PURESAFE Final Conference

Wednesday 21 January 2015

SESSION 4 - TELEROBOTICS AND REMOTE HANDLING - 503/1-001 - Council Chamber (08:50 - 13:00)

-Conveners: Rachid ALAMI

time	[id] title	presenter
08:50	[20] Welcome	
09:00	[21] Vision for Robotic Manipulation	SICILIANO, Bruno
09:50	[22] Telerobotic Challenges Addressed by PURESAFE	FERRE, Manuel
10:30	Coffee Break	
11:00	[23] Status of the Target Handling on the pbar-Target at FAIR	HELMECKE, Manuela
	[24] On Design and Development of Super Fragment Separator (Super-FRS) Remote Handling Logistics: Systems Engineering Prospective (RP9)	AMJAD, Faraz
	[25] A Systematic Approach to Define, Analyze and Develop Remote Handling Tasks in Radiation Areas (RP7)	ORONA, Luis
12:00	[26] Design for Remote Handling Compatibility at CERN – First Steps	KERSHAW, Keith
12:20	[52] Practical Experiences from Remote Handling in Fusion	ROLFE, Alan