



Recent developments in tracking and vertexing methods

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Vertex 2015

Santa Fe, June 4, 2015

R. Frühwirth, HEPHY Vienna 1 Vertex 2015





- Developments for LHC Run 2
 - ATLAS
 - CMS
 - LHCB
- Real-time Tracking
 - ATLAS
 - CMS
 - CBM
 - LHCb
- Other developments
 - CMS @ HL-LHC
 - Belle II
 - Fuzzy c-regression
- Summary and outlook





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OAW

Developments for LHC Run 2: ATLAS Tracking

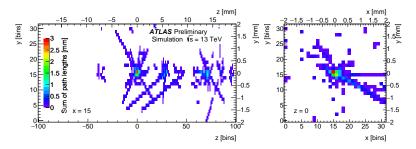
⇒ See talk by Gabriel Facini!



Developments for LHC Run 2: ATLAS Vertexing



- ➡ Imaging algorithm for vertex reconstruction
- Define 3D histogram in box $4 \times 4 \times 400$ mm around the origin
- Helical track trajectories are linearised and back-projected into the histogram using a voxel raytracing algorithm
- Histogram content in each traversed bin is incremented by the path length of the linearised track in the bin
- Example:



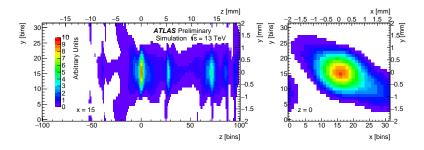
ATI -PHYS-PUB-2015-008







- The back-projected track image is transformed into frequency space by a discrete Fourier transform
- The frequency space histogram is multiplied by two filters: acceptance and smoothing
- The filtered frequency space image is back-transformed to position space
- Result:

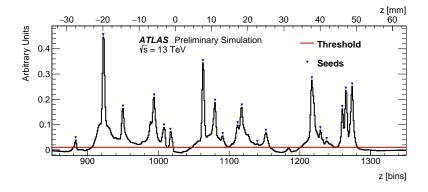




Developments for LHC Run 2: ATLAS Vertexing



- The resulting image is passed to a separate clustering algorithm where all seeds are identified from peaks in the image
- Projection to the z-axis:



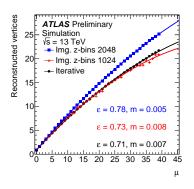
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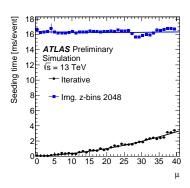






- Comparison to iterative reconstruction with the adaptive vertex finder
- Min bias events, μ is number of in-time pile-up





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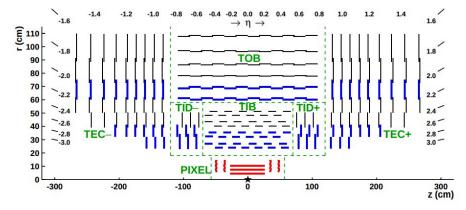


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The CMS Tracker

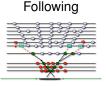


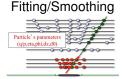




- >> Iterative combinatorial track finding
- In each iteration:
 - Seed generation: initial track segment with 2 or 3 hits
 - Track following: pick up compatible hits and branch
 - Track fitting: estimate track parameters
 - Track selection: drop bad track candidates
- After each iteration, hits belonging to high quality tracks are removed

Seeding Seeding Seeding



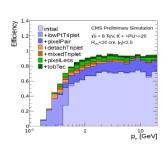


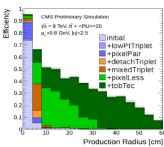






N	Step Name	Seeding	Target Track
0	Initial	pixel triplets	prompt, high p _T
-1	LowPtTriplet	pixel triplets	prompt, low p _T
2	PixelPair	pixel pairs	high p⊤ recovery
3	DetachTriplet	pixel triplets	displaced
4	MixedTriplet	pixel+strip triplets	displaced-
5	PixelLess	inner strip pairs	displaced+
6	TobTec	outer strip pairs	displaced++





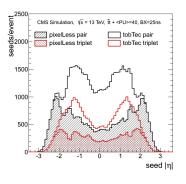
E. Brondolin, Connecting The Dots 2015

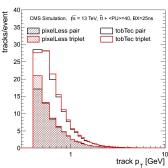


Developments for LHC Run 2: CMS Tracking



- ➤ New seeding algorithm
- For triplet-based seeding from strips
- Straight-line fit of 3 points in r-z plane, tighter beam constraint, tighter quality selection
- Half of the seeds are rejected, efficiency not affected





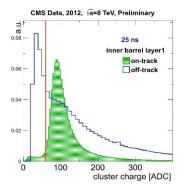
E. Brondolin, Connecting The Dots 2015

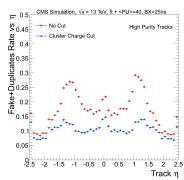


Developments for LHC Run 2: CMS Tracking



- Cluster charge cut
 - Larger occupancy resulted in doubling the time and the fake rate
- Cluster charge cut accounts for sensor thickness, p_T and crossing angle
- Timing and fake rate are back to normal





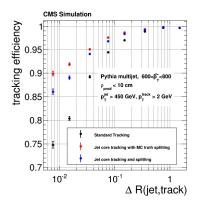
E. Brondolin, Connecting The Dots 2015







- ightharpoonup New iteration for high $p_{\rm T}$ jets
- Iterative cluster splitting in the pixels
- k-means clustering, taking into account the total cluster charge
- Improved efficiency at small ΔR

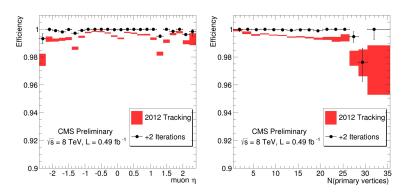




Developments for LHC Run 2: CMS Tracking



- Two new iterations for muons
 - ullet Inward: muon system o tracker
 - ullet Outward: tracker o muon system, with looser cuts

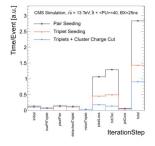


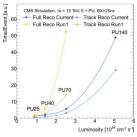


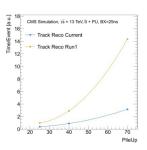
Developments for LHC Run 2: CMS Tracking



- **▶** Reduction of time consumption
- Optimization of the code and the iteration logic
- Factor 2 at PU=20, factor 3 at PU=30, factor 4 at PU=70





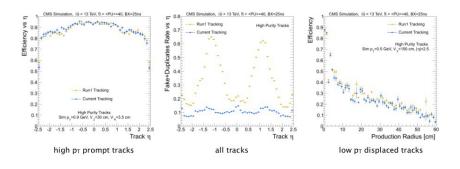








⇒ Expected performance for Run 2



- Efficiency for prompt tracks is similar
- Fake rate is reduced by a factor of up to 6
- Efficiency for displaced tracks is slightly lower





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Developments for LHC Run 2: LHCB Tracking

⇒ See talk by Stefano Gallorini!





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⇒ See talk by Guido Volpi!





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Real-time Tracking: CMS Track Trigger



See talk by Marco De Mattia!





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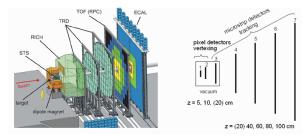


Real-time Tracking: CBM Tracking



➡ CBM experiment

- Future fixed-target heavy-ion experiment at FAIR
- 10⁷ Au+Au collisions/sec
- ~1000 charged particles/collision
- Non-homogeneous magnetic field
- ullet Double-sided strip detectors o 85% fake space-points!



http://www-alt.gsi.de/documents/DOC-2006-Nov-46-1.pdf



Real-time Tracking: CBM Tracking



➡ Event reconstruction

- Full reconstruction online and offline
- Cellular Automaton track finder
- Kalman filter track fitter
- Short-lived-particle finder
- All reconstruction algorithms are vectorized and parallelized



V. Akishina and I. Kisel, CHEP2015

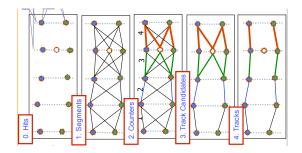






CA track finder

- Intrinsically parallel, simple, very fast
- Build short track segments
- Connect according to the track model
- Tree structures appear, collect segments into track candidates
- Select the best track candidates



V. Akishina and I. Kisel, CHEP2015

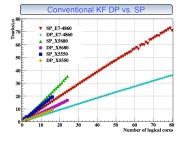


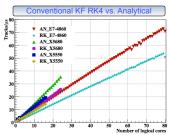




> KF track fit library

- Tools: filter, smoother, deterministic annealing filter
- Variants: single precision, double precision, square-root filter, UD factorization filter
- Propagator: Runge-Kutta, analytic formulas
- Excellent many-core scalability!





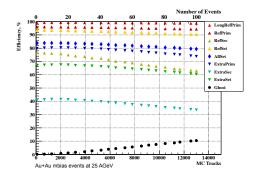
V. Akishina and I. Kisel, CHEP2015

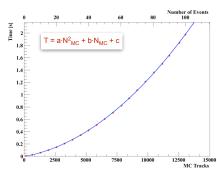


Real-time Tracking: CBM Tracking



- Track finding efficiency
 - Gather minimum bias events into a single event





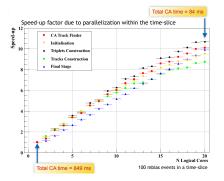
V. Akishina and I. Kisel, CHEP2015







- ➡ Time-based track reconstruction
- Beam in CBM is continuous
- Measurements will be 4D: x, y, z, t
- Significant overlapping of events in the detector
- Reconstruction of time slices instead of events



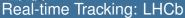
V. Akishina and I. Kisel, CHEP2015





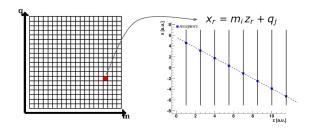
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- ➡ Plans for HL upgrade
- Specialized tracking processor with 40 MHz throughput
- Based on concept of Artificial Retina
- ➡ Principles of Artificial Retina
- The parameter space of the tracks is discretized into cells
- Each cell corresponds to an ideal track intersecting the detector layers in the centers of its receptive fields

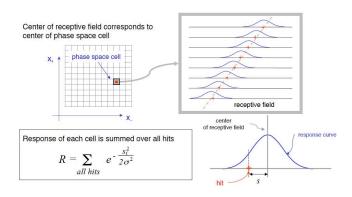


A. Abba et al., JINST 10 C03018





- For a real track, the distance between the actual hits and the centers of the receptive fields is computed
- The response or excitation of a cell is a function of these distances, summed over all receptors and hits

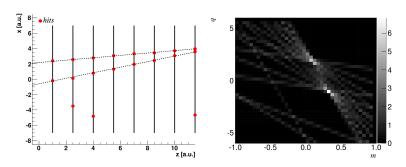


A. Abba et al., LHCb-PUB-2014-026





- Tracks are identified by local maxima of response in the array of cells
- Similar to Hough transform in 2D



A. Abba et al., JINST 10 C03018

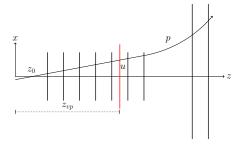


Real-time Tracking: LHCb



➡ Artificial Retina for VELO/UT

- Consider virtual plane at $z = z_{vp}$
- Track is defined by transverse coordinates u, v
- 2D artificial retina with 2×22500 cells
- Implementation in FPGA



A. Abba et al., LHCb-PUB-2014-026

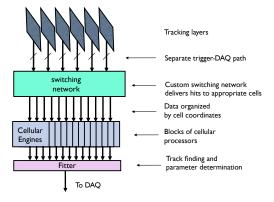




Real-time Tracking: LHCb

➡ Architecture

Overview of the architecture of the track processing unit (TPU)



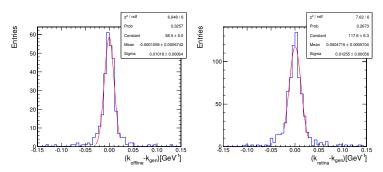
A. Abba et al., LHCb-PUB-2014-026





Real-time Tracking: LHCb

- ⇒ Simulation, timing and resolution
- Design has been validated by a ModelSim simulation
- TPU can keep up with an input frequency of 40 MHz at the occupancy predicted for 2020
- Curvature resolution about 25% worse as offline



A. Abba et al., LHCb-PUB-2014-026





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Other developments: CMS @ HL-LHC tracking

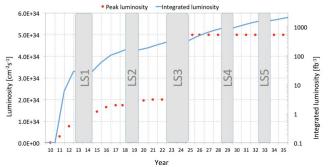


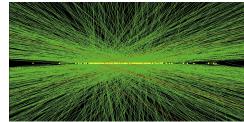
- New tracker for High-Luminosity LHC
 - Main challenges are radiation and pile-up caused by the high luminosity
 - Radiation challenge will be addressed by the detector designers
 - Pile-up challenge requires a track trigger complementing the muon and calorimeter information
- See talk by Marco De Mattia!



TEPHY Other developments: CMS @ HL-LHC tracking







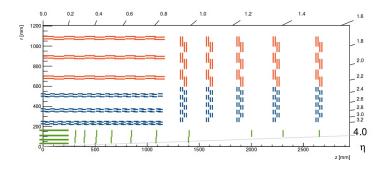
Simulated Event at PU=140 (102 Vertices)







► Layout of the CMS tracker for HL-LHC



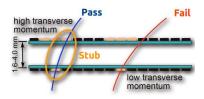
- Pixels: 4 barrel layers and 10 forward/backward disks
- Pixel-strip (PS) modules: 3 barrel layers and 5 forward/backward disks
- Strip-strip (2S) modules: 3 barrel layers and 5 forward/backward disks



Other developments: CMS @ HL-LHC tracking



Stacked sensors for triggering



- Want to exploit the stacked geometry for full offline reconstruction
- Reconstruct Vector hits from position measurements
- PS modules: 2 precise coordinates, 1 precise direction
- 2S modules: 1 precise coordinate, 1 precise direction
- Precision depends on stack separation
- Rough estimate of curvature possible



Other developments: CMS @ HL-LHC tracking



- Track finding with vector hits
- Preliminary study for WIT 2012, simplified simulation
- Have begun to set up a full simulation
- Will explore several algorithms:
 - Convergent Hough transform
 - Cellular Automaton
 - Artificial Retina
 - Combinatorial Kalman filter
 - ...





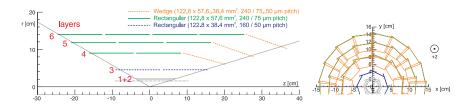
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> VXD — Vertex Detector

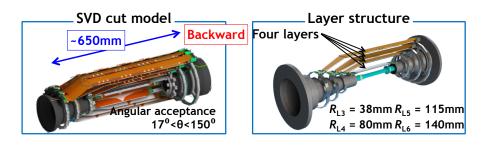
- VXD consists of two parts
- SVD (Silicon Vertex Detector) with 4 layers of double-sided Si strip sensors
- PXD (Pixel Detector) with two layers of DEPFET pixel sensors







■ SVD structure







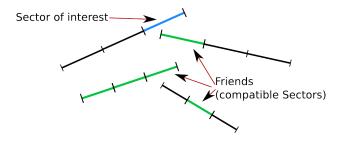
- SVD stand-alone track finding
- Want to find low p_T tracks
- Needed for data reduction in the PXD, has to run in HLT
- ullet Only 4 layers, little internal redundancy o prior information required
- Combinatorics reduced by precomputed sector map
- Several sector maps for different momentum ranges allowed





Sector map

- Sensors are sub-divided into sectors
- Each sector knows its friend sectors
- Sectors are friends if a track from the vertex can pass through both of them
- Hits are sorted into sectors





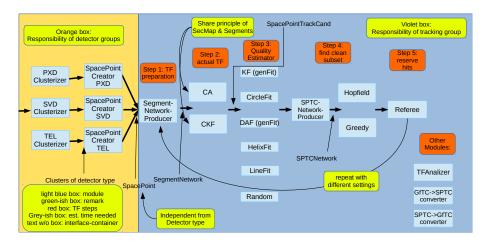


- Segment finding
- Segments are pairs of hits in friend sectors
- Sector map decides whether segment is accepted (2-hit filter)
- ➡ Tracklet finding
- Tracklets are pairs of segments sharing a hit
- Sector map decides whether tracklet is accepted (3-hit filter)
- Cut-based at the moment, will be supplemented by a NN
- ➡ Track finding
- Cellular Automaton connects tracklets to track candidates
- Quality estimation by fast circle/helix fit or full KF track fit
- Hopfield network selects best non-overlapping set of track candidates
- Extrapolate to PXD and define regions of interest
- Alternatives are envisaged, e.g. combinatorial Kalman Filter, 4-hit filters





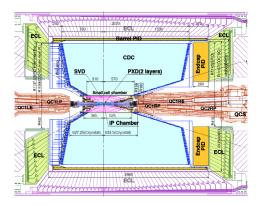
Overview of SVD track finding







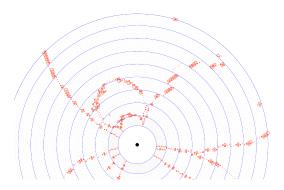
- ➤ CDC Central Drift Chamber
 - 56 concentric layers in 9 super layers, alternating axial and stereo
 - 14336 drift cells with sense wires in approximate hexagonal arrangement







- ➡ Algorithms
 - Cellular Automaton
 - Legendre transform

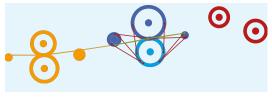




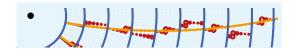


➡ Cellular Automaton

Step 1: Build segments from individual hits in each super layer



Step 2: Build tracks from segments

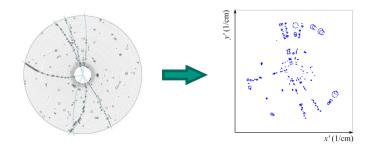


O. Frost, CHEP 2015





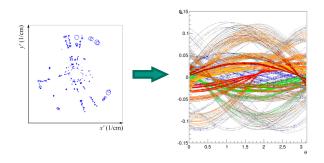
- ▶ Legendre transform
- Extension of Hough transform
- Conformal mapping transforms tracks to straight lines, drift circles remain circles







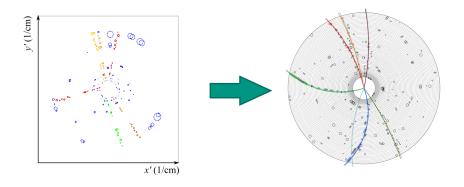
- Legendre transform: drift circles to sine curves
- An intersection of sinusoids in Legendre space corresponds to a common tangent to drift circles
- Legendre space is discretized, maxima found by voting algorithm
- Voting implemented by QuadTree







- ➡ Example event
 - \bullet Simulated event: $B^- \to D^0 \; (\to K^- \; \pi^+) \; \pi^-$ + beam background







Other developments: Belle II Track merging and fit

Track merging

- Extrapolate tracks from CDC into VXD
- Extrapolate tracks from VXD into CDC

➡ Final track fit

- Least-squares fit with GENFIT package
- Can be done for several mass hypotheses

⇒ GENFIT

- Detector independent fitting package, detector description is Geant4 geometry/material
- Various propagators: analytical, Runge-Kutta, others can be implemented by the users
- Various methods: Kalman filter, deterministic annealing filter, general broken lines fit
- Very flexible: accepts hits on plane sensors (pixels/strips), wires with drift circles, other geometries can be implemented by the users
- Easy to interface with MillePede





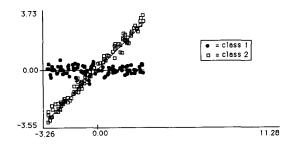
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- Starting point is an unlabeled mixture of regression models
- Fuzzy c-regression (FCR) is a method for simultaneous fuzzy labeling and estimation of the regression models, see [?]
- Solution is obtained by an iterative procedure, similar to EM algorithm



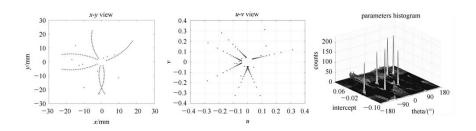
Niu Li-Bo, Chinese Physics C Vol. 39, No. 3 (2015)





➡ Application to tracking

- Conformal transformation transforms circles to straight lines
- Initial number of tracks and initial values of angle and intercept from 2D Hough transform
- Run FCR on all hits in the u-v plane

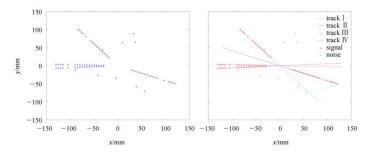


Niu Li-Bo, Chinese Physics C Vol. 39, No. 3 (2015)





- Simulated example
- Prototype TPC for ILC
- 21 measurements between 30 mm and 130 mm
- Spatial resolution $\sigma = 100 \, \mu m$
- Hit efficiency 90%
- Artificial noise added

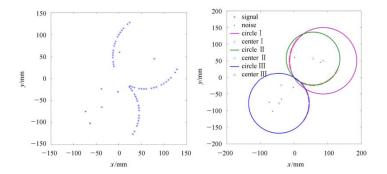


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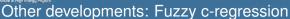


- Extension to circle finding
 - A circle fit in the plane can be transformed to fitting a plane in 3D by projection to the Riemann sphere or a circular paraboloid
 - FCR can be used to fit all planes/circles simultaneously



Niu Li-Bo, Chinese Physics C Vol. 39, No. 3 (2015)







- ➡ How useful is it?
 - Depends heavily on a good initialization of the regression models
 - Remains to be seen whether useful for high track multiplicity





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Summary and outlook

→ Improvements for Run2

- Basic approach of iterative seeding and track following still feasible
- Accumulation of "small" changes can have a big impact
- Correct treatment of pixel clusters essential for efficiency and resolution in narrow jets

➡ Real-time tracking

- Requires hardware beyond CPU: GPU, Associative Memory, FPGA
- Code adapted to various types of hardware, vectorized, parallelized
- If correctly designed, bulk of code can still be shared between on-line and off-line

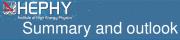


Summary and outlook

- >> Vertex reconstruction
- Iterative vertex finding still feasible in Run 2
- Imaging algorithm possible alternative
- Plan to study application of model-based clustering to vertex finding
 - Uses Bayesian paradigm
 - Can use prior information on number of vertices
 - Can use prior information on vertex distribution

→ Other topics

 See talks at "Connecting The Dots" workshop in Berkeley, Feb. 2015: https://indico.physics.lbl.gov/indico/conferenceDisplay.py?confld=149







Thank you!





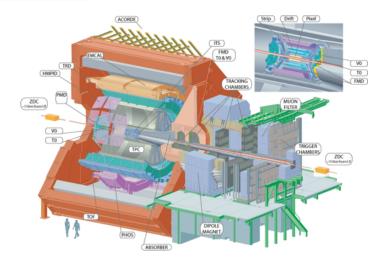
Bonus slides







▶ ALICE detector

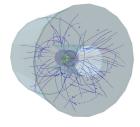




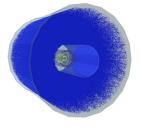




Formidable tracking problem



A pp event (real data)

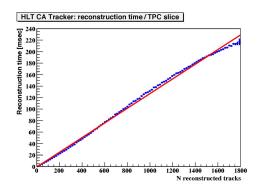


A heavy ion event (simulated)





- → ALICE High-level trigger
- Full track reconstruction in HLT
- Based on Cellular Automaton approach
- Reconstruction time proportional to multiplicity

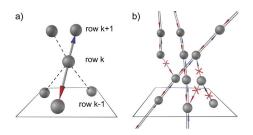






⇒ Cellular automaton

- Combinatorial search for track candidates
- Unphysical hit combinations are eliminated at the local level
- Two steps
 - a) Neighbor finder: For each hit in row k, search the best pair of adjacent hits; store the links of the three hits that form a straight line
 - Evolution step: Reciprocal links are determined and saved, all the other links are removed



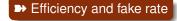




- Track finding and fitting
- Track finding: Track candidates are created by following the hit-to-hit links
- Track fit: The geometrical trajectories are fitted by a Kalman Filter, with a quality check
- Track extension: Track candidates are extended in order to collect hits close to the trajectory
- Track candidate selection: In case of overlaps select the longest track candidate
- Final quality check: Lower cut on number of hits and momentum

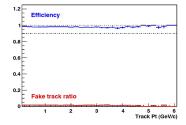








pp collisions at 14 TeV



Central heavy ion collisions at 5 TeV





- Tracking on GPU hardware
 - Code ported first to NVIDIA/CUDA, recently to AMD/OpenCL
 - Only single precision calculations
 - Numerically stable Kalman filter
 - Dynamic scheduler, optimized memory layout

