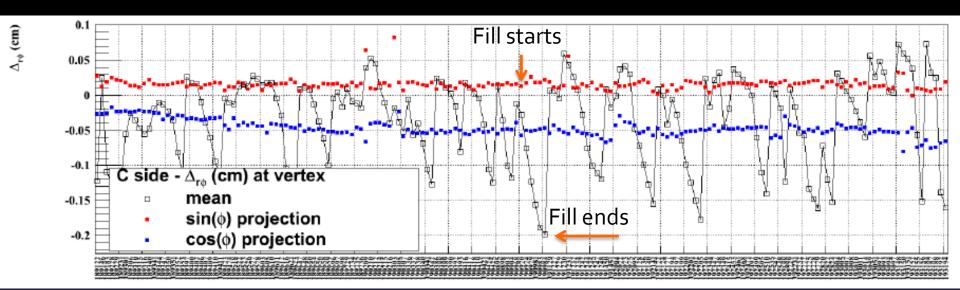
Calibration over more than one run

Marian Ivanov, Kai Schweda

Use case: spatial distortions at high IR



Charging up of inner field cage observed on C - side

Depends on interaction rate x primary ionisation (Ar \approx 2.0 x Ne)

Spatial distortions, i.e. $\Delta r \phi$ at vertex could reach **5mm** in run 2

→ Time dependent ! Clear structures within fill

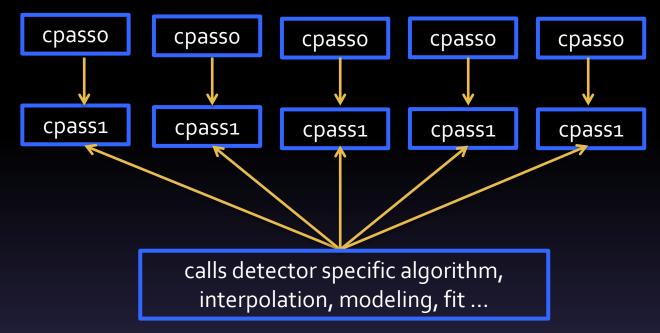
3/19/2015

→ Need time-dependent space point calibration, per fill

 \rightarrow Use **external detectors**, i.e. ITS, TRD, TOF, for calibration

2

Calibration per LHC fill



- Cpass1 starts right after cpasso finished for a run
- (A) make cpass1 output for all runs of an LHC fill available
- 1 run might last as long as 1 LHC fill (up to 24h)
- run1: 1 calibration object created per time interval, e.g. drift velocity each 15 min
- (B) Issue: memory consumption
 - \rightarrow convert cluster-to-track residual histograms to distortion maps (each 30 min)
- Model + fit to calibration output over 1 LHC fill → continuous space point correction

Proposal

- Goal: automated scheme for calibration
- Lego train: manual intervention
- Minimize usage of resources:
 (A) filling of cluster-residuals histos or trees in cpass1,
 O(10⁴) jobs

(B) creation of distortion maps O(10¹) jobs

Run on grid (alien jobs)

alternatively / interim solution as cron jobs at GSI

Action items

- In advance to data taking: ITS, TRD, TOF alignment with sufficient precision (interpolation error inside TPC < 200 µm, intrinsic tracklet resolution)
- ITS-TRD-TOF interpolation method, available as macro, needs to be ported to TPCcalibration class
- Define minimum granularity of residual histos, decide whether to use histos or trees depending on memory consumption vs CPU time

Action items, cont'ed

- Fit distortion maps with physics model to confirm understanding
- distortion maps + linear interpolation in time for ultimate precision
- Statistics required for 0.1mm target resolution: 180 bins in φ x 10 bins in θ x (3.5mm/0.2mm)²
 → 5 x 10⁵ tracks, 1 x 10⁴ pp collisions @50 Hz
 → each 2000 s ≈ 30 min (for ITS-TOF)
 → TRD needs 4x less statistics, 8 min