

# CDB and Batch Processing

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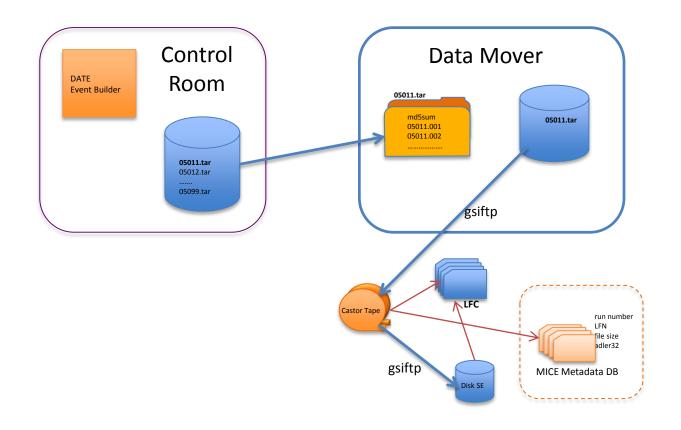
MICE CM42 Analysis, Software and Reconstruction

# Raw Data Mover (2!)

- The Raw Data Mover has been upgraded
- Runs on a new SL6 box with EMI UI 3.x
- Ugly system command executing has been removed
- Uses EMI new GFAL2 Python API the code is now more "pythonic".
- Successfully tested during mock runs last fall
- Runs w/o major interruptions during current data taking

### Raw Data Mover Workflow

(as a reminder)



# Raw Data Mover Summary

- Developed in summer 2011, in use since Oct 2011,
- Rewritten in 2014 to use GFAL2
- Successfully used to store data on Castor to date,
- Uses up-to-date Python API,
- Use robot certificate, currently my personal,
- Still not using the dongle

### MAUS Reconstruction on the Grid

- GRID MAUS installation via CVMFS at RAL,
- Propagated to Brunel, Imperial and the PPD
- Build and compiled on SL6, last build used is MAUS\_v0.9.4, last built and installed - 0.9.5
- All current data being reconstructed with this version, no major glitches
- No major changes to the framework (see my talk for CM37)

# **Configuration Database**

project status

- We maintain a primary CDB server in the Control Room, including a supermouse WebService front end.
- A hot standby in the PPD which mirrors TH primary DB, read only
- A preprod DB with write access

# Configuration Database (contd.)

#### An extension to the server API:

- Batch Iteration number which allows storing multiple MAUS data cards for the same MAUS version,
- MC serial number
- Server-site code extended
- Python API for the client written

A few bug fixes have been done on the server (Calibration, DAQ Cabling and Tracker calibration) Encoding problem fixed on preprod, so BLOBs are decode properly now.

### **Configuration DB**

Request from Pierrick to provide API to store/retrieve data for the cooling channel.

- Relevant table existed in the DB,
- The Web Service interface is deployed, Python API exists.
- The C-API has been written using gSOAP binding, unit test using Cunit. Ready since last year and rusting.

# Configuration DB (contd.)

Latest development - Beamline a.k.a Run Control C-API

- Python API cannot be used due to problems with multithreading
- Reverse-engineered the Python API and C equivalents written.
- As for the Coolingchannel C-API gSOAP C binding is used,

### Beamline CDB API

- A set of C structs has been created to hold beamline data both for getters and setters
- A set of 'constructors' (default and custom)
  has been written to facilitate API usage. The
  destructor exists as well.
- A set of 'push' functions is provided to simplify creation of linked lists (like the magnet list).

### Beamline CDB API

- The API is 90% ready, one low priority 'get' function not yet complete.
- Uses XML schema to validate data supplied by a user
- CUNIT tests exist
- Documentation exists (doxygen)
- Project on Launchpad:

bzr+ssh://bazaar.launchpad.net/~janusz-martyniak/mcdb/mice.cdb.client.api-C/

### CDB C API

#### In numbers ..

•					
•	Language	files	blank	comment	code
•					
•	С	83	739	1583	4468
•	XSD	7	77	58	515
•	C/C++ Header	12	90	129	402
•	make	1	29	17	73
•					
•	SUM:	103	935	1787	5458
_					

Well commented;)?

## CDB - Summary

- CDB is fully operational, bugs discovered have been fixed
- Server code Python API has been extended (Batch Iteration Number and MC Serial Number)
- C-API developed for the Collingchannel (not used yet), and Beamline (only roughly tested in the Control room)