A common real time framework for SuperKEKB and Hyper Suprime-Cam at Subaru telescope

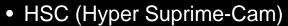
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Introduction

SuperKEKB

- In KEK, Tsukuba, Japan
- Observation of CPV in B-meson decay in e⁺e⁻ collision
- Better understanding of CPV phenomena
- Upgrade Belle experiment
 - Much larger data than Belle
 - Luminosity: ~10³⁶cm⁻²s⁻¹
 - 50 billion BB-bar pair (50ab⁻¹)
 - ~250KB / event, 2GB / sec.



- Subaru telescope, Hawaii, USA
- Search for Dark energy
- Next generation CCD camera for Subaru telescope
- Take the place of SC (Suprime-Cam) in 2011
- 110 CCDs arranged in grid
- 1 shot / 5 min. (including exposure time), 1.5GB / shot (880M pixels)
 - 1.5GB data for every 5 minutes
 - Data should be processed in 20 seconds to determine next exposure





Motivation

- Larger data to be processed for upgraded experiments
 - For SuperKEKB, ~100 times larger data than Belle experiment
 - For HSC, ~10 times larger data than SC
- Common interests in data processing between SuperKEKB and HSC
 - Real-time / On-demand processing parts
 - Module based data processing
- The limitation of current framework
 - Object persistence
 - Obsolete packages and environments
- New computing resources
 - Classic resources SMP, network clusters
 - New resources GRID, cloud computing and et cetera

Requirements

Software Pipeline Architecture

- Module pipelining for data processing
- Real-time / On-demand module pipelining

Object-oriented Framework

- Provides convenient interface to the most common analysis tool ROOT
- Object persistence in data handling
- Supports legacy interface

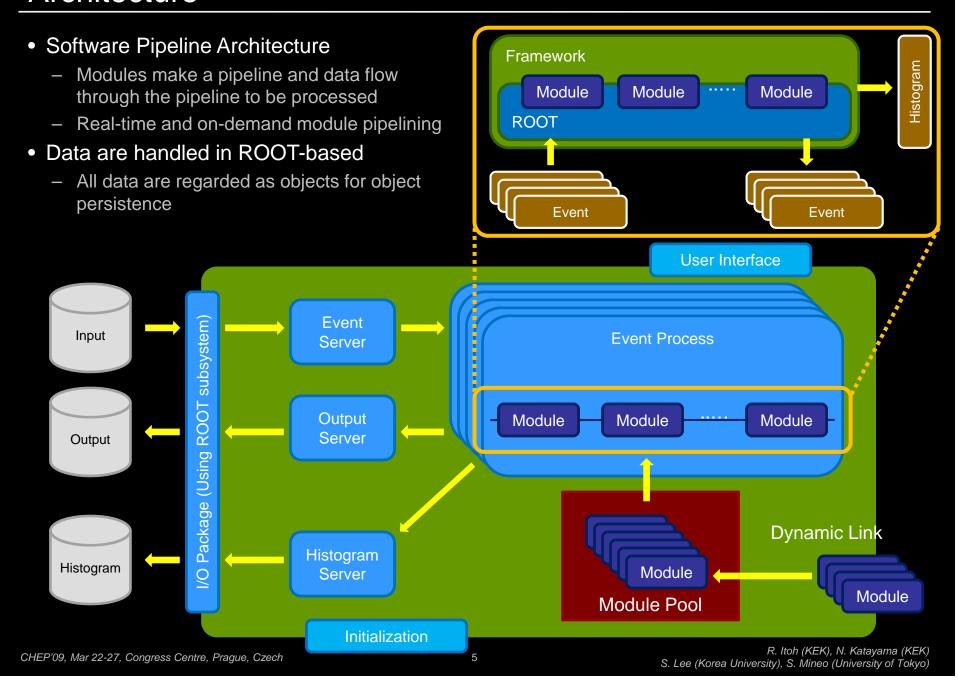
Real-time and Parallel Processing

- Huge data processing in real-time
- Data / module parallel processing
- Not only for the SMP but also network clusters and GRID
- Module pipelining over network
- Versatile and transparent parallel processing layer
- Provide an interface for new computing resources
- Dynamic optimization of resource allocation

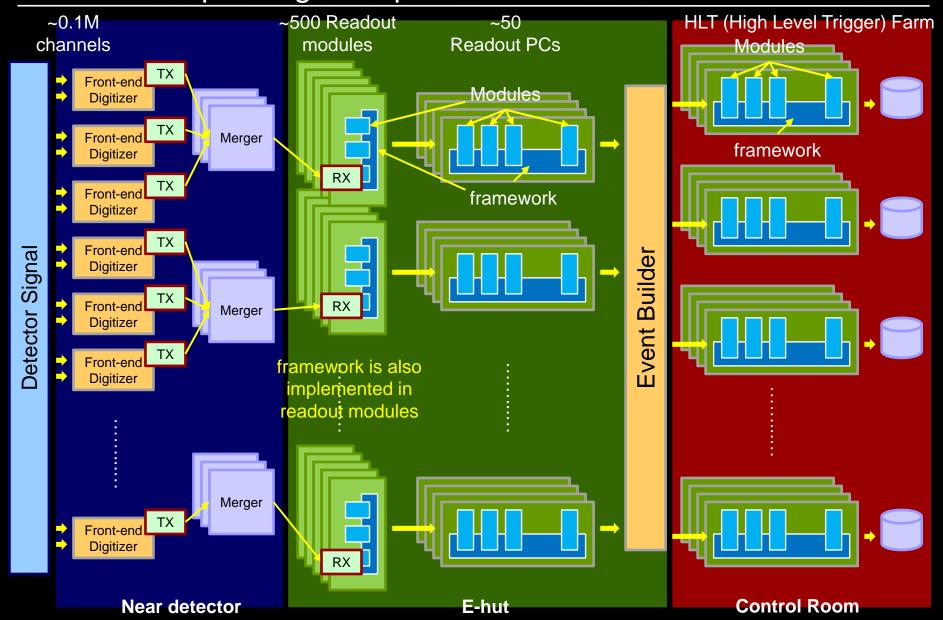
Integrated Environment

- No boundary between DAQ and offline analysis
- Integrated access method to ROOT files over GRID network

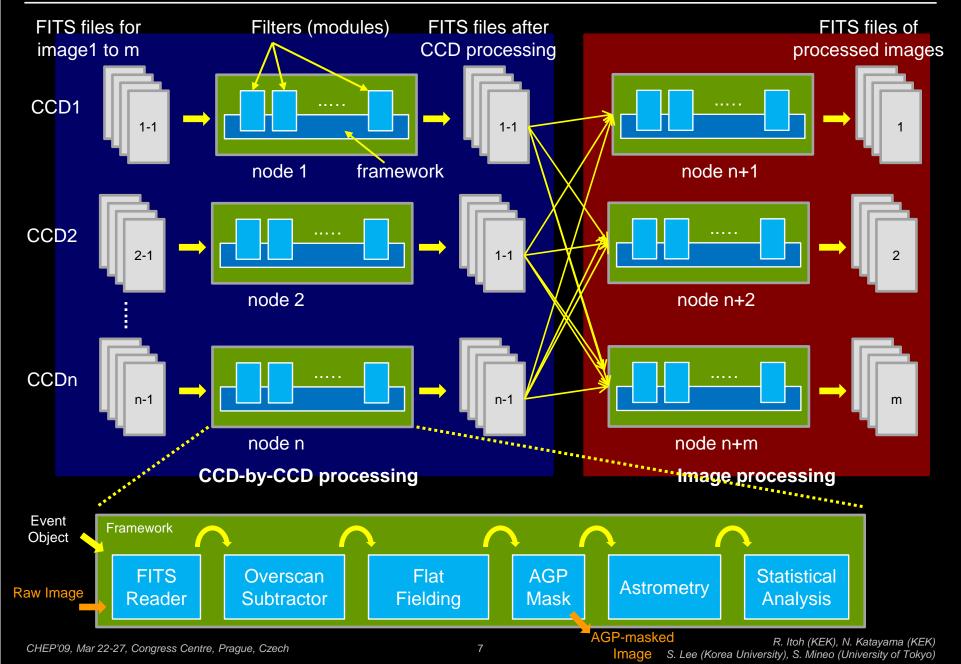
Architecture



Real-time Pipelining in SuperKEKB

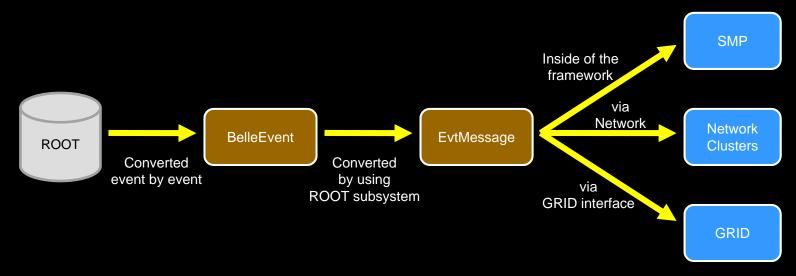


Real-time Pipelining in HSC



Object Persistence

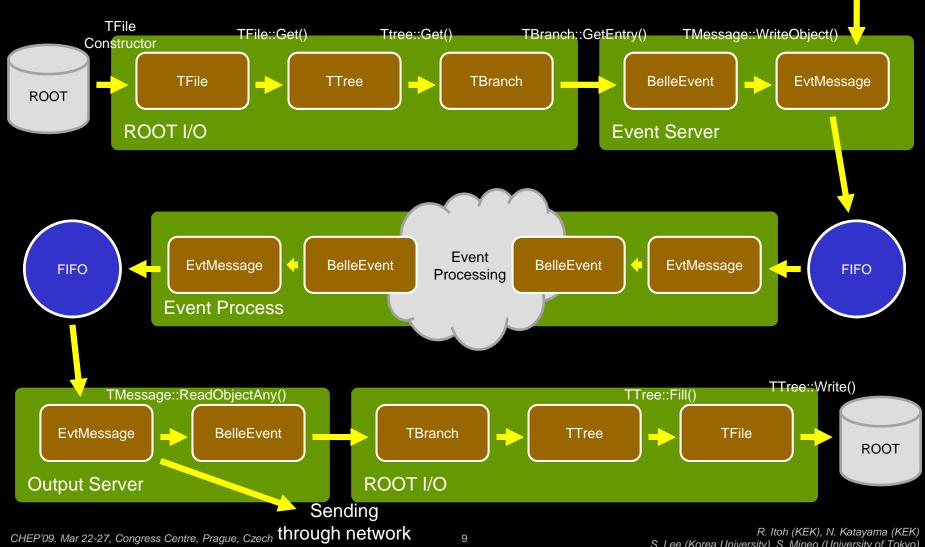
- All data inside the framework are regarded as objects
- BelleEvent Object
 - A basic unit of event data in user level
 - Input / Output ROOT files consist of BelleEvent object itself
 - Provides functions to get information from event data
- EvtMessage Object
 - A basic unit of event data for transferring inside of the framework
 - EvtMessage is derived from TMessage in ROOT
 - Event data are encapsulated as EvtMessage and transferred inside of SMP, through network clusters and GRID



Object-oriented Data Flow in SMP

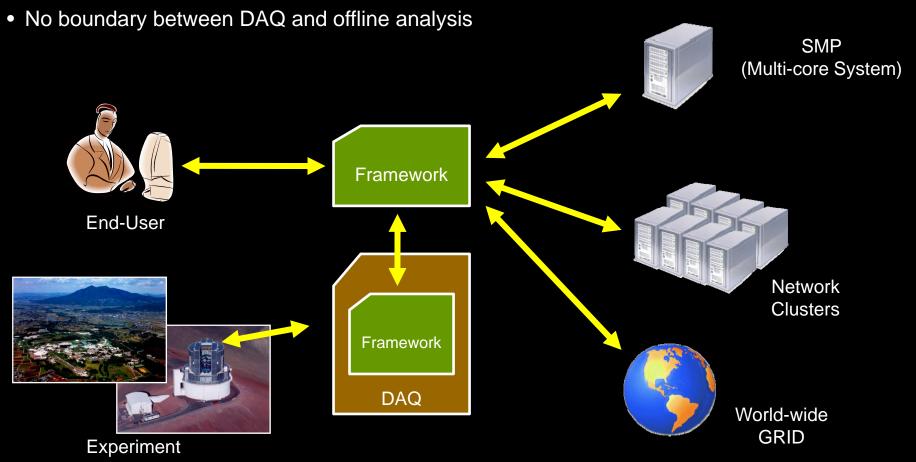
- The ROOT subsystem is used for ROOT I/O and building EvtMessage
- Data are divided event by event and are encapsulated defined objects

Receiving from network

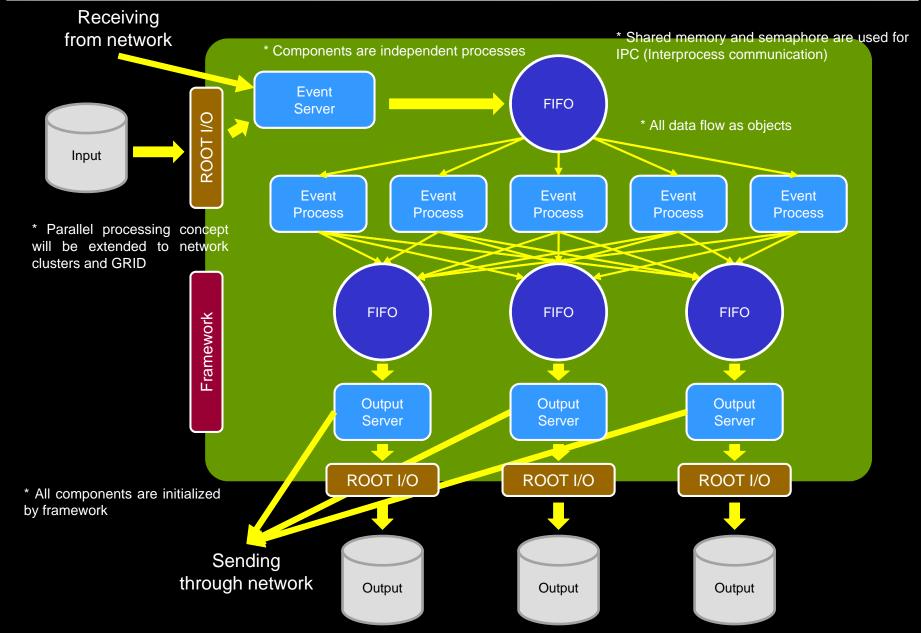


Parallel Processing Strategy

- New framework will provide consistent interface for parallel processing
- Dynamic resource selection among SMP, network clusters, and GRID by framework
- ROOT subsystem for networking (TSocket) will be used for network clusters
- GRID interface could be integrated into the new framework



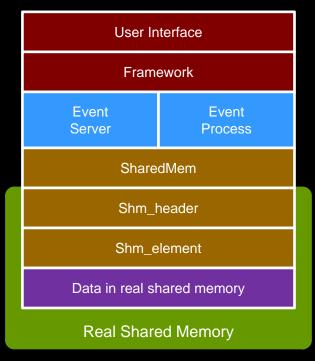
Parallel Processing Scheme in SMP

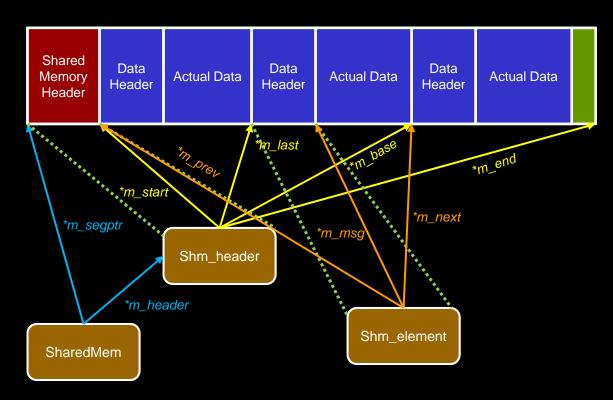


Shared Memory as FIFO (First-In First-Out)

- Logical Structure of shared memory as FIFO
 - Layers make a hierarchy
- Each components has pointers to handle shared memory scheme
- This logical structure provides behavior of FIFO
 - Earlier input data is sent first
 - Similar to ring buffer





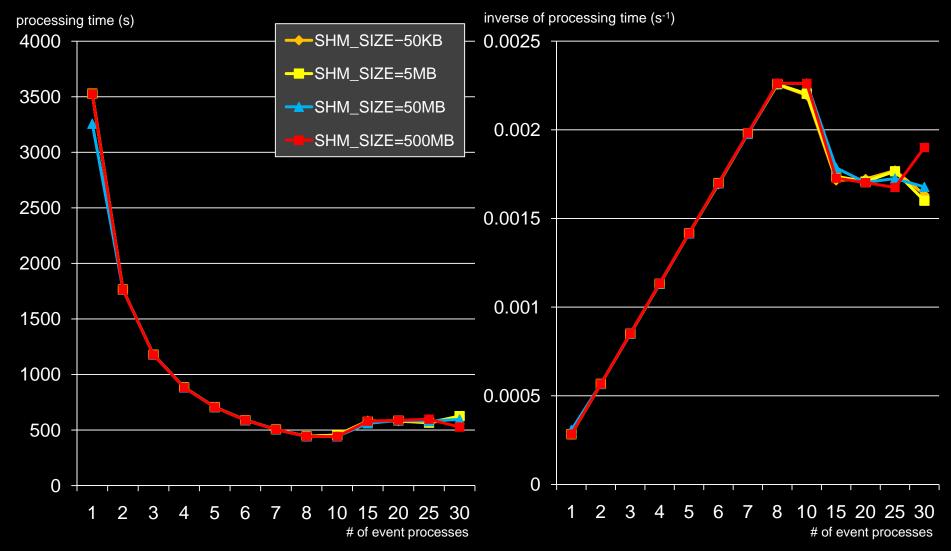


Current Development Status

- Fundamental components of the framework are implemented
 - Interfaces to handle modules, I/O
 - Many parts of codes are reused from the old framework of Belle experiment
- Object-oriented data flow scheme is designed and implemented
 - By combining ROOT subsystem, object persistence in the framework is implemented
 - Objects are designed for not only SMP but also distributed computing systems
- Parallel data processing
 - Designed and implemented for SMP first
 - Customized shared memory is designed and implemented
 - Integration parallel processing part (including shared memory) to the framework
 - Functionalities are tested in various environments
 - Performance behaviors for various # of CPUs are observed by testing
- Parallel module pipelining
 - Integration HSC modules to the framework
 - Real-time image processing is tested

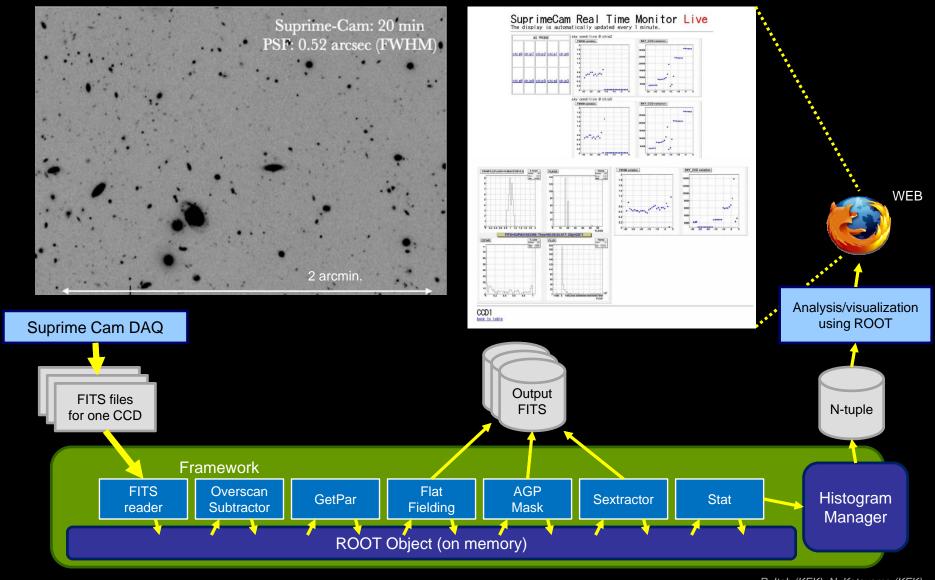
Performance Test – Time Consumption of Modules

- 8-core system (Xeon E5405 (2Ghz, Quad-core) * 2, 8GB RAM)
- # of events to be processed: 100,000 events (~300KB per events)



Functionality Test in SC (Suprime-Cam)

• The framework is combined with HSC modules and the functionalities are tested



Summary

- Upgraded experiments require more powerful framework
 - SuperKEKB and HSC
- The framework is based on software pipeline architecture
 - Real-time / On-demand pipelining
- Key functionalities
 - Object persistence
 - ROOT-based data handling
 - Convenience for both of end-users and developers
 - Parallel processing
 - Parallel data processing and module pipelining
 - Provides an integrated interface to local computing resources SMP and network clusters
 - A bridgehead for using world-wide computing resources
- The framework is being developed
 - Parallel data processing in SMP is developed and tested
 - Implementation in network clusters by this fall
 - Implementation for GRID by early of next year
 - Parallel module pipelining over network is developed and tested