

*CMS and ATLAS
di-boson and aTGC(aQGC)
meeting*



ZZ 7 TeV ATLAS+CMS aTGC combination status

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aTGC combination status

An effort to combine aTGC limits from ATLAS+CMS is ongoing.

- First goal is to tune ATLAS and CMS tools to provide consistent results using ZZ 7TeV input
 - At the moment tuning tools with deltaNLL criteria (goal: limits within 1%)
- Identified many technical differences in the way how the aTGC limits were set between experiments

ATLAS publication

<https://atlas.web.cern.ch/Atlas/GROUPS/PHYSICS/PAPERS/STDM-2012-02/>

- Channels: ZZ->4l and ZZ->2l2nu
- Signal: Sherpa MC with ME weights
- Fit on Pt(Z) distribution
- F-C limits
- trG nuisance shape; nuisance summation:

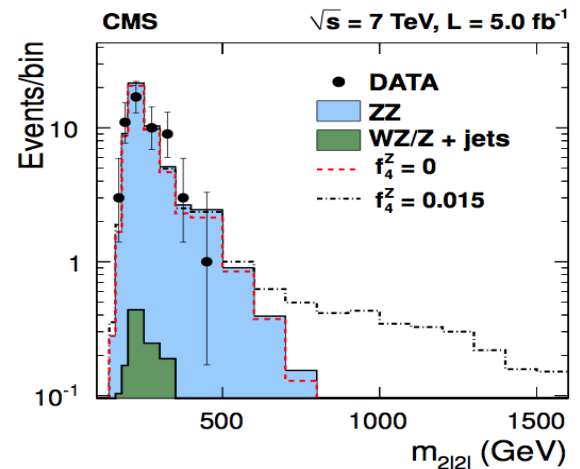
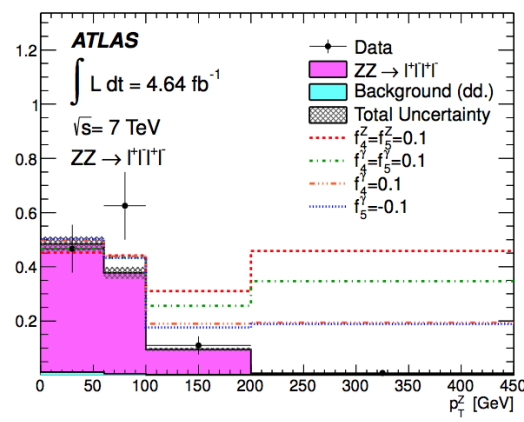
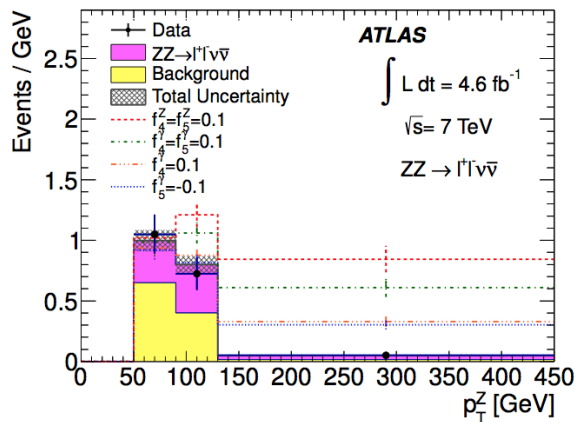
$$N_{-i} = N_{-i}(S) \left(1 + \sum_k \sigma_k^i \tau_k\right)$$

CMS publication

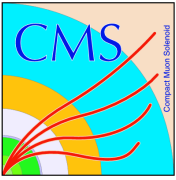
<http://link.springer.com/article/10.1007%2FJHEP01%282013%29063>

- Channel: ZZ->4l
- Signal: Sherpa MC with pol2 fit on reco yields
- Fit on M(ZZ) distribution
- CLs limits; RooStats combine
- lnN nuisance shape; nuisance summation:

$$N_{-i} = N_{-i}(S) \prod_k (1 + \sigma_k^i \tau_k)$$



Exchange format: text file with yields, signal parameter fit values and uncertainties.



Updates since our last meeting

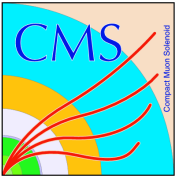


1. Cross checked channels with disagreement $>1\%$ by comparing limits when adding uncertainties to the fit one-by-one
2. Fixed inconsistency in systematic uncertainty in $ZZ \rightarrow 2l2\nu$ channel
3. Fixed systematic disagreement in expected limit
 - Due to difference in definition of expected limit (toys \rightarrow Asimov dataset, post-fit \rightarrow pre-fit nuisances)
4. Few bug fixes

Overall status:

Achieved 1% agreement in all (**almost all**) 1D observed (expected) limits

- for every channel individually and combined
- with and without uncertainty included in the fit
- with $\ln N$ and trG uncertainty shape



Expected limits (f5) with full uncertainty



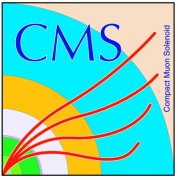
All within 1%!

1D deltaNLL limit		f_5^y		f_5^z	
<u>ATLAS input:</u>		CMS code	ATLAS code	CMS code	ATLAS code
4l	lnN	[-0.0179, 0.0177]	[-0.0180, 0.0178]	[-0.0152, 0.0152]	[-0.0153, 0.0153]
	trG	[-0.0180, 0.0178]	[-0.0181, 0.0180]	[-0.0153, 0.0153]	[-0.0154, 0.0154]
2l2nu	lnN	[-0.0186, 0.0173]	[-0.0187, 0.0175]	[-0.0156, 0.0146]	[-0.0158, 0.0148]
	trG	[-0.0192, 0.0180]	[-0.0192, 0.0180]	[-0.0162, 0.0151]	[-0.0162, 0.0151]
4l +2l2nu	lnN	[-0.0149, 0.0143]	[-0.0151, 0.0143]	[-0.0126, 0.0121]	[-0.0128, 0.0121]
	trG	[-0.0153, 0.0146]	[-0.0153, 0.0147]	[-0.0129, 0.0124]	[-0.0129, 0.0124]

1D deltaNLL limit		f_5^z		f_5^y	
<u>CMS input:</u>		CMS code	ATLAS code	CMS code	ATLAS code
4l	lnN	[-0.0169, 0.0167]	[-0.0170, 0.0167]	[-0.0141, 0.0144]	[-0.0143, 0.0145]
	trG	[-0.0170, 0.0167]	[-0.0169, 0.0167]	[-0.0142, 0.0144]	[-0.0142, 0.0144]

1D deltaNLL limit		f_5^z		f_5^y	
		CMS code	ATLAS code	CMS code	ATLAS code
<u>combined</u>	lnN	[-0.0125, 0.0120]	[-0.0126, 0.0119]	[-0.0105, 0.0103]	[-0.0105, 0.0103]
	trG	[-0.0126, 0.0122]	[-0.0127, 0.0121]	[-0.0106, 0.0104]	[-0.0106, 0.0104]

Correlated uncertainties for ATLAS+CMS combination: luminosity and theoretical uncertainty on signal.



Observed limits (f5) with full uncertainty



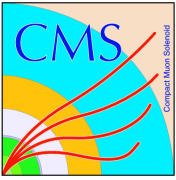
All within 1%!

1D deltaNLL limit		f_5^y		f_5^z	
<u>ATLAS input:</u>		CMS code	ATLAS code	CMS code	ATLAS code
4l	lnN	-	-	-	-
	trG	[-0.0182, 0.0182]	[-0.0183, 0.0182]	[-0.0155, 0.0156]	[-0.0155, 0.0156]
2l2nu	lnN	-	-	-	-
	trG	[-0.0205, 0.0192]	[-0.0204, 0.0192]	[-0.0172, 0.0162]	[-0.0172, 0.0162]
4l +2l2nu	lnN	[-0.0151, 0.0144]	[-0.0152, 0.0145]	[-0.0128, 0.0122]	[-0.0129, 0.0123]
	trG	[-0.0153, 0.0146]	[-0.0154, 0.0147]	[-0.0129, 0.0124]	[-0.0130, 0.0124]

1D deltaNLL limit		f_5^z		f_5^y	
<u>CMS input:</u>		CMS code	ATLAS code	CMS code	ATLAS code
4l	lnN	[-0.0129, 0.0126]	[-0.0128, 0.0125]	[-0.0107, 0.0109]	[-0.0107, 0.0109]
	trG	[-0.0129, 0.0126]	[-0.0128, 0.0125]	[-0.0107, 0.0109]	[-0.0107, 0.0109]

1D deltaNLL limit		f_5^z		f_5^y	
		CMS code	ATLAS code	CMS code	ATLAS code
<u>combined</u>	lnN	[-0.0108, 0.0103]	[-0.0108, 0.0103]	[-0.00906, 0.00886]	[-0.00902, 0.00885]
	trG	[-0.0108, 0.0104]	[-0.0108, 0.0103]	[-0.00908, 0.00890]	[-0.00907, 0.00891]

Correlated uncertainties for ATLAS+CMS combination: luminosity and theoretical uncertainty on signal.



Expected limits (f4) with full uncertainty



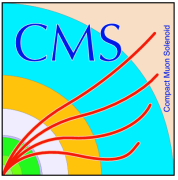
2% off all other within 1%

1D deltaNLL limit		f_4^y		f_4^z	
<u>ATLAS input:</u>		CMS code	ATLAS code	CMS code	ATLAS code
4l	lnN	[-0.0175, 0.0175]	[-0.0176, 0.0176]	[-0.0150, 0.0150]	[-0.0150, 0.0150]
	trG	[-0.0177, 0.0176]	[-0.0177, 0.0177]	[-0.0151, 0.0151]	[-0.0152, 0.0153]
2l2nu	lnN	[-0.0177, 0.0176]	[-0.0177, 0.0176]	[-0.0149, 0.0149]	[-0.0149, 0.0149]
	trG	[-0.0183, 0.0182]	[-0.0184, 0.0183]	[-0.0154, 0.0154]	[-0.0155, 0.0155]
4l +2l2nu	lnN	[-0.0144, 0.0143]	[-0.0143, 0.0143]	[-0.0122, 0.0122]	[-0.0122, 0.0122]
	trG	[-0.0147, 0.0147]	[-0.0145, 0.0145]	[-0.0125, 0.0125]	[-0.0124, 0.0124]

1D deltaNLL limit		f_4^z		f_4^y	
<u>CMS input:</u>		CMS code	ATLAS code	CMS code	ATLAS code
4l	lnN	[-0.0140, 0.0145]	[-0.0138, 0.0148]	[-0.0140, 0.0145]	[-0.0137, 0.0148]
	trG	[-0.0140, 0.0145]	[-0.0138, 0.0148]	[-0.0140, 0.0145]	[-0.0138, 0.0148]

1D deltaNLL limit		f_4^z		f_4^y	
		CMS code	ATLAS code	CMS code	ATLAS code
<u>combined</u>	lnN	[-0.0119, 0.0123]	[-0.0120, 0.0123]	[-0.0102, 0.0104]	[-0.0102, 0.0104]
	trG	[-0.0120, 0.0125]	[-0.0121, 0.0125]	[-0.0103, 0.0105]	[-0.0103, 0.0105]

Correlated uncertainties for ATLAS+CMS combination: luminosity and theoretical uncertainty on signal.



Observed limits (f_4) with full uncertainty



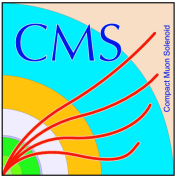
All within 1%!

1D deltaNLL limit		f_4^y		f_4^z	
<u>ATLAS input:</u>		CMS code	ATLAS code	CMS code	ATLAS code
4l	lnN	-	-	-	-
	trG	[-0.0180, 0.0180]	[-0.0180, 0.0180]	[-0.0154, 0.0154]	[-0.0154, 0.0154]
2l2nu	lnN	-	-	-	-
	trG	-	[-0.0195, 0.0194]	-	[-0.0165, 0.0164]
4l +2l2nu	lnN	[-0.0146, 0.0146]	[-0.0147, 0.0146]	[-0.0124, 0.0124]	[-0.0125, 0.0125]
	trG	[-0.0148, 0.0148]	[-0.0148, 0.0148]	[-0.0126, 0.0126]	[-0.0126, 0.0126]

1D deltaNLL limit		f_4^z		f_4^y	
<u>CMS input:</u>		CMS code	ATLAS code	CMS code	ATLAS code
4l	lnN	[-0.0122, 0.0134]	[-0.0122, 0.0133]	[-0.0104, 0.0111]	[-0.0104, 0.0111]
	trG	[-0.0122, 0.0133]	[-0.0121, 0.0133]	[-0.0104, 0.0111]	[-0.0104, 0.0111]

1D deltaNLL limit		f_4^z		f_4^y	
		CMS code	ATLAS code	CMS code	ATLAS code
<u>combined</u>	lnN	[-0.0102, 0.0108]	[-0.0102, 0.0108]	[-0.00871, 0.00909]	[-0.00870, 0.00907]
	trG	[-0.0103, 0.0109]	[-0.0103, 0.0108]	[-0.00874, 0.00913]	[-0.00875, 0.00912]

Correlated uncertainties for ATLAS+CMS combination: luminosity and theoretical uncertainty on signal.

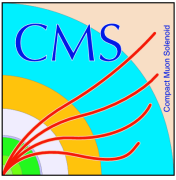


Problematic Expected limit (f_4) in close



Comparison of limits while adding uncertainties one-by-one in the fit.

1D deltaNLL limit (trG)	f_4^Z		
<u>CMS input:</u>	CMS code	ATLAS code	Relative difference (%)
no uncertainty	[-0.013771, 0.014343]	[-0.013789, 0.014398]	[-0.13, -0.38]
ZZ other only	[-0.013967, 0.014531]	[-0.014054, 0.014561]	[-0.62, -0.21]
adding ZZ theory	[-0.013975, 0.014539]	[-0.014074, 0.014551]	[-0.71, -0.08]
adding bkg uncertainty	[-0.013975, 0.014539]	[-0.013976, 0.014536]	[-0.00, 0.02]
adding lumi (all uncertainties)	[-0.013979, 0.014539]	[-0.013841, 0.014794]	[0.99, -1.76]



Open questions and todo list



Open questions

Statistical criteria for final combined measurement

- Both experiments agree that F-C is appropriate criteria?

Uncertainty shape

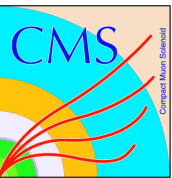
- Both experiments agree with lnN shape?

Definition of expected limit

- Asimov dataset or toys?
- A posteriori (post-fit: with nuisance parameters set to best fit values from fit on data) vs a priori (pre-fit: all nuisance parameters set to 0) expected

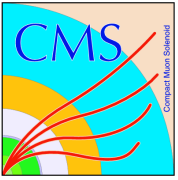
Todo list

- Understand and fix disagreement in expected f_4^z limit for CMS input
 - Run 2D limits
 - Run F-C limits



Backup





Uncertainty table for the combination



uncertainty	ATLAS: 4l [p _T Z]	ATLAS: 2l2nu [p _T Z]	CMS: 4l [MZZ]
<i>N_bins</i>	4	3	5 (x3 channels)
Luminosity	3.9%	3.9%	2.2%
Stat on signal	Shape (UNCORR bins)	-	-
	-	Shape (UNCORR bins)	-
Stat on bkg data-driven	Shape (UNCORR bins)	-	-
	-	Shape (UNCORR bins)	-
Stat on bkg MC	-	Shape (UNCORR bins)	-
Reco uncertainty	Shape (CORR bins)	Shape (CORR bins)	-
Syst on bkg data-driven	Shape (cross CORR bins)	Shape (cross CORR bins)	-
Syst on bkg MC	-	Shape (CORR bins)	-
Total bkg uncertainty	-	-	Per channel (CORR bins)
Signal other (stat+fit+reco)	-	-	13.42% (CORR bins, CORR channel)
Signal theory (PDF+scale)	Shape (CORR bins)	Shape (CORR bins)	4% (CORR bins)

Uncertainties in the same row are correlated!