

Fast integration program for spin tracking

Straight Forward Integrators Up To Now

Two Integrators*:

- 4th order Runge-Kutta (Selcuk)
- 5th order Predictor-Corrector (Yannis)

Both are:

- Accurate for short times
- Slow
- Not very flexible
- Expressed in cartesian lab-frame coordinates
- Hard to parallelize (well)
- Written in old style/language

=> decide to write a new code in C++

* <http://arxiv.org/abs/1503.02247>

Goals For New Development

New code should be:

- Fast
- Parallel, possibly on GPUs
- Very accurate
- Flexible
- Able to use different integration algorithms
- Able to give indications about precision
- Able to track particles in 3 dimensional lattices



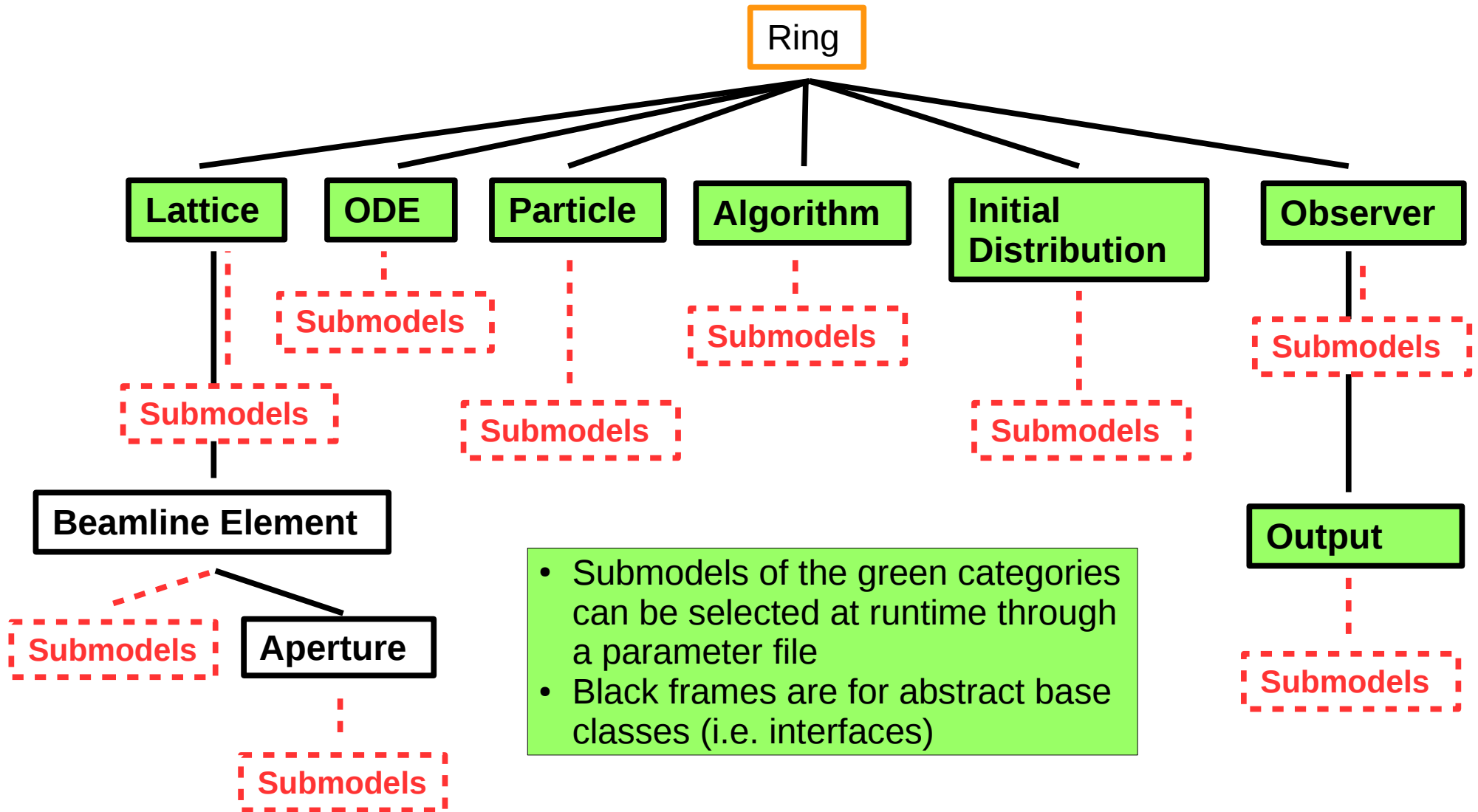
Design Decisions

Use:

- Boost library, especially package odeint (different integrators)
- VexCL* for parallelizing code on CPUs/GPUs
- ROOT and/or Gnuplot for postprocessing
- Curvilinear coordinate system with s as independent parameter
- Easy to extend modular design with fixed interfaces
- Virtual constructors to select different models at runtime

* **V**ector **EX**pression template library for Open**CL**/CUDA,
<https://github.com/ddemidov/vexcl>,
<http://arxiv.org/abs/1212.6326>

Modular Design



Benchmarking: Magnetic Ring

- All benchmarking is done with **Bulirsch-Stoer algorithm** at required relative and absolute accuracies of 10^{-8} (10^{-10} with rf cavity)
- **Data type: long double**

Pitch Effect: Small correction C of spin precession frequency due to vertical pitch, $\omega = \omega_a(1 - C)$

Without focusing: ω is matched to the 10^{-11} level, same accuracy as frequency fit

With focusing: ω is matched to the 10^{-10} level, frequency is still determined to the 10^{-11} level

- analytic formula also makes approximations
- can express analytic results in terms of tune → **tune is correct to at least 10^{-10} level**

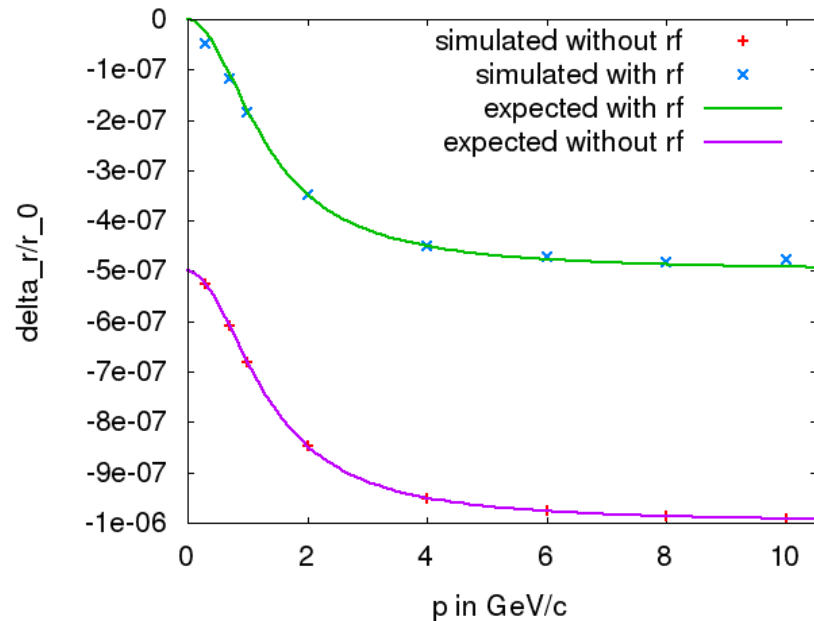
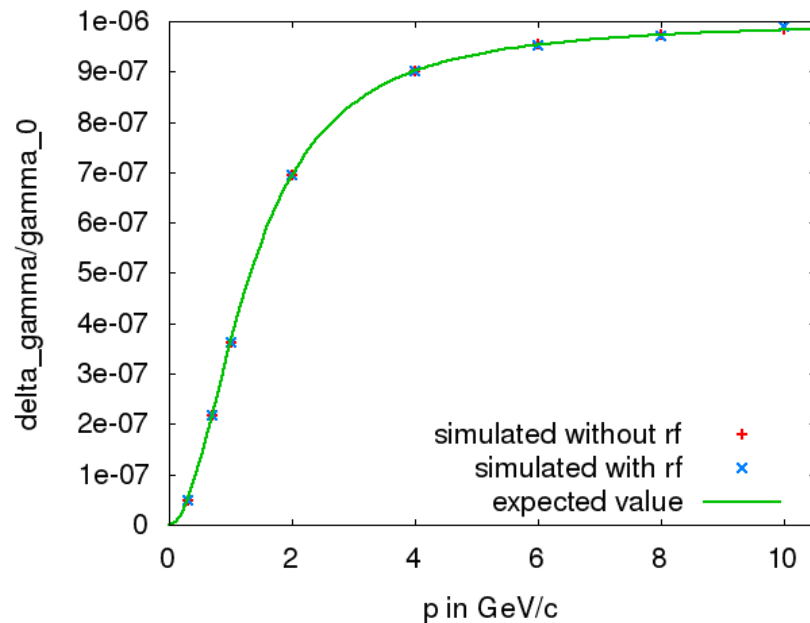
Benchmarking: Electric Ring 1

All-electric ring, ideal particle but with vertical pitch, no focusing, expect:

$$\left\langle \frac{\Delta\gamma}{\gamma_0} \right\rangle = \langle \theta_y^2 \rangle \frac{\gamma_0^2 - 1}{\gamma_0^2 + 1}$$

$$\left\langle \frac{\Delta r}{r_0} \right\rangle = \begin{cases} -\frac{1}{2} \langle \theta_y^2 \rangle \frac{\gamma_0^2 - 1}{\gamma_0^2 + 1} & \text{with rf} \\ -\langle \theta_y^2 \rangle \frac{\gamma_0^2}{\gamma_0^2 + 1} & \text{without rf} \end{cases}$$

- Y. Orlov at ECT Trento workshop, Oct. 1-5, 2012
- <http://arxiv.org/abs/1504.07304>
- <http://arxiv.org/abs/1503.06660>

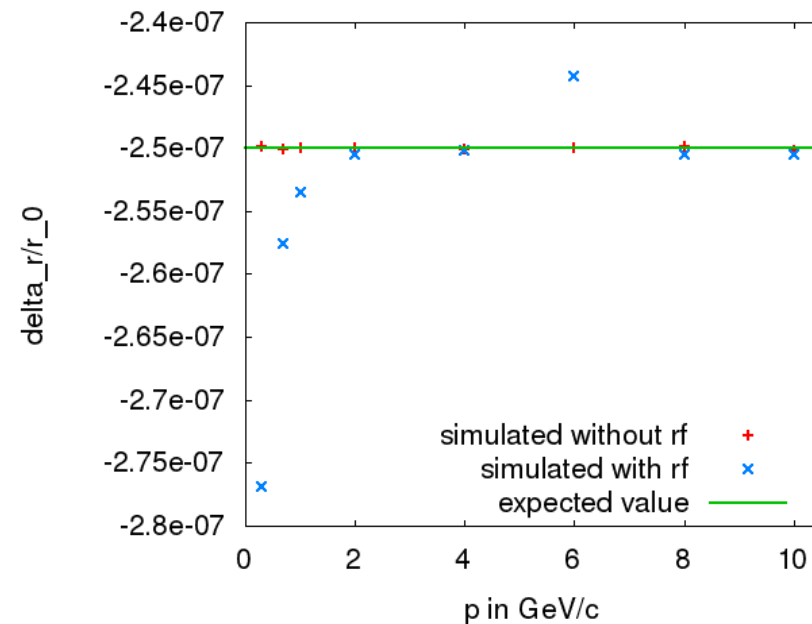
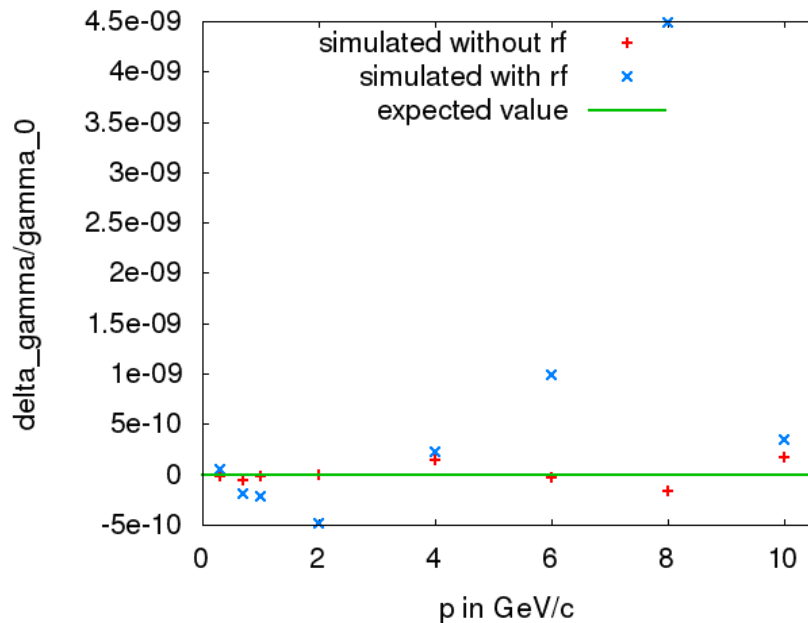


Benchmarking: Electric Ring 2

All-electric ring, ideal particle with vertical pitch, weak focusing expect:

$$\left\langle \frac{\Delta\gamma}{\gamma_0} \right\rangle = 0$$

$$\left\langle \frac{\Delta r}{r_0} \right\rangle = -\frac{1}{2} \langle \theta_y^2 \rangle = -\frac{1}{4} \langle \theta_0^2 \rangle = -2.5 \cdot 10^{-7}$$



→ rf results not that great, probably because of extended cavity and slow oscillations

Some (not surprising) Observations

- Errors due to machine accuracy can be cut by higher precision numbers, algorithm errors and simplification errors remain
- Algorithm errors can be cut by using shorter time steps
→ **Precision needs time!**
- Time step seems to be limited by oscillation frequencies, **dt should be much smaller than shortest oscillation period**
- Magnitude of spin is not conserved during simulation → loss rate can be good accuracy measure
- Total energy is conserved due to formulation of the problem, ratio of potential energy to kinetic energy changes over time, i.e. **radial drift is observed instead of energy loss due to non-symplectic algorithms**

Plans For Future

- **Parallelize!**
- Calculate beam parameters from many particle simulations
- Implement new submodels, i.e. new beamline elements, etc
- Possibly use Hamiltonian approach together with new geometric integrators in order to respect evolution on Lie groups
- **Use the program!**