

# Plans for delivery and commission the RF system

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For the MICE RF team

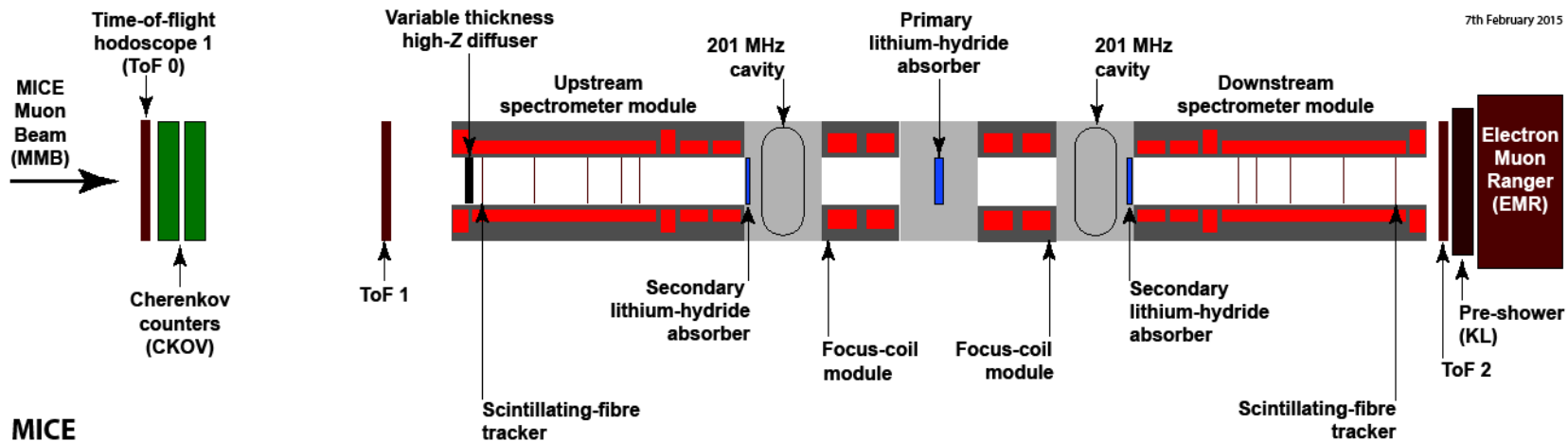


# Content

- The RF System has several Key subsystems which have been addressed in other talks
  - **RF Cavities and Cavity Modules**
    - Progress on the tests at the MTA discussed in the second paper
    - Cavity modules addressed in third paper
  - **RF drive and distribution system**
    - Plans for test, delivery and installation of amplifiers will be addressed here
      - Encompasses development of remote control (2<sup>nd</sup> talk) and LLRF control (final talk)
  - **Cavity tests at RAL**
    - Opportunity for a full system test
    - Commission all major components before assembly in beam line
  - **Muon-RF phase determination**
    - If time permits

# MICE High Power RF systems

- MICE HPRF system requirements have changed
  - Fewer cavities, no coupling coil
  - Required operational date on the beamline is Summer 2017
    - Requires early commissioning of the hardware: Starting Aug 2016
  - Enables demonstration of ionisation cooling with re-acceleration
  - First results complete before end US fiscal year 2017
- It is relevant to review the timeframe and resources required to deliver this system



# MICE High Power RF drive systems: Commissioning



- **2MW peak output from RF drive amplifiers, are unchanged**
  - First triode amplifier proven and installed at RAL
  - First tetrode amplifier also proven with pulsed power modulators
    - These are now back at Daresbury
- **Commissioning System No. 2**
  - Recommissioning of tetrode pre-amplifier no. 1 underway at DL
    - Operated at 100kW in the past two weeks
  - This will be used to commission triode No. 2 with first modulators
    - Mechanically refurbished triode no 2 is now installed in test facility
    - Requires electrical work to finish
  - Tetrode No. 1 will be replaced by tetrode no 2 by end of year
    - Tetrode no 2 also primarily requires electrical completion
  - Remote control system no. 1 will be implemented in control rack by end of year
  - 2<sup>nd</sup> Triode and Tetrode amplifiers operating with 1<sup>st</sup> control rack and modulators by end 2015
  - 2<sup>nd</sup> Triode and Tetrode Amplifiers operating with 2<sup>nd</sup> modulators and control rack by end Summer 2016

# MICE High Power RF systems: Tim Stanley

Triode No. 1 at RAL



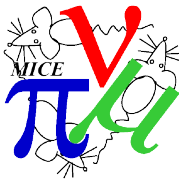
Triode No. 2 Completed  
Mechanical Refurb at Daresbury



Tetrode No. 1 Re-commissioned at Daresbury Lab



# MICE High Power RF drive systems: Installation and Test



- **Amplifier System No. 1**

- First triode remains installed at RAL
- Reinstall Tetrode No.1 with Modulators No.1 and control racks No. 1 Spring- Aug '16
  - Build on previous installation for TIARA tests
  - Note there may be some conflict with key people required for installation at RAL and commissioning at DL
  - Will require mechanical modification to the Mezzanine
- Prove with 1 Month of test operation into resistive loads

- **Amplifier System No. 2**

- Project completion of Daresbury proving trials by Summer' 2016
- Installation can commence from July '16 to Jan '17 (preliminaries need not await July '16)
  - Build on experience from installation of system No. 1
  - Will require new wiring 'loom' installation, additional cooling water panel and mechanical modification to the Mezzanine
- Prove with 1 Month of test operation into resistive loads

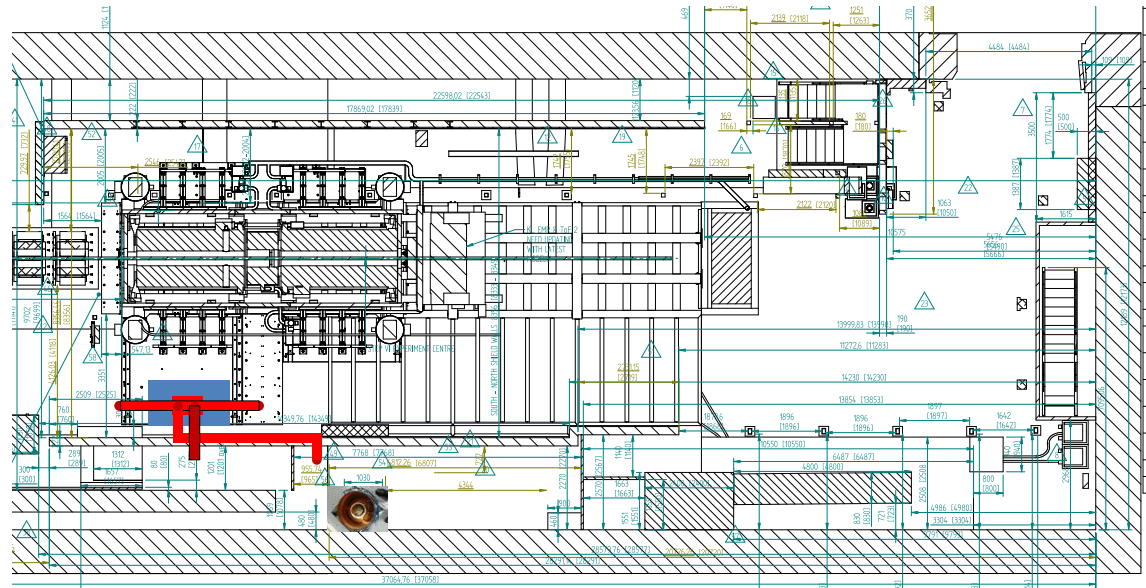
# Cavities: Pre-Installation

## Cavity Module No. 1: Arrival and Installation

- Assumed to arrive under purge and fully assembled May '16
  - Assume cavity will not require any further baking
- In advance, auxiliary systems will be prepared in MICE hall
  - Clean room: Essential in case any intervention is required
  - Independent cooling loop for each cavity with tight thermal regulation
- LLRF tests to verify safe transport and arrival
- Install cavity next to shield wall opposite U/S SS, special distribution network
- Install vacuum pumps and pump cavity ready for operation late Jun 2016 (1-2 months)

## Cavity Module No. 2: Arrival and Installation

- Assumed to follow same pattern as Cavity module No. 1 with object of completion at Oct 2016



MICE CM42: RF Drive Summary 24th June  
2015

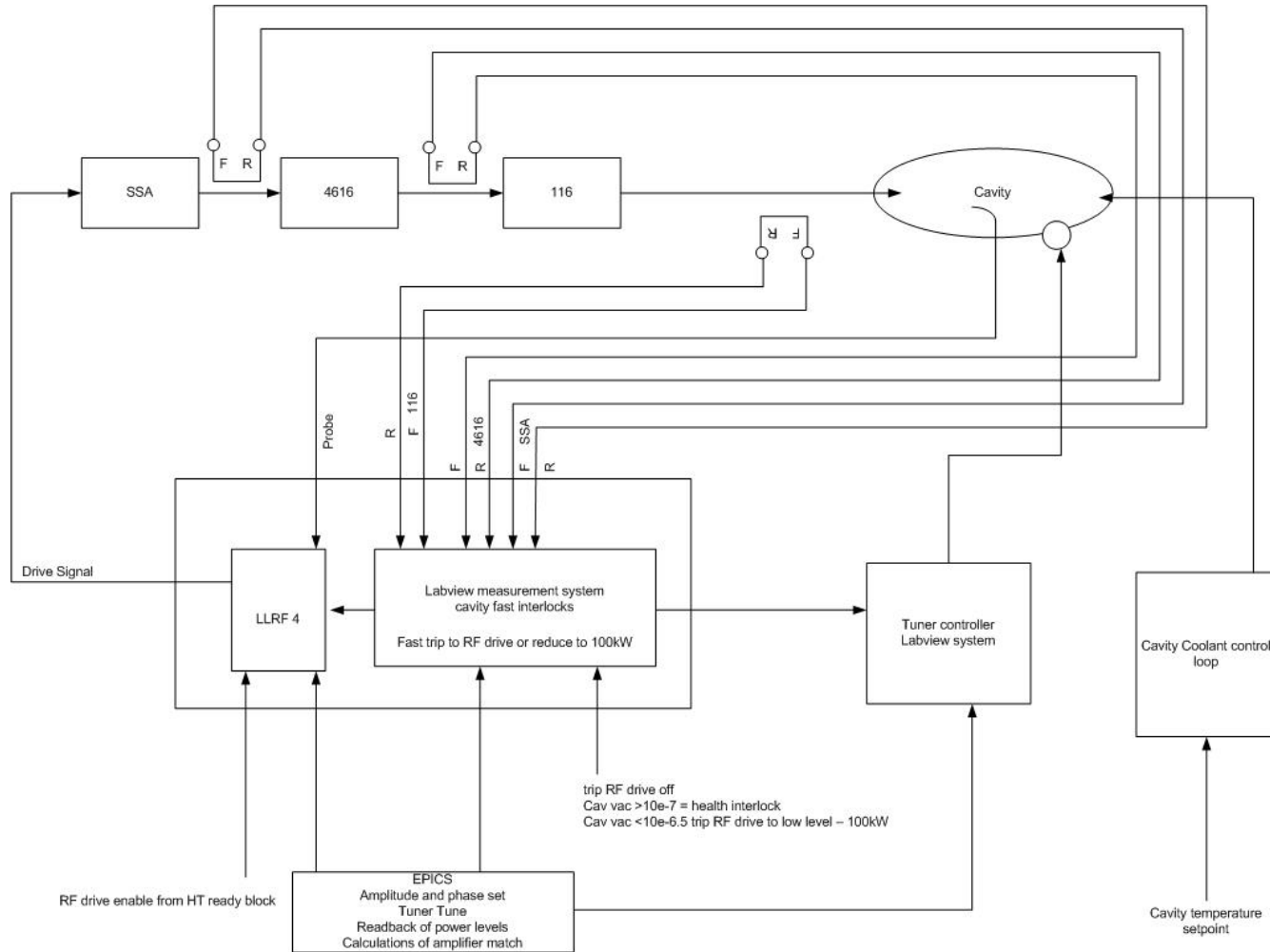


# Cavities: Pre-Commissioning

- **Pre-requisites**
  - RF system No.1 with full remote controls is expected to be available in July 2016
  - Cavity No 1 expected available by June 2016
  - LLRF tuner control and RF closed loop control system expected by Summer 2016
  - Installation of RF power feeds to the test point (shield wall opp. U/S SS)
- **HPRF Tests of Cavity No. 1**
  - Initial tests on a single cavity, using drive system No. 1
  - Aug '16- Oct '16, est 2 months for complete tests
- **HPRF Tests of Cavity No. 2**
  - Oct '16- Dec '16 using drive system No. 1
  - Leave in situ until last possible moment
  - Opportunistically test with drive system no. 2 if timing is good



# LLRF Drive and Cavity Control System: Andy Moss





# Cavities: Installation

- **Pre-requisites**

- Completion of tests on two cavities with RF amplifier No. 1
  - Ideally also pre-commissioning tests with Amplifier No. 2 and Cavity No. 2
- After tests cavities left under purge N<sub>2</sub> gas
- Removal of the STEP IV yoke and completion of the absorber, spool pieces
- Build of floor plates, mechanical integration components
- Installation of final RF distribution network (planned for Aug '16- Feb '17)

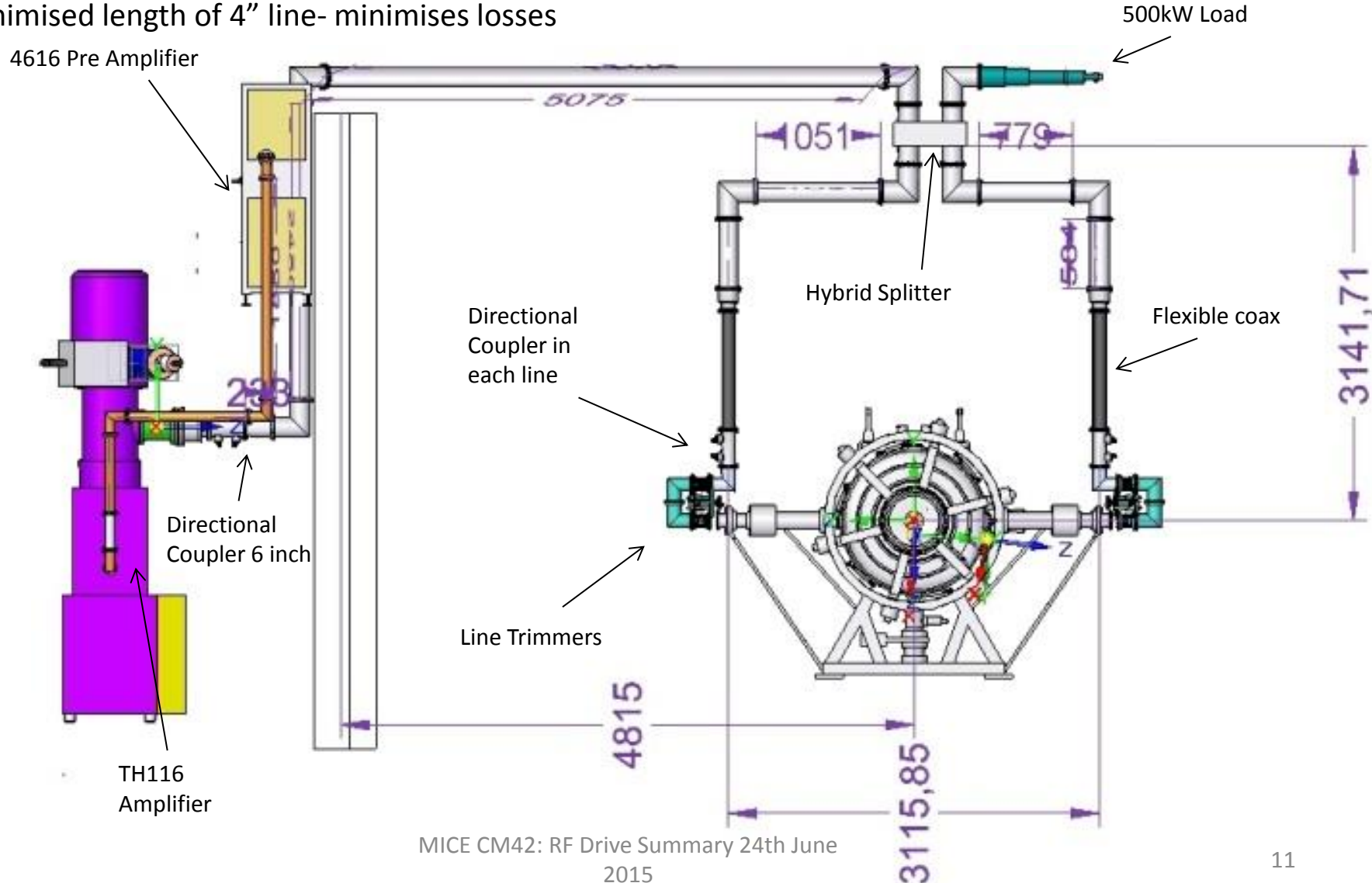
- **Procedure**

- Cavities should be left under purge until the last possible moment.
- Absorber and spool sections 'beam line vessel' should be pumped separately and left under purge
- When final installation is imminent, the 'beam line vessel' cavity gap be opened and the apertures blocked with thin plates
- When ready, the end plates of the cavity modules should be removed, replaced with thin plates for installation
  - Cavities immediately installed in the beam line vessel
  - Immediately 'rough pumped', then HV pumped
- Starting by Feb '17 and planned complete early March 2017, validate with LLRF measurements

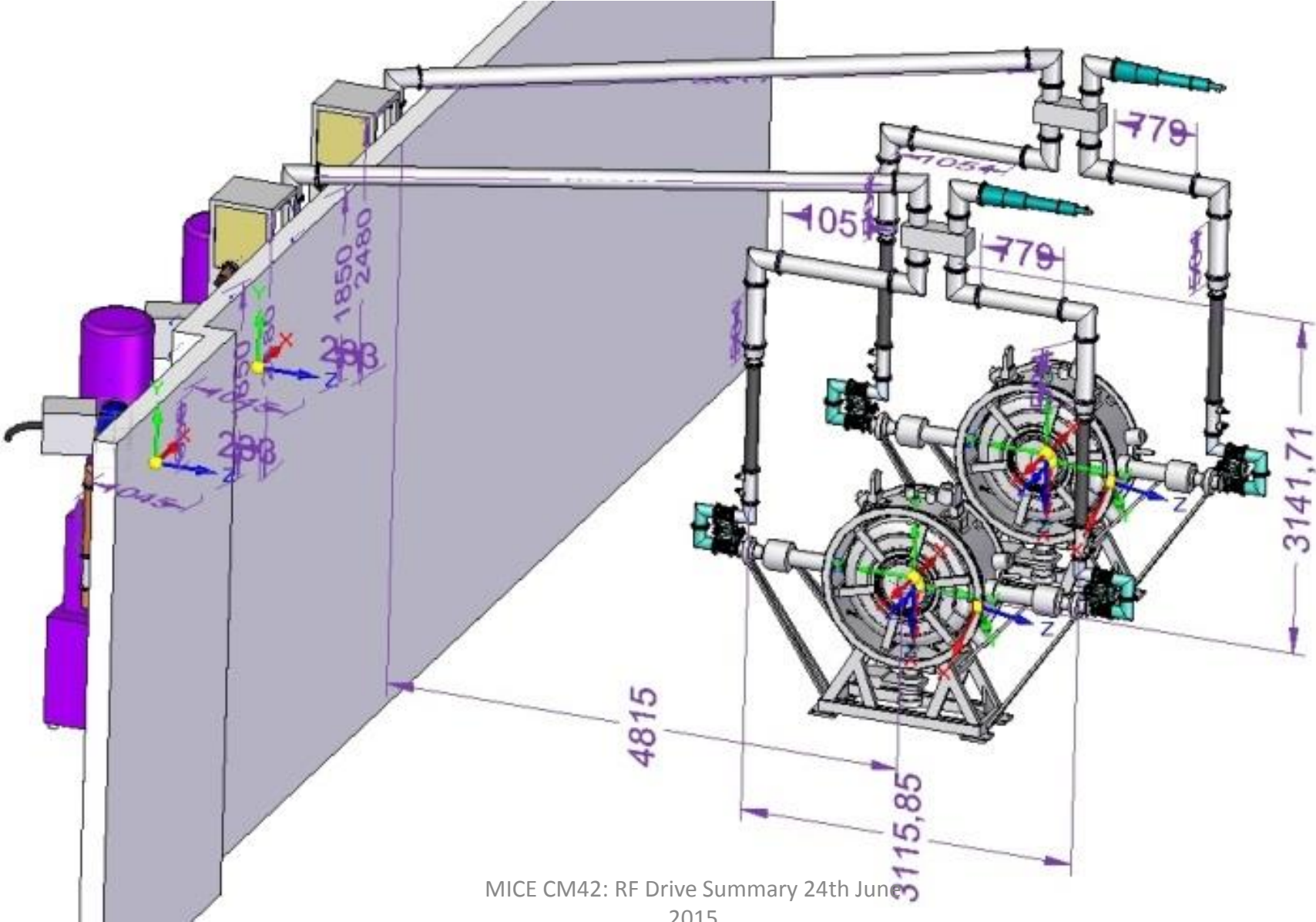
# RF network: Alan Grant



- Simplified distribution network- feasible to route overhead
- Off-centre mounting of hybrid takes up phase shift
- Orientation of load arbitrary- align with the 6" distribution line and share mountings
- Minimised length of 4" line- minimises losses



# RF network



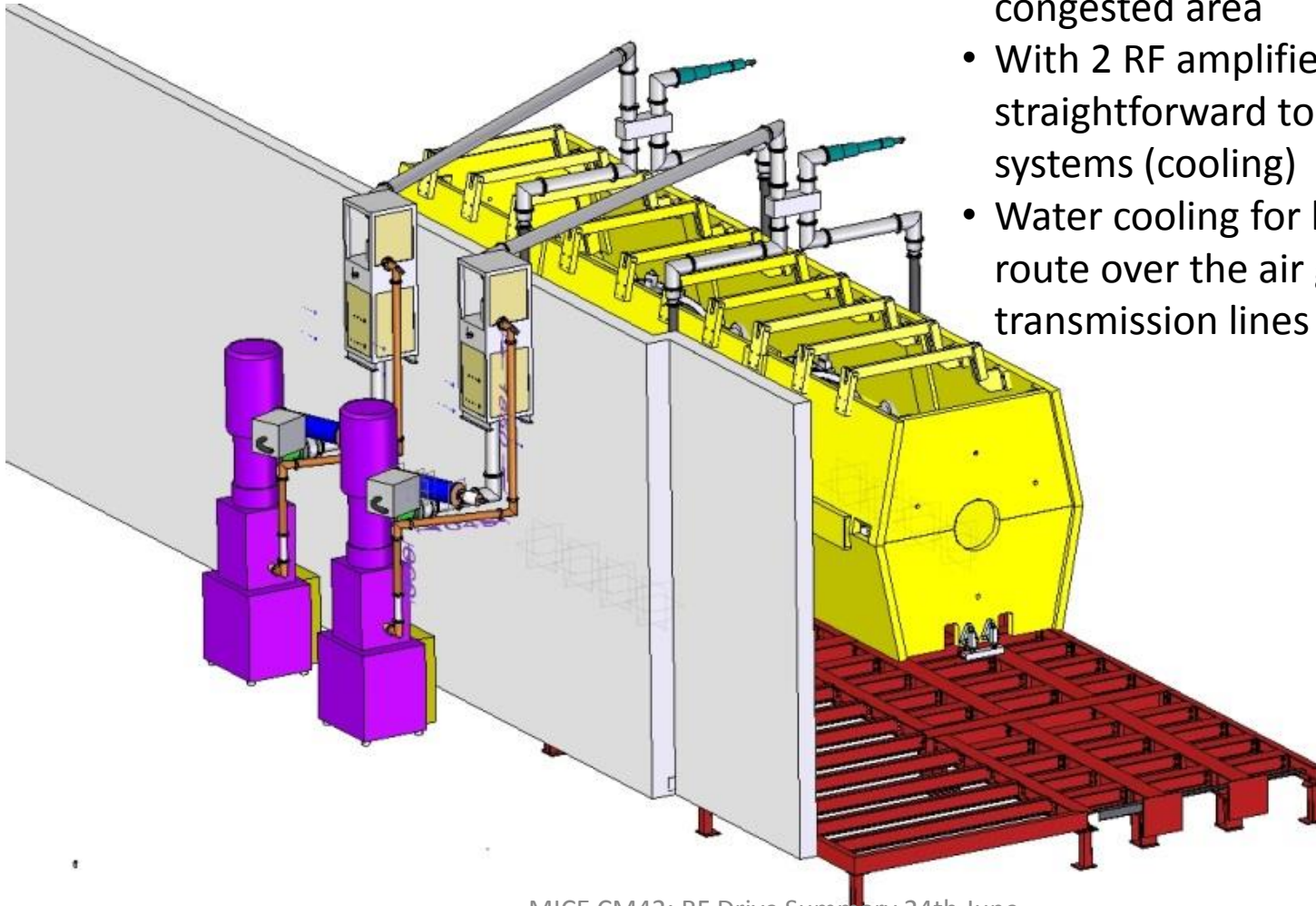


# Cavities: Commissioning

- **Commissioning without B field**
  - Cavities should be HPRF tested on beam line before yoke is complete
    - In case any intervention is required
  - Estimate <1 month operation of both cavities together, so completion by April 2017
- **Commissioning with B field**
  - Requires completion of Yoke and re-commissioning of all magnets
    - Note ONE magnet only will be added to the STEP IV set
    - Yoke plate final installation est ~ 1 wk
    - Commissioning of magnets will benefit from the STEP IV plan
      - Outlined by Jaroslaw yesterday
  - Tests of the cavities with magnetic field and all systems April 2017, say 2wks- 1mnth
    - In parallel with magnet commissioning if possible

# RF network

- Load on each splitter to absorb unbalanced reflections
- Retracted crane hook clears coax over the wall.
- Support from present 'shield wall' and yoke supports
- 2<sup>nd</sup> amplifier moved to 3<sup>rd</sup> position behind wall to ease installation in congested area
- With 2 RF amplifiers now relatively straightforward to place auxiliary systems (cooling)
- Water cooling for load will need to route over the air gap on the transmission lines



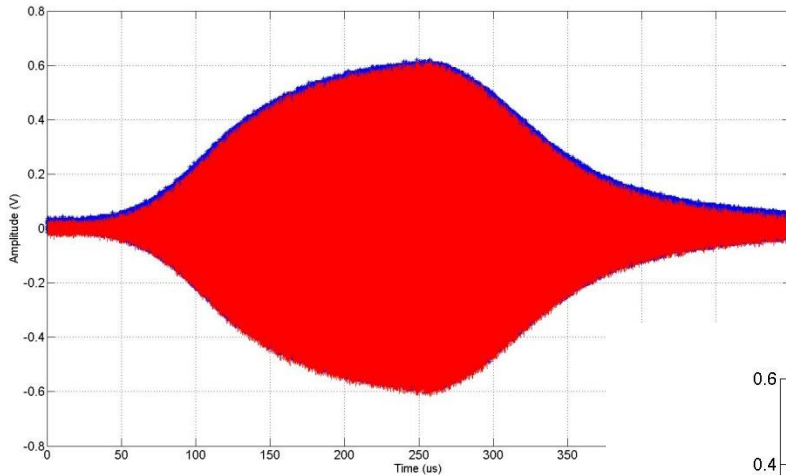


# RF Phase determination: Alex Dick

- Need to be able to select particles for analysis by their RF transit phase
  - Allows the 'bundling' of particles for coherent analysis
  - i.e. As if we are considering the interactions of a real particle 'bunch'
- Particle transit time determined by ToF detectors- used in difference measurements
  - ToF resolution  $\sim 50\text{ps}$
  - Time is not directly referenced to external clock
  - Closest ToF is  $\sim 2.5\text{m}$  upstream of 1<sup>st</sup> cavity
- Cavity transit time inferred by the ToF transit time and the tracker measurement of momentum
  - Tracker resolution,  $p_z \sim 200\text{MeV}/c$  is  $\Delta p_z \sim \pm 1.3\text{MeV}/c$
  - For 2.5m gap transit delay is  $\sim 9.6\text{ns} \pm 15\text{ps}$
  - Combining ToF resolution and Momentum projection resolution  $\sim \pm 52\text{ps}$
  - Desire to know RF phase to better than 0.3 of this  $\sim 20\text{ps}$

# Demonstration of subsample approach

- Traces of cavity fill from MTA tests
- Test viability of subsampling the AC waveform- suppress data management by orders of magnitude
- Reconstructing signal in Fourier domain and comparing signals (Blue is Raw, Red is DSP)

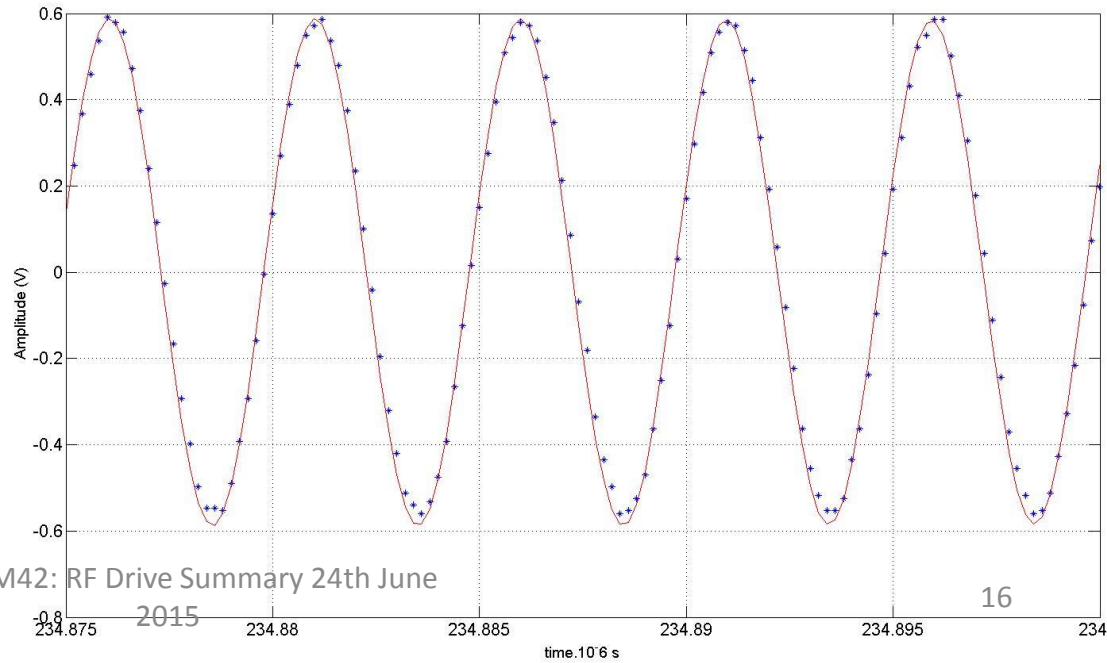


- Note suppression of DC bias
- Note DSP has effectively filtered the signal
- Suppressing noise and instrument artefacts

- Zero crossing offsets between Raw and DSP?

Range from 10-75 ps

Not good enough



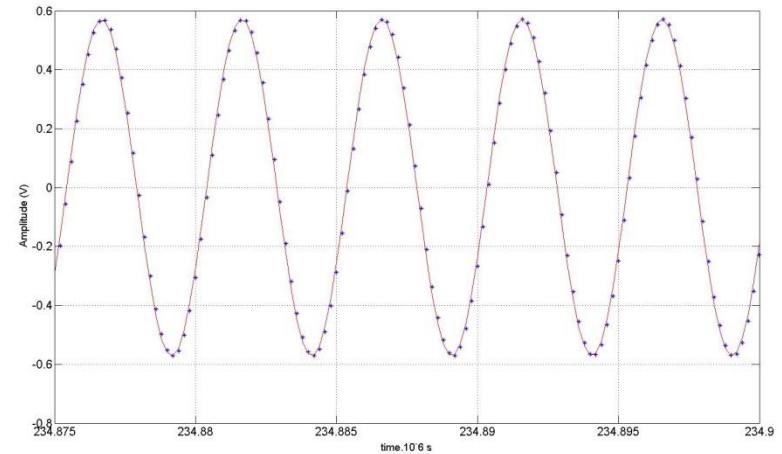
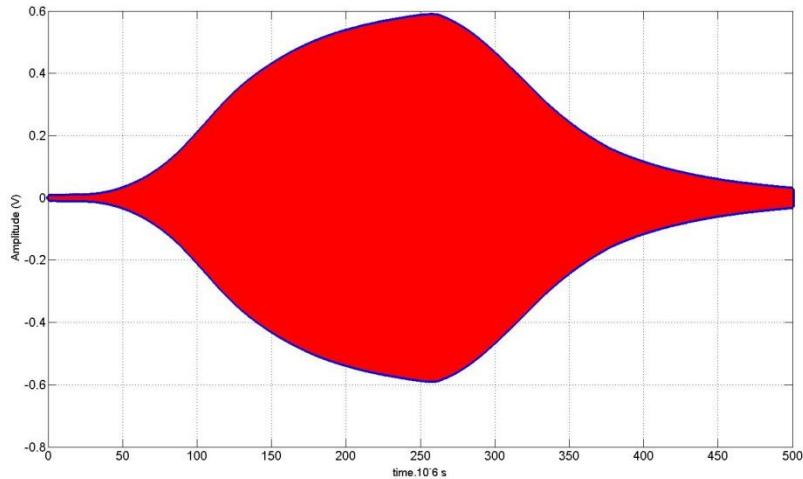
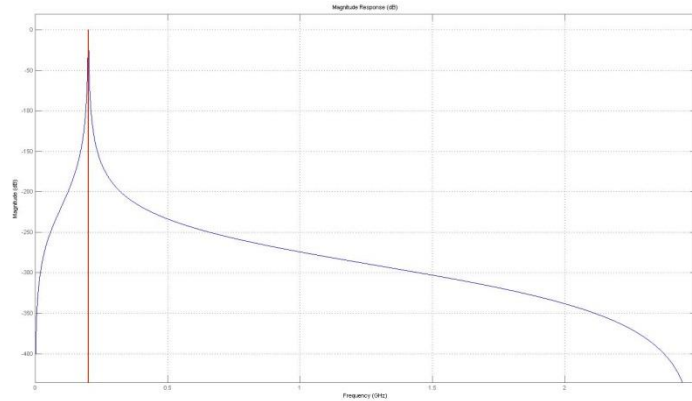


# Filter: Suppress noise and digitiser artefact

Butterworth Filter with flat 2MHz passband at 201.25MHz

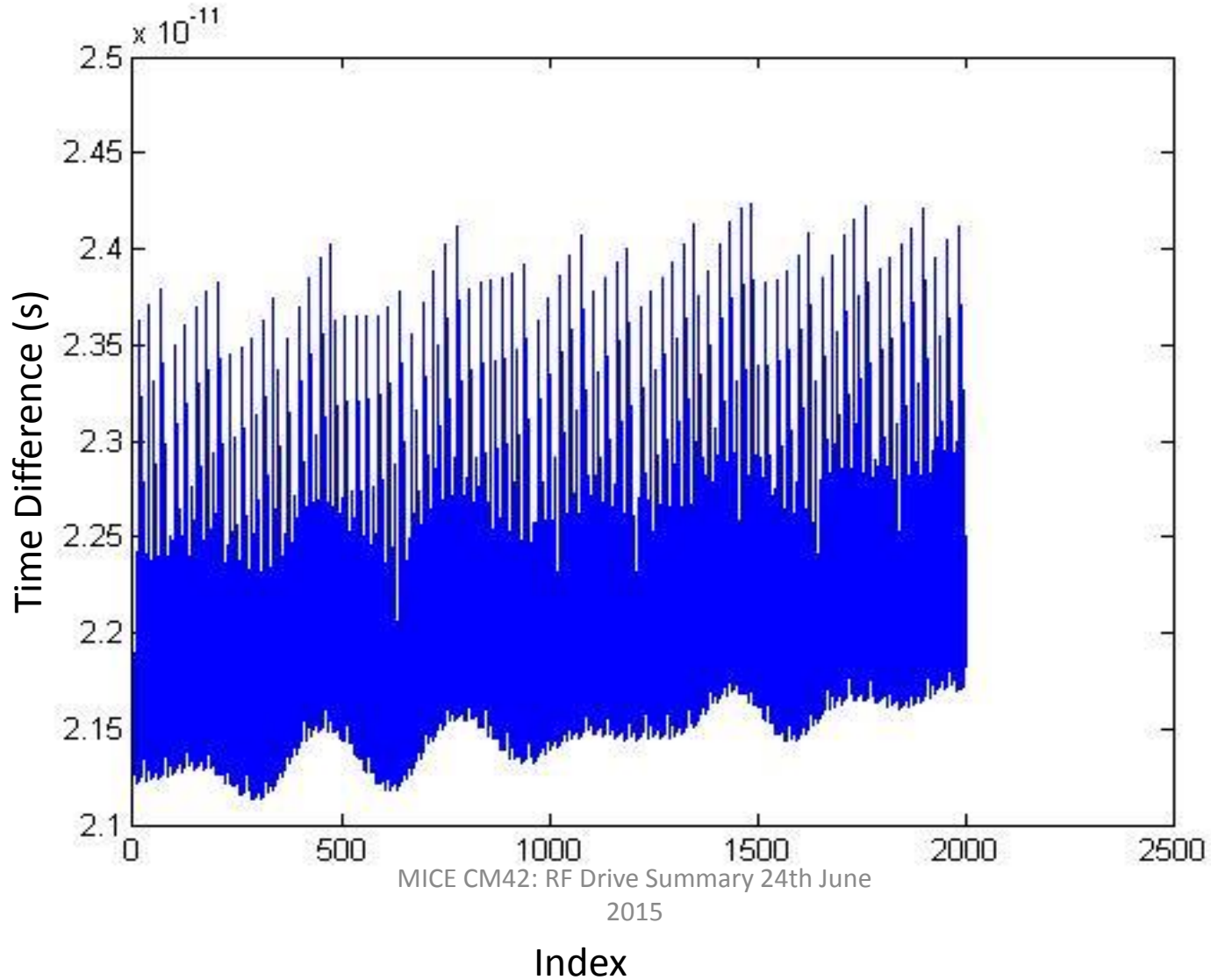
Very precise reproduction of signal

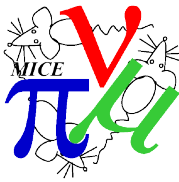
Much less variation in phase difference  $\sim 1-2\text{ps}$   
(between original and reconstructed signals)





# Difference between Original and Reconstructed signal Zero Crossings (Filtered)





# Hardware: Digitisers

- Will be important to provide clock synchronisation and trigger- i.e.  $t=0$  synchronisation for ToF TDC's and RF instruments
  - $t=0$  can be defined by an external trigger to zero all timebases
  - Just before accelerating gradient reaches maximumOR
  - Just before start of RF pulse
  - Use a pulse generator to provide 40MHz clock, and provide trigger by logical AND between clock and trigger pulse- should sync start of timebases
- CAEN V1761 have external clock drive for acquisition rate
  - 10 bit rather than 8 bit units currently recording MTA data
  - Facilitate interfacing with 40MHz clocks of TDC's (requires programming of the clock controller)
  - Need to understand trigger jitter statement?



## Hardware: TDC approach

- This is currently planning to use the TDC (CAEN 1290) that are already being used to record the ToF signals
- RF signal driving discriminators, use TDC time stamps to find cavity 'zero crossings'
  - 25 ps bin size
- Same electronics enhances confidence that any drift in time accuracy will be similar
  - Unfortunately LeCroy discriminators seem problematic at 200MHz
  - Input impedance wanders with frequency, at 201.25MHz,  $98+j68\Omega$
  - Could be matched with L-branch network, but still doesn't fix rate problem
- RF signal amplitude and spectrum is very well known: no need for a CFD
  - Threshold trigger system is much less complex
  - Quote obtained from Phillips Scientific for updating and non-updating leading edge discriminators
  - 3ns double event resolution and 300MHz bandwidth, <30ps jitter



# Summary

- **Drive Commissioning Timetable**
  - Amplifier No. 1 with automation installed and operational by Aug 2016
  - Amplifier No. 2 with automation installed and operational by Feb 2017
  - LLRF and cavity control systems operational by Aug 2016
- **Cavities**
  - Arrival May 2016
  - Cavity no. 1 ready for standalone tests by end June 2016 : Complete by Oct 2016
  - Cavity No. 2 ready for standalone test by Oct 2016 : Complete by Dec 2016
  - Cavity installation to beamline Mar '17
  - Installation of distribution network by Feb '17
  - Tests of the cavities without B-field late March /early April
  - Tests of Cavities with B-field, May 2017
- **Muon Timing**
  - Subsampling techniques appears to work – filtering the signal is important
    - Requires resilience analysis
    - Digitiser selection needs to be complete
  - TDC technique- suitable discriminators identified
    - All other hardware in hand