# An Analytical Benchmark for the Calculation of Current Distribution in Superconducting Cables

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## Outline

- > Motivation
- > Historical Overview
- > Model and assumptions
- Set of analytical formulae for current distribution in multistrand cables:
  - non uniform boundaries
  - localised quenches
  - •localised driving voltages
- **≻**Conclusions

(1)

- Development of numerical codes including the calculation of current distribution
- > Large effort in the experimental activity
- The experimental validation is essential, but can be affected by approximations of the electromagnetic model and uncertainty in the evaluation of the model parameters
- > Analytical work can be used for a preliminary, independent code validation

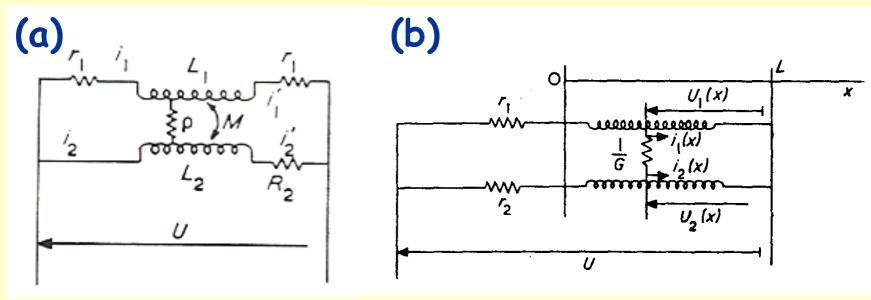
(2)

- Despite the large theoretical and experimental effort there is a lack of new design criteria taking into account uneven current distributions
- Analytical formulae for maximum currents induced in cables, time constants and redistribution lengths can be useful
- Previous analytical solutions are based on 2-strand cable models, a generalization to N-strand cables is interesting

## Historical Overview

(1)

Turck (1974): analysis of 2-strand cables, both insulated (a) and non insulated (b)

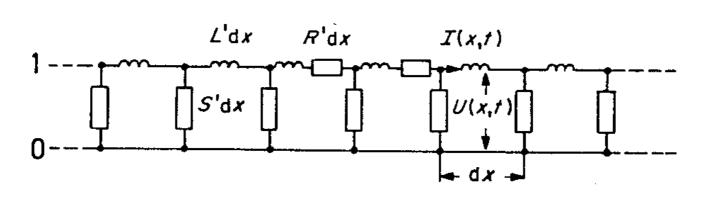


- $\triangleright$  Axial propagation of current sharing imposed at the boundaries with a magnetic diffusivity D=D(G, $L_1+L_2-2M$ )
- > Faulty wires
- > Short circuits between strands

#### Historical Overview

(2)

Ries (1980): analysis of 2-strand cables



- >Study of current sharing among quenching strands
- Determination of cable thermal stability through analytical calculation of power dissipated during transient
- > Definition of a characteristic redistribution length

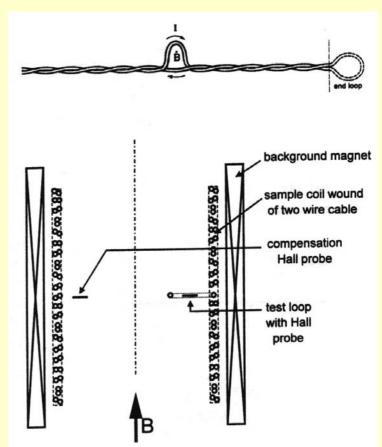
$$\lambda = \frac{1}{\sqrt{R'S'}} \qquad \tau = \frac{L'}{\pi R'}$$

#### Historical Overview

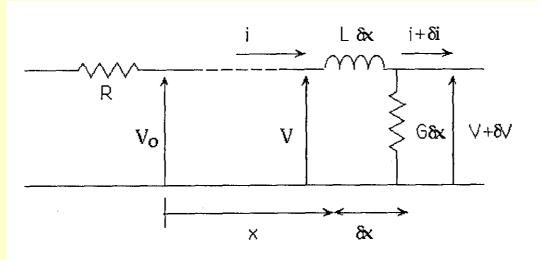
(3)

## Krempasky-Schmidt (1995): "Theory of supercurrents" with a 2-strand cable model

- Study of longitudinal variations of dB/dt
- > Two analytical solutions:
- Field ramps
   (forced diffusion)
- Constant field phases (free diffusion)
- Solution for a generic cycle is obtained through superposition due to linearity of the model



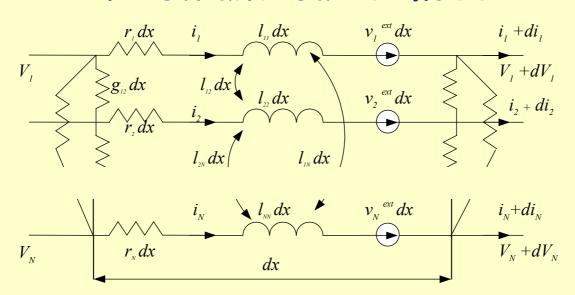
## Historical Overview (4) Mitchell (1999): analysis of 2-strand cables



- >Study of current redistribution from a normal zone
- >R is kept constant during the transient
- The redistribution region is considered to be in the superconducting state
- > Development of a lumped circuit approximation to the solution

## Model and assumptions

#### N-strand cable model



#### The model equations:

$$\mathbf{gl} \frac{\partial \mathbf{i}}{\partial t} + \frac{\partial^2 \mathbf{i}}{\partial x^2} + \mathbf{gri} - \mathbf{gv}^{ext} = 0$$

must be coupled with appropriate initial and boundary conditions

#### General solution

$$\mathbf{i}(x,t) = \frac{i_{op}(t)}{\sqrt{N}}\mathbf{b}_0 + \frac{2}{L} \int_0^L d\xi \ \mathbf{K}^{(0)}(x,\xi,t) \ \mathbf{i}^{(0)}(\xi) + \frac{2}{L} \int_0^L d\xi \int_0^t d\tau \ \mathbf{K}(x,\xi,t-\tau) \mathbf{v}^{ext}(\xi,\tau)$$

- Feneral analytical solution applies to circulant I and g matrices:  $I_{h,k} = I_{h-1,k-1} h, k = 2, N$ ;  $I_{1,k} = I_{N,K-1}$
- This condition is met: in Rutherford cables in CICCs wound in only one stage on average in multiple stage CICCs
- This solution involves: Intricate mathematical functions for kernels Numerical calculation of integrals

## Assumptions for simplified solutions

- 1 Nil initial current distribution  $i_h(x, 0) = 0$  h = 1, N
- 2 Nil longitudinal resistance  $r_h(x, t) = 0$  h = 1, N
- 3 Simplified model matrices

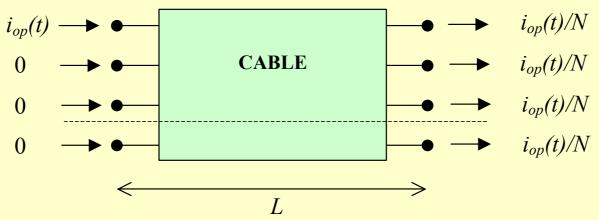
$$l_{hk} = l \text{ if } h = k$$
 $l_{hk} = m \text{ if } h \neq k$ 
 $g_{hk} = g \text{ with } h \neq k$ 

> These assumptions are strong, but:

they do not affect the validity of the benchmark when the solutions are compared to numerical codes

they allow an estimation of the mean behaviour of strand currents

## 1) Non uniform current distribution at the cable boundaries

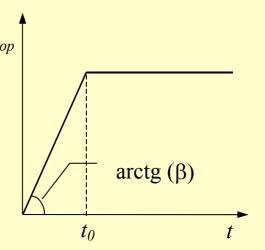


$$\begin{cases} \mathbf{g} \ \mathbf{l} \frac{\partial \mathbf{i}}{\partial t}(x,t) + \frac{\partial^2 \mathbf{i}}{\partial x^2}(x,t) = 0 \\ \mathbf{i} \ (x,t=0) = 0 \\ i_1(x=0,t) = i_{op}(t), & i_h(x=0,t) = 0 \\ i_h(x=L,t) = \frac{i_{op}(t)}{N} & h = 1, N \end{cases}$$

External voltage is neglected

## Current cycle: ramp-up + plateau

$$i_{op}(t) = \beta t$$
 for  $t \le t_1$   
 $i_{op}(t) = \beta t_1$  for  $t > t_1$ 



## Strand currents during the current ramp $(t \le t_1)$

## Linear variation with *x*

#### **Deviation from linearity**

$$i_1(x,t) = i_{op}(t) - i_{op}(t) \frac{N-1}{N} \frac{x}{L} - \frac{N-1}{N} 2\beta \sum_{n=1}^{\infty} \frac{\tau}{n^3 \pi} \sin\left(\frac{n\pi x}{L}\right) \left[1 - \exp\left(\frac{-t}{\tau_n}\right)\right]$$

$$i_h(x,t) = i_{op}(t)\frac{x}{NL} + \frac{1}{N}\beta \sum_{n=1}^{\infty} \frac{\tau}{n^3 \pi} \sin\left(\frac{n\pi x}{L}\right) \left[1 - \exp\left(\frac{-t}{\tau_n}\right)\right] \qquad h = 2, N$$

## Strand currents during the current plateau $(t > t_1)$

## Linear variation with *x*

## Deviation from linearity

$$i_1(x,t) = i_{op}(t) - i_{op}(t) \frac{N-1}{N} \frac{x}{L} - \frac{N-1}{N} 2\beta \sum_{n=1}^{\infty} \frac{\tau}{n^3 \pi} \sin\left(\frac{n\pi x}{L}\right) \exp\left(\frac{-t}{\tau_n}\right) \left[\exp\left(\frac{t_1 n^2}{\tau}\right) - 1\right]$$

$$i_h(x,t) = i_{op}(t)\frac{x}{NL} + \frac{1}{N}2\beta \sum_{n=1}^{\infty} \frac{\tau}{n^3 \pi} \sin\left(\frac{n\pi x}{L}\right) \exp\left(\frac{-t}{\tau_n}\right) \left[\exp\left(\frac{t_1 n^2}{\tau}\right) - 1\right] \qquad h = 2, N$$

Cable main time constant
Cable time constants

$$\tau = N (l - m) g \left(\frac{L}{\pi}\right)^{2}$$

$$\tau_{n} = \left(\frac{\tau}{n^{2}}\right)$$

### At times much longer than the time constant $(t \gg \tau)$

<u>Current ramp</u>: the non linear term becomes negligible with respect to the linear term

$$\lim_{t \to \infty} \sum_{n=1}^{\infty} \frac{\tau}{n^3 \pi} \sin \left( \frac{n \pi x}{L} \right) \left[ 1 - \exp \left( \frac{-t n^2}{\tau} \right) \right] = \frac{\pi^2}{12} \tau \frac{x}{L} \left( 1 - \frac{x}{L} \right) \left( 2 - \frac{x}{L} \right)$$

 $i_{op}(t)\frac{N-1}{N}\frac{x}{L}$  the linear term increases in time

<u>Current plateau</u>: the non linear term becomes negligible with respect to the linear term

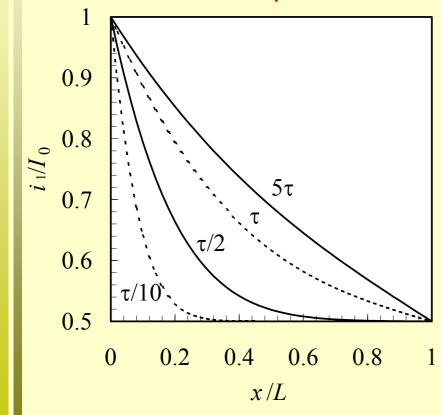
$$\lim_{t \to \infty} \sum_{n=1}^{\infty} \frac{\tau}{n^3 \pi} \sin \left( \frac{n \pi x}{L} \right) \exp \left( \frac{-t n^2}{\tau} \right) \left[ \exp \left( \frac{t_1 n^2}{\tau} \right) - 1 \right] = 0$$

$$i_{op}(t)\frac{N-1}{N}\frac{x}{L}$$
 the linear term is constant

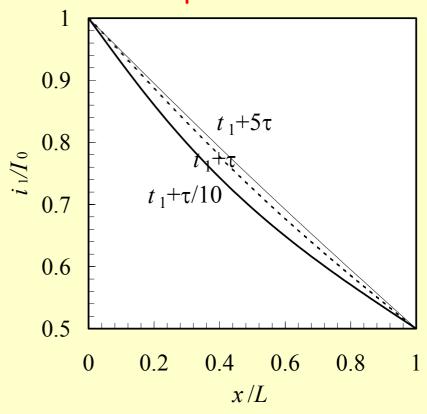
## Calculations: space dependance

2-strand cable: L = 2.3 m,  $I = 5.0 \cdot 10^{-6}$  H/m,  $m = 2.5 \cdot 10^{-6}$  H/m,  $g = 7.463 \cdot 10^{6}$  S/m,  $\tau = 2$  s,  $\beta = 60$  A/s,  $t_1 = 5$   $\tau$ 

#### Current ramp: strand 1



#### Current plateau: strand 1



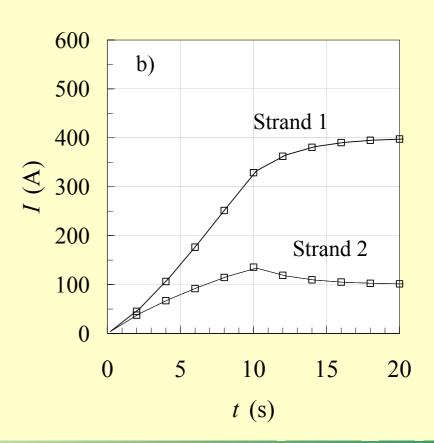
### Calculations: time dependance

2 and 3-strand cable: analytical solution (symbols) vs numerical simulation (lines)

#### 2-strand cable

#### 600 a) 500 Strand 1 400 € 300 200 Strand 2 100 0 0 5 10 15 20 *t* (s)

#### 3-strand cable

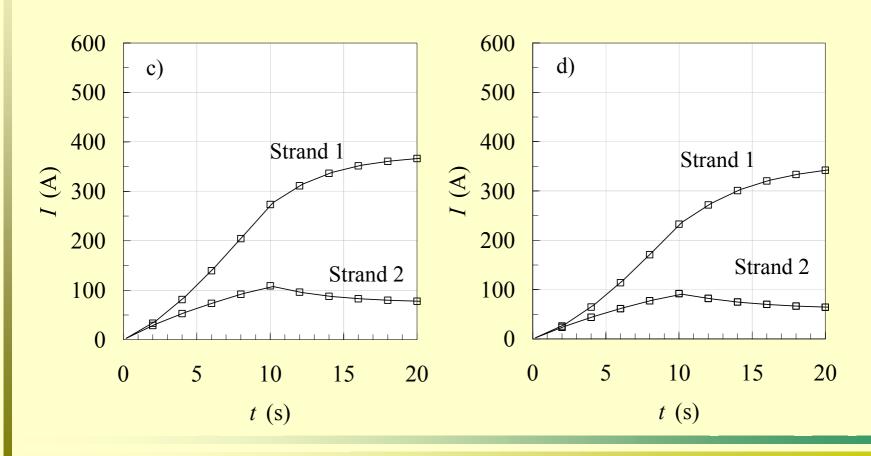


## Calculations: time dependance

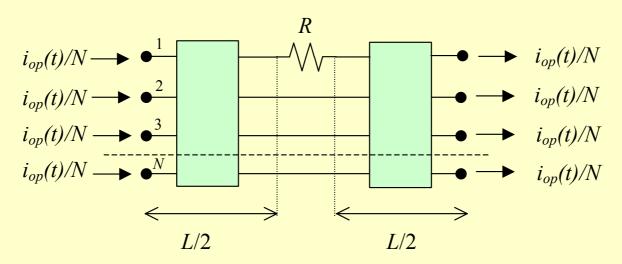
4 and 5-strand cable: analytical solution (symbols) vs numerical simulation (lines)



#### 5-strand cable



## 2) Quench in one strand



- Uniform current distribution at the boundaries
- External voltage is neglected
- ➤ A lumped resistance in the middle of the cable is representative of the first phases of quench in strand #1
- Extension of the solution already available for 2-strand cables (Turck, Mitchell)

## Strand currents during a current ramp with ramp rate $\beta$ ( $t \le t_1$ ) in $0 \le x \le L/2$

$$i_{1}(x,t) = \frac{i_{op}(t)}{N} + \frac{i_{op}(t)}{N} \frac{2x}{L} \frac{\omega}{1-\omega} + \frac{\beta}{N} A(x,t,\omega)$$

$$i_{h}(x,t) = \frac{i_{op}(t)}{N} - \frac{i_{op}(t)}{N} \frac{1}{N-1} \frac{2x}{L} \frac{\omega}{1-\omega} - \frac{\beta}{N(N-1)} A(x,t,\omega) \qquad h = 2, N$$

Strand currents during the current plateau  $(t > t_1)$  in  $0 \le x \le L/2$ 

$$i_{1}(x,t) = \frac{i_{op}(t)}{N} + \frac{i_{op}(t)}{N} \frac{2x}{L} \frac{\omega}{1-\omega} + \frac{\beta}{N} \left[ A(x,t,\omega) - A(x,t-t_{1},\omega) \right]$$

$$i_{h}(x,t) = \frac{i_{op}(t)}{N} - \frac{i_{op}(t)}{N} \frac{1}{N-1} \frac{2x}{L} \frac{\omega}{1-\omega} - \frac{\beta}{N(N-1)} \left[ A(x,t,\omega) - A(x,t-t_{1},\omega) \right]$$

$$h = 2. N$$

## Linear term (current in the quenched strand)

$$\frac{i_{op}(t)}{N} + \frac{i_{op}(t)}{N} \frac{\omega}{1 - \omega} \frac{2x}{L} = \frac{\frac{i_{op}(t)}{N} \ln x = 0}{\frac{i_{op}(t)}{N} + \frac{i_{op}(t)}{N} \frac{\omega}{1 - \omega}} \quad \text{in } x = L/2$$

$$\omega = -R g L (N-1)/4$$

If  $R \to \infty$  or  $g \to \infty$  then  $\omega \to \infty$  and the current in the normal zone x=L/2 goes to zero

$$\frac{i_{\text{op}}(t)}{N} + \frac{i_{\text{op}}(t)}{N} \frac{\omega}{1 - \omega} = 0$$

## Non linear term (current in the quenched strand)

Space dependance

Time dependance

$$A(x,t,\omega) = 2\sum_{n=1}^{\infty} \frac{\cos(\xi_n(\omega))\sin(\xi_n(\omega)\cdot 2x/L)}{\cos(\xi_n(\omega))\sin(\xi_n(\omega)) - \xi_n(\omega)} \left(-\tau\right) \left(\frac{\pi/2}{\xi_n(\omega)}\right)^2 \left(\exp\left(-\frac{t}{\tau_n}\right) - 1\right)$$

Cable main time constant

Cable time constants

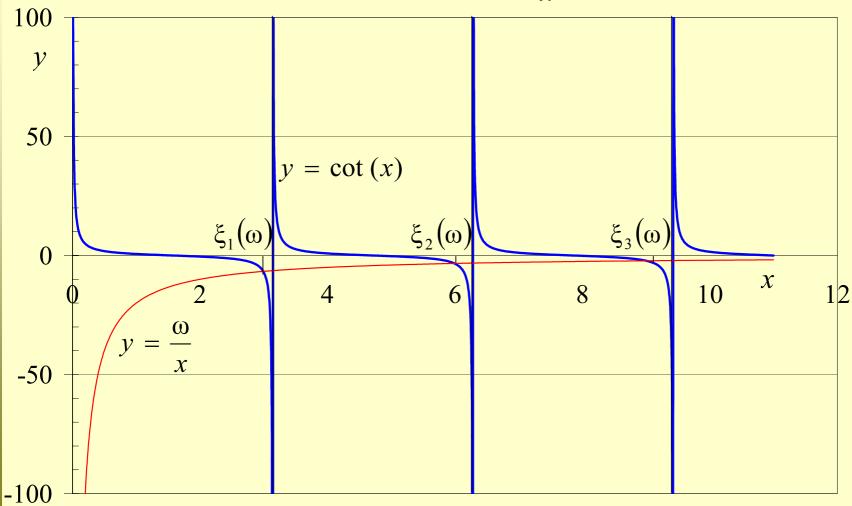
$$\tau = N (l - m) g \left(\frac{L}{\pi}\right)^{2}$$

$$\tau_{n} = \frac{\tau}{\left(\frac{\xi_{n}(\omega)}{\pi/2}\right)^{2}}$$

At times much longer than the time constant  $(t \gg \tau)$ 

The non linear term becomes negligible with respect to the linear term, both during the current ramp and the current plateau



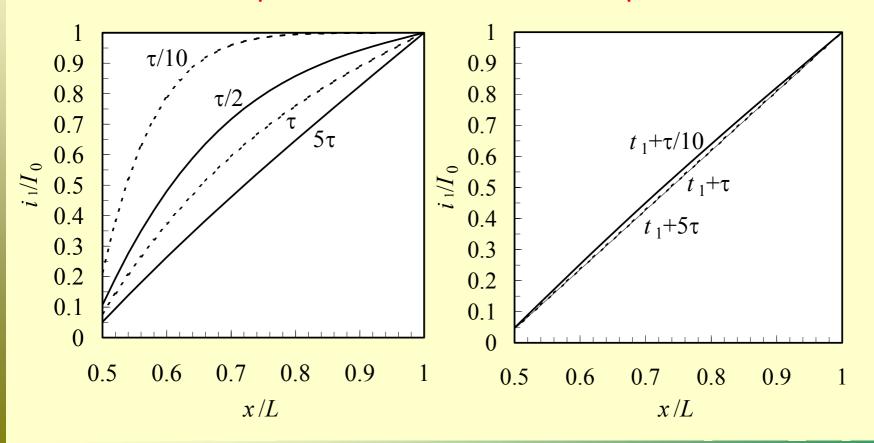


## Calculations: space dependance

2-strand cable: L = 2.3 m, I = 5.0 10<sup>-6</sup> H/m, m = 2.5 10<sup>-6</sup> H/m, g = 7.463 10<sup>6</sup> S/m,  $\tau$  = 2 s,  $\beta$  = 60 A/s,  $t_1$  = 5  $\tau$ 

#### Current ramp: strand 1

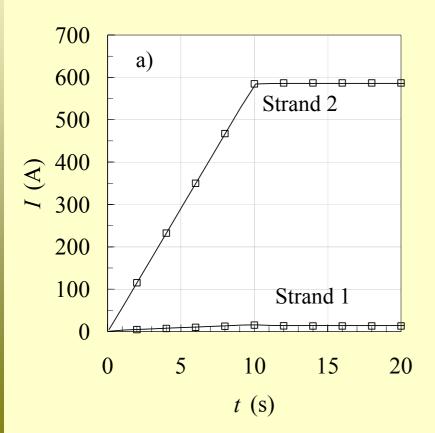
#### Current plateau: strand 1



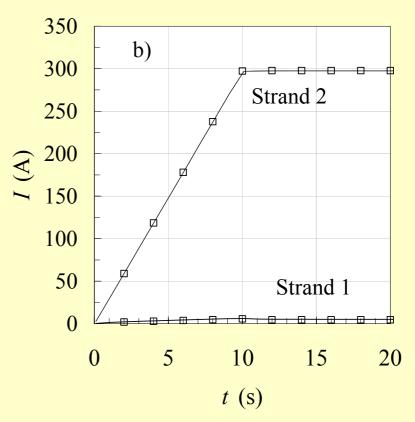
### Calculations: time dependance

2 and 3-strand cable: analytical solution (symbols) vs numerical simulation (lines)

#### 2-strand cable



#### 3-strand cable



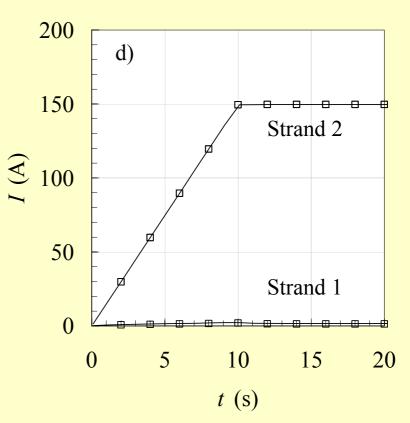
### Calculations: time dependance

4 and 5-strand cable: analytical solution (symbols) vs numerical simulation (lines)

#### 4-strand cable

#### 250 c) 200 Strand 2 150 100 50 Strand 1 0 5 15 0 10 20 *t* (s)

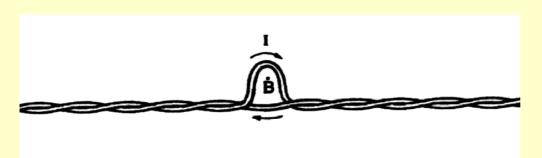
#### 5-strand cable



## 3) Driving voltage excitation

Extension of the solution already available for 2-strand

cables (Krempasky-Schmidt)



$$V_1^{ext} = \frac{dB}{dt} A$$

$$\begin{cases}
\mathbf{g} \ \mathbf{l} \frac{\partial \mathbf{i}}{\partial t}(x,t) + \frac{\partial^2 \mathbf{i}}{\partial x^2}(x,t) - \mathbf{g} \mathbf{v}^{ext}(x,t) = 0 \\
\mathbf{i} \ (x,t=0) = 0 \\
i_{op}(t) = 0 \\
v_1^{ext} = \frac{V_1^{ext}}{\delta} \text{ for } x \in \left[\frac{L-\delta}{2}, \frac{L+\delta}{2}\right], v_1^{ext} = 0 \text{ for } x \in \left[0, \frac{L-\delta}{2}\right] \text{ and } x \in \left[\frac{L+\delta}{2}, L\right] \\
v_h^{ext} = 0 \text{ for } x \in [0, L] \text{ with } h = 2, N
\end{cases}$$

#### Strand currents during the field ramp

Time dependance 
$$i_h(x,t) = \frac{4}{\pi\alpha} I_h \sum_{n=1}^{\infty} \left[ \frac{1}{n^2} \left( 1 - e^{-\frac{t}{\tau_n}} \right) \sin\left(\frac{n\alpha x}{w}\right) \sin\left(n\alpha\right) \right]$$

#### Strand currents during the constant field phase

$$i_h(x,t) = \frac{4}{\pi\alpha} I_h \sum_{\substack{n=1\\n \text{ odd}}}^{\infty} \left[ \frac{1}{n^2} \left( 1 - e^{-\frac{t_1}{\tau_n}} \right) e^{-\frac{(t-t_1)}{\tau_n}} \sin\left(\frac{n \alpha x}{w}\right) \sin\left(n \alpha\right) \right]$$

$$\alpha = \pi \frac{L - \delta}{2L}$$
 Cable main time constant  $\tau = N \left( l - m \right) g \left( \frac{L}{\pi} \right)^2$ 

**Exponential decay** 

$$w = \frac{L - \delta}{2}$$
 Cable time constants  $\tau_n = \frac{\tau}{n^2}$ 

#### Maximum currents

$$I_1 = (N-1)\frac{wgV^{ext}}{2}$$

$$I_h = -\frac{wgV^{ext}}{2}$$
 with  $h = 2, N$ 

## Redistribution length

$$\vartheta = \frac{t}{\tau}$$

Adimensional time

$$\eta_h = \frac{i_h}{I_h}$$

Adimensional current

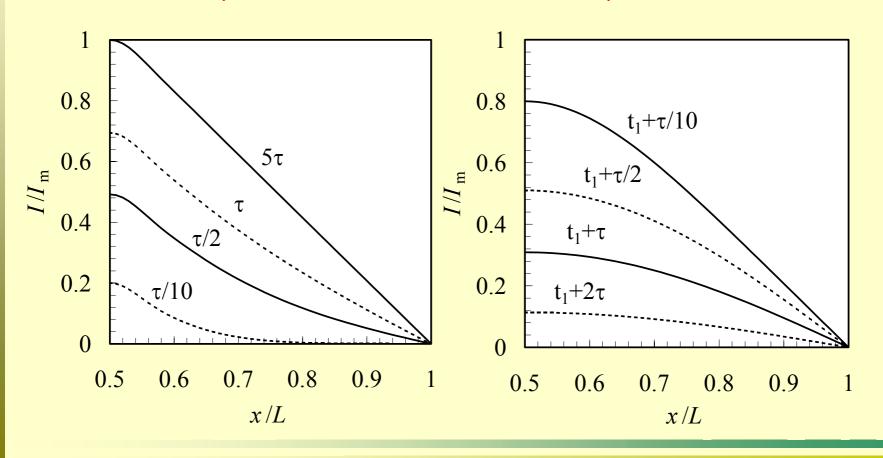
$$\eta_h(x,t) = \frac{4}{\pi\alpha} \sum_{n=1}^{\infty} \left[ \frac{1}{n^2} \left( 1 - e^{-\vartheta n^2} \right) \sin\left(\frac{n\alpha x}{w}\right) \sin(n\alpha) \right]$$

## Calculations: space dependance

2-strand cable: L = 2.3 m,  $I = 5.0 \cdot 10^{-6}$  H/m,  $m = 2.5 \cdot 10^{-6}$  H/m,  $g = 7.463 \cdot 10^{6}$  S/m,  $\tau = 2$  s,  $t_1 = 5 \cdot \tau$ 

#### Field ramp: strand 1

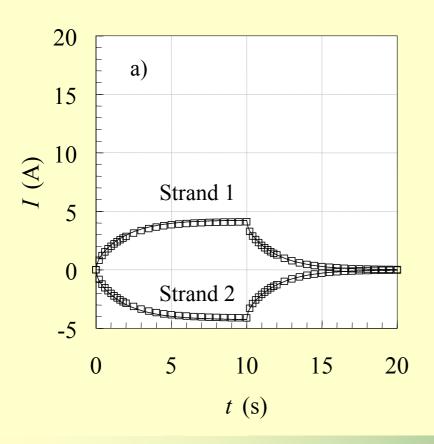
#### Field plateau: strand 1



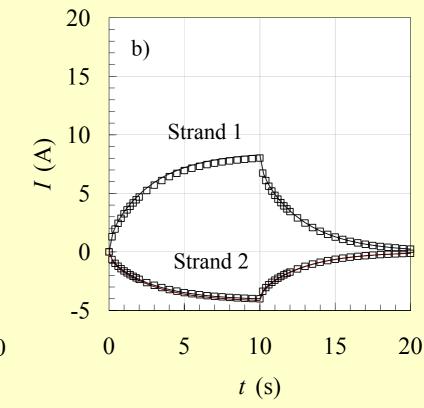
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2 and 3-strand cable: analytical solution (symbols) vs numerical simulation (lines)





#### 3-strand cable



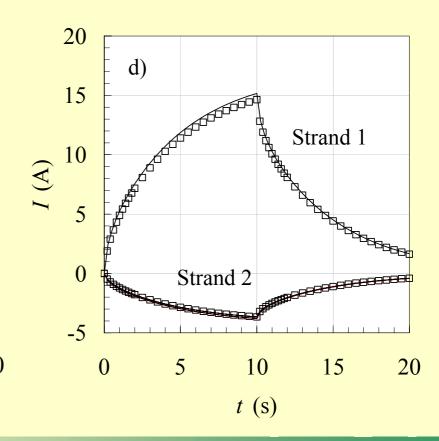
## Calculations: time dependance

4 and 5-strand cable: analytical solution (symbols) vs numerical simulation (lines)



#### 20 c) 15 Strand 1 10 I(A)0 Strand 2 -5 5 10 15 20 *t* (s)

#### 5-strand cable



### **Conclusions**

**(1)** 

Set of analytical formulae for current distribution in superconducting cables for:

- Preliminary benchmarking of numerical codes based on distributed parameters models (CDCABLE, NUCCIC, THEA, ...)
- Estimation of strand currents mean behaviour in the presence of:
  - non uniform boundaries
  - •localised quenches (Turck, Mitchell for 2-strand cables)
  - localised driving voltages (Krempasky-Schmidt for 2-strand cables)

### **Conclusions**

(2)

- ➤ Quick Estimation of:
  - Time constants
  - Redistribution lengths
  - Maximum currents due to driving voltages
- Non-linear current-voltage characteristics of strands is not taken into account
- > Substitution of numerical codes is not possible