



Performance Verification of the FlashCam Prototype Camera for the Cherenkov Telescope Array

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Challenges for cameras of imaging atmospheric Cherenkov telescopes



Cherenkov Telescope Array (CTA)





>100 telescopes over km² areas



cherenkov telescope array



32 countries >200 institutes >1300 members



Atacama desert, Chile Roque de los Muchachos, La Palma

FlashCam for the medium-sized telescopes: Architecture



Photon detector plane



12-pixel groups with 1.5" PMTs:

- *highly integrated:* HV supply, preamp, slow control
- clean interface to readout system: DC-coupled analogue, differential signal transmission (cat. 6 cables)
- *passively cooled:* <3 W per module
- aluminium-coated light concentrators increase collection efficiency



Modular readout system



192 FADCs Trig.

Motherboard



low-power FPGA with soft core
2 connectors for mezzanines
readout via Gbit Ethernet

2x 12-channel FADC



250 MS/s, 12 bit <1.5 W/channel

Trigger & clock distribution



semi-passive distribution of clock, sync, and trigger I/O



- 97 FPGAs buffer and analyse the digital traces *synchronously*
- transmission capacity of 12 trigger boards: 2.7 Tbit/s
- trigger on local, short light pulses; digital pre-processing & patch size configurable



dead-time free readout with >2 GByte/s (>20 kHz) via four 10 Gbit/s Ethernet fibres

Tests of prototype camera mechanics on prototype MST structure



Arrival of prototype camera mechanics at integration lab





FlashCam prototype setup in dark room



Back view & current status



Two types of PMTs installed in PDP:

- 358 Hamamatsu R11920-100 (8 dynodes) & 359 Hamamatsu R12992-100 (7 dynodes) tubes
- remaining slots filled with dummy heater modules

Readout system complete:

- readout electronics for up to 2304 channels installed
- cabling nearly complete (optimising for mass prod.)

Near final safety, power, and mechanics:

- power consumption of complete system as specified
- closed-circuit cooling with 5...35°C coolant works

Software development & interfacing in progress:

- DAQ over 1 km 4×10G fibres works
- remote control of all components works
- internal system analysis in progress
 - continuous *full* operation since Aug. 2016
 - >20 TByte of test data taken & analysed

From functionality tests to verification testing

- products to be deployed on a CTA site have to fulfil a list of environmental, RAMS, and performance requirements
- will focus on performance requirements:
 - min. readout rate & max. allowed dead time
 - time synchronisation between channels
 - charge & time resolution of pulse reconstruction
 - Iongterm (temperature) stability of signal path





Readout & time synchronisation between FADCs

- full-camera readout verified at >20 kHz statistical trigger rates (2.2 GByte/s)
 - → >5× required min. rate (>2.5× goal rate) with no dead time
- time synchronisation of all channels verified with equal HV settings
 - ➡ pulses of all 7/8-dynode tubes within ±1 ns before timing flat-fielding



fully synchronous readout system works as specified

Automatic gain flat-fielding before verifying charge & time resolution



- flat-field procedure based on prior knowledge of individual excess noise factors
- ~2% precision after few minutes (limited by max. repetition rate of laser)

standard procedure before all test measurements

Charge resolution verified at expected NSB rates and beyond



- from a large data set covering the whole operational range (up to >5,000 p.e./pulse & 3 GHz NSB)
- DC background in each pixel is estimated from baseline shift (~0.25 LSB/MHz)

Time resolution verified at expected NSB rates and beyond



Longterm stability — Temperature cycling over 30 h



- FlashCams are thermally insulated and cooled via liquid/air heat exchangers
 - interior temperatures are strongly coupled to coolant
- perform initial gain flat-fielding and baseline adjustment, let everything drift for 30 h and monitor changes

Longterm stability — Temperature drifts



- baseline drift: (-0.4 ± 0.1) LSB/K
- end-to-end gain and timing drifts seem to be dominated by PDP:
 - 7 dynodes: (-0.2 ± 0.1) %/K gain & (4 ± 2) ps/K transit time
 - 8 dynodes: (-0.4 ± 0.1) %/K gain & (6 ± 2) ps/K transit time
 - consistent with eff. HV change of about –0.5 V/K

Longterm stability — Temperature coefficients



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 - 8 dynodes: (-0.4 ± 0.1) %/K gain & (6 ± 2) ps/K transit time
 - consistent with eff. HV change of about –0.5 V/K
- all reconstruction parameters are well-behaved and exceptionally stable

Summary & outlook



FlashCam is a stable, high-performance Cherenkov camera well-suited for CTA:

- all major performance parameters have been verified and exceed CTA requirements
- longterm stability & reliability tests are ongoing; trigger verification next
- pre-production of two cameras has started; aim for two pre-series cameras late 2017