

Modelling Longitudinal Gradient Bends in a Storage Ring

Michael Ehrlichman

Paul Scherrer Institut

Noah Bittermann (Summer Student)

University of Minnesota

In collaboration with David Sagan, Cornell University



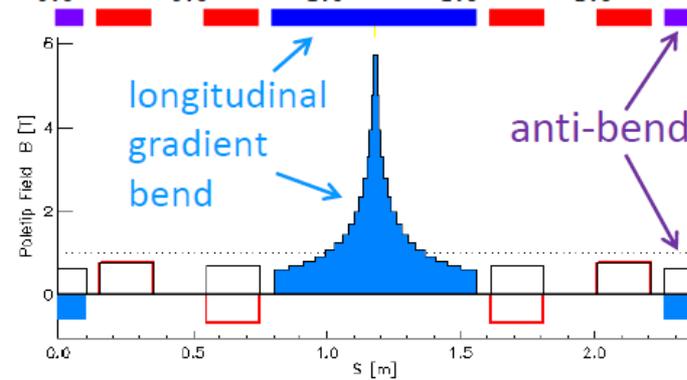
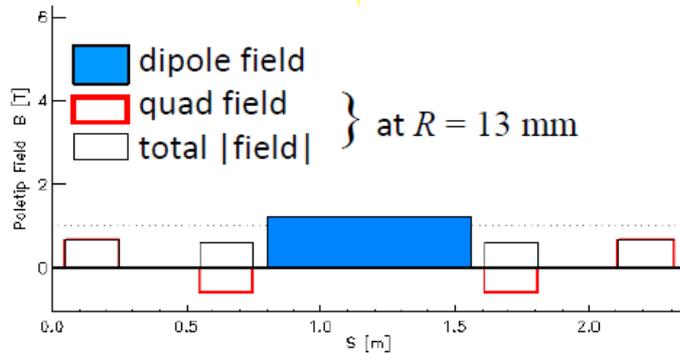
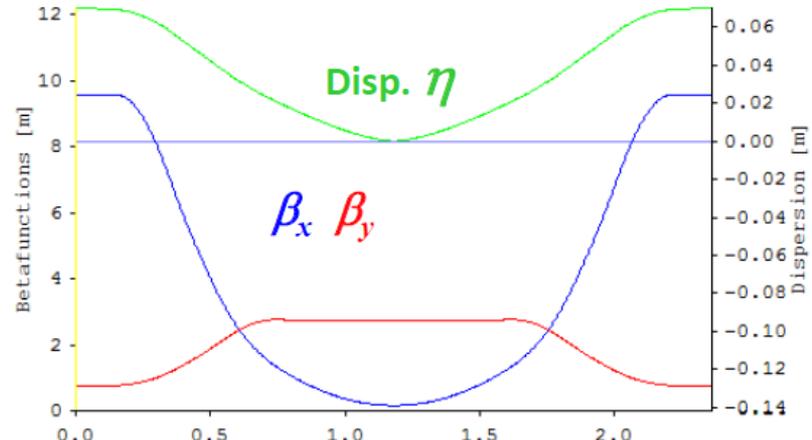
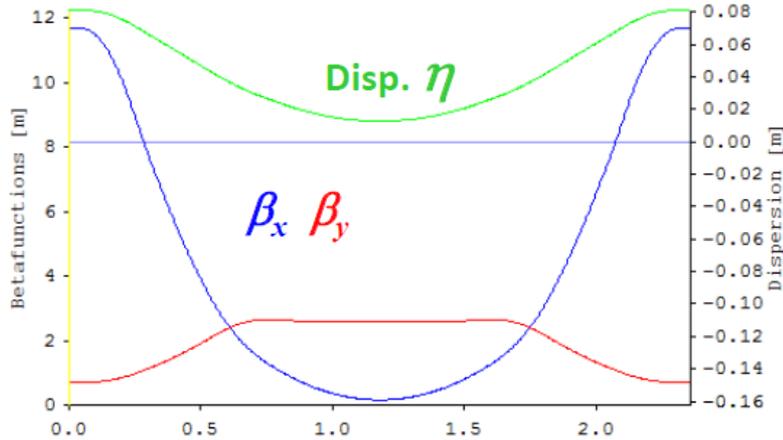
Overview

- PSI is planning an SLS upgrade, tentatively called SLS2.
- SLS2 will replace the storage ring with a design that achieves lower emittance by exploiting **small NEG-coated vacuum chambers** and **LGB+AB optics**.
 - Small chambers allow for tighter focusing.
 - Longitudinal Gradient Bends (LGB) minimize the I_5 integral.
 - Anti-Bends (AB) allow greater freedom to focus the dispersion function into the bends.
- LGBs are a non-conventional lattice element, whose modelling is not trivial.
- We consider two types of LGB: C-shaped Dipole & Canted Cosine-Theta Solenoid.
- And two modelling techniques: “Stack of sbends” & Fitted Maps

LGB Theory

conventional: $\varepsilon = 990 \text{ pm}$ ($F = 3.4$)

LGB/AB: $\varepsilon = 200 \text{ pm}$ ($F = 0.69$)



Emittance generated in a bend scales with:

$$I_{5a} = \oint ds g^3 \mathcal{H}_a$$

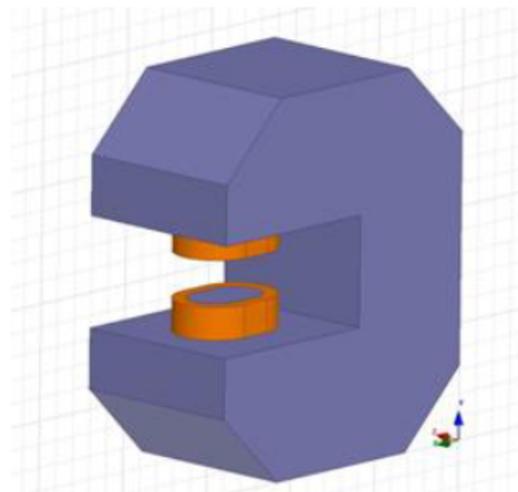
This bend field profile minimizes I_5 .



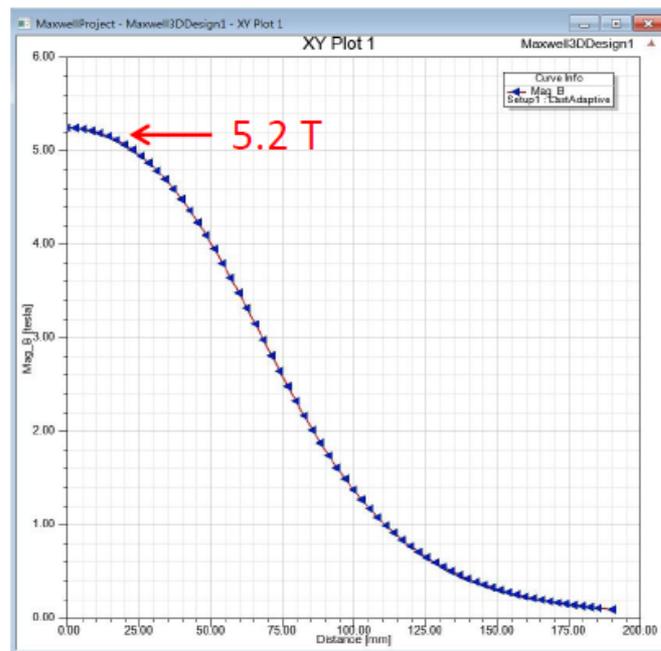
1. C-shaped dipole

ALS-style magnet

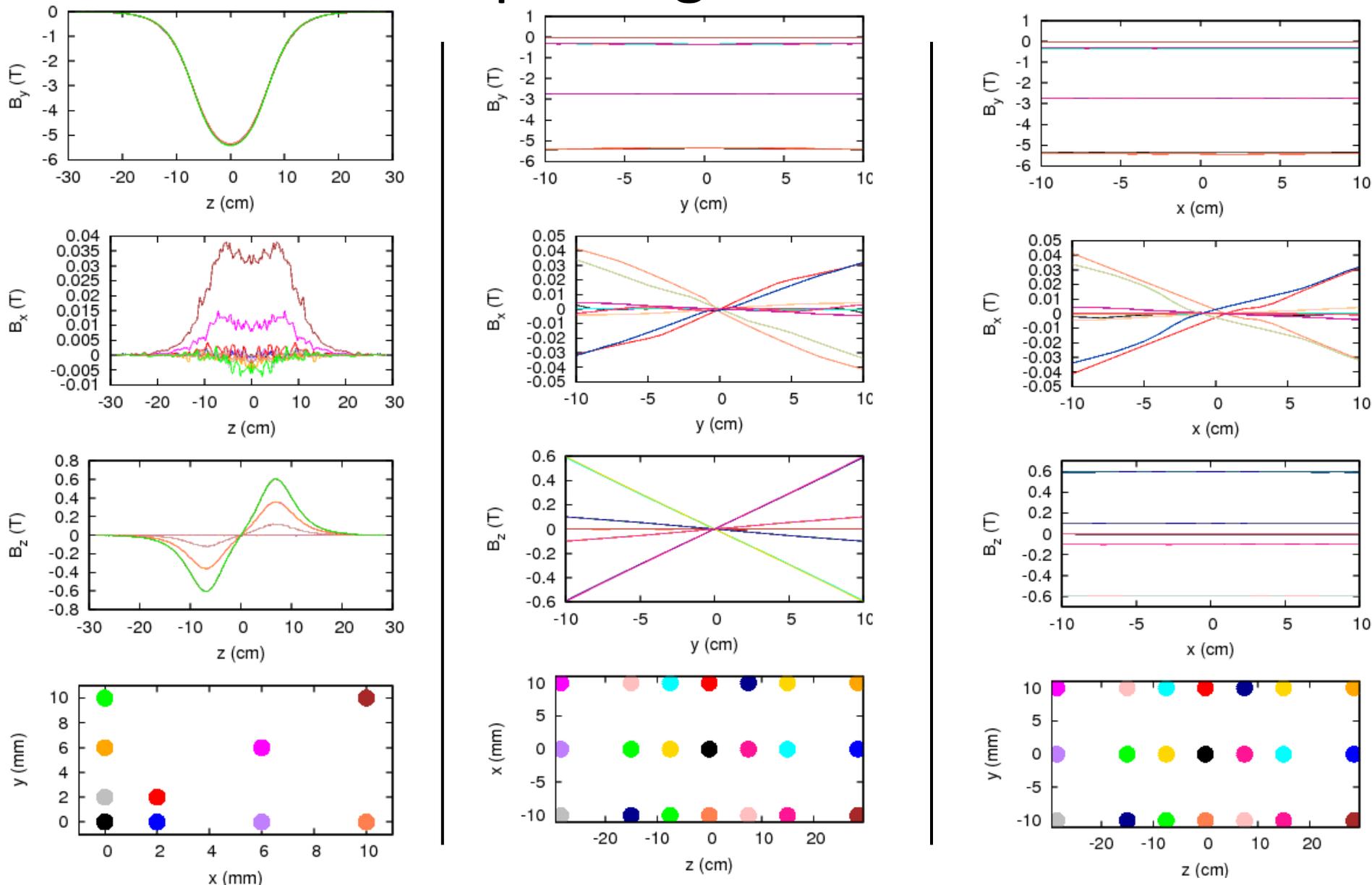
- ◆ C-shape yoke
 - open to ring outside (radiation)
 - retractable from vacuum chamber
 - ◆ Racetrack coils
 - no torsion of conductor
 - any geometry: tape, wire...
 - ◆ Warm bore
 - removable vacuum chamber
 - decoupling vacuum \leftrightarrow cryogenics
 - ◆ Cold iron
 - avoid air gap between coil and iron to enhance field
 - one cryostat for yoke, upper and lower coils
- 😊 simple geometry
- ☹ bell shaped rather than hyperbolic field
 \Rightarrow +45% in emittance



*Courtesy
Alexander
Anghel
PSI*



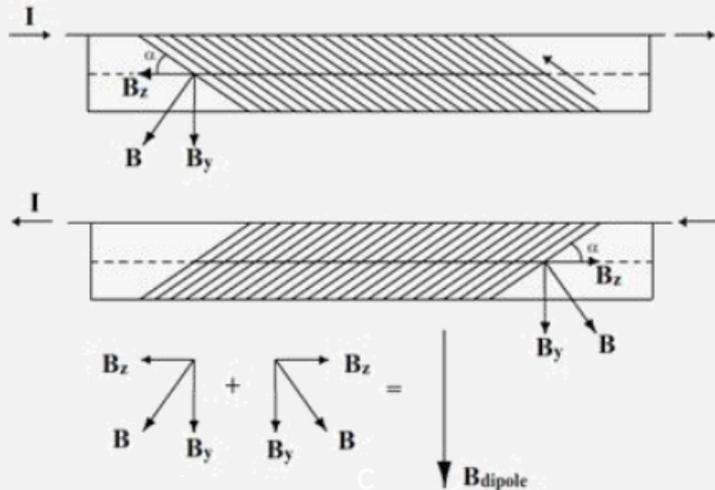
Field of C-Shape Magnet from CAD Model



- For this C-Shape magnet CAD model, B_x is relatively small and dominated noise, and assumed to be an artifact.

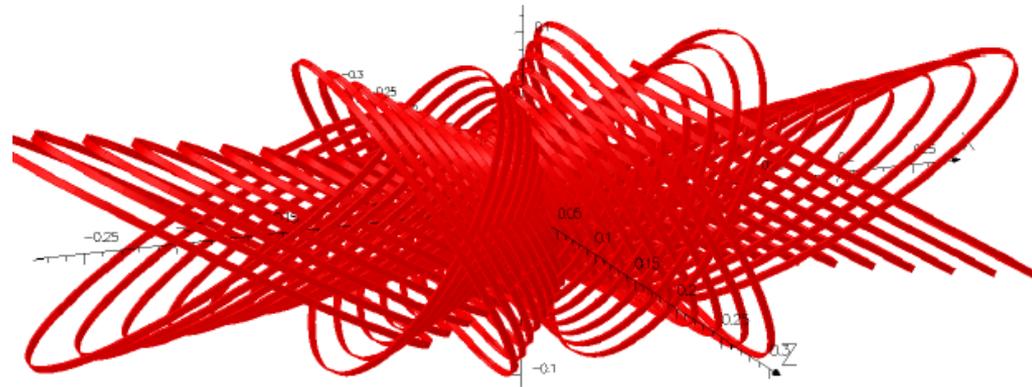
2. Canted-cosine-theta (CCT) solenoid

CCT principle



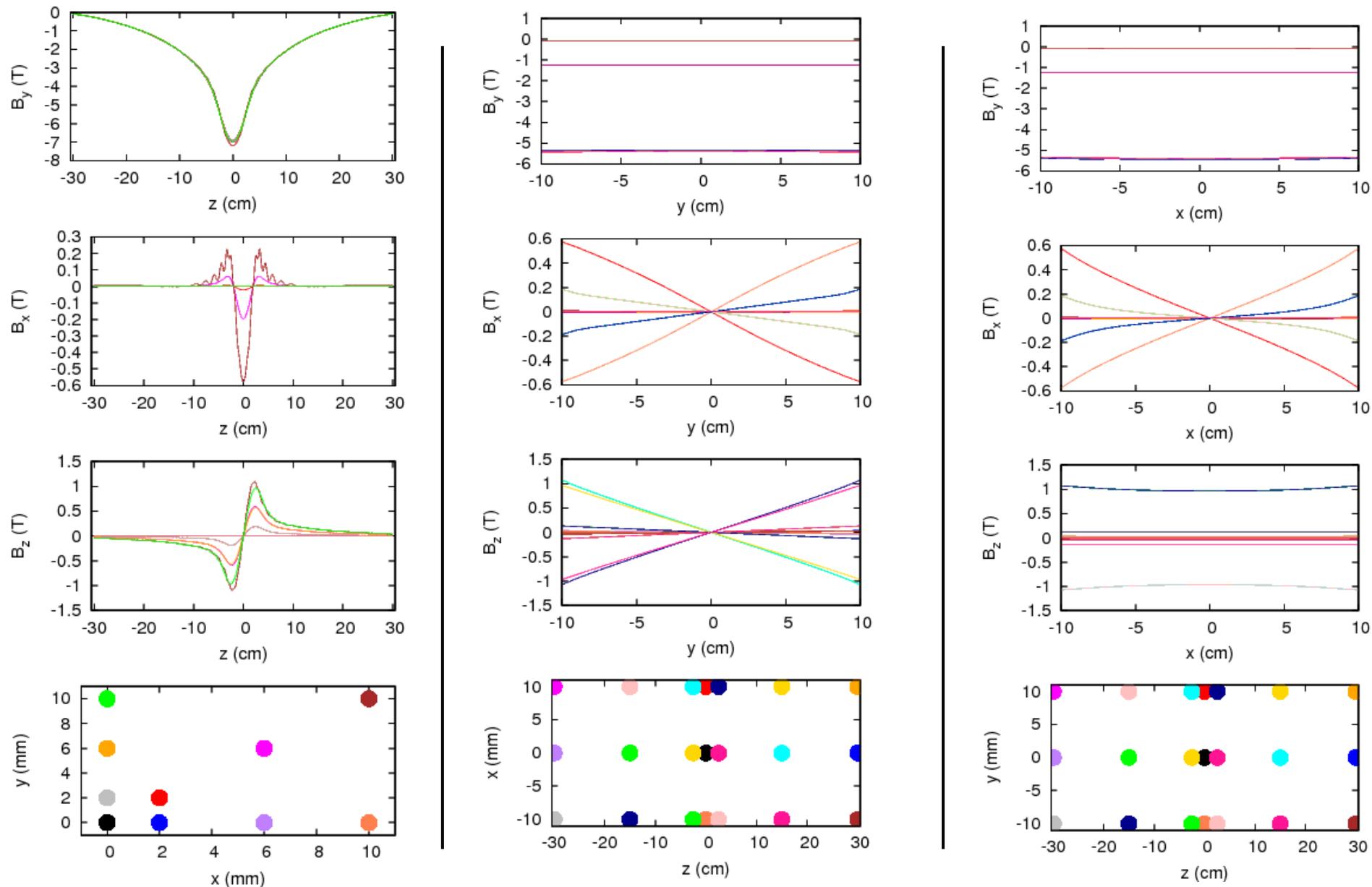
- ◆ Pure dipole field ($\cos \theta$) from superposition of canted solenoids
 - ◆ Any field profile by adding layers
 - ◆ Mechanical support of each winding \rightarrow low magnetic forces
- ☞ L. Caspi and L. Brouwer, BeMa2 workshop, Bad Zurzach, Dec. 1-4, 2014
- ☞ D. I. Meyer and R. Flasck, NIM 80 (1970) 339

Modification for SLS-2 super-LGB



- ◆ hyperbolic mandrel
 - follow radiation fan opening
 - lower field towards edges
- ◆ superimposed layers
 - approximate hyperbolic field profile
- 😊 very low magnetic forces
- ☹ complex geometry & engineering

Field of Canted Solenoid Magnet from CAD Model

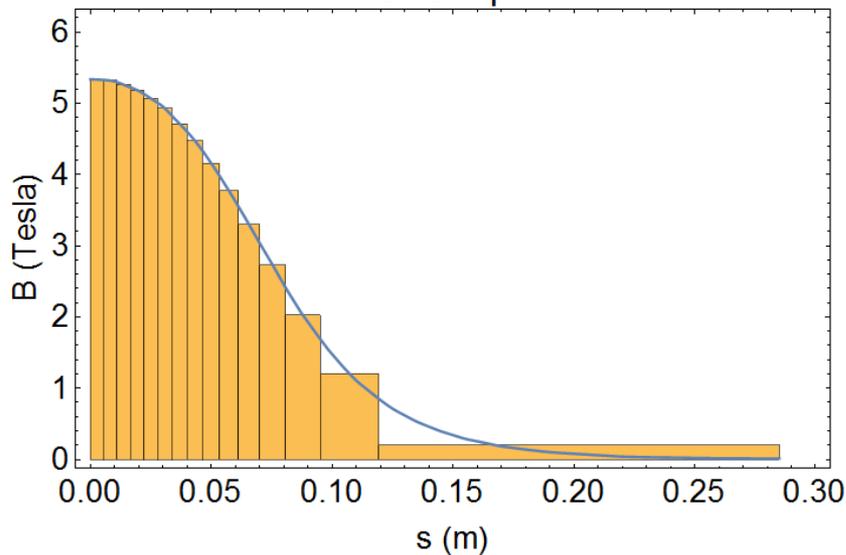


- For canted solenoid magnet, B_x is not negligible.

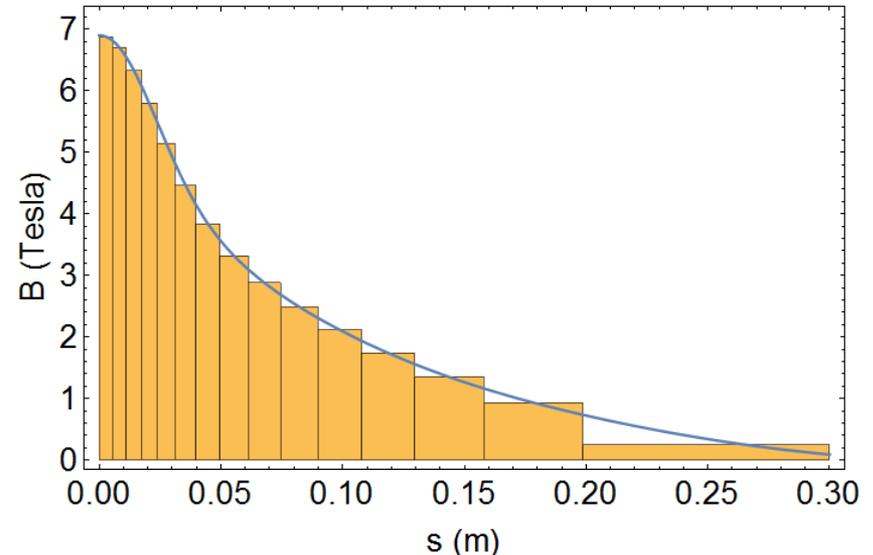
Stack of Sector Bends Model

- A sequence of standard sbends is fit to the LGB profile.
 - Can be easily implemented in any accelerator code.
- Based on bend field B_y along axis of magnet body.
- B_y is from either a rad-int optimization process or magnet designers (CAD).
- Construction Method:
 1. Divide total bend angle by some number of slices.
 2. Stack slices one-at-a-time, adjusting length to get bend-angle. Field strength for slice set by B_y data.
 3. Face angles are set to yield a stack with parallel faces. Stack is rectangular.
 1. Fringe fields are

C-Shape



Canted Solenoid



Map Model (1/2)

- For CESR and CESR-TA, fitted field maps were used to perform lattice calculations on wiggler-dominated storage rings.
 - Documented in Bmad Manual ^[1].
- Generalized the wiggler-modeling technique to work with LGB-dominated storage rings.
 - Work by Noah Bittermann (summer student U. Minn).
 - Developed in collaboration with David Sagan at Cornell.
- Wigglers have a net-zero bend field, and so a constant term was not needed.
 - The basis was not complete.
- LGBs have a net bend field, and require a constant offset.
 - Modify series to allow for constant terms.
 - Makes the series complete.
 - Updates are documented in latest edition of Bmad Manual.

[1] “The Bmad Reference Manual,” David Sagan, available online.

Map Model (2/2)

- Series from solution to source-free Ampere's Law in Coulomb gauge.
- Satisfies Maxwell's equations term-wise.
- Complete, but not orthogonal.
- Using Lie exponential of Hamiltonian, series is easily transformed into symplectic integrator.
- Fit to 3D gridded B-vector data from CAD model of magnet.
- **Result: ability to symplectically integrate through arbitrary magnetic fields with arbitrary precision and accuracy.**
- **Can treat map-model elements same as any other lattice element.**
 - **Linear optics calculations**
 - **Long-term tracking studies**
 - **Allows for misalignment studies**

$$\mathbf{B}(x, y, z) = \sum_i \mathbf{B}_i(x, y, z; C, k_x, k_y, k_z, x_0, y_0, \phi_z, plane)$$

$$B_x = -C \frac{k_x}{k_y} \sin(k_x x + \phi_x) \sinh(k_y y + \phi_y) \cos(k_z z + \phi_z)$$

$$B_y = C \cos(k_x x + \phi_x) \cosh(k_y y + \phi_y) \cos(k_z z + \phi_z)$$

$$B_s = -C \frac{k_z}{k_y} \cos(k_x x + \phi_x) \sinh(k_y y + \phi_y) \sin(k_z z + \phi_z)$$

$$\text{with } k_y^2 = k_x^2 + k_z^2 .$$

$$B_x = C \frac{k_x}{k_z} \sinh(k_x x + \phi_x) \sinh(k_y y + \phi_y) \cos(k_z z + \phi_z)$$

$$B_y = C \frac{k_y}{k_z} \cosh(k_x x + \phi_x) \cosh(k_y y + \phi_y) \cos(k_z z + \phi_z)$$

$$B_s = -C \cosh(k_x x + \phi_x) \sinh(k_y y + \phi_y) \sin(k_z z + \phi_z)$$

$$\text{with } k_z^2 = k_x^2 + k_y^2 ,$$

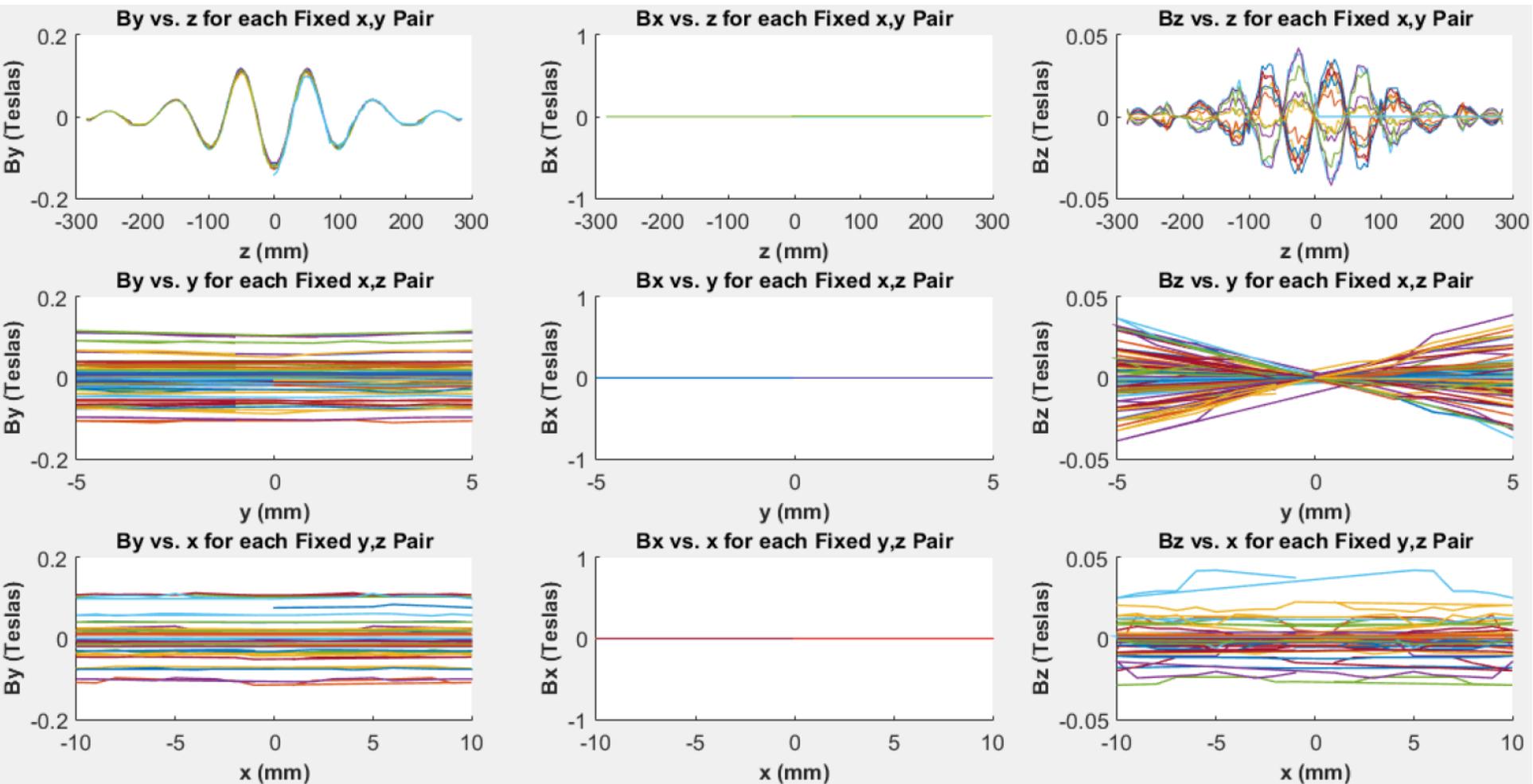
$$B_x = C \sinh(k_x x + \phi_x) \sin(k_y y + \phi_y) \cos(k_z z + \phi_z)$$

$$B_y = C \frac{k_y}{k_x} \cosh(k_x x + \phi_x) \cos(k_y y + \phi_y) \cos(k_z z + \phi_z)$$

$$B_s = -C \frac{k_z}{k_x} \cosh(k_x x + \phi_x) \sin(k_y y + \phi_y) \sin(k_z z + \phi_z)$$

$$\text{with } k_x^2 = k_y^2 + k_z^2 .$$

Residuals of 7-Term Fit to C-Shape Magnet

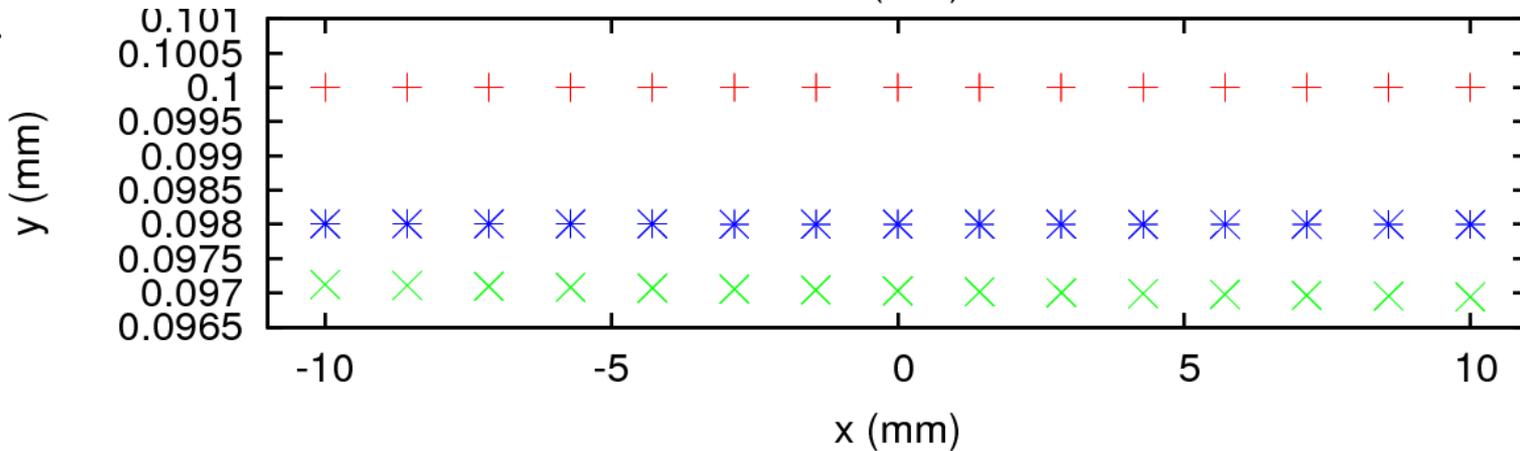
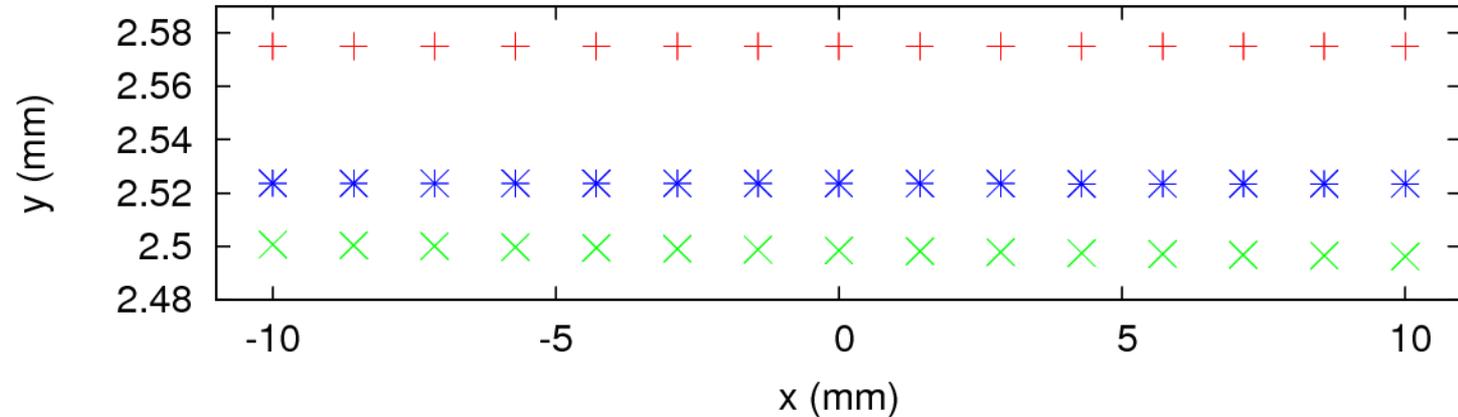
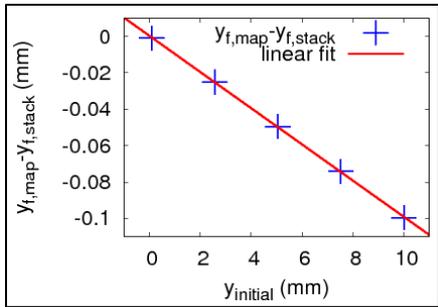
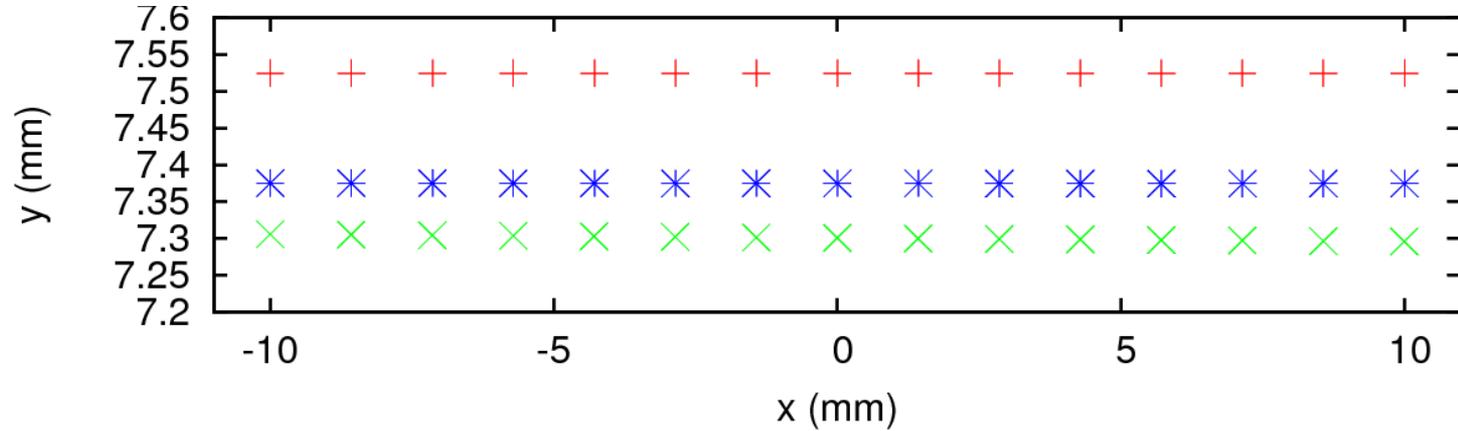


C-Shaped LGB-7 Terms	B_x (T)	B_y (T)	B_z (T)
Maximum Residual Magnitude	0.0	1.4×10^{-1}	4.2×10^{-1}
Sum of Residual Magnitudes	0.0	8.6×10^2	1.6×10^2
Average Residual (23,776 data points)	0.0	3.6×10^{-2}	6.8×10^{-3}

Note: Lattice with 12 Map LGBs is about 30% slower to track than with stack LGBs.

C-Shape Trajectory Comparisons

Initial +
Final Map x
Final Stack *

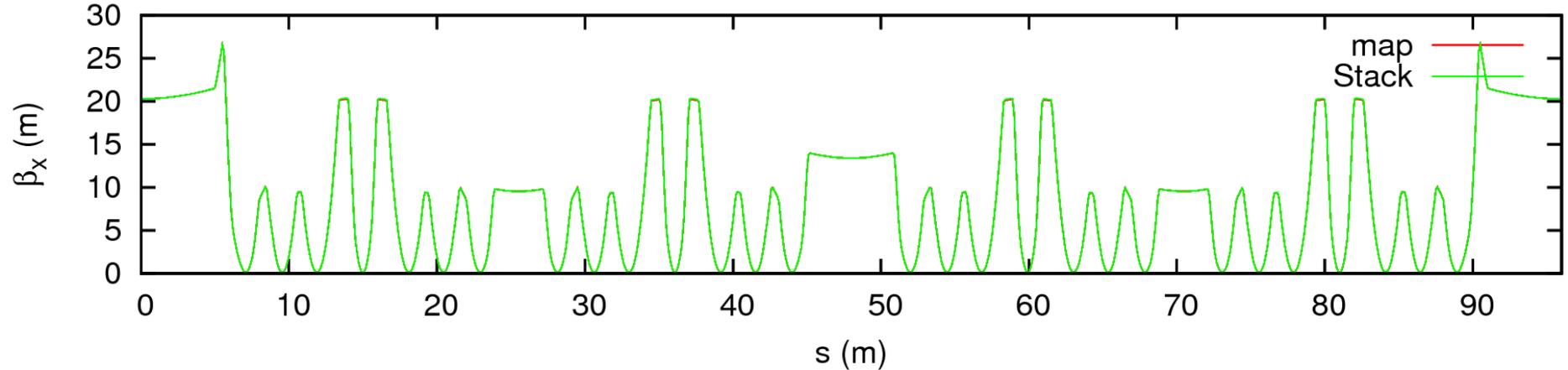


- Vert. residual versus offset is mostly linear, and independent of x.

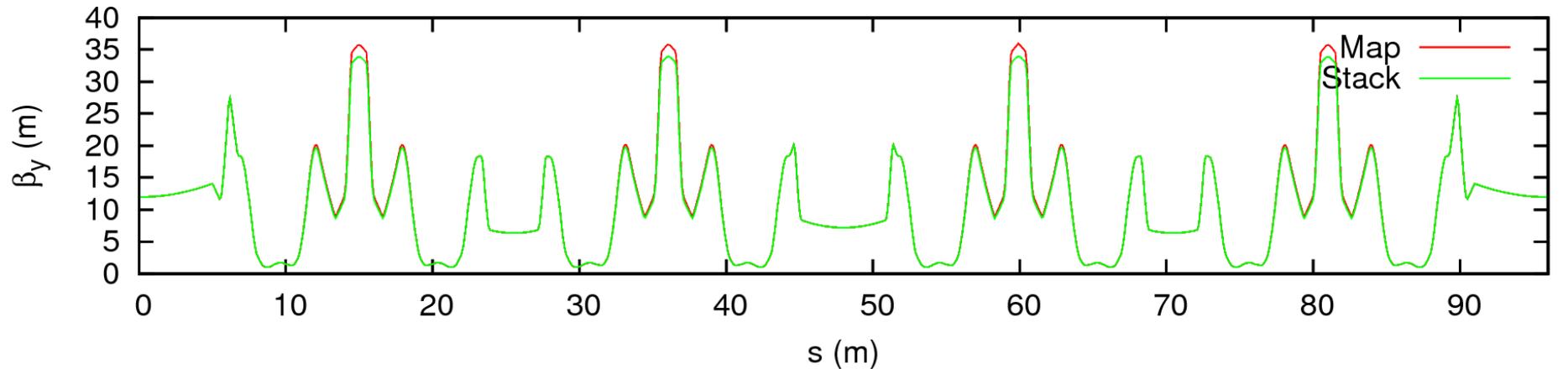
Linear optics (C-Shape)

- Arc quadrupoles and dispersion-focusing bends matched for Map or Stack model.

Horizontal Beta Functions for Lattice with C-Shape LGB



Vertical Beta Functions for Lattice with C-Shape LGB



Emittance Map: 262 μm

Emittance Stack: 230 μm

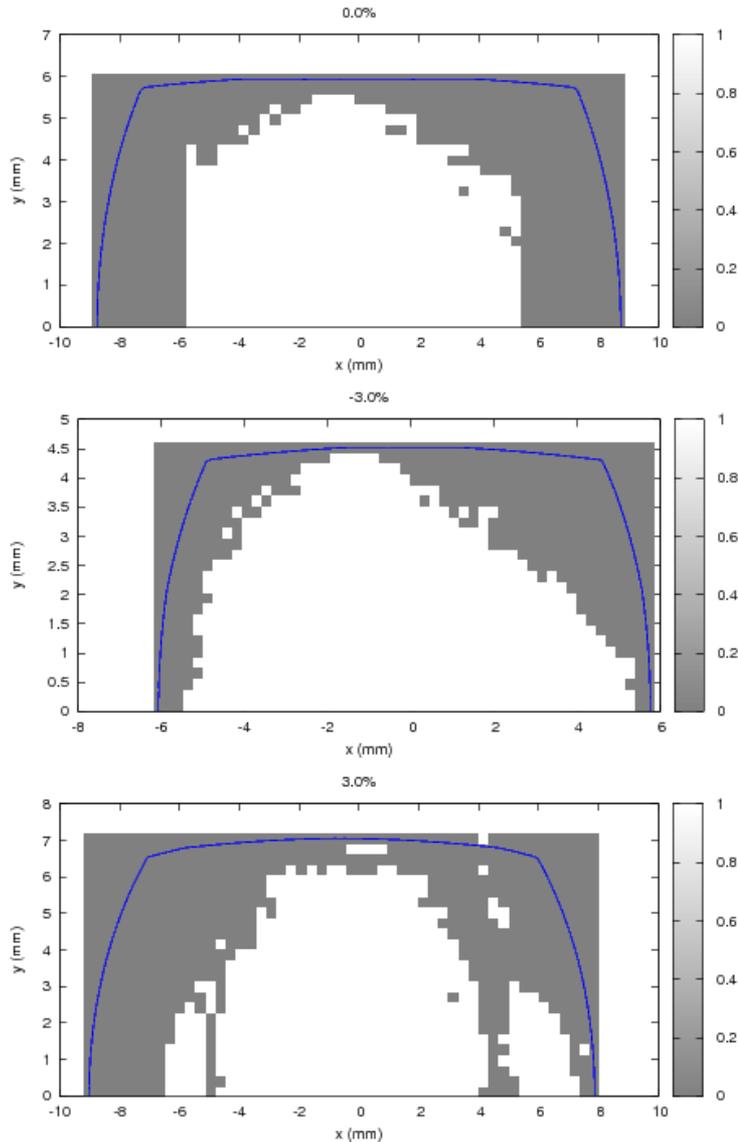
Natural Chromaticity Map: (-162, -80.7)

Natural Chromaticity Stack: (-162, -76.5)

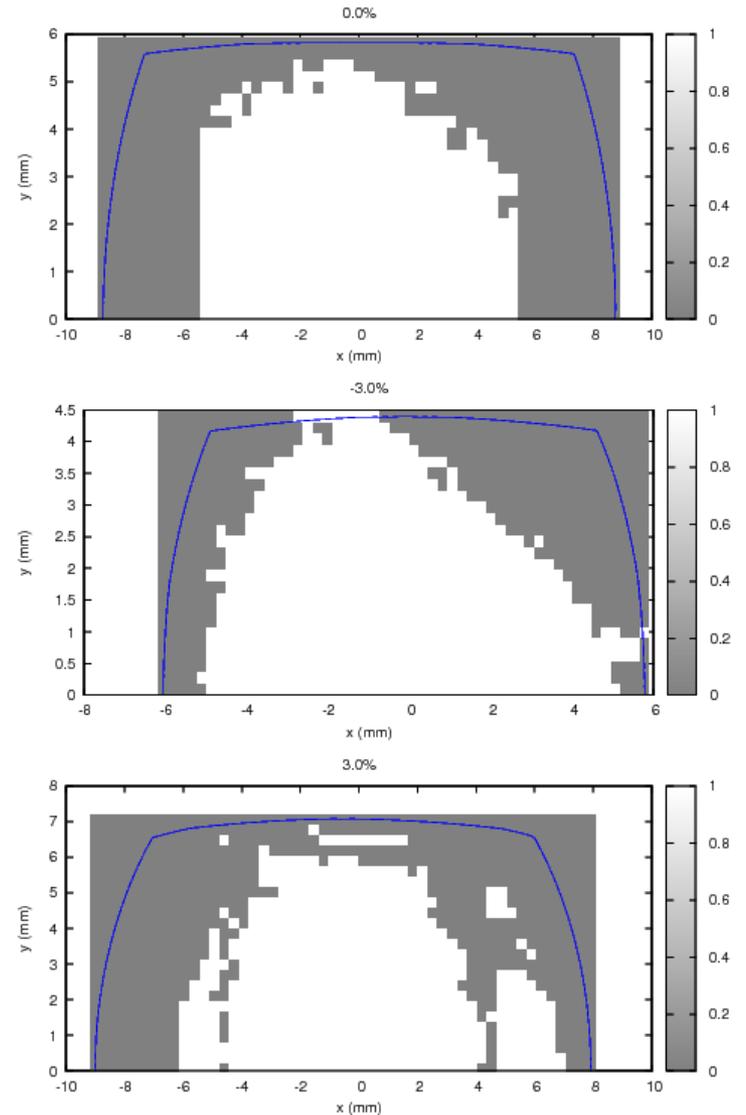
DA Correction (C-Shape)

- Sextupoles & Octupoles set using genetic optimizer.
- Completely random initial populations, no seeding.
- Both arrive at similar results.

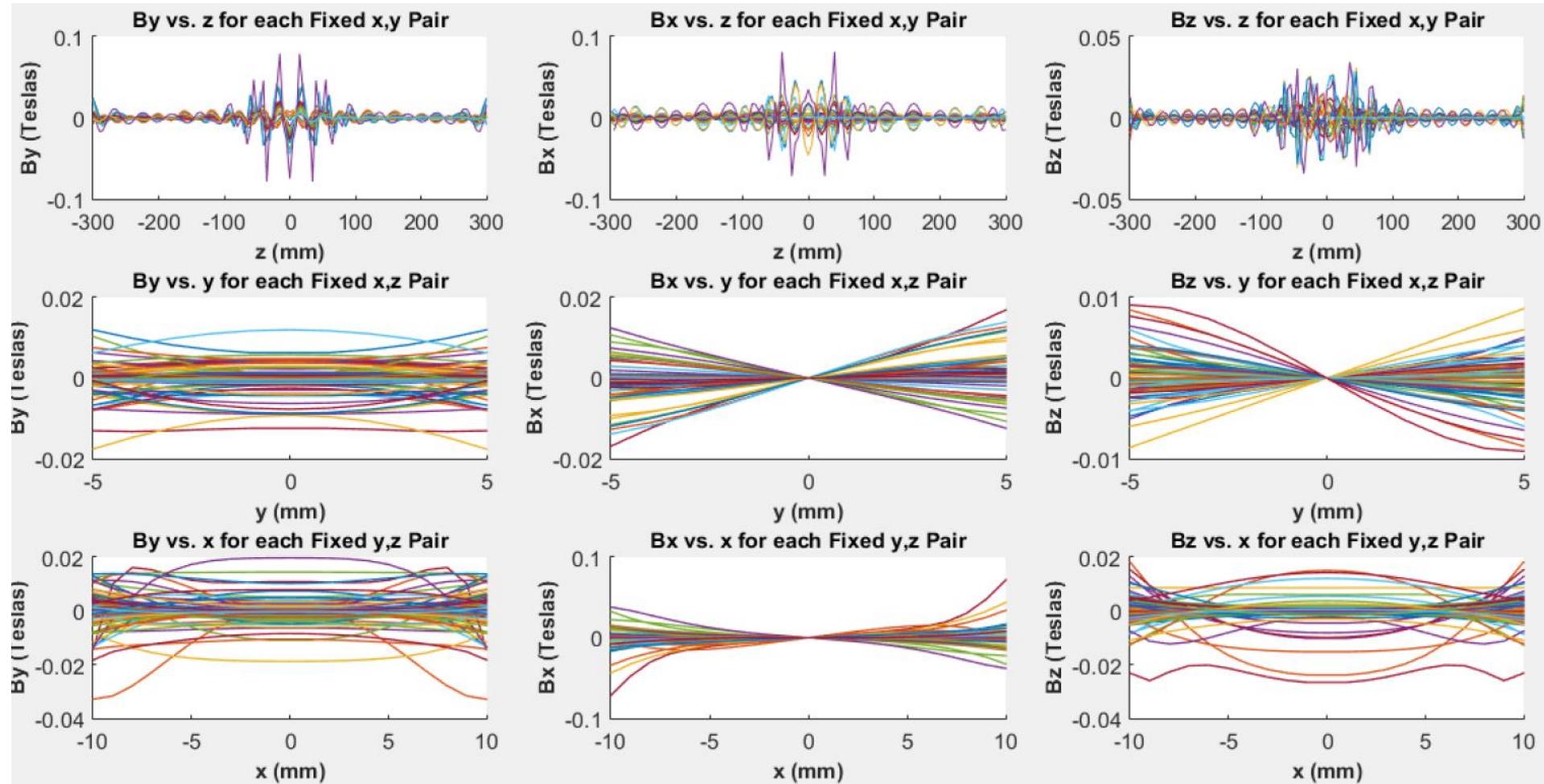
Stack Model



Map Model



Residuals of 9-Term Fit to CCT Magnet

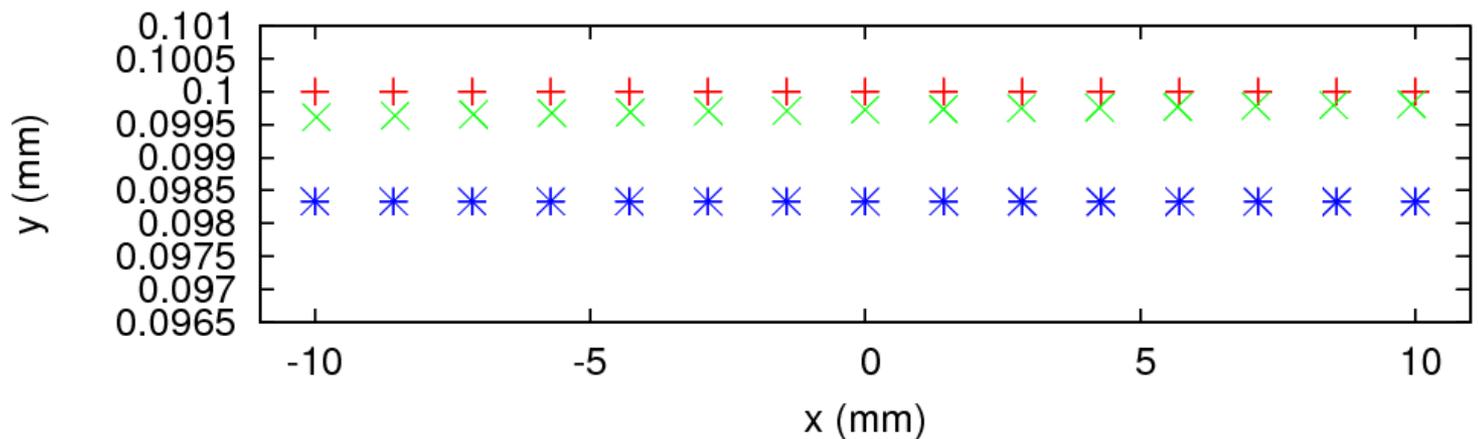
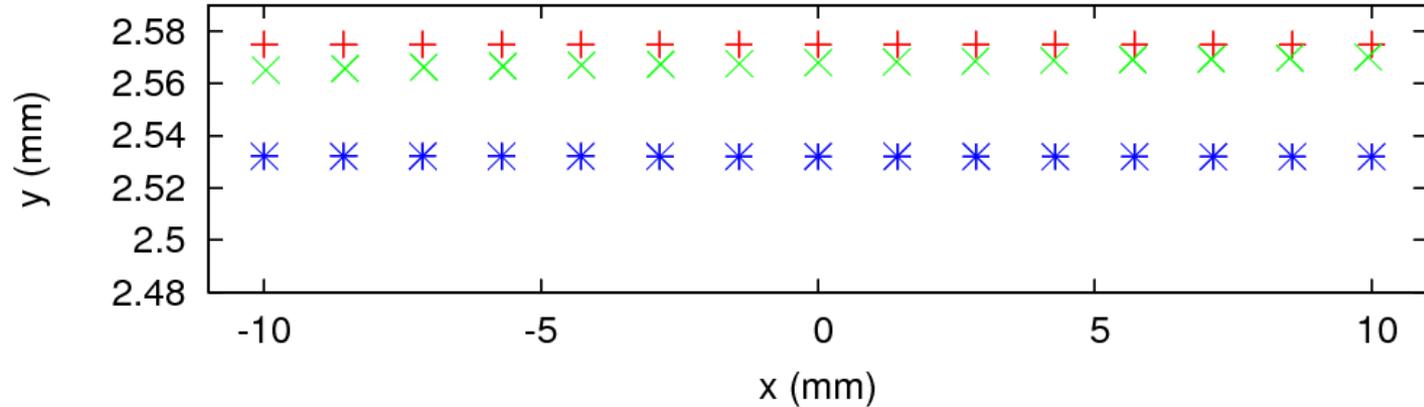
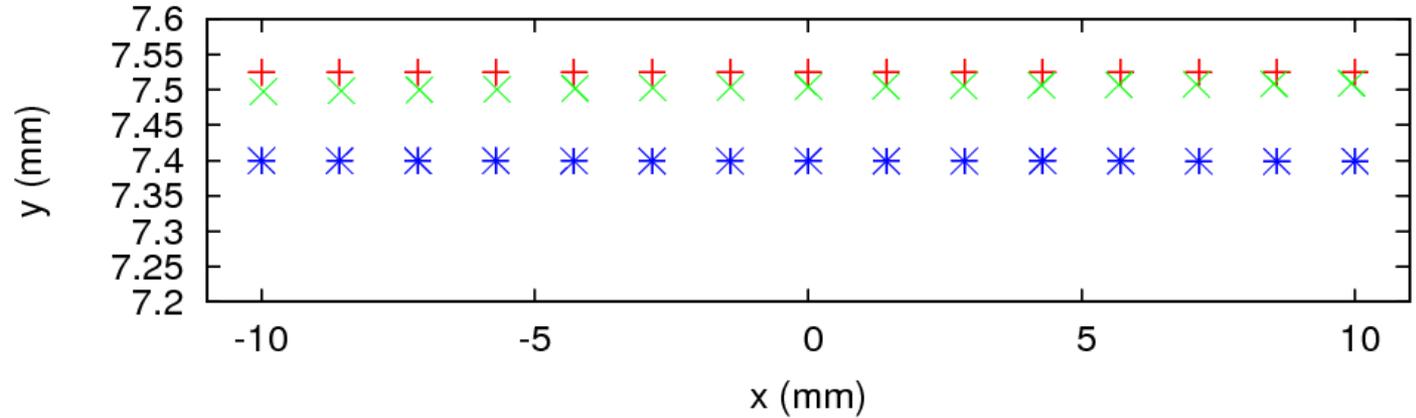


Canted Solenoid LGB-9 Terms	B_x (T)	B_y (T)	B_z (T)
Maximum Residual Magnitude	8.1×10^{-2}	7.9×10^{-2}	3.4×10^{-2}
Sum of Residual Magnitudes	1.78×10^2	2.0×10^2	1.3×10^2
Average Residual (50,900 data points)	3.0×10^{-3}	3.3×10^{-3}	2.1×10^{-3}

Note: Lattice with 12 Map LGBs is about 30% slower to track than with stack LGBs.

Canted Solenoid Trajectory Comparisons

Initial +
Final Map ×
Final Stack *

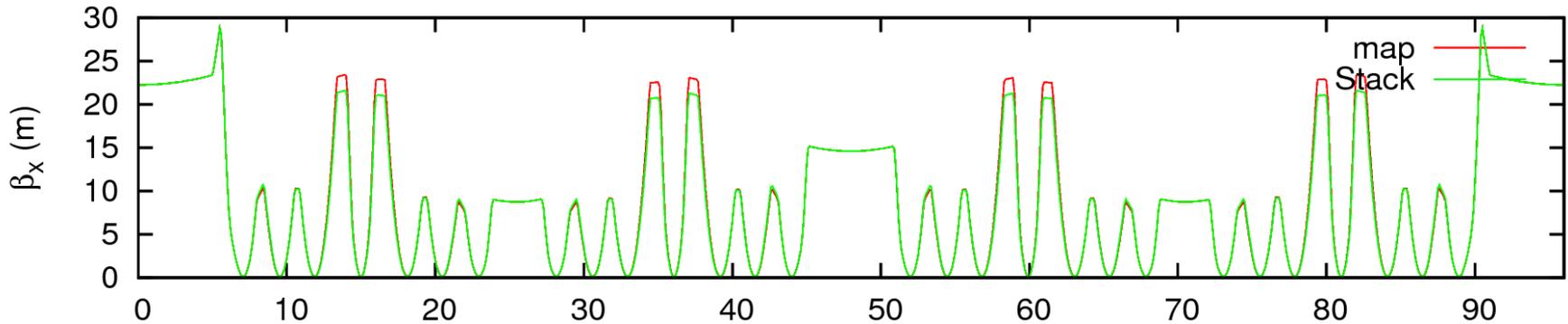


- B_x field along mid-plane complicates trajectory.
- Vertical residual depends on x.
- A noticeable horizontal residual is present.

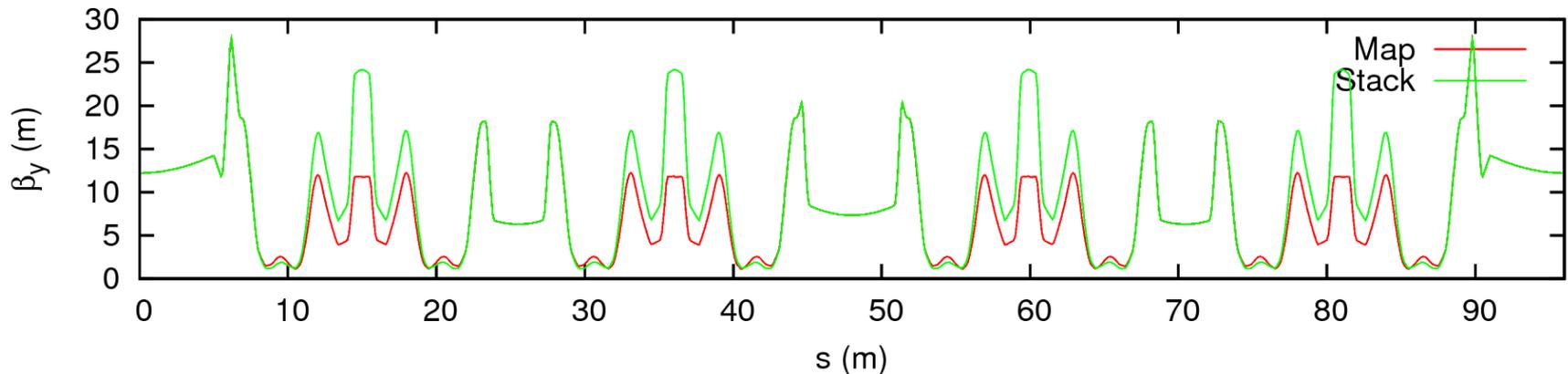
Linear optics (Solenoid)

- Arc quadrupoles and dispersion-focusing bends matched for Map or Stack model.

Horizontal Beta Functions for Lattice with Solenoid LGB



Vertical Beta Functions for Lattice with Solenoid LGB



Emittance Map: 198 pm

Emittance Stack: 187 pm

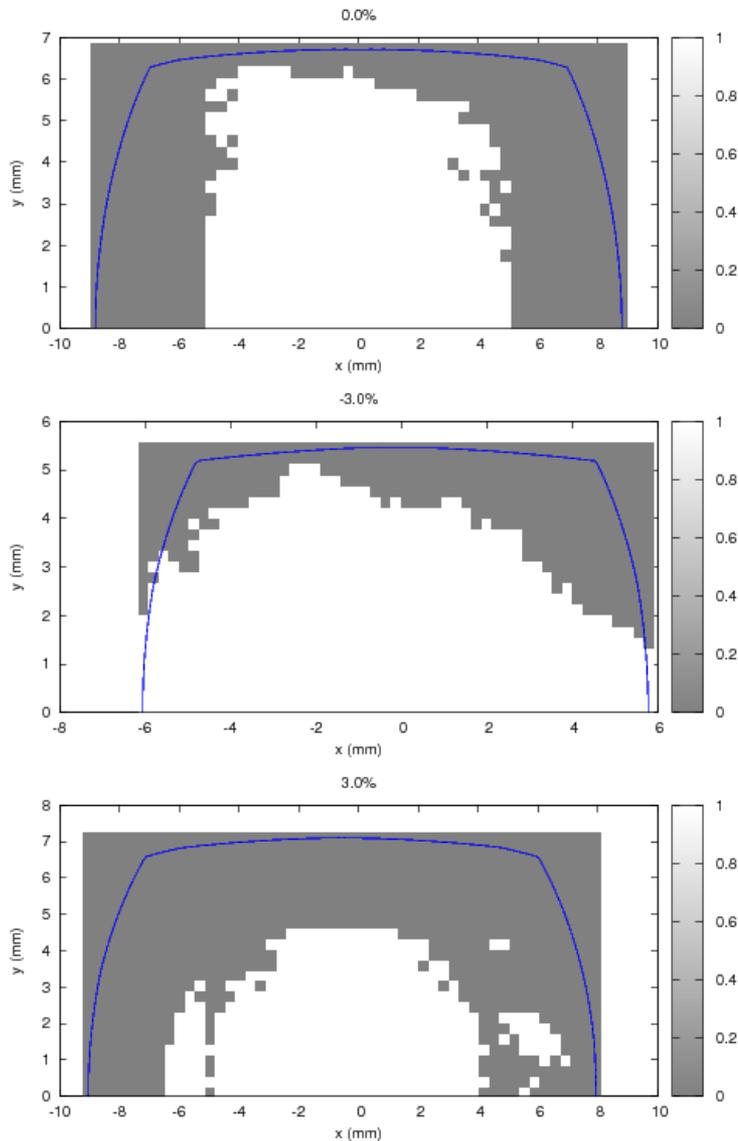
Natural Chromaticity Map: (-171, -53.0)

Natural Chromaticity Stack: (-166, -66.6)

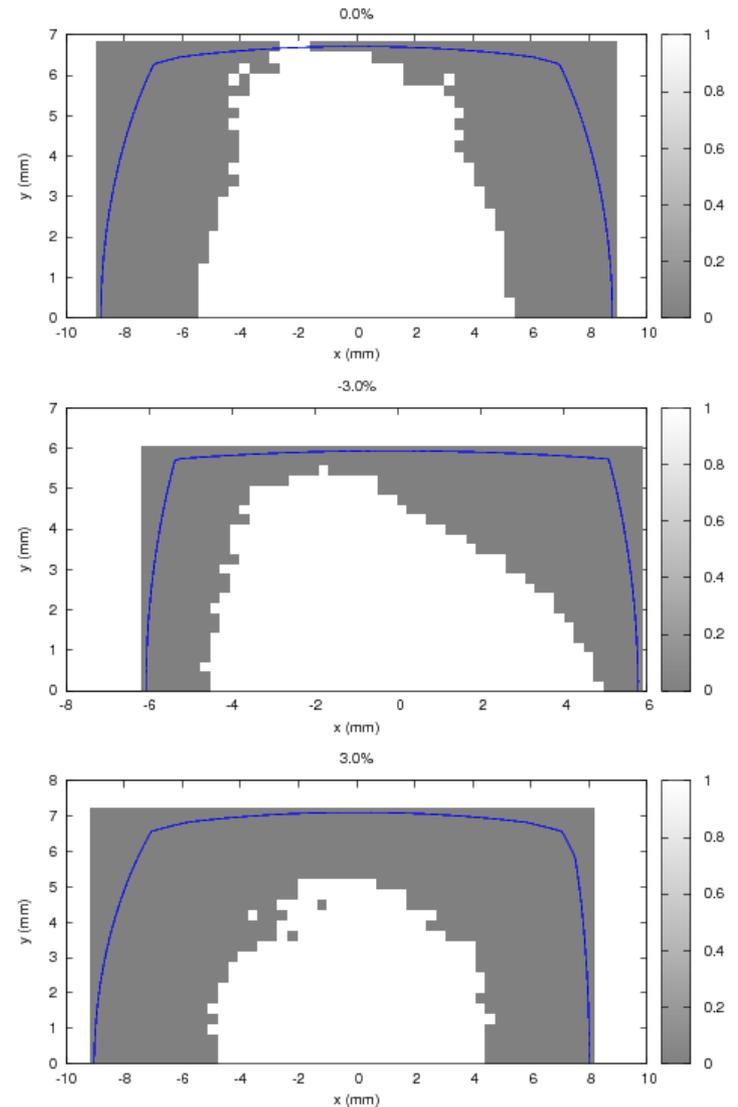
DA Correction (Solenoid)

- Sextupoles & Octupoles set using genetic optimizer.
- Completely random initial populations, no seeding.
- B_x field seems acceptable to large J particles.

Stack Model



Map Model



Further Techniques

- For c-shape magnet, use multipole expansion about closed orbit to find slice-by-slice focusing correction for stack (M. Aiba, PSI). (in progress)
 - Theory promising for C-Shaped magnet, not yet tested.
 - Expansion suggests that higher order components of field should be small (agrees with DA map result).
- Use kick-map (collaboration with Weiming Guo, BNL) as a check or alternative to fitted map method. (in progress)

Conclusion

- Magnet modelling method suitable for both linear optics calculations and long-term particle tracking implemented for SLS2 project.
 - Linear optics and rad. int. calculations depend on modeling method.
 - Stack method seems to get the linear optics wrong for CCT.
- Lattice optics depends on particular design of LGB magnet.
 - Bend field along axis is not a sufficient description of LGB.
- Modelling and theory suggest a slice-by-slice vertical focusing term may be sufficient to make stack method fairly accurate for C-Shaped magnet.