

# Using R in ROOT with the ROOT-R package

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# What is R ?



- R is an open source language and environment for statistical computing and graphics.
  - open source implementation of S language developed by J. Chambers
  - R popularity and usage increased largely in recent years
- R provides a large variety of statistical tools
  - linear and nonlinear modelling, classical statistical tests, time-series analysis, classification, clustering, ...
- Environment is highly extensible with a large number of existing packages



# Introduction

- ROOT-R package
  - a new ROOT package to interface with R environment
    - to use R, its functions and tools from the ROOT prompt or any C++ application
    - give access to ROOT users to the R capabilities and its rich functionality
- Developed by O. A. Zapata (GSOC student 2014)



# C++ Interface to R

- ROOT-R make uses of the R packages Rcpp and RInside
  - packages providing integration of R with C++
    - mapping back and forth of R object to C++ classes
    - calling R commands from C++ code
- ROOT-R provides an extra layer to Rcpp and RInside
  - new classes to facilitate conversion between ROOT/C++ objects and R objects
  - easy to call R functions from ROOT prompt and C++ code



# Goal of ROOT-R

- Give easy access to ROOT users to R tools
  - more focused on using the statistical tools rather than graphics tools from R
- To further integrate R in ROOT plug-ins based on R can be developed
  - ROOT::Math::Minimizer plug-in using R optimisation packages (RMinimizer)
  - Plan to develop TMVA methods based on R classification packages (GSOC project for 2015)



# How does it work ?

- TRInterface: main class interfacing to R
  - static instance that can be made available at the ROOT prompt
  - can be used to execute R commands

```
root[0] auto r = ROOT::R::TRInterface::Instance();  
root[1] r.Parse("print(version$version.string)");  
[1] "R version 3.1.0 (2014-04-10)"
```



# R Object -> ROOT

- TRObjectProxy class for converting from R objects to ROOT/C++ objects

```
root[] ROOT::R::TRObjectProxy rop = r.ParseEval("c(1,2,3,4)");  
root[] std::vector<double> v = rop.As<std::vector<double>>();
```

- Better to use **operator=** for convenience

```
root[] std::vector<double> v = r.ParseEval("c(1,2,3,4)");  
root[] TMatrixD m = r.ParseEval("matrix(c(1,2,3,4),2,2)");  
root[] std::array<double,10> a = r.ParseEval("seq(1:10)");
```

- Or TRInterface:**operator[]** using the name of the R object

```
root[] r.Parse("mat=matrix(c(1,2,3,4),2,2)");  
root[] TMatrixD m = r["mat"];
```



# Using Operator << and >>

- We can also use `operator<<` to pass an R command to the TRInterface

```
root[] r << "mat<-matrix(c(1,2,3,4),2,2)";
```

- And use `operator >>` to transform an R object into a ROOT/C++ object

```
root[] TMatrixD m;  
root[] r["mat"] >> m
```



# ROOT/C++ -> R

- ROOT/C++ objects can be passed to R using the `operator[]` of `TRInterface`




```
root[] std::vector<double> v = {1,2,3,4,5};  
root[] r["v"] = v;  
root[] r.Parse("print(v)");  
[1] 1 2 3 4 5
```

- or in combination with `operator<<`

```
root[] TMatrixD A(2,2,v.data() );  
root[] r["A"] << A;  
root[] r << "print(A)";  
      [,1] [,2]  
[1,]    1    2  
[2,]    3    4
```



# Supported Object Conversions

- C++ fundamental types (int, float, double)
-  ● R scalar (vectors of size 1)
- `std::vector`, `std::array`, `std::list`, `TVectorD`
-  ● R vector types
- `TMatrixD`  R matrix
- Direct conversion from / to more complex R object (e.g. list or data frames) is not supported yet



# Passing Functions to R

- If you have free C functions

```
Double_t myfun(Double_t x) {  
    return 2*cos(x);  
}  
Double_t myfun2(const std::vector<Double_t> & x) {  
    return x[1]*cos(x[0]);  
}
```

- you can use the class TRFunction to pass it to R

```
r["dilog"] << ROOT::R::TRFunction(TM::DiLog);  
r["myfun"] << ROOT::R::TRFunction(myfun);  
r["myfun2"] << ROOT::R::TRFunction(myfun2);  
r << "print(dilog(0))";  
r << "print(myfun(0))";  
r << "print(myfun2(c(0,4)))";
```

- Can be used for passing functions to numerical algorithms from R (Numerical integration, minimisation, etc...)



# Example: Integration in R

- Integrate a function in R.

Note R uses vectors as inputs to functions

```
std::vector<Double_t> BreitWignerVectorized(const std::vector<Double_t> & xx) {
    std::vector<Double_t> result(xx.size());
    for(Int_t i=0;i<xx.size();i++)
    {
        result[i]=TMath::BreitWigner(xx[i]);
    }
    return result;
}

void Integrate() {

    auto r = ROOT::R::TRInterface::Instance();
    r["BreitWigner"]=ROOT::R::TRFunction(BreitWignerVectorized);
    Double_t value=r.ParseEval("integrate(BreitWigner, lower = -2, upper = 2)$value");

    std::cout<<"Integral of the BreitWigner in [-2, 2] =" << value << std::endl;
}
```



# Passing C++ Classes to R

- It is also possible to pass a C++ class from ROOT to R
  - Requires defining a R module advertising the class methods in the R environment
  - ROOT-R facilitate this by providing some helper cpp macros
- More information available at ROOT-R online documentation

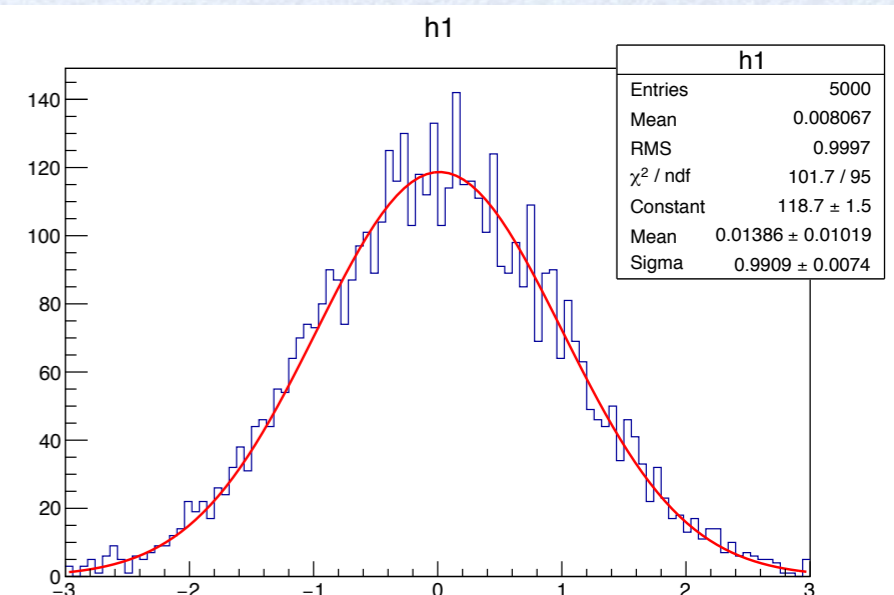


# RMinimizer

- ROOT plugin for Minimisation implemented using R
  - give access to R optimisation tools when fitting or multi-dimensional function minimisation
    - based on R optim/optimx packages
  - Class developed by Kirby Hermann (GSOC student 2014)

```
ROOT::Math::MinimizerOptions::SetDefaultMinimizer("RMinimizer", "L-BFGS-B");  
hist->Fit("gaus");
```

```
root [4] h1.Fit("gaus")  
Value at minimum =101.673  
*****  
Minimizer is RMinimizer / L-BFGS-B  
Chi2           =          101.673  
NDF            =           95  
NCalls         =          265  
Constant       =          118.694 +/- 1.47659  
Mean           =           0.0138555 +/- 0.0101907  
Sigma          =           0.990906 +/- 0.00741443
```





# Future Developments

- Add wrapper classes (plugin) in ROOT for R classification tools
- integrate some of R classification tools in TMVA
  - GSOC project for 2015
- Extend ROOTR to map also R data frames



# Conclusions

- ROOTR provides easy access to R tools in ROOT and C++
- Easy to use directly R from ROOT prompt
  - extend the functionality of ROOT
  - can be used also to verify and cross-check some of existing ROOT math and stat tools
  - new ROOT plugins or wrapper classes implemented using R can be easily created
- Package is ready to be released in next ROOT production version (6.0.4)



# Documentation

- ROOT-R User Guide

- <http://gfif.udea.edu.co/web/tiki-print.php?page=ROOTR%20Cling%20Users%20Guide>

- ROOT-R Twiki page

- <http://gfif.udea.edu.co/web/tiki-index.php?page=ROOTR+Cling>