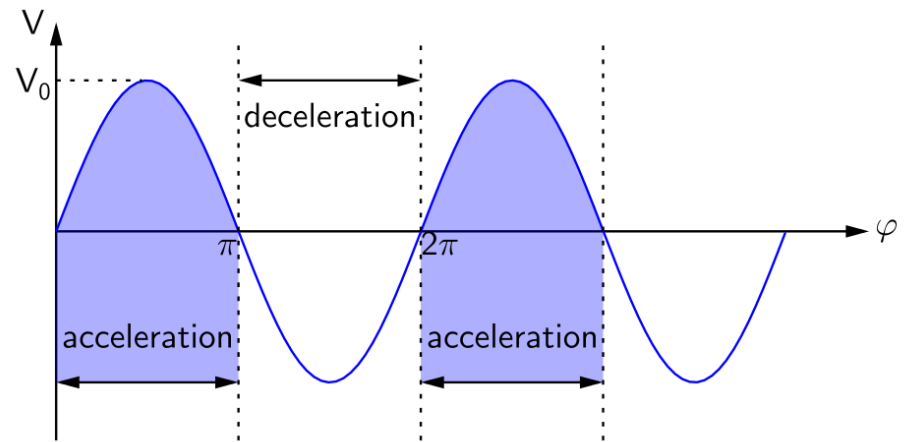
$$\Delta E^{n+1} = \Delta E^n + eV^n \sin \varphi^n - (E_s^{n+1} - E_s^n) \quad (5)$$

RF acceleration synchronous w/ magnetic ramp

RF acceleration within the bunch

* N.B. the sinusoidal term is to be replaced by a sum of sinusoids in the case of multiple RF harmonics

Radio-frequency (RF) cavity voltage



Condition for RF acceleration:

$$eV^n \sin \varphi_s^n = (E_s^{n+1} - E_s^n) > 0$$

$$\therefore \varphi_s \in (0, \pi)$$

Stationary energy: $\varphi_s = 0$ or π

Phase EOM: 'drift'

- Assume a particle that has a time delay and energy offset w.r.t. to the synchronous particle $(\Delta t^n, \Delta E^n)$
 - The first update the energy $\Delta E^n \rightarrow \Delta E^{n+1}$ according to Eq. 5
- Next turn, the particle crosses the cavity with a time delay of

$$\Delta t^{n+1} = \Delta t^n + \frac{2\pi}{\omega} - \frac{2\pi}{\omega_s} \quad (6)$$

- The corresponding RF phase is

$$\Delta \varphi^{n+1} = \frac{f_{RF}^{n+1}}{f_{RF}^n} \Delta \varphi^n + 2\pi h \left(\frac{1}{1 - \eta(\delta^{n+1})\delta^{n+1}} - 1 \right) \quad (7)$$

- Note that Eqs. 5 & 7 for kick and drift are exact

- Usual approximation: $\Delta \varphi^{n+1} = \frac{f_{RF}^{n+1}}{f_{RF}^n} \Delta \varphi^n - 2\pi h \eta_0 \delta^{n+1} \quad (8)$

Synchronous phase

- Small amplitude oscillations

$$(5) \Leftrightarrow \Delta \dot{E} = \frac{eV\omega_0}{2\pi} (\sin \varphi - \sin \varphi_s)$$

$$\Delta \dot{E} \approx \frac{eV\omega_0 \cos \varphi_s}{2\pi} \Delta \varphi$$

$$(8) \Leftrightarrow \Delta \dot{\varphi} = \frac{h\eta_0\omega_0}{\beta^2 E} \Delta E$$

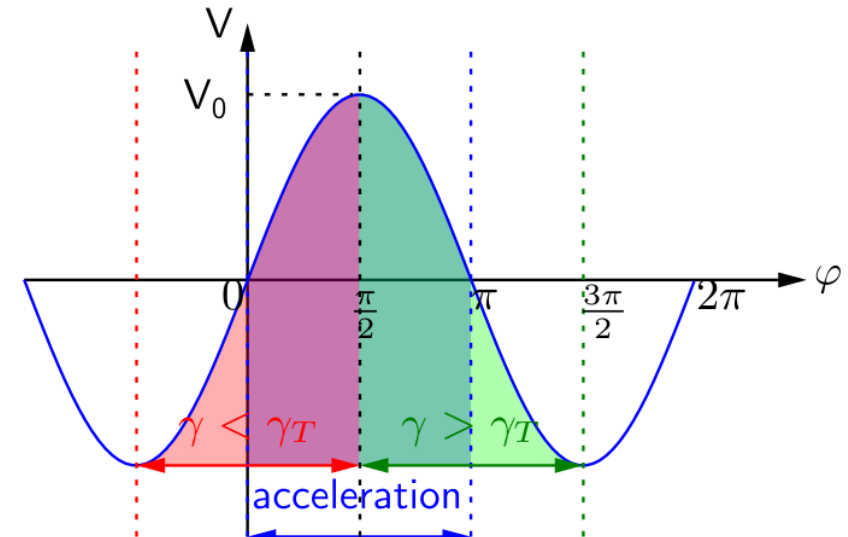
- Second derivative (same for $\Delta \varphi$):

$$\Delta \ddot{E} = \frac{eVh\eta_0 \cos \varphi_s}{2\pi\beta^2 E} \omega_0^2 \Delta E$$

- Simple harm. osc. if $\eta_0 \cos \varphi_s < 0$
- Synchrotron oscillation frequency

$$\omega_s \equiv \sqrt{\frac{eVh\eta_0 \cos \varphi_s}{2\pi\beta^2 E}} \omega_0$$

Synchronous phase of RF voltage



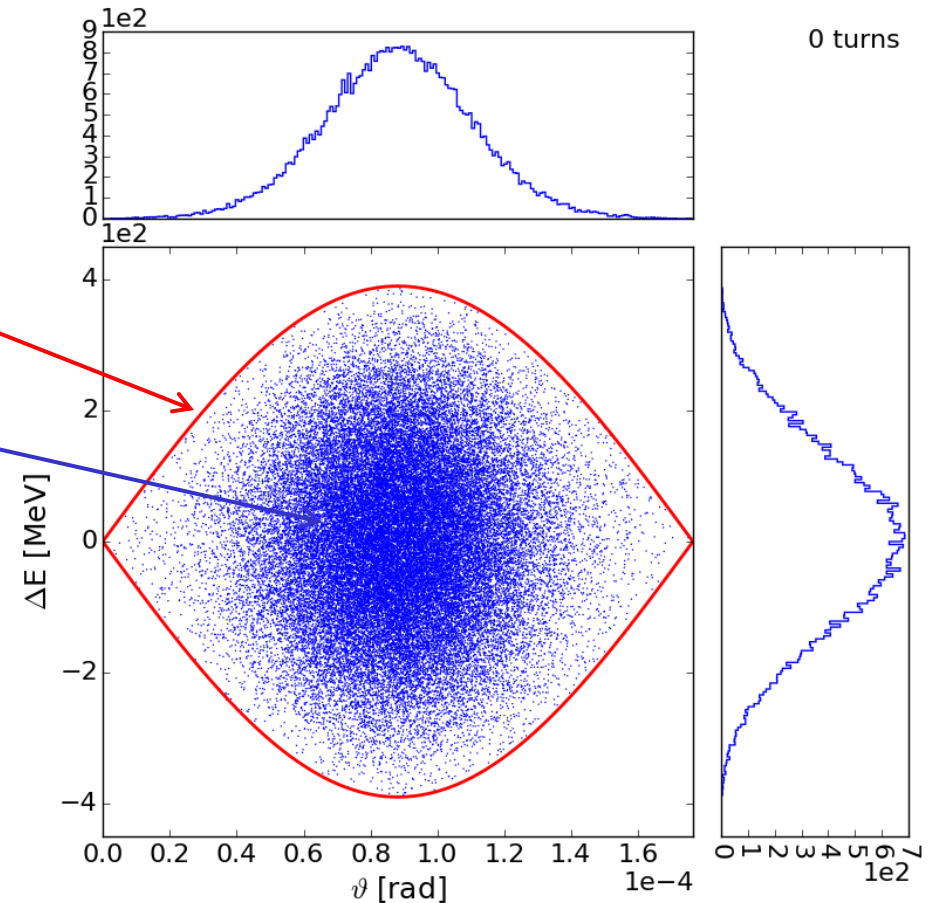
Condition for longitudinal stability, i.e. beam to stay bunched/bundled:

$$\therefore \varphi_s \in [0, \frac{\pi}{2}) \text{ if } \gamma < \gamma_T$$

$$\therefore \varphi_s \in (\frac{\pi}{2}, 0] \text{ if } \gamma < \gamma_T$$

Some terminology...

- The RF potential that confines the beam determines the **'bucket'**
 - Contour: **'separatrix'**
- The beam that is inside a bucket is a **'bunch'**
- The complete beam we call a **'bunch train'**
 - Can consist of **'batches'** with larger spacing in-between



A few examples of how to shape bunches
RF MANIPULATIONS

LHC Point 4 – RF acceleration, 2005

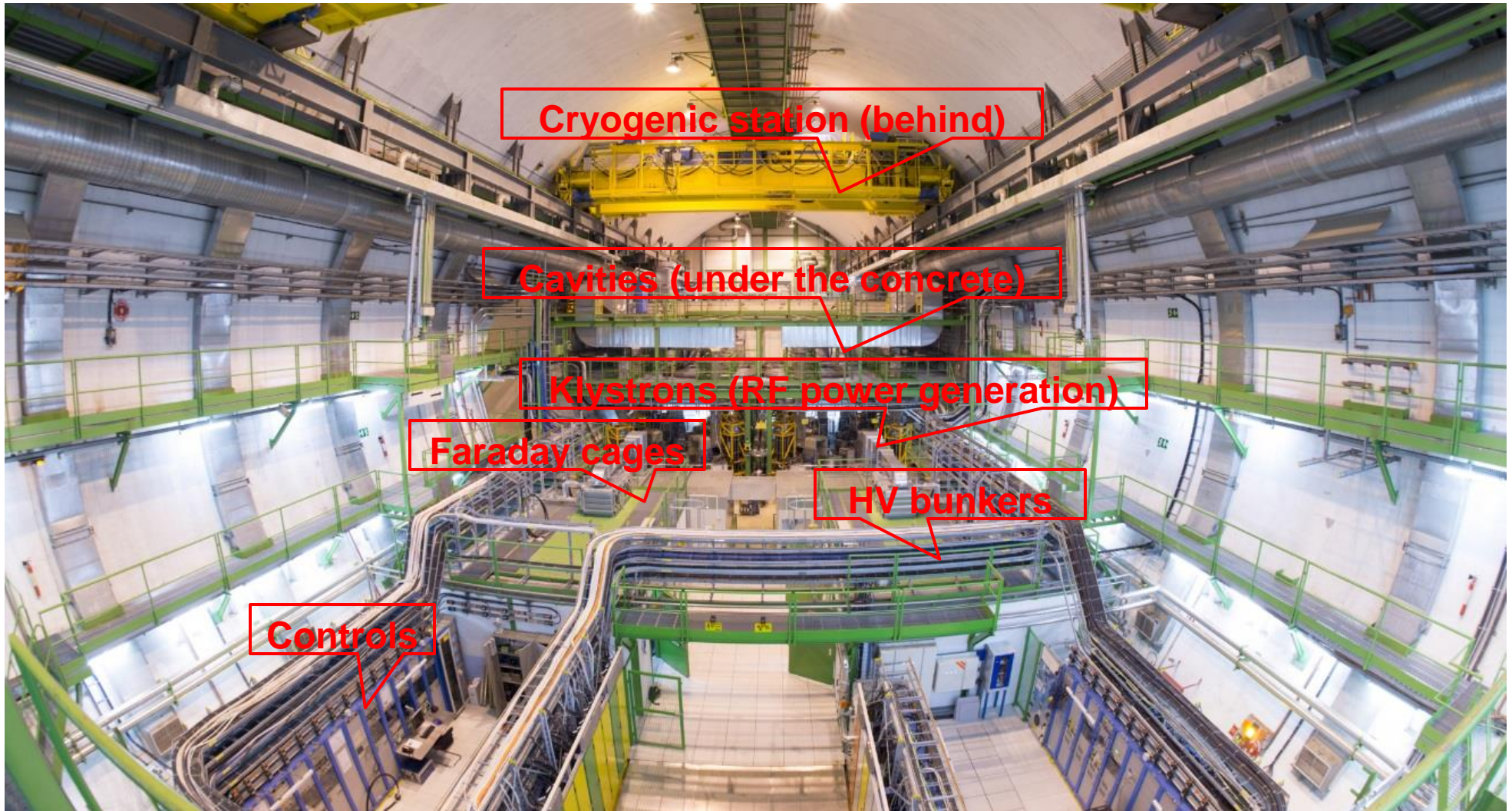


Former LEP ALEPH
detector cavern



Empty tunnel
waiting for cavities

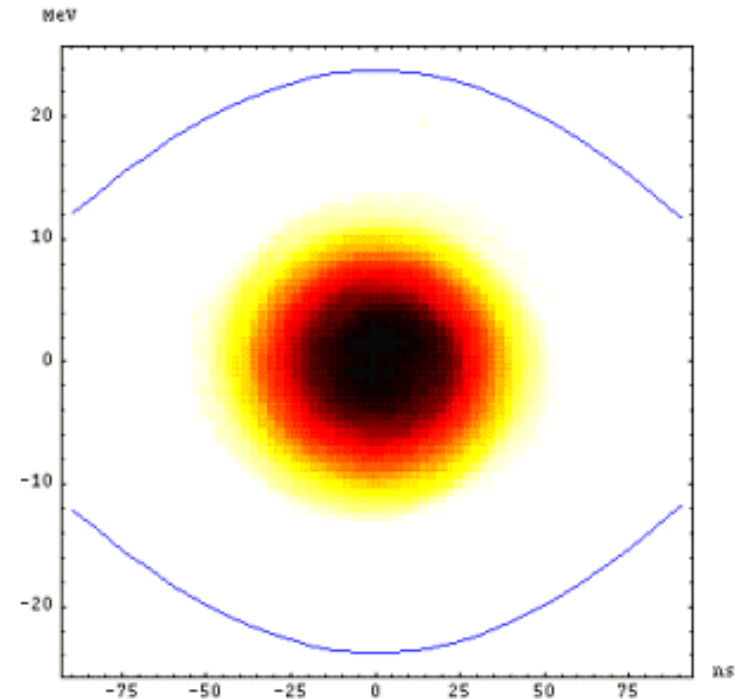
LHC Point 4 – RF acceleration, 2012



Bunch splitting

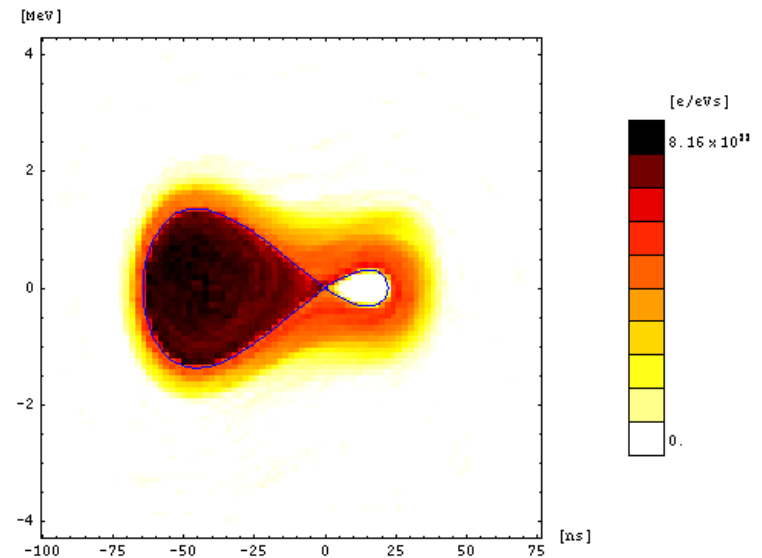
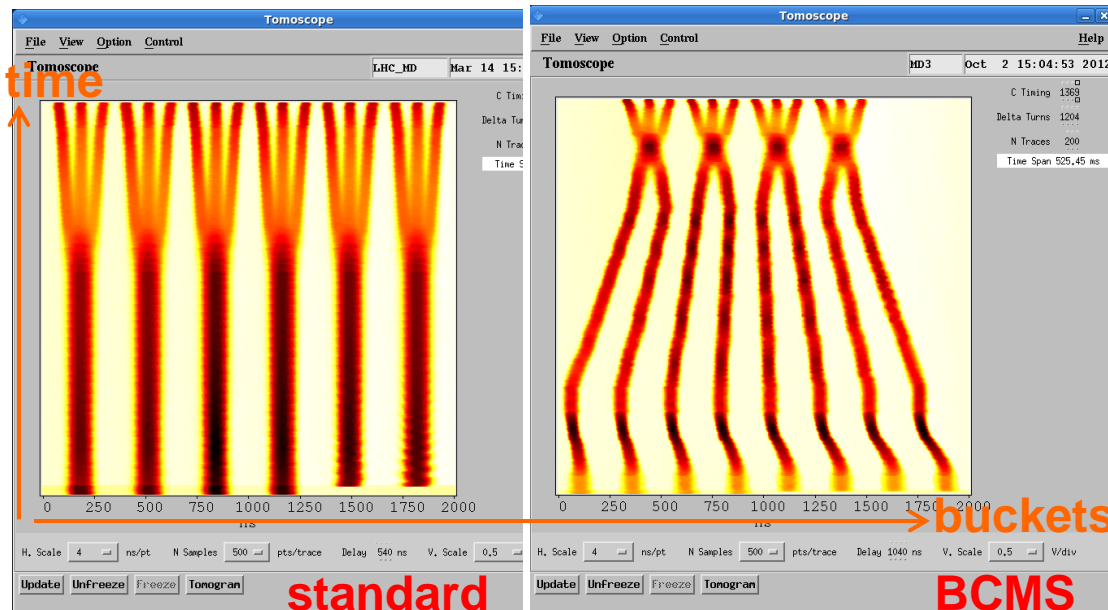
- **Bunch splitting is used several times in the PS, to increase the number of bunches and shorten their bunch length**
 - PS bucket: 100 ns, LHC bucket: 2.5 ns!
- **How it's done: add slowly (adiabatically) a higher-harmonic component to the RF potential**
- **Numerical challenge: what is a bucket in this case? In multi-RF, what are the synchronous phase(s)?**

PS bunch splitting (measured via tomography)



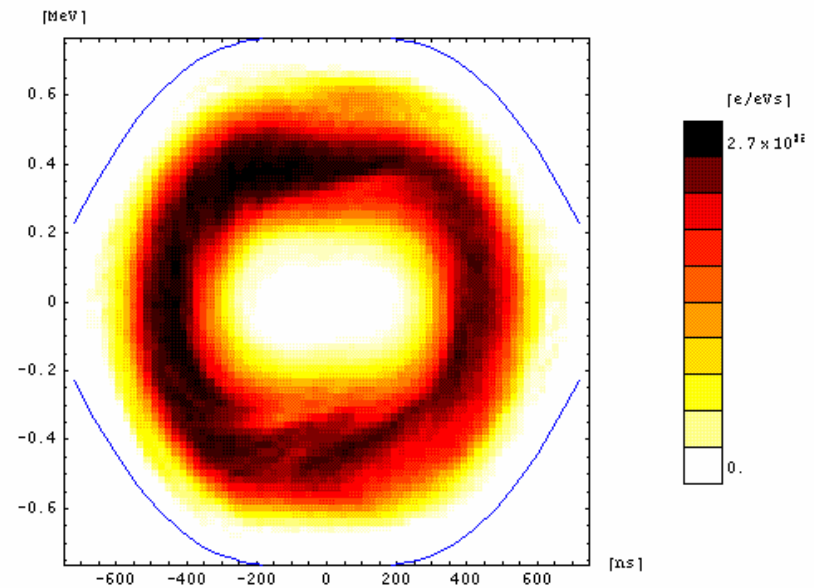
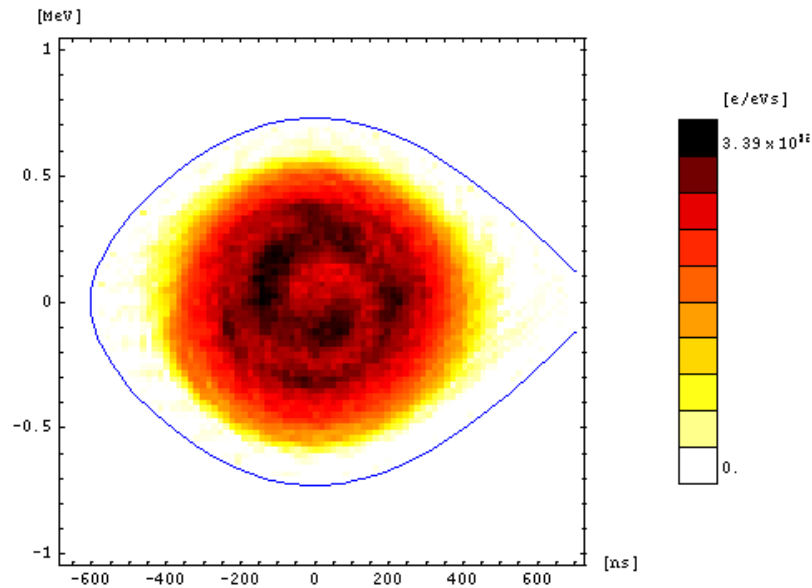
Bunch merging

- **The opposite of bunch splitting**
 - Used in the PS 'BCMS' beam production scheme to produce brighter beams for the LHC
 - BCMS = batch compression, merging, and splitting



Phase-space shaping

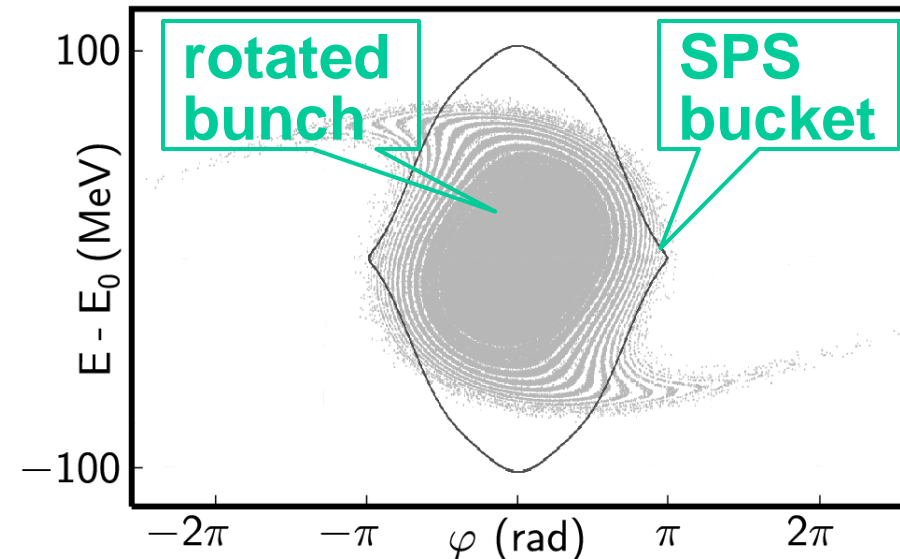
- Phase-space ‘painting’ through intentional filamentation (mixing)
 - Mismatched bunch
- Hollow bunches to produce a flat line density



Bunch rotation in phase space

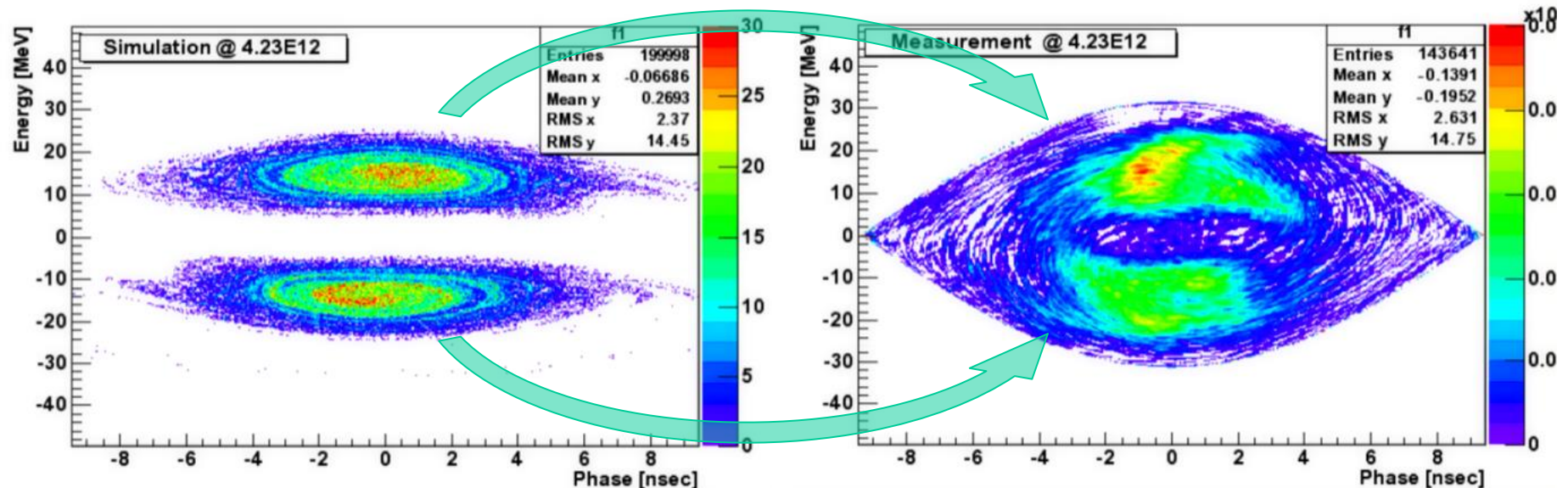
- **Through a sudden (non-adiabatic) voltage increase, the bunch starts to rotate in phase space**
 - A bunch that has initially a long bunch length and small momentum spread will have after $\frac{1}{4}T_s$ a short bunch length and large momentum spread

Used in the PS just before extraction to fit the long PS bunches into the SPS bucket



Slip stacking

- **Merging two bunch trains to increase flux by slipping them in phase/position relative each other**
 - Need 2 different RF systems at different frequencies: one train is decelerated, one accelerated, and finally both are captured
 - Operational at Fermilab, planned for SPS ion operation to halve bunch spacing



Interaction of the beam and its surroundings
COLLECTIVE EFFECTS

Space charge

- **Space charge refers to the 3D charge density distribution $\rho(\vec{x})$**
- **In a real bunch, particles will not only feel the external RF potential, but also the Coulomb interaction with neighbouring particles, which generates an electric potential as well**
 - Negligible for ultra-relativistic beams
- **Ideally, one would need to solve the 3D Poisson equation $\nabla^2 \phi = -\nabla \cdot \vec{E} = -\frac{\rho}{\epsilon_0}$, using many particles and taking into account the external RF potential and the beam pipe (in BCs)**
 - In computational plasma physics this is usually done using the particle-in-cell (PIC) method
 - In beam dynamics, we try to avoid such expensive methods
- Instead, we model the space charge effect through effective potentials, as an **impedance**

Machine impedance

- Talking of which it suddenly becomes very complicated...
- The accelerator is built of many conducting elements: beam pipes, cavities, kickers, etc., having a frequency-dependent complex (hermitian) **impedance** $Z(f)$
 - The impedance is a machine property
- Can be described via its Fourier-transform the **wake field** $W(t)$; in longitudinal plane: $W_{\parallel}(t > 0) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\omega e^{i\omega t} Z_{\parallel}(\omega)$
- There is a whole ‘zoo’ of analytical impedance models for
 - Resistive wall, space charge, broadband-resonators, etc.
- Often, however, we need more accurate data
 - Electromagnetic simulations, e.g. CST Studio

Beam-machine interaction

- The beam, having a time-dependent current density $j(t)$ will interact with the impedance
- Just like in an electric circuit, an electric potential $\phi = jZ$ will be induced
- Hence, the effective potential according to which the beam will move is the sum of the RF and beam-induced potential
- The modified energy equation becomes

$$\begin{aligned}
 \Delta E^{n+1} &= \\
 &= \Delta E^n + eV^n \sin \varphi^n - (E_s^{n+1} - E_s^n) - \\
 &\quad - e^2 \int_{-\infty}^{t^{n+1}} d\tau \lambda(\tau) W_{\parallel}(t^{n+1} - \tau) \quad (9)
 \end{aligned}$$

beam

machine

convolution of bunch line density and wake

Modelling collective effects

- **Due to the convolution, the motion of a particle ‘behind’ depends on the induced voltage of the particles ‘in front’**
- **The energy kick due to collective effects can be modelled**
 - In frequency domain: kick = impedance \times bunch spectrum
 - In time domain: kick = convolution of wake and bunch profile
 - Numerically, both methods have pros and cons (\rightarrow Lecture 2)
- **Usually it is more effective to discretise the bunch profile using **slices** and calculate collective effects separate from the EOMs every turn**
 - The slicing has to be chosen such that all frequencies playing a role are resolved $\Delta t < \frac{1}{f}$

The concept of Landau damping

- Now if an impedance sits e.g. at a frequency that matches the synchrotron frequency of the bunch, collective oscillations can be excited, the bunch can become **unstable**
- In fact, even without any machine impedance, purely due to space charge, a bunch with no momentum spread (i.e. all particles oscillating with ω_s) is unstable as well
- It is due to the momentum spread in the bunch, and the resulting ‘tune spread’ in synchrotron oscillation frequency $\omega_s = \omega_s(\varphi)$ that the bunch is stable. This natural damping of oscillations is called **Landau damping**.
- There are many types of beam instabilities and each of them has its own intensity threshold. Thresholds can be increased through controlled damping, at least up to some level...

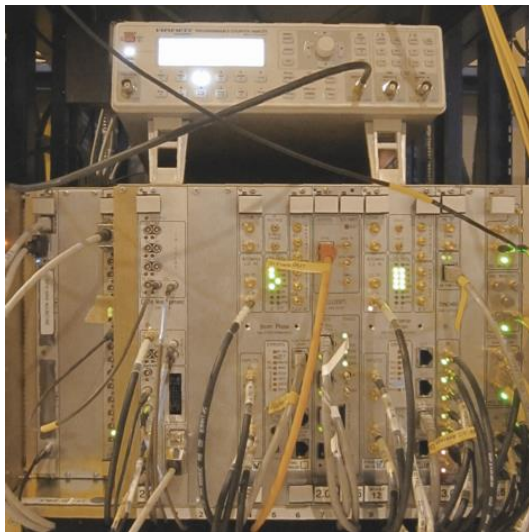
Low-power level RF loops

LLRF

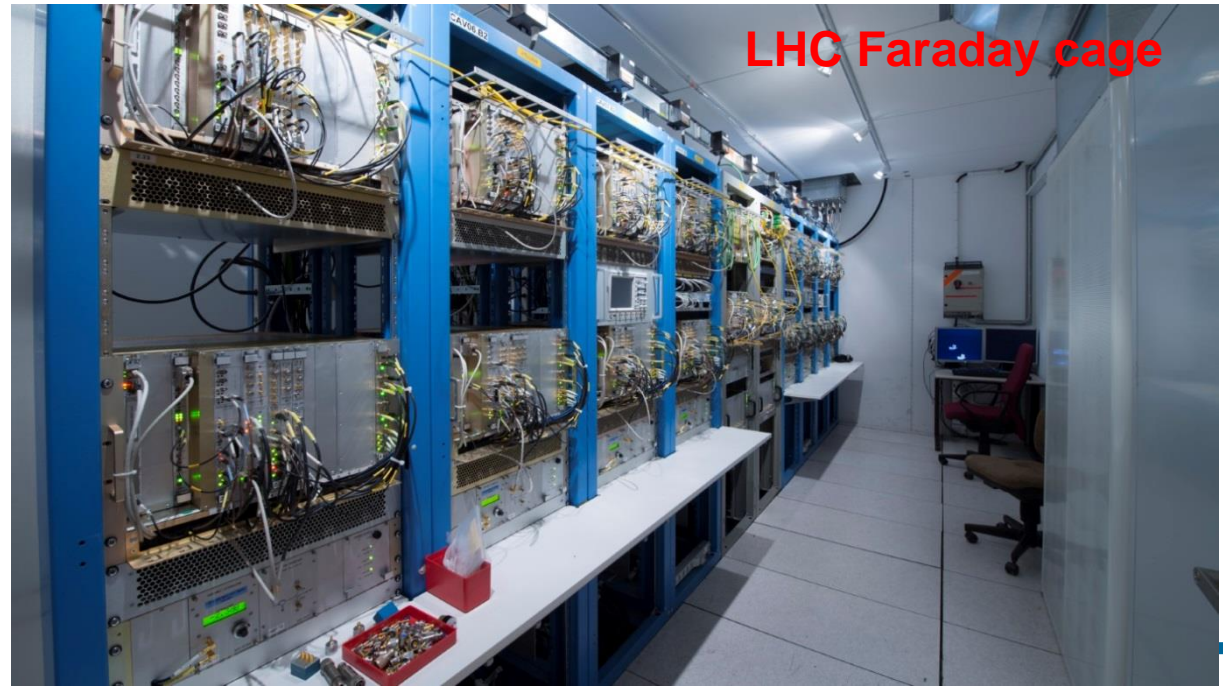
What are LLRF loops?

- **LLRF loops are control electronics that act on-line on RF voltage, phase, and frequency with the main purpose of**
 - Monitor and correct the applied RF w.r.t. the designed RF
 - Correct for noise or collective effects
 - Stabilise the beam by damping collective oscillations
- **For shielding, LLRF equipment is installed in ‘Faraday cages’**

LHC Beam control



LHC Faraday cage



Examples

- **Keeping cavity V and φ as programmed**
 - Cavity loop: Slow feedback
 - One-turn-delay feedback to compensate for beam loading
 - Feed-forward (optional): to reduce the errors in the correction
- **Synchro and radial loops: keep the bunch centred**
 - Synchro loop: synchronises RF with magnetic field ($\omega_{RF} = h\omega_0$)
 - Radial loop: corrects transverse position
- **Beam phase loop: correct differences btw. RF and beam phase**
 - Damp injection oscillations, phase noise, etc.
- **Longitudinal/transverse dampers: designed to damp instabilities (longitudinal/transverse oscillations)**

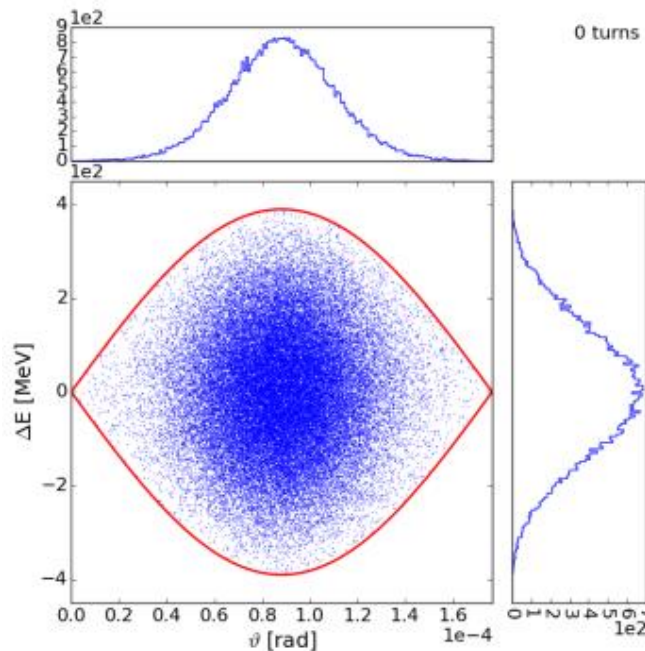
How to model LLRF loops?

- **Some loops are ‘built in’ in the numerical model: we assume**
 - Cavity V and φ as programmed (e.g. cavity loop, FB, FF)
 - RF frequency as programmed (e.g. synchro loop)
- **Other loops have to be modelled via their action**
 - Applying transfer functions on the particle coordinates (e.g. transverse damper)
 - Changing the EOMs (phase loop)
 - Modelling the electronics (loop gain, bandwidth, etc.)
- **In general, we need to take into account frequency and phase shifts in the EOMs**

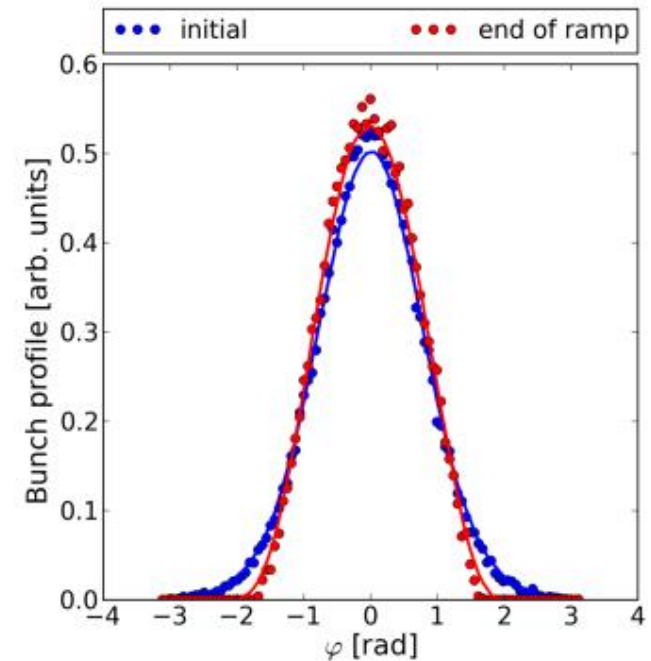
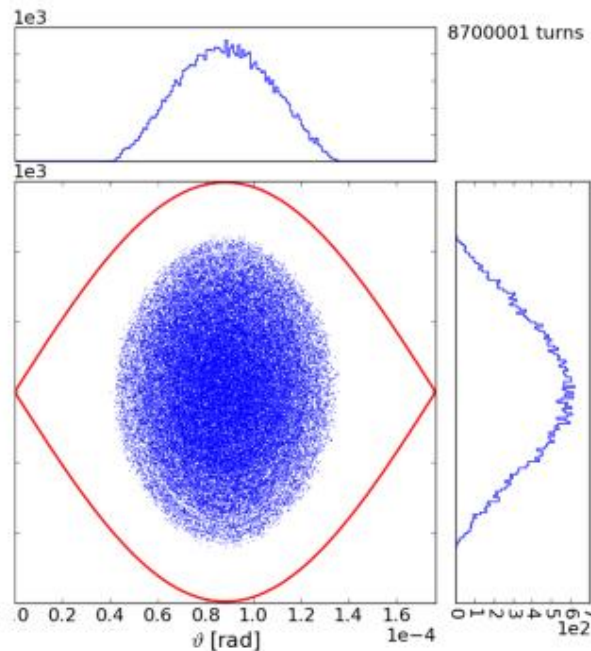
A 'real' example

- Simulation of the LHC acceleration ramp with controlled emittance blow-up and phase loop
 - Natural bunch shrinkage during ramp leads to loss of Landau damping; controlled phase noise injection used for blow-up

Before ramp, 450 GeV



After ramp, 4 TeV



Are end-to-end simulations possible?

COMPLEXITY OF NUMERICAL MODELS

End-to-end simulations?

- **So-called end-to-end simulations are used to calculate beam dynamics in linacs, from one end to the other**
 - Possible because one can use mapping from one stage to another, and the investigated phenomena are very different
- **Could we do something similar for synchrotrons, say simulate the beam dynamics from injection to PSB till physics in LHC?**
- **What do you think? What is your feeling for the complexity of the problem?**

A (very) rough runtime estimate (1)

- How long would it take to simulate ‘just’ the LHC full beam with intensity effects?
- A reasonable simulation that was done:
 - Single bunch
 - 50,000 particles, 100 slices
 - Acceleration ramp: 8,700,000 turns (11 minutes real time)
 - Phase loop and noise injection for controlled emittance blow-up
 - No intensity effects
 - Runtime: **3 days on a single CPU**

A (very) rough runtime estimate (2)

- + Intensity effects (might even need much more particles/slices)
× 2 → **6 days**
- + Full LHC cycle: injection (1 h) + ramp (11 min.) + physics (8 h)
× 50 → **300 days ~ 1 year**
- + In physics: beam-beam interaction, 6D phase space
× 2-10? → **2 years**
- + Full beam
× 2808 → **5600 years**
- + Coupled bunch effects
× 2-10? → **>10000 years (>> LHC lifetime!)**

Take-home messages

- **What is a bunch and how can we accelerate it?**
- **How does the magnetic field relate to the cavities' RF frequency in a synchrotron?**
- **What kind of basic effects (building blocks) do we need to consider in a numerical model?**

References

- CERN BLonD Beam Longitudinal Dynamics code: <http://blond.web.cern.ch>
- Machine operation websites accessible via: <https://espace.cern.ch/be-dep/OP/default.aspx>
- S.Y. Lee: [Accelerator Physics](#), World Scientific, Singapore, 2012
- A.W. Chao: [Physics of collective beam instabilities in high energy accelerators](#), Wiley, New York, 1993
- S. Hancock: PS RF manipulations measured with the PS tomograph <https://tomograp.web.cern.ch/tomograp/examples.html>
- S. Hancock: PS BCMS production scheme <https://indico.cern.ch/event/238152/session/2/contribution/9/material/slides/1.pdf>
- H. Timko: Studies on PS bunch rotation and PS-SPS transmission <http://journals.aps.org/prstab/pdf/10.1103/PhysRevSTAB.16.051004>
- Slip stacking: [Anckenbrandt](#) (1981), [MacLachlan](#) (2001), [Seiya et al.](#) (2008)