



**Mario Deile, Patrick Fassnacht**

on behalf of the

**ATLAS-ALFA and TOTEM Roman Pot Teams**

with special thanks to

Collimation WG, LHC interlock team, Operators, PH-DT, EN-ICE

**MPP Meeting**

**24 April 2015**

summarising

EDMS 1503866 (ALFA)

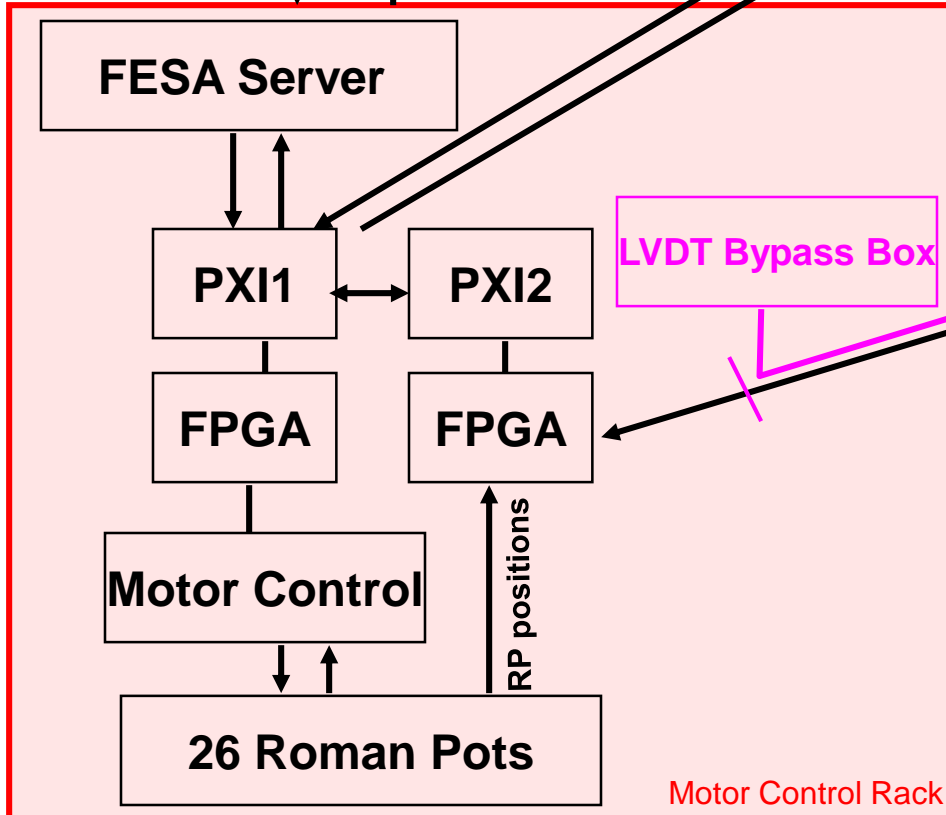
EDMS 1501228 (TOTEM)

# Movement System Architecture (strongly simplified)



**Collimator Control Application  
in CCC  
(adapted to RPs)**

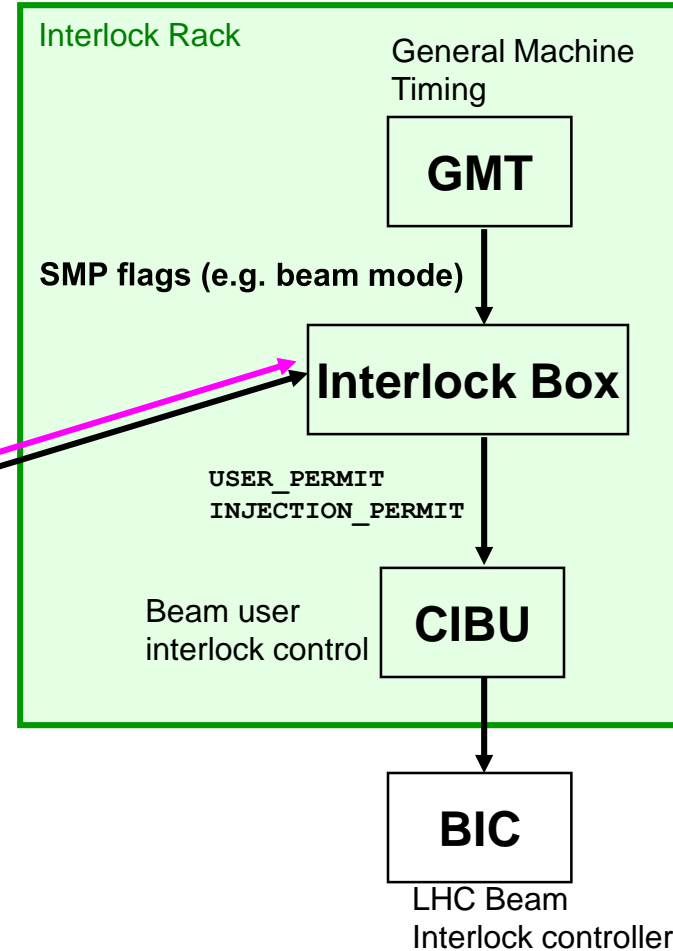
**DCS**



request position,  
set limits

read position,  
give feedback

RP Extraction  
Info





- **User Permits** (1 per beam):

User Permit is removed if:

(a pot is outside garage in the wrong beam mode) or (a pot is not within position limits)  
→ beam dump and retraction of all RPs with the springs

- **Injection Permits** (1 per beam):

Injection Permit is removed if a pot is outside garage (defined by electrical link from HOME switch)

... apart from an Override key and an LVDT bypass key (consult the full logic)

Logic implemented on a programmable circuit (“Interlock Box”)

**New in 2015:**

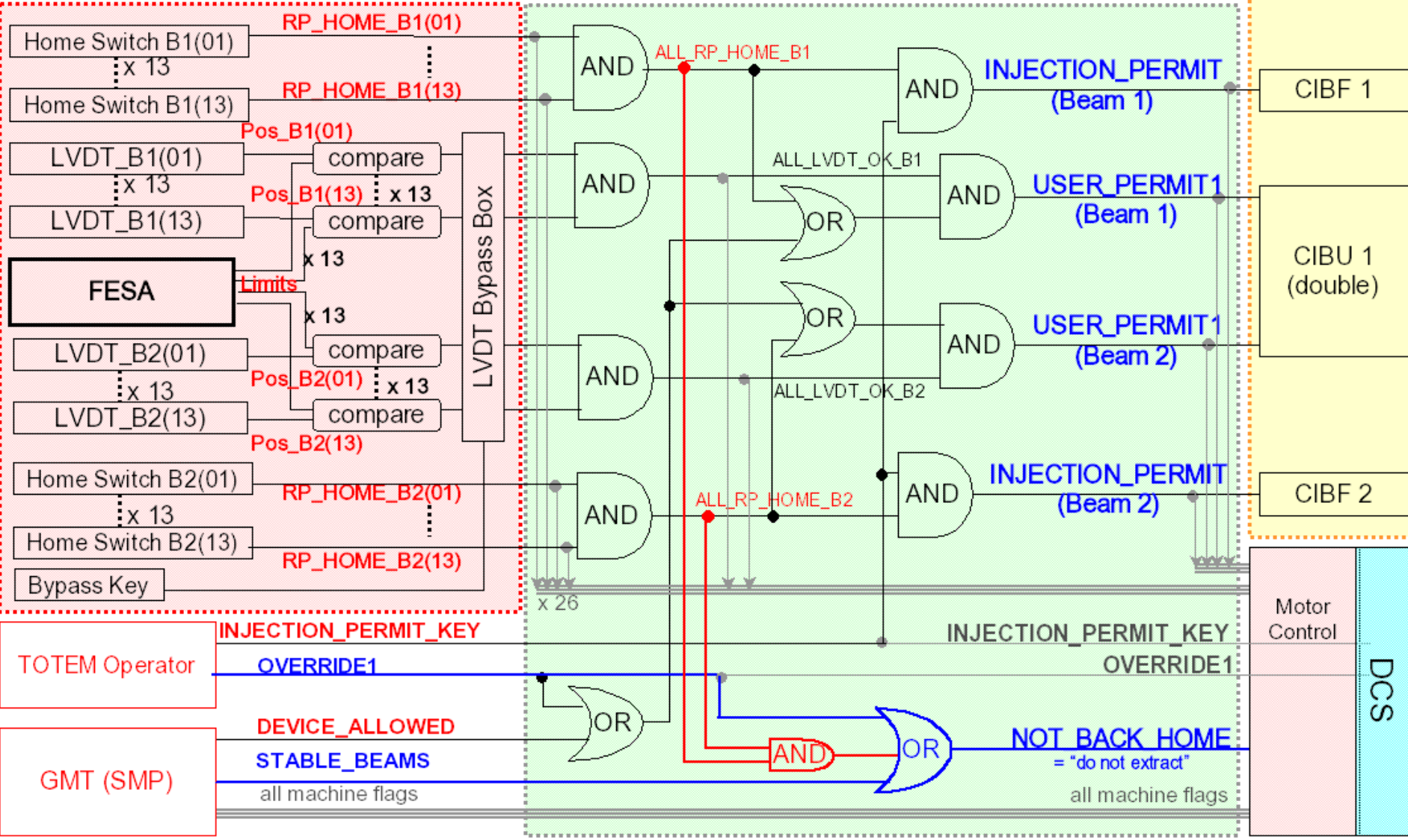
- Separation of active movement control and position interlock functionalities: 2 PXI computers
- TOTEM: addition of 2 single horizontal pots, now total of 26 pots  
→ interlock box circuit board completely redone (allows for up to 32 pots!)
- But: logic unchanged !

# Interlock Logic 2015

IN MOTOR CONTROL RACK

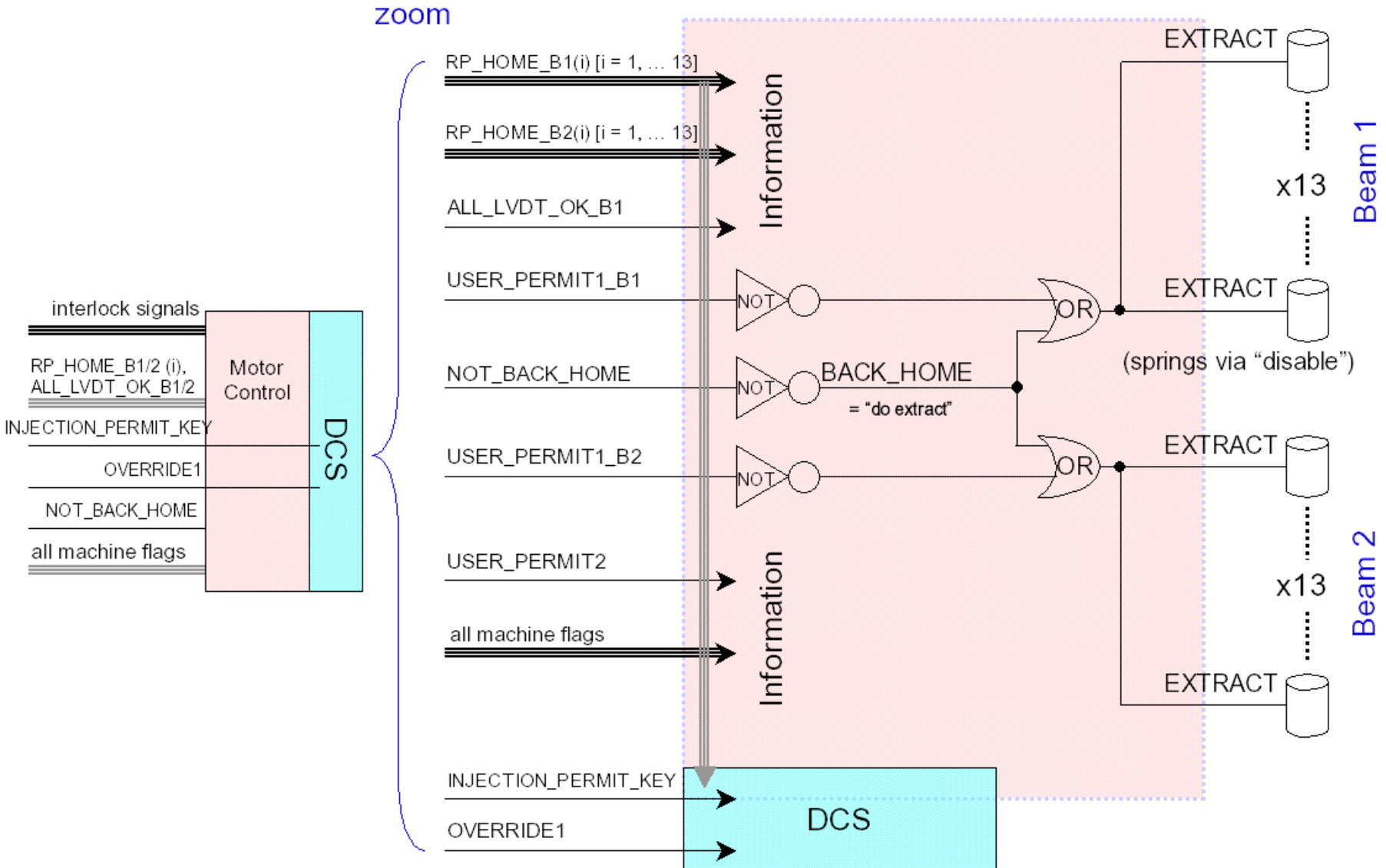
TOTEM INTERLOCK BOX

CMS S1E08



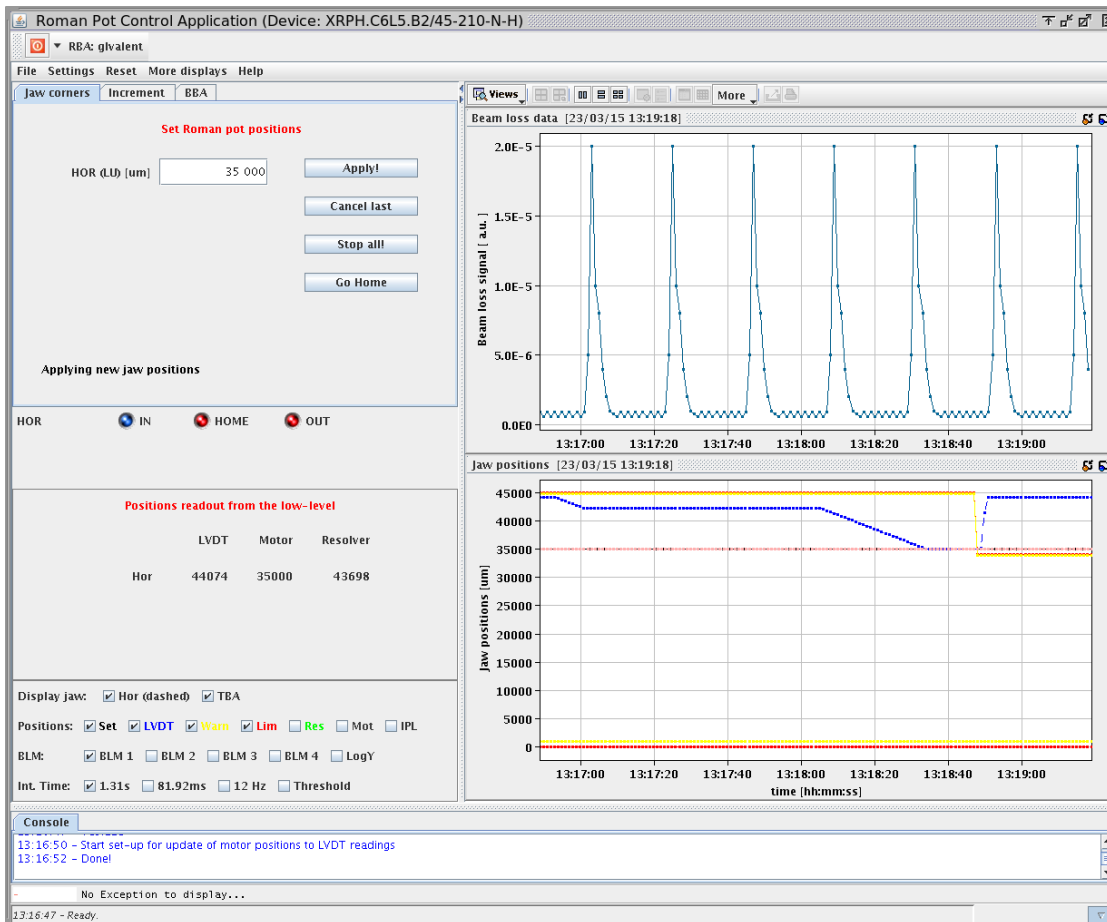
# Interlock Logic 2015

## (Zoom on the motor control)





- developed and maintained by G. Valentino (BE-ABP)
- strongly improved during LS1:
  - \* all limits displayed (now also new inner limits)
  - \* nomenclature of switches corrected
  - \* preview line before applying a movement command





## ALFA Interlock validation test

### 4 test sequences:

#### 1. Injection Permits

- Rest of ATLAS was at “Ready for injection” (including injection key)
- Then ALFA breaks the injection permit by moving in a Roman Pot.
- Done for all 8 pots

#### 2. Beam mode test

- Test of ALFA reaction vs Beam Modes and “moveable devices allowed”
- About 1 hour needed for each beam.
- All worked as expected.
- Done for one pot per beam.

#### 3. Systematic check of limits (old/new inner limits)

- A few errors found and corrected.
- Final validation made on all Roman Pots with final firmware.
- Done separately for each beam, all pots.

#### 4. LVDT bypass key **see EDMS 1203969**

- Test of key reactions in case of hardware failure (to allow LHC operation).
- All worked as expected

# Beam-Mode Dependent Test Sequence



Inputs	Combinations to be tested (labelled by the small blue numbers)							
	1	2	3	4	5	6	7	8
ALL_LVDT_OK_Bi	1	1	1	1	1	1	1	1
ALL_RP_HOME_Bi	1	1	1	1	1	1	1	1
DEVICE_ALLOWED	1	1	1	1	0	0	0	0
STABLE_BEAMS	1	1	0	0	1	1	0	0
OVERRIDE1	1	0	1	0	1	0	1	0
USER_PERMIT1(Bi)	1	1	1	1	N/A	N/A	1	1
EXTRACT	0	0	0	0	N/A	N/A	0	0

Inputs	7	8	9	10	11			
	ALL_LVDT_OK_Bi	1	1	1	1	1	1	1
ALL_RP_HOME_Bi	0	0	0	0	0	0	0	0
DEVICE_ALLOWED	1	1	1	1	0	0	0	0
STABLE_BEAM	1	1	0	0	1	1	0	0
OVERRIDE1	1	0	1	0	1	0	1	0
USER_PERMIT1(Bi)	1	1	1	1	N/A	N/A	1	0
EXTRACT	0	0	0	1	N/A	N/A	0	1

Inputs	13	14	15	16	17			
	ALL_LVDT_OK_Bi	0	0	0	0	0	0	0
ALL_RP_HOME_Bi	1	1	1	1	1	1	1	1
DEVICE_ALLOWED	1	1	1	1	0	0	0	0
STABLE_BEAM	1	1	0	0	1	1	0	0
OVERRIDE1	1	0	1	0	1	0	1	0
USER_PERMIT1(Bi)	0	0	0	0	N/A	N/A	0	0
EXTRACT	1	1	1	1	N/A	N/A	1	1

Inputs	19	20	21	22	23			
	ALL_LVDT_OK_Bi	0	0	0	0	0	0	0
ALL_RP_HOME_Bi	0	0	0	0	0	0	0	0
DEVICE_ALLOWED	1	1	1	1	0	0	0	0
STABLE_BEAM	1	1	0	0	1	1	0	0
OVERRIDE1	1	0	1	0	1	0	1	0
USER_PERMIT1(Bi)	0	0	0	0	N/A	N/A	0	0
EXTRACT	1	1	1	1	N/A	N/A	1	1

5 input signals → 2<sup>5</sup> = 32 combinations

Test sequence = optimised path reaching each of the conditions (input combinations; blue numbers) at least once.

Exceptions: configurations with orange result fields = unreachable

Impossible modes  
(STABLE\_BEAMS without DEVICE\_ALLOWED)

						19.03.	
2	STABLE_BEAMS	0	all pots at home motor reset	open limits: inner warning = 34 mm, inner dump = 33 mm	USER_PERMIT = 1	17:06	17:43
2 to 8			move pot to 35 mm		USER_PERMIT = 1	17:08	17:45
8 to 10	to UNSTABLE_BEAMS				USER_PERMIT = 1	17:10	17:45
10 to 4			automatic extraction		USER_PERMIT = 1	17:11	17:47
4 to 2	to STABLE_BEAMS				USER_PERMIT = 1	17:11	17:48
			motor reset		USER_PERMIT = 1	17:14	17:50
2 to 8			move pot to 35 mm		USER_PERMIT = 1	17:15	17:51
8 to 20				illegal limits: inner warning = 37 mm, inner dump = 36 mm	USER_PERMIT = 0	17:17	17:52



## ALFA: Beam mode test

### An example.

From Elog

14:27  
ALFA: Beam mode dependent interlock test for beam 1.  
Using B7R1 Upper.  
State Transition 21 to 3.  
Open limits. Warning at 29 mm, dump at 28 mm  
Update motor position

One test among a list of 38 !!

1) Beam mode "unstable" & Pot at 30mm  
=> User\_Permit = 1

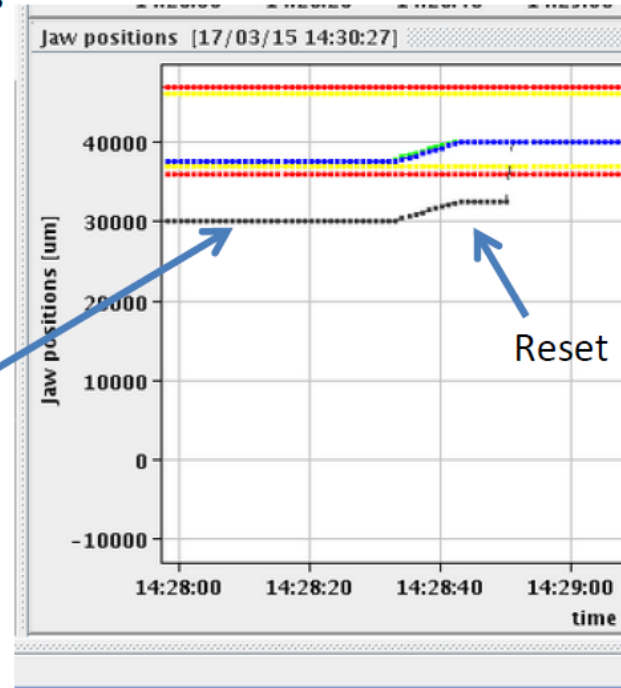
2) Change limits

LEFT-UP WARN IN	<input type="text" value="37.0000"/>	<input type="text" value="29"/>
LEFT-UP DUMP IN	<input type="text" value="36.0000"/>	<input type="text" value="28"/>

Violation => User\_Permit = 0  
Extract and User\_Permit = 1

(from T to F and back) →

3) Open limits



CIB.US15.R1.B1 frame

Permit	Timestamp	Visibility	Event Type	Description
✔✔	17-03-15 14:25:37.315211	EXPERT	DISABLED_PERMIT	2 B F-T
✔✔	17-03-15 14:25:37.315211	EXPERT	DISABLED_PERMIT	2 A F-T
✔✔	17-03-15 14:25:37.306797	EXPERT	DISABLED_PERMIT	2 A T-F
✔✔	17-03-15 14:25:37.306797	EXPERT	DISABLED_PERMIT	2 B T-F
✔✔	17-03-15 14:25:37.295163	EXPERT	DISABLED_PERMIT	2 B F-T
✔✔	17-03-15 14:25:37.295163	EXPERT	DISABLED_PERMIT	2 A F-T
✔✔	17-03-15 14:25:35.786806	EXPERT	DISABLED_PERMIT	2 A T-F
✔✔	17-03-15 14:25:35.786805	EXPERT	DISABLED_PERMIT	2 B T-F

## ALFA: Systematic check of limits (old/new inner limits)



Figure 4. *TOP*: Collimator application used to move Roman Pot B7L1 Upper.  
*BOTTOM*: Corresponding loss of INJECTION\_PERMIT seen in the BIS history buffer.

# ALFA - summary

- Full set of tests done in two days (16<sup>th</sup> and 17<sup>th</sup> March). Total time order of 5-6 hours, when all fine.
- All tests successful but:
  - *Since we had a very small change on DCS side (Enabling/Disabling & fast extraction) which is not yet tested*
  - *PXI crashed*

EDMS note is done at 95% (see above).

<https://edms.cern.ch/edmsui/#!/master/navigator/document?D:1958749382:1958749382:subDocs>

EDMS note will go for circulation right after

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CH-1211 Geneva 23  
Switzerland



ATLAS Project Document No.  
**ATL-UR-ER-0003**

CERN Div./Group or Supplier/Contractor Document No.  
**PH-ADO**

EDMS Document No.  
**1503866**

Date: 11 April 2015

## Functional Specification and Test Report

### THE ATLAS-ALFA INTERLOCK LOGIC IN 2015: SPECIFICATION AND TEST RESULTS



- Beam-mode dependent tests successful at the second attempt (problem with transmission of the DEVICE\_ALLOWED signal on the TOTEM side at the first attempt)
- Final validation done after all bug fixes in FPGA logics
- Still some PXI crashes; no impact on the interlock logic
- RP extraction via DCS not yet functional (communication problem between DCS and PXI), but emergency extraction via hardware button in TOTEM CR tested.
- EDMS test report waiting for comments

<https://edms.cern.ch/document/1501228>

- Spare interlock box:
  - being programmed
  - test to be performed in the lab with simulated input flags

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the  
TOTEM  
Experiment at LHC

TOTEM Project Document No.

**TOTEM**

CERN Div./Group or Supplier/Contractor Document No.

**PH-TOT**

EDMS Document No.

**1501228 v. 0.3**

Date: 09 April 2015

## Functional Specification and Test Report

### THE TOTEM INTERLOCKS IN 2015: TEST PROCEDURE AND RESULTS

#### Abstract

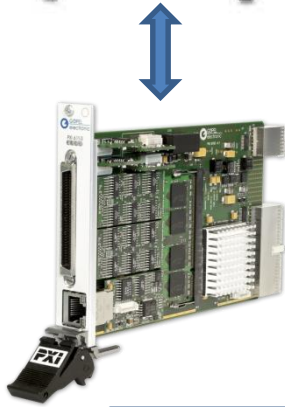
This document summarises the recommissioning tests of the TOTEM interlock system after the Long Shutdown 1, performed in March 2015.

The End

# BEFORE LS1



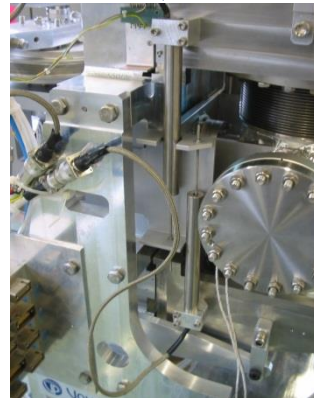
ALFA POSITION CONTROL SYSTEM PXI CRATE



Before LS1 one single FPGA card for controlling stepper motors, LVDT and Resolver position readout , microswitches and signals and interlocks position processing



Motor, Resolver and switches



LVDT's



Motor Drives



Interlocks and LHC signals Drives

# AFTER LS1



## ALFA POSITION CONTROL SYSTEM PXI CRATE. ACCORDING COLLIMATORS ARCHITECTURE



one FPGA card for controlling stepper motors, resolver position readout , microswitches, motor drives and LHC signals exchange



second FPGA card for safety position readout by means of the LVDT's and safety position interlock and LVDT\_FAULT signal generation



Motor, Resolver and switches



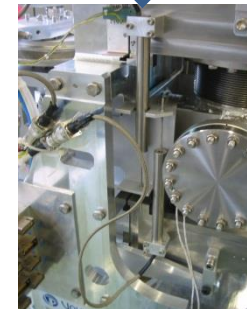
Motor Drives



LHC signal exchange



Signal Position interlock Interface crate



LVDT safety position readout



LVDT Position Fault Interlock To detector Interlock Box