

MAUS Update

A. Dobbs

Imperial College London

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Current Release

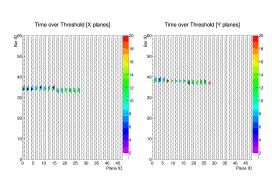
- MAUS is currently on version 0.9.3
 - bzr branch lp:maus
 - See http://micewww.pp.rl.ac.uk/projects/maus/wiki
- Now supports building with multiple cores (use -j N)
- G4BeamLine now fully incorporated for upstream beamline simulation
- GRID running now working with a full release
- Physics Block Challenge data produced using release 0.9.2
 - http://www.ppe.gla.ac.uk/~rbayes/MICE_6pi200_1/pass2_ simulation_mausv0p9p2.tar.gz

EMR

EMR

F. Drielsma

- MC: Complete
- MC digitisation: Complete
- Real data unpacking: Complete
- Reconstruction: 80% complete
- Calibration needs to go to CDB
- See EMR talks

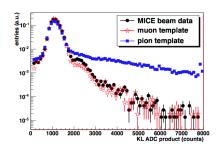


250 MeV/c Muon Event

KL

M. Bogomilov, J. Nugent

- MC: Complete
- MC data digitisation: Virtually complete
- Real data digitisation: Complete
- Reconstruction: Complete
- MC validation: Complete



L. Cremaldi, D. Rajaram

- MC: 30% complete.
 - Material characterization/layers are complete
 - Photon bouncing will not be implemented, but data-driven model of PE production used instead
- MC data digitisation: 0% complete
 - Private model made, but not in MAUS, hoping to get student to implement.
- Real data digitisation: 50% complete
 - Re-written the fadc integrators and pedestal finders
- Reconstruction: 25% complete
 - \bullet PE counts from the PMTs used for a while to make $e/\mu/\pi$ predictions using Poisson algorithms for producing likelhoods, but no MAUS implementation

Tracker

Current Release

- D. Adey, A. Dobbs, C. Heidt, C. Hunt, M. A. Uchida
 - MC: Complete (perhaps a bit of tinkering with the noise algorithm)
 - MC data digitisation: Complete
 - Unpacking: Broken post release 0.7.3 (fix done?)
 - Real data digitisation: Status unsure due to unpacking problem
 - Reconstruction: Almost complete. Final track fit algorithms being refined and tuned
 - MC validation: Mostly complete.
 - Online displays: 60% complete



D. Rajaram

- MC: Complete
- MC digitisation: Mostly complete. MC trigger work ongoing.
- Unpacking: Complete
- Real data digitisation: Complete
- Reconstruction: Complete
- Online displays: Complete

Global

M. A. Uchida, C. Pidcott, J. Greis

- 3 PID variables now in release
- Tracking being overhauled, switching from transfer matrix method to Runge-Kutta
- Downstream: Tracks and PID
- Upstream: Tracks
- Requires detector output in global coordinate system
- Good progress being made, estimate 50% complete, expected completetion date of 30th June 2015
- See dedicated Global talks for details



rrent Release Detectors Global **Tests Summary**00000 0 •00 00

Test Coverage

Test Coverage I

Directory	Line Coverage ≑		Functions \$		Branches \$	
src/common_cpp/API	74.2 %	230 / 310	76.4 %	178 / 233	44.2 %	99 / 224
src/common_cpp/Converter	92.5 %	49 / 53	66.5 %	149 / 224	40.2 %	53 / 132
src/common_cpp/Converter/DataConverters	88.7 %	204 / 230	59.7 %	105 / 176	47.6 %	81 / 170
src/common_cpp/DataStructure	27.8 %	12585 / 45322	25.5 %	2270 / 8889	11.2 %	1756 / 15740
src/common_cpp/DataStructure/Global	95.3 %	548 / 575	83.9 %	151 / 180	77.0 %	137 / 178
src/common_cpp/DetModel	100.0 %	23 / 23	90.0 %	9/10	70.0 %	7 / 10
src/common_cpp/DetModel/EMR	1.7 %	3 / 180	15.4 %	6 / 39	14.3 %	6 / 42
src/common_cpp/DetModel/SciFi	62.1 %	64 / 103	55.0 %	11/20	38.9 %	14 / 36
<pre>src/common_cpp/FieldTools</pre>	93.8 %	316 / 337	90.7 %	49 / 54	75.8 %	135 / 178
src/common_cpp/Globals	97.9 %	95 / 97	100.0 %	12 / 12	73.6 %	53 / 72
src/common_cpp/JsonCppProcessors	95.0 %	1168 / 1230	74.3 %	1848 / 2486	39.8 %	739 / 1855
<pre>src/common_cpp/JsonCppProcessors/Common</pre>	81.3 %	157 / 193	68.3 %	569 / 833	37.6 %	258 / 686
src/common_cpp/JsonCppProcessors/Common /ObjectProcessorNS	83.0 %	190 / 229	91.0 %	1842 / 2025	54.4 %	319 / 586
<pre>src/common_cpp/JsonCppProcessors/Global</pre>	92.9 %	78 / 84	65.0 %	39 / 60	46.2 %	24 / 52
src/common_cpp/JsonCppStreamer	60.3 %	149 / 247	62.7 %	52 / 83	31.2 %	116/372
src/common_cpp/Maths	88.5 %	1735 / 1961	85.7 %	355 / 414	79.1 %	800 / 1012
src/common_cpp/Optics	92.7 %	558 / 602	79.1 %	87 / 110	75.7 %	156 / 206
src/common_cpp/Plotting/SciFi	44.1 %	520 / 1179	62.2 %	56 / 90	28.6 %	170 / 594
src/common_cpp/Recon/Bayes	54.5 %	54 / 99	64.7 %	11 / 17	57.1 %	16 / 28
src/common_cpp/Recon/Global	86.5 %	787 / 910	82.9 %	126 / 152	63.0 %	298 / 473
src/common_cpp/Recon/Kalman	92.7 %	999 / 1078	94.0 %	125 / 133	76.4 %	165 / 216
src/common_cpp/Recon/SciFi	85.7 %	1317 / 1536	93.2 %	138 / 148	61.1 %	615 / 1006
src/common_cpp/Simulation	88.8 %	1359 / 1530	93.8 %	182 / 194	62.8 %	511 / 814
src/common_cpp/Utils	70.2 %	1239 / 1764	79.5 %	245 / 308	54.4 %	636 / 1170

Test Coverage

Test Coverage II

Directory	Line Coverage \$			Functions \$		Branches 🕈	
<pre>src/input/InputCppDAQData</pre>		58.5 %	637 / 1089	72.4 %	89 / 123	40.9 %	235 / 575
src/input/InputCppDAQOfflineData		85.1 %	40 / 47	88.9 %	8/9	43.5 %	20 / 46
src/input/InputCppRoot		91.0 %	141 / 155	92.6 %	25 / 27	63.4 %	109 / 17
src/legacy/BeamTools		46.1 %	1063 / 2306	45.9 %	162 / 353	39.0 %	450 / 115
src/legacy/Config		35.9 %	745 / 2073	49.8 %	148 / 297	31.4 %	423 / 134
src/legacy/DetModel/Ckov		1.2 %	2 / 169	20.0 %	4/20	8.7 %	4/4
src/legacy/DetModel/KL		2.1 %	3 / 145	30.0 %	6/20	8.6 %	6/7
src/legacy/DetModel/TOF		2.6 %	1/38	25.0 %	2/8	20.0 %	2/1
src/legacy/DetModel/Virtual		42.7 %	53 / 124	52.9 %	9/17	34.1 %	15 / 4
src/legacy/EngModel		28.0 %	103 / 368	56.6 %	30 / 53	28.3 %	73 / 25
src/legacy/Interface		40.3 %	1406 / 3489	33.2 %	230 / 693	37.6 %	606 / 161
src/legacy/Interface/Interpolation		73.7 %	112 / 152	61.5 %	24 / 39	59.2 %	45 / 7
src/legacy/Interface/Meshing		76.8 %	209 / 272	62.3 %	43 / 69	81.7 %	116 / 14
src/legacy/Optics		1.3 %	29 / 2311	7.4 %	30 / 404	3.1 %	32 / 102
src/legacy/Simulation		150.0 %	257 / 257	100.0 %	3/3	67.6 %	23 / 3

Test Coverage

Test Coverage III

Directory	Line Coverage \$		Functions \$		Branches \$	
src/map/MapCppEMRPlaneHits	94.5	% 172 / 182	73.3 %	11 / 15	71.3 %	67 / 94
src/map/MapCppEMRRecon	93.2	% 382 / 410	82.6 %	19 / 23	77.2 %	224 / 290
src/map/MapCppExampleMAUSDataInput	100.0	% 17 / 17	90.0 %	9/10	43.8 %	7 / 16
src/map/MapCppGlobalPID	94.5	% 69 / 73	70.0 %	7 / 10	67.2 %	39 / 58
src/map/MapCppGlobalReconImport	93.6	% 44 / 47	70.0 %	7 / 10	56.2 %	18 / 32
<pre>src/map/MapCppGlobalTrackMatching</pre>	90.9	% 30 / 33	70.0 %	7 / 10	41.7 %	10/24
src/map/MapCppKLCellHits	93.9	% 77 / 82	75.0 %	9 / 12	48.1 %	26 / 54
src/map/MapCppKLDigits	92.6	% 88 / 95	69.2 %	9/13	51.9 %	28 / 54
src/map/MapCppKLMCDigitizer	82.6	% 176/213	80.0 %	12 / 15	54.4 %	86 / 158
src/map/MapCppSimulation	96.4	% 27/28	77.8 %	7 / 9	33.3 %	6 / 18
src/map/MapCppTOFDigits	90.8	% 148 / 163	87.5 %	14 / 16	66.0 %	70 / 106
src/map/MapCppTOFMCDigitizer	87.6	% 227 / 259	81.2 %	13 / 16	56.2 %	126 / 224
<pre>src/map/MapCppTOFSlabHits</pre>	97.2	% 106 / 109	91.7 %	11 / 12	56.9 %	33 / 58
src/map/MapCppTOFSpacePoints	91.7	% 143 / 156	94.1 %	16 / 17	50.4 %	67 / 133
<pre>src/map/MapCppTrackerDigits</pre>	47.6	% 10/21	54.5 %	6/11	6.2 %	2 / 32
src/map/MapCppTrackerMCDigitization	68.7	% 92 / 134	58.8 %	10 / 17	39.2 %	29 / 74
src/map/MapCppTrackerMCNoise	90.5	% 38 / 42	66.7 %	8 / 12	33.3 %	14 / 42
src/map/MapCppTrackerRecon	98.7	% 74 / 75	86.7 %	13 / 15	43.1 %	25 / 58
src/output/OutputCppRoot	83.7	% 128 / 153	96.6 %	28 / 29	49.8 %	128/257
<pre>src/output/OutputCppRoot/build</pre>	25.2	% 362 / 1436	28.3 %	41 / 145	14.5 %	154 / 1059
src/py_cpp	76.7	% 415 / 541	89.8 %	53 / 59	55.4 %	133 / 240
<pre>src/reduce/ReduceCppGlobalPID</pre>	79.1	% 87 / 110	85.7 %	6/7	61.4 %	43 / 70
<pre>src/reduce/ReduceCppGlobalPID/build</pre>	25.9		29.7 %	33 / 111	14.4 %	121 / 843
<pre>src/reduce/ReduceCppPatternRecognition</pre>	69.2	% 36 / 52	21.9 %	7 / 32	37.5 %	3/8
<pre>src/reduce/ReduceCppPatternRecognition/build</pre>	25.0	% 290 / 1160	29.2 %	33 / 113	14.2 %	124/871
<pre>src/reduce/ReduceCppTofCalib</pre>	44.6	% 79 / 177	29.4 %	10 / 34	10.5 %	4 / 38
<pre>src/reduce/ReduceCppTofCalib/build</pre>	26.8	% 305 / 1137	32.1 %	36 / 112	14.8 %	126 / 849

To Do for Step IV

Towards MAUS 1.0:

- Tracker real data unpacking broken post release 0.7.3
- Tracker finalisation
- Slow memory leaks still present
- Detector output in global coordinate frame
- Finish Global PID and track reconstruction
- Online displays



Questions

Questions

