



The ATLAS High Level Trigger Steering

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With acknowledgement to ATLAS T/DAQ.



Outline

- Setting the scene: ATLAS trigger
- Motivation: HLT strategy
- Solution: HLT Steering
- Steering details:
 - Trigger Menu
 - Configuration
 - Algorithms
 - Logic
 - Caching
- Performance
- Monitoring
- Conclusions



The ATLAS Trigger System

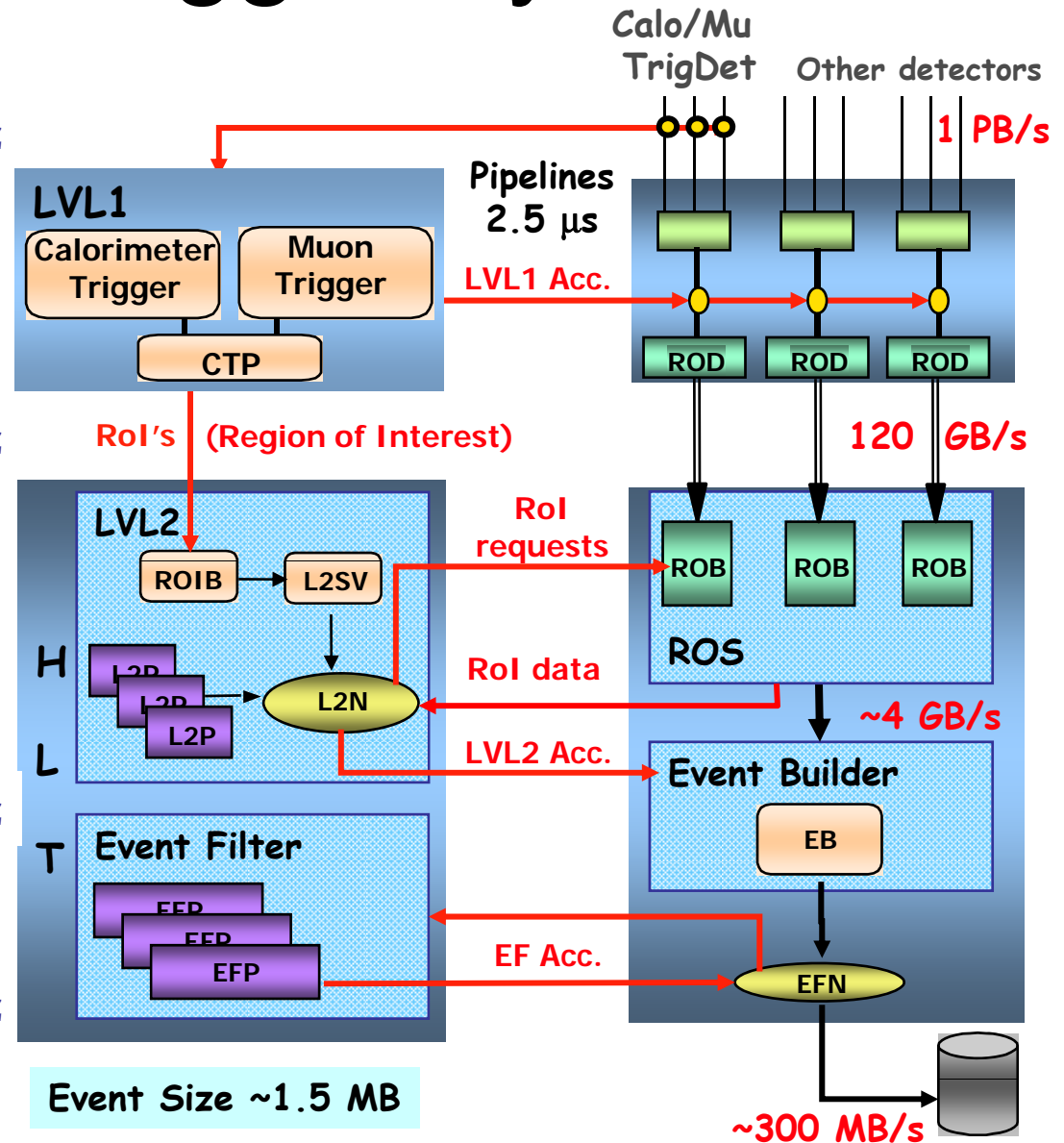
- Level 1
 - Hardware based
 - Coarse granularity calorimeter and muons only
- High Level Trigger (HLT)
 - **Level 2** and **Event Filter**
 - Software based
 - Mostly commodity hardware (PC + Ethernet)
- Level 2 (L2)
 - Data requested from ROBs over network
 - Full detector granularity in Rols
 - Special fast algorithms
- Event Filter (EF)
 - Seeded by L2
 - Potential full event access
 - Full detector granularity
 - Offline algorithms

40 MHz

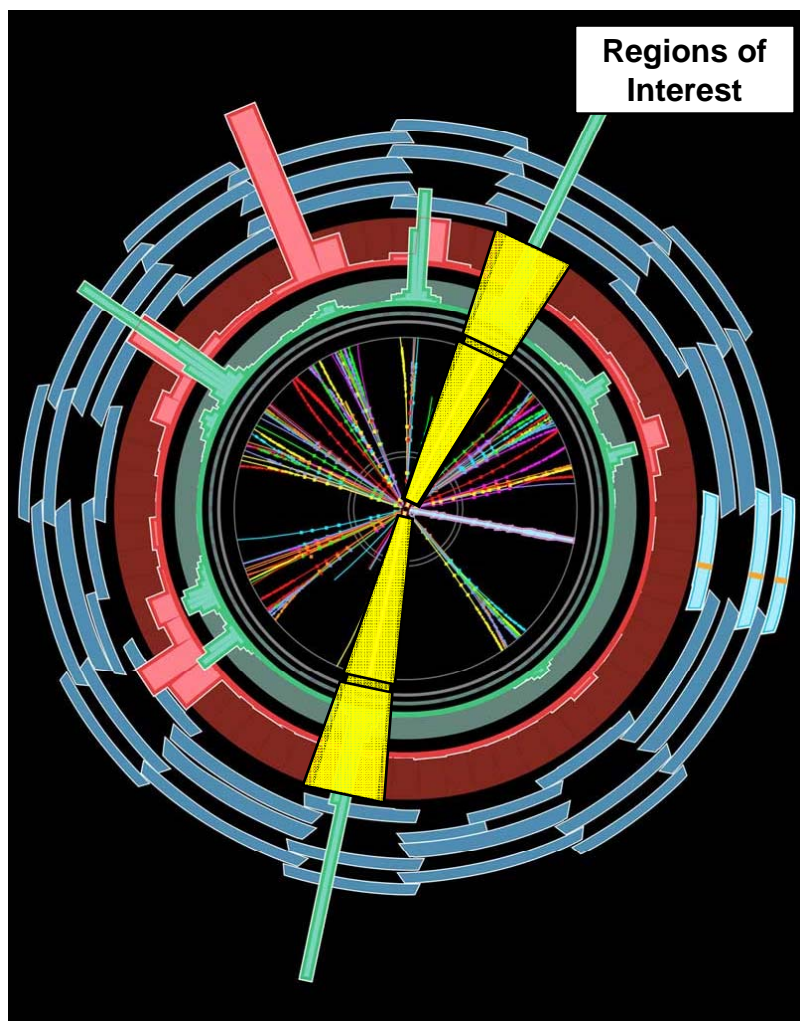
75 kHz

~3 kHz

~200 Hz



Key features of ATLAS trigger strategy



- HLT uses Regions of Interest
 - Based on L1 triggers
 - Reduce data bandwidth at L2
 - Reduce processing time
- Early rejection
 - Three level trigger
 - **Steps** within L2 and EF
 - Reduce processing time
 - Reduce decision latency

HLT steering - in a nutshell

- RoI mechanism
 - Each trigger level or sub-**step** is seeded by the result of the previous one
- Early rejection
 - Drop event as soon as it cannot pass the trigger
 - Minimise average processing time
- Fast
 - Leave most time for event-selection algorithms
- Flexible
 - Enable/disable triggers
 - Construct complex menus from simple building blocks
- Instrumented for monitoring
- Work in both online and offline s/w environments
 - Online data taking
 - Offline development/debugging and simulation



Sample trigger menu

Generic name	e5	e5_PT	e10	g10	2e10	e20_XE12	XE12
LVL1	EM3 PS		EM8		2EM8	EM18_XE12	XE12 PS
LVL2	e5	PT	e10	g10	2e10	e20_xe12	PT
EF	e5	PT	e10	g10	2e10	e20_xe12	PT

Chain:

represents several steps,
several algorithms at
each step

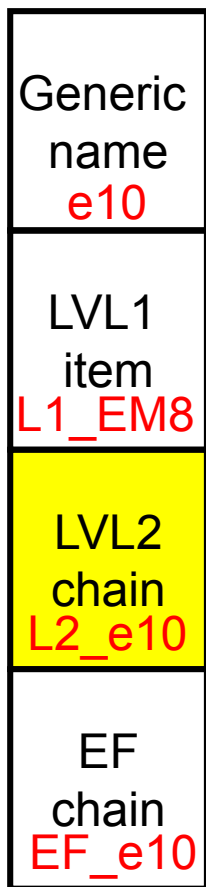
From
It c
var

multiple and combined triggers,
(PS) and/or pass through (PT)

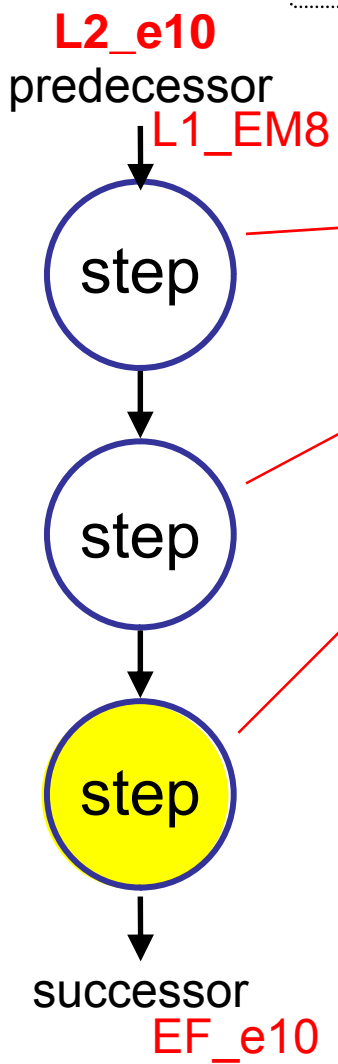


Steering concepts

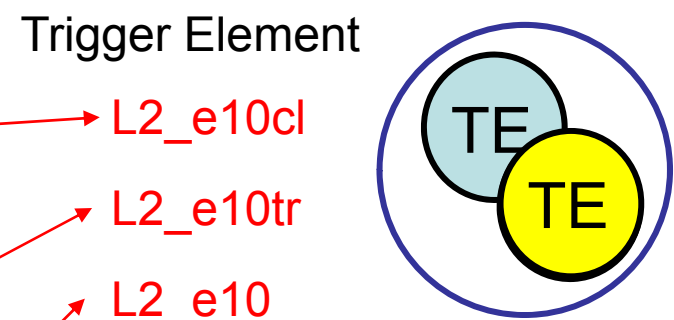
See also: J Stelzer "The configuration system of the ATLAS trigger" Thu 15:20 (Software components, tools and databases)



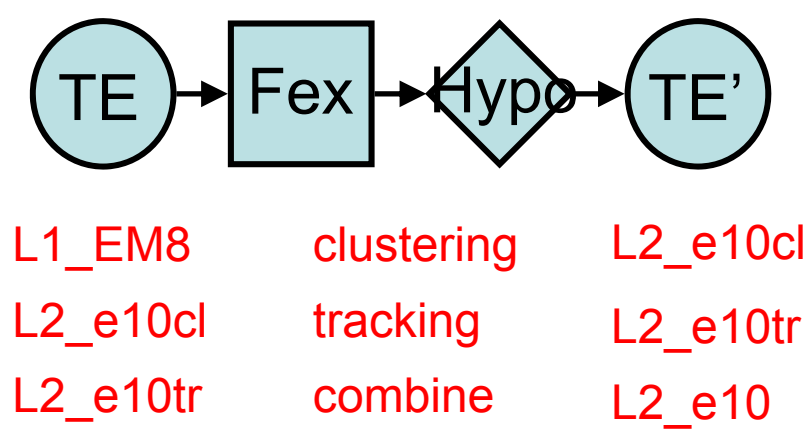
Chain



Step

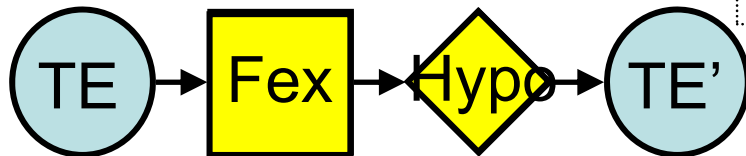


Sequence



Algorithms

Sequence



See also: T Fonseca Martin “Event reconstruction algorithms for the ATLAS trigger” Mon 17:55 (Online Computing)

Typical feature extraction (Fex) algorithm:

- Seeded by previous step or RoI
- Retrieves detector data
- Finds “feature” e.g. cluster, track
- Updates RoI position
- Runs once per RoI

Typical hypothesis (Hypo) algorithm:

- Follows Fex algorithm
- Compares features to hypothesis
- Marks TE' as valid or not
- Runs once per threshold

Example Hypotheses:

Calo cluster: Cut on cluster shape parameters

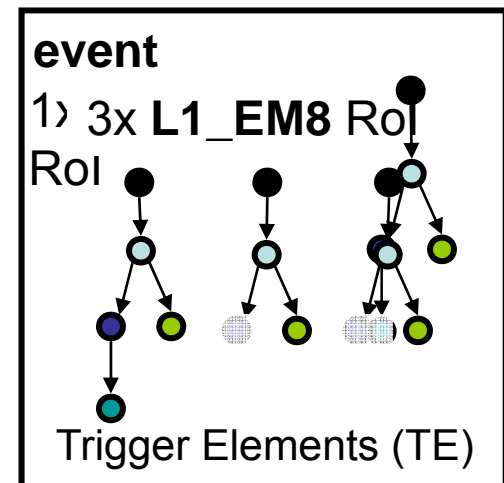
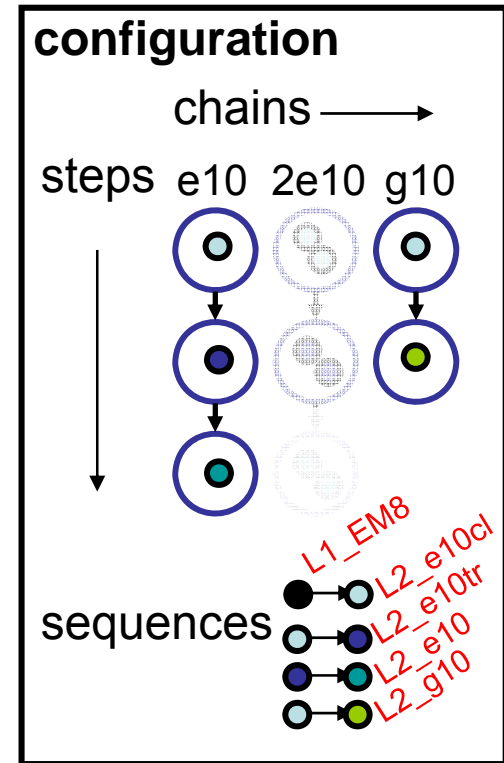
Electron: cut on cluster-track matching variables

Most cases: apply E_T or p_T threshold

Other types of algorithm available for more complex logic.

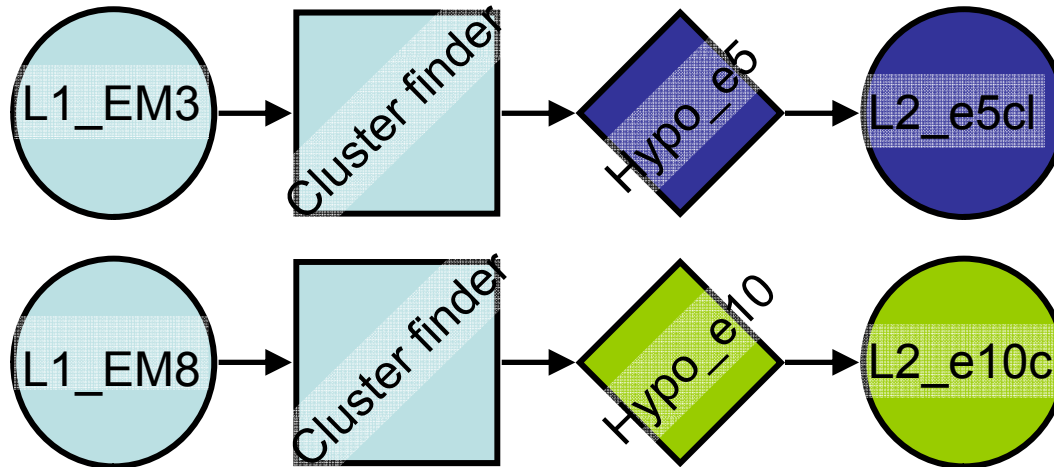
Steering logic

- Static configuration + dynamic event state
- First create initial TEs from L1 Rols
 - One per threshold per Rol
 - At EF, from L2 output instead
- Activate relevant chains
- Loop over steps
 - Loop over active chains
 - Loop over TEs (event) that match step requirements (config)
 - Run sequence that links TE from prev. step in chain to required TE
 - Result (depends on algorithms): TE is active or not
 - If insufficient active TEs remain, deactivate chain
 - If no active chains remain, end loop
- Apply pre-scale, pass-through and reject/accept event



Caching

Two sequences: same fex, different hypo:



1) Steering will run fex only once;

Second time, results are taken from cache

2) Same sequence in different chains is also cached

⇒ **Implicit caching** when same item appears multiple times in configuration

Benefits of caching

- Useful gain in speed
- Simplifies configuration
- Times consistent with target

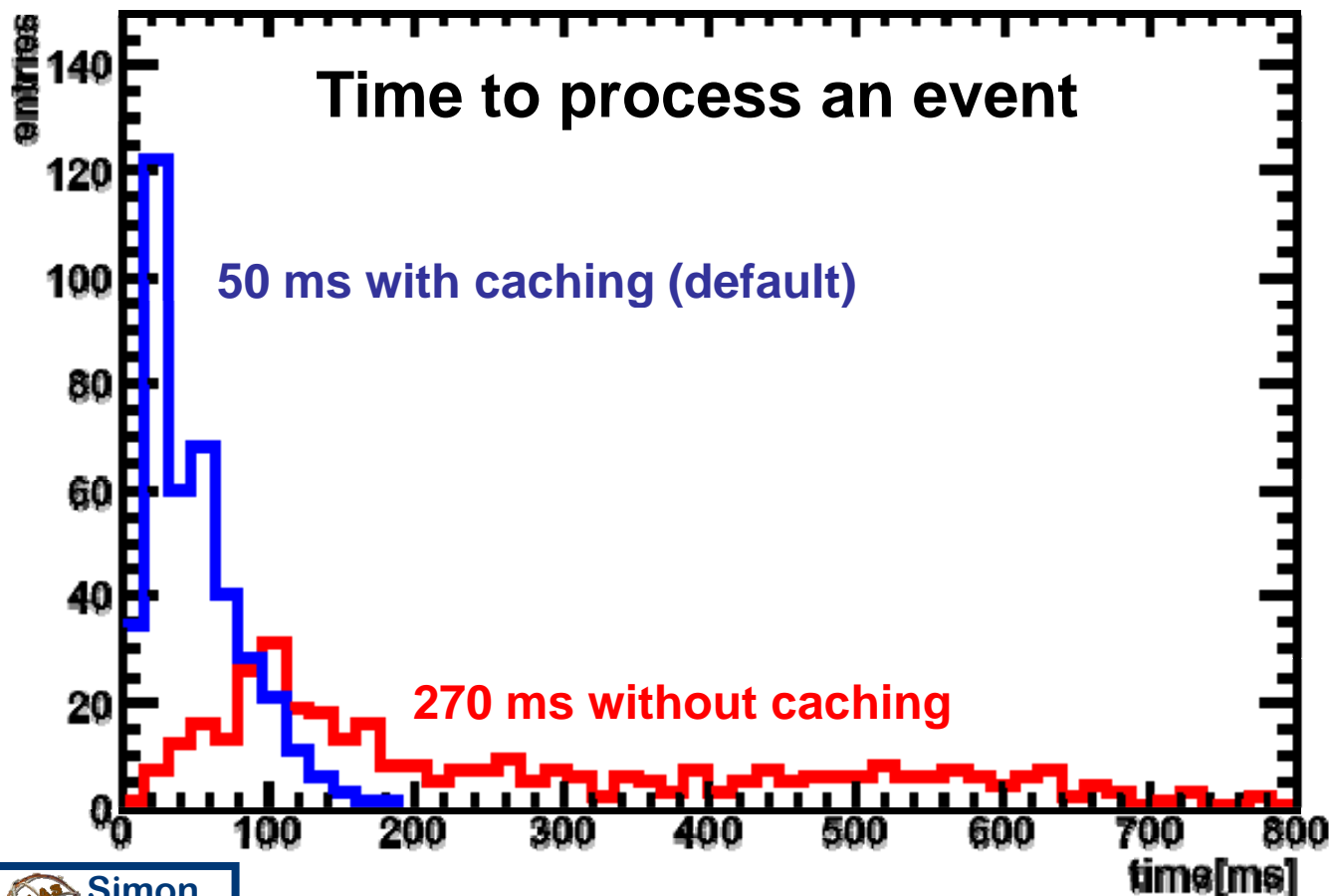
3 GHz Xeon CPU

Code is not yet optimised: expect to reduce steering time.

No rejection: worst case scenario.

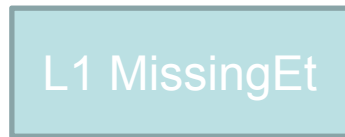
Inclusive e/γ menu for very low lumi.

400 top events: atypically busy; average 16 Rols (~4 EM) per event rather than the usual ~2.

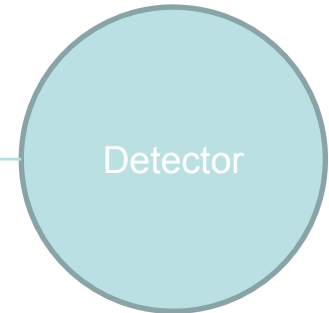


Missing E_T trigger

Trigger level 1



coarse calorimeter cells



8 MET thresholds

4 SumET thresholds



Trigger level 2



Refine L1 MET by adding all L2 muons



Check energy against hypothesis



Calculate $\Delta\phi$ btw. hardest jets & MET



Cut on angles

Trigger level 3 (EF)

Start from fine granularity calorimeter cells
Then again, add EF muons ...

- 1) L2 MET trigger algorithms get all available muons (jets) and the last MET as inputs!
- 2) When executed again (for 2nd L1 threshold), the old results are re-used: sequence caching



HLT steering - overhead time

- Framework is only small fraction of total
- Times consistent with target

3 GHz Xeon CPU

Average time to process an event

Chains Evaluation 47.73(94.0 %)

Code is not yet optimised: expect to reduce steering time.

No rejection: worst case scenario.

Inclusive e/γ menu for very low lumi.

400 top events: atypically busy; average 16 Rols (~4 EM) per event rather than the usual ~2.



Monitoring Overhead 0.53(1.0 %)

Result Building 0.45(0.9 %)

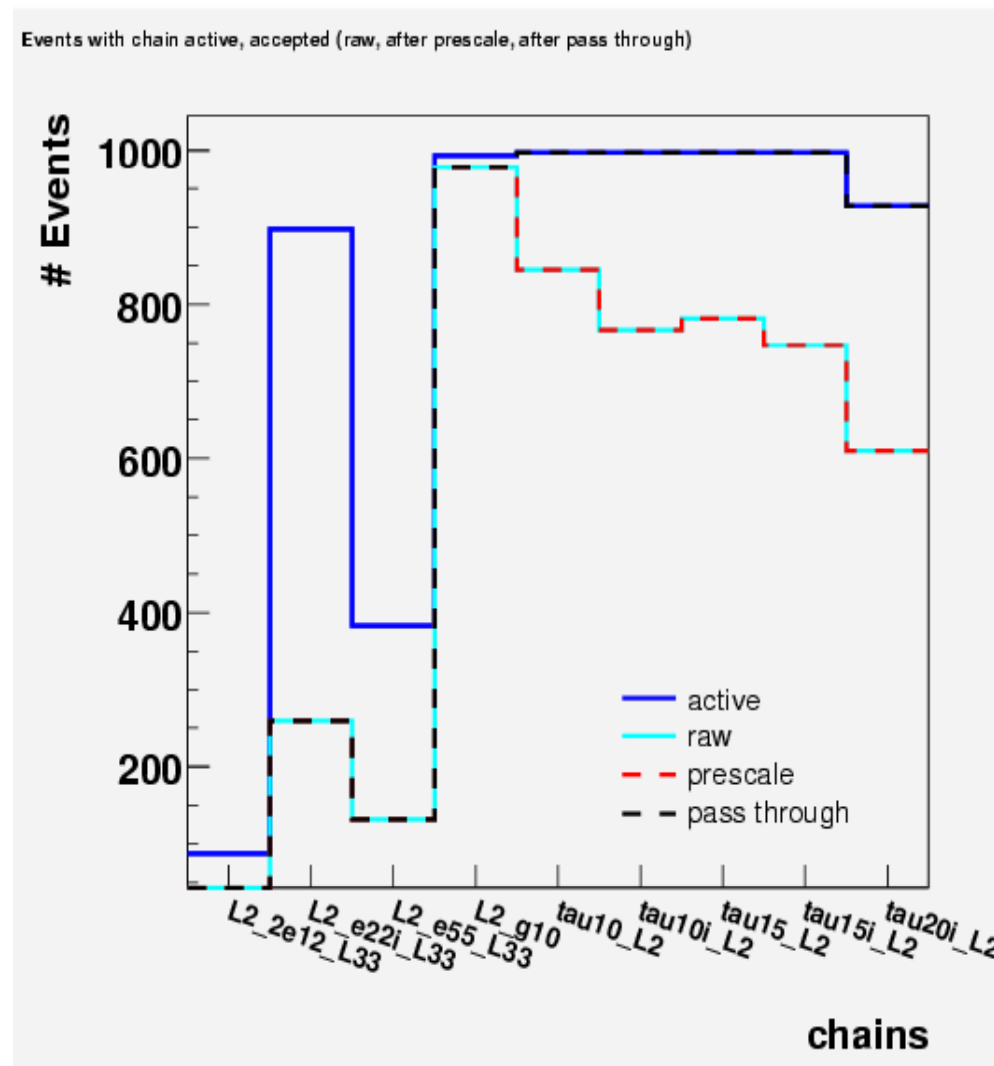
Lvl Converter 2.07(4.1 %)



Steering has been run live online during cosmic data runs

Monitoring

- Vital for online operation
- Steering instrumented to count events
 - By chain and by step
 - before & after pre-scale and pass-through
- Also monitoring RoI position, TE abundances, errors, times
- Histograms gathered and merged for online monitoring display
 - Time stamps allow conversion to rates
- IMonitoredAlgorithm interface allows algorithms to declare variables for histogramming.
 - These are also gathered, merged and available for online display.
 - Same histos used for validation.



Conclusions

- The HLT steering implements the key features of the HLT event selection strategy:
 - Region of Interest/seeding
 - Steps/early rejection
- Complex menus have been built up
- Caching saves time and simplifies config
- Time overhead is modest
- Well instrumented for monitoring
- Already used in cosmic runs and tech. runs
- More information in the paper

Other ATLAS T/DAQ presentations at CHEP07

- *Monday, 03 September 2007*
 - [421] **Implementation and Performance of the ATLAS Second Level Jet Trigger**
 - Patricia CONDE MUÑO
 - Poster 1 board 19
 - [437] **Remote Management of nodes in the ATLAS Online Processing Farms**
 - Marc DOBSON
 - Poster 1 board 21
 - [143] **The ATLAS High Level Trigger Steering**
 - by Simon GEORGE (Royal Holloway)
 - (Oak Bay: 16:50 - 17:05)
 - [339] **Event reconstruction algorithms for the ATLAS trigger**
 - by Teresa Maria FONSECA MARTIN (CERN)
 - (Oak Bay: 17:55 - 18:10)
 - [378] **Trigger Selection Software for Beauty physics in ATLAS**
 - by Dmitry EMELIYANOV (RAL)
 - (Oak Bay: 18:10 - 18:25)
- *Wednesday, 05 September 2007*
 - [112] **A software framework for Data Quality Monitoring in ATLAS**
 - by Serguei KOLOS (University of California Irvine)
 - (Oak Bay: 14:35 - 14:50)
 - [332] **The ATLAS DAQ System Online Configurations Database Service Challenge**
 - by Igor SOLOVIEV (CERN/PNPI)
 - (Oak Bay: 15:05 - 15:20)
 - [45] **The ATLAS Trigger: Commissioning with cosmic-rays**
 - by Jamie BOYD (CERN)
 - (Lecture Theatre: 17:30 - 17:45)
- *Thursday, 06 September 2007*
 - [28] **Integration of the Trigger and Data Acquisition Systems in ATLAS**
 - by Benedetto GORINI (CERN)
 - (Oak Bay: 14:50 - 15:05)
 - [50] **The configuration system of the ATLAS Trigger**
 - by Jörg STELZER (CERN, Switzerland)
 - (Lecture Theatre: 15:20 - 15:40)



Backup slides

Time constraints on HLT Algorithms

- LVL2 timing requirement
 - Need to absorb up to 75 kHz LVL1 rate (upgradeable to 100 kHz)
 - Processing of a new event is initiated every 10 μ s
 - ~500 1U slots allocated to the LVL2 farm
 - Current baseline: 500 quad-core dual CPU (≥ 2 GHz), one event per core
 - \Rightarrow ~40 ms average processing time per event (includes data access & processing time)
- EF timing requirement
 - Need to absorb up to ~3 kHz LVL2 rate
 - Processing of a new event is initiated every ~300 μ s
 - ~1800 1U slots for the EF farm
 - Current baseline: 1800 quad-core dual CPU (≥ 2 GHz), one EF process per core
 - ~4s average processing time per event (includes data access & processing time)
- Aggregate processing power of current baseline HLT farms is consistent with assumption in TDR based on 8 GHz single core dual CPU
- Relative allocation of LVL2 & EF processors is configurable



Time measurements

- Top events
 - 400 events
 - 0.6 MU, **3.6 EM**, 5.0 TAU, 6.8 J Rols
 - i.e. tot 16 per event
 - Not typical!
- Menu
 - LVL2 e/g with very low thresholds for commissioning at low lumi
 - 47 chains.
- CPU
 - 3 GHz Xeon
- Time
 - Caching saves ~80% and is on by default
 - Steering overhead (with caching) ~6%
- Compared to realistic setup
 - Expect to use few hundred chains in full menu
 - Expect average ~2 Rols per event with high lumi thresholds and typical events
 - Online technical runs show times in more realistic setup are compatible (or close) with no. of available processors



Monitoring

steps		total rate	L2_2e12_L33	L2_e22i_L33	L2_e55_L33	L2_g10	tau10_L2	tau10i_L2	tau15_L2	tau15i_L2	tau20i_L2
PT rate	1000	11	259	132	978	997	997	997	997	997	927
PS rate	1000	11	259	132	978	845	767	782	747	610	
raw rate	1000	11	259	132	978	845	767	782	747	610	
step 3	0	11	259	132	-1	845	767	782	747	610	
step 2	0	28	290	151	978	848	770	785	750	611	
step 1	0	28	290	151	993	974	947	964	938	788	
Input	1000	88	897	383	993	997	997	997	997	997	927