

ATLAS Tile Calorimeter Cesium calibration system

Control and analysis software

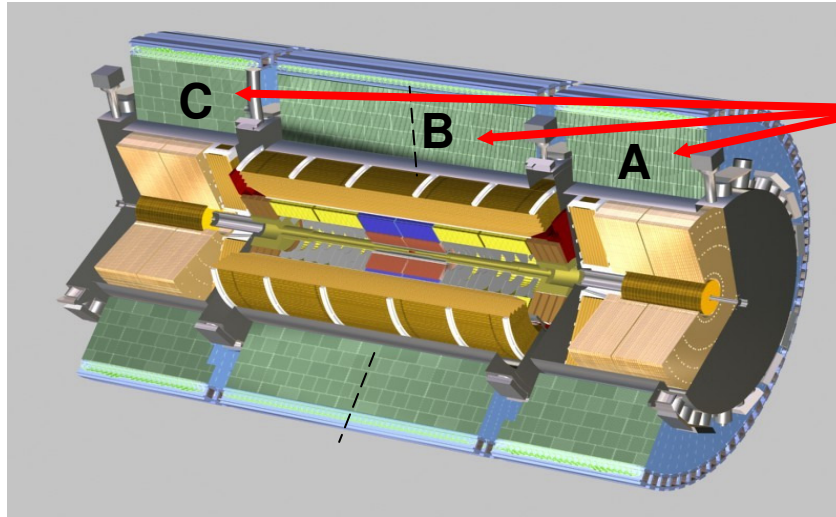
Presented at CHEP-2007
on behalf of Tile Collaboration
by Oleg Solovyanov, IHEP Protvino, Russia



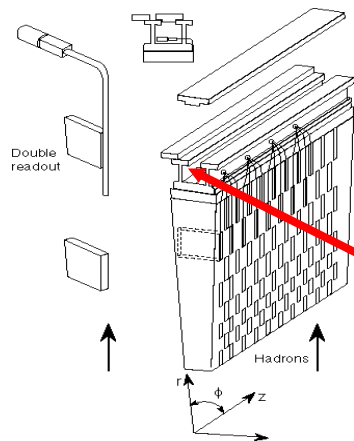
Outline

- ATLAS Tile Calorimeter
- Cesium calibration system
- Software architecture
- Operation, results and performance
- Conclusions

Tile Calorimeter

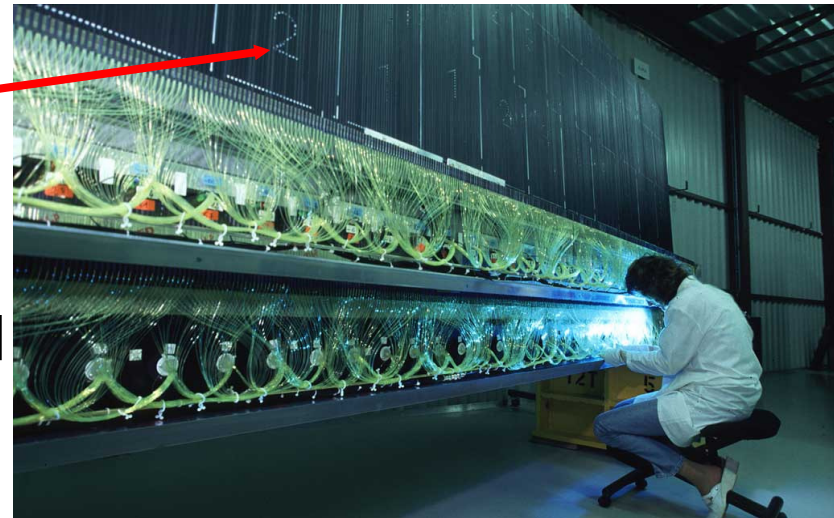


View of ATLAS[1] calorimeter system. The TileCal[2] sampling calorimeter constructed of steel plates (absorber) and scintillating plastic tiles (active material). It is designed as one barrel and two extended barrel parts. All the three sections have a cylindrical structure divided in ϕ by 64 wedges.



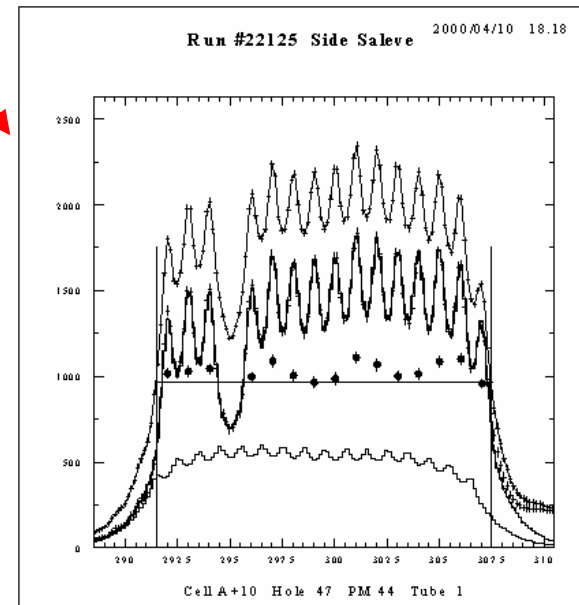
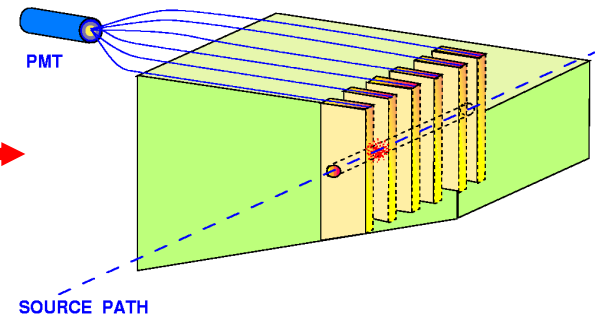
Within modules there are a number of cells corresponding to the projective geometry

Front-end electronics [3] located inside module's girder



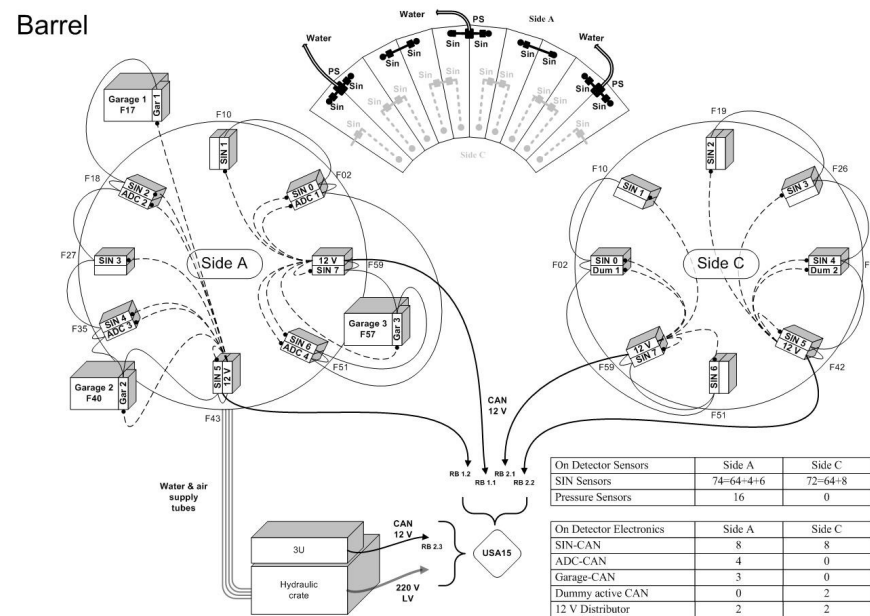
Cesium calibration system

- To calibrate and monitor the TileCal, a powerful ($\sim 10\text{mCi}$) ^{137}Cs γ -source is used
- While the source moves in the detector inside calibration tubes by a flow of liquid, integrated PMT currents from front-end electronics are read out
- The use of a movable source allows to test the optical quality of the scintillators and fibers, to equalize the response of all the cells ($<1\%$), to monitor each cell over the time and to provide the overall energy calibration [4]
- In order to transport the radioactive source in a safe and controllable way along the 10km of tubes inside the calorimeter, an elaborate source drive and monitoring system are needed [5],[6]
- An intelligent on-line software is required to perform the task of source movement and detector response analysis

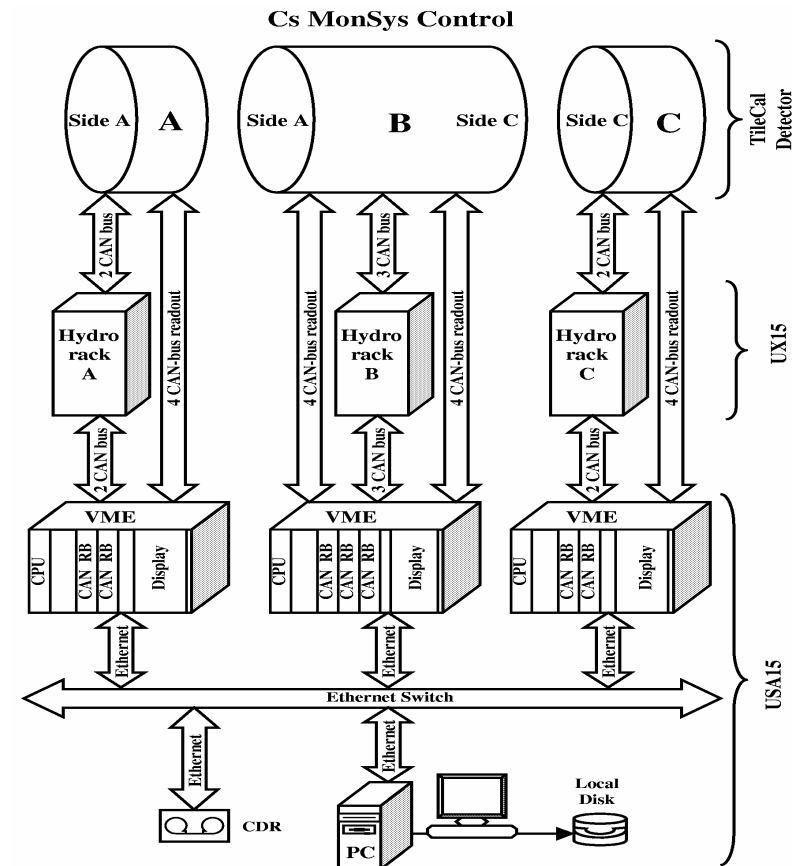


Electronics layout

■ Control and readout scheme



■ Schematic view of sensors and control boards layout around the calorimeter



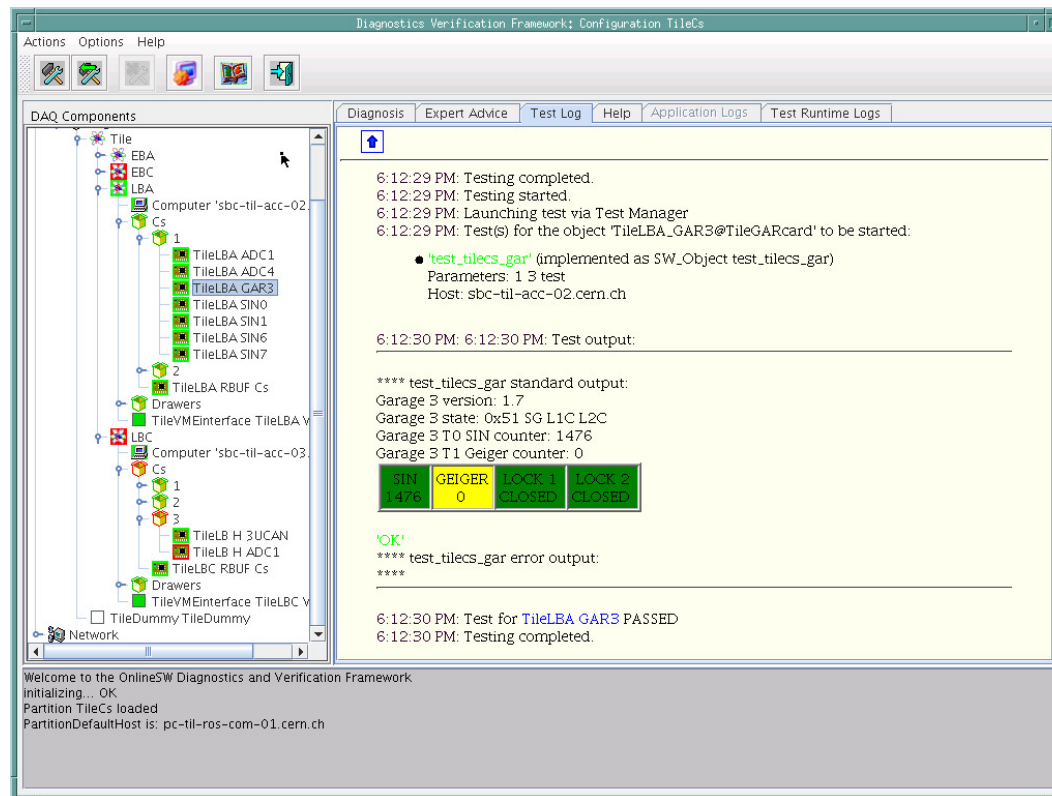
Software requirements

- Control and operate the hydraulics, electronics and run the ^{137}Cs source through the whole Tile calorimeter sensitive volume
- Read out the integrated current of the PMTs, while the source capsule moves with the designed speed, perform readout switching when capsule passes from one module to another*
- Be capable to correct/adjust the run conditions according to current system status and on-line analysis information
- Visualize results of online analysis and the position of the capsule, and the physical conditions of the run
- Store raw and reconstructed data
- Communicate with detector control system and calibration databases
- Monitor status of the hardware components, perform their tests and calibration

*readout is possible only from one module at a time

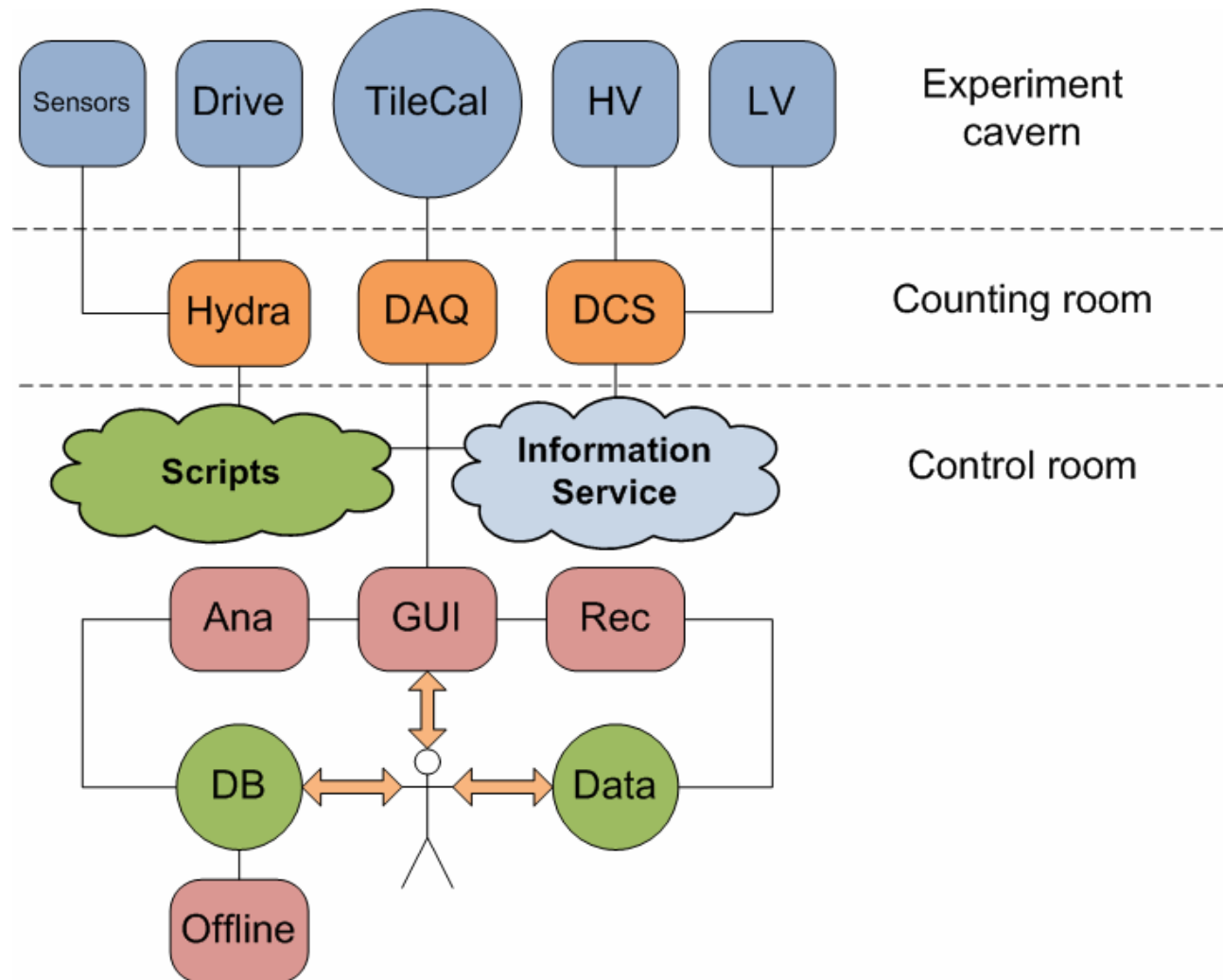
Electronics tests

To cope with system size, diversity and complexity of components, a set of tests has been developed with the help of ATLAS DVS framework [7], which allows to describe a hierarchy of components and their tests, to be executed in a sequential or parallel way, depending on the need.



- 10000 PMT channels in 256 front-end electronics “drawers”
- 500 source control sensors read out by 100 boards of 7 different types
- Electronics and their tests are described in configuration database
- Executed from command line or GUI
- Results provided in text or HTML format
- Expert system approach

Software architecture



- Readout and control processes running inside VME crates
- Information service (IS)[8],[9] as communication media between processes
- Embedded scripting facilities for program logics
- GUI, DB and other facilities for operator

Scripts

- Scripting facilities for program flow control and configuration add flexibility and ease of use for non-experts
- Embedded Python interpreter with extension library links together hardware objects and their representation inside Information service to share data between processes
- Configuration with Python scripts helps complex descriptions of different setups
- Standard scripts for control process algorithms and runtime behavior

```
■ # move_source.py - move the source
■ import time

■
■ global sinpath, switchpos, switchneg
■ global base_pump_speed, finger_from, finger_to, direction
■ global tube_from, tube_to
■ global source_position

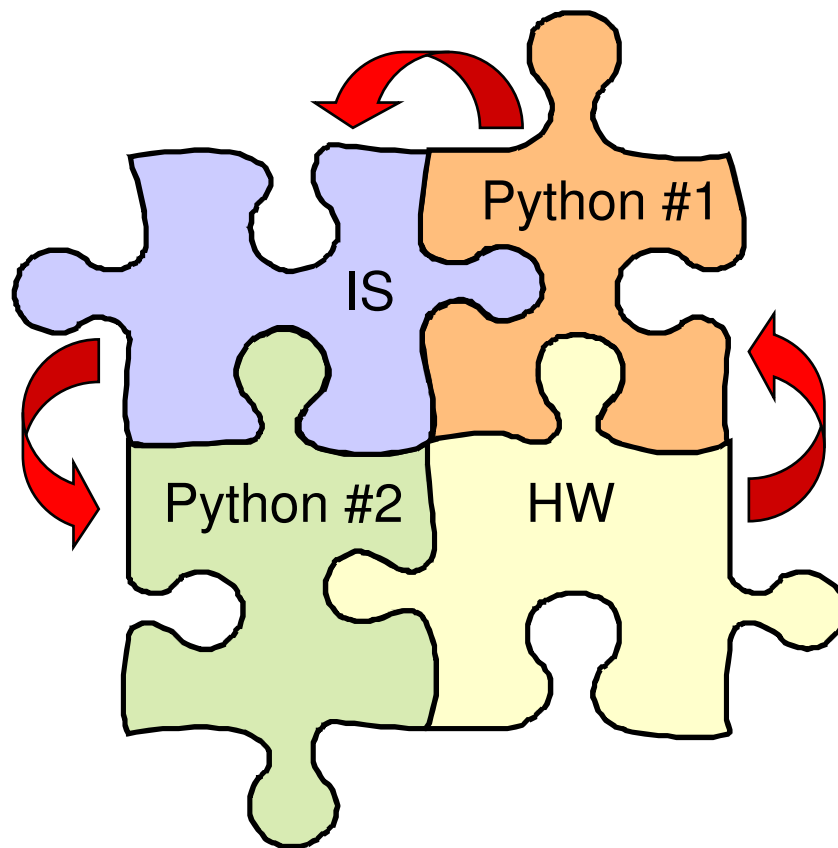
■
■ # determine contour size as number of modules between from
■ and to pipes
■ def contour_size(f,t):
■     size = abs(pipes[t]-pipes[f])
■     if size > 12: size = size-64
■     return abs(size)

■
■ # find the last hitte sin
■ def find_source(since=0):
■     lastsin = '00'
■     lasthit = since
■     for s in sinpath:
■         # anticlockwise direction
■         if direction>0:
■             if sin[s].hit>=lasthit:
■                 lasthit = sin[s].hit
■                 lastsin = s[:2] # leave 2 digit module name
■         # clockwise direction
■         else:
■             if sin[s].hit>lasthit:
■                 lasthit = sin[s].hit
■                 lastsin = s[:2]

■     return int(lastsin)
```

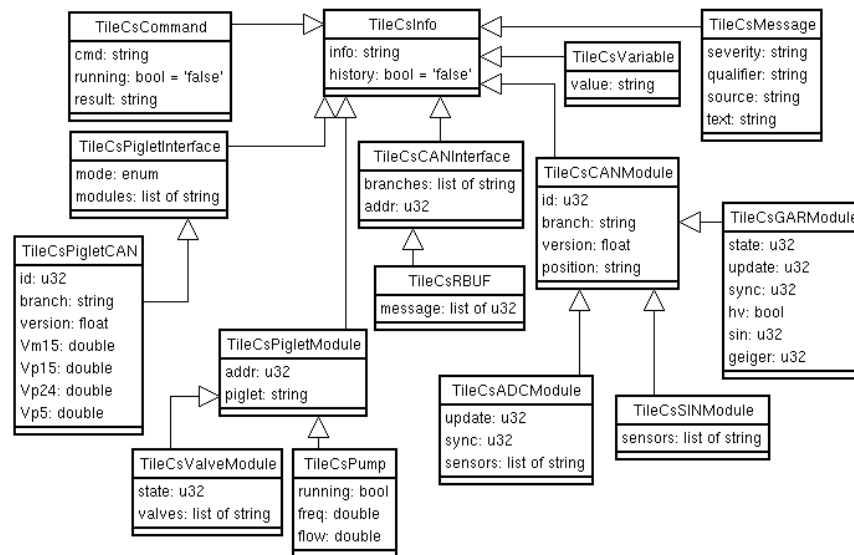
Script example

Python extention



- A set of Cs specific extention classes for Python
- Python object links together hardware component and IS representation
- Python object interacts with hardware
- Updates IS information
- Objects of Python “Info” classes, subscribed to the update, gets new state
- Information exchange between Python scripts running at different computers

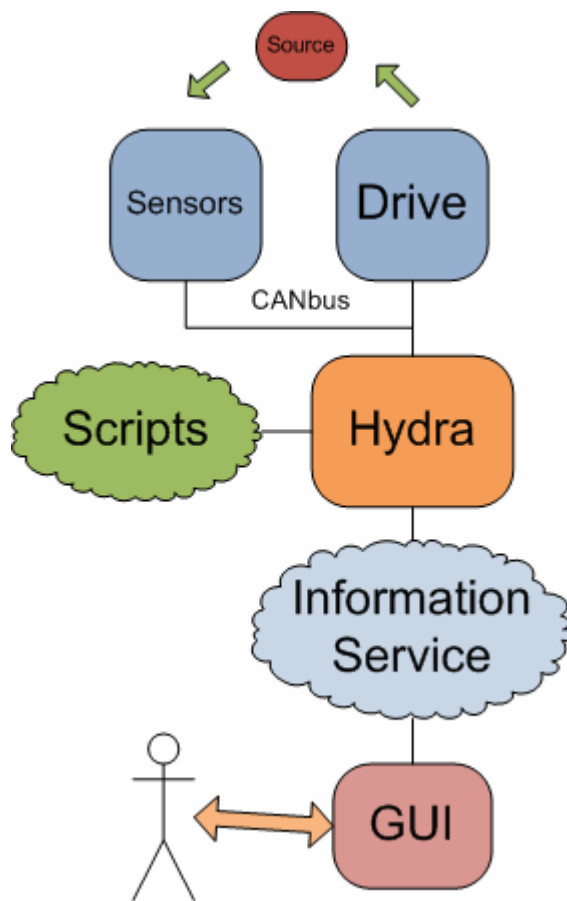
IS classes



TileCs IS schema (part)

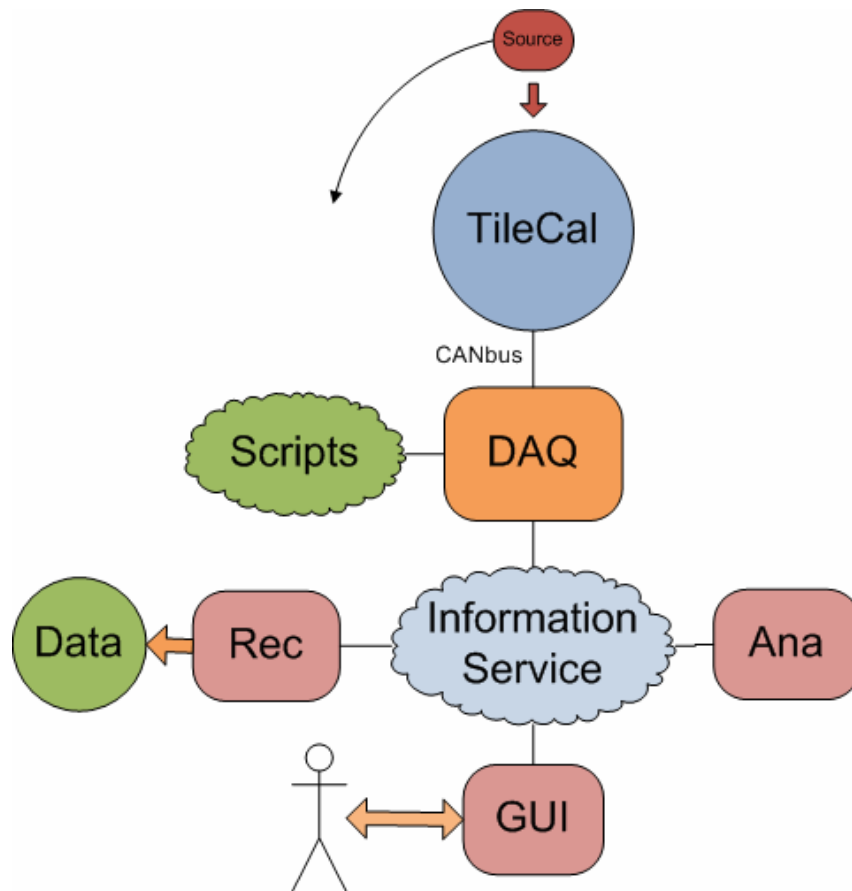
- An hierarchy of information service classes describes Cs specific hardware and software objects to share information between processes
- Many useful IS features
 - ❑ `is_Is` and `is_monitor` utilities
 - ❑ autogenerated C++ and Java bindings
 - ❑ command listener
 - ❑ server history “time machine”
 - ❑ server backup helps crash recovery

Control processes



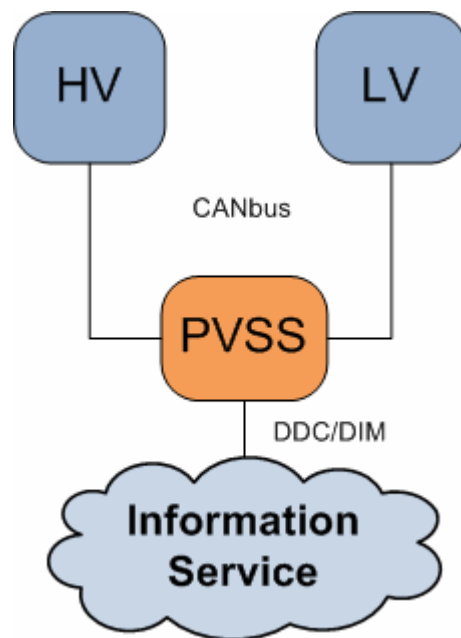
- Hydra controls the drive and sensors via CANbus
- Moves the source
- Reacts to current source position to switch drive contours
- Provides information for other processes
- Executes commands received from GUI or other processes
- Uses scripts to change configuration and control logics

DAQ



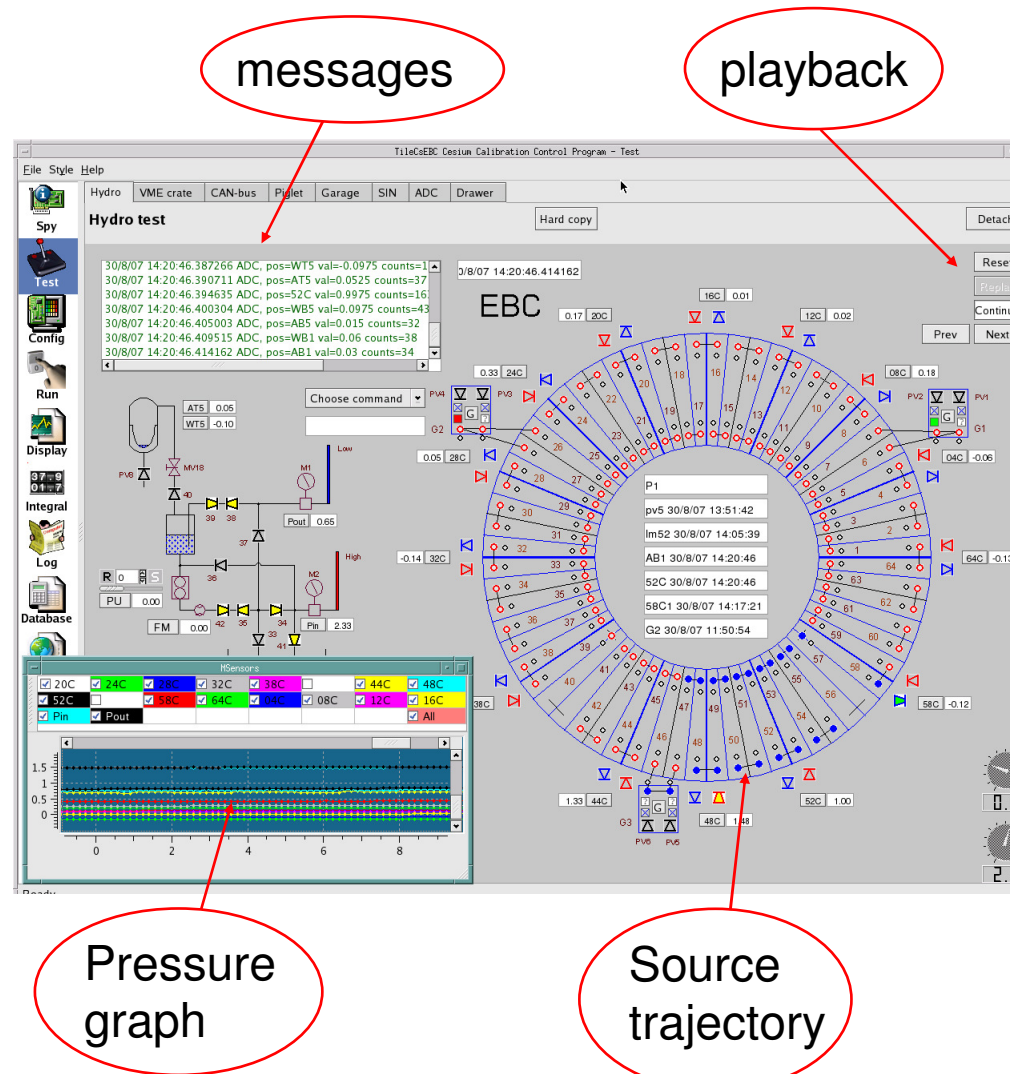
- DAQ process read out PMT responses and control front-end electronics via CANbus
- Switches front-end module readout based on current source position
- Provides data to the analysis and recording processes via IS

DCS and safety



- To fulfill the task of save and controlled operation an interface to detector control system (DCS) is required
- DDC package [10] of ATLAS TDAQ is used to retrieve and send high voltage and other important information, like temperatures, power supply status
- Source position, run status is provided for experiment operators (SLIMOS, etc.)

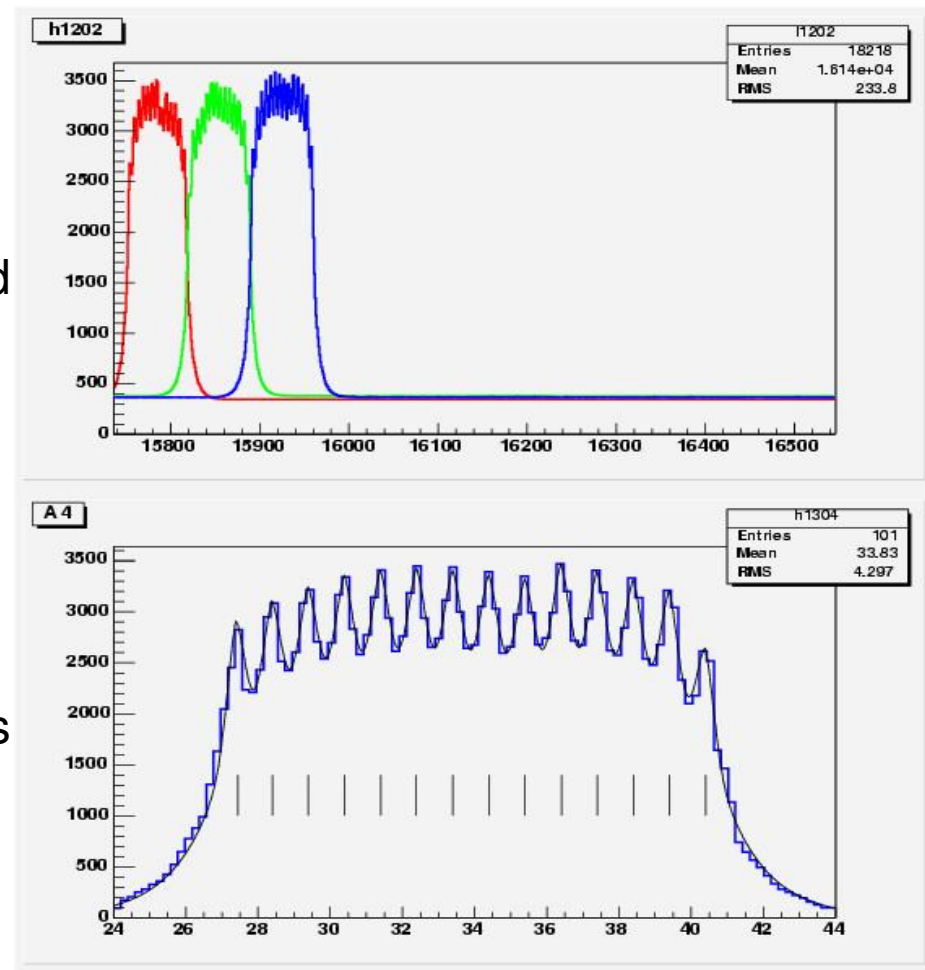
GUI



- QT application
- Allows to manipulate with any single valve as well as to send high level commands
- Receives information from all the sensors and visualize status of the system in real time
- Have important playback feature: full history can be replayed in accelerated mode

Data analysis

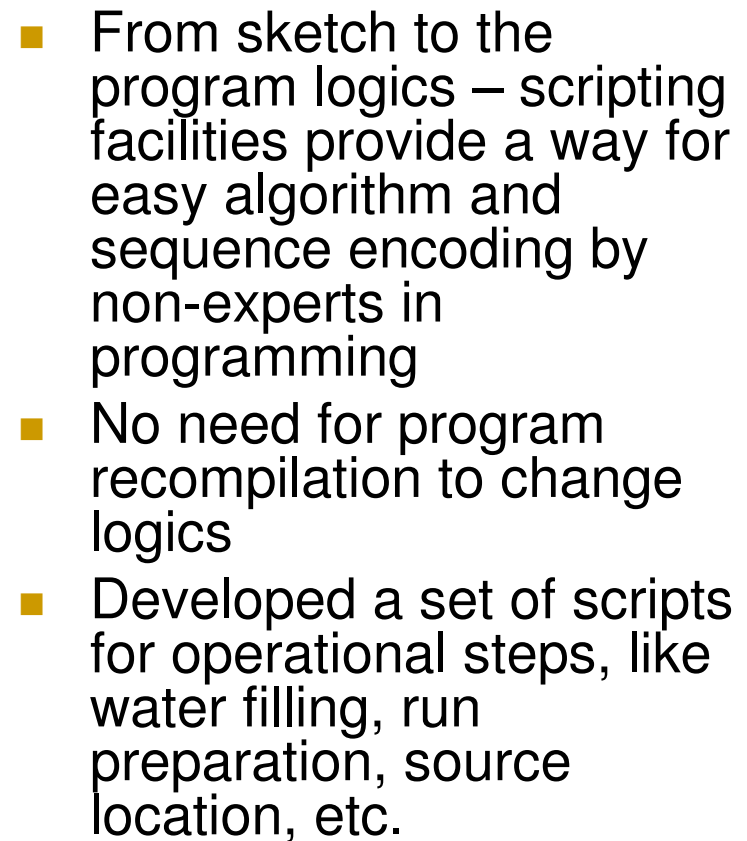
- Almost all TileCal modules are different, so sophisticated analysis software is required to achieve calibration with required precision
- Raw data taken during the run saved to a file in form of ROOT trees for easy access and visualization.
- Analysis can be started during the run as soon as data from one calorimeter module are available
- Response in every cell is calculated and results are used in iterative equalization procedure.
- Global data quality flag from analysis process might be taken into account by control process (e.g. to send capsule back to some particular bad module or to stop the run)
- Results are visualized in GUI and stored in the database



Cell response to the passing source

The diagram shows a water distribution system with the following components and flow paths:

- Water Source:** A tank at the bottom left with a dotted pattern, connected to the main line via a valve labeled PV7 (6.7).
- Main Distribution Line:** A horizontal line with several valves:
 - Valve 36 (5.4) with a green checkmark.
 - Valve 35 (7.2) with a green checkmark.
 - Valve 34 (6.3) with a green checkmark.
 - Valve 33 (6.1) with a green checkmark.
 - Valve 32 (5.2) with a green checkmark.
 - Valve 31 (4.1) with a green checkmark.
 - Valve 30 (7.1) with a green checkmark.
- Water Flow:** Indicated by red arrows and the word "water" in red. The flow is from left to right through the main line.
- Branch to Air:** A vertical branch from the main line at valve 37 (5.5) leads to a tank at the top left. This branch contains:
 - Valve MV18 (40) with a green checkmark.
 - Valve 38 (5.8) with a green checkmark.
 - Valve 39 (5.7) with a green checkmark.
 - Valve 40 (5.6) with a green checkmark.
 The tank is labeled "Air" in red.
- Branch to High Pressure:** A vertical branch from the main line at valve 32 (5.2) leads to a tank at the top right. This branch contains:
 - Valve MV17 (41) with a green checkmark.
 - Valve 41 (7.1) with a green checkmark.
 The tank is labeled "High" in red.
- Branch to Low Pressure:** A vertical branch from the main line at valve 31 (4.1) leads to a tank at the bottom right. This branch contains:
 - Valve MV19 (41) with a green checkmark.
 - Valve 41 (7.1) with a green checkmark.
 The tank is labeled "Low" in red.
- Pressure Measurement:** Two pressure gauges are shown:
 - M1 (5.1) on the branch to the "Air" tank.
 - M2 (5.2) on the branch to the "High" tank.
- Handwritten Annotations:**
 - A red circle at the top right contains the word "filling".
 - Red arrows and the word "water" indicate the flow direction.
 - Red arrows and the word "Air" indicate the flow direction to the top-left tank.
 - Red arrows and the word "High" indicate the flow direction to the top-right tank.
 - Red arrows and the word "Low" indicate the flow direction to the bottom-right tank.



RUN operation scenario

■ Preparation

- ❑ FE electronics tests: pressure sensors, SINs, garage sensors, 3U-crates etc.
- ❑ Safety checks: locate the source, air pressure leak test
- ❑ Functionality of the equipment: hydraulic drive, garage locks etc.
- ❑ Control of liquid flow: pump, air pressure, detector local pressures etc.
- ❑ Water filling: fill detector volume with liquid from the water storage tanks

■ Cs RUN

- ❑ Run the source capsule at a desired speed, keeping an eye on its current position with SIN sensors and detector response
- ❑ Collect PMT responses and store it along with the online analysis of the correctness of the information
- ❑ Adjust the source movement, data readout and online analysis modes according to the current run conditions (situation)

■ Post run tasks

- ❑ Water draining: pump, air pressure, detector local pressures
- ❑ Safety checks: garages, source location, source blocking

Results

- Cesium calibration system is installed in the ATLAS experiment cavern, commissioning is ongoing
- Regular electronics tests verified the integrity and stability of the components
- Dummy source runs allowed to check system functionality and operational logic before introducing the radioactive source to the still busy environment of experiment installation

Performance

- 100Hz trigger frequency
- Data flow rate relatively small, ~20 KB/s
- The full Tile Calorimeter barrel scan normally should take about 8 hours and produce ~300 MBs of raw data
- Several runs per year are planned, after initial series of runs for optical quality verification, primary equalization and calibration effort

Conclusions

- A system to calibrate and monitor ATLAS Tile Calorimeter with a movable radioactive source, driven by liquid flow, has been installed in the ATLAS pit
- Online software has been developed, using ATLAS TDAQ components for database, information exchange, electronics tests, communication with detector control systems, etc.
- Scripting facilities allowed for quick prototyping and modification flexibility by non-experts
- GUI provided operator with clear status and control, and history mechanism for post-run problem analysis
- Data analysis software with online response
- Good performance has been achieved for data taking and online analysis, to cope with the task at the speed of source travel
- Many thanks to all Tile collaboration and ATLAS TDAQ group

References

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